

Iuliia (Yulia) Kotseruba

PHD CANDIDATE · DEPARTMENT OF ELECTRICAL ENGINEERING AND COMPUTER SCIENCE

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Education

York University

Toronto, Canada

PHD ELECTRICAL ENGINEERING AND COMPUTER SCIENCE

2019 - present

- Advisor: Prof. John K. Tsotsos
- Dissertation title: "Investigating and Modeling Effects of Task and Context on Drivers' Gaze Allocation"
- Expected to complete in Spring 2024

York University

Toronto, Canada

MSc ELECTRICAL ENGINEERING AND COMPUTER SCIENCE

2012 - 2016

- Advisor: Prof. John K. Tsotsos
- Thesis title: "Visual attention in dynamic environments and its application to playing online games"

University of Toronto

Toronto, Canada

BSc HONS. COMPUTER SCIENCE

2006 - 2010

- Specialist in Artificial Intelligence

National University of "Kyiv-Mohyla Academy"

Kyiv, Ukraine

BA HONS. PHILOSOPHY

2002 - 2006

- Minor in Religious Studies
- Thesis advisor: Prof. Andrii Baumeister
- Thesis title: "On transcendental analytic in I. Kant's *Critique of Pure Reason*"

Professional Experience

2021-2022 **Associate Researcher, Intern**, Noah's Ark Lab, Huawei, Canada

2014-

present

Research Associate, Tsotsos Lab for Active and Attentive Vision, York University, Canada

2010-2012 **Research Programmer**, Jurisica Lab, University Health Network, Canada

Technical skills

PROGRAMMING Python (proficient), MATLAB (proficient), C/C++ (prior experience), OpenCL/CUDA/OpenGL/GLSL (prior experience), Java (prior experience)

DATA ANALYTICS Pandas (proficient), NumPy (proficient), Matplotlib (proficient), PostgreSQL (prior experience)

MACHINE LEARNING PyTorch (proficient), Keras (proficient), OpenCV (proficient), Tensorflow (prior experience)

Publications

UNDER REVIEW

Kotseruba, I., Tsotsos J.K. (2024). SCOUT+: Towards practical task-driver drivers' gaze prediction, (submitted).

Kotseruba, I., Tsotsos J.K. (2024). Data Limitations for Modeling Top-Down Effects on Drivers' Attention, (submitted).

Kotseruba, I., & Tsotsos, J. K. (2023). Understanding and Modeling the Effects of Task and Context on Drivers' Gaze Allocation. arXiv:2310.09275.

BOOKS

Kotseruba, I., Tsotsos J.K., "The Computational Evolution of Cognitive Architectures", Oxford University Press, (accepted).

PEER-REVIEWED JOURNALS

Kotseruba, I., & Tsotsos, J. K. (2022). Attention for vision-based assistive and automated driving: a review of algorithms and datasets. *IEEE Transactions on Intelligent Transportation Systems*, 23(11), 19907–19928.

Tsotsos, J. K., Abid, O., Kotseruba, I., & Solbach, M. D. (2021). On the control of attentional processes in vision. *Cortex*, 137, 305-329.

Kotseruba, I., & Tsotsos, J. K. (2020). 40 Years of Cognitive Architectures: Core Cognitive Abilities and Practical Applications. *Artificial Intelligence Review*, 53(1), 17-94.

Tsotsos, J. K., Kotseruba, I., & Wloka, C. (2019). Rapid visual categorization is not guided by early salience-based selection. *PloS one*, 14(10), e0224306.

Tsotsos, J. K., Kotseruba, I., Rasouli, A., & Solbach, M. D. (2018). Visual attention and its intimate links to spatial cognition. *Cognitive processing*, 19, 121-130.

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2017). Understanding pedestrian behavior in complex traffic scenes. *IEEE Transactions on Intelligent Vehicles*, 3(1), 61-70.

Tsotsos, J., Kotseruba, I., & Wloka, C. (2016). A focus on selection for fixation. *Journal of Eye Movement Research*, 9(5).

Fortney, K., Xie, W., Kotlyar, M., Griesman, J., Kotseruba, Y., & Jurisica, I. (2012). NetwoRx: connecting drugs to networks and phenotypes in *Saccharomyces cerevisiae*. *Nucleic acids research*, 41(D1), D720-D727.

Kotseruba, Y., Cumbaa, C. A., & Jurisica, I. (2012). High-throughput protein crystallization on the World Community Grid and the GPU. In *Journal of Physics: Conference Series*, 341(1), p. 012027.

PEER-REVIEWED CONFERENCES

** equal contribution*

Rasouli, A., & Kotseruba, I. (2023). PedFormer: Pedestrian behavior prediction via cross-modal attention modulation and gated multitask learning. In *IEEE International Conference on Robotics and Automation (ICRA)* (pp. 9844-9851).

Kotseruba, I., & Rasouli, A. (2023). Intend-Wait-Perceive-Cross: Exploring the Effects of Perceptual Limitations on Pedestrian Decision-Making. In *IEEE Intelligent Vehicles Symposium (IV)* (**Oral**).

