### Assignment3

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#### Problem 1

```
X \sim N(\mu, \Sigma) where X = (X_1, ... X_p)
```

The conditional distribution  $X_i, X_j | X_s = x_s$  is still a Gaussian distribution with mean and covariance given by:  $X_i, X_j | X_s = x_s \sim N(\mu_{ij|S}, \Sigma_{ij|S})$ 

$$\left( \Sigma_{\{ijS\},\{ijS\}} \right)^{-1} = \begin{pmatrix} K_{\{i,j\},\{i,j\}} & K_{\{i,j\},S} \\ K_{S,\{i,j\}} & K_{S} \end{pmatrix}$$

When  $X_i \perp \!\!\! \perp X_j | X_s$  is true,  $K_{ij|S} = 0$ , which makes  $\left( \Sigma_{\{ijS\},\{ijS\}} \right)^{-1}$  diagonal. Therefore,  $X_i \perp \!\!\! \perp X_j | X_s \Rightarrow \left( \Sigma_{\{ijS\},\{ijS\}} \right)_{ij}^{-1} = 0$  holds.

When  $(\Sigma_{\{ijS\},\{ijS\}})_{ij}^{-1} = 0$  is true,  $K_{ij|S} = (\Sigma_{ij|S})^{-1} = 0$ .  $(\Sigma_{ij|S})^{-1}$  is the precision matrix for the conditional distribution  $X_i, X_j | X_s = x_s$ , so  $X_i$  and  $X_j$  are independent given  $X_s$ .

Therefore,  $X_i \perp\!\!\!\perp X_j | X_s \Leftrightarrow (\Sigma_{\{ijS\},\{ijS\}})_{ij}^{-1} = 0.$ 

#### Problem 2

```
# simulate data from a given MRF independence model
set.seed(123)

K <- cbind(c(10,7,7,0),c(7,20,0,7),c(7,0,30,7),c(0,7,7,40))
data <- as.data.frame(mvrnorm(n=10000,mu=c(0,0,0,0),Sigma=solve(K)))
colnames(data) <- c("X1","X2","X3","X4")

K
```

```
## [,1] [,2] [,3] [,4]
## [1,] 10 7 7 0
## [2,] 7 20 0 7
## [3,] 7 0 30 7
## [4,] 0 7 7 40
```

In the precision matrix,  $K_{ij}=0$  implies that variable  $X_i$  and  $X_j$  are conditionally independent given all other variables. Given the precision matrix K,  $K_{14}=K_{41}=0$  and  $K_{23}=K_{32}=0$ . Therefore the following conditional independencies are represented by K:

$$X_1 \perp \!\!\! \perp X_4 | X \setminus \{X_1, X_4\}$$

 $X_2 \perp \!\!\! \perp X_3 | X \setminus \{X_2, X_3\}$  The corresponding graph is an undirected graph that has no edges between  $X_1$  and

 $X_4$ , and  $X_2$  and  $X_3$ . All other pairs of variables are connected by edges. Now, I will verify the conditional independence constraints by using linear regression.  $X_1 \perp \!\!\! \perp X_4 | X \setminus \{X_1, X_4\}$ :

```
# conditional independence of X1 and X4 given X2, X3
m14 = lm(X1 \sim X2 + X3 + X4, data = data)
summary(m14)
##
## Call:
## lm(formula = X1 ~ X2 + X3 + X4, data = data)
##
## Residuals:
##
        Min
                   1Q
                        Median
                                      3Q
                                               Max
## -1.36729 -0.21127 0.00304 0.21389 1.20994
##
## Coefficients:
##
                 Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.001934
                            0.003141
                                        0.616
                                                  0.538
## X2
                -0.682729
                            0.012203 -55.950
                                                 <2e-16 ***
## X3
               -0.695282
                            0.015540 -44.741
                                                 <2e-16 ***
                 0.007927
## X4
                            0.020037
                                        0.396
                                                  0.692
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.3141 on 9996 degrees of freedom
## Multiple R-squared: 0.4564, Adjusted R-squared: 0.4563
## F-statistic: 2798 on 3 and 9996 DF, p-value: < 2.2e-16
In this linear model, the coefficient of X4 turned out to be non-significant with p-value <0.05.
X_2 \perp \!\!\! \perp X_3 | X \backslash \{X_2, X_3\}:
# conditional independence of X2 and X3 given X1, X4
m23 = lm(X2 \sim X1 + X3 + X4, data = data)
summary(m23)
##
## Call:
## lm(formula = X2 ~ X1 + X3 + X4, data = data)
##
## Residuals:
##
        Min
                   1Q
                        Median
                                      3Q
                                               Max
## -0.90282 -0.15318  0.00188  0.15342  0.85952
## Coefficients:
```

```
##
                Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.001141
                          0.002247
                                     0.508
                                              0.612
## X1
              -0.349303
                          0.006243 -55.950
                                             <2e-16 ***
                                              0.312
## X3
               0.012316
                          0.012177
                                     1.011
               -0.352810
                          0.013891 -25.398
                                             <2e-16 ***
## X4
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.2246 on 9996 degrees of freedom
## Multiple R-squared: 0.3841, Adjusted R-squared: 0.3839
## F-statistic: 2078 on 3 and 9996 DF, p-value: < 2.2e-16
```

