Discrete Mathematics

Review

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Course Schedule

Topics	Courses	note
Logic	Propositional Logic	***
	Predicate Logic	****
Set Theory	Sets	***
	Functions	***
	Relations	****
Graph Theory	Graphs	***
	Trees	****
Review	All	****

Logic

Propositional logic (命题逻辑)

- Negation (否定) (NOT, ¬)
- · Conjunction (合取) (AND, △)
- Disjunction (析取) (OR, ∨)
- Conditional statement (条件) (Implication) (IF THEN→)
- Logical equivalence (逻辑等价)
 - Prove logical equivalence
- · Normal forms (范式)*
 - Disjunctive normal form (析取范式)
 - Conjunctive normal form (合取范式)

Translating English to Logical Expressions

Problem: Translate the following sentence into propositional logic:

- "You can access the Internet from campus only if you are a computer science major or you are not a freshman."
- One solution:
 - p: "You can access the internet from campus,"
 - q: "You are a computer science major,"
 - r: "You are a freshman."

Different ways of expressing $p\rightarrow q$

 $p\rightarrow (q \vee \neg r)$

```
if p, then q
if p, q
q unless ¬p
q if p
q when p
q whenever p
q follows from p
p implies q
p only if q
q when p
q is sufficient for q
q is necessary for p
```

- A necessary condition for p is q
- · A sufficient condition for q is p

Common mistake for $p\rightarrow q$

- · Correct: p only if q
- · Mistake to think "q only if p"

Logically equivalent

- Two compound propositions p and q are logically equivalent if $p \mapsto q$ is a tautology.
- We write this as $p \Leftrightarrow q$ or as $p \equiv q$ where p and q are compound propositions.
- Two compound propositions p and q are equivalent if and only if the columns in a truth table giving their truth values agree.
- This truth table show $\neg p \lor q$ is equivalent to $p \to q$.

p	9	¬p	¬p∨q	p→q
T	Т	F	T	Т
Τ	F	F	F	F
F	Т	Т	Т	Τ
F	F	Τ	Т	Т

Key logical equivalences

• Identity Laws (恒等律):

$$p \wedge T \equiv p \qquad p \vee F \equiv p$$

· Domination Laws (支配律):

$$p \lor T \equiv T$$
 $p \land F \equiv F$

• Idempotent laws (幂等律):

$$p \lor p \equiv p \qquad p \land p \equiv p$$

• Double Negation Law (双非律):

$$\neg(\neg p) \equiv p$$

• Negation Laws (否定律):

$$p \vee \neg p \equiv T$$
 $p \wedge \neg p \equiv F$

Key logical equivalences

Commutative Laws (交換律):

$$p \lor q \equiv q \lor p \qquad p \land q \equiv q \land p$$

• Associative Laws (结合律):

$$(p \land q) \land r \equiv p \land (q \land r)$$

 $(p \lor q) \lor r \equiv p \lor (q \lor r)$

• Distributive Laws (分配律):

$$(p \lor (q \land r) \equiv (p \lor q)) \land (p \lor r)$$
$$(p \land (q \lor r)) \equiv (p \land q) \lor (p \land r)$$

Absorption Laws (吸收率):

$$p \lor (p \land q) \equiv p \quad p \land (p \lor q) \equiv p$$

Equivalence proofs

$$\neg(p \lor (\neg p \land q))$$

is logically equivalent to

$$\neg p \land \neg q$$

Solution:

$$\neg(p \lor (\neg p \land q)) \quad \equiv \quad \neg p \land \neg(\neg p \land q) \qquad \text{by the second De Morgan law}$$

$$\equiv \quad \neg p \land [\neg(\neg p) \lor \neg q] \qquad \text{by the first De Morgan law}$$

$$\equiv \quad \neg p \land (p \lor \neg q) \qquad \text{by the double negation law}$$

$$\equiv \quad (\neg p \land p) \lor (\neg p \land \neg q) \qquad \text{by the second distributive law}$$

$$\equiv \quad F \lor (\neg p \land \neg q) \qquad \text{because } \neg p \land p \equiv F$$

$$\equiv \quad (\neg p \land \neg q) \lor F \qquad \text{by the commutative law}$$
for disjunction
$$\equiv \quad (\neg p \land \neg q) \qquad \text{by the identity law for } \mathbf{F}$$

Simplifying statement

We can use logical rules to simplify a logical formula.

$$abla (\neg p \land q) \land (p \lor q)$$
 $\equiv (\neg \neg p \lor \neg q) \land (p \lor q)$
 $\equiv (p \lor \neg q) \land (p \lor q)$
 $\equiv p \lor (\neg q \land q)$
 $\equiv p \lor \mathsf{False}$
 $\equiv p$

The De Morgan's Law allows us to always "move the NOT inside".

Principal disjunctive normal form (PDNF):

- 求主析取范式的方法:
 - 先化成与其等价的析取范式;
 - 若析取范式的基本积中同一命题变元出现多次,则将其化成只出现一次;
 - 去掉析取范式中所有为永假式的基本积,即去掉基本积中含有形如 $p \land \neg p$ 的子公式的那些基本积;
 - 若析取范式中缺少某一命题变元如p,则可用公式(p ∨ ¬p)∧q ⇔ q将命题变元P补充进去,并利用分配律展开,然后合并相同的基本积

Principal conjunctive normal form (PCNF)

- 求主合取范式的方法:
 - 先化成与其等价的合取范式;
 - 若合取范式的基本积中同一命题变元出现多次,则将其化成只出现一次;
 - 去掉合取范式中所有为永真式的基本积,即去掉基本和中含有形如 pv¬p的子公式的那些基本和;
 - 若合取范式中缺少某一命题变元如p,则可用公式(p / ¬p) v q ⇔ q将命题变元P补充进去,并利用分配律展开,然后合并相同的基本和



Minterm vs Maxterm

• The relations between m_i and M_i are

$$M_i \Leftrightarrow \neg m_i \quad m_i \Leftrightarrow \neg M_i$$

p,q,r	maxterms	p∧q∨r		p,q,r	minterms	p∧q∨r	
0,0,0	$p \lor q \lor r$	0	M_{O}	0,0,0	$\neg p \land \neg q \land \neg r$	0	m_0
0,0,1	$p \lor q \lor \neg r$	1	M_1	0,0,1	$\neg p \land \neg q \land r$	1	m_1
0,1,0	$p \lor \neg q \lor r$	0	M_2	0,1,0	$\neg p \land q \land \neg r$	0	m_2
0,1,1	$p \lor \neg q \lor \neg r$	1	M_3	0,1,1	$\neg p \land q \land r$	1	m_3
1,0,0	$\neg p \vee q \vee r$	0	M_4	1,0,0	$p \land \neg q \land \neg r$	0	m_4
1,0,1	$\neg p \lor q \lor \neg r$	1	M_5	1,0,1	$p \land \neg q \land r$	1	m_5
1,1,0	$\neg p \lor \neg q \lor r$	1	M_6	1,1,0	$p \land q \land \neg r$	1	m_6
1,1,1	$\neg p \lor \neg q \lor \neg r$	1	M_7	1,1,1	$p \land q \land r$	1	m_7

Translate CNF to DNF

Let CNF of A be

$$(P \lor Q \lor \neg R) \land (P \lor \neg Q \lor \neg R)$$

Find the DNF of A.

Solution:

The CNF of A is $M_1 \wedge M_3$ so the DNF can be written as

$$\sum$$
 (0, 2, 4, 5, 6, 7)

And thus we have

$$(\neg P \land \neg Q \land \neg R) \lor (\neg P \land Q \land \neg R) \lor (P \land \neg Q \land \neg R)$$
$$\lor (P \land \neg Q \land R) \lor (P \land Q \land \neg R) \lor (P \land Q \land R)$$

Find the normal forms of $(p \rightarrow \neg q) \rightarrow \neg r$

Solution:

$$(p\rightarrow \neg q)\rightarrow \neg r$$

 $\Leftrightarrow \neg (\neg p \vee \neg q) \vee \neg r$
 $\Leftrightarrow (p \wedge q) \vee \neg r$
 $\Leftrightarrow (p \vee \neg r) \wedge (q \vee \neg r)$
 $\Leftrightarrow (p \vee \neg r) \wedge (q \vee \neg r) \wedge (q \vee \neg r) \wedge (p \vee q \vee \neg r)$

Predicate Logic (谓词逻辑)

- Predicates (谓词)
- Quantifiers (量词)*
 - Universal quantifier (全称量词)
 - Existential quantifier (存在量词)
- Nested quantifiers (嵌套量词)*

Predicate



- Predicate logic uses the following new features:
 - Variables: x, y, z
 - Predicates: P(x), M(x)
 - Quantifiers: For all, symbol: ∀; There exists, symbol: ∃
- Propositional functions are a generalization of propositions.
 - They contain variables and a predicate, e.g., P(x)
 - Variables can be replaced by elements from their domain.



Quantifiers with restricted domains

 What do the following statements mean for the domain of real numbers?

$$\forall x < 0, x^2 > 0$$
 same as $\forall x (x < 0 \rightarrow x^2 > 0)$
 $\forall y \neq 0, y^3 \neq 0$ same as $\forall y (y \neq 0 \rightarrow y^3 \neq 0)$
 $\exists z > 0, z^2 = 2$ same as $\exists z (z > 0 \land z^2 = 2)$

Be careful about \rightarrow and \land in these statements



Nested quantifiers

 Nested quantifiers are often necessary to express the meaning of sentences in English as well as important concepts in computer science and mathematics.

Example: "Every real number has an inverse" is

$$\forall x \exists y(x + y = 0)$$

where the domains of x and y are the real numbers.

We can also think of nested propositional functions:

$$\forall x \exists y(x + y = 0)$$
 can be viewed as $\forall x Q(x)$ where $Q(x)$ is $\exists y P(x, y)$ where $P(x, y)$ is $(x + y = 0)$

Translating nested quantifiers into English

Example 1: Translate the statement

$$\forall x \ (C(x) \lor \exists y \ (C(y) \land F(x,y)))$$

where C(x) is "x has a computer," and F(x,y) is "x and y are friends," and the domain for both x and y consists of all students in your school.

Solution: Every student in your school has a computer or has a friend who has a computer.

