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Dynamic Dispatch

For dynamic dispatch the decision on which member function to invoke is made using run-time type of an object. This is other type of dispatch is static dispatch, where the decision on which member function to invoke is made using compile-time type of an object. A difference between Java and C++ is that Java uses dynamic dispatch by default, that is, everything is virtual, while C++ supports both types of dispatch. Virtual methods are only needed under certain circumstances, specifically when you want to use polymorphism. The syntax use in C++ for dynamic dispatch is the "virtual" keyword. By using "virtual", dynamic dispatch is implemented with the use of virtual method tables. The C++ compiler inserts a virtual method table for every class having virtual function or class inherited from the class that has a virtual function. In essence, each object has a pointer to the virtual method table. That table has the addresses of the methods. Any virtual method must follow the pointer to the object, then follow the virtual method table pointer. It proceeds to look up the method pointer and jump to that method.

As an example, I created three classes: Person superclass, and two subclasses called Student and Teacher (as shown by the picture below). I used the virtual keyword to make the functions use dynamic dispatch. In the main method, I created a Person pointer p pointing to Person, a Person pointer s pointing to Student, and a Person pointer t pointing to Teacher.

```
class Person {
public:
    virtual void who() {
        cout<< "I am a human" << endl;
    }
    virtual void where() {
        cout<< "I am on Earth" << endl;
    }
};

class Student: public Person {
public:
    virtual void who() {
        cout<< "I am a student" << endl;
    }
};

class Teacher: public Person {
public:
    virtual void where() {
        cout << "I am at UVA" << endl;
    }
};</pre>
```

```
int main() {
    Person *p = new Person();
    p->who();
    p->where();

Person *s = new Student();
    s->who();
    s->where();

Person *t = new Teacher();
    t->who();
    t->where();
    return 0;
}
```

Per expected, the code printed the following:

```
I am a human
I am on Earth
I am a student
I am on Earth
I am a human
I am at UVA
```

The code was able to decide what member function to call during run time. For example, as the Student Class inherited the Person Class. The vtable of Student Class contains pointer to the who() function of Student class ("I am a student"), but the pointer to where() is of base class, the Person class ("I am on Earth").

I used godbolt.org to convert my C++ code into assembly. The assembly gave a vtable, which is the virtual table that contains the pointers. The vtable contains the addresses of the appropriate methods as well as the pointers to metadata. As shown in the table, in the virtual table for Teacher, the function who() is called from the Person class while the function where() is called from the Teacher class. In the virtual table for Student, the function who() is called from the Student class while the function where() is called from the Person class.

```
vtable for Teacher:
       .quad
              typeinfo for Teacher
       .quad
              Person::who()
       .quad
              Teacher::where()
       .quad
vtable for Student:
       .quad
       .quad
               typeinfo for Student
       .quad Student::who()
       .quad Person::where()
vtable for Person:
       .quad
       .quad
              typeinfo for Person
       .quad Person::who()
       .quad Person::where()
```

The assembly code for the Person::who() and the Student::who() looks almost identical, it is the difference in the virtual table. QWORD PTR shows the pointer in dynamic dispatch.

```
Student::who():
Person::who():
                                                                     push rbp
       push
                                                                             rbp, rsp
               rbp, rsp
       mov
                                                                             rsp, 16
               rsp, 16
                                                                              OWORD PTR [rbp-8], rdi
               QWORD PTR [rbp-8], rdi
                                                                      mov esi, OFFSET FLAT:.LC2
       mov esi, OFFSET FLAT:.LC0
                                                                             edi, OFFSET FLAT: ZSt4cout
                                                                           std::basic_ostream<char, std::char_traits<char
              edi, OFFSET FLAT: ZSt4cout
       call
              std::basic ostream<char, std::char traits<char> :
                                                                              esi, OFFSET FLAT:_ZSt4endlIcSt11char_traitsIcEE
              esi, OFFSET FLAT: ZSt4endlIcSt11char_traitsIcEER
       mov
                                                                      call std::basic_ostream<char, std::char traits<char
              std::basic ostream<char, std::char traits<char>
                                                                      nop
       leave
                                                               .LC3:
```

The assembly code from the main method is shown below. The first picture is from the pointer p and second picture is the pointer s. The call to the first function, who() has the virtual pointer to the appropriate function. The call to the second function where() has a line that wasn't in the who() function. It is the assembly line "add rax, 8" which shows that since we are calling the second overridden method, we access an offset of the virtual method pointer by 8 bytes.

```
mov
        edi, 8
call
        operator new(unsigned long)
        rbx, rax
mov
        QWORD PTR [rbx], 0
mov
        rdi, rbx
mov
        Person::Person() [complete object constructor]
call
        QWORD PTR [rbp-24], rbx
mov
        rax, QWORD PTR [rbp-24]
mov
        rax, QWORD PTR [rax]
mov
        rax, QWORD PTR [rax]
mov
        rdx, QWORD PTR [rbp-24]
mov
mov
        rdi, rdx
call
        rax
        rax, QWORD PTR [rbp-24]
mov
        rax, QWORD PTR [rax]
mov
        rax, 8
add
        rax, QWORD PTR [rax]
mov
        rdx, QWORD PTR [rbp-24]
mov
mov
        rdi, rdx
call
        rax
```

```
edi, 8
mov
call
        operator new(unsigned long)
mov
        rbx, rax
        QWORD PTR [rbx], 0
mov
mov
        rdi, rbx
        Student::Student() [complete object constructor]
call
        QWORD PTR [rbp-32], rbx
mov
        rax, QWORD PTR [rbp-32]
mov
        rax, QWORD PTR [rax]
mov
        rax, QWORD PTR [rax]
mov
        rdx, QWORD PTR [rbp-32]
mov
        rdi, rdx
mov
call
        rax, QWORD PTR [rbp-32]
mov
        rax, QWORD PTR [rax]
mov
        rax, 8
add
        rax, QWORD PTR [rax]
mov
        rdx, QWORD PTR [rbp-32]
mov
        rdi, rdx
mov
call
        rax
```

