6.046/18.410 Problem Set 3

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1 Key Word Search

<u>Convention</u>: Here for a string, its leftmost digit is labeled as #0. For example for M = 111000, we have M[0] = 1 and M[5] = 0. A different indexing convention may lead to small differences in the following parts.

1.1 Part (a)

<u>Description</u>: Scan from the 0-th to the (r-s)-th digit of M, digit by digit. For the i-th digit, check the matching between substring M[i:i+s-1] and S_1 , as well as between M[i:i+s-1] and S_2 . Use two counters to keep track of the number of successful matches of S_1 and S_2 . When all the digits are checked, compare the two counters and output the more frequent substring.

<u>Correctness</u>: This algorithm checks all the possible matches for S_1 and S_2 by directly comparing against the substring of M at each location. Since the loop goes through all the s-digit substrings of M, it is guaranteed that the count gives the correct number of successful matches.

Runtime: There are r - s + 1 possible s-digit substrings. The comparison against each of them takes O(s) time, since it involves s single-bit comparisons. The overall runtime is thus T(r,s) = O(s(r-s+1)) = O(rs). The simplification to O(rs) is based on the fact that s < r.

1.2 Part (b)

<u>Description</u>: Define a function $f : \{0,1\} \mapsto \{-1,1\}$ that maps the binary digit 0 to coefficient -1 and binary digit 1 to coefficient 1. Now construct the following polynomials

$$P(x) = \sum_{i=0}^{r-1} f(M[i])x^{r-i-1}$$

$$Q_1(x) = \sum_{i=0}^{s-1} f(S_1[i])x^i$$

$$Q_2(x) = \sum_{i=0}^{s-1} f(S_2[i])x^i$$

Notice that the polynomial for M is decending in the power of x, i.e. the 0-th digit of M corresponds to x^{r-1} , while the polynomials for S_1 and S_2 are ascending, i.e. the 0-th digit of S_1 or S_2 corresponds to x^0 .

We claim that, in the polynomial $C_1(x) = P(x)Q_1(x)$, the coefficient for x^i , denoted by $c_{1,i}$, reflects the number of matched bits of S_1 in the substring M[r-i-1:r+s-i-2], where $i=s-1,s,\cdots,r-1$. Specifically, this relation is given by

of matched bits of
$$S_1$$
 at $M[r-i-1] = \frac{1}{2}(s+c_{1,i})$

Replacing the index in M by i, where $i = 0, 1, \dots, r - s$, and foculng on unmatched bits,

of unmatched bits of
$$S_1$$
 at $M[i] = \frac{1}{2}(s - c_{1,r-i-1})$

Since we tolarate at most e unmatches, if

$$c_{1,r-i-1} \ge s - 2e$$

we identify a successful match of S_1 at M[i]. Due to the range of i, the subscript r-i-1 runs from s-1 to r-1.

Obviously, the same is true for S_2 . The proof is stated below. But before that, I will show an example. This helps clarify the indexing used here.

Example: Let M = 110101 and $S_1 = 100$. Then r = 6 and s = 3. According to the indexing convention, $\overline{M[0]} = 1$, M[1] = 1, M[2] = 0, \cdots , M[5] = 1. This corresponds to a polynomial

$$P(x) = x^5 + x^4 - x^3 + x^2 - x + 1$$

The polynomial $Q_1(x)$, however, is ascending in the power of x.

$$S_1(x) = 1 - x - x^2$$

Their product is

$$C_1(x) = P(x)Q_1(x) = -x^7 - 2x^6 + x^5 + x^4 - x^3 + x^2 - 2x + 1$$

Let i=0 for example. Number of unmatched bits at M[0] can be calculated from $c_{1,r-i-1}=c_{1,5}$, i.e. the coefficient of x^5 , which is 1.

of unmatched bits of
$$S_1$$
 at $M[0] = \frac{1}{2}(s - c_{1,5}) = \frac{1}{2}(3 - 1) = 1$

which is verified by the fact that M[0:2] = 110 differs from S_1 by one digit.

Correctness: Let $x, y \in \{0, 1\}$. Notice that f(x)f(y) = 1 if x = y, and f(x)f(y) = -1 if $x \neq y$. Therefore,

$$C_{1}(x) = P(x)Q_{1}(x)$$

$$= \sum_{i=0}^{r-1} \sum_{j=0}^{s-1} f(M[i])f(S_{1}[j])x^{r-i+j-1}$$

$$= \sum_{k=0}^{r-s} x^{r-k-1} \sum_{j=0}^{s-1} f(M[k+j])f(S_{1}[j])$$

$$= \sum_{k=0}^{r-s} (\# \text{ of matches at } M[k] - \# \text{ of unmatches at } M[k])x^{r-k-1}$$

where a substitution k = i - j has been made.