Example 2: Translate the statement

$$\exists x \forall y \ \forall z \ ((F(x,y) \land F(x,z) \land (y \neq z)) \rightarrow \neg F(y,z))$$

Solution: There is a student none of whose friends are also friends with each other.

Translating English into predicate logic

Example: Translate "The sum of two positive integers is always positive" into a logical expression.

Solution:

- Rewrite the statement to make the implied quantifiers and domains explicit:
 - "For every two integers, if these integers are both positive, then the sum of these integers is positive."
- 2. Introduce the variables x and y, and specify the domain, to obtain: "For all positive integers x and y, x + y is positive."
- 3. The result is:

$$\forall x \forall y ((x > 0) \land (y > 0) \rightarrow (x + y > 0))$$

where the domain of both variables consists of all integers

量词演算规则

· 量词对 / 、 \/ 的分配律

$$\forall x (A(x) \land B(x)) \Leftrightarrow \forall x A(x) \land \forall x B(x), \\ \exists x (A(x) \lor B(x)) \Leftrightarrow \exists x A(x) \lor \exists x B(x)$$

逻辑等价式

两个命题公式等价,当且仅当在同一赋值下的真值均相同,它们只是形式不同,内涵完全相同。

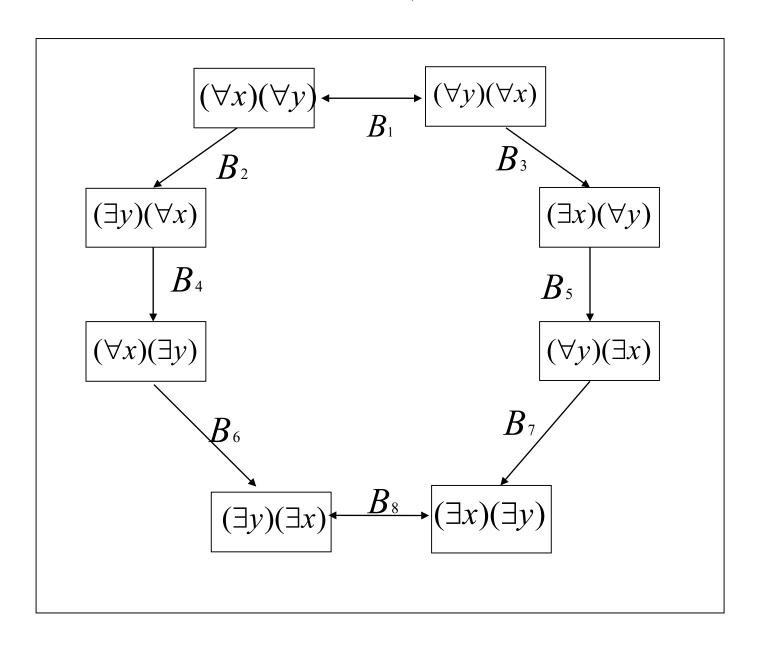
永真蕴含式

若A为真,则B必为真,就有A⇒B。

逻辑等价与永真蕴涵的关系

A⇔B, 当且仅当A⇒B且B⇒A。

记忆规律



Set

Key Points

- set, subset (proper subset 真子集)
- Cardinality (基数: Size of a Set)
- Set Operations
 - Union (并)
 - Intersection (交)
 - Difference (差)
 - Complement (补)
 - Symmetric Difference (对称差) (Option)

Sets

- Set = a collection of distinct unordered objects
- Members of a set are called elements
- How to determine a set
 - Listing
 - Example: $A = \{1,3,5,7\} = \{7,5,3,1,3\}$
 - Description
 - Example: $B = \{x \mid x=2k+1, 0 < k < 30\}$
 - Venn Diagrams
 - A Venn diagram provides a graphic view of sets
 - Venn diagrams are useful in representing sets and set operations which can be easily and visually identified.

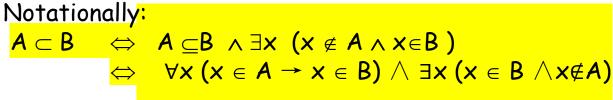
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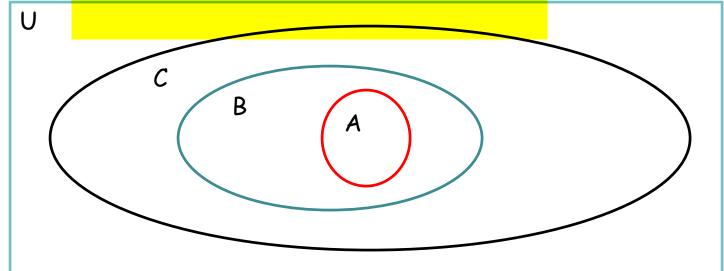
 Various sets are represented by circles inside a big rectangle representing the universal set.

Subsets

- Useful rules:
- $A = B \Leftrightarrow (A \subseteq B) \land (B \subseteq A)$
- $(A \subseteq B) \land (B \subseteq C) \Rightarrow A \subseteq C \text{ (next Venn Diagram)}$

When " \subset " is used instead of " \subseteq ", proper containment is meant. subset A of B is said to be a **proper subset** if A is not equal to B.





Cardinality

Hint: After eliminating the redundancies just look at the number of top level commas and add 1 (except for the empty set).

A:

- 1. $|\{1, -13, 4, -13, 1\}| = |\{1, -13, 4\}| = 3$
- 2. $|\{3, \{1,2,3,4\}, \emptyset\}| = 3$. To see this, set $S = \{1,2,3,4\}$. Compute the cardinality of $\{3,5,\emptyset\}$
- 3. $|\{\}| = |\emptyset| = 0$
- 4. $|\{\{\}, \{\{\}\}\}, \{\{\{\}\}\}\}\}| = |\{\emptyset, \{\}, \{\emptyset\}, \{\{\emptyset\}\}\}| = 3$

Power Set (幂集)

Definition: The power set of S is the set of all subsets of S.

Denote the power set by P(S) or by 2^{s} .

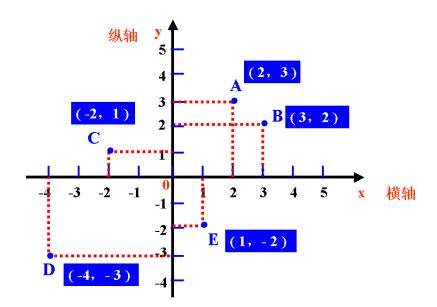
The latter weird notation comes from the following.

Lemma: $|2^{s}| = 2^{|s|}$

Cartesian Product (笛卡儿积)

The most famous example of 2-tuples are points in the Cartesian plane \mathbf{R}^2 . Here ordered pairs (x,y) of elements of \mathbf{R} describe the coordinates of each point. We can think of the first coordinate as the value on the x-axis and the second coordinate as the value on the y-axis.

Definition: The Cartesian product of two sets A and B -denoted by $A \times B$ - is the set of all ordered pairs (a, b) where $a \in A$ and $b \in B$.



Cartesian Product

A: $A = \{1,2\}, B = \{3,4\}, C = \{5,6,7\}$ $A \times B \times C = \{(1,3,5), (1,3,6), (1,3,7), (1,4,5), (1,4,6), (1,4,7), (1,4,7), (1,4,6), (1,4,7), (1,4,7), (1,4,6), (1,4,7), ($

(2,3,5), (2,3,6), (2,3,7),

(2,4,5), (2,4,6), (2,4,7)

Lemma: The cardinality of the Cartesian product is the product of the cardinalities:

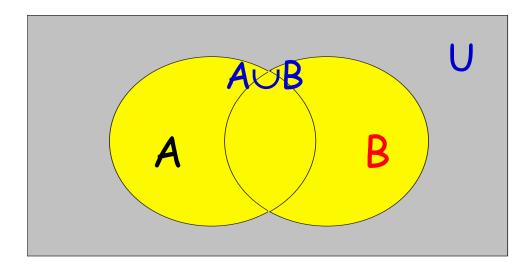
$$|A_1 \times A_2 \times ... \times A_n| = |A_1| \cdot |A_2| \cdot ... \cdot |A_n|$$

Q: What does $\emptyset \times S$ equal?

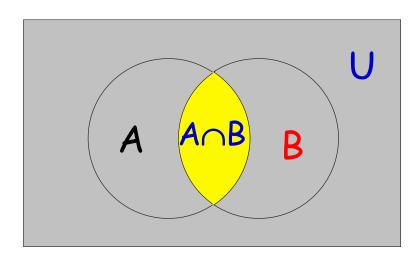
A: From the lemma:

$$|\varnothing \times S| = |\varnothing| \cdot |S| = 0 \cdot |S| = 0$$

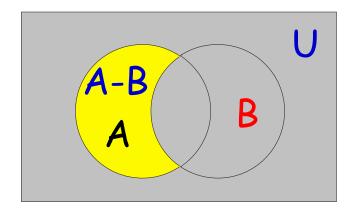
- Union: Elements in at least one of the two sets.
 - $A \cup B = \{x \mid x \in A \lor x \in B\}$
 - Example:
 - $A = \{a, b\}, B = \{b, c, d\}$
 - $A \cup B = \{a, b, c, d\}$



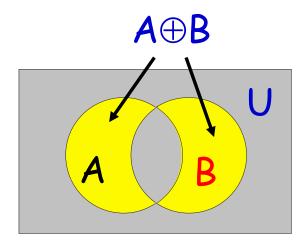
- Intersection: Elements in exactly one of the two sets.
 - $A \cap B = \{x \mid x \in A \land x \in B\}$
 - Example:
 - $A = \{a, b\}, B = \{b, c, d\}$
 - $A \cap B = \{b\}$



- Difference: Elements in first set but not second. Difference is also called the relative complement (相对补) of B in A.
 - $A-B = \{x \mid x \in A \land x \notin B\} = A \cap B^c$
 - Example
 - $A = \{a, b\}, B = \{b, c, d\}$
 - $A-B = \{a\}$



- Symmetric Difference: Elements in exactly one of the two sets.
 - $A \oplus B = \{ x \mid x \in A \oplus x \in B \} = (A B) \cup (B A) = (A \cup B) (A \cap B)$
 - Example:
 - $A = \{a, b\}, B = \{b, c, d\}$
 - $A \oplus B = \{a,c,d\}$