Sources:

https://lukasatkinson.de/2016/dynamic-vs-static-dispatch/

- https://en.wikipedia.org/wiki/Dynamic_dispatch
- https://pabloariasal.github.io/2017/06/10/understanding-virtual-tables/

Optimized Code

In C++, one can generate optimized code with the -O2 compiler flag. The -O2 flag sets the options that create the fastest code in the majority of cases. -O2 increases both compilation time and the performance of the generated code.

To compare code generated normally to optimized code, I created a function called multiply and a main method that calls the function.

```
int multiply(int x,int y) {
    int z = 0;
    for (int i = 0; i < y; i++) {
        z += x;
    }
    int w = 0;
    w += 2;
    return z;
}

int main() {
    cout << multiply(2,3) << endl;
    return 0;
}</pre>
```

The multiply function takes in two parameters: an integer x and an integer y. Instead of multiplying the two numbers, the function takes the use of a for loop that adds the integer "x" y number of times, so the returning value would be equal to multiplication. At the end of the code, I initialized an integer w and added two to it. This unrelated part was added to see how it would affect my assembly language with optimization. If an instruction is not necessary to the final output of the program, then it may be optimized away completely.

I used godbolt.org to convert my C++ code into assembly language. By just skimming the code, I already noticed a massive change with the use of the -O2 flag, as the one without the optimization flag contained twice as many lines compared to the code with the addition of the flag. It used less code and more efficient code. The two images below are the multiply function. The left is compiled without any compiler options and the right takes use of the -O2 flag.

```
multiply(int, int):
       push
               rbp
       mov
               rbp, rsp
               DWORD PTR [rbp-20], edi
               DWORD PTR [rbp-24], esi
               DWORD PTR [rbp-4], 0
       mov
       mov DWORD PTR [rbp-8], 0
.L3:
               eax, DWORD PTR [rbp-8]
               eax, DWORD PTR [rbp-24]
       cmp
       jge
               .L2
               eax, DWORD PTR [rbp-20]
       mov
       add
               DWORD PTR [rbp-4], eax
               DWORD PTR [rbp-8], 1
               .L3
.L2:
               DWORD PTR [rbp-12], 0
               DWORD PTR [rbp-12], 2
       add
       mov
              eax, DWORD PTR [rbp-4]
       pop
```

```
multiply(int, int):

test esi, esi
jle .L3

mov eax, esi
imul eax, edi
ret

.L3:

xor eax, eax
ret
```

The results were significant, because by using optimization, the compiler recognized that the purpose of the function is to multiply two numbers and used "imul" instead of looping and adding the first number each time. Branching is not ideal, as it slows down the execution speed of a program. Because a large percentage of the time is spent inside loops, loop optimization has a significant impact. Another difference was that the optimization got rid of the useless code I made with "int w". The function on the left has a third step called ".L2:" while the one on the right ignored the lines that doesn't affect the return of "z". There are no pointers or any memory access with push and pop in the optimized code.

A difference in the main method is shown below.

```
main:
                rbp
       push
               rbp, rsp
       mov
       mov
               esi, 3
               edi, 2
       mov
               multiply(int, int)
       call
               esi, eax
       mov
               edi, OFFSET FLAT: ZSt4cout
               std::basic ostream<char, std::char traits<char> >::operator<<(int)</pre>
       call
       mov
               esi, OFFSET FLAT: ZSt4endlIcSt11char traitsIcEERSt13basic ostreamIT TO ES6
                rdi, rax
               std::basic_ostream<char, std::char_traits<char> >::operator<<(std::basic_ostream
       call
       mov
               eax, 0
                rbp
       pop
        ret
```

```
main:
    sub    rsp, 8
    mov    esi, 6
    mov    edi, OFFSET FLAT:_ZSt4cout
    call    std::basic_ostream<char, std::char_traits<char> >::operator<<(int)
    mov    rdi, rax
    call    std::basic_ostream<char, std::char_traits<char> >& std::endl<char, std::char_trait
    xor    eax, eax
    add    rsp, 8
    ret</pre>
```

As expected, the picture on the top is the assembly code without optimization. With the use of optimization, the push and pop were gone, reducing memory access. The optimized code uses fewer x86 instructions.

Optimizing code can be very important, as it can save memory and time. It minimizes the power consumed by a program.

Sources:

- https://unix.stackexchange.com/questions/452337/what-does-the-o2-option-for-gcc-do
- https://www.quora.com/What-is-O2-flag-compile-How-do-I-do-it
- https://en.wikipedia.org/wiki/Optimizing compiler