Rasouli, A.*, & Kotseruba, I.* (2022). Intend-wait-cross: Towards modeling realistic pedestrian crossing behavior. In *IEEE Intelligent Vehicles Symposium (IV)* (pp. 83-90).

Kotseruba, I., Rasouli, A., & Tsotsos, J. K. (2021). Benchmark for evaluating pedestrian action prediction. In *IEEE/CVF Winter Conference on Applications of Computer Vision (WACV)* (pp. 1258-1268).

Kotseruba, I., Rasouli, A., & Tsotsos, J. K. (2020). Do they want to cross? Understanding pedestrian intention for behavior prediction. In *IEEE Intelligent Vehicles Symposium (IV)* (pp. 1688-1693).

Rasouli, A.*, Kotseruba, I.*, Kunic, T., & Tsotsos, J. K. (2019). PIE: A large-scale dataset and models for pedestrian intention estimation and trajectory prediction. In *IEEE/CVF International Conference on Computer Vision (ICCV)* (pp. 6262-6271) (**Oral**).

Tsotsos, J., Kotseruba, I., Andreopoulos, A., & Wu, Y. (2019). Why does data-driven beat theory-driven computer vision?. In *IEEE/CVF International Conference on Computer Vision (ICCV) Workshops*.

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2020). Pedestrian action anticipation using contextual feature fusion in stacked RNNs. In *British Machine Vision Conference (BMVC)*.

Kotseruba, I., Wloka, C., Rasouli, A., & Tsotsos, J. K. (2020). Do saliency models detect odd-one-out targets? New datasets and evaluations. In *British Machine Vision Conference (BMVC)* (**Oral**).

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2018, November). Towards social autonomous vehicles: Understanding pedestrian-driver interactions. In *IEEE International Conference on Intelligent Transportation Systems (ITSC)* (pp. 729-734).

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2018). It's not all about size: On the role of data properties in pedestrian detection. In *European Conference on Computer Vision (ECCV) Workshops*.

Wloka, C., Kotseruba, I., & Tsotsos, J. K. (2018). Active fixation control to predict saccade sequences. In IEEE Conference on Computer Vision and Pattern Recognition (CVPR) (pp. 3184-3193).

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2017). Are they going to cross? A benchmark dataset and baseline for pedestrian crosswalk behavior. In IEEE International Conference on Computer Vision (ICCV) Workshops (pp. 206-213).

Rasouli, A., Kotseruba, I., & Tsotsos, J. K. (2017). Agreeing to cross: How drivers and pedestrians communicate. In IEEE Intelligent Vehicles Symposium (IV) (pp. 264-269).

PRE-PRINTS AND TECHNICAL REPORTS

Rasouli, A., Alizadeh, S., Kotseruba, I., Ma, Y., Liang, H., Tian, Y., Huang, Z., Liu, H., Wu, J., Goebel, R., Yang, T., Taylor, M.E., Paull, L., & Chen, X. (2023). Driving SMARTS Competition at NeurIPS 2022: Insights and Outcome. In NeurIPS 2022 Competition Track (pp. 73-84).

Kotseruba, I., Papagelis, M., & Tsotsos, J. K. (2021). Industry and Academic Research in Computer Vision. arXiv:2107.04902.

Kotseruba, I., & Tsotsos, J. K. (2021). Behavioral research and practical models of drivers' attention. arXiv:2104.05677.

Wloka, C., Kunić, T., Kotseruba, I., Fahimi, R., Frosst, N., Bruce, N. D., & Tsotsos, J. K. (2018). SMILER: Saliency model implementation library for experimental research. arXiv:1812.08848.

Kotseruba, I., & Tsotsos, J. K. (2017). STAR-RT: Visual attention for real-time video game playing. arXiv:1711.09464.

Kotseruba, I., Rasouli, A., & Tsotsos, J. K. (2016). Joint attention in autonomous driving (JAAD). arXiv:1609.04741.

Presentations

* *presenting author*

INVITED TALKS

Keynote talk: Kotseruba, I.*, Tsotsos, J.K.*, *40 Years of Cognitive Architectures*. AAAI Symposium, Arlington, Virginia, USA, 2018.

CONTRIBUTED PRESENTATIONS

Oral: Kotseruba, I.*, Rasouli, A., J. K. Tsotsos, *Intend-Wait-Perceive-Cross: Exploring the Effects of Perceptual Limitations on Pedestrian Decision-Making*. Intelligent Vehicles Symposium (IV), Anchorage, AK, USA, 2023.

Poster: Kotseruba, I.*, Rasouli, A., J. K. Tsotsos, *Benchmark for Evaluating Pedestrian Action Prediction*. Winter Conference on Applications in Computer Vision (WACV), Virtual, 2021.

Poster: Kotseruba, I.*, Rasouli, A., J. K. Tsotsos, *Do they want to cross? Understanding pedestrian intention for behavior prediction*. Intelligent Vehicles Symposium (IV), Virtual, 2020.