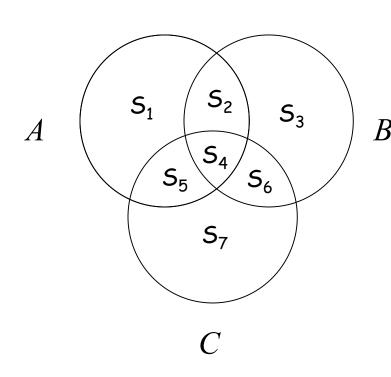
Using Properties of Set Operations

- How can we prove $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$?
- Method I:
- $x \in A \cup (B \cap C)$
- $\Leftrightarrow x \in A \lor x \in (B \cap C)$
- $\Leftrightarrow x \in A \lor (x \in B \land x \in C)$
- \Leftrightarrow ($x \in A \lor x \in B$) \land ($x \in A \lor x \in C$)
- (distributive law for logical expressions)
- $\Leftrightarrow x \in (A \cup B) \land x \in (A \cup C)$
- $(A \cup B) \cap (A \cup C)$

Using Properties of Set Operations

Method II: Venn Diagram

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$



L.H.S

$$A = S_1 \cup S_2 \cup S_4 \cup S_5$$

$$B \cap C = S_4 \cup S_6$$

$$A \cup (B \cap C) = S_1 \cup S_2 \cup S_4 \cup S_5 \cup S_6$$

R.H.S.

$$(A \cup B) = S_1 \cup S_2 \cup S_3 \cup S_4 \cup S_5 \cup S_6$$

 $(A \cup C) = S_1 \cup S_2 \cup S_4 \cup S_5 \cup S_6 \cup S_7$
 $(A \cup B) \cap (A \cup C) = S_1 \cup S_2 \cup S_4 \cup S_5 \cup S_6$

Using Properties of Set Operations

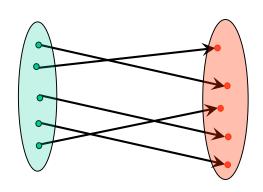
- Method III: Membership table
 - 1 means "x is an element of this set"
 - 0 means "x is not an element of this set"

ABC	Bnc	$A \cup (B \cap C)$	$A \cup B$	A U C	$(A \cup B) \cap (A \cup C)$
000	0	0	0	0	0
001	0	0	0	1	0
010	0	0	1	0	0
011	1	1	1	1	1
100	0	1	1	1	1
101	0	1	1	1	1
110	0	1	1	1	1
111	1	1	1	1	1

Functions

More formally, we write $f:A \to B$

to represent that f is a function from set A to set B, which associates an element $f(a) \in B$ with an element $a \in A$.



The domain (input) of f is A.

The codomain (output) of f is B.

Definition: For every input there is exactly one output.

Note: the input set can be the same as the output set, e.g. both are integers.

Properties of Functions

- A function $f:A\to B$ is said to be one-to-one (or injective (单射)), if and only if $\forall x, y \in A$ ($f(x) = f(y) \to x = y$)
- In other words: f is one-to-one if and only if it does not map two distinct elements of A onto the same element of B.
- How can we prove that a function f is one-to-one?
 - Whenever you want to prove something, first take a look at the relevant definition(s):

$$\forall x, y \in A (f(x) = f(y) \rightarrow x = y)$$

Example:

$$f: \mathbf{R} \rightarrow \mathbf{R}$$

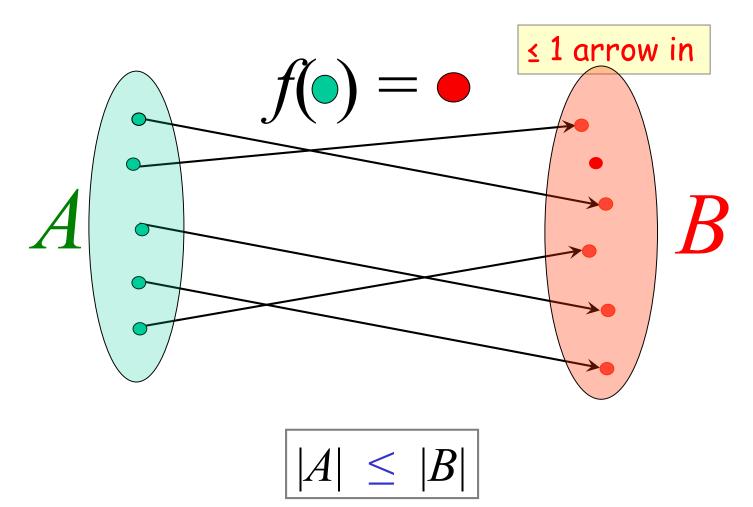
 $f(x) = x^2$

Disproof by counterexample:

$$f(3) = f(-3)$$
, but $3 \neq -3$, so f is not one-to-one.

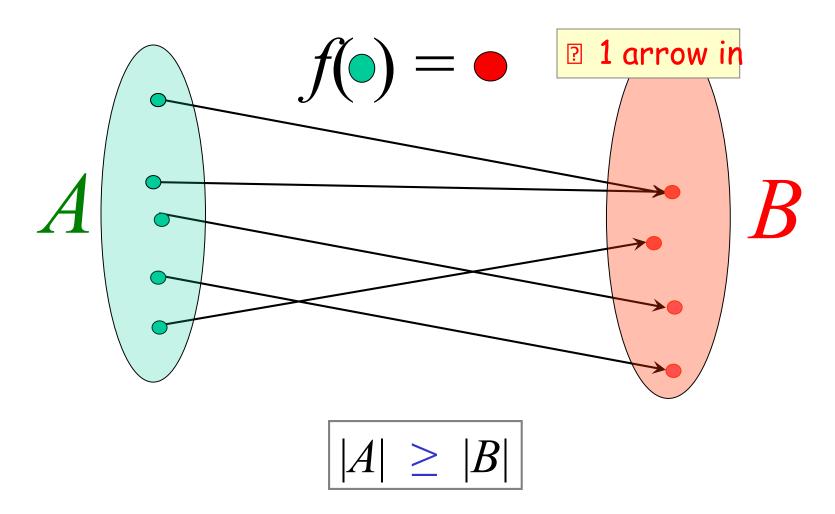
Injections

 $f:A \to B$ is an injection if no two inputs have the same output.



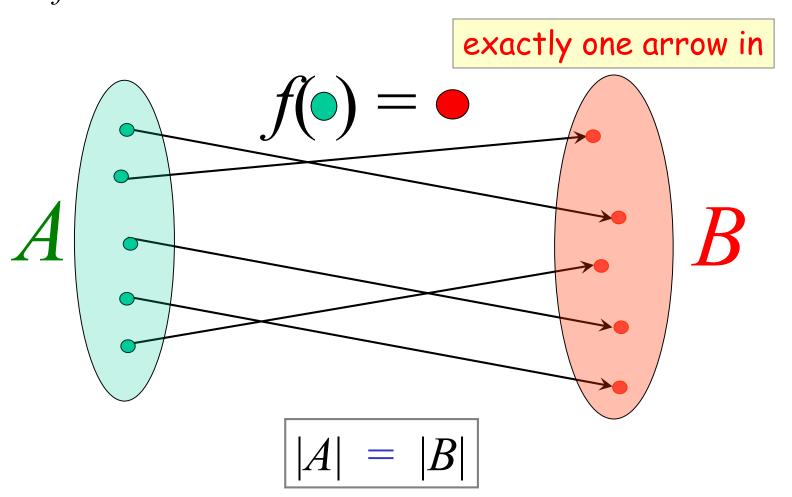
Surjections

 $f:A \to B$ is a surjection if every output is possible.



Bijections

 $f:A \to B$ is a bijection if it is surjection and injection.



Composition

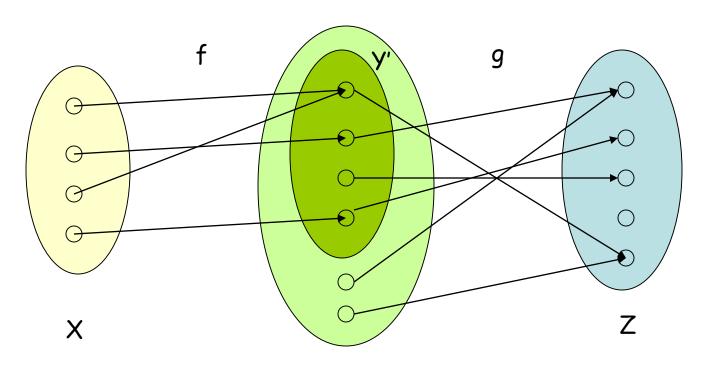
- The composition of two functions $g:A \rightarrow B$ and $f:B \rightarrow C$, denoted by $f\circ g$, is defined by $(f\circ g)(a) = f(g(a))$
- This means that
 - first, function g is applied to element $a \in A$, mapping it onto an element of B,
 - then, function f is applied to this element of B, mapping it onto an element of C.
 - Therefore, the composite function maps from A to C.

Example:

$$f(x) = 7x - 4$$
, $g(x) = 3x$,
 $f: \mathbf{R} \to \mathbf{R}$, $g: \mathbf{R} \to \mathbf{R}$
 $(f^{\circ}g)(5) = f(g(5)) = f(15) = 105 - 4 = 101$
 $(f^{\circ}g)(x) = f(g(x)) = f(3x) = 21x - 4$

Composition of Functions

Two functions $f:X\to Y'$, $g:Y\to Z$ so that Y' is a subset of Y, then the composition of f and g is the function $g\circ f\colon X\to Z$, where $g\circ f(x)=g(f(x))$.



Summary

- f,g injective, fog injective
- f,g surjective, fog surjective
- f, g bijective, fog bijective

If fog injective, then g injective

反证

- · 假设g不是单射,则存在a不等于b,满足g(a)=g(b)
- ==> fg(a)=fg(b)(1)
- · 因为fg是单射, a不等于b
- ==>fg(a) \neq fg(b) (2)
- 矛盾
- · 故g是单射!

fog surjective, f surjective?

Modulus operator (模运算)

- Let x be a nonnegative integer and y a positive integer
- $r = x \mod y$ is the remainder when x is divided by y
 - Examples:

 $1 = 13 \mod 3$

 $6 = 234 \mod 19$

4 = 2002 mod 111

- Basically, remove the complete y's and count what's left
- mod is called the modulus operator

取模运算("Modulo Operation")和取余运算("Complementation")两个概念有重叠的部分但又不完全一致。区别在于对负整数进行除法运算时操作不同。

如:

1.求 整数商: c = a/b;

2.计算模或者余数: r = a - c*b.