Let $n_{1,k}^m = \#$ of matched bits of S_1 at M[k], and $n_{1,k}^u = \#$ of unmatched bits of S_1 at M[k]. From the equation above, it is clear that $c_{1,r-k+1} = n_{1,k}^m - n_{1,k}^u$. Since $n_{1,k}^m + n_{1,k}^u = s$, we have

$$n_{1,k}^u = \frac{1}{2}(s - c_{1,r-k-1})$$

A successful match of S_1 has $n_{1,k}^u \leq e$. The criterion is thus

$$c_{1 r-k-1} \ge s - 2e$$

The same is true for S_2 .

Algorithm 1 Solving Eve's string matching problem in $O(r \log r)$

```
1: procedure STRINGMATCHING(M, S_1, S_2, e)
        Calculate coefficients of P(x), Q_1(x) and Q_2(x)
       Call FFT to evaluate P(x), Q_1(x) and Q_2(x) on a collapsing set A of r+s-1 points: x_1, \dots, x_{r+s-1}
3:
        Calculate C_1(x_1), \dots, C_1(x_{r+s-1}) and C_2(x_1), \dots, C_2(x_{r+s-1}), where C_1 = PQ_1 and C_2 = PQ_2
4:
        Call IFFT to calculate c_{1,i} and c_{2,i}, i.e. coefficients of C_1(x) and C_2(x), where i=0,\cdots,r+s-2
5:
6:
       count1, count2 \leftarrow 0
       for i = s - 1 : r - 1 do
                                                           \triangleright Counting, only coefficients of x^{s-1}, \cdots, x^{r-1} matters
7:
           if c_{1,i} \geqslant s - 2e then
8:
               count1++
9:
           if c_{2,i} \geqslant s - 2e then
10:
11:
               count2 + +
       if count1 > count2 then return S_1
12:
       else if count1 < count2 then return S_2
13:
       else return S_1, S_2
14:
```

1.3 Part (c)

Description: See the pseudocode.

<u>Correctness</u>: From the previous part, we know that $n_{\alpha,k}^u = \frac{1}{2}(s - c_{\alpha,r-k-1})$, where $\alpha = 1, 2$. Therefore, by looking at the coefficients of the product polynomials, we can determine the number of "good matches", i.e. the number of k such that $n_{\alpha,k}^u \leq e$. The pattern that has more good matches is a more frequent pattern. Notice that since $k = 0, \dots, r - s$, only the coefficients of x^{r-k-1} , in other words x^{s-1}, \dots, x^{r-1} , matters.

Runtime: The first step, calculating coefficients for P(x), $Q_1(x)$ and $Q_2(x)$, costs O(r) + O(s) + O(s) = O(r) time. The second step, FFT, costs $O((r+s)\log(r+s)) = O(r\log r)$ time. The third step, evaluating $C_1(x)$ and $C_2(x)$ at r+s-1 points, costs O(r+s) = O(r) time. The fourth step, IFFT, costs $O(r\log r)$ time. Finally, counting and comparing costs O(r-s) = O(r) time. Therefore, the total runtime is $O(r\log r)$.

2 Optical Fiber Network

2.1 Part (a)

Proof

By contradiction. Suppose S differs from T by more than one edges. Consider the set T-S of all edges that are in T but not in S. Let e_T be the edge of minimum weight in T-S. Adding e_T into S creates a cycle C_S . T cannot contain cycles, so $C_S \not\subseteq T$, which means that there must be some $e_S \in C_S$ such that $e_S \in S-T$.

Adding e_S into T creates a cycle C_T . By the same reasoning, there must be some $e_T' \in C_T$ such that $e_T' \in T - S$. Consider the spanning tree $T' = T - \{e_T'\} + \{e_S\}$. We have w(T) < w(T') due to the uniqueness of T as an MST. Therefore, $w(e_T') < w(e_S)$. Moreover, since e_T is chosen to be the lightest edge in T - S, $w(e_T) \le w(e_T')$. Therefore, $w(e_T) < w(e_S)$.

Consider the spanning tree $S' = S - \{e_S\} + \{e_T\}$. Then w(S') < w(S). Since S' only differs from S by one edge, $S' \neq T$. Therefore, w(T) < w(S') < w(S), contradicting the fact that S is the second minimum spanning tree.

Consequently, when MST is unique, a second minimum spanning tree differs from MST by exactly one edge.

2.2 Part (b)

<u>Description</u>: For convenience let D[u, u] = NULL and let its weight be $w(\text{NULL}) = -\infty$. The algorithm performs a depth-first traversal of T. Maintain A as a subset of V containing all the vertices that are visited.

