Assignment3

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Problem 1

```
X \sim N(\mu, \Sigma) where X = (X_1, ... X_p)
```

The conditional distribution $X_i, X_j | X_s = x_s$ is still a Gaussian distribution with mean and covariance given by: $X_i, X_j | X_s = x_s \sim N(\mu_{ij|S}, \Sigma_{ij|S})$

$$\left(\Sigma_{\{ijS\},\{ijS\}} \right)^{-1} = \begin{pmatrix} K_{\{i,j\},\{i,j\}} & K_{\{i,j\},S} \\ K_{S,\{i,j\}} & K_{S} \end{pmatrix}$$

When $X_i \perp \!\!\! \perp X_j | X_s$ is true, $K_{ij|S} = 0$, which makes $\left(\Sigma_{\{ijS\},\{ijS\}} \right)^{-1}$ diagonal. Therefore, $X_i \perp \!\!\! \perp X_j | X_s \Rightarrow \left(\Sigma_{\{ijS\},\{ijS\}} \right)_{ij}^{-1} = 0$ holds.

When $(\Sigma_{\{ijS\},\{ijS\}})_{ij}^{-1} = 0$ is true, $K_{ij|S} = (\Sigma_{ij|S})^{-1} = 0$. $(\Sigma_{ij|S})^{-1}$ is the precision matrix for the conditional distribution $X_i, X_j | X_s = x_s$, so X_i and X_j are independent given X_s .

Therefore, $X_i \perp\!\!\!\perp X_j | X_s \Leftrightarrow (\Sigma_{\{ijS\},\{ijS\}})_{ij}^{-1} = 0.$

Problem 2

```
# simulate data from a given MRF independence model
set.seed(123)

K <- cbind(c(10,7,7,0),c(7,20,0,7),c(7,0,30,7),c(0,7,7,40))
data <- as.data.frame(mvrnorm(n=10000,mu=c(0,0,0,0),Sigma=solve(K)))
colnames(data) <- c("X1","X2","X3","X4")

K
```

```
## [,1] [,2] [,3] [,4]
## [1,] 10 7 7 0
## [2,] 7 20 0 7
## [3,] 7 0 30 7
## [4,] 0 7 7 40
```

In the precision matrix, $K_{ij}=0$ implies that variable X_i and X_j are conditionally independent given all other variables. Given the precision matrix K, $K_{14}=K_{41}=0$ and $K_{23}=K_{32}=0$. Therefore the following conditional independencies are represented by K:

$$X_1 \perp \!\!\! \perp X_4 | X \setminus \{X_1, X_4\}$$

 $X_2 \perp \!\!\! \perp X_3 | X \setminus \{X_2, X_3\}$ The corresponding graph is an undirected graph that has no edges between X_1 and

 X_4 , and X_2 and X_3 . All other pairs of variables are connected by edges. Now, I will verify the conditional independence constraints by using linear regression. $X_1 \perp \!\!\! \perp X_4 | X \setminus \{X_1, X_4\}$:

```
# conditional independence of X1 and X4 given X2, X3
m14 = lm(X1 \sim X2 + X3 + X4, data = data)
summary(m14)
##
## Call:
## lm(formula = X1 ~ X2 + X3 + X4, data = data)
##
## Residuals:
##
        Min
                   1Q
                        Median
                                      3Q
                                               Max
## -1.36729 -0.21127 0.00304 0.21389 1.20994
##
## Coefficients:
##
                 Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.001934
                            0.003141
                                        0.616
                                                  0.538
## X2
                -0.682729
                            0.012203 -55.950
                                                 <2e-16 ***
## X3
               -0.695282
                            0.015540 -44.741
                                                 <2e-16 ***
                 0.007927
## X4
                            0.020037
                                        0.396
                                                  0.692
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.3141 on 9996 degrees of freedom
## Multiple R-squared: 0.4564, Adjusted R-squared: 0.4563
## F-statistic: 2798 on 3 and 9996 DF, p-value: < 2.2e-16
In this linear model, the coefficient of X4 turned out to be non-significant with p-value <0.05.
X_2 \perp \!\!\! \perp X_3 | X \backslash \{X_2, X_3\}:
# conditional independence of X2 and X3 given X1, X4
m23 = lm(X2 \sim X1 + X3 + X4, data = data)
summary(m23)
##
## Call:
## lm(formula = X2 ~ X1 + X3 + X4, data = data)
##
## Residuals:
##
        Min
                   1Q
                        Median
                                      3Q
                                               Max
## -0.90282 -0.15318  0.00188  0.15342  0.85952
## Coefficients:
```

```
##
                Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.001141
                          0.002247
                                     0.508
                                              0.612
## X1
               -0.349303
                          0.006243 -55.950
                                              <2e-16 ***
                                              0.312
## X3
               0.012316
                          0.012177
                                     1.011
               -0.352810
                          0.013891 -25.398
                                              <2e-16 ***
## X4
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.2246 on 9996 degrees of freedom
## Multiple R-squared: 0.3841, Adjusted R-squared: 0.3839
## F-statistic: 2078 on 3 and 9996 DF, p-value: < 2.2e-16
```