求模运算和求余运算在第一步不同: 取余运算在取c的值时,向0 方向舍入;而取模运算在计算c的值时,向负无穷方向舍入。

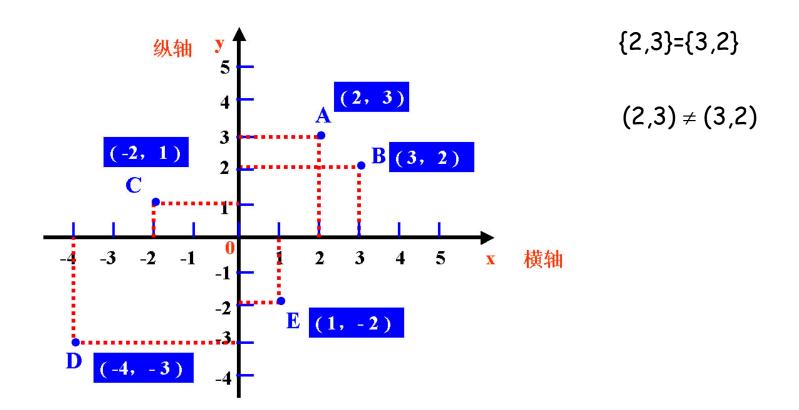
当a,b符号不一致时。求模结果的符号和b一致,求余运算结果的符号和a一致。

Relations

- Cartesian Product, Relations and Binary Relations
- Properties of relations
 - reflexive (自反), irreflexive (反自反), symmetric (对称), antisymmetric (反对称), transitive (传递)
- Representing Binary Relations
- Operations of relations
- · Closure (闭包)

Cartesian product (笛卡尔积)

- If A_1 , A_2 , ..., A_m are nonempty sets, then the **Cartesian Product** of them is the set of all ordered m-tuples $(a_1, a_2, ..., a_m)$, where $a_i \in A_i$, i = 1, 2, ... m.
- Denoted $A_1 \times A_2 \times ... \times A_m = \{(a_1, a_2, ..., a_m) \mid a_i \in A_i, i = 1, 2, ... m\}$



Using matrices to denote Cartesian product

- If $A = \{1, 2, 3\}$ and $B = \{a, b, c\}$, find $A \times B$
- $A \times B = \{(1,a), (1,b), (1,c), (2,a), (2,b), (2,c), (3,a), (3,b), (3,c)\}$
- For Cartesian Product of two sets, you can use a matrix to find the sets.
- Example: Assume A = $\{1, 2, 3\}$ and B = $\{a, b, c\}$. The table below represents A \times B.

	а	b	С	
1	(1, a)	(1, b)	(1, c)	
2	(2, a)	(2, b)	(2, c)	
3	(3, a)	(3, b)	(3, c)	

The cardinality of the Cartesian Product equals the product of the cardinality of all of the sets:

$$|A_1 \times A_2 \times ... \times A_m| = |A_1| \cdot |A_2| \cdot ... \cdot |A_m|$$

Relations: Subsets of Cartesian products

A:

1. Database \subseteq {Names} \times {Foods} \times {Colors} \times {Jobs}

Definition: Let A_1 , A_2 , ..., A_n be sets. An n-ary relation on these sets (in this order) is a subset of $A_1 \times A_2 \times ... \times A_n$.

Most of the time we consider n = 2 in which case have a binary relation and also say the relation is "from A_1 to A_2 ".

With this terminology, all functions are relations, but not vice versa.



Binary relations *

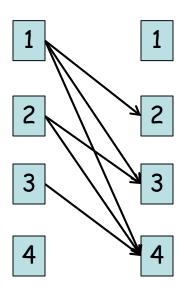
- Given two sets A and B, its Cartesian product $A \times B$ is the set of all ordered pairs (a, b) where $a \in A$ and $b \in B$
 - In symbols $A \times B = \{(a, b) | a \in A \text{ and } b \in B\}$
- **Definition**: Let A and B be sets. A binary relation R from a set A to a set B is a subset of the Cartesian product $A \times B$.
- In other words, for a binary relation R we have $R \subseteq A \times B$. We use the notation aRb to denote that $(a, b) \in R$ and aRb to denote $(a, b) \notin R$.

Example: $A = \{1, 2, 3\}$ and $B = \{a, b\}$ $R = \{(1, a), (1, b), (2, b), (3, a)\}$ is a relation between A and B. 3 is related to a by R.

Example: Let P be a set of people, C be a set of cars, and D be the relation describing which person drives which car(s).

Binary relations on a set*

• Solution: R={(1,2),(1,3),(1,4),(2,3),(2,4),(3,4)}

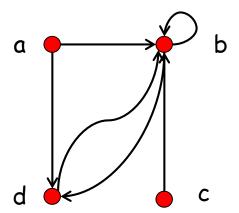


R	1	2	3	4
1		×	×	×
2			×	×
3				×
4				

Representing binary relations

 We have many ways of representing binary relations. We now take a closer look at two ways of representation: Boolean (zero-one) matrices and directed graphs.

	<i>C</i> 1	C2	<i>C</i> 3	<i>C</i> 4	<i>C</i> 5
P1	0	0	0	1	1
P2	1	0	0	1	0
Р3	0	0	0	0	0





The matrix of a relation

- If R is a relation from a set X to itself and M_R is the matrix of R, then
 M_R is a square matrix.
- Example: Let $X = \{2,3,4,5\}$ and $R = \{(x,y) \mid x+y \text{ divides by 3}\}$. Then :

fill it

Properties of relations

Special properties for relation on a set A:

- Reflexive : every element is self-related. I.e. aRa for all $a \in A$
- Symmetric: order is irrelevant. I.e. for all $a,b \in A$ aRb iff bRa
- Transitive: when a is related to b and b is related to c, it follows that a is related to c. I.e. for all a,b,c $\in A$ aRb and bRc implies aRc
- Q: Which of these properties hold for:
- 1) "Siblinghood"
- 2) "<"

3) "≤"



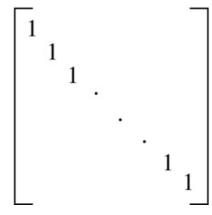
Properties of relations

- Warnings: there are additional concepts with confusing names
 - Antisymmetric: not equivalent to "not symmetric". Meaning: it's never the case for a ≠ b that both aRb and bRa hold.
 - Asymmetric: also not equivalent to "not symmetric". Meaning: it's never the case that both aRb and bRa hold.
 - Irreflexive: not equivalent to "not reflexive". Meaning: it's never the case that aRa holds.

Reflexive

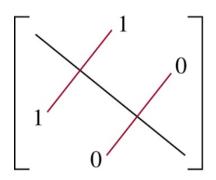
- The matrix of a relation on a set, which is a square matrix, can be used to determine whether the relation has certain properties
- Recall that a relation R on A is reflexive if (a,a)∈R. Thus R is reflexive
 if and only if (a_i,a_i)∈R for i=1,2,...,n
- Hence R is reflexive iff m_{ii}=1, for i=1,2,..., n.
- R is reflexive if all the elements on the main diagonal of M_R are 1

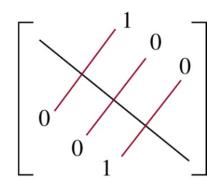
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Visualization

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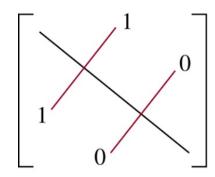


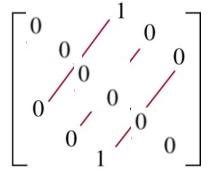


(a) Symmetric

(b) Antisymmetric

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(a) Symmetric

(b) Asymmetric

Symmetric, Asymmetric and Antisymmetric

- · 对称的(symmetric):对所有的aRb,都有bRa
- 非对称的(not symmetric): 存在一些aRb,满足bRa
- · 不对称的(asymmetric):对所有的aRb,都有bRa
- 非不对称的(not asymmetric): 存在一些aRb,满足bRa
- 反对称的(antisymmetric): 对所有的aRb和bRa,都有a=b
- 非反对称的(not antisymmetric): 存在一些a≠b,满足aRb和bRa
 可见:
- (1) asymmetric→not symmetric,而not symmetric不能得出asymmetric
- · (2) asymmetric→antisymmetric,而antisymmetric不能得出asymmetric

举例1: A={1,2,3,4},R={(1,2),(2,2),(3,4),(4,1)},则:

- R是非对称的(not symmetric),因为(1,2)属于R,而(2,1)不属于R;
- R是非不对称的(not asymmetric),因为(2,2)属于R
- · R是反对称的(antisymmetric),因为对于任意azb,不存在(a,b)和(b,a)都属于R

Useful summary

- Let R be a relation on a set A, i.e. R is a subset of the Cartesian product $A \times A$
 - R is **reflexive** if $(x, x) \in R$ for every $x \in A$
 - R is irreflexive if $(x, x) \notin R$ for every element $x \in A$.
 - R is symmetric if for all x, y \in A such that $(x,y) \in$ R then $(y,x) \in$ R
 - R is antisymmetric if for all $x, y \in A$ such that $x \neq y$, if $(x, y) \in R$ then $(y, x) \notin R$
 - R is transitive if $(x, y) \in R$ and $(y, z) \in R$ imply $(x, z) \in R$

Operators on Relations

- Operators on Sets
- Inversion
- Composite *

Combining Relations

- Let R₁ be a relation from X to Y
- Let R₂ be a relation from Y to Z
- **Definition**: The composition of R_1 and R_2 , denoted $R_2 \bullet R_1$ (or $R_2 \odot R_1$), is a relation from X to Z defined by $\{(x, z) \mid (x, y) \in R_1 \text{ and } (y, z) \in R_2 \text{ for some } y \in Y\}$
- In other words, if relation R_1 contains a pair (x, y) and relation R_2 contains a pair (y, z), then $R_2 R_1$ contains a pair (x, z).

 $R_2 \bullet R_1$ contains a pair $(x, z) : x R_2 \bullet R_1 z$

Definition: If R is a relation from A to B, and S is a relation from B to C then the **composite** of R and S is the relation $S \cdot R$ (or just SR) from A to C defined by setting a $S \cdot R$ c if and only if there is some b such that aRb and bSc.

