

LIGO SEMINAR

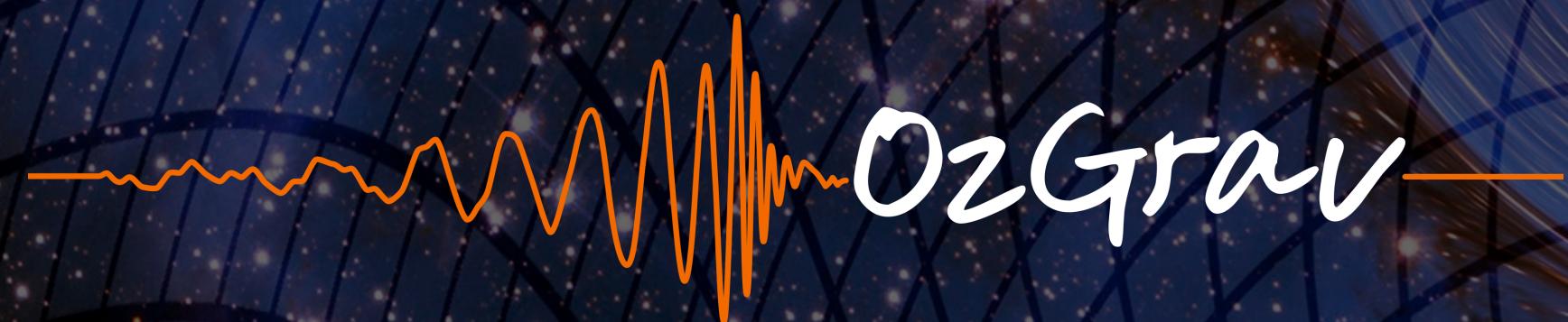
MULTI-DETECTOR NETWORK DETECTION AND CHARACTERISATION OF GRAVITATIONAL-WAVE BURSTS WITH THE BAYESWAVE PIPELINE

29TH OF MARCH 2024

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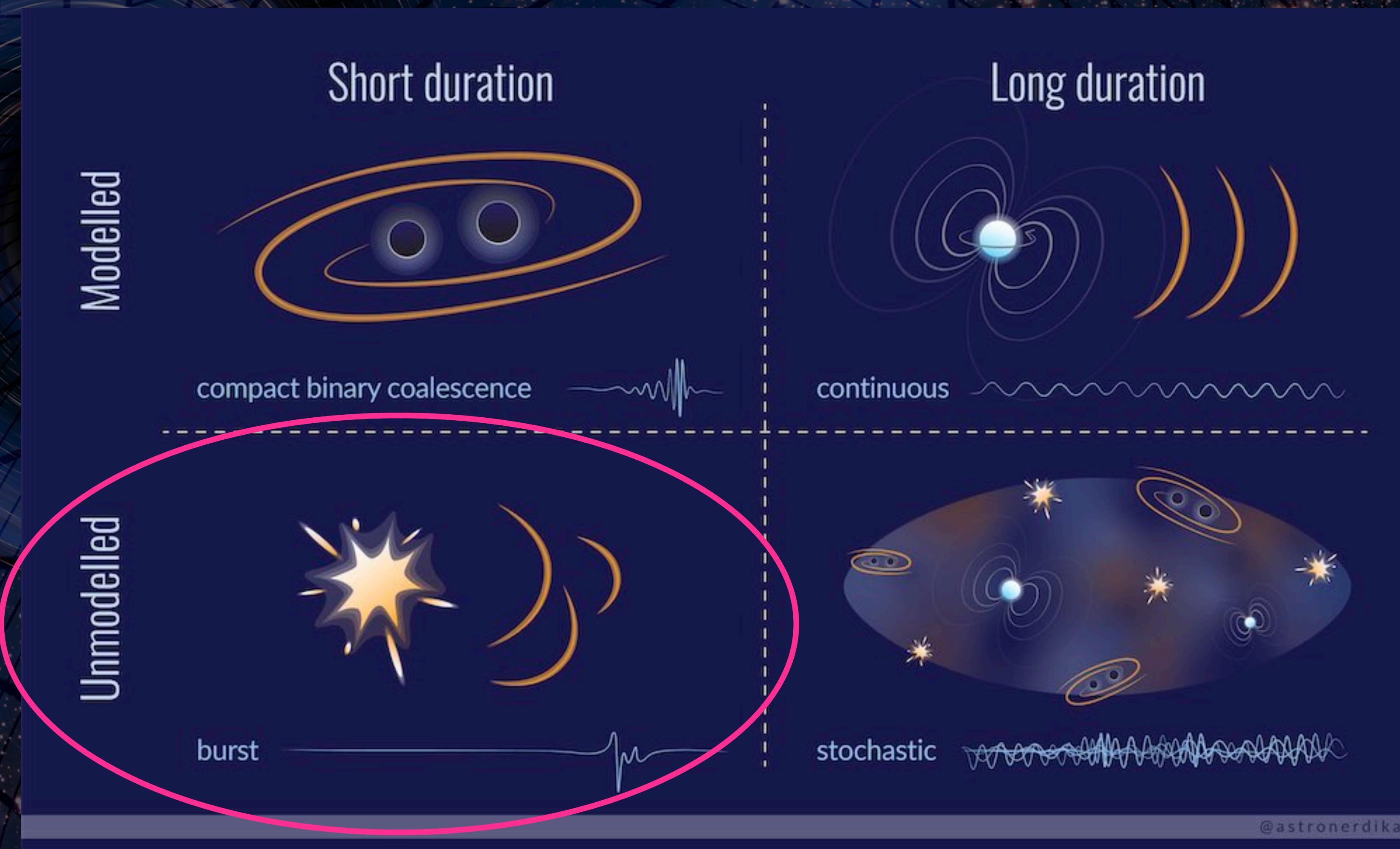
ARC Centre of Excellence for Gravitational Wave Discovery



TALK OVERVIEW

- Gravitational-wave (GW) bursts and Instrumental glitches
- *BayesWave* algorithm overview
- Multi-detector network analyses with *BayesWave*
 - **PART I:** Impact of noise transients on GW burst detection efficiency
 - **PART II:** Characterization of gravitational-wave burst polarizations

TYPES OF GW SOURCES



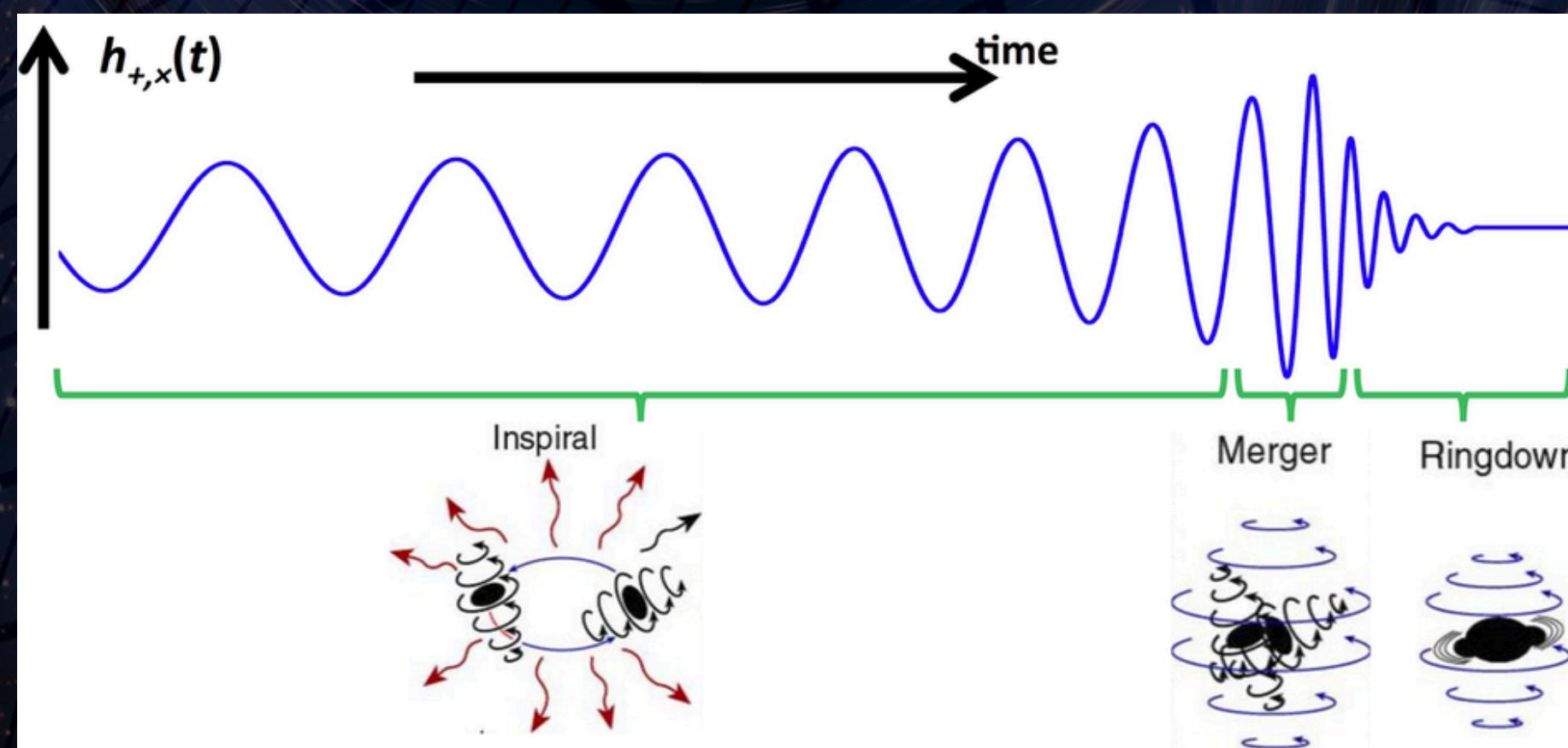
WHY SEARCH FOR “UNMODELED” BURSTS?

- Detection of known potential sources

- Supernovae (SNe)
- Gamma-ray Bursts (GRB)

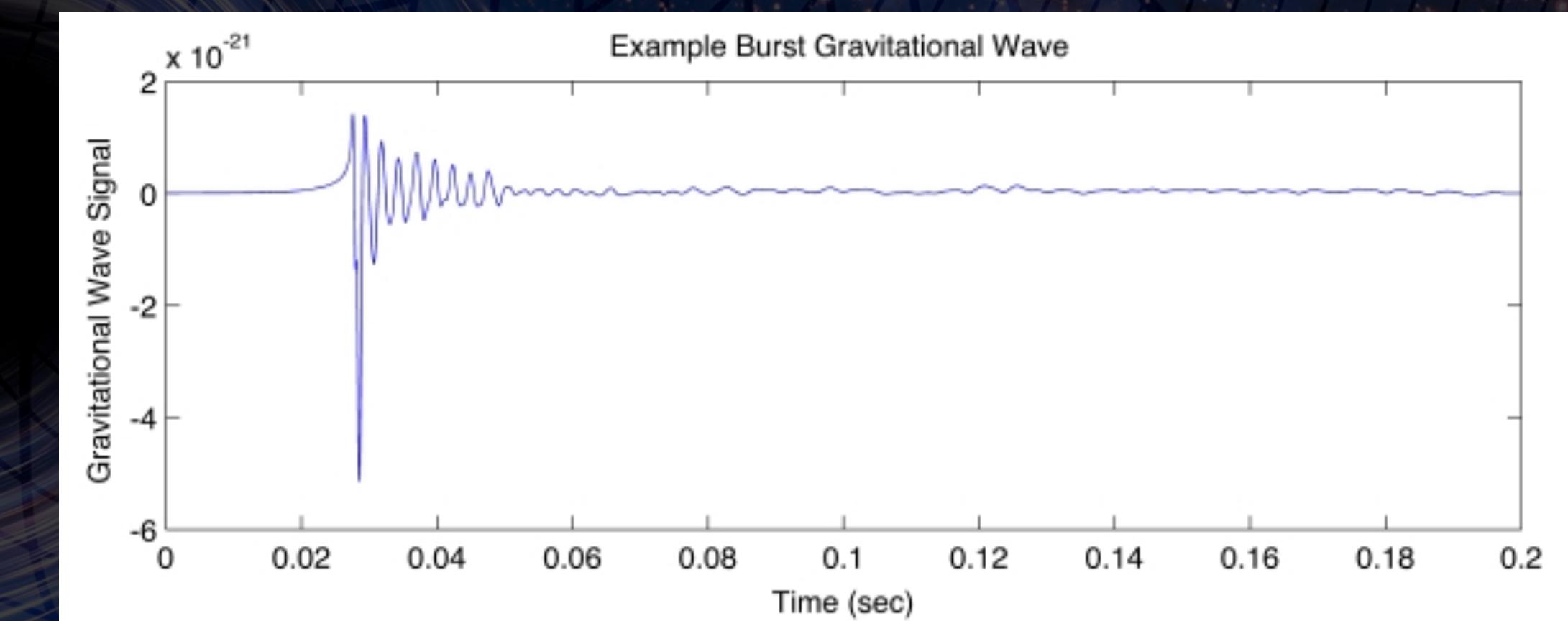
- New discoveries!

- We may not know the source, but we know what the waveform looks like



[Image: M. Favata/SXS/K. Thorne]

Modelled, well-understood waveforms (CBC)



[Image: A. Stuver/LIGO using data from C. Ott, D. Burrows, et al.]

Sample unmodeled GW burst waveform

WHAT IS IN THE DETECTOR DATA?

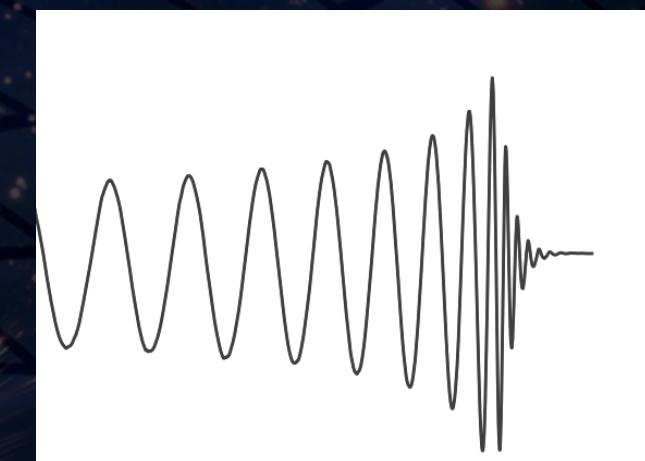
Data

=

Signal
(maybe)

+

Noise



\vec{s}

$h(\vec{\theta})$

\vec{n}

Noise components:

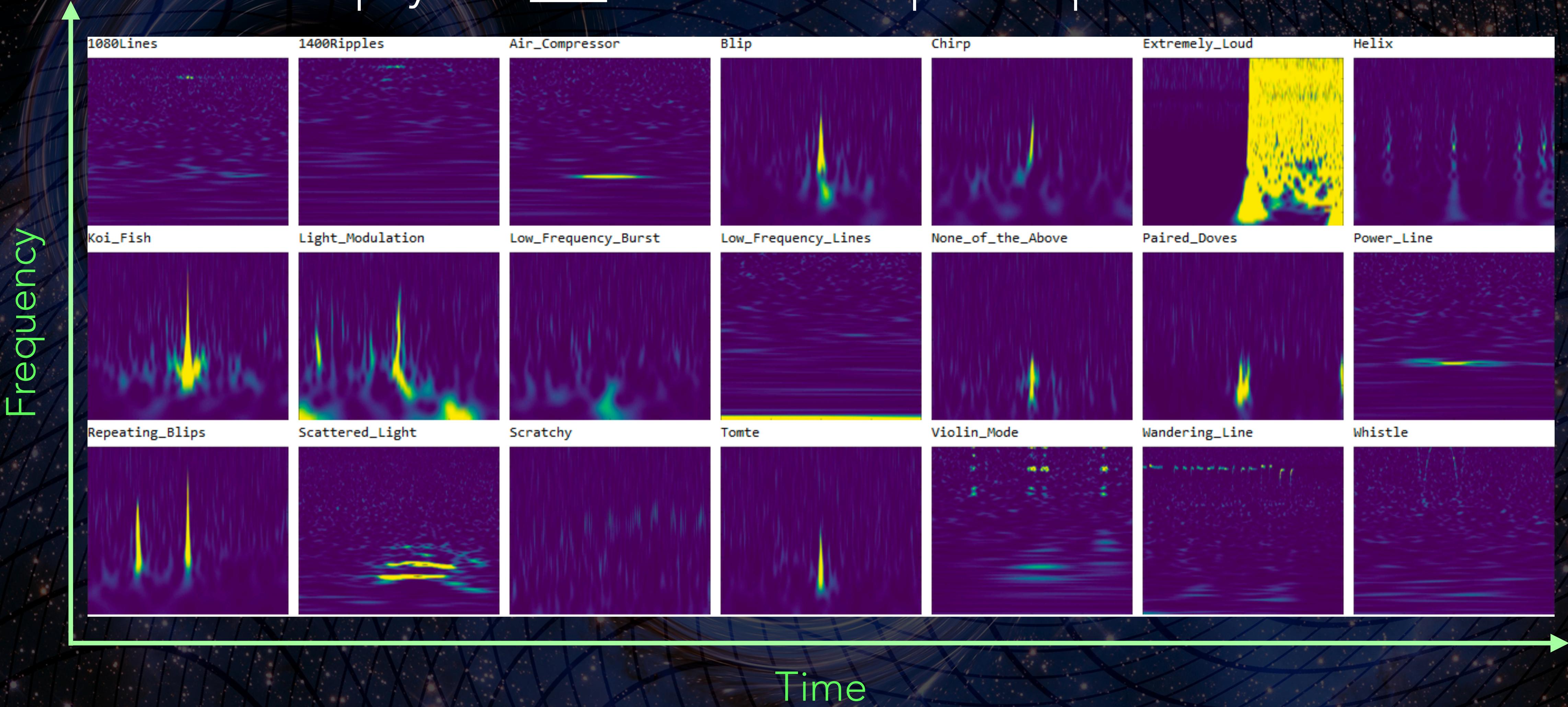
$$\vec{n} = \overrightarrow{n_G} + \vec{g}$$

Stationary, Gaussian noise

Instrumental glitches
(non-stationary, non-Gaussian)

THE PROBLEM: INSTRUMENTAL GLITCHES

Non-astrophysical and non-Gaussian power spikes in the detector



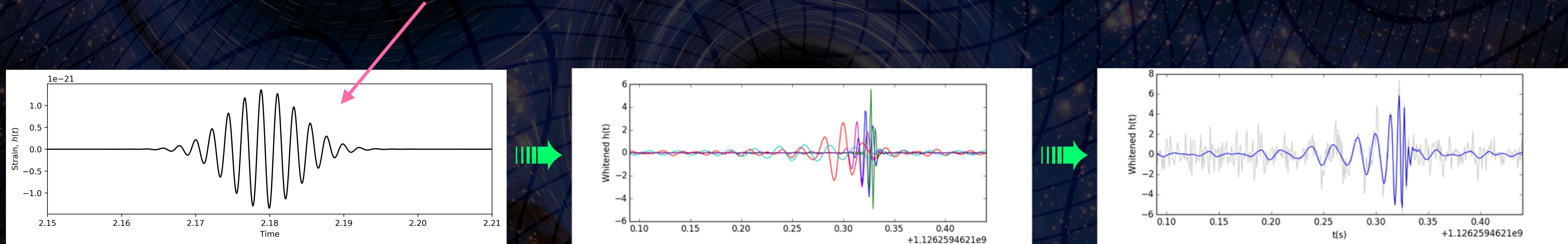


INTRODUCING...

THE BAYESWAVE ALGORITHM

BAYESWAVE: ALGORITHM OVERVIEW

- An unmodelled transient gravitational wave (burst) analysis algorithm
- Enables joint characterization of instrumental glitches and GW bursts
- Reconstructs transient, non-Gaussian features in the data by summing a set of sine-Gaussian wavelets, with no *a priori* assumptions



Images courtesy of Meg Millhouse

BayesWave publications:

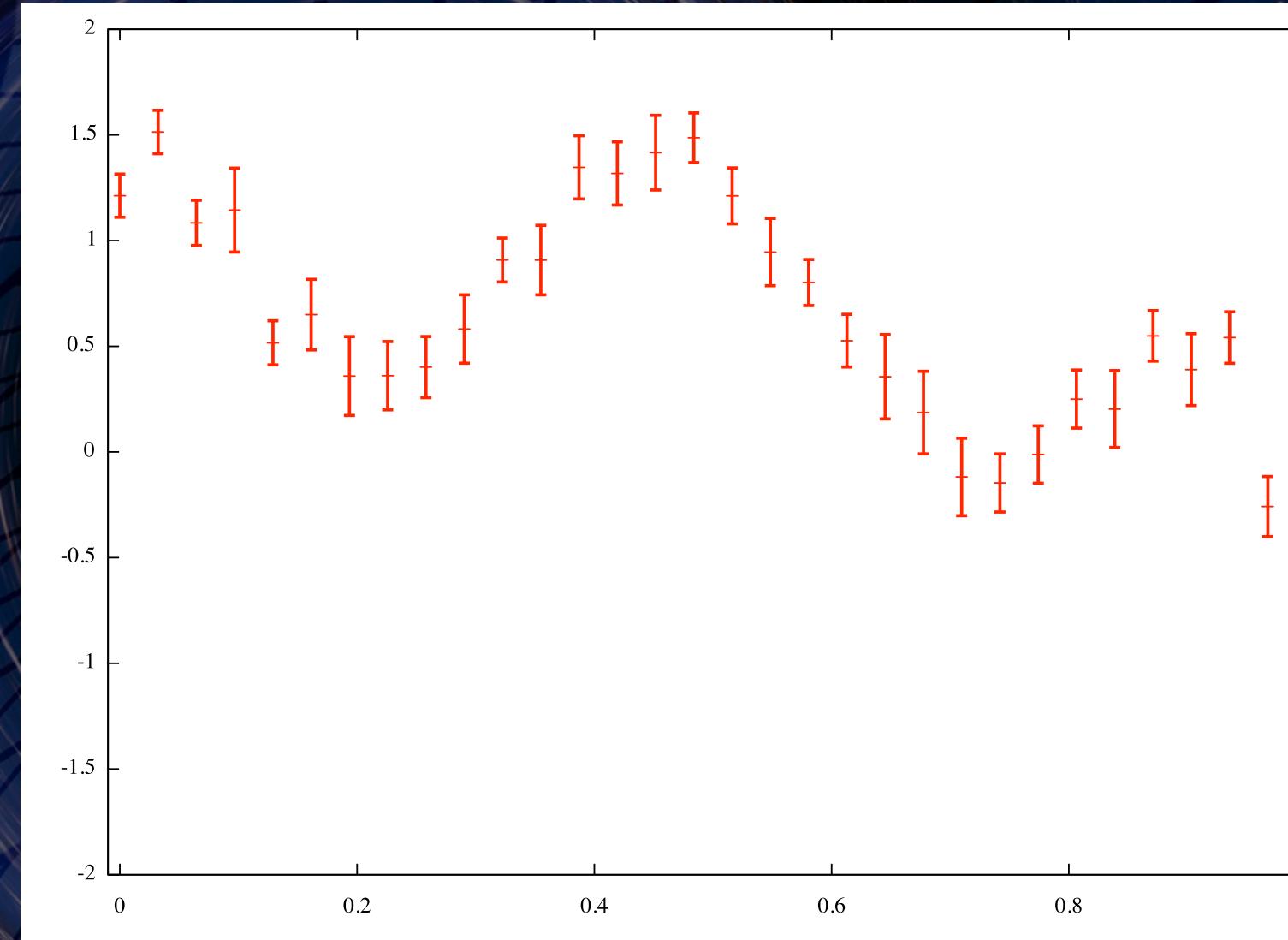
Cornish + Littenberg, Class. Quant. Grav 32, 130512 (2015)

