

view\_frames Result

Recorded at time: 315.632

odom

sentry::base\_footprint

Broadcaster: /gazebo  
Average rate: 91.202 Hz  
Most recent transform: 315.629 ( 0.003 sec old)  
Buffer length: 3.410 sec

base\_footprint

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 315.632 sec old)  
Buffer length: 0.000 sec

Broadcaster: /livox\_tf\_transform  
Average rate: 19.709 Hz  
Most recent transform: 315.724 ( -0.092 sec old)  
Buffer length: 3.501 sec

base\_link

livox\_laser

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 315.632 sec old)  
Buffer length: 0.000 sec

imu\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 315.632 sec old)  
Buffer length: 0.000 sec

laser\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10.300 Hz  
Most recent transform: 315.549 ( 0.083 sec old)  
Buffer length: 3.301 sec

wheel\_l\_b

Broadcaster: /robot\_state\_publisher  
Average rate: 10.300 Hz  
Most recent transform: 315.549 ( 0.083 sec old)  
Buffer length: 3.301 sec

wheel\_l\_f

Broadcaster: /robot\_state\_publisher  
Average rate: 10.300 Hz  
Most recent transform: 315.549 ( 0.083 sec old)  
Buffer length: 3.301 sec

wheel\_r\_b

Broadcaster: /robot\_state\_publisher  
Average rate: 10.300 Hz  
Most recent transform: 315.549 ( 0.083 sec old)  
Buffer length: 3.301 sec

wheel\_r\_f