Notation is weird because generalizing functional composition: $f \cdot g(x) = f(g(x))$.

Combining Relations

Composite relation: $S \circ R$

$$(a, b) \in S \circ R \leftrightarrow \exists x : (a, x) \in R \land (x, b) \in S$$

Note:

$$(a, b) \in R \land (b, c) \in S \rightarrow (a, c) \in S \circ R$$

Example:

$$R = \{ (1,1), (1,4), (2,3), (3,1), (3,4) \}$$

$$S = \{ (1,0), (2,0), (3,1), (3,2), (4,1) \}$$

$$S \circ R = \{ (1,0), (1,1), (2,1), (2,2), (3,0), (3,1) \}$$

Examples

- Let X and Y be relations on A = {1, 2, 3, ...}.
- $X = \{(a, b) \mid b = a + 1\}$ "b equals a plus 1" $(X = \{(b, c) \mid c = b + 1\}$ "c equals b plus 1")
- $Y = \{(a, b) \mid b = 3a\}$ "b equals 3 times a" $(Y = \{(b, c) \mid c = 3b\}$ "c equals 3 times b")

Y maps an element a to the element 3a, and afterwards X maps 3a to 3a + 1), resulting in X • Y= $\{(a,b) \mid b = 3a + 1\}$ X • Y= $\{(a,c) \mid c = 3a + 1\} = \{(a,b) \mid b = 3a + 1\}$

$$Y \bullet X = \{(a, b) \mid b = 3a + 3\}$$

Power of relations

Power of relation: R^n

$$R^0 = I_A \qquad R^1 = R \quad R^{n+1} = R^n \circ R$$

Example:
$$R = \{ (1,1), (2,1), (3,2), (4,3) \}$$

$$R^2 = R \circ R = \{ (1,1), (2,1), (3,1), (4,2) \}$$

$$R^3 = R^2 \circ R = \{(1,1), (2,1), (3,1), (4,1)\}$$

$$R^4 = R^3 \circ R = R^3$$

Power of relations

Theorem: Suppose |A|=n, R is a relation on A. Then there exists s and t, such that $R^s=R^t$, $0 < s,t < 2^{n^2}$

Proof:

For any k, R^k is the subset of AxA, as $|AxA| = n^2$, $|P(AxA)| = 2^{n^2}$. Then we can list all the relations as R^0 , R^1 , ..., $R^{2^{n^2}}$. It is easy to check that there are $2^{n^2} + 1$ relations. So there must exist $R^s = R^t$, $0 < s, t < 2^{n^2}$

有穷集合上关系的幂序列式一个周期变化的序列!

Examples

 $X=\{a,b,c\}$, R_1 , R_2 , R_3 , R_4 , Show the power of these relations

$$R_{1} = \{(a,b),(a,c),(c,b)\}$$

$$R_{2}^{2} = \{(a,b)\}, R_{1}^{3} = \emptyset, R_{1}^{4} = \emptyset, \cdots$$

$$R_{2}^{2} = \{(a,c),(b,a),(c,b)\},$$

$$R_{2}^{3} = \{(a,a),(b,b),(c,c)\} = R_{2}^{0}$$

$$R_{2}^{4} = R_{2}, R_{2}^{5} = R_{2}^{2}$$

$$R_{2}^{6} = R_{2}^{3}, \cdots$$

$$R_{3}^{2} = \{(a,c),(b,c),(c,c)\} = R_{3}^{3} = R_{3}^{4} = R_{3}^{5} \cdots$$

$$R_{4}^{2} = \{(a,a),(b,b),(c,c)\} = R_{3}^{3} = R_{3}^{4} = R_{3}^{5} \cdots$$

$$R_{4}^{2} = \{(a,a),(b,b),(c,c)\} = R_{4}^{0}$$

$$R_{4}^{3} = R_{4}, R_{4}^{5} = R_{4}^{3} \cdots$$

Summary

Theorem: Let R be the relation on a set A. Then we have

R is reflexive iff $I_A \subseteq R$

R is irreflexive iff $I_A \cap R = \emptyset$

R is symmetric iff $R = R^{-1}$

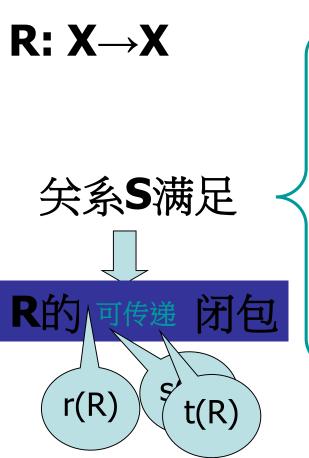
R is antisymmetric iff $R \cap R^{-1} \subseteq I_A$

R is transitive iff $R \bullet R \subseteq R$

Theorem:

A relation R is transitive if an only if $R^n \subseteq R$ for all $n = 1, 2, 3, \dots$

Closures of Relations



(1) S 是自可传递的

(2)R⊆ S

(3)对任何 可传递 关系S'

 $R \subseteq S'$



S⊆S'

Reflexive Closures

• **Example**: Find the reflexive closure of relation $R = \{(1, 1), (1, 2), (2, 1), (3, 2)\}$ on the set $A = \{1, 2, 3\}$.

· Solution:

- We know that any reflexive relation on A must contain the elements (1,1), (2,2), and (3, 3).
- By adding (2, 2) and (3, 3) to R, we obtain the reflexive relation S, which is given by $S = \{(1, 1), (1, 2), (2, 1), (2, 2), (3, 2), (3, 3)\}.$
- S is reflexive, contains R, and is contained within every reflexive relation that contains R.
- Therefore S is reflexive closure of R.

Symmetric Closures

- Example: Find the symmetric closure of the relation R = {(a, b) | a > b}
 on the set of positive integers.
- Solution:
 - The symmetric closure of R is given by $R \cup R^{-1} = \{(a, b) \mid a > b\} \cup \{(b, a) \mid a > b\} = \{(a, b) \mid a \neq b\}$

Transitive Closures

• **Example:** Find the transitive closure of the relation $R = \{(1, 3), (1, 4), (2, 1), (3, 2)\}$ on the set $A = \{1, 2, 3, 4\}$.

· Solution:

- R would be transitive, if for all pairs (a, b) and (b, c) in R there were also a pair (a, c) in R.
- If we add the missing pairs (1, 2), (2, 3), (2, 4), and (3, 1), will R be transitive?
- No, because the extended relation R contains (3, 1) and (1, 4), but does not contain (3, 4).
- By adding new elements to R, we also add new requirements for its transitivity. We need to look at paths in digraphs to solve this problem.
- Imagine that we have a relation R that represents all train connections in the US.

Transitive Closures

Therefore, R* is the union of Rⁿ across all positive integers n:

$$R^* = \bigcup_{n=1}^{\infty} R^n = R^1 \bigcup R^2 \bigcup R^3 \cdots$$

Theorem: For a relation R on a set A with n elements, the transitive closure R* is given by:

$$R^* = R \cup R^2 \cup R^3 \cup ... \cup R^n$$

For matrices representing relations we have:

$$M_{R^*} = M_R \vee M_R^{[2]} \vee M_R^{[3]} \vee ... \vee M_R^{[n]}$$

Equivalence Relations



- Equivalence relations are used to relate objects that are similar in some way.
- **Definition**: A relation on a set A is called an equivalence relation if it is reflexive, symmetric, and transitive.
- Two elements that are related by an equivalence relation R are called equivalent.

Equivalence Relations

Example: Suppose that R is the relation on the set of strings that
consist of English letters such that aRb if and only if I(a)=I(b), where
I(x) is the length of the string x. Is R an equivalence relation?

Solution:

- R is reflexive, because I(a) = I(a) and therefore aRa for any string a.
- R is symmetric, because if I(a) = I(b) then I(b) = I(a), so if aRb then bRa.
- R is transitive, because if I(a) = I(b) and I(b) = I(c), then I(a) = I(c), so aRb and bRc implies aRc.
- R is an equivalence relation.

Equivalence Classes

- Definition: Let R be an equivalence relation on a set A. The set of all elements that are related to an element a of A is called the equivalence class of a.
- The equivalence class of a with respect to R is denoted by $[a]_R$.
- When only one relation is under consideration, we will delete the subscript R and write [a] for this equivalence class.
- If $b \in [a]_R$, b is called a representative of this equivalence class.

Equivalence relations

Example:

- Consider set $X = \{1,2,...,13\}$. Define xRy as 5 divides x y (i.e., x y = 5k, for some int k). We can verify that R is reflexive, symmetric, and transitive. Here is how.
- The equivalence class [1] consists of all x with xR1. Thus:
 - [1] = $\{x \in X \mid 5 \text{ divides } x 1\} = \{1, 6, 11\}$
- Similarly:
 - \cdot [2] = {2, 7, 12}
 - \cdot [3] = {3, 8, 13}
 - $[4] = \{4, 9\}$
 - · [5] = {5, 10}

- Definition: Let X be a set and R a relation on X, R is a partial order on X if R is reflexive, antisymmetric and transitive. A set X together with a partial ordering R is called a partially ordered set, or poset, or PO, and is denoted by (X, R).
- Example: Is $(x, y) \in R$ in partial order if $x \ge y$?
 - Yes, since:
 - Reflexive: $(x, x) \in R$
 - Anti-symmetric: If $(x, y) \in R$ and $x \neq y$, then $(y, x) \notin R$
 - Transitive: If $(x, y) \in R$ and $(y, z) \in R$, then $(x, z) \in R$

- Example: Is the "inclusion relation"

 a partial ordering on the power set of a set 5?
 - \subseteq is reflexive, because $A \subseteq A$ for every set $A \in S$.
 - \subseteq is antisymmetric, because if $A \neq B$, then $A \subseteq B \land B \subseteq A$ is false.
 - \subseteq is transitive, because if $A \subseteq B$ and $B \subseteq C$, then $A \subseteq C$.
- Consequently, $(P(S), \subseteq)$ is a partially ordered set or poset.

- Let $x,y \in X$,
 - If (x,y) or (y,x) are in R, then x and y are comparable.
 - If $(x,y) \notin R$ and $(y,x) \notin R$, then x and y are incomparable.
 - **Definition**: If every pair of elements in X are comparable, then R is a total order on X.
 - In this case, X is called a totally ordered or linearly ordered set, and ≤ is called a total order or linear order. A totally ordered set is also called a chain.