Cornish et al., Phys. Rev. D 103, 044006 (2021)

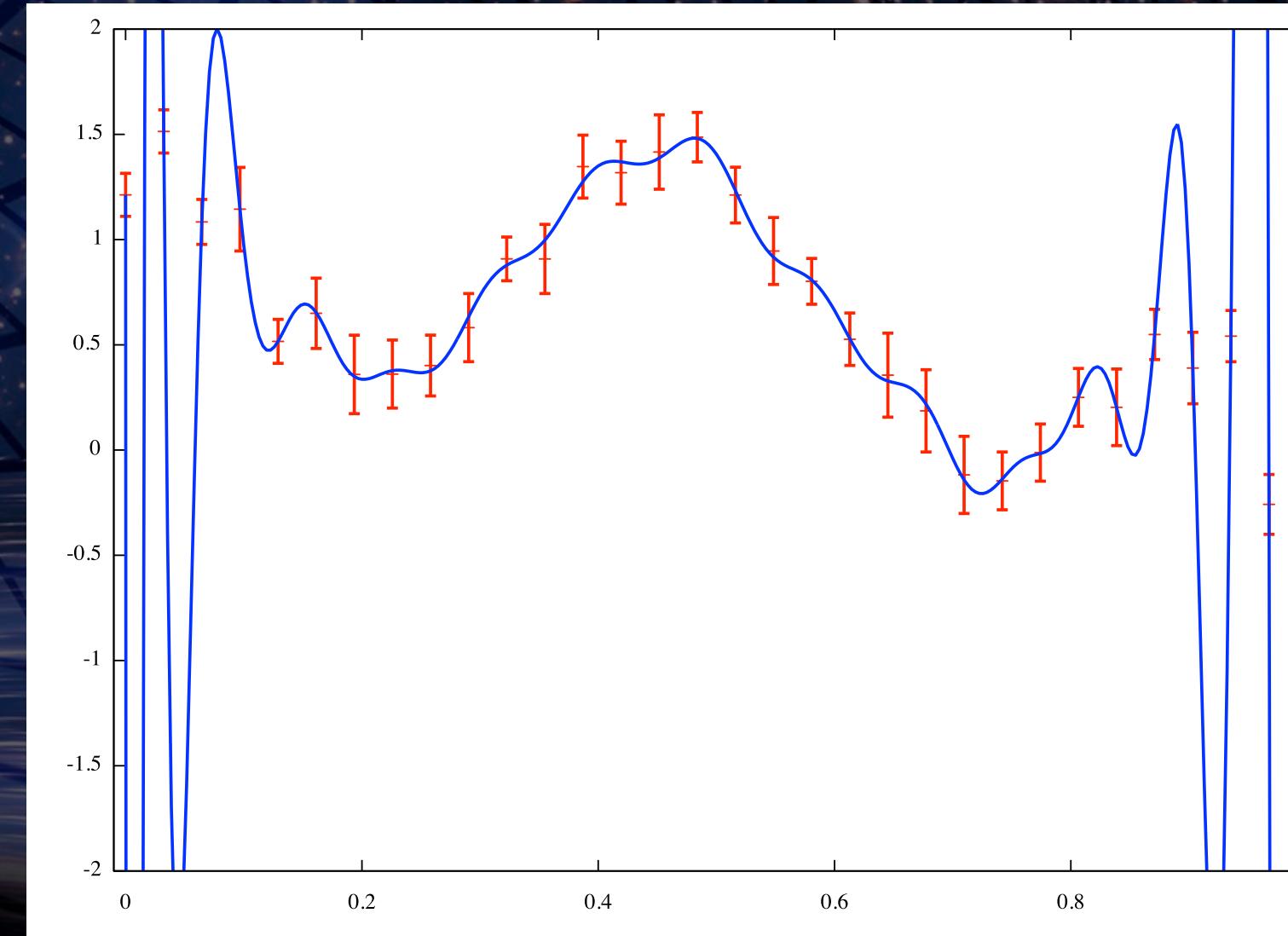
BAYESWAVE: MODEL PARAMETERS - RJMCMC

- BayesWave uses the trans-dimensional Reversible Jump Markov Chain Monte Carlo (RJMCMC)
 1. To sample model (i.e. wavelet) parameters
 2. To sample model dimensions i.e. number of wavelets used to describe instrumental glitches and/or GW signals
- Trans-dimensional steps involve adding/removing a wavelet

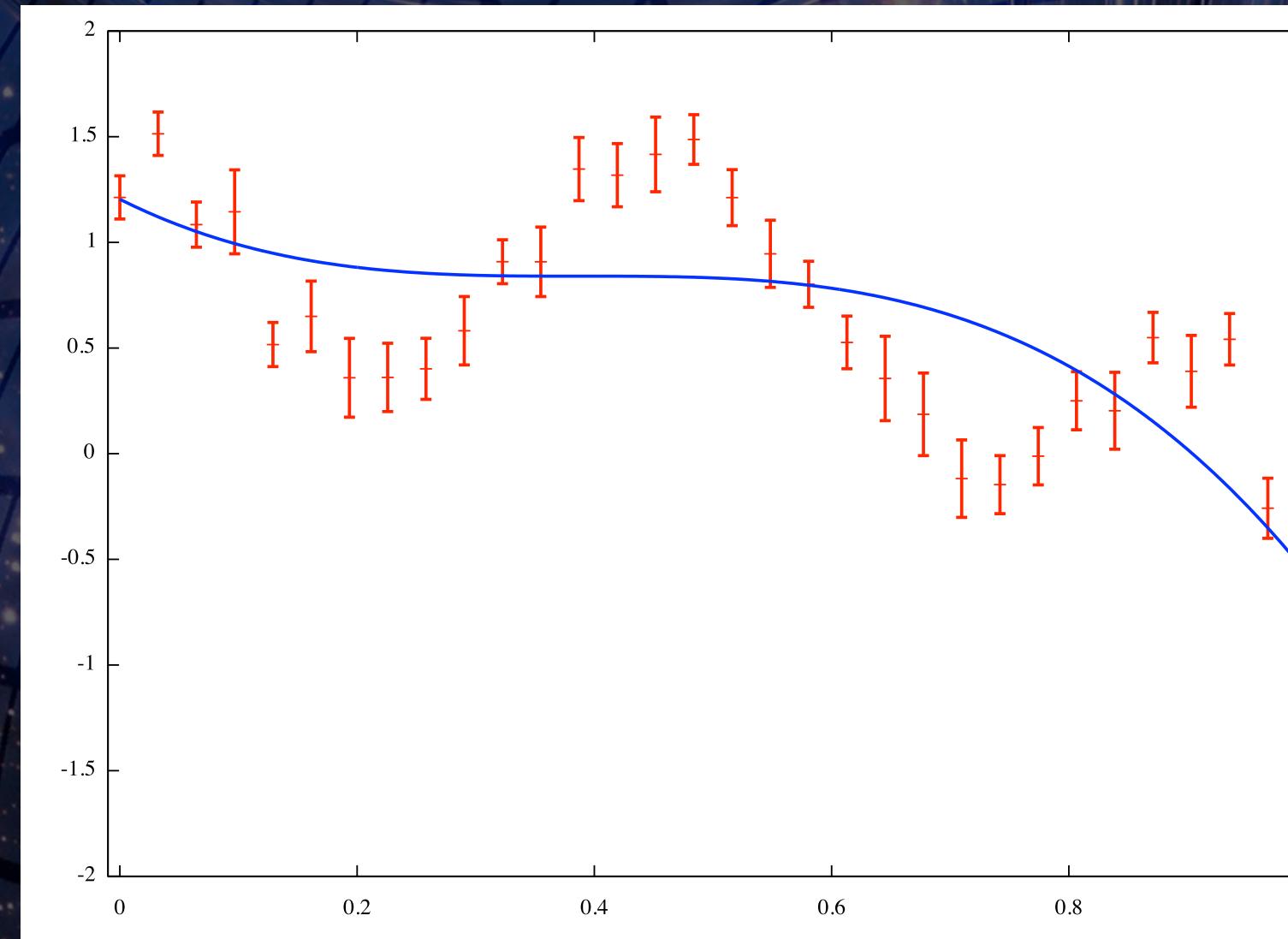
RJMCMC: FINDING THE BEST FIT MODEL



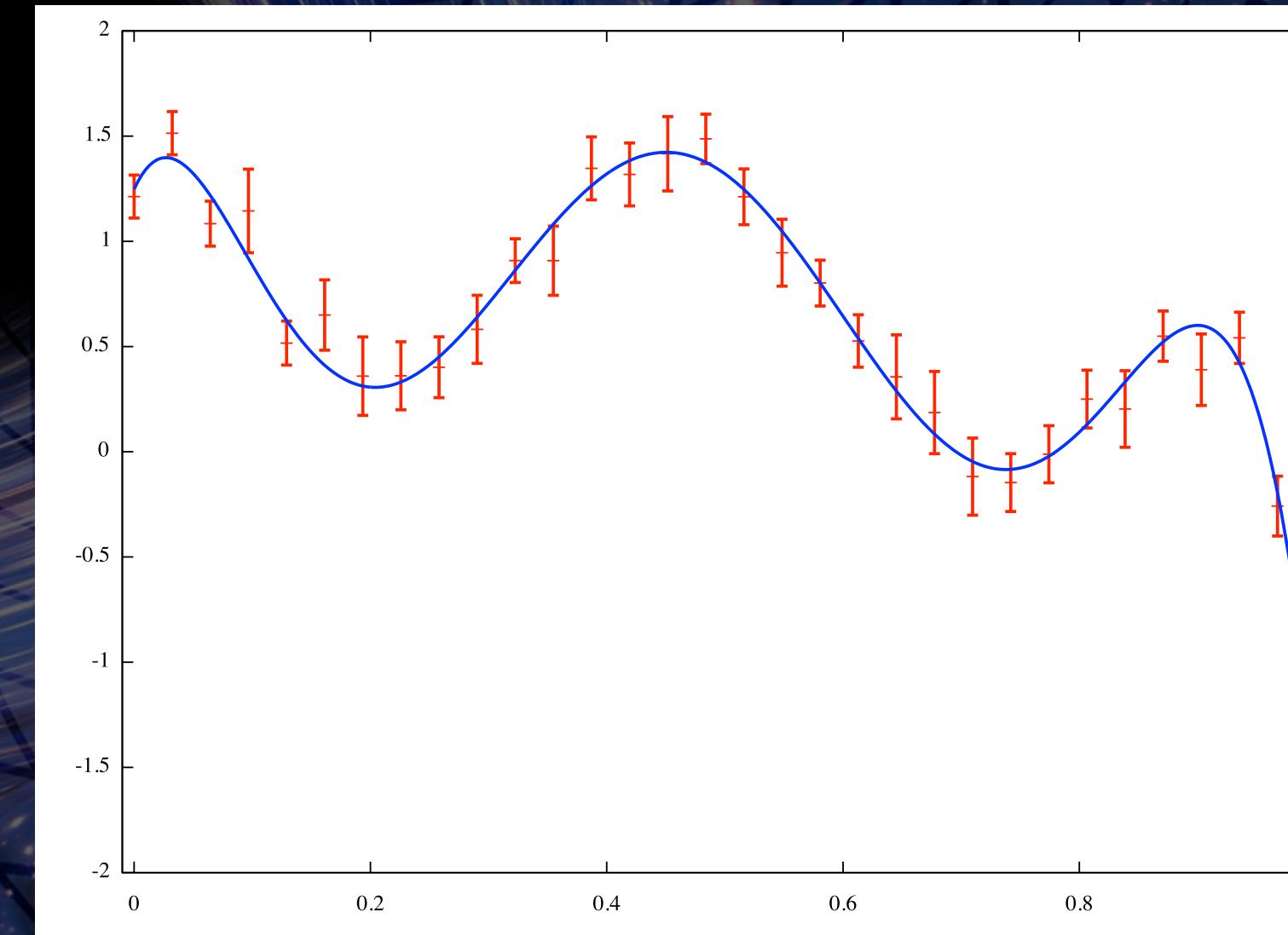
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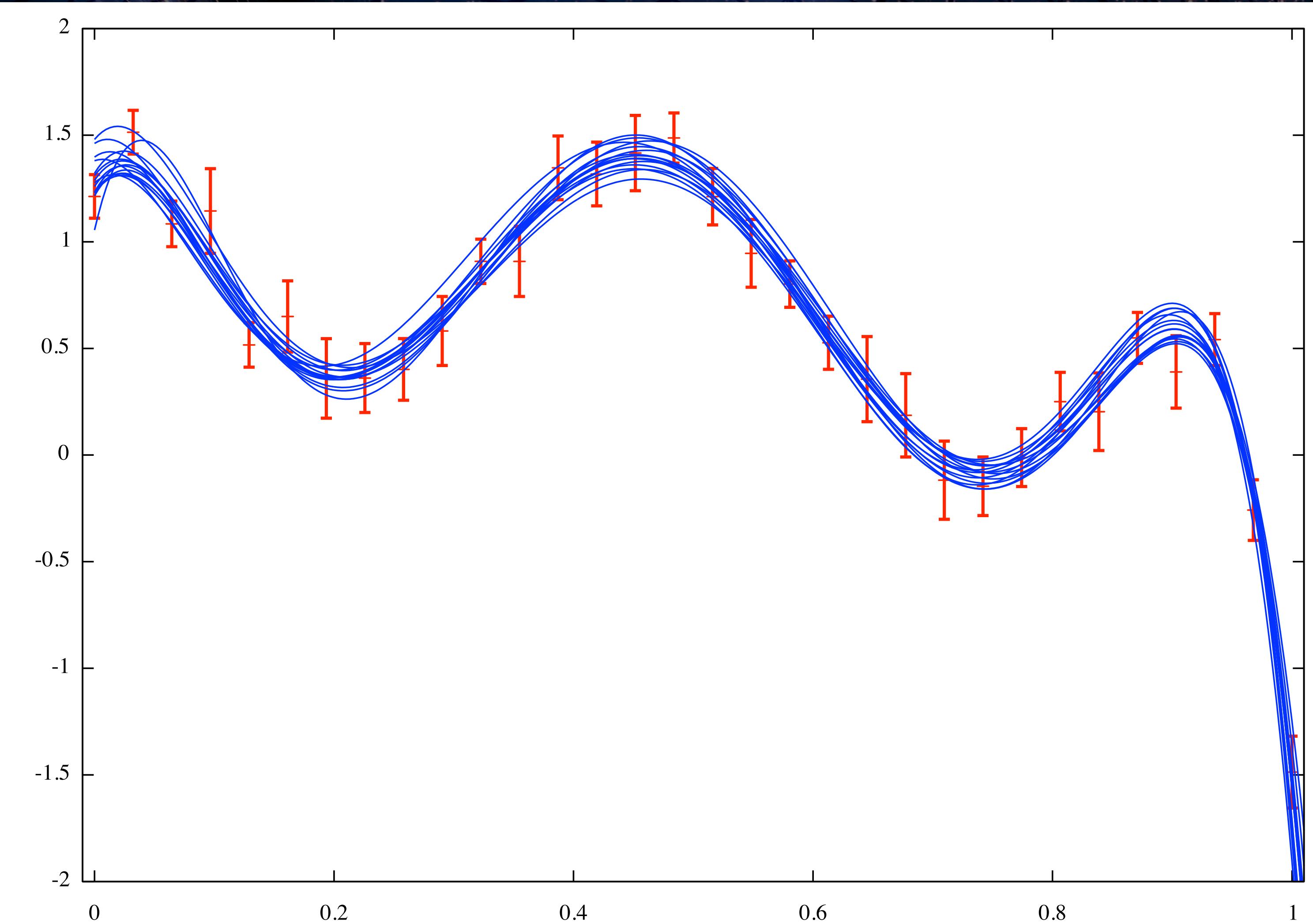


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[Image credits: Neil Cornish]

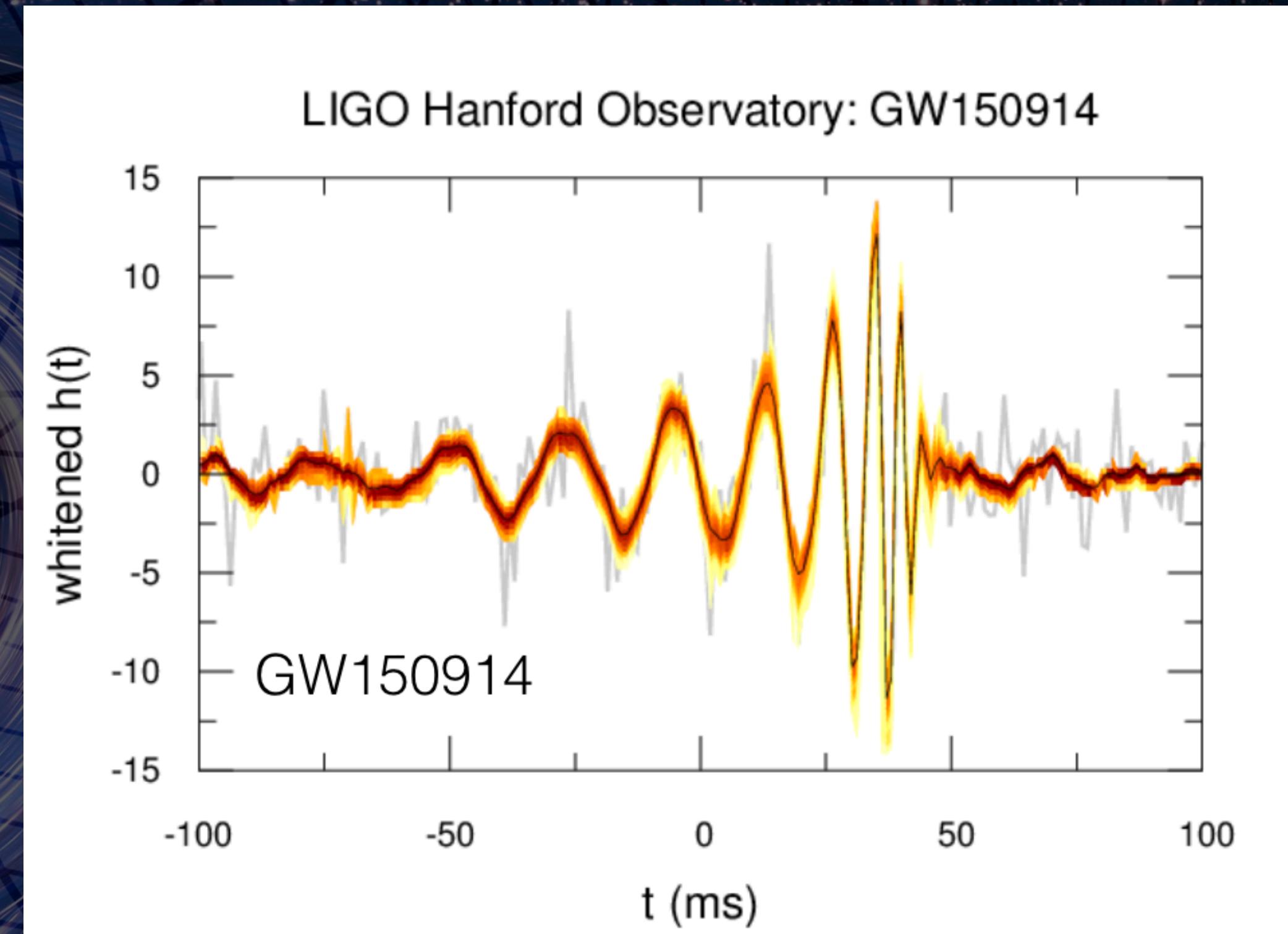
RJMCMC: POSTERIOR DISTRIBUTION OF SUITABLE FITS



[Image credits: Neil Cornish]

BAYESWAVE: WAVEFORM POSTERIOR

- At each MCMC iteration, we get:
 - (i) Number of wavelets, N
 - (ii) Parameters of each of the N wavelets from which we can construct waveform model by summing all the N wavelets
- Waveform Posterior:
Combine waveform models across all iterations



[Image courtesy of Jonah Kanner, Tyson Littenberg, and Meg Millhouse]

BAYESWAVE: MODEL SELECTION

- Reconstructs transient features using three independent models:
 - Signal plus Gaussian-noise model, \mathcal{S}
 - Glitch plus Gaussian-noise model, \mathcal{G}
 - Gaussian-noise only model, \mathcal{N}
- “Model everything and let the data sort it out”

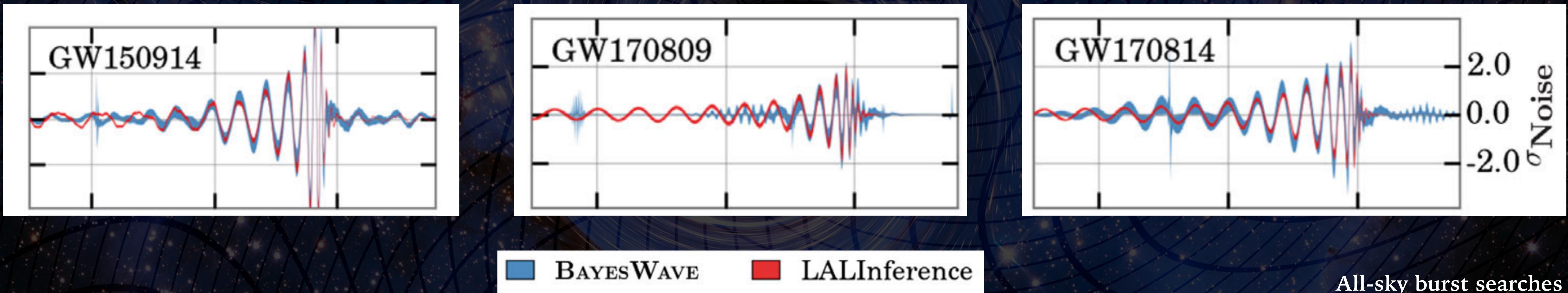
BAYES FACTOR = Bayesian evidence ratio between two models

$$\text{e.g. } \mathcal{B}_{\mathcal{S},\mathcal{G}} = \frac{p(\vec{s} | \mathcal{S})}{p(\vec{s} | \mathcal{G})}$$

If $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} > 0 \Rightarrow \mathcal{S}$ is more strongly supported by data than \mathcal{G}

BAYESWAVE: ROLE IN GW BURST SEARCHES

- Used to follow-up searches for GW events in O1, O2 and O3 *
To assess consistency with matched-filter (model-based) searches
- Also used to follow-up trigger events found by coherent WaveBurst (cWB) to increase detection confidence



GWTC-1: Phys. Rev. X 9, 031040 (2019),
GWTC-2: Phys. Rev. X 11, 021053 (2021),
GWTC-3: arXiv:2111.03606 (2021).