In this linear model, the coefficient of X3 turned out to be non-significant with p-value <0.05.

Therefore, the conditional independencies are verified.

The list of edges are  $X_1 - X_2$ ,  $X_1 - X_3$ ,  $X_2 - X_4$ ,  $X_3 - X_4$ .

```
# fit the model (estimate the precision matrix subject to the graph constraints)
glist <- list(
    c("X1", "X2"),
    c("X1", "X3"),
    c("X2", "X4"),
    c("X3", "X4")
)
ddd <- cov.wt(data, method="ML")
fit <- ggmfit(ddd$cov, ddd$n.obs, glist) # Estimate parameters using IPF
fit$K # estimated precision matrix</pre>
```

```
## X1 X2 X3 X4

## X1 10.182411 6.988142 7.140856 0.000000

## X2 6.988142 19.832337 0.000000 7.076402

## X3 7.140856 0.000000 29.394792 6.852069

## X4 0.000000 7.076402 6.852069 40.745105
```

It appears that the model fitting worked because we can see that the estimated precision matrix has  $K_{14}=K_{41}=0$  and  $K_{23}=K_{32}=0$ , and everything else non-zero, indicating that the above conditional independencies hold.

#### Problem 3

```
# Gaussian Bayesian Network model
# covariance matrix
set.seed(123)
```

```
Sig <- cbind(c(3,-1.4,0,0),c(-1.4,3,1.4,1.4),c(0,1.4,3,0),c(0,1.4,0,3))
data <- as.data.frame(mvrnorm(n=10000,mu=c(0,0,0,0),Sigma=Sig))
colnames(data) <- c("X1","X2","X3","X4")
```

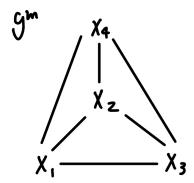
DAG 
$$\mathcal{G}$$
:  $X_1 \to X_2 \leftarrow X_3$  and  $X_4 \to X_2$ 

(a) Given the model, correlation constraints are:

```
X_1 \perp \!\!\! \perp X_3 | X_2
X_1 \perp \!\!\! \perp X_4 | X_2
X_3 \perp \!\!\! \perp X_4 | X_2
```

# # estimate the correlation cor(data)

We can see that the correlation between  $X_1$  and  $X_3$ ,  $X_1$  and  $X_4$ ,  $X_3$  and  $X_4$  are very close to zero.



(b)

The precision matrix K for  $\mathcal{G}^m$  is 4 by 4 matrix with non-zero off-diagonal elements because all the pairs in the moralized graph are connected by edges. This indicates that all the pairs are conditionally dependent given the rest of other variables, meaning that they have non-zero partial correlations. Even though the covariance matrix  $\Sigma$  shows zero direct covariances between some pairs of variables, the precision matrix K reflects the conditional dependencies imposed by the moralized graph  $\mathcal{G}^m$  where all pairs of variables are connected.

