

Introduction to Machine Learning

Lecture 1 Guang Bing Yang, PhD

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- My name: Guangbing Yang
- My research interest and experience focuses on: Text summarization, Visual semantics, Natural Language Processing, Machine Learning/deep learning/reinforcement learning algorithms, statistics, and data science.
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- My brief CV:
 - [Guangbing Yang, Ph.D. - Texas A&M University-Commerce](#)
 - [Guangbing Yang - Google Scholar](#)

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Evaluation

- **Five assignments:**
 - Assignment 1 worth 10%, Assignment 2 to 5 worth 15%
- Final project and presentation, worth 25%
- Attendance and activity, worth 5%

Tentative Dates - Check the MyCourseVille, or lecture notes.

Project: Proposal Due April 9, 2021

Presentation: May 14th, 2021

Project report: May 14th, 2021

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Project

- The purpose of the final project is to provide you a bit of experience trying to do a very basic but original research in machine learning and coherently writing up your result.
- In this project, **what is expected:**
 - A simple but original idea, clearly describe and discussed.
 - Link it to existing methods
 - Implement and test (model performance evaluation) on a small scale problem
- **What is required:**
 - write some basic code to build a machine learning model and train/test it on some data
 - make some figures (e.g., architecture, system design, work flow, training/testing evaluation result plots, and others)
 - read some research papers, collect references, and
 - write an essay (no more than 3 pages) to discuss your model, algorithm, and results, etc.

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As reference books

- Deep Learning, MIT, ISBN: 9780262035613

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What is Machine Learning about?

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Types of Machine Learning

Given a series of input vectors: $X_1, X_2, X_3, \dots, X_n$

- **Supervised Learning:** the goal is to learn a **mapping** from inputs x to outputs y , given a labeled set of input-output pairs $\mathbb{D} = \{(x_i, y_i)\}_{i=1}^N$, \mathbb{D} is called training dataset.
- **Unsupervised Learning:** the goal is to learn interesting **patterns** in the data. Only inputs x are given, no labeled data provided. Sometimes, the unsupervised learning is also called **knowledge discovery**.
- **Reinforcement Learning:** the goal is to learn actions that maximize the reward in a long-term. RL is beyond the scope of this course. But we may introduce it a little if we have time.
- **Semi-supervised Learning:** given a few of labeled data, but lots of unlabeled data. (Not cover this topic in this course)

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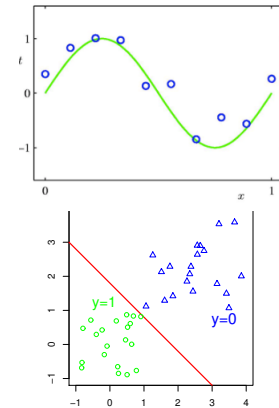
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Supervised Learning

- **Regression:** target output y_i are continuous. The goal is to predict the output (real values) given new inputs
- **Classification:** target output y_i are discrete class labels. The goal is to correctly classify new inputs



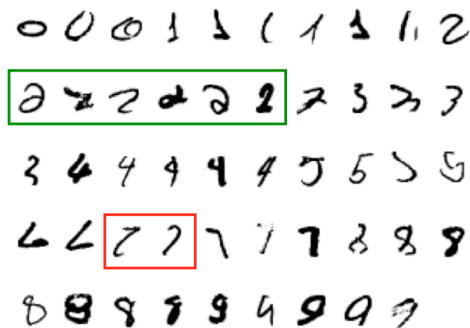
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Examples of classification



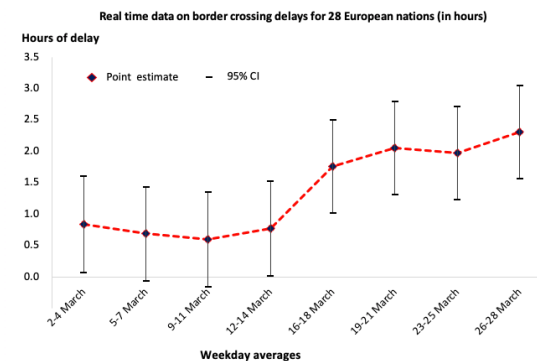
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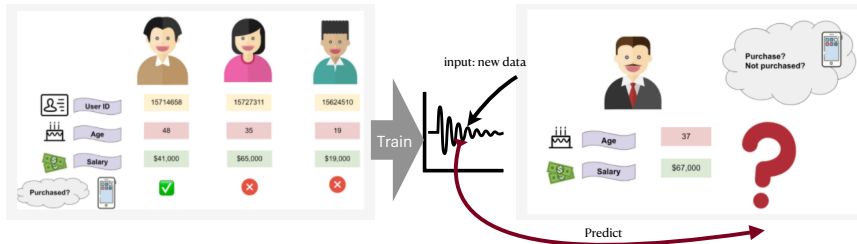
Examples of regression



Reference: <https://voxeu.org/article/covid-concussion-and-supply-chain-contagion-waves>

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Examples of Logistic Regression (classification)



Given same labeled data: client information with purchased (targets/labels), to predict a new customer whether or not buy a new phone.

