# CSED490F Lab: Autograd

Team 4: Yunkyu Lee (20210733), Hyeonu Cho (20230740)

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#### 1 Automatic Differentiation

Reverse-mode automatic differentiation performs back-to-front accumulation of local gradients based on the chain rule. Consider a function  $f: \mathbb{R}^n \to \mathbb{R}^m$ , and its  $m \times n$  Jacobian  $\mathbf{J}_f$ . For  $\mathbf{y} = f(\mathbf{x})$ , suppose we know  $\nabla_{\mathbf{y}} \mathcal{L}$ , the gradient of some scalar value  $\mathcal{L}$  w.r.t.  $\mathbf{y}$ . Then, we can obtain  $\nabla_{\mathbf{x}} \mathcal{L}$  as a vector-Jacobian product (VJP):

$$\nabla_{\mathbf{x}} \mathcal{L} = (\nabla_{\mathbf{y}} \mathcal{L})^{\top} \mathbf{J}_f$$

As  $\mathbf{J}_{f_1 \circ f_2} = \mathbf{J}_{f_1} \circ \mathbf{J}_{f_2}$ , we can chain the above VJP in order to obtain gradients of composed functions. Therefore, knowing the local gradients of function outputs w.r.t. their inputs is sufficient for reverse-mode automatic differentiation. We describe the local gradients of some operators below.

#### 1.1 Basic Operations

$$\operatorname{Add}(x,y) = x + y, \quad \frac{\partial \operatorname{Add}}{\partial x} = 1, \quad \frac{\partial \operatorname{Add}}{\partial y} = 1 \tag{1}$$

$$\operatorname{Mul}(x,y) = x \times y, \quad \frac{\partial \operatorname{Mul}}{\partial x} = y, \quad \frac{\partial \operatorname{Mul}}{\partial y} = x \tag{2}$$

$$\operatorname{Pow}(x,y) = x^y, \quad \frac{\partial \operatorname{Pow}}{\partial x} = yx^{y-1}, \quad \frac{\partial \operatorname{Pow}}{\partial y} = x^y \log x \tag{3}$$

$$Log(x) = \log x, \quad \frac{\partial Log}{\partial x} = x^{-1}, \tag{4}$$

$$\operatorname{ReLU}(x) = \max(x, 0), \quad \frac{\partial \operatorname{ReLU}}{\partial x} = yx^{y-1}, \tag{5}$$

$$\operatorname{Sum}(x, \operatorname{axis}) = \sum_{i \in \operatorname{axis}} x_i, \quad \frac{\partial \operatorname{Sum}}{\partial x} = 1, \tag{6}$$

$$\mathtt{MatMul}(x,y) = xy, \quad \frac{\partial \mathtt{MatMul}}{\partial x} = y, \quad \frac{\partial \mathtt{MatMul}}{\partial y} = x \tag{7}$$

#### 1.2 Classification

Following [1], we use a shifted softmax for numerical stability:

$$Softmax(x_j) = \frac{\exp(x_j - s)}{\sum_i \exp(x_i - s)}$$

The negative log-likelihood loss (with log-probability input)

$$\text{NLLLoss}(\log \hat{y}, y) = -y \log \hat{y}$$

The cross-entropy loss (with logit inputs) can be seen as a combination of Softmax and NLLLoss.

- 1.3 Matrix Multiplication
- 1.4 Cross Entropy Loss

## 2 MNIST Classification

Utilizing the operators described in section 1, we perform testing on the MNIST dataset.

### References

[1] Pierre Blanchard, Desmond J Higham, and Nicholas J Higham. "Accurately computing the log-sum-exp and softmax functions". In: *IMA Journal of Numerical Analysis* 41.4 (Aug. 2020), pp. 2311-2330. ISSN: 0272-4979. DOI: 10.1093/imanum/draa038. eprint: https://academic.oup.com/imajna/article-pdf/41/4/2311/40758053/draa038.pdf. URL: https://doi.org/10.1093/imanum/draa038.