- Example: Is (Z, \le) a totally ordered poset?
 - Yes, because $a \le b$ or $b \le a$ for all integers a and b.
- Example: Is (Z⁺, division) a totally ordered poset?
 - No, because it contains incomparable elements such as 5 and 7.

- In a poset the notation $a \le b$ denotes that $(a, b) \in R$.
- Note that the symbol ≤ is used to denote the relation in any poset, not just the "less than or equal" relation.
- The notation a < b denotes that $a \le b$, but $a \ne b$.
- If a < b we say "a is less than b" or "b is greater than a".

Lexicographic Order

- How can we define a lexicographic ordering on the set of English words?
- This is a special case of an ordering of strings on a set constructed from a partial ordering on the set.
- We already have an ordering of letters (such as a < b, b < c, ...), and from that we want to derive an ordering of strings.
- Let us take a look at the general case, that is, how the construction works in any poset.

Lexicographic Order

- First step: Construct a partial ordering on the Cartesian product of two posets, (A_1, \leq_1) and (A_2, \leq_2) :
- (a_1,a_2) (b_1,b_2) if $(a_1 <_1 b_1) \lor [(a_1=b_1) \land (a_2 <_2 b_2)]$
- $(a_1,a_2) \le (b_1,b_2)$ if $(a_1 <_1 b_1) \lor [(a_1 = b_1) \land (a_2 \le_2 b_2)]$
- Examples:
 - In the poset $(Z \times Z, \leq)$, ...
 - is (5, 5) < (6, 4)? YES
 - is (6, 5) < (6, 4)? NO
 - is (3, 3) < (3, 3) ? NO

Lexicographic Order

- Second step: Extend the previous definition to the Cartesian product of n posets (A_1, \leq_1) , (A_2, \leq_2) , ..., (A_n, \leq_n) :
- $(a_1, a_2, ..., a_n)$ < $(b_1, b_2, ..., b_n)$ if $(a_1 <_1 b_1) \lor \exists i>0$ $(a_1 = b_1, a_2 = b_2, ..., a_i = b_i, a_{i+1} <_{i+1} b_{i+1})$
- $(a_1, a_2, ..., a_n) \le (b_1, b_2, ..., b_n)$ if $(a_1 <_1 b_1) \lor \exists i > 0$ $(a_1 = b_1, a_2 = b_2, ..., a_i = b_i, a_{i+1} <_{i+1} b_{i+1}) \lor (a_1 = b_1, a_2 = b_2, ..., a_n = b_n)$
- Examples:
 - Is (1,1,1,2,1) < (1,1,1,1,2)? No
 - Is (1, 1, 1, 1, 1) < (1, 1, 1, 1, 2)? Yes

Hasse Diagram (哈斯图)

- Hasse diagram is a graphical display of a poset.
- A point is drawn for each element of the poset, and line segments are drawn between these points according to the following two rules:
 - 1. If x < y in the poset, then the point corresponding to x appears lower in the drawing than the point corresponding to y.
 - 2. The line segment between the points corresponding to any two elements x and y of the poset is included in the drawing iff x covers y or y covers x.

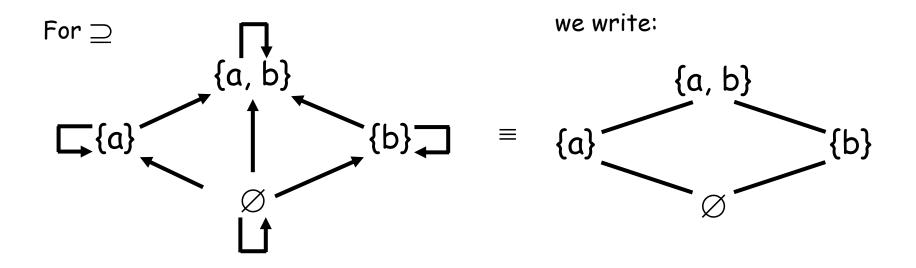
Cover Relation

• Let (S, \leq) be a poset. We say that an element $y \in S$ covers an element $x \in S$ if x < y and there is no element $z \in S$ such that x < z < y. The set of pairs (x, y) such that y covers x is called the covering relation of (S, \leq) .

Hasse Diagrams

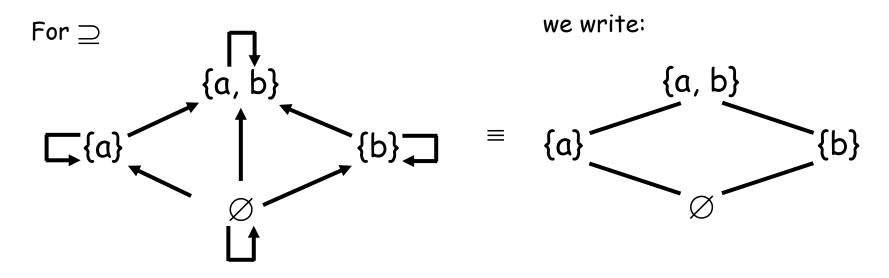
We produce Hasse Diagrams from directed graphs of relations by doing a transitive reduction plus a reflexive reduction (if weak) and (usually) dropping arrowheads (using, instead, "above" to give direction)

- 1) Transitive reduction discard all arcs except those that "directly cover" an element.
- 2) Reflexive reduction discard all self loops.



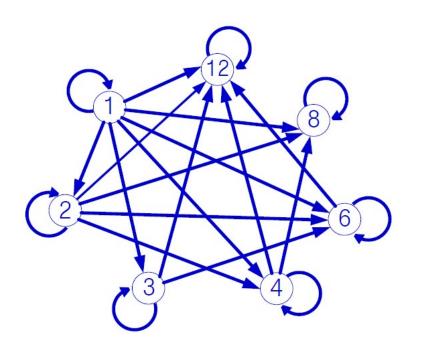
The Procedure Summary

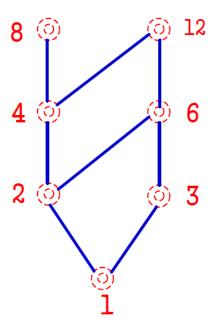
- Start with the directed graph for this relation.
- Because a partial ordering is reflexive, a loop (a, a) is present at every vertex a. Remove these loops.
- Next, remove all edges that must be in the partial ordering because of the presence of other edges and transitivity. That is, remove all edges (x, y) for which there is an element $z \in S$ such that x < z and z < x.
- Finally, arrange each edge so that its initial vertex is below its terminal vertex (as it is drawn on paper). Remove all the arrows on the directed edges, because all edges point "upward" toward their terminal vertex.



Hasse Diagram

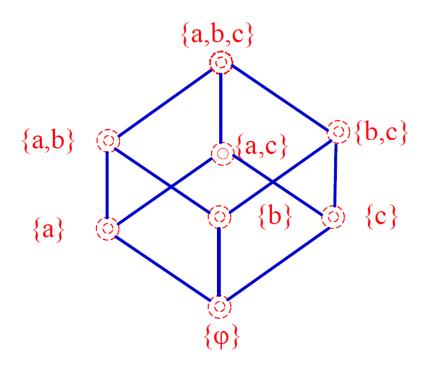
• **Example**: A={1,2,3,4,6,8,12}, integral division relation.





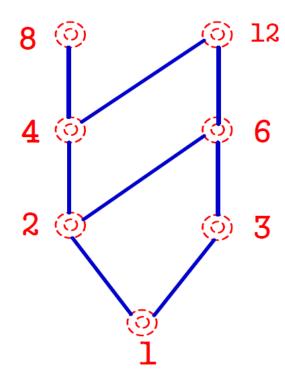
Hasse Diagram

• Example: $S=\{a, b, c\}, (P(S), \subseteq)$



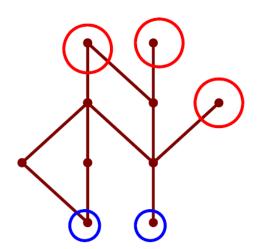
Maximum/Minimum/Greatest/Least

- Maximum/Minimum element
- 极大、极小
- Greatest/Least element
- 最大、最小



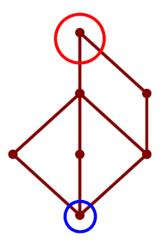
Minimum and Maximum

- **Definition**: In a poset S, an element z is a minimum element if there is no element $b \in S$, thus $b \le z$ and $b \ne z$.
- How about definition for maximum element?
- Example:
 - Reds are maximal.
 - Blues are minimal.



Least and Greatest

- **Definition**: In a poset S, an element z is a Least element if $\forall b \in S$, $z \le b$.
- · How about definition for Greatest element.
- Example:
 - Reds are greatest.
 - Blues are least.
- Greatest/Least may not exist.



Least and Greatest

• Theorem: In every poset, if the greatest element exists, then it is unique. Similarly for the least.

Proof:

- Suppose there are two greatest elements, a_1 and a_2 , with $a_1 \ne a_2$. Then $a_1 \le a_2$, and $a_2 \le a_1$, by defining of greatest. So $a_1 = a_2$, a contradiction. Thus, our assumption was incorrect, and the greatest element, if it exists, is unique.
- Similar proof for least.

Basics for Graphs

Key Points

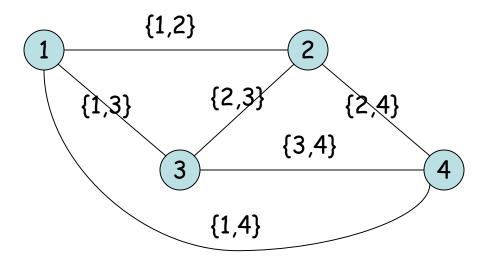
- Graph basics and definitions
 - Vertices/nodes, edges, adjacency(邻域), incidence
 - Degree, in-degree, out-degree
 - Subgraphs, unions, isomorphism
 - Adjacency matrices
- Types of Graphs
 - Undirected graphs
 - Simple graphs, Multigraphs (多重边图), Pseudographs (伪图)
 - Digraphs, Directed multigraph
 - Bipartite (二部图)
 - Complete graphs, cycles (圈图), wheels (轮图), cubes, complete bipartite

Simple Graphs

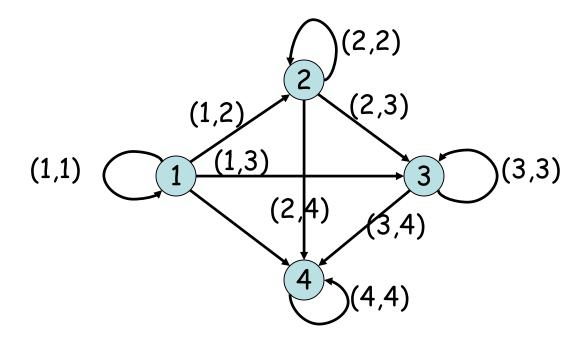
Different purposes require different types of graphs. Exempli Gratia (EG):

Suppose a local computer network

- Is bidirectional (undirected)
- Has no loops (no "self-communication")
- Has unique connections between computers Sensible to represent as follows:



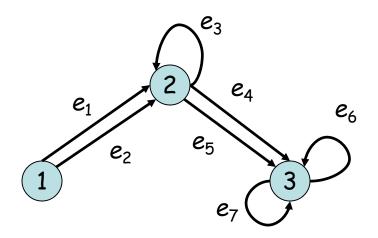
A: Each edge is directed so an ordered pair (or tuple) rather than unordered pair.