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Popular Algorithms

For Regression Problems

- Linear regression: Objective function: $\min_w [Xw - y]^2$, no regularization
- Ridge regression: The ridge coefficients minimize a penalized residual sum of squares: $\min_w [Xw - y]^2 + \alpha[w]^2$, L2 regularization
- Lasso: a linear model that estimates sparse coefficients. $\min_w \frac{1}{2n_{samples}} [Xw - y]^2 + \alpha w$, L1 regularization
- Elastic-Net: a linear regression model trained with both L1 and L2 regularization of the coefficients. $\min_w \frac{1}{2n_{samples}} [Xw - y]^2 + \alpha \rho w + \frac{\alpha(1-\rho)}{2} w^2$, L1 plus L2 regularizations.
- Bayesian regression: a fully probabilistic model with normal distribution around Xw , $p(y | X, w; \alpha, \sigma) = \mathcal{N}(y | Xw, \alpha, \sigma^2)$

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Popular Algorithms

For Classification Problems

- Logistic regression
- Naive Bayes
- Decision Trees
- k-Nearest Neighbours
- Random Forests
- Gradient Tree Boosting
- XGBoost

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Brief History of Machine Learning

- Alan Turing's paper "Computing Machinery and Intelligence" in 1950, probably the earliest start the research of machine learning.
- Arthur Samuel in 1959 first time, stated the term "machine learning"
- Tom M. Mitchell in 1997 provided a widely quoted, more formal definition of ML
- After 1990s, machine learning became a separated filed from Artificial Intelligence.
- Nowadays, ML is an essential part of the AI.
- After 2010, Deep Learning and Reinforcement Learning, which are core part of ML, are more popular.

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Current & Future

- Due to globalization, the majority of jobs moved to “knowledge work” from “manual labor”.
- The massive amounts of data and information available to us from the web make the jobs of knowledge workers even harder.
- Making sense of all the data with our job in mind is becoming a more essential skill.
- Machine learning will help you get through all data and extract some information.
- Machine learning becomes the essential skills.
- It has a very bright future!

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Reviews

- Linear Algebra
 - Matrix Multiplication
 - Vector-Vector Multiplication
 - Matrix-Vector Multiplication
 - Matrix-Matrix Products
 - Operations and Properties
 - Matrix Calculus
- Probability Theory
 - General Concepts
 - Expected Values
- Common Probability Distributions

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Linear Algebra Brief Review

- **Linear algebra** is a branch of mathematics providing a concise way to represent and operate on a set of linear equations via vectors and matrices.

- For example, system equations:

$$\begin{aligned} 2x_1 + 3x_2 &= 15 \\ -x_1 + 2x_2 &= 6 \end{aligned}$$

can be represented using matrix
and matrix operations

$$Ax = y$$
$$A = \begin{bmatrix} 2 & 3 \\ -1 & 2 \end{bmatrix}, y = \begin{bmatrix} 15 \\ 6 \end{bmatrix}$$

- To solve this system equation, many steps may be needed, but later, you will see we can get it quickly and easily using matrix operations.

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Matrix Multiplication

- The **product** of two matrices $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times p}$ is the matrix:

$$C = AB \in \mathbb{R}^{m \times p}$$

$$\text{where } C_{ij} = \sum_{k=1}^n A_{ik} B_{kj}$$

Note that in order for the matrix product to exist, the number of columns in A must equal the number of rows in B.

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Vector - Vector Multiplication

- The **product** of two vectors, $a, b \in \mathbb{R}^n$, the outcome of the product $a^T b$, also called the **inner product** or **dot product** of vectors, is a real number calculated by
- In this case, $a^T b = b^T a$ because the size of the vector a and b are the same, which is n .

$$a^T b \in \mathbb{R} = [a_1 a_2 \dots a_n] \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} = \sum_{i=1}^n a_i b_i = (a_1 b_1 + a_2 b_2 + \dots + a_n b_n)$$

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Vector - Vector Multiplication

- In contrast, for two vectors, $a \in \mathbb{R}^m, b \in \mathbb{R}^n$ with different size, the **outer product** of $ab^T \in \mathbb{R}^{m \times n}$, is defined as,
- In this case, ab^T is a $m \times n$ matrix rather than a real scalar value.
- For others, matrix - vector, vector - matrix and matrix - matrix, please see lecture note: 'review-linear-algebra.pdf'

$$ab^T \in \mathbb{R}^{m \times n} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} [b_1 b_2 \dots b_n] = \begin{bmatrix} a_1 b_1 & a_1 b_2 & \dots & a_1 b_n \\ a_2 b_1 & a_2 b_2 & \dots & a_2 b_n \\ \vdots & \vdots & \dots & \vdots \\ a_m b_1 & a_m b_2 & \dots & a_m b_n \end{bmatrix}$$