In this linear model, the coefficient of X3 turned out to be non-significant with p-value <0.05.

Therefore, the conditional independencies are verified.

The list of edges are $X_1 - X_2, \, X_1 - X_3, \, X_2 - X_4, \, X_3 - X_4.$

```
# fit the model (estimate the precision matrix subject to the graph constraints)
library(gRim)
glist <- list(
    c("X1", "X2"),
    c("X1", "X3"),
    c("X2", "X4"),
    c("X3", "X4")
)
ddd <- cov.wt(data, method="ML")
fit <- ggmfit(ddd$cov, ddd$n.obs, glist) # Estimate parameters using IPF
fit$K # estimated precision matrix</pre>
```

```
## X1 X2 X3 X4

## X1 10.182411 6.988142 7.140856 0.000000

## X2 6.988142 19.832337 0.000000 7.076402

## X3 7.140856 0.000000 29.394792 6.852069

## X4 0.000000 7.076402 6.852069 40.745105
```

It appears that the model fitting worked because we can see that the estimated precision matrix has $K_{14} = K_{41} = 0$ and $K_{23} = K_{32} = 0$, and everything else non-zero, indicating that the above conditional independencies hold.

Problem 3

```
# Gaussian Bayesian Network model
# covariance matrix
```

```
set.seed(123)
Sig <- cbind(c(3,-1.4,0,0),c(-1.4,3,1.4,1.4),c(0,1.4,3,0),c(0,1.4,0,3))
data <- as.data.frame(mvrnorm(n=10000,mu=c(0,0,0,0),Sigma=Sig))
colnames(data) <- c("X1","X2","X3","X4")</pre>
```

DAG
$$\mathcal{G}: X_1 \to X_2 \leftarrow X_3 \text{ and } X_4 \to X_2$$

(a) Given the model, correlation constraints are:

$$X_1 \perp \!\!\! \perp X_3 | X_2$$

$$X_1 \perp \!\!\! \perp X_4 | X_2$$

$$X_3 \perp \!\!\! \perp X_4 | X_2$$

```
# estimate the correlation
cor(data)
```

```
## X1 X2 X3 X4

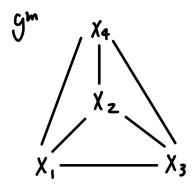
## X1 1.0000000 -0.4661188 0.012187930 -0.011504563

## X2 -0.46611880 1.0000000 0.463034923 0.473314198

## X3 0.01218793 0.4630349 1.00000000 0.006392376

## X4 -0.01150456 0.4733142 0.006392376 1.000000000
```

We can see that the correlation between X_1 and X_3 , X_1 and X_4 , X_3 and X_4 are very close to zero.



(b) The precision matrix K for \mathcal{G}^m is 4 by 4 matrix with non-zero off-diagonal elements because all the pairs in the moralized graph are connected by edges. Additionally, K indicates that

(c)

Problem 4

```
library(dagitty)

# simulate 10000 observations from the following graph
g <- dagitty( "dag{ x <- u1; u1 -> m <- u2; u2 -> y }" )
```

Problem 5

