

Collective motion in large deviations of active particles

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in collaboration with E. Fodor, F. van Wijland, M.E. Cates, and R.L. Jack

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• yketa/DAMTP_MSC_2019_Wiki



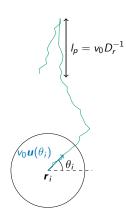








- Model of active Brownian particles.
- 2 Active work and its large deviations.
- Oescription of dynamical phase transition.
- Mechanism for collective motion.



standard ABP model

$$\dot{\mathbf{r}}_i = -D\nabla_i U(\{\mathbf{r}_j\}) + v_0 \mathbf{u}(\theta_i) + \sqrt{2D} \boldsymbol{\eta}_i \quad (1)$$
$$\dot{\theta}_i = \sqrt{2D_r} \boldsymbol{\xi}_i \quad (2)$$

$$V_1 = \sqrt{2D_1\zeta_1}$$
 (2)

$$\tilde{l}_p = v_0 D_r^{-1} / \sigma \tag{3}$$

T. Nemoto et al., Physical Review E 99, 022605 (2019).

G. S. Redner et al., Physical Review Letters 110, 055701 (2013).

How far does the active forcing translate into real motion?

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active work
$$\mathbf{w}_{\tau} = \frac{1}{v_0 N \tau} \sum_{i=1}^{N} \int_{0}^{\tau} \mathbf{u}(\theta_i) \circ \dot{\mathbf{r}}_i \, \mathrm{d}t$$
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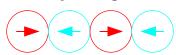
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flocking



$$\dot{\mathbf{r}}_i \approx v_0 \mathbf{u}(\theta_i) \Rightarrow \langle \mathbf{w}_{\tau} \rangle = 1$$

jamming



$$\dot{\mathbf{r}}_i \approx 0 \Rightarrow \langle \mathbf{w}_{\tau} \rangle = 0$$

Large deviations

How does the active work control emerging behaviours?

H. Touchette, Physics Reports 478, 1-69 (2009).

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T. Nemoto et al., Physical Review E 93, 062123 (2016).

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$$P_s[\{\boldsymbol{r}_i,\theta_i\}_0^{\tau}] \propto P_0[\{\boldsymbol{r}_i,\theta_i\}_0^{\tau}] e^{-sN\tau w_{\tau}}$$
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- Ompute probabilities of these fluctuations.

$$P(\mathbf{w}_{\tau}) \simeq \exp(-N\tau I(\mathbf{w}_{\tau})) \tag{8}$$

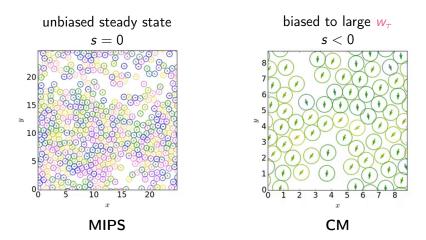
$$I(\mathbf{w}_{\tau}) = \sup_{s} \{-s\mathbf{w}_{\tau} - \psi(s)\} \tag{9}$$

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$$\nu = \frac{1}{N} \sum_{i=1}^{N} u(\theta_i), \ \bar{\nu}_{\tau} = \frac{1}{\tau} \int_{0}^{\tau} |\nu(t)| \, \mathrm{d}t$$
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separation between steady state physics and symmetry breaking physics

Modified dynamics

F. den Hollander, Large deviations, Vol. 14 (American Mathematical Soc., 2008).

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Modified dynamics

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$$I(w) \le \lim_{\tau \to \infty} \mathcal{D}_{\mathrm{KL}}(P_{g(w)}^{\mathrm{mod}} || P)$$
(15)

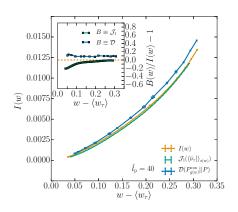
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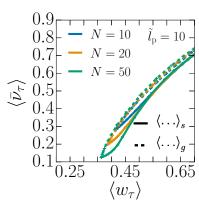
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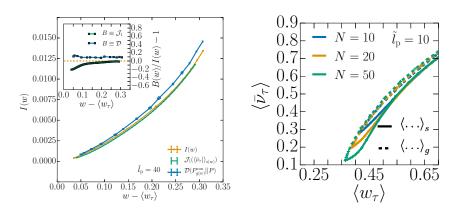
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Bounds to the rate function



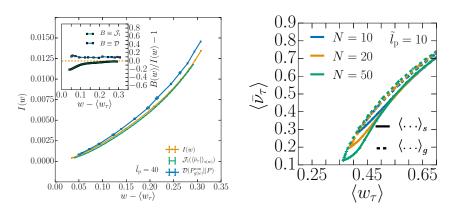


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CM: response to biasing $s \leftrightarrow$ response to aligning interaction g

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- We compute exactly for a system of **2 particles on a ring** the relation between w_{τ} and particle alignment.
- We propose a fluctuating hydrodynamic theory which captures the emergence of polar order in the biased state.

Thank you!

Suppression of density fluctuations

• At P = 0, biasing w.r.t. w_{τ} is equivalent to biasing w.r.t. $|\tilde{\rho}_{\boldsymbol{q}}|^2$.

$$S_{s}(\boldsymbol{q}) = \left\langle |\tilde{\rho}_{\boldsymbol{q}}|^{2} \right\rangle_{s} = \begin{cases} \chi_{0}, & s = 0\\ b_{s}q, & s < 0 \end{cases}$$
 (16)

 \Rightarrow We expect hyperuniformity in the isotropic s < 0 phase for $N \gg 1$.

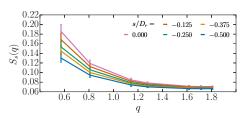


Figure: Biased structure factor S_s .

 \rightarrow Finite system shows suppression of density fluctuations for s < 0.

J. Dolezal and R. L. Jack, Journal of Statistical Mechanics: Theory and Experiment 2019, 123208 (2019).