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Operations and Properties

• Identity Matrix & Diagonal Matrix

- a square matrix with ones on the diagonal and zeros everywhere else. It is denoted as: $I \in \mathbb{R}^{n \times n}, I_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$
- property of identity matrix: for all $A \in \mathbb{R}^{m \times n}, AI = A = IA$
- diagonal matrix is a matrix where all non-diagonal elements are zeros, denoted as $D = \text{diag}(d_1, d_2, \dots, d_n)$. It is not necessary a square matrix, with $D_{ij} = \begin{cases} d_i & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$

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Operations and Properties

• The Transpose

- The transpose of a matrix results from flipping the rows and columns.
- Given a matrix $A \in \mathbb{R}^{m \times n}$, its transpose, written $A^T \in \mathbb{R}^{n \times m}$, is the $n \times m$ matrix whose entries are given by $(A^T)_{ij} = A_{ji}$
- The properties:
 - $(A^T)^T = A$
 - $(AB)^T = B^T A^T$
 - $(A + B)^T = A^T + B^T$

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Operations and Properties

• The Inverse

- The inverse of a square matrix $A \in \mathbb{R}^{n \times n}$ is denoted as $A^{-1} \in \mathbb{R}^{n \times n}$.
- It is unique and $A^{-1}A = I = AA^{-1}$
- Note that not all matrices, including some square matrices, have inverses. By definition, non-square matrices have no inverses.
- Particularly, if A^{-1} exists, we say A is **invertible** or **non-singular**, otherwise, it is **non-invertible** or **singular**. Also, the determinant of the A ($\det A$) is not zero, and is vice versa.
- The properties:
 - $(A^{-1})^{-1} = A$
 - $(AB)^{-1} = B^{-1}A^{-1}$
 - $(A^{-1})^T = (A^T)^{-1}$

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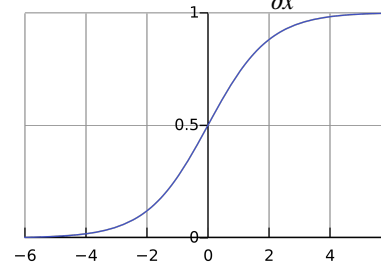
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Sigmoid function & its derivative

• The Sigmoid function

- $S(x) = \frac{1}{1 + e^{-x}}$ is denoted as $x \in \mathbb{R}^n$.
- Its derivative or gradient defined as $\frac{\partial S(x)}{\partial x} = S(x)(1 - S(x))$

•



Sigmoid function-chart from Wikipedia page: Sigmoid function

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Probability Theory Brief Review

- **Probability Theory** studies the **uncertainty**.
- **Statistics** somehow apply probability theory to explain the variation in some measure of interest. In other words, probability quantifies uncertainty, statistics explains variation.
- For example,
 - Roll a 6-side die. What is the probability of obtaining a 6? (a probability problem)
 - Observe the variation of the annual income of a person. What factors explain the variation in a person's income. (a statistic problem, which is 'variation = factors of observation + random errors'. Clearly, no way to account for all factors that affect person's income, have to leave any remaining variation to uncertainty).
- In later lectures, you will see a loss function (or cost function) can be taken as the random error in the variation expression list above.
- That is why we say machine learning use statistics and probability to address the uncertainty problem.

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Probability Theory Brief Review

• Elements of Probability

- **Sample space:** the sample space is denoted by Ω , it is the event set
- **Events:** a particular subset of Ω , denoted as $A, A \subseteq \Omega$.
- **Probability measure:** A function $P : F \rightarrow R$ that satisfies the following properties:
 - $P(w) \geq 0$
 - $\sum_{w \in \Omega} P(w) = 1$
 - If A_1 and A_2 are disjoint, then $P(A_1 \cup A_2) = P(A_1) + P(A_2)$, more generally, if A_1, A_2, \dots, A_n are mutually disjoint, then $P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$

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Probability Theory Brief Review

• Properties of Probability:

- If $A \subseteq B$, $P(A) \leq P(B)$
- $P(A \cap B) = \min(P(A), P(B))$
- $P(A \cup B) \leq P(A) + P(B)$ - (Union Bound)
- $P(A^c) = 1 - P(A)$ since A^c is called A's complement, A^c and A are disjoint. $A^c \cup A = \Omega$, and $P(A^c \cup A) = P(\Omega) = 1 = P(A^c) + P(A)$
- If A_1, \dots, A_k are a set of disjoint events such that $\sum_{i=1}^k A_i = \Omega$, then $\sum_{i=1}^k P(A_i) = P(\Omega) = 1$ (Law of Total Probability)
- Independence: A and B are said to be independent events if $P(A \cap B) = P(A)P(B)$, or
 - conditional independence: $P(A|B) = P(A)$ or, $P(B|A) = P(B)$

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Probability Theory Brief Review

• Product Law:

- Let A and B be events and assume $P(B) \neq 0$, then $P(A \cap B) = P(A|B)P(B)$.