All-sky burst searches

O1: Phys. Rev. D 95, 042003 (2017)
O2: Phys. Rev. D 100, 024017 (2019)
O3: Phys. Rev. D 104, 122004 (2021)

PART IA:
BURST DETECTION CONFIDENCE
OF BAYESWAVE
WITH MULTI-DETECTOR NETWORKS



EXPANDING GW DETECTOR NETWORK

- Existing 2nd-generation ground-based detectors:
 - (1) LIGO - Hanford and Livingston, United States
 - (2) Virgo, Italy
 - (3) KAGRA, Japan
- LIGO India approved and under commission
- Three observing runs O1, O2, O3; and O4 is happening right now



Livingston

Hanford

[Image credits: LIGO Lab Caltech]

ANALYTIC SCALING OF $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$

- BayesWave's detection confidence quantified using the log signal-versus-glitch-model Bayes factor, $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$
- Analytic approximation of $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ for a 2-detector network is

$$\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \simeq \frac{5N}{2} + N \ln V_\lambda + \boxed{5N \ln \left(\frac{\text{SNR}_{\text{net}}}{\sqrt{N}} \right)} - \sum_{n=1}^N \ln \bar{Q}_n + \left[2 + \ln \frac{\sqrt{\det C_\Omega}}{4\pi^2} \right]$$

- Main scaling: $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \sim N \ln \text{SNR}_{\text{net}}$
 - (i) N : number of wavelets (i.e. model complexity)
 - (ii) SNR_{net} : signal-to-noise ratio

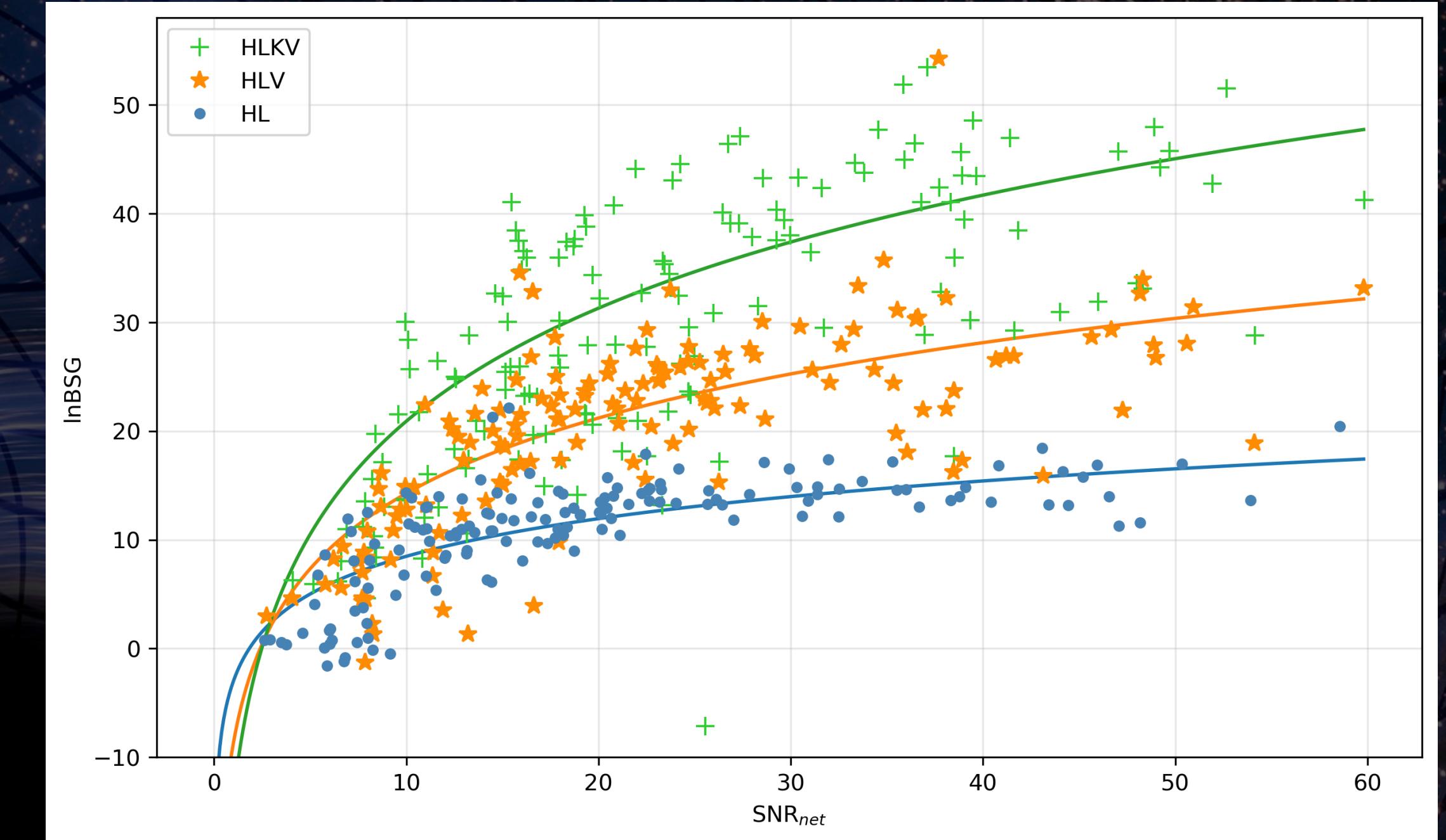
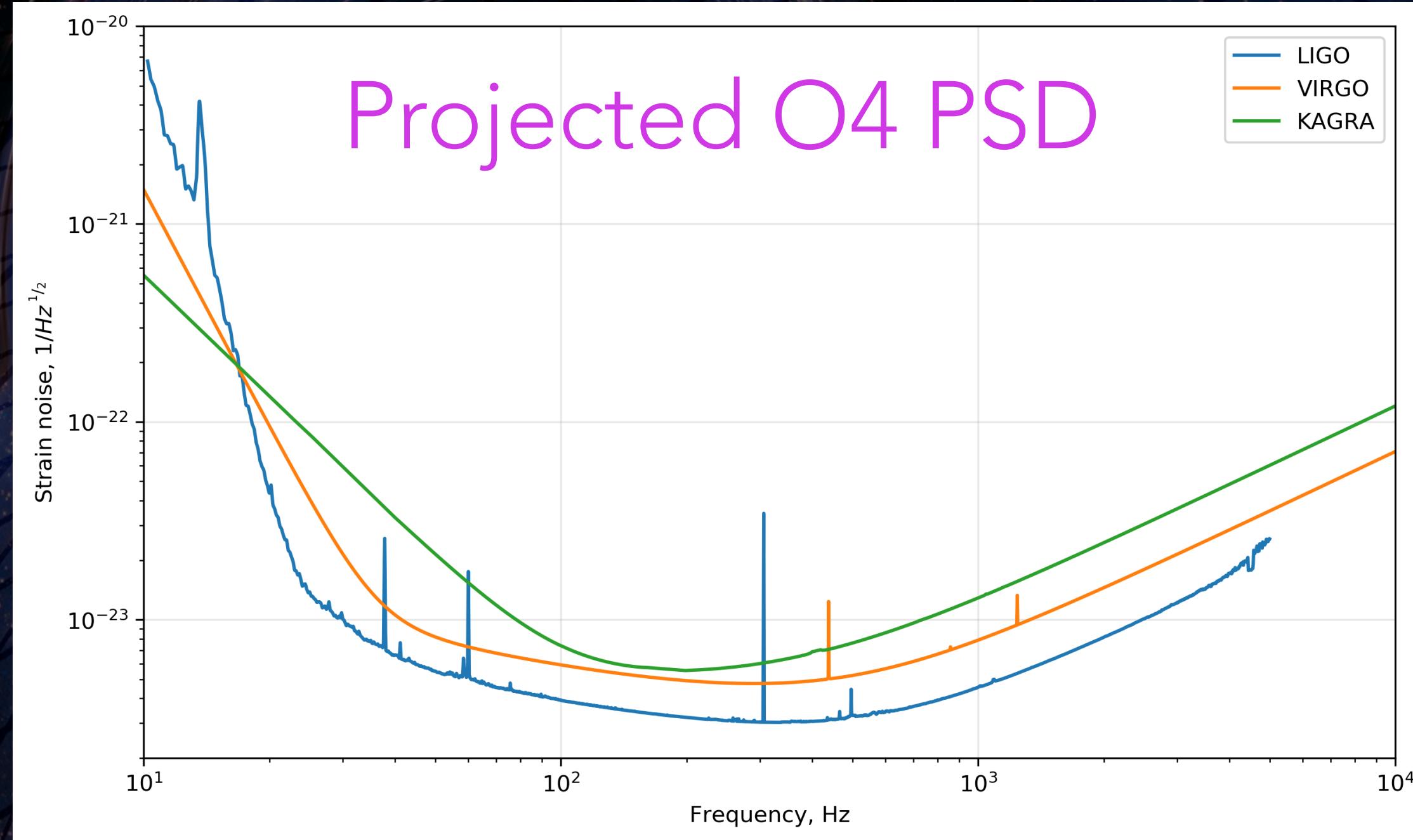
ANALYTIC SCALING OF $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$

- Generalizing for an \mathcal{J} -detector network:

$$\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \simeq (\mathcal{J} - 1) \left[\frac{5N}{2} + N \ln(V_\lambda) - \sum_{n=1}^N \ln(\bar{Q}_n) + 5N \ln \left(\frac{\text{SNR}_{\text{net}}}{\sqrt{N}} \right) \right] - \frac{5}{2} \mathcal{J} N \ln(\mathcal{J}) + \left(2 + \ln \frac{\sqrt{\det C_\Omega}}{V_\Omega} \right)$$

- Main scaling: $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \sim \mathcal{J} N \ln \text{SNR}_{\text{net}}$
 - (i) \mathcal{J} : number of detectors
 - (ii) N : number of wavelets (i.e. model complexity)
 - (iii) SNR_{net} : signal-to-noise ratio

EMPIRICAL SCALING: SINE-GAUSSIAN INJECTIONS ($N=1$)

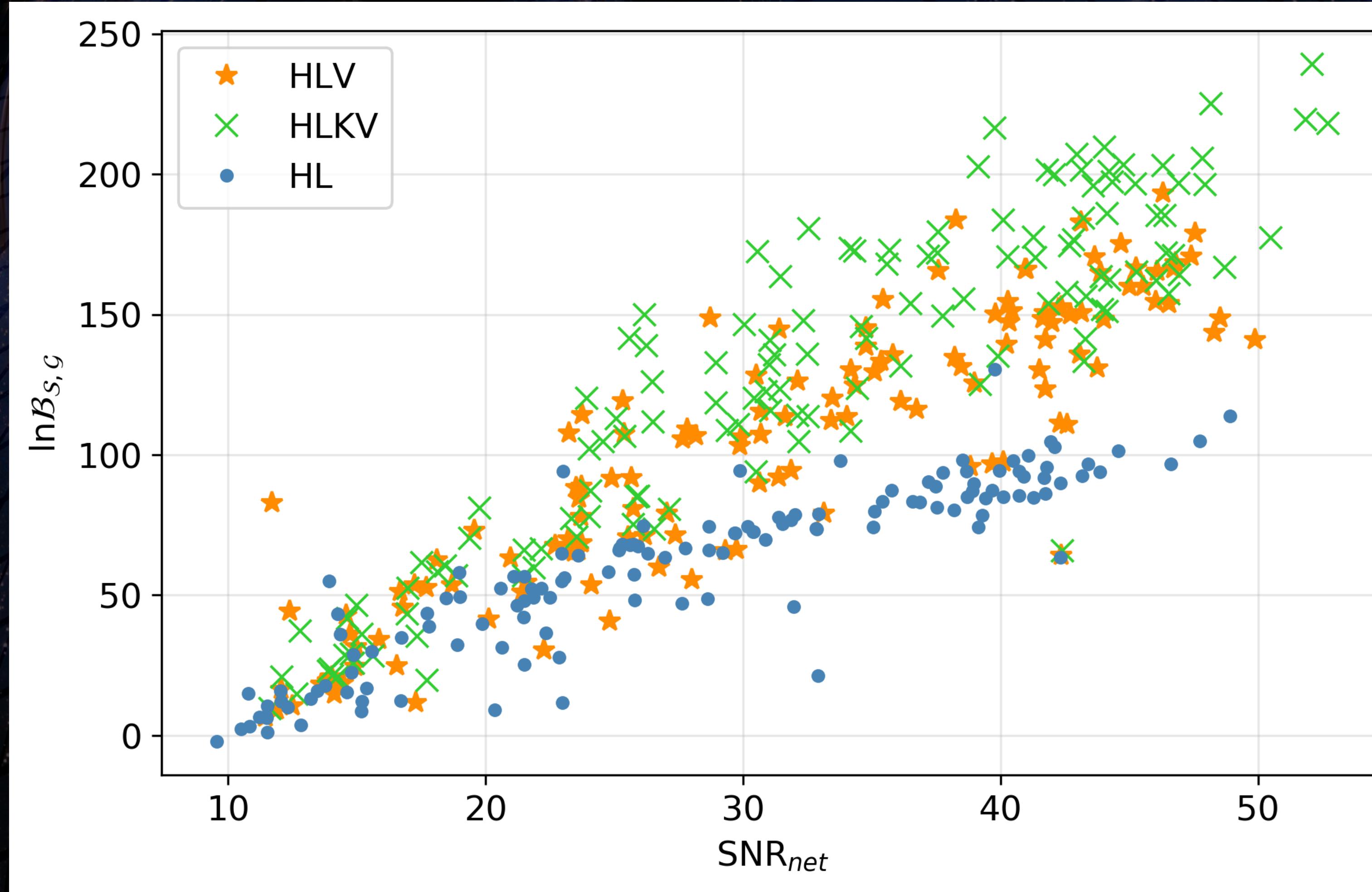


$$\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \simeq (\mathcal{J} - 1) \left[\frac{5N}{2} + N \ln(V_\lambda) - \sum_n^N \ln(\bar{Q}_n) + 5N \ln \left(\frac{\text{SNR}_{\text{net}}}{\sqrt{N}} \right) \right] - \frac{5}{2} \mathcal{J} N \ln(\mathcal{J}) + \left(2 + \ln \frac{\sqrt{\det C_\Omega}}{V_\Omega} \right)$$

for $N = 1$ simplifies to:

$$\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} \approx (\mathcal{J} - 1)[5 \ln \text{SNR}_{\text{net}} + c] + \frac{5}{2} \mathcal{J} \ln \mathcal{J} + d$$

EMPIRICAL SCALING: BINARY BLACK HOLE INJECTIONS

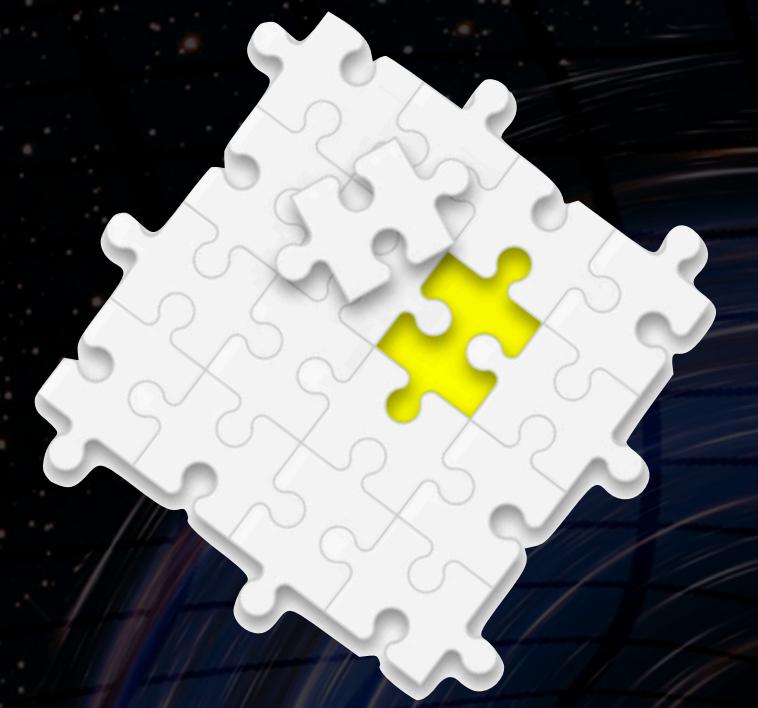


At comparable SNR_{net} ...

$\ln \mathcal{B}_{S,G}$ increases as the number of detector \mathcal{I} increases



Consistent with
 $\ln \mathcal{B}_{S,G} \sim \mathcal{I} N \ln \text{SNR}_{\text{net}}$



THE MISSING PUZZLE PIECE

- This work studies the improvement in $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ of astrophysical triggers with expanded detector networks
- BUT...
Larger detector networks are more susceptible to instrumental glitches i.e. noisier detector backgrounds!

PART IB:
IMPACT OF NOISE TRANSIENTS ON
GW BURST DETECTION EFFICIENCY
OF BAYESWAVE





AIM OF THIS WORK

- Study the overall performance of *BayesWave* by accounting for the noise background
- Compare performance between:
 - Hanford-Livingston (HL), 2-detector network
 - Hanford-Livingston-Virgo (HLV), 3-detector network

FALSE ALARM PROBABILITY, P_{FA}

/measure of detection significance/

Probability that a trigger event with a given
detection statistic ($\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$) is a false alarm
i.e. non-astrophysical

Lower P_{FA} = Higher astrophysical significance

DETECTION EFFICIENCY P_{det}

/figure of merit for *BayesWave*'s overall performance/

Probability of detecting an astrophysical event
with a given significance (P_{FA})

EFFICIENCY CURVES

To characterise

DETECTION EFFICIENCY P_{det}

as a function of

FALSE ALARM PROBABILITY P_{FA}

EFFICIENCY CURVE "RECIPE"

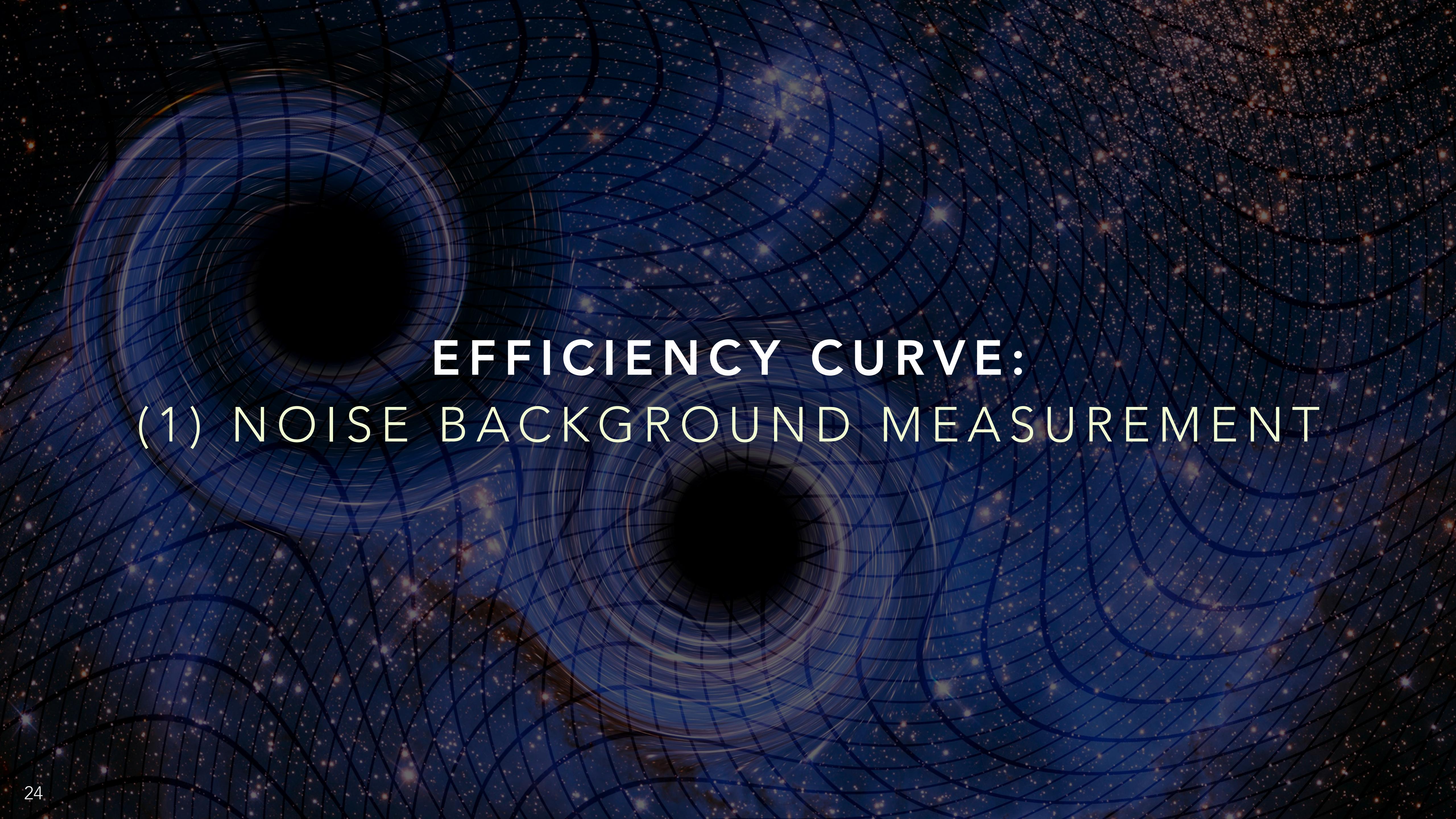
2 COMPONENTS:

(1) NOISE BACKGROUND MEASUREMENTS $\rightarrow P_{\text{FA}}$

- Distribution of BayesWave's detection statistics $\ln \mathcal{B}_{\mathcal{S}, \mathcal{G}}$ for **non-astrophysical triggers**

(2) ASTROPHYSICAL MEASUREMENTS $\rightarrow P_{\text{det}}$

- As above, but for **astrophysical triggers**
- Compare with noise background measurements to get P_{det}



EFFICIENCY CURVE: (1) NOISE BACKGROUND MEASUREMENT

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STEP 1: Down-selecting background triggers

- From Coherent WaveBurst (cWB) trigger lists of O3a time-slide data

HOW?