Thus the set of edges E is just the represented relation on V.

Directed Multigraphs

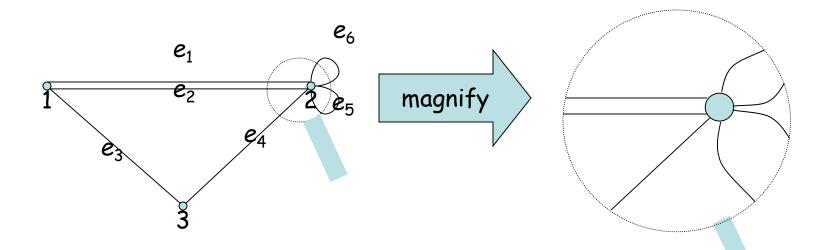
A: Have function with domain the edge set and codomain $V \times V$.



$$e_1 \rightarrow (1,2), e_2 \rightarrow (1,2), e_3 \rightarrow (2,2), e_4 \rightarrow (2,3), e_5 \rightarrow (2,3), e_6 \rightarrow (3,3), e_7 \rightarrow (3,3)$$

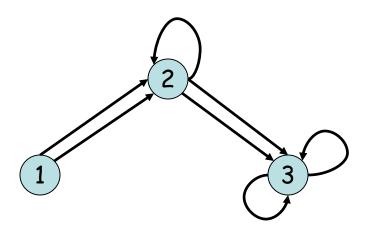
Degree

A: Add 1 for every regular edge incident with vertex and 2 for every loop. Thus deg(2) = 1 + 1 + 1 + 2 + 2 = 7



Oriented Degree when Edges Directed

The **in-degree** of a vertex (deg⁻) counts the number of edges that stick in to the vertex. The **out-degree** (deg⁺) counts the number sticking out.



Q: What are in-degrees and out-degrees of all the vertices?

Handshaking Theorem*

Theorem: In an undirected graph
$$|E| = \frac{1}{2} \sum_{v \in V} \deg(v)$$

In a directed graph $|E| = \sum_{v \in V} \deg^+(v) = \sum_{v \in V} \deg^-(v)$

Q: In a party of 5 people can each person be friends with exactly three others?

A: Imagine a simple graph with 5 people as vertices and edges being undirected edges between friends (simple graph assuming friendship is symmetric and irreflexive). Number of friends each person has is the degree of the person.

Handshaking would imply that |E| = (sum of degrees)/2 or2|E| = (sum of degrees) = (5.3) = 15.Impossible as 15 is not even. In general:

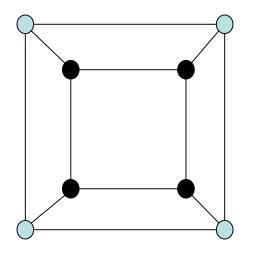
Euler Characteristic

The formula is proved by showing that the quantity $(chi)\chi = r - |E| + |V|$ must equal 2 for planar graphs. χ is called the **Euler characteristic**. The idea is that any connected planar graph can be built up from a vertex through a sequence of vertex and edge additions. For example, build 3-cube as follows:

r is the number of regions.

A region is a part of the plane completely disconnected off from other parts of the plane by the edges of the graph.

Animated Invariance of Euler Characteristic



	<i>E</i>	r	χ = r- E + V
8	12	6	2

Face-Edge Handshaking

For all graphs handshaking theorem relates degrees of vertices to number of edges.

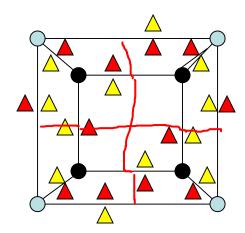
For planar graphs, can relate regions to edges in similar fashion:

EG: There are two ways to count the number of edges in 3-cube:

- 1) Count directly: 12
- Count no. of edges around

each region; divide by 2:

(4+4+4+4+4+4)/2 = 12 (2 triangles per edge)



Face-Edge Handshaking

Definition: The degree of a region F is the number of edges at its boundary, and is denoted by deg(F).

Theorem: Let G be a planar graph with region set R. Then:

$$|E| = \frac{1}{2} \sum_{F \in R} \deg(F)$$

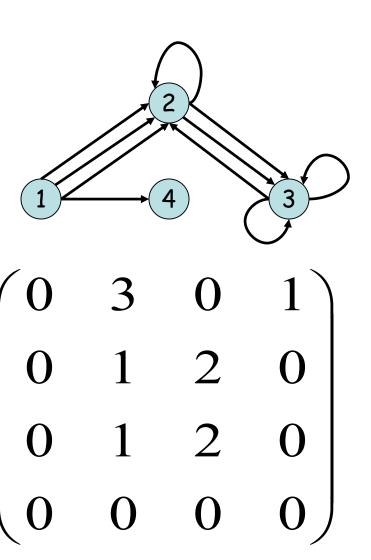
Adjacency Matrix-Directed Multigraphs

Can easily generalize to directed multigraphs by putting in the number of edges between vertices, instead of only allowing 0 and 1:

For a directed multigraph G = (V, E) define the matrix A_G by:

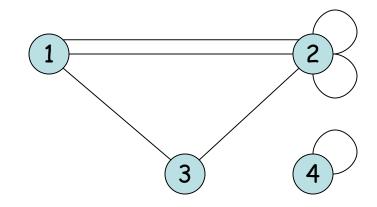
- Rows, Columns —one for each vertex in V
- Value at i th row and j th column is the number of edges with source the i th vertex and target the j th vertex

Adjacency Matrix-Directed Multigraphs



A:

Adjacency Matrix-General



A:

Notice that answer is symmetric.

$$egin{pmatrix} 0 & 2 & 1 & 0 \ 2 & 2 & 1 & 0 \ 1 & 1 & 0 & 0 \ 0 & 0 & 0 & 1 \ \end{pmatrix}$$

Graph Isomorphism Undirected Graphs

Definition: Suppose $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are pseudographs. Let $f: V_1 \rightarrow V_2$ be a function s.t.:

- 1. f is bijective
- 2. for all vertices u,v in V_1 , the number of edges between u and v in G_1 is the same as the number of edges between f (u) and f (v) in G_2 .

Then f is called an isomorphism and G_1 is said to be isomorphic to G_2 .



Graph Isomorphism Digraphs

Definition: Suppose $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are directed multigraphs. Let $f: V_1 \rightarrow V_2$ be a function s.t.:

- 1) f is bijective
- 2) for all vertices u,v in V_1 , the number of edges from u to v in G_1 is the same as the number of edges between f (u) and f (v) in G_2 . Then f is called an isomorphism and G_1 is said to be isomorphic to G_2 .

Note: Only difference between two definitions is the italicized "from" in no. 2 (was "between").

Properties of Isomorphims

Since graphs are completely defined by their vertex sets and the number of edges between each pair, isomorphic graphs must have the same intrinsic properties. I.e. isomorphic graphs have the same...

...number of vertices and edges

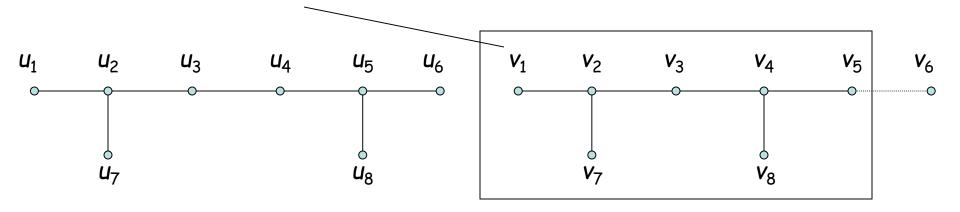
...degrees at corresponding vertices

...types of possible subgraphs

...any other property defined in terms of the basic graph theoretic building blocks!

Graph Isomorphism-Negative Examples

This subgraph is not a subgraph of the left graph.



Why not? Deg. 3 vertices must map to deg. 3 vertices. Since subgraph and left graph are symmetric, can assume v_2 maps to u_2 . Adjacent deg. 1 vertices to v_2 must map to degree 1 vertices, forcing the deg. 2 adjacent vertex v_3 to map to u_3 . This forces the other vertex adjacent to v_3 , namely v_4 to map to u_4 . But then a deg. 3 vertex has mapped to a deg. 2 vertex \rightarrow

Paths and Connectivity

Paths

A: For simple graphs, any edge is unique between vertices so listing the vertices gives us the edge-sequence as well.

Definition: A simple path contains no duplicate edges (though duplicate vertices are allowed). A cycle (or circuit) is a path which starts and ends at the same vertex.

Note: Simple paths need not be in simple graphs. E.g., may contain self-loops.

Paths in Directed Graphs

One can define paths for directed graphs by insisting that the target of each edge in the path is the source of the next edge:

Definition: A path of length n in a directed graph is a sequence of n edges e_1 , e_2 , ..., e_n such that the target of e_i is the source e_{i+1} for each i.

In a digraph, one may instead define a path of length n as a sequence of n+1 vertices v_0 , v_1 , v_2 , ... , v_n such that for each consecutive pair v_i , v_{i+1} there is an edge from v_i to v_{i+1} .

Connectivity

Definition: Let G be a pseudograph. Let u and v be vertices. u and v are connected to each other if there is a path in G which starts at u and ends at v. G is said to be connected if all vertices are connected to each other.