• Random Variable: In probability, it is a **function** from Ω to a real number. Because the outcome of the experiment with sample space Ω is random, the number produced by the function is also random as well.

- Consider an experiment in which a coin is flipped three times, and the sequence of heads and tails is observed as: $\Omega = \{hhh, hht, htt, hth, ttt, tth, thh, tht\}$.
- Define the random variables such as
 - (1) the total number of heads,
 - (2) the total number of tails, and
 - (3) the number of heads minus the number of tails.
- Each of these is a real-valued function defined on Ω . In other words, each of them is a rule that assigns a real number to every point $w \in \Omega$.

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Probability Theory Brief Review

• Bayes Rule:

- defined as: Let A and B_1, \dots, B_n be events where the B_i are disjoint, $\bigcup_{i=1}^n B_i = \Omega$, and $P(B_i) > 0$ for all i, Then,
- $P(B_j|A) = \frac{P(A|B_j)P(B_j)}{\sum_{i=1}^n P(A|B_i)P(B_i)}$
- Where $\sum_{i=1}^n P(A|B_i)P(B_i) = P(A)$ is called evidence or marginal distribution of joint probability of A and B over B.
- If let $P(B_j)$ as the **prior** probability, and $P(A|B_j)$ as the likelihood function, then the **posterior** probability is given by: $P(B_j|A) = \frac{P(A|B_j)P(B_j)}{\sum_{i=1}^n P(A|B_i)P(B_i)}$. Since the evidence P(A) does not change with B, so $P(B_j|A) \propto P(A|B_j)P(B_j)$
- Based on above expression, we often say '*posterior* \propto *likelihood* \times *prior*' — This is a very important concept in machine learning, particularly in *generative* approaches.

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Probability Theory Brief Review

• Expected Values:

- **Expectation:** If X is a discrete random variable with PMF $p_X(x)$ and $g: \mathbb{R} \rightarrow \mathbb{R}$ is an arbitrary function. In this case, $g(X)$ can be considered a random variable, the expected value of $g(X)$, denoted by $E(g(X))$ is

• $E(g(X)) = \sum_{x \in X} g(x)p_X(x)$, provided that $\sum_{x \in X} |g(x)|p_X(x) < \infty$. If the sum diverges, the expectation is undefined.

• For continues random variables: $E(g(X)) = \int_{-\infty}^{\infty} g(x)f_X(x)dx$

- **Variance:** $Var(X) = E\{[X - E(X)]^2\}$ or $Var(X) = E[X^2] - [E(X)]^2$

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Probability Theory Brief Review

- Common probability distributions:

- Discrete distribution:

- Bernoulli distribution: $p(x) = \begin{cases} p & \text{if } x = 1 \\ 1 - p & \text{if } x = 0 \end{cases}$, or $p(x) = \begin{cases} p^x(1-p)^{1-x} & \text{if } x = 0 \text{ or } x=1 \\ 0 & \text{otherwise} \end{cases}$.

- Continuous distribution:

- Uniform: (where $a < b$): equal probability density to every value between a and b on the real line. $f(x) = \begin{cases} \frac{1}{b-a} & \text{if } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$

- Normal distribution or Gaussian distribution: $f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$

- It depends on two parameters: μ , called **mean**, and σ , called **variance**.

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Assignment 1

- Assignment 1 worth 10%, and is about reviews of mathematics and Python programming. Very easy (bonus!).
- Google Colab is a Jupiter Notebook running in the cloud.
- Copy and download my Colab to your Google drive (Important note: Don't modify my Colab notebook, otherwise other classmates will see your work.)
- Working on your copy of the Colab notebook. Don't forget to add your name and student id in it.
- After finishing it, share it with me (only me, do not share your work with others.)
- All programming exercises MUST be running correctly in Colab without any errors and exceptions. If your code cannot run at all, and I cannot see any kind of outputs, you receive no grade points for that part.
- Before you submit your Colab notebook, make sure to leave the outputs (results) of the functions in the notebook. I ONLY review the outputs of your functions or the final results.
- The assignment due at Feb 5th, 2021. It is an individual assignment.
- Just remind you to beware of academic integrity and responsible behaviour.
- Academic dishonesty or academic misconduct is cheating. The minimum penalty is Failing grade (F) for assignment/project.
- The consequences for any of academic dishonesty can be very serious based on university's regularization.

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Any questions?
Next section, the lab

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