Oral, poster: Rasouli, A.*, Kotseruba, I.*, J. K. Tsotsos, *PIE: A Large-Scale Dataset and Models for Pedestrian Intention Estimation and Trajectory Prediction*. International Conference on Computer Vision (ICCV), Seoul, South Korea.

Oral, poster: Kotseruba, I.*, Wloka, C., Rasouli, A., J. K. Tsotsos, *Do Saliency Models Detect Odd-One-Out Targets? New Datasets and Evaluations*. British Machine Vision Conference (BMVC), Cardiff, UK.

Poster: Rasouli, A.*, Kotseruba, I.*, J. K. Tsotsos, *Perception, inference, and prediction: Towards pedestrian behavior understanding*. NCRN Annual General Meeting, Queen's University, ON, Canada, 2019.

Poster: Wloka, C., Kotseruba, I.*, J. K. Tsotsos, *Active fixation control to predict saccade sequences*. International Conference on Computer Vision and Pattern Recognition (CVPR), Salt Lake City, AZ, USA, 2017.

Poster: Rasouli, A.*, Kotseruba, I.*, J. K. Tsotsos, *Are They Going to Cross? A Benchmark Dataset and Baseline for Pedestrian Crosswalk Behavior*. Autonomous Driving Workshop at International Conference on Computer Vision, Venice, Italy, 2017.

Poster: Rasouli, A.*, Kotseruba, I.*, J. K. Tsotsos, *Understanding pedestrian behavior in complex traffic scenes*. Intelligent Vehicles Symposium (IV), Redondo Beach, CA, USA.

Poster: Rasouli, A.*, Kotseruba, I.*, J. K. Tsotsos, "Visual Saliency in Search and Exploration of Unknown Environments", NCFRN Annual General Meeting, Kelowna, BC, Canada, 2015

Poster: Kotseruba, I.*, J. K. Tsotsos, “Visual Attention in Dynamic Environments”, Vision Sciences Society (VSS), St. Pete Beach, FL, USA, 2014.

Awards

2020–2023	Alexander Graham Bell Doctoral Award (CGS D) , Natural Sciences and Engineering Research Council of Canada	\$ 35,000/year
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Teaching Experience

W2024	EECS3462 User Interfaces , Teaching Assistant	York University
F2023	EECS3401 Introduction to AI and Logical Programming , Teaching Assistant	York University
W2023	EECS3311 Software Design , Teaching Assistant	York University
F2022	EECS3401 Introduction to AI and Logical Programming , Teaching Assistant	York University
W2022	EECS2031 Software Tools , Teaching Assistant	York University
F2020	EECS3311 Software Design , Teaching Assistant	York University
W2020	EECS3221 Operating Systems Fundamentals , Teaching Assistant	York University
F2020	EECS3461 User Interfaces , Teaching Assistant	York University
F2019	EECS2031 Software Tools , Teaching Assistant	York University
F2019	EECS2030 Advanced Java Programming , Teaching Assistant	York University
W2013	EECS2021 Computer Organization , Teaching Assistant	York University
F2013	EECS2021 Computer Organization , Teaching Assistant	York University

Professional service

Nov, 2023	Ad-hoc Adjudicating Committee for Tenure and Promotion , Graduate student representative	York University
2022	Driving SMARTS Competition , Organizing committee member	NeurIPS
2022	Symposium on Cognitive Theories in AI , Program committee member	AAAI
2022	”All things attention” Workshop , Program committee member	NeurIPS
2022	Lassonde Undergraduate Summer Research Conference , Judge	York University
2020-2021	Tenure and Promotion Committee , Graduate student representative	York University
2021	Ontario Computer Vision Workshop (OCVW) , Program committee member	York University

GRANT REVIEW

European Research Council (ERC)
ETH Zurich Research Commission

BOOK PROPOSAL AND BOOK REVIEW

MIT Press
Springer Nature

CONFERENCE REVIEW

International Conference on Computer Vision and Pattern Recognition (CVPR)
International Conference on Computer Vision (ICCV)
European Conference on Computer Vision (ECCV)
Neural Information Processing Systems (NeurIPS)
International Conference on Robotics and Automation (ICRA)
International Conference on Intelligent Robots (IROS)
Intelligent Vehicles Symposium (IV)

Winter Conference on Applications of Computer Vision (WACV)
International Conference on Pattern Recognition (ICPR)
Conference on Computer and Robot Vision (CRV)

JOURNAL REVIEW

Transactions on Intelligent Transportation Systems
Computer Vision and Image Understanding (CVIU)
International Journal of Computer Vision (IJCV)
Robotics and Automation Letters (A-RL)
Journal of Field Robotics
Transportation Research Part F: Traffic Psychology and Behavior
Artificial Intelligence Review
Cognitive Processing
Frontiers in Computer Science

Professional Memberships

Sigma Xi, The Scientific Research Honor Society
Computer Vision Foundation
IEEE