A is initialized to contain only the root r. Maintain the property that $D[u_1, u_2]$ is determined for every $u_1, u_2 \in A$. This is done by the following: whenever a new vertice v is visited, calculate $D[u_i, v] = D[v, u_i]$ for all $u_i \in A$, before adding v into A. This calculation is done by the equation below, where w(u, v) denotes the weight of (u, v).

$$D[u_i, v] = \begin{cases} D[u_i, v.father] & \text{if } w(D[u_i, v.father]) \geqslant w(v, v.father) \\ (v, v.father) & \text{otherwise} \end{cases}$$

which holds for all newly added v. $v \neq r$ since $r \in A$ at the beginning, so v.father exists. Moreover, $v.father \in A$ when v is visited since the traversal is depth-first, so $D[u_i, v.father]$ can be accessed.

The procedure ends when every vertex is visited. In the meantime, D is complete filled.

The pseudocode contains more details.

Algorithm 2 Finding the longest edge on a unique path

```
1: procedure LongestEdge(T)
 2:
        A \leftarrow [T.root]
        D(T.root, T.root) \leftarrow \text{NULL}
 3:
        DEPTH-FIRST(T.root, A, D)
 4:
        return D
 5:
    procedure Depth-First(root, A, D)
 7:
        if root.childNum = 0 then return
 8:
            for i = 1 : root.childNum do
 9:
                for u in A do
10:
                    if w(D[u, root]) \geqslant w(root, child[i]) then
                                                                                                         \triangleright w(\text{NULL}) = -\infty
11:
                         D[u, root.child[i]] \leftarrow D[u, root]
12:
                        D[root.child[i], u] \leftarrow D[u, root]
13:
                    else
14:
                         D[u, root.child[i]] \leftarrow (root, child[i])
15:
                         D[root.child[i], u] \leftarrow (root, child[i])
16:
                D[root.child[i], root.child[i]] \leftarrow NULL
17:
                A.append(root.child[i])
18:
                Depth-First(root.child[i], A, D)
19:
20:
            return
```

Correctness: Since A is connected, for $u_1, u_2 \in A$, all the edges of T in the unique path connecting u_1 and u_2 lie in A. So $D[u_1, u_2]$ can be determined within A, even though A is only a subset of V. Moreover, all such D entries are determined for A. This is because (1) A is initialized with this property (2) whenever a new vertex v is about to be added into A, $D[u_i, v] = D[v, u_i]$ is calculated for every $u_i \in A$. Therefore, as A eventually expands to V, we get the full D matrix.

Furthermore, the correctness of this algorithm relies on the correctness of the following equation

$$D[u_i, v] = \begin{cases} D[u_i, v.father] & \text{if } w(D[u_i, v.father]) \geqslant w(v, v.father) \\ (v, v.father) & \text{otherwise} \end{cases}$$

Since the new vertex v connects to A at $v.father \in A$, the unique path from v to $u_i \in A$ is the union of (v, v.father) and the unique path from v.father to u_i . Therefore, the heaviest edge must be either (v, v.father) or $D[u_i, v.father]$, depending on which has a higher weight. This proves the correctness of the equation above.

<u>Runtime</u>: The algorithm visits V vertices. At vertex v, it calculates D[u,v] for all $u \in A$. For one v, this means O(V) operations, each of which contains constant times of comparing and value assigning. Therefore, the total runtime is $O(V) \times O(V) = O(V^2)$.

2.3 Part (c)

Description: For each $(u, v) \in E$, consider the tree $S_{u,v} = T \cup \{(u, v)\} - \{D[u, v]\}$. The $S_{u,v}$ with minimal weight is the second-best spanning tree. See the pseudocode.

Algorithm 3 Finding the second-best spanning tree

```
1: procedure SecondBest(T, E, V)
       D = \text{LongestEdge}(T)
3:
       maxWeightReduce \leftarrow -\infty
       for (u, v) in E do
4:
          if w(D[u,v]) - w(u,v) > maxWeightReduce then
5:
              maxWeightReduce \leftarrow w(D[u,v]) - w(u,v)
6:
              (u^*, v^*) \leftarrow (u, v)
7:
       S \leftarrow T \cup \{(u^*, v^*)\} - \{D[u^*, v^*]\}
8:
       return S
9:
```

Correctness: According to part (a), S only differs from T by one edge. Suppose $(u,v) \in S$ but $(u,v) \notin T$. Then in order to avoid a loop, one of the edges along the original path connecting u and v must be removed from S. In order to minimize w(S), the optimal choice of this edge is the heaviest one, D[u,v]. By looping over all possible $(u,v) \in E$, we compare across different $S_{u,v} = T \cup \{(u,v)\} - \{D[u,v]\}$. The lightest of all is the lightest possible spanning tree that differs from T by exactly one edge. Part (a) tells us that it must be the second-best spanning tree S.

<u>Runtime</u>: Longestedge costs $O(V^2)$. Then the algorithm loops through all |E| vertex pairs. In each iteration only constant amount of work is done. Therefore, the loops runs at $O(E) = O(V^2)$ time. Altogether, this algorithm has a runtime of $O(V^2)$.