Fraction of randomly selected triggers satisfying $\rho \geq 7$

ρ scales with signal-to-noise ratio (SNR)

- HL → 1008 triggers
- HLV → 1134 triggers

EFFICIENCY CURVE: (1) NOISE BACKGROUND MEASUREMENT

STEP 2: Identifying Gaussian-noise-like background triggers

- Events more consistent with the Gaussian-noise model, \mathcal{N} than the Gaussian-noise plus signal model, \mathcal{S} :
$$\ln \mathcal{B}_{\mathcal{S},\mathcal{N}} - \Delta \ln \mathcal{B}_{\mathcal{S},\mathcal{N}} \leq 0$$
- Meaningless to compare odds between signal and glitch models via $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$
- Cannot remove from dataset as they still satisfy $\rho \geq 7$
- Assign arbitrarily low detection statistics: $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} = -500$

EFFICIENCY CURVE: (1) NOISE BACKGROUND MEASUREMENT

STEP 3: Calculate P_{FA} as a function of $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$

P_{FA}
/probability of false alarm/

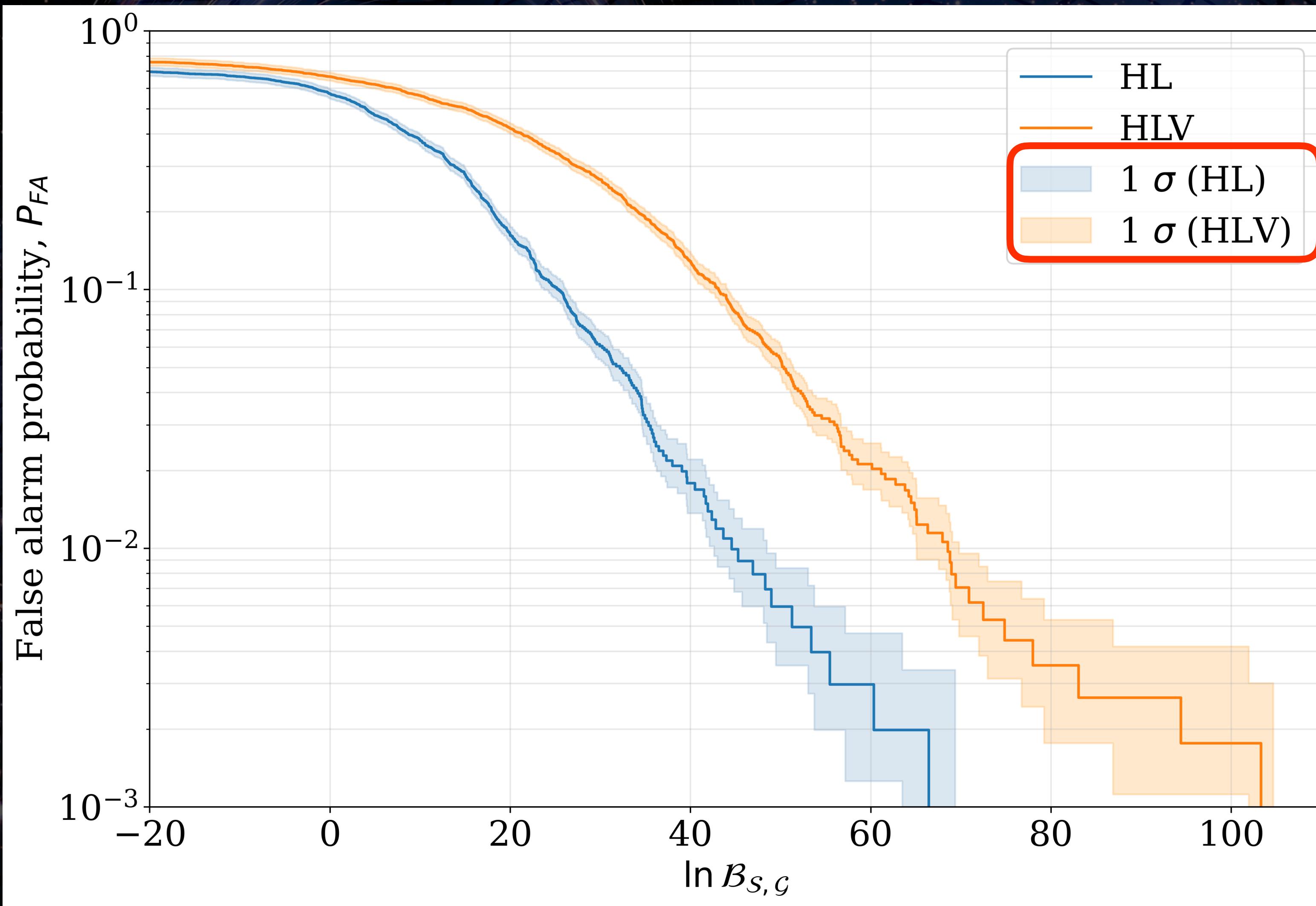
Per-trigger probability (i.e. fraction) of non-astrophysical triggers detected above a given $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ threshold

Why not False alarm RATE (FAR)?

- FAR is a time-averaged quantity
- The timescales of HL and HLV time-slide background data are different

- P_{FA} is time-independent and marginalises over the number of triggers analysed is more suitable for comparison between the two networks

EFFICIENCY CURVE: (1) NOISE BACKGROUND MEASUREMENT



STEP 4: Error bars

Assume Poisson process

s.t.

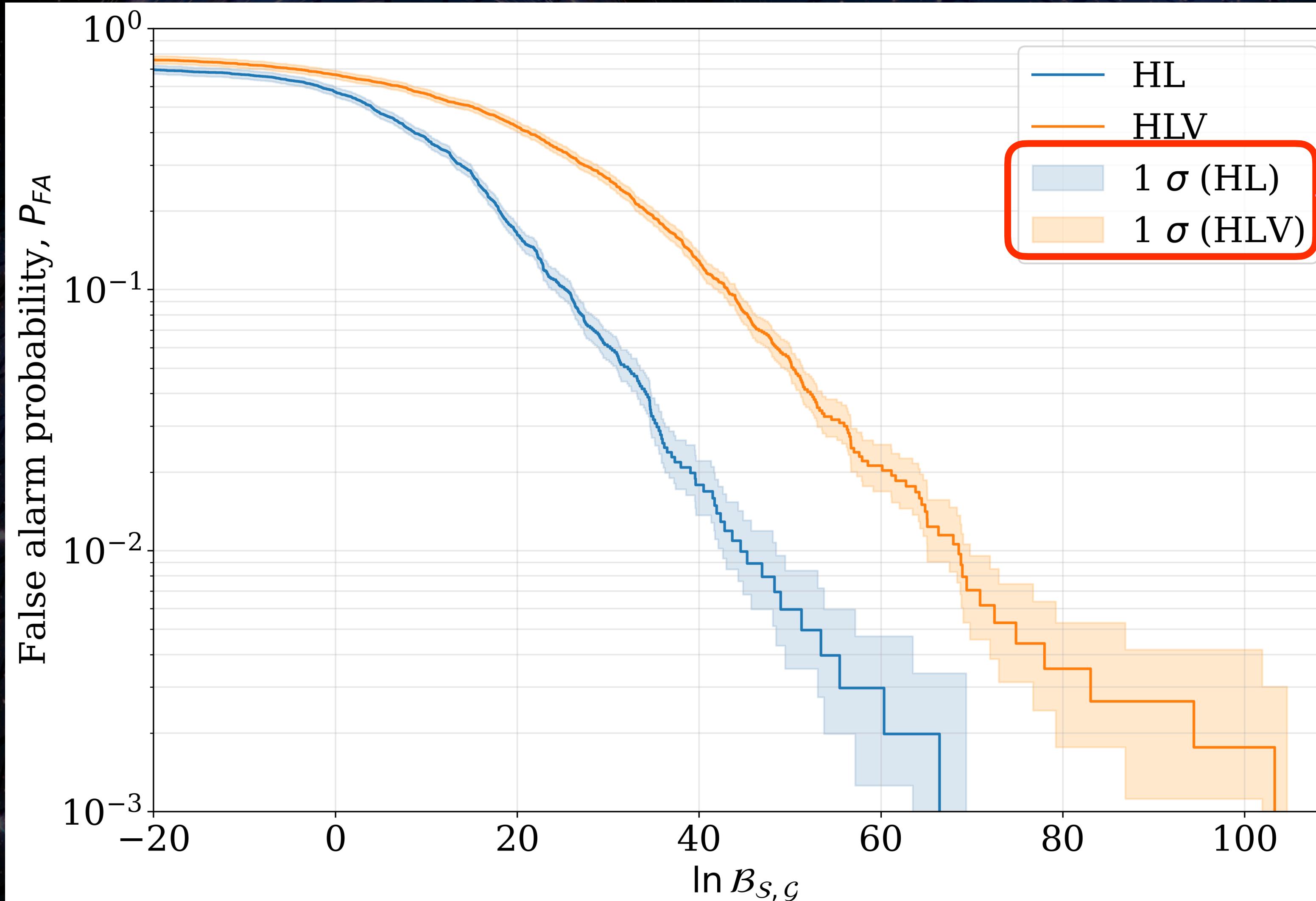
$1-\sigma$ in background event
counts, $n = \sqrt{n}$

∴

$1-\sigma$ in P_{FA} is $\frac{\sqrt{n}}{N}$

N : Total number of triggers
(1008 in HL, 1134 in HLV)

EFFICIENCY CURVE: (1) NOISE BACKGROUND MEASUREMENT



Poisson uncertainty region

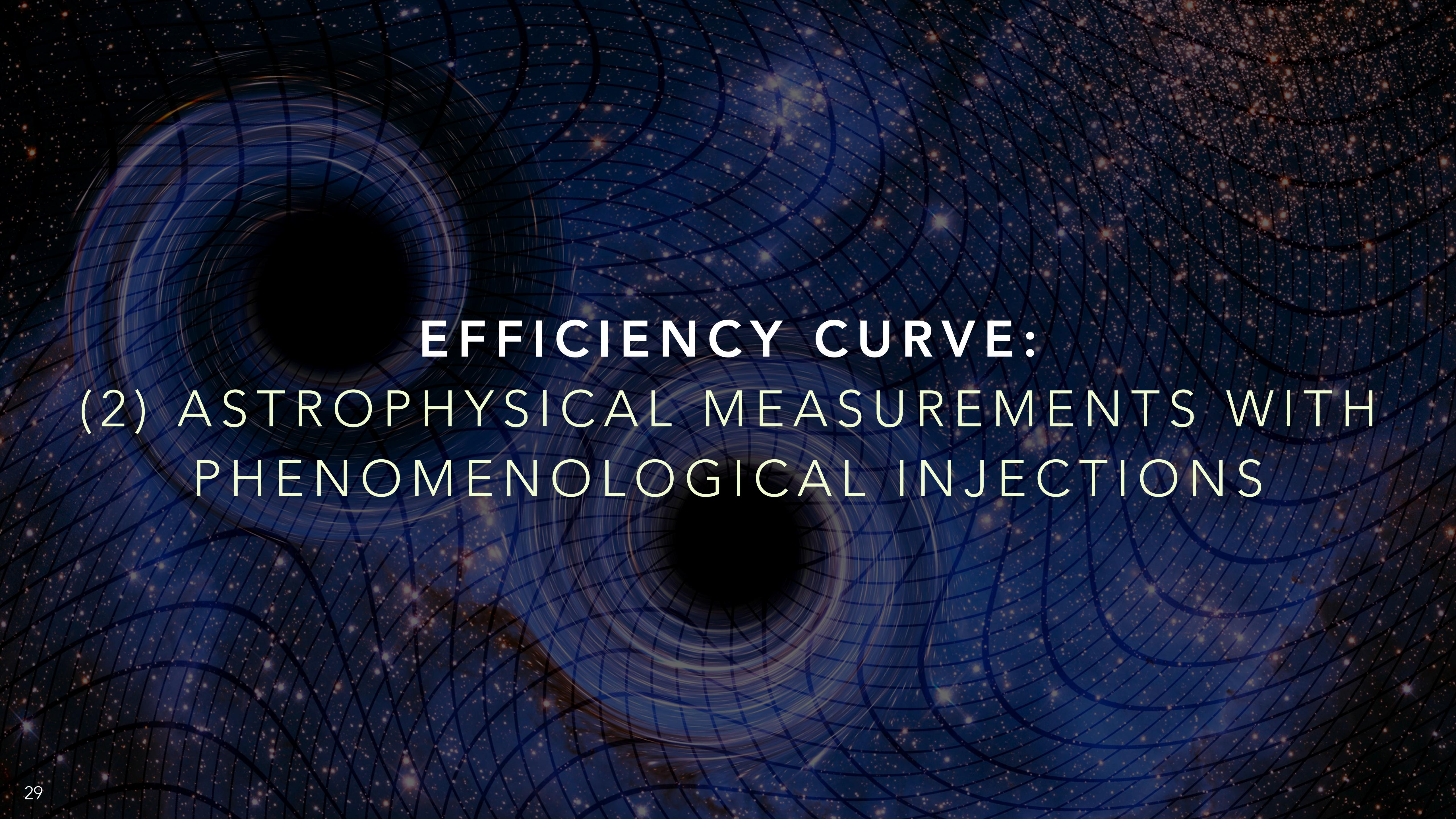
Assuming background noise is a
Poisson process

P_{FA} in HLV is higher than HL
for all $\ln \mathcal{B}_{S,G}$

i.e. HLV background is
NOISIER than HL

Consistent with cWB

Szczepańczyk et al. (2022)



EFFICIENCY CURVE: (2) ASTROPHYSICAL MEASUREMENTS WITH PHENOMENOLOGICAL INJECTIONS

EFFICIENCY CURVE: (2) ASTROPHYSICAL MEASUREMENTS

Properties of injected events

- **Phenomenological binary black hole (BBH) waveforms**
- 1200 injections
- Equal component masses $30M_{\odot}$
- Randomly sampled distances such that the network SNR is within range
 $10 \leq \text{SNR}_{\text{net}} \leq 50$
- Uniform sky location, inclination and polarisation
- **Injected into** randomly selected segments throughout all of **O3a**

EFFICIENCY CURVE: (2) ASTROPHYSICAL MEASUREMENTS

Filtering non-detections

- O3a data is noisier than simulated HLV data,
∴ Injected SNR_{net} are lower than the range $10 \leq \text{SNR}_{\text{net}} \leq 50$
- Nominal *BayesWave* significance threshold
Only follow-up events with $\text{SNR}_{\text{net}} \geq 10$
c.f. Only followed-up cWB (background) events with $\rho \geq 7$
- 790 events left → **The denominator of P_{det}**

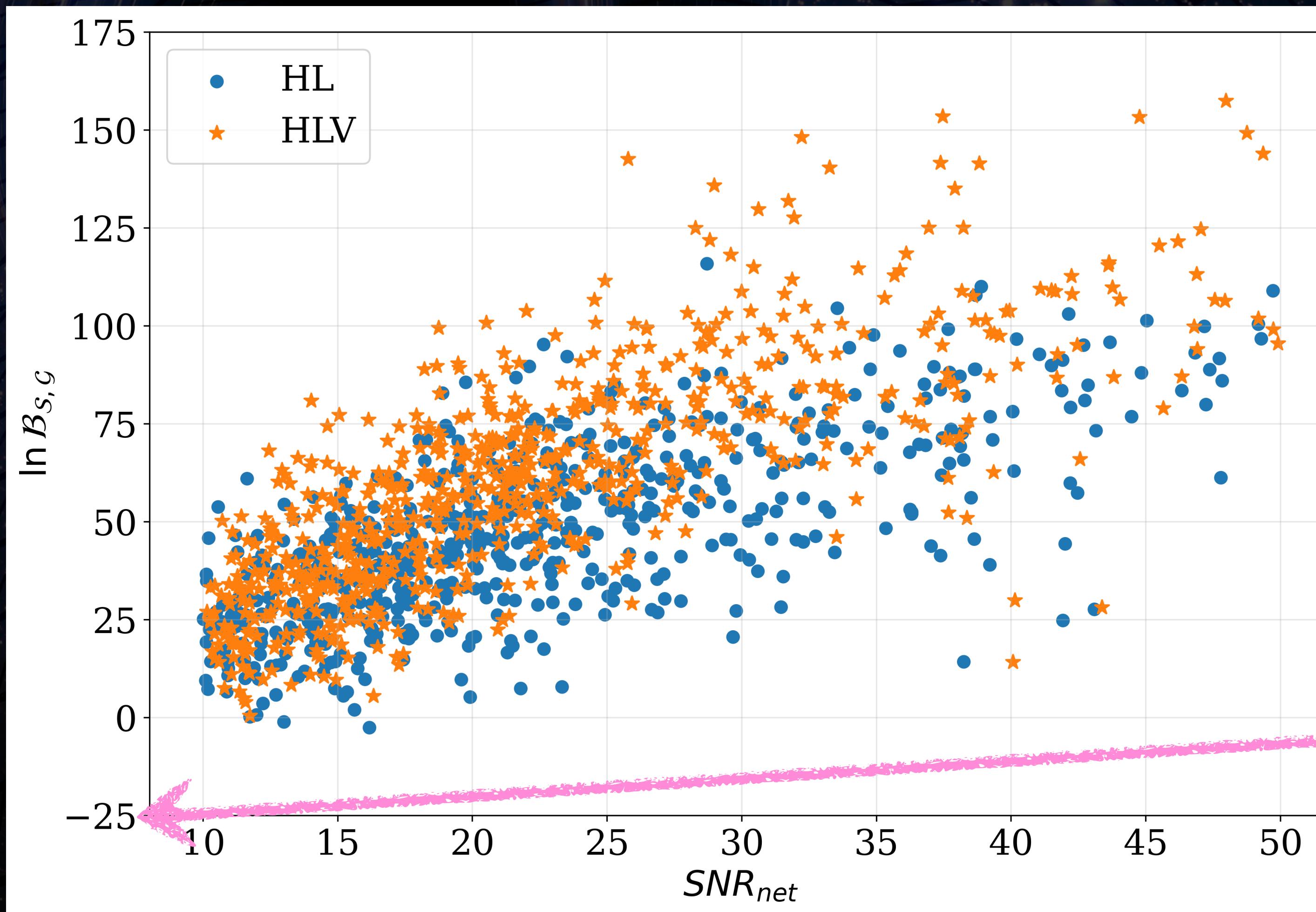
EFFICIENCY CURVE: (2) ASTROPHYSICAL MEASUREMENTS

IS1 Gaussian-noise-like events

- Events that satisfy $\text{SNR}_{\text{net}} \geq 10$
- But are more consistent with Gaussian noise
i.e. $\ln \mathcal{B}_{\mathcal{S},\mathcal{N}} - \Delta \ln \mathcal{B}_{\mathcal{S},\mathcal{N}} \leq 0$
- Retained in IS1 but...
Assign arbitrarily low detection statistics: $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} = -500$
(same as background triggers)

EFFICIENCY CURVE: (2) ASTROPHYSICAL MEASUREMENTS

Distribution of BBH injections

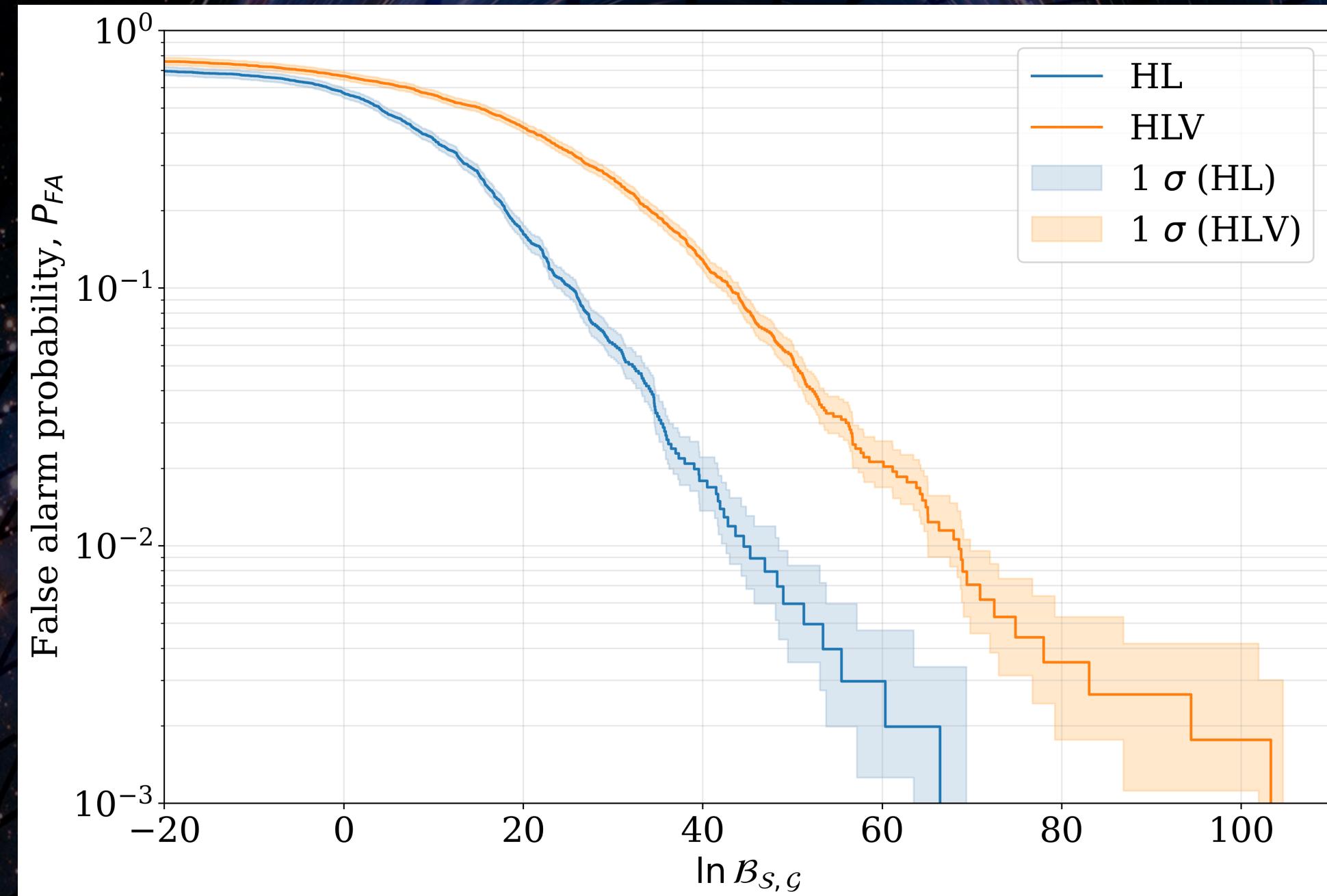


Consistent with previous work:

$$\ln \mathcal{B}_{S,G} \sim \mathcal{I}N \ln \text{SNR}_{\text{net}}$$

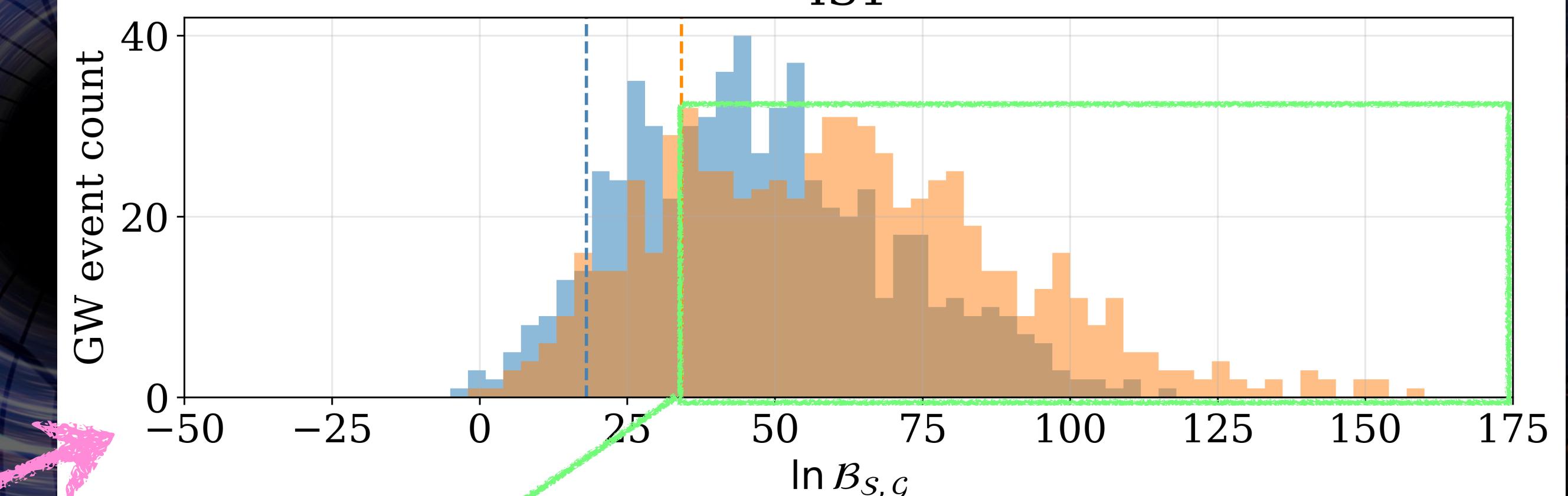
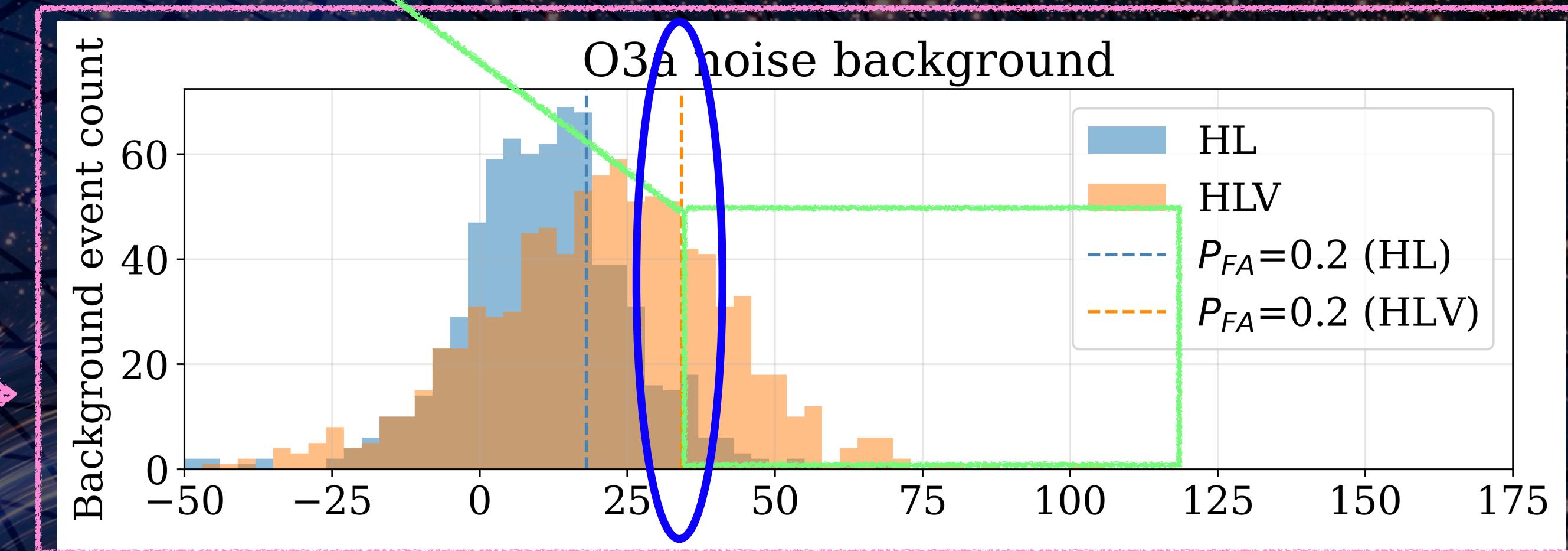
$\ln \mathcal{B}_{S,G} = -500$ events
not shown

CONSTRUCTING EFFICIENCY CURVE



$P_{FA} = 0.2$
/probability of false alarm/

Fraction of non-astrophysical triggers detected above a given $\ln \mathcal{B}_{S,G}$ threshold

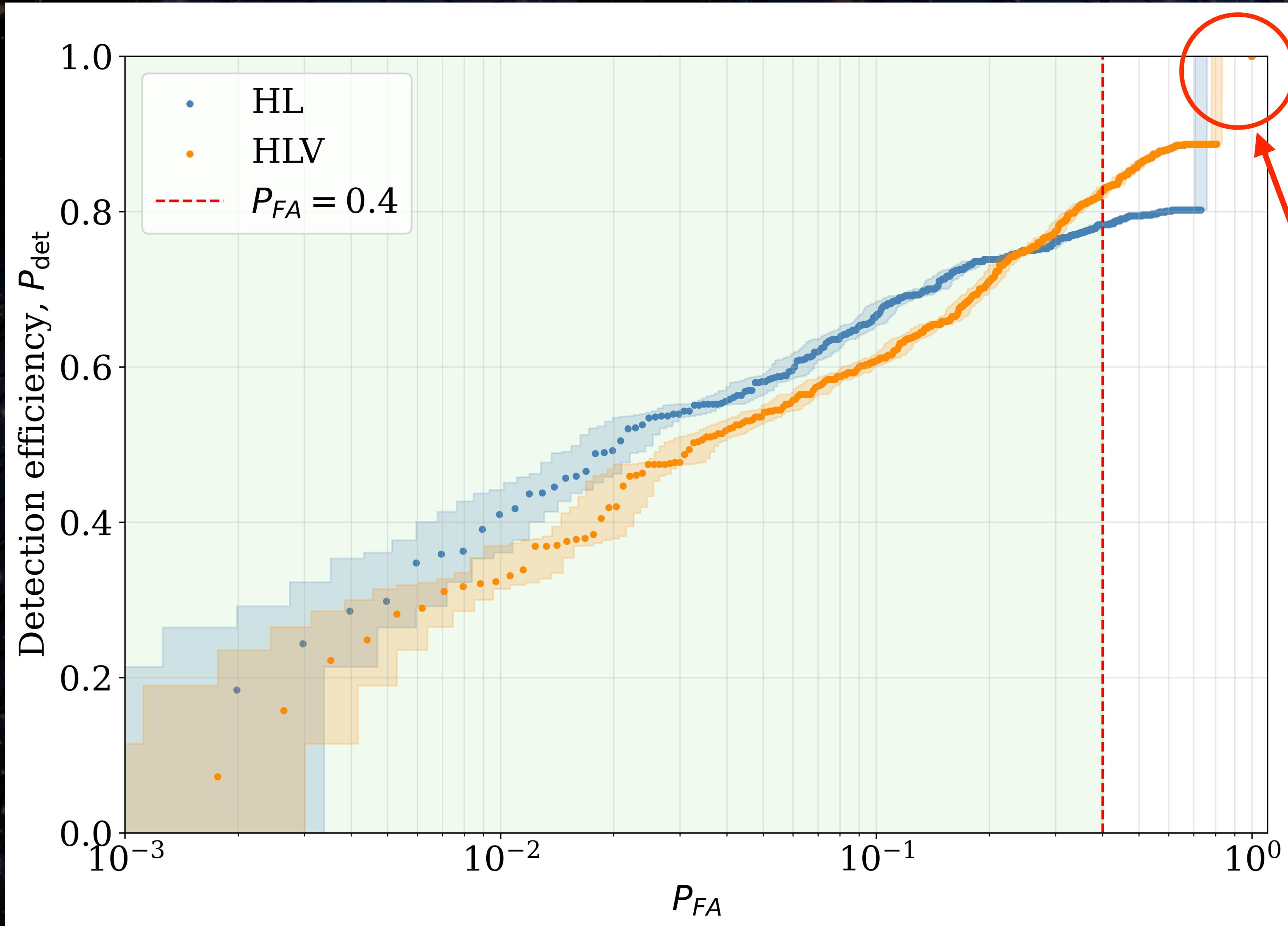


Again, $\ln \mathcal{B}_{S,G} = -500$
events not shown

P_{det}
/Detection efficiency/

Fraction of astrophysical events detected with significance i.e. $P_{FA} \geq 0.2$

EFFICIENCY CURVES OF HL AND HLV



1- σ P_{FA} POISSON UNCERTAINTY REGION

same as background measurement

Cluster of Gaussian-noise-like events with

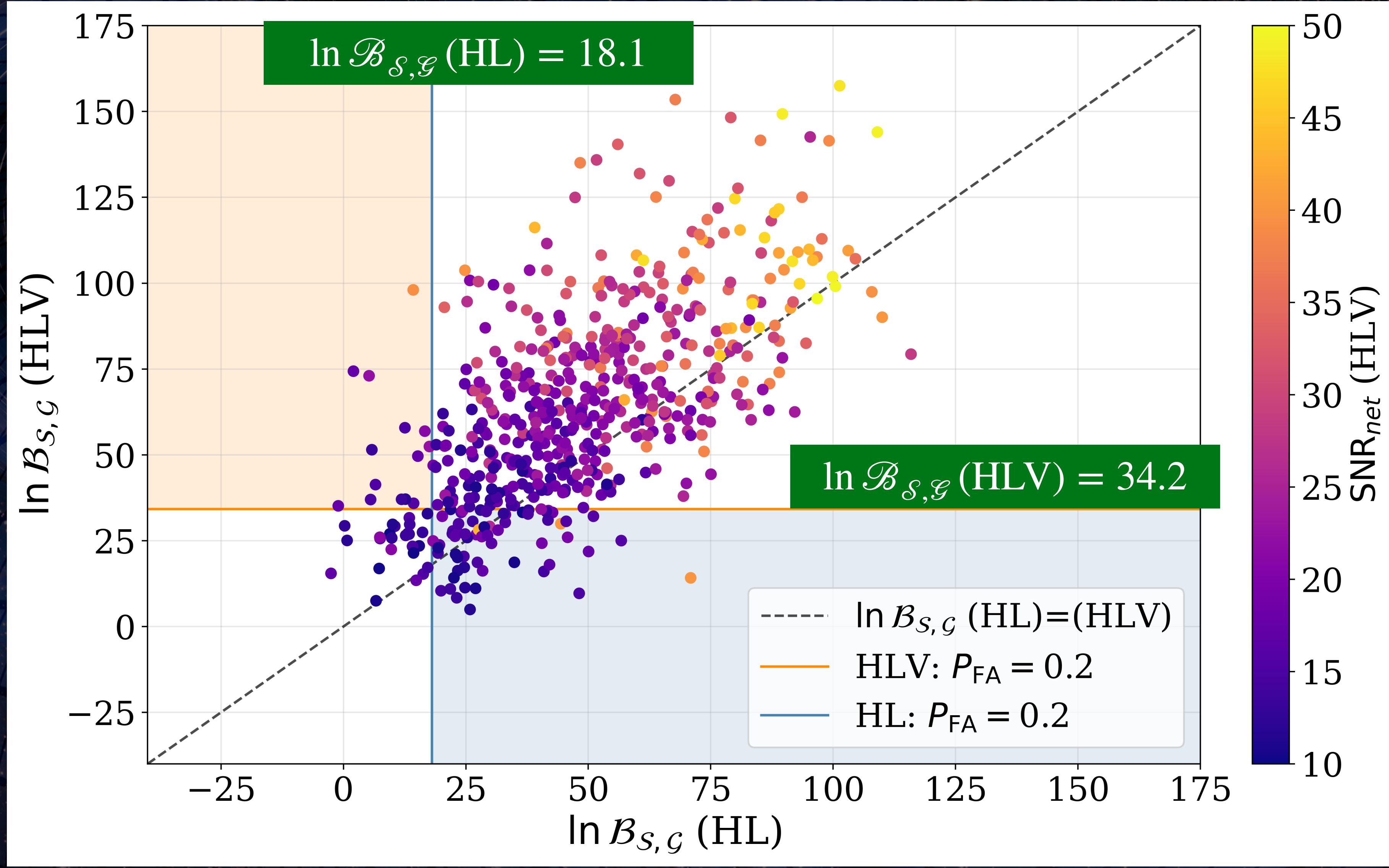
$\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} = -500$ and $P_{FA} = 1$

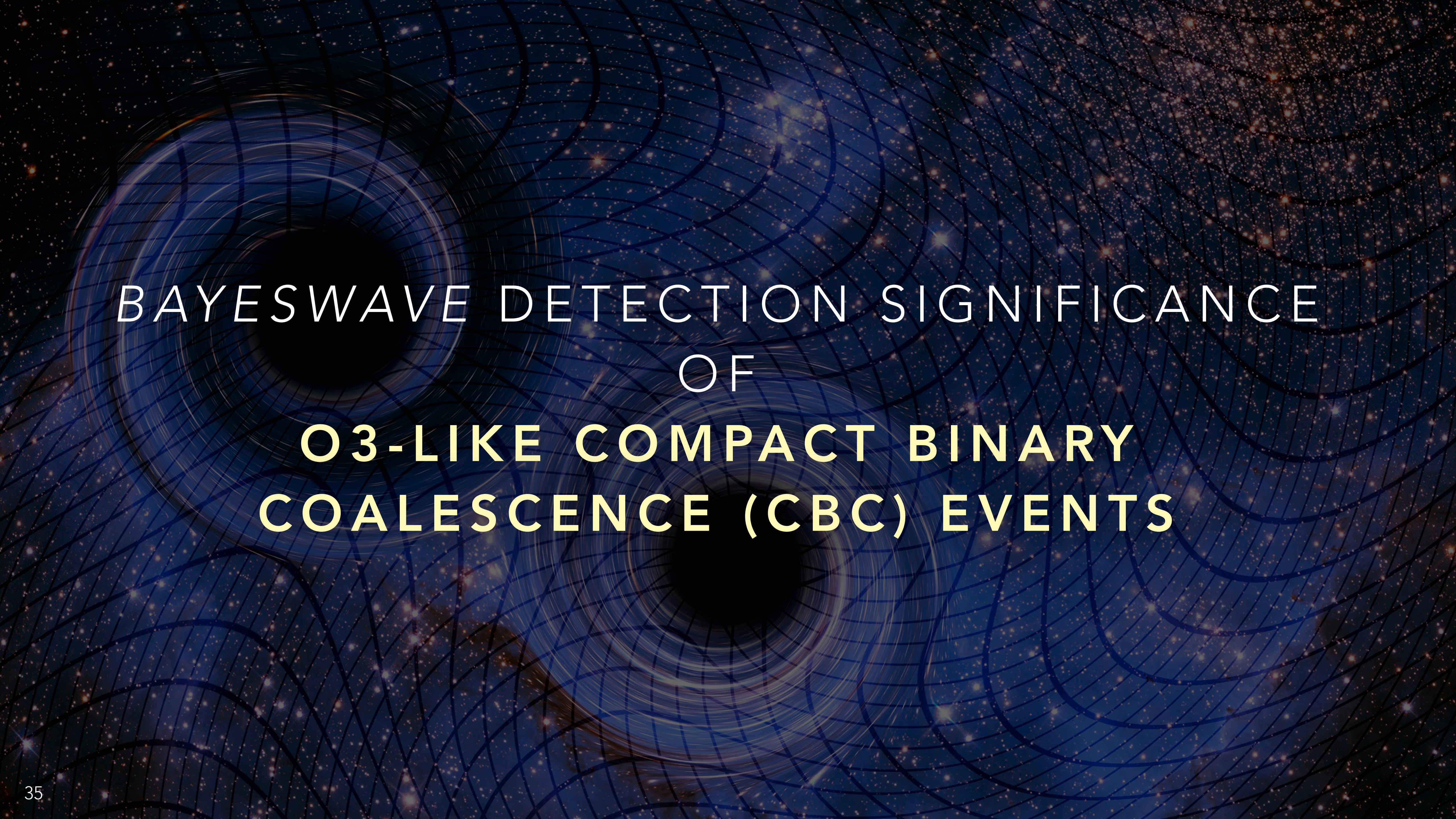
(i.e. minimal detection significance)

Practically meaningful regime $P_{FA} \leq 0.4$

P_{det} of HL very slightly higher than HLV,
but the difference is not significant

P_{FA} AND $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ COMPARISON





BAYESWAVE DETECTION SIGNIFICANCE OF O3-LIKE COMPACT BINARY COALESCENCE (CBC) EVENTS

O3-LIKE CBC INJECTIONS

To measure *BayesWave's* detection significance of
O3 GW candidates

Using the O3a **HL** and **HLV** backgrounds measured in this study

O3-LIKE CBC INJECTIONS

- Off-source waveforms
 - Waveform parameters sampled from match-filter posteriors of O3a/O3b candidate GW events
 - Injected in the proximity of the actual event
 - 17 candidates from O3a, 5 candidates from O3b
 - ** O3b waveforms are injected into random segments of O3a data
 - 50 off-source waveforms per GW candidate
 - i.e. $(17+5) \times 50 = 1100$ injections

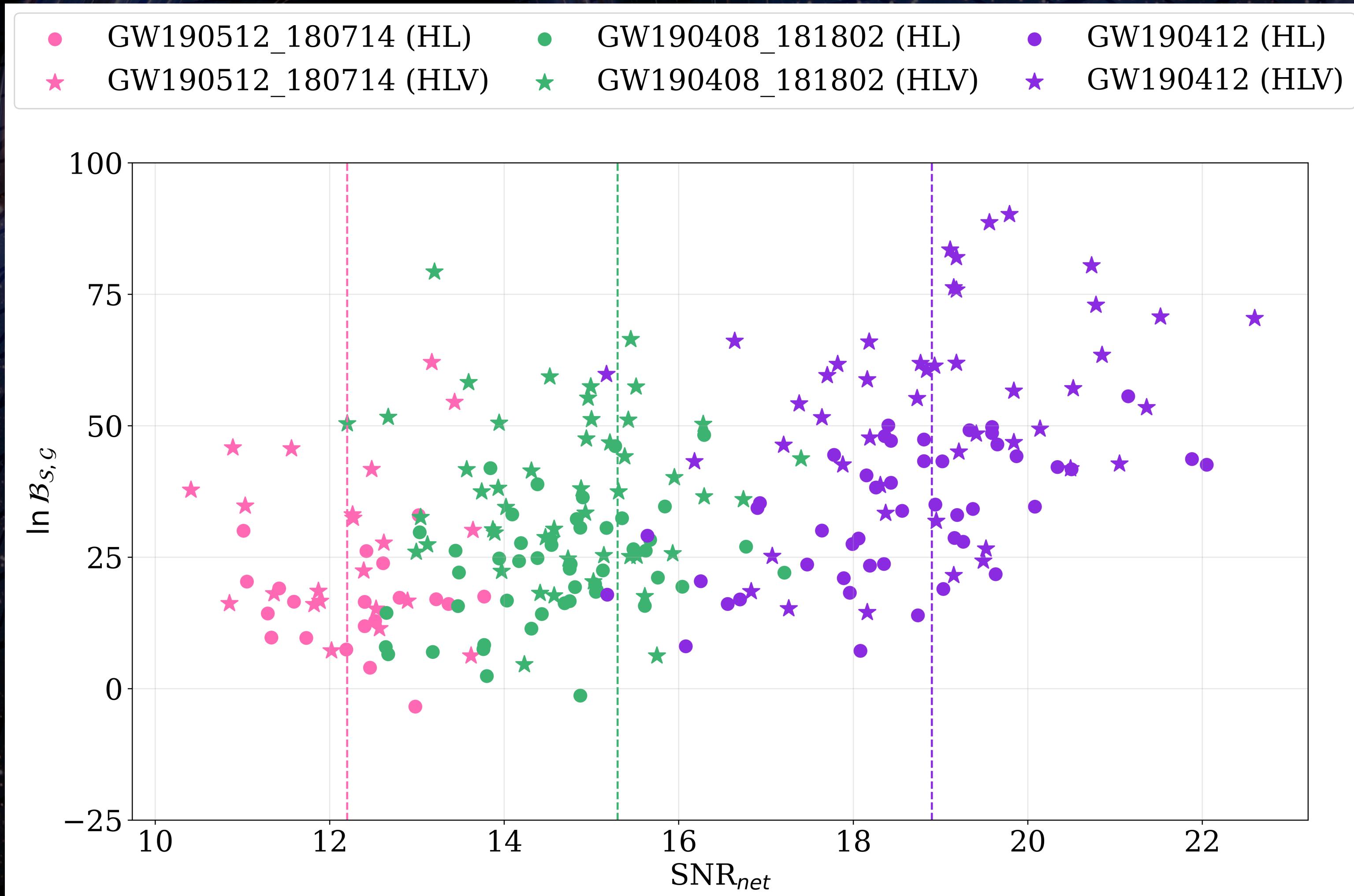
O3-LIKE CBC INJECTIONS

Filtering injections

- **Non-detections:**
 - Only follow-up injections with $\text{SNR}_{\text{net}} \geq 10$
c.f. Only followed-up cWB (background) events with $\rho \geq 7$
 - 4 (low match-filter SNR) GW candidates removed :: ≤ 25 (less than half of)
off-source waveforms satisfy BayesWave's detection criteria
- **Gaussian-noise-like injections**
 - Assign arbitrarily low detection statistics: $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}} = -500$