- 1. Note: Any vertex is automatically connected to itself via the empty path.
- 2. Note: A suitable definition for directed graphs will follow later.

N-Connectivity

The network is best because it can only become disconnected when 2 vertices are removed. In other words, it is 2-connected. Formally:

Definition: A connected simple graph with 3 or more vertices is 2-connected if it remains connected when any vertex is removed. When the graph is not 2-connected, we call the disconnecting vertex a cut vertex.

There is also a notion of N-Connectivity where we require at least N vertices to be removed to disconnect the graph.

Connectivity in Directed Graphs

Resolution: Don't bother choosing which definition is better. Just define to separate concepts:

- 1. Weakly connected: can get from a to b in underlying undirected graph
- 2. Semi-connected (my terminology): can get from a to b OR from b to a in digraph
- 3. Strongly connected: can get from a to b AND from b to a in the digraph

Definition: A graph is strongly (resp. semi, resp. weakly) connected if every pair of vertices is connected in the same sense.

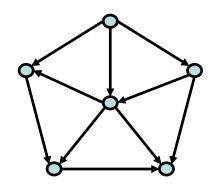
Connectivity in Directed Graphs

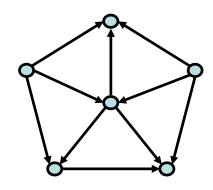
A:

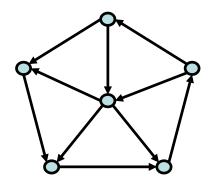
semi

weak

strong





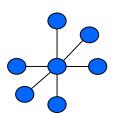


Tree

Graphs with no cycles?

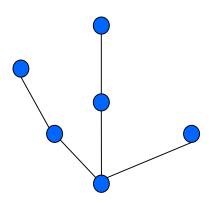
A forest.





Connected graphs with no cycles?

A tree.





Tree Characterizations

Definition. A tree is a connected graph with no cycles.

Characterization by paths:

A graph is a tree if and only if there is a unique simple path between every pair of vertices.

Characterization by number of edges:

A graph is a tree if and only if it is connected and has n-1 edges.

Spanning Trees

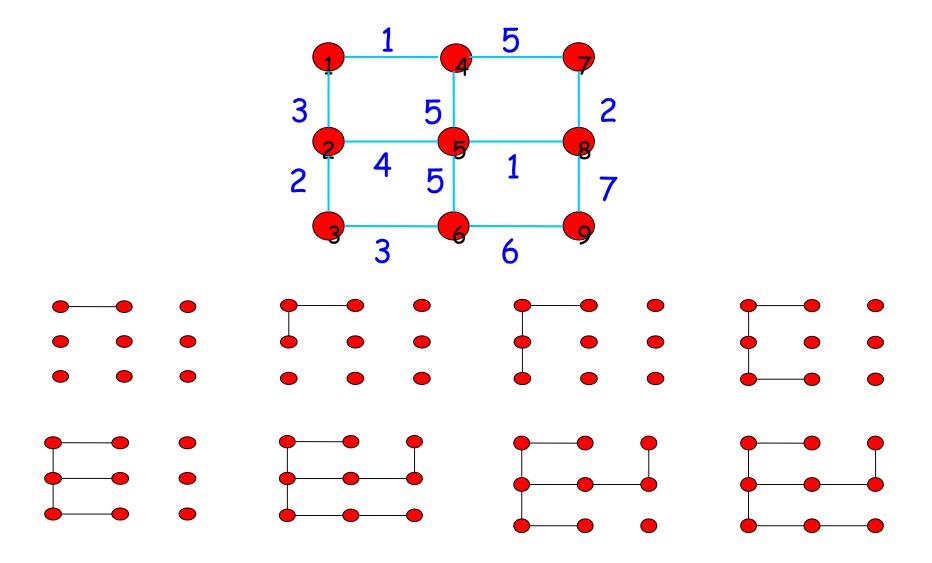
- Definition: Let G be a simple graph. A spanning tree of G is a subgraph of G that is a tree containing every vertex of G.
- •Note: A spanning tree of G = (V, E) is a connected graph on V with a minimum number of edges (|V| 1).
- **Example:** Since winters in Boston can be very cold, six universities in the Boston area decide to build a tunnel system that connects their libraries.
- A spanning tree in an undirected graph G(V,E) is a subset of edges $T\subseteq E$ that are acyclic and connect all the vertices in V.
- A spanning tree must consist of exactly n-1 edges.
- Suppose that each edge has a weight associated with it. Say that the weight of a tree T is the sum of the weights of its edges $w(T) = \sum_{e \in T} w(e)$
- The minimum spanning tree in a weighted graph G(V,E) is one which has the smallest weight among all spanning trees in G(V,E)

Spanning Trees

·Prim's Algorithm:

- Begin by choosing any edge with smallest weight and putting it into the spanning tree,
- successively add to the tree edges of minimum weight that are incident to a
 vertex already in the tree and not forming a simple circuit with those edges
 already in the tree,
- stop when (n 1) edges have been added.

Prim's algorithm

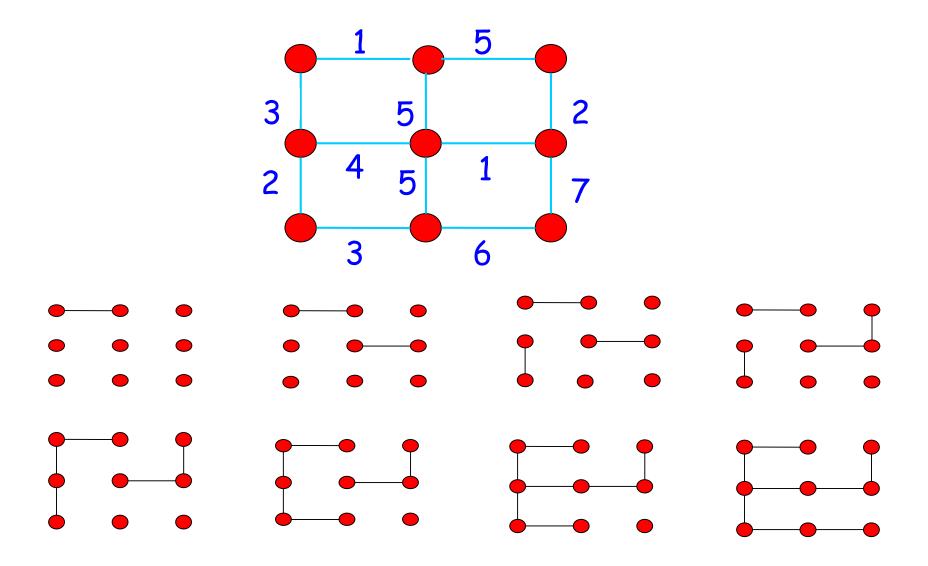


Spanning Trees

·Kruskal's Algorithm:

- •Kruskal's algorithm is identical to Prim's algorithm, except that it does not demand new edges to be incident to a vertex already in the tree.
- •Both algorithms are guaranteed to produce a minimum spanning tree of a connected weighted graph.

Kruskal's algorithm



Rooted Trees

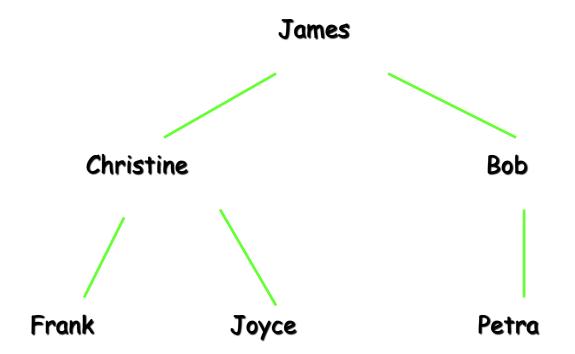
- •We often designate a particular vertex of a tree as the root. Since there is a unique path from the root to each vertex of the graph, we direct each edge away from the root.
- Thus, a tree together with its root produces a directed graph called a rooted tree.

- •If v is a vertex in a rooted tree other than the root, the parent of v is the unique vertex u such that there is a directed edge from u to v.
- ·When u is the parent of v, v is called the child of u.
- ·Vertices with the same parent are called siblings.
- •The ancestors of a vertex other than the root are the vertices in the path from the root to this vertex, excluding the vertex itself and including the root.

Rooted Trees

- •The level of a vertex v in a rooted tree is the length of the unique path from the root to this vertex.
- •The level of the root is defined to be zero.
- •The height of a rooted tree is the maximum of the levels of vertices.

•Example I: Family tree



Trees

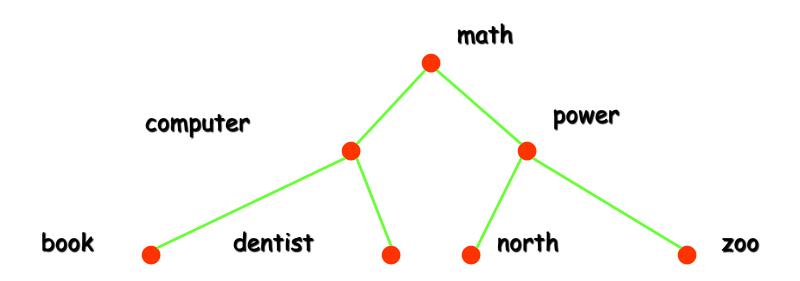
- •Definition: A rooted tree is called an m-ary tree if every internal vertex has no more than m children.
- •The tree is called a **full m-ary tree** if every internal vertex has exactly m children.
- •An m-ary tree with m = 2 is called a binary tree.
- •Theorem: A tree with n vertices has (n 1) edges.
- •Theorem: A full m-ary tree with i internal vertices contains n = mi + 1 vertices.

Binary Trees

- Every node has at most two children
- Most popular tree in computer science
- Given N nodes, what is the minimum depth of a binary tree?
- · What is the maximum depth of a binary tree with N nodes?

Binary Search Trees

•Example: Construct a binary search tree for the strings math, computer, power, north, zoo, dentist, book.



Binary Search Trees

- •To perform a search in such a tree for an item x, we can start at the root and compare its key to x. If x is less than the key, we proceed to the left child of the current vertex, and if x is greater than the key, we proceed to the right one.
- This procedure is repeated until we either found the item we were looking for, or we cannot proceed any further.