(c)

```
# estimate precision matrix K
estK = ggmfit(cov.wt(data, method = "ML")$cov, cov.wt(data, method = "ML")$n.obs, glist = glist)$K
# output estimated K
estK
```

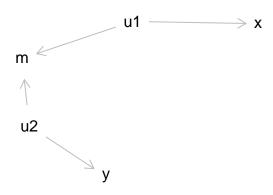
```
##
               Х1
                          X2
                                                   X4
## X1 0.427104764 0.2001358 -0.004798841 0.000000000
## X2 0.200135811 0.5291716 0.000000000 -0.202133735
## X3 -0.004798841 0.0000000 0.337174079 -0.003159849
## X4 0.000000000 -0.2021337 -0.003159849 0.418846284
# take the inverse of K
solve(estK)
              Х1
                          X2
                                     ХЗ
                                                 Х4
##
## X1 2.99172214 -1.38708078 0.03630902 -0.66912636
## X2 -1.38708078 2.95998158 -0.00635506
                                         1.42842869
## X3 0.03630902 -0.00635506 2.96652480
                                         0.01931305
## X4 -0.66912636 1.42842869 0.01931305 3.07701107
# output the true covariance matrix
Sig
##
       [,1] [,2] [,3] [,4]
## [1,] 3.0 -1.4 0.0 0.0
## [2,] -1.4 3.0 1.4 1.4
## [3,] 0.0 1.4 3.0 0.0
## [4,] 0.0 1.4 0.0 3.0
```

The estimated covariance matrix is mostly similar to true covariance matrix but differ slightly on  $X_2$  and  $X_3$ , and  $X_4$  and  $X_4$ .

#### Problem 4

```
library(dagitty)

# simulate 10000 observations from the following graph
g <- dagitty( "dag{ x <- u1; u1 -> m <- u2; u2 -> y }" )
plot(g)
```



```
# simulate data based on the DAG
set.seed(123)
n = 10000
u1 = rnorm(n)
u2 = rnorm(n)
x = u1 + rnorm(n)
m = u1 + u2 + rnorm(n)
y = u2 + rnorm(n)
data \leftarrow data.frame(x = x, m = m, y = y)
\# estimate the effect of x on y adjusting for m in a linear regression
m1 = lm(y \sim x + m, data = data)
summary(m1)
##
## Call:
## lm(formula = y \sim x + m, data = data)
##
## Residuals:
       Min
##
                1Q Median
                                3Q
                                       Max
## -4.6875 -0.8515 0.0020 0.8471 4.6296
##
## Coefficients:
                Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.011052
                           0.012631
                                      0.875
                                               0.382
## x
               -0.192179
                           0.009655 -19.905
                                              <2e-16 ***
## m
                0.411101
                           0.008010 51.320
                                             <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 1.263 on 9997 degrees of freedom
## Multiple R-squared: 0.2086, Adjusted R-squared: 0.2084
## F-statistic: 1317 on 2 and 9997 DF, p-value: < 2.2e-16
# 95% CI for the effect of x on y adjusting for m
confint(m1, "x", level = 0.95)
##
          2.5 %
                    97.5 %
```

```
## x -0.2111049 -0.1732535
```

The estimate of X on Y adjusted for M is -0.19 with a 95% CI of (-0.21, -0.17), which is statistically significant.

```
# identify the sufficient adjustment set from dagitty
adjustmentSets(g, exposure = "x", outcome = "y")
```

## {}

The empty set was returned, which makes sense because M is a collider in the path X to Y and should not be adjusted.

The new estimate and 95% CI can be obtained by the following:

```
# estimate the effect of x on y adjusting for nothing in a linear regression
m2 = lm(y \sim x, data = data)
summary(m2)
##
## Call:
## lm(formula = y ~ x, data = data)
##
## Residuals:
##
       Min
                1Q Median
                                3Q
                                       Max
  -5.1477 -0.9357 0.0027 0.9579
                                   5.3572
##
## Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.006057
                          0.014196
                                     0.427
                                               0.670
## x
               0.006232
                          0.009944
                                     0.627
                                               0.531
##
## Residual standard error: 1.42 on 9998 degrees of freedom
## Multiple R-squared: 3.928e-05, Adjusted R-squared: -6.074e-05
## F-statistic: 0.3927 on 1 and 9998 DF, p-value: 0.5309
# 95% CI for the effect of x on y adjusting for nothing
confint(m2, "x", level = 0.95)
```

```
## 2.5 % 97.5 %
## x -0.01326051 0.02572401
```

The estimate of X on Y adjusted for nothing is 0.006 with a 95% CI of (-0.013, 0.025), which is not statistically significant.

The first case implies that there is a causal effect of X on Y, and the second case implies the opposite. According to the DAG, adjusting for notation would be more appropriate when examining the effect of X on Y, and we confirmed that X has no causal effect on Y from the linear regression. The first case tells us that misadjustment can potentially create a non-existent causal effect between two variables and should be evaluated cautiously.

## Problem 5