O3-LIKE CBC INJECTIONS

Visualising distributions of off-source injections



Median match-filter SNR

GW190512_180714 → 12.2

GW190408_181802 → 15.3

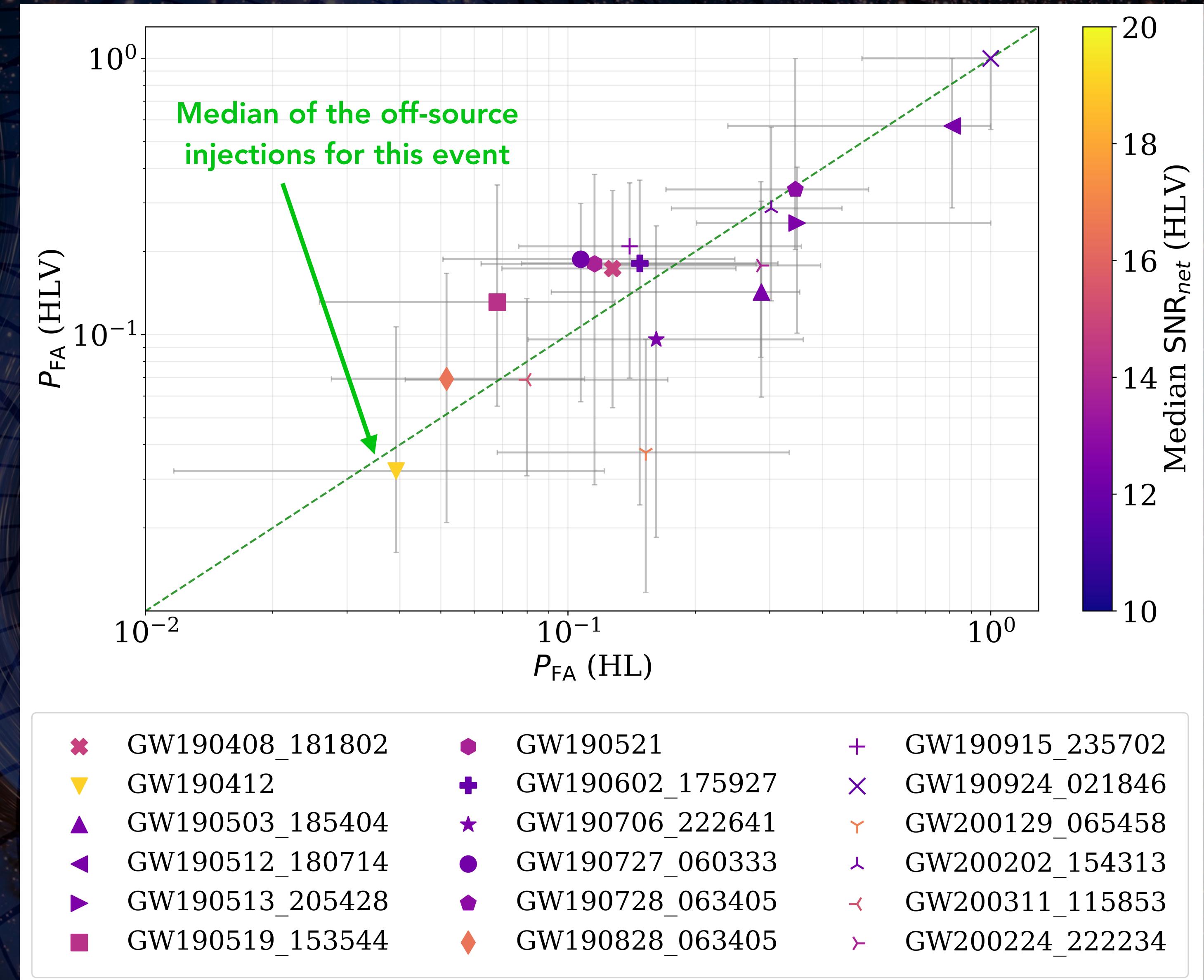
GW190412 → 18.9

BAYESWAVE DETECTION SIGNIFICANCE

REMAINING 18
O3-LIKE
CBC INJECTIONS

Error bars
IQR of P_{FA} within each GW candidate

All events are detected with comparable significance between HL and HLV



SUMMARY OF RESULTS

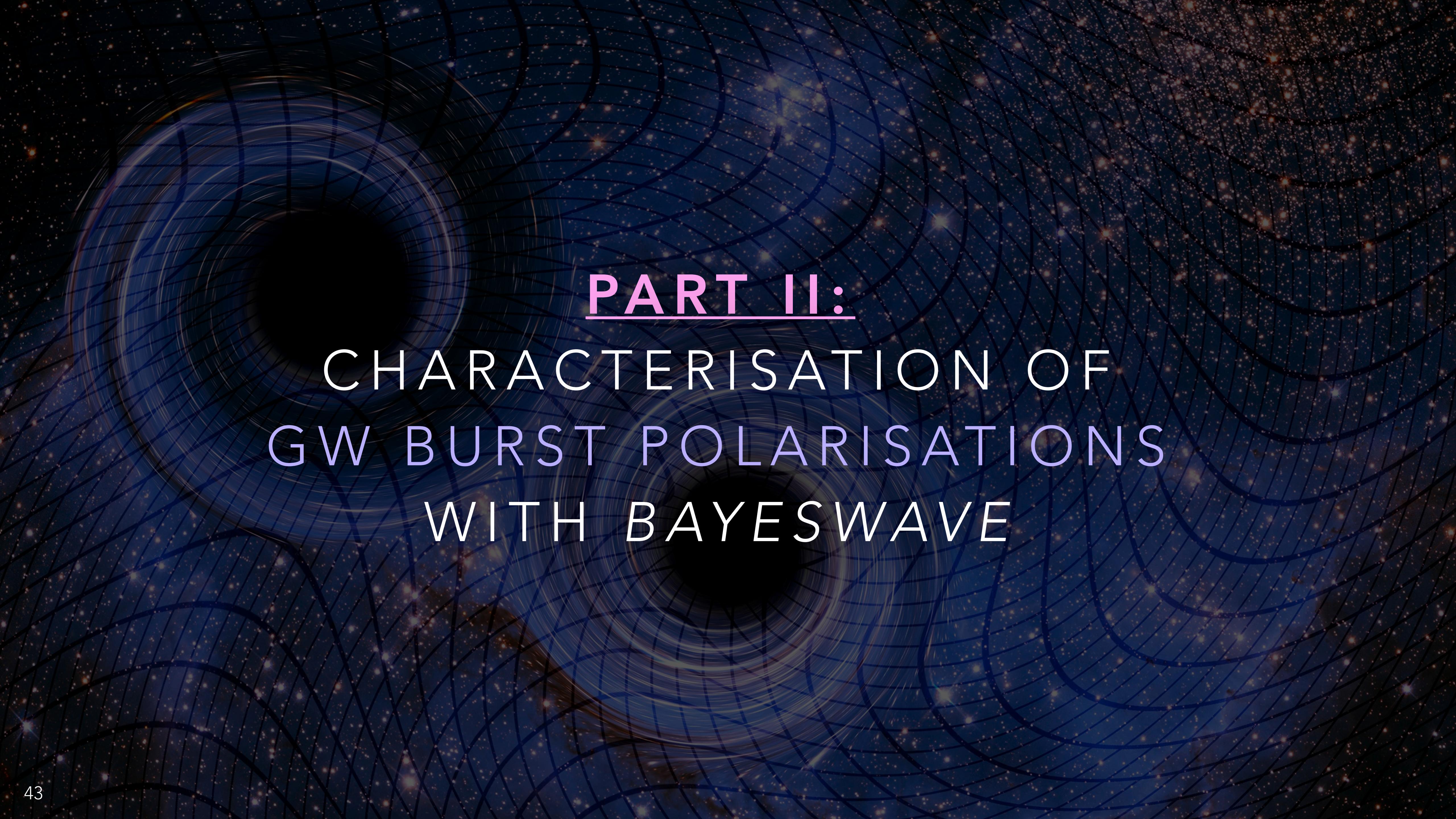
- Both the phenomenological BBH injections and O3-like events show comparable **BayesWave** performance with HL and HLV at O3 sensitivities
 - Although $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ increases with more detectors, false alarm probability P_{FA} is also higher (i.e. noisier detector backgrounds)
∴ Larger detector networks need to attain higher $\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$ to achieve the same significance (P_{FA}) as smaller networks
- Findings consistent with:
 - LVK O3 all-sky burst search (Phys. Rev. D **104**, 122004)
 - cWB search, Szczepański et al. 2022 (Phys. Rev. D **107**, 062002)

KEY TAKEAWAY

BayesWave's detection efficiency is comparable for two- and three-detector networks in O3

because

more frequent glitches in expanded detector networks offsets the advantage of higher detection statistics ($\ln \mathcal{B}_{\mathcal{S},\mathcal{G}}$)

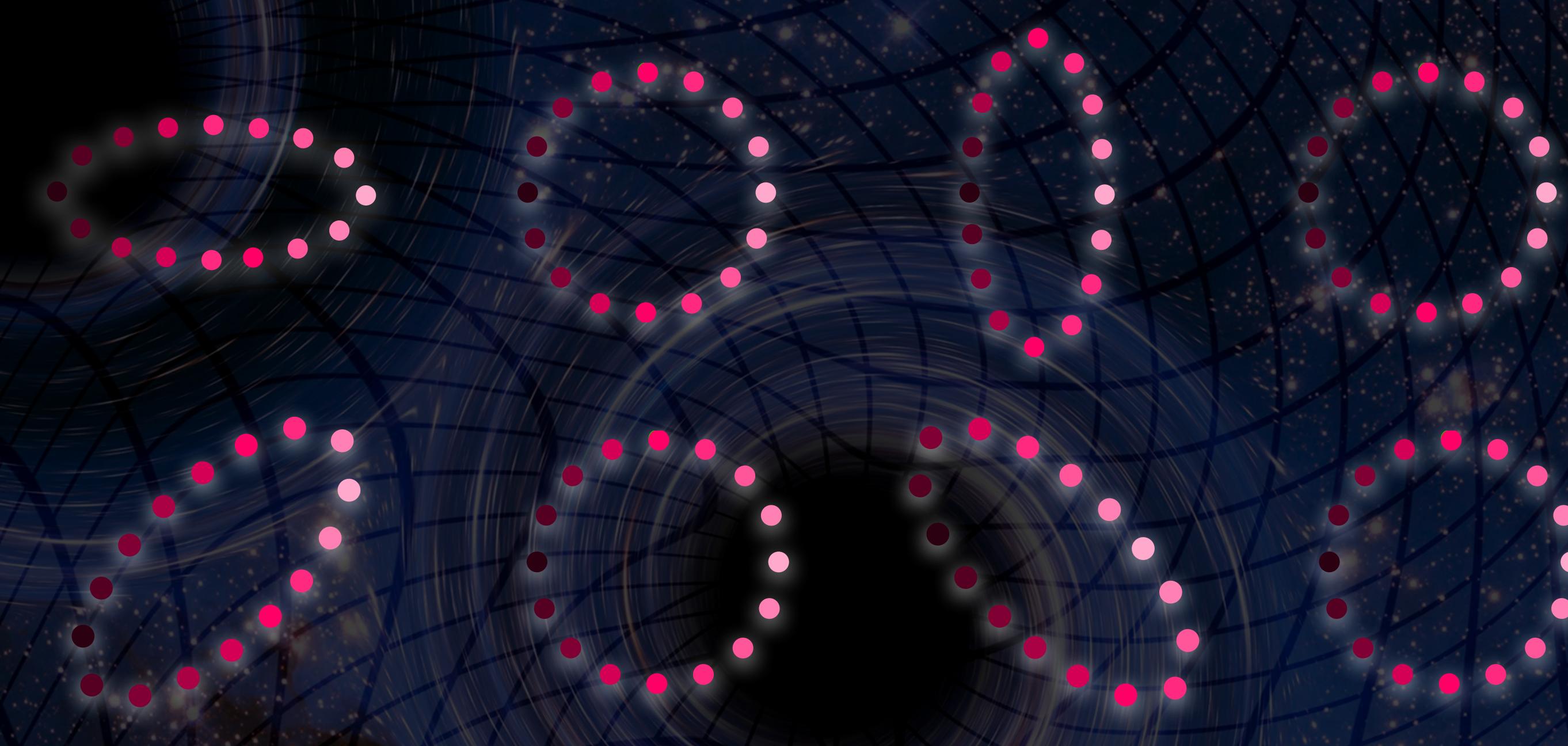


PART II:
CHARACTERISATION OF
GW BURST POLARISATIONS
WITH BAYESWAVE

GW POLARISATIONS

- According to General Relativity, GWs have two polarisations

- Plus (+)



- Cross (X)

Deformation of a ring of free-falling particles
by each polarisation modes

DISENTANGLING GW POLARISATIONS

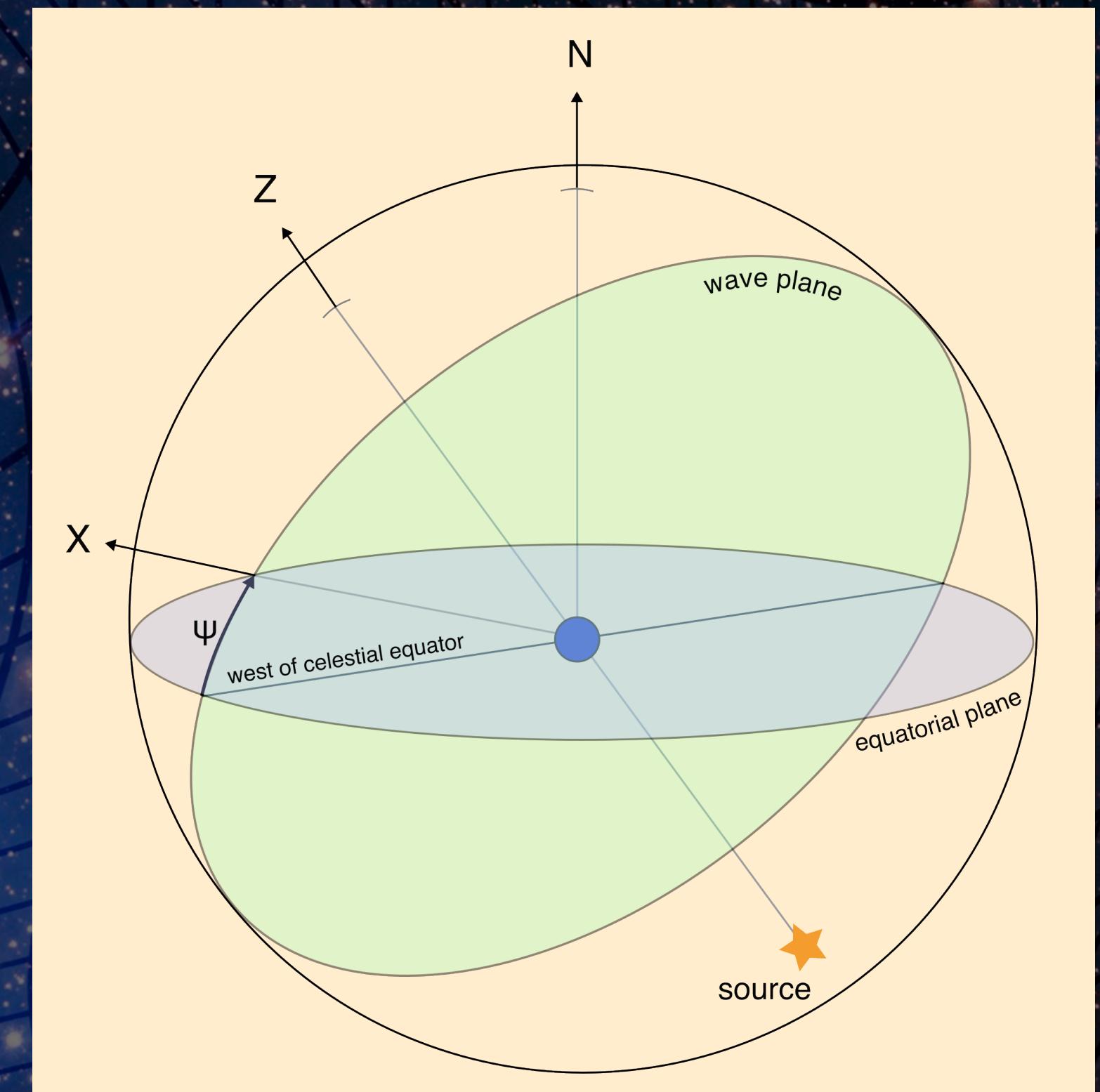
- Antenna pattern functions : $F_x(\Omega, \psi)$ and $F_+(\Omega, \psi)$
 - Sensitivity of a detector to each polarisation state
 - Ω = the sky location of the source
 - ψ = the polarization angle
- Interferometric response of detector I (in the frequency domain)
 - $\tilde{h}_I = [F_{x,I}(\Omega, \psi)\tilde{h}_x + F_{+,I}(\Omega, \psi)\tilde{h}_+] e^{2\pi i f \Delta t_I(\Omega)}$
 - \tilde{h}_+ and \tilde{h}_x = amplitudes at a nominal reference location
 - Δt_I = light travel time from the reference location to detector I

THE POLARISATION ANGLE ψ

- Arbitrarily defined w.r.t to a reference direction: west of celestial equator
- Z is the direction of propagation of the GW
- X is the x-axis of the wave plane
 - $\psi = 0$ if X is parallel to the reference direction
- X and Y are the directional vectors used to define the polarisation components

$$h_+ = \frac{1}{2} \left(\hat{x}_i \hat{x}_j - \hat{y}_i \hat{y}_j \right) h^{ij}$$

$$h_X = \frac{1}{2} \left(\hat{x}_i \hat{y}_j + \hat{y}_i \hat{x}_j \right) h^{ij}$$



DISENTANGLING GW POLARISATIONS

$$\tilde{h}_I = \left[F_x(\Omega, \psi) \tilde{h}_x + F_+(\Omega, \psi) \tilde{h}_+ \right] e^{2\pi i f \Delta t(\Omega)}$$

- Contains up to four unknowns:
 - The two polarisation modes
 - Sky location
 - Source orientation ψ
- Need responses from **multiple detectors** to extract the polarisation components

BAYESWAVE SIGNAL MODEL UPDATE

- Elliptical polarisation, \mathbf{E}

$$\tilde{h}_+ = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^n, \phi^n)$$

$$\tilde{h}_\times = i\epsilon \tilde{h}_+$$

- Relaxed polarisation, \mathbf{R}

$$\tilde{h}_+ = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^{n,+}, \phi^{n,+})$$

$$\tilde{h}_\times = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^{n,\times}, \phi^{n,\times})$$

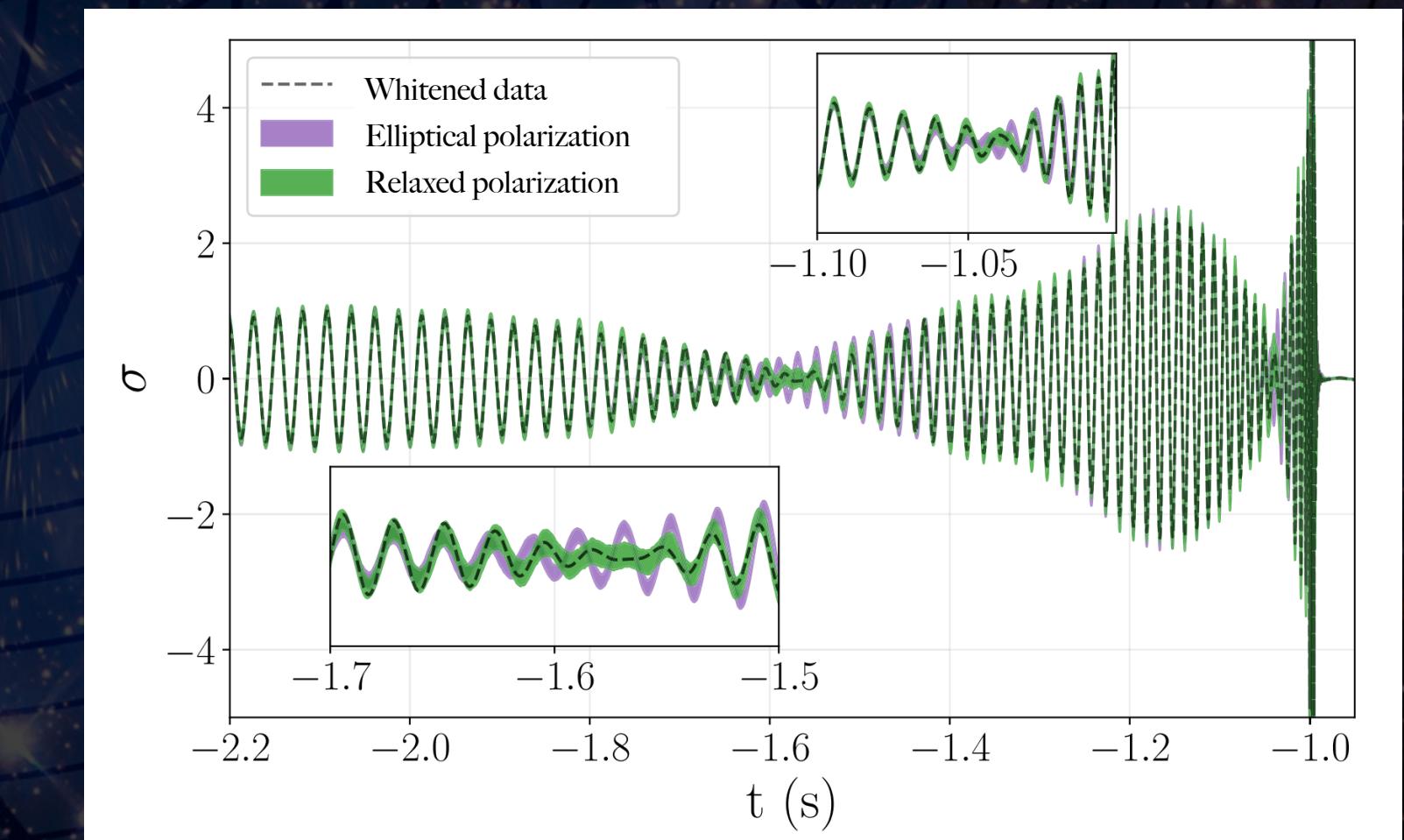
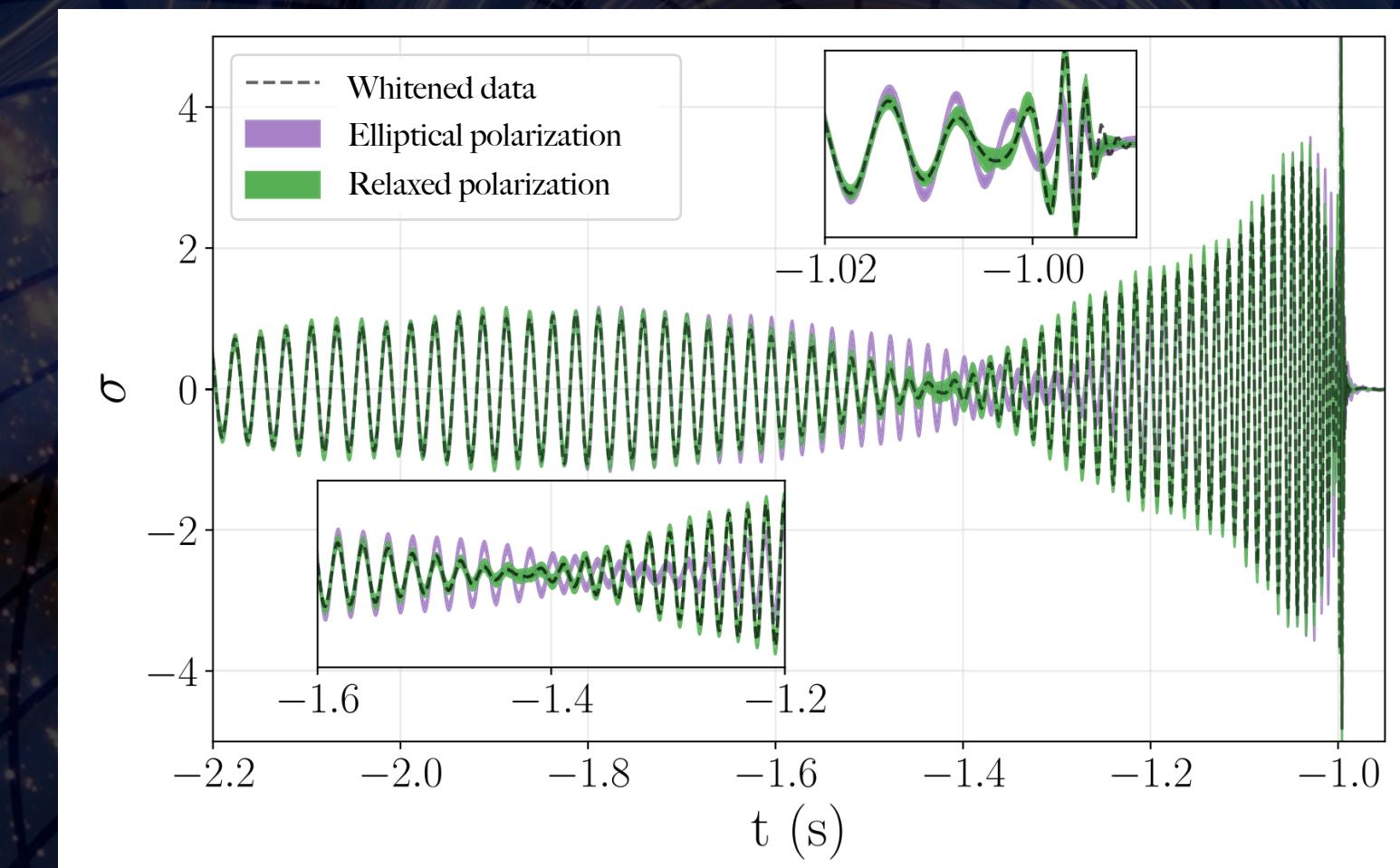
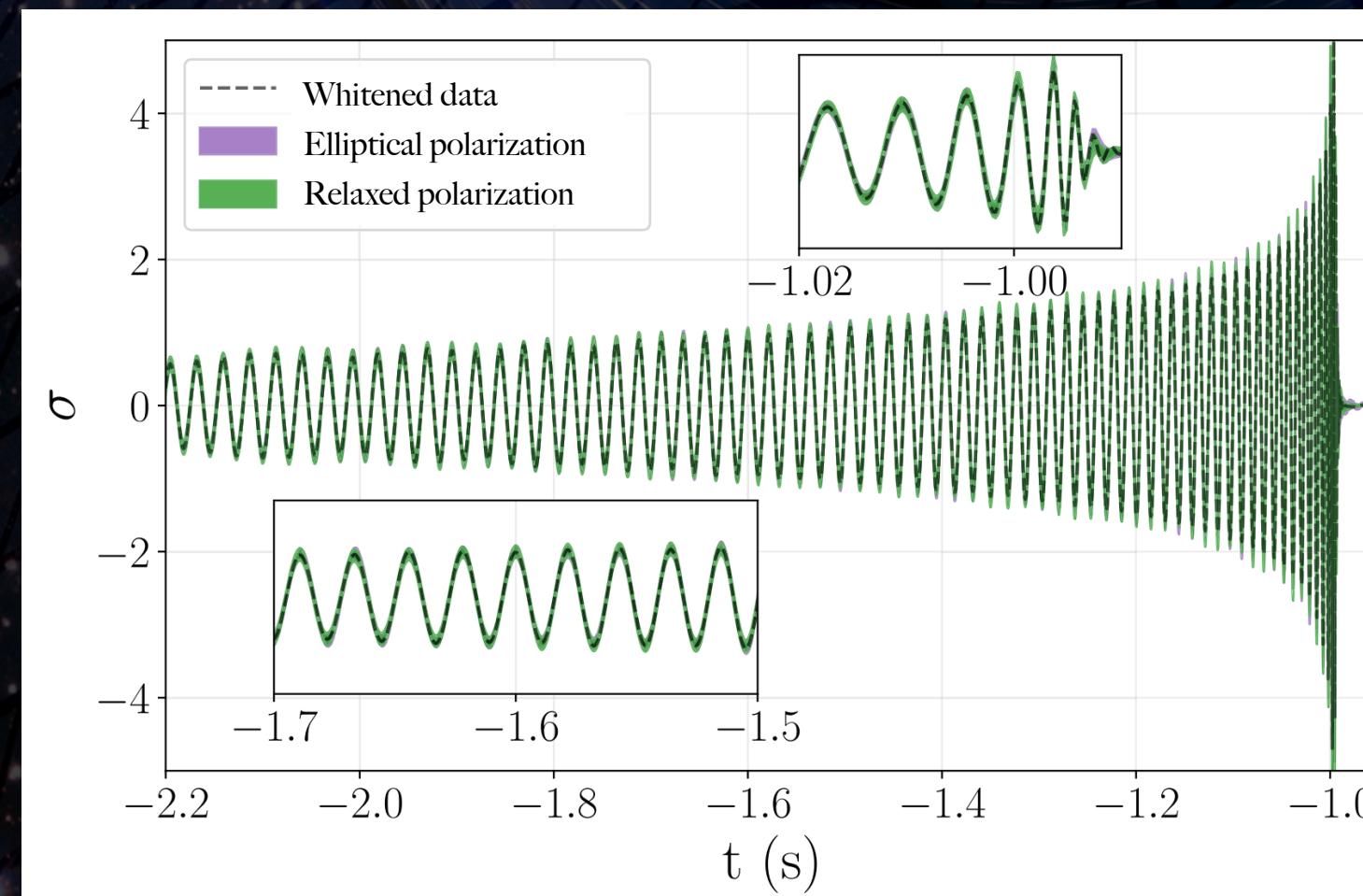
To avoid
degeneracies with
the glitch model

Λ : wavelet
 ϵ : ellipticity

N : number of wavelets
in signal model

WHY THE RELAXED POLARIZATION (R) MODEL?

- E does not hold for CBCs with time-varying polarisations, e.g.
 - Distinctive higher-order modes
 - Spin-precessing
- Other transient signals like supernovae are also generally unpolarised



ELLIPTICAL (E) VS. RELAXED (R)

How well do the E and R polarization models represent GW signals from non-precessing and precessing binaries

TWO INJECTION SETS

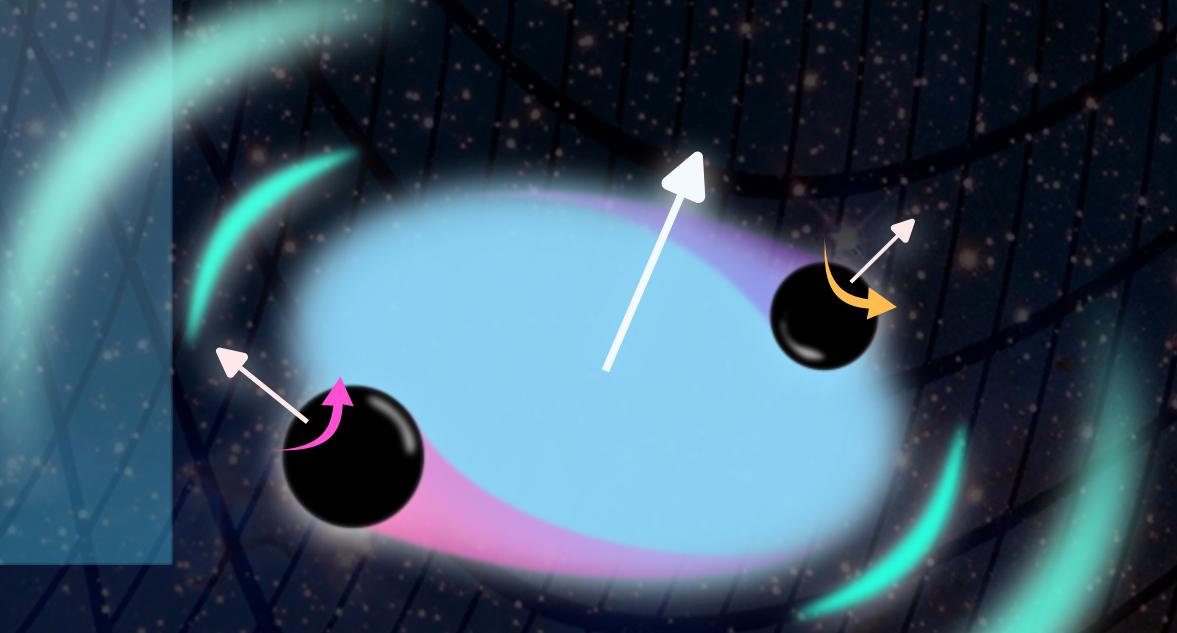
- IMRPhenomPv3 - Phenomenological (precessing) BBH waveforms
- 200 injections
- High mass ratio $40M_{\odot} - 8M_{\odot}$
- Sampled distances such that the HLV SNR_{net} ~ 50 (loud and ideal!)
- Uniform sky location and polarisation angle
- Injected into simulated LIGO and Virgo noise

Non-precessing

- Fixed inclination at 45°
- Zero spin i.e. $|\vec{\chi}_i| = 0$;
 $\vec{\chi}_i = \vec{s}_i/m_i^2$ is the dimensionless spin parameter

Precessing

- Fixed *initial* inclination at 45°
- *Initial* spin for each component mass is independently sampled within $0.1 \leq |\vec{\chi}_i| \leq 1.0$



DIMENSIONLESS PRECESSION SPIN PARAMETER

$$\chi_p := \frac{\max(A_1 S_{1\perp}, A_2 S_{2\perp})}{A_1 m_1^2}$$

$$0 \leq \chi_p \leq 1$$

Non-zero when in-plane spin is present

i.e. spin components that are not (anti)parallel to the orbital angular momentum

COMPARING ELLIPTICAL (E) AND RELAXED (R)

Bayes Factor

$$\ln \mathcal{B}_{\mathbf{R},\mathbf{E}} = \ln p(\vec{s} \mid \mathbf{R}) - \ln p(\vec{s} \mid \mathbf{E})$$

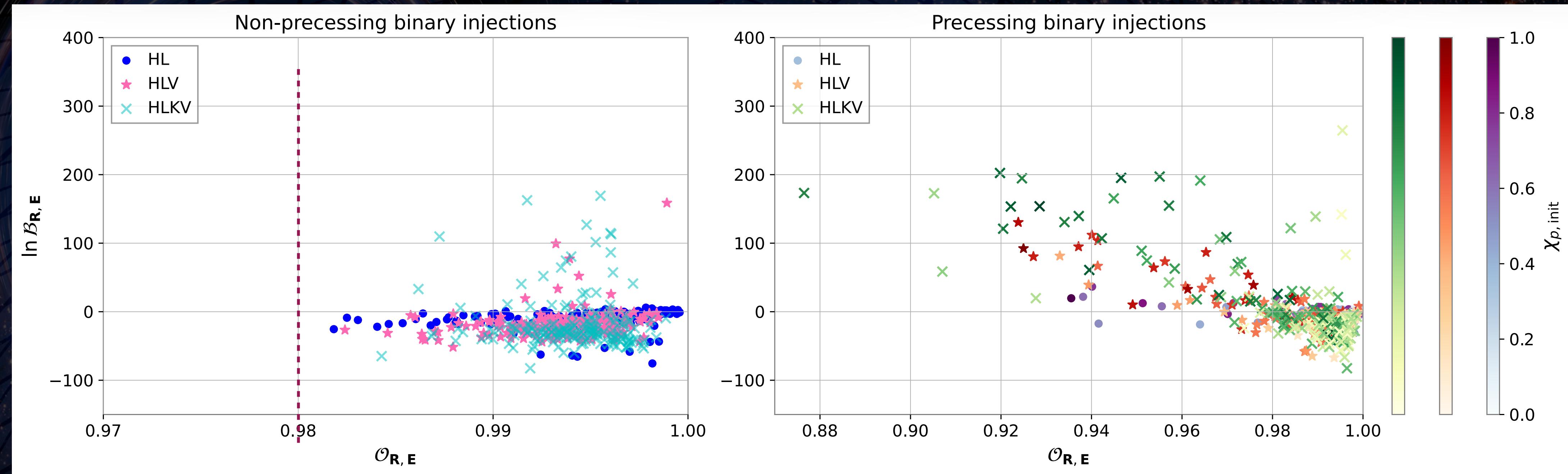
Network overlap (i.e. match)

$$\mathcal{O}_{\mathbf{R},\mathbf{E}} = \frac{\sum_i (h_{\mathbf{R}}^i \mid h_{\mathbf{E}}^i)}{\sqrt{\sum_i (h_{\mathbf{R}}^i \mid h_{\mathbf{R}}^i) \sum_i (h_{\mathbf{E}}^i \mid h_{\mathbf{E}}^i)}}$$

where h^i is the BayesWave-recovered waveform for the i -th detector

(PRELIMINARY RESULTS)

HOW WELL DO THE \mathbf{E} AND \mathbf{R} POLARIZATION MODELS REPRESENT GW SIGNALS FROM NON-PRECESSING AND PRECESSING BINARIES



Is it Gaussian noise?

$\ln \mathcal{B}_{\mathbf{R}, \mathcal{N}}$ and $\ln \mathcal{B}_{\mathbf{E}, \mathcal{N}} \geq 50$

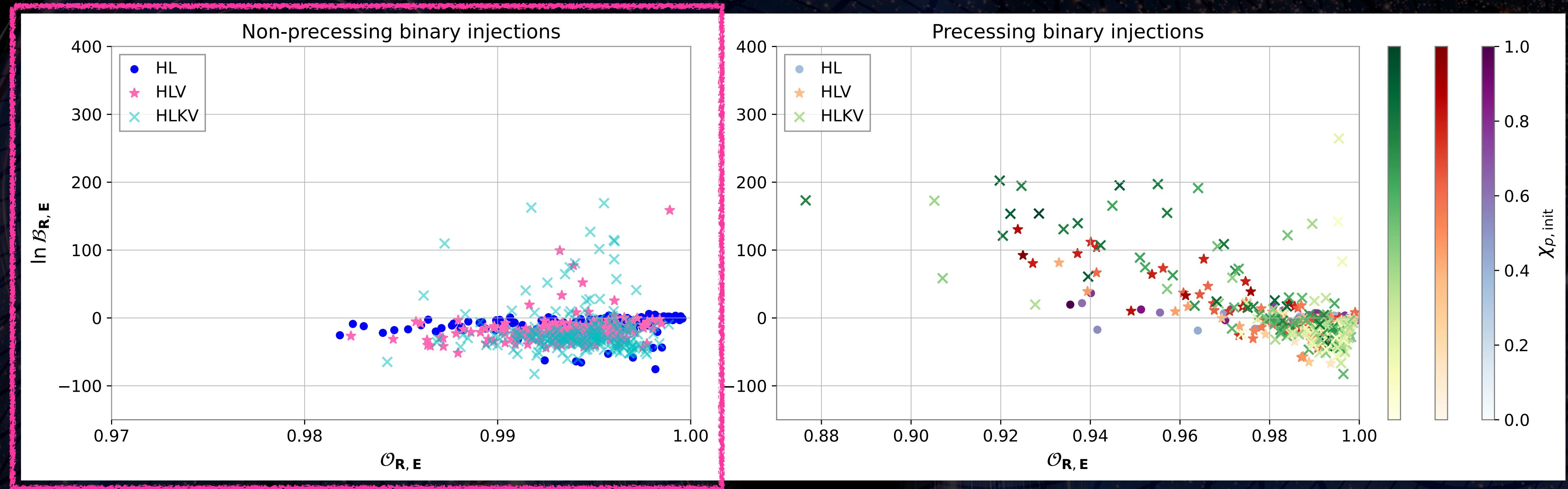


It is a glitch?

$\ln \mathcal{B}_{\mathbf{R}, \mathcal{G}}$ and $\ln \mathcal{B}_{\mathbf{E}, \mathcal{G}} \geq 20$

(PRELIMINARY RESULTS)

HOW WELL DO THE \mathbf{E} AND \mathbf{R} POLARIZATION MODELS REPRESENT GW SIGNALS FROM NON-PRECESSING AND PRECESSING BINARIES



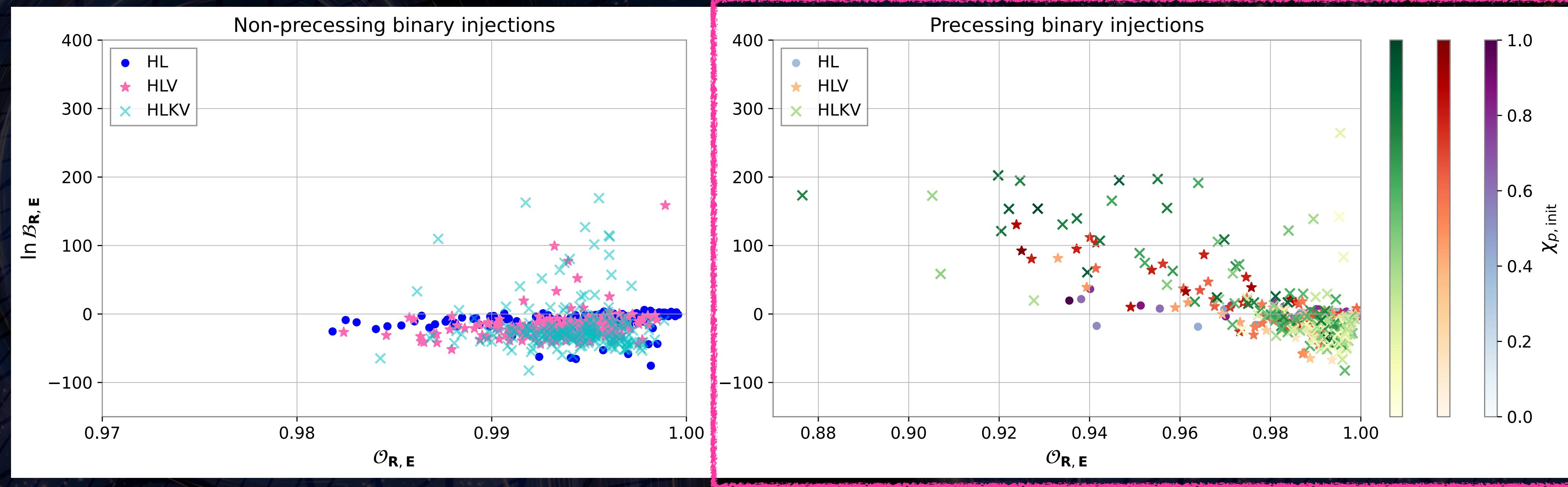
Evidence of model $\mathcal{M} \simeq \text{Likelihood} \times \frac{\Delta V_{\mathcal{M}}}{V_{\mathcal{M}}}$

Bayes factor, $\mathcal{B}_{\mathbf{R}, \mathbf{E}} \simeq \text{Likelihood ratio} \times \frac{\Delta V_{\mathbf{R}}}{\Delta V_{\mathbf{E}}} \frac{V_{\mathbf{E}}}{V_{\mathbf{R}}}$

$\Delta V_{\mathcal{M}}$: Posterior volume
 $V_{\mathcal{M}}$: Total parameter space volume of model \mathcal{M}

(PRELIMINARY RESULTS)

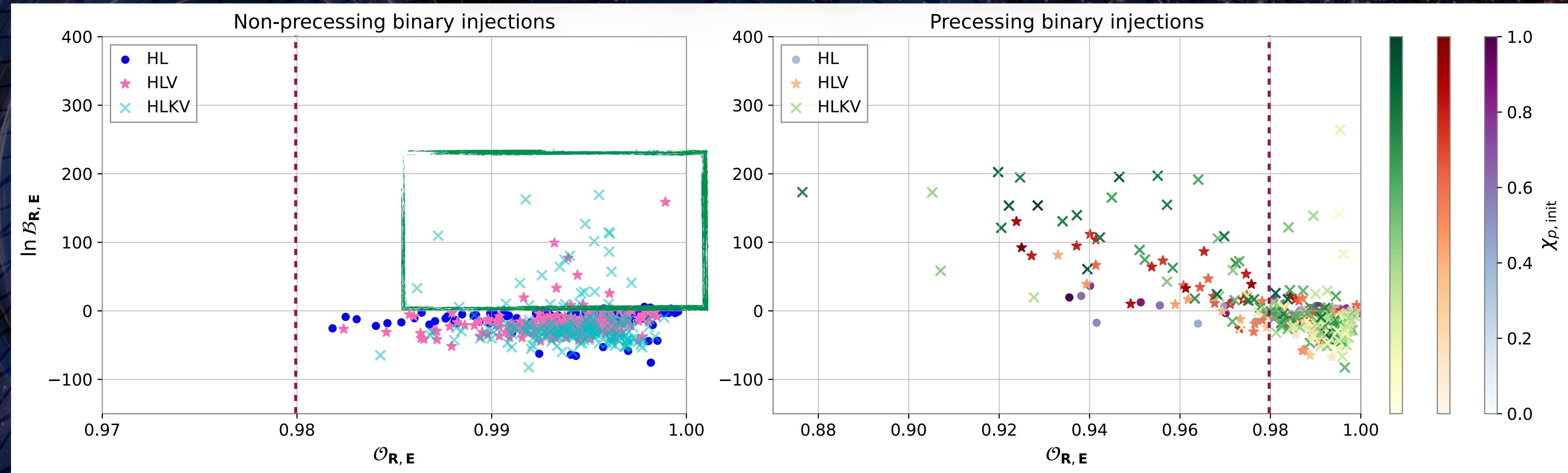
HOW WELL DO THE $\textcolor{violet}{E}$ AND $\textcolor{green}{R}$ POLARIZATION MODELS REPRESENT GW SIGNALS FROM NON-PRECESSING AND PRECESSING BINARIES



- (1) Generally lower $\mathcal{O}_{\mathbf{R},\mathbf{E}}$ compared to the non-precessing binary injections, especially for events with higher $\chi_{p,\text{init}}$
- (2) $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}}$ becomes increasingly positive as $\mathcal{O}_{\mathbf{R},\mathbf{E}}$ reduces \Rightarrow more evidence for $\textcolor{green}{R}$
- (3) Increase in $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}}$ is more prominent with larger detector networks

(PRELIMINARY RESULTS)

EVENTS WITH $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}} \geq 0$ FOR NON-PRECESSING BINARIES WHAT DO THEY IMPLY?

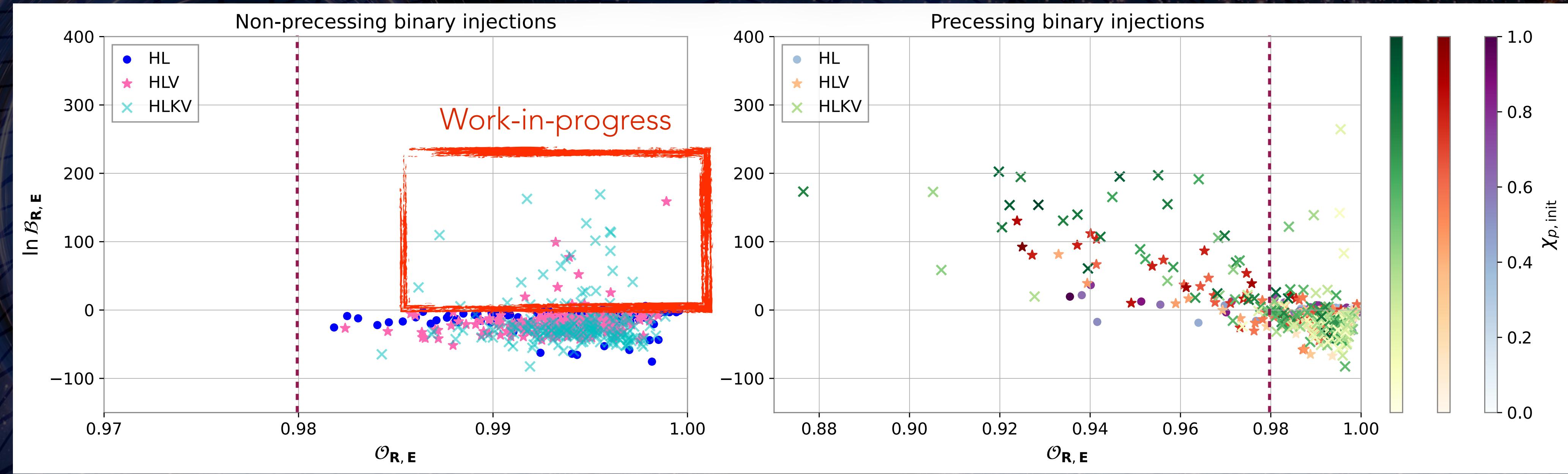


- Events with $\mathcal{O}_{\mathbf{R},\mathbf{E}} \sim 1$ and $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}} \geq 0$ are purely obtained by chance
- We get a very different $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}}$ with different (Markov) chain RNG seeds
- If $\mathcal{O}_{\mathbf{R},\mathbf{E}} \gtrsim 0.98$, $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}} \geq 0$ does not conclusively imply a preference of **R** over **E**

(PRELIMINARY RESULTS)

EVENTS WITH $\ln \mathcal{B}_{R,E} \geq 0$ FOR NON-PRECESSING BINARIES

WHAT DO THEY IMPLY?

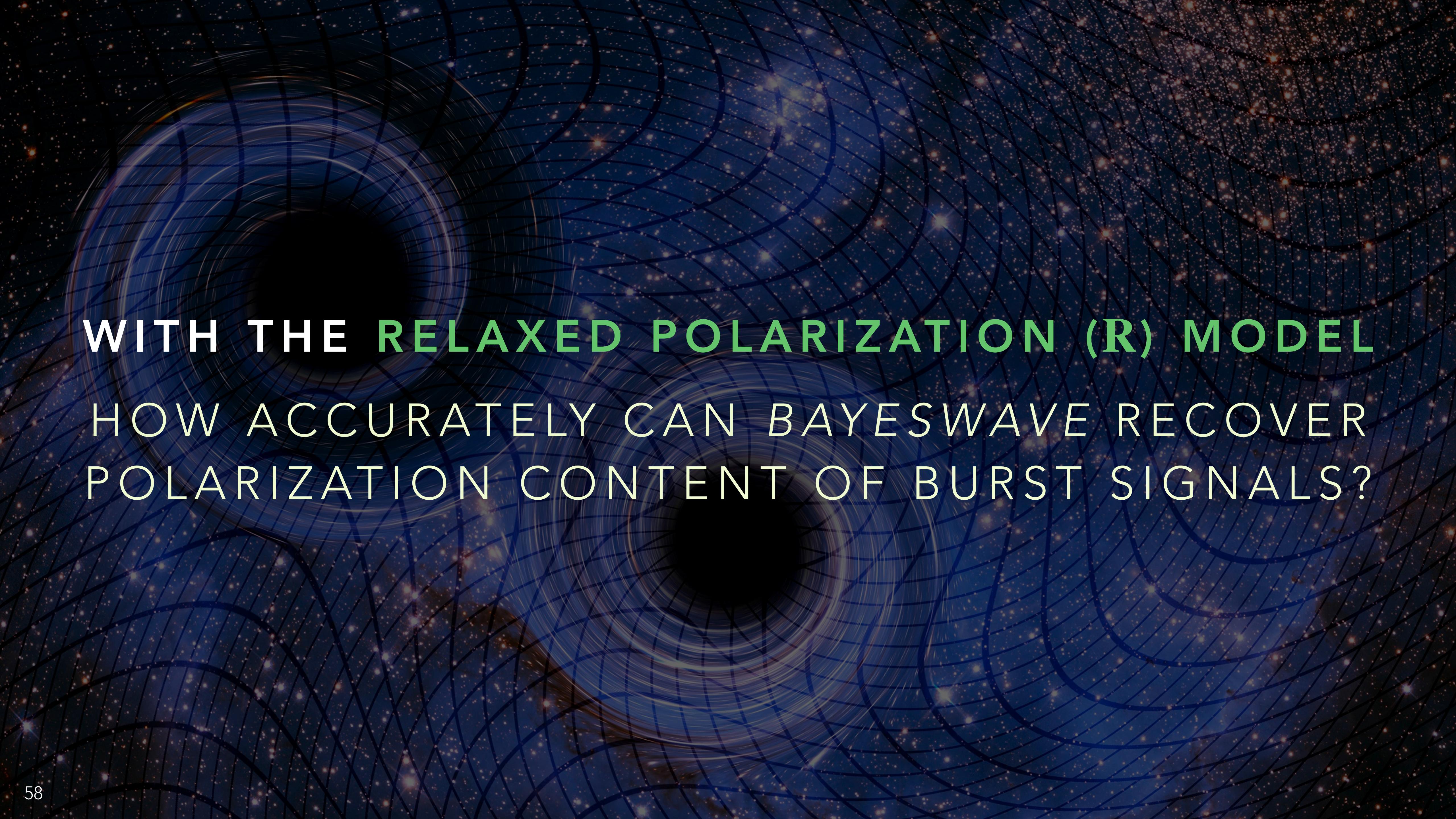


- Under investigation
- Testing stability of evidence computation for relaxed polarization model

SO....

HOW WELL DO THE **E** AND **R** POLARIZATION MODELS REPRESENT GW SIGNALS FROM NON-PRECESSING AND PRECESSING BINARIES?

- Non-precessing binaries are equally well-represented by both **E** and **R**, so if we had to choose one...
Occams Razor says to pick the simpler one (**E**)
- Precessing binaries with high in-plane spin are generally better represented by **R**



WITH THE RELAXED POLARIZATION (R) MODEL
HOW ACCURATELY CAN BAYESWAVE RECOVER
POLARIZATION CONTENT OF BURST SIGNALS?

EXTRACTING POLARISATION CONTENT WITH STOKES PARAMETERS (IN LINEAR BASIS)

$$\boxed{\begin{aligned} I &= |\tilde{h}_+|^2 + |\tilde{h}_\times|^2 \\ Q &= |\tilde{h}_+|^2 - |\tilde{h}_\times|^2 \\ U &= \tilde{h}_+ \tilde{h}_\times^* + \tilde{h}_\times \tilde{h}_+^* \\ V &= i(\tilde{h}_+ \tilde{h}_\times^* - \tilde{h}_\times \tilde{h}_+^*) \end{aligned}}$$

→ Total intensity

} → Linear polarisation

→ Circular polarisation

EXTRACTING POLARISATION CONTENT WITH STOKES PARAMETERS (IN CIRCULAR BASIS)

$$\boxed{\begin{aligned} I &= |\tilde{h}_R|^2 + |\tilde{h}_L|^2 \\ Q &= \tilde{h}_R \tilde{h}_L^* + \tilde{h}_L \tilde{h}_R^* \\ U &= i(\tilde{h}_R \tilde{h}_L^* - \tilde{h}_L \tilde{h}_R^*) \\ V &= |\tilde{h}_R|^2 - |\tilde{h}_L|^2 \end{aligned}}$$

{}

- Total intensity
- Linear polarisation
- Circular polarisation

$$\tilde{h}_R = \frac{1}{\sqrt{2}} (\tilde{h}_+ - i\tilde{h}_\times)$$

$$\tilde{h}_L = \frac{1}{\sqrt{2}} (\tilde{h}_+ + i\tilde{h}_\times)$$

FRACTIONAL POLARISATION

Linear fraction

$$L = \frac{\sqrt{Q^2 + U^2}}{I}$$

Circular fraction

$$C = \frac{V}{I}$$

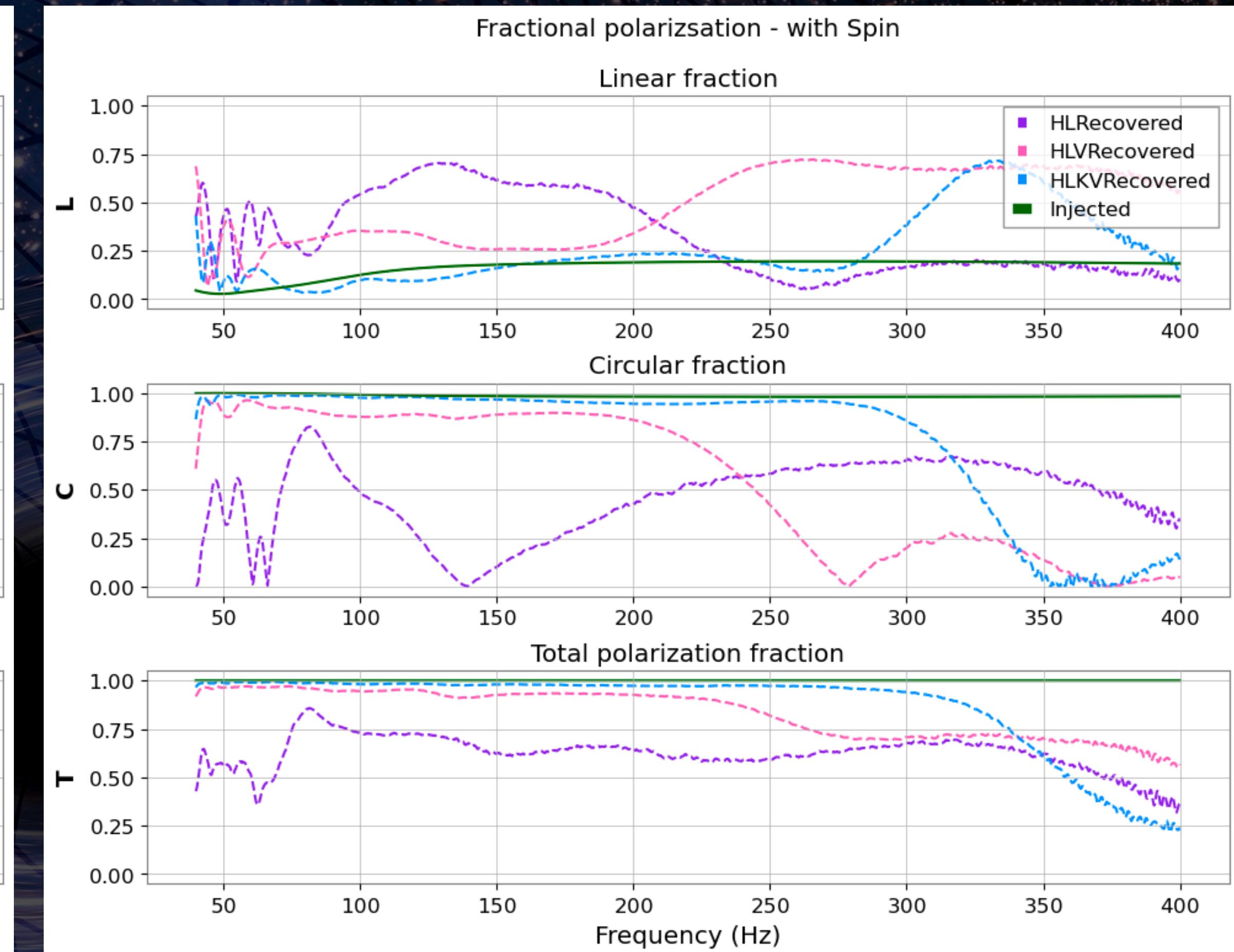
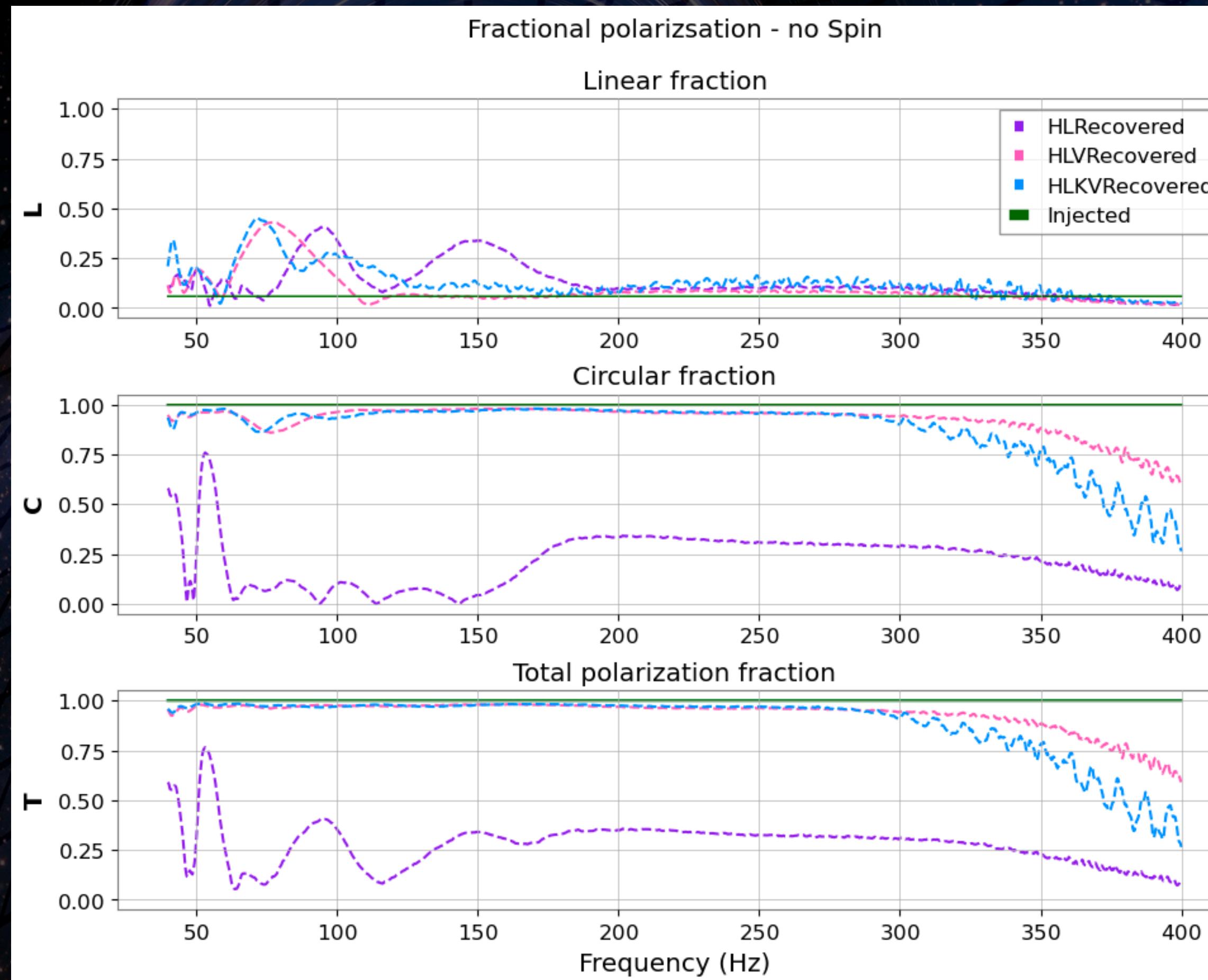
Degree of polarization

$$T = \frac{\sqrt{Q^2 + U^2 + V^2}}{I}$$

GWs are polychromatic!

All L, C, T are functions of frequency
and $T \leq 1$

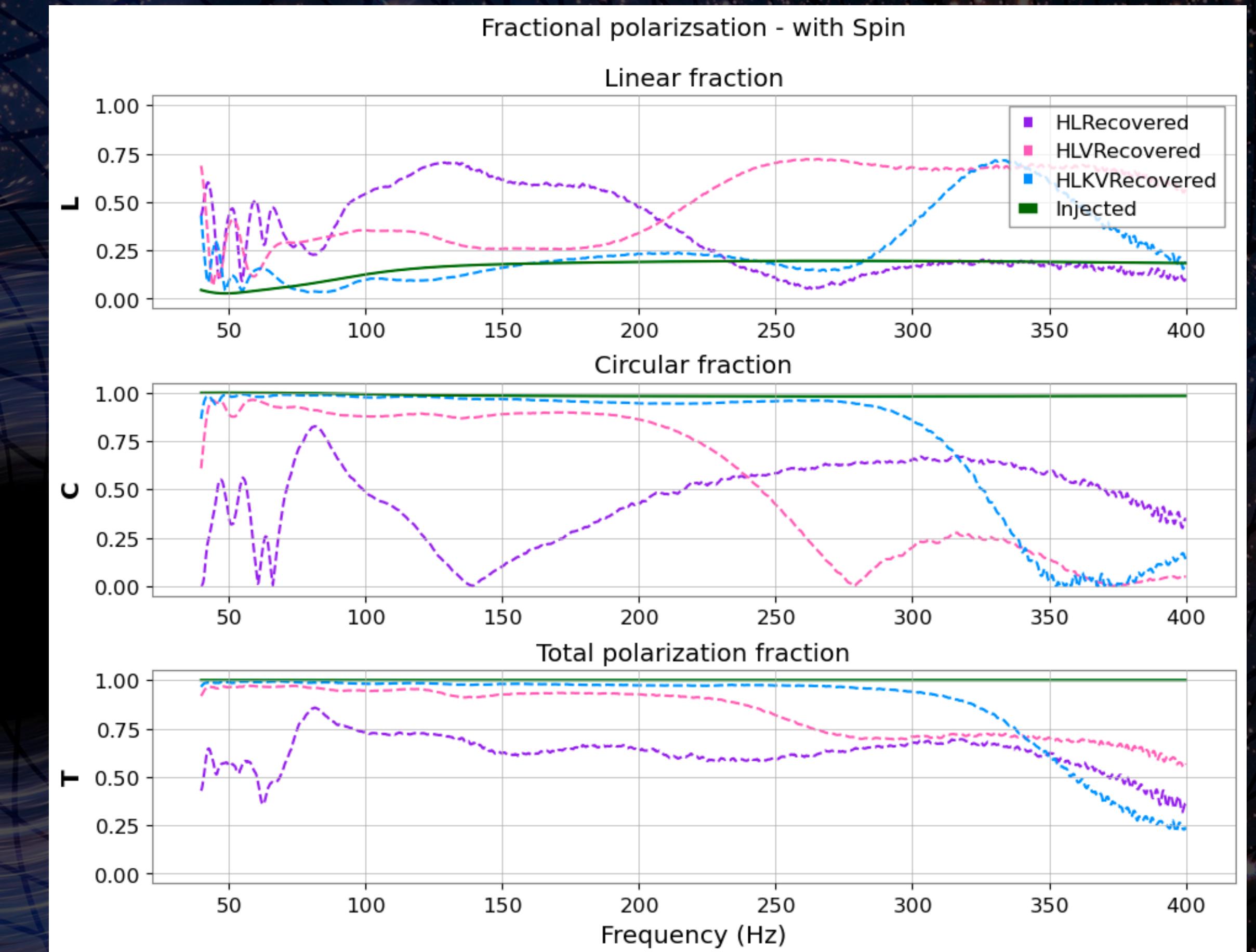
RECOVERING FRACTIONAL POLARISATION



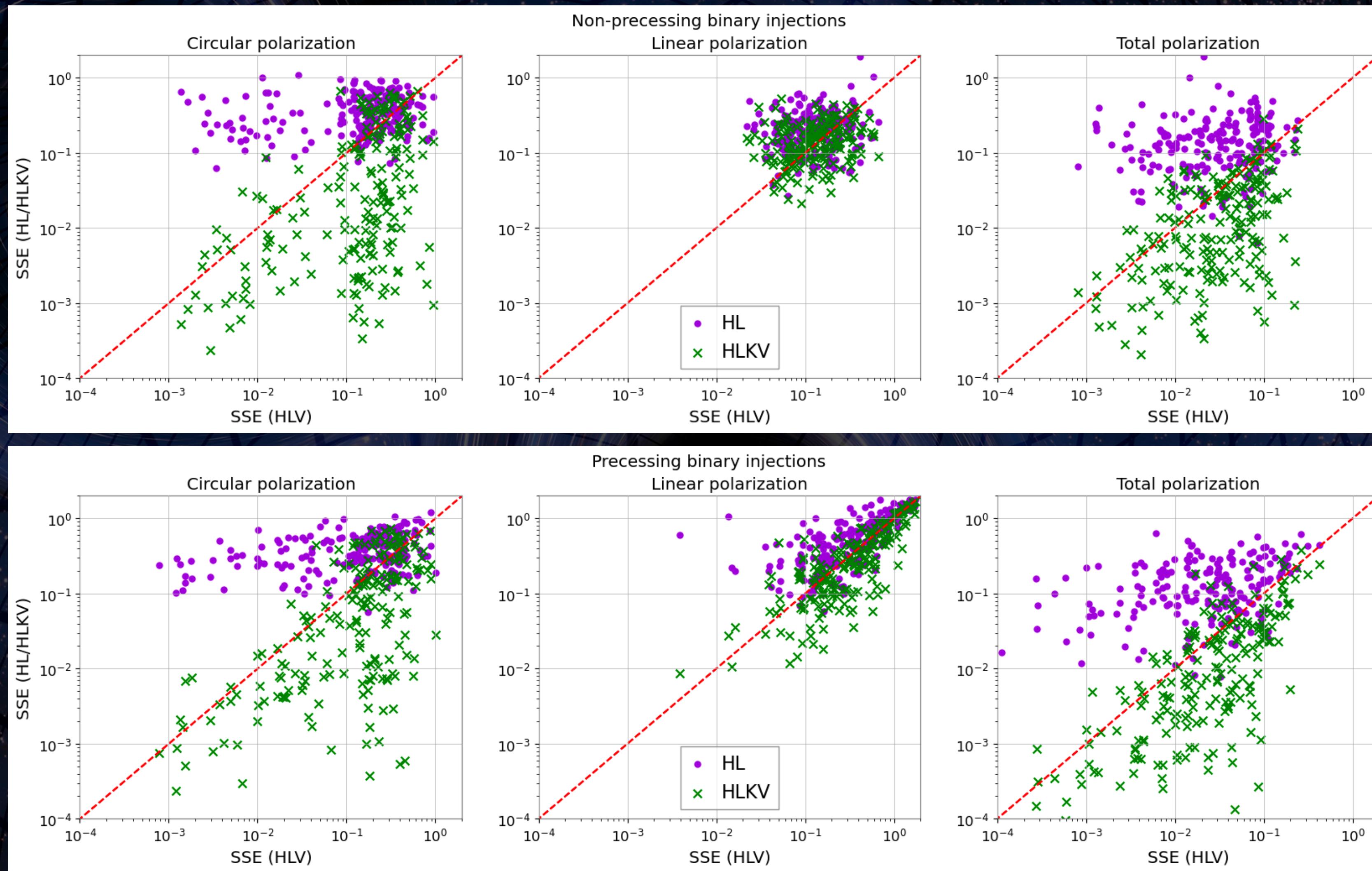
QUANTIFYING ACCURACY OF RECOVERY: SUM OF SQUARED ERRORS (SSE)

Using L as an example:

$$\text{SSE} = \sum_{f_i=f_{\text{low}}}^{f_{\text{high}}} \left[\mathbf{L}_{\text{inj}}(f_i) - \mathbf{L}_{\text{rec}}(f_i) \right]^2$$



COMPARING RECOVERY FOR DIFFERENT DETECTOR CONFIGURATIONS



SUMMARY

- Assess *BayesWave*'s ability to characterize GW burst polarizations using simulated precessing and non-precessing BBH signals.
- Compare $\ln \mathcal{B}_{\mathbf{R},\mathbf{E}}$ for the two types of BBH and find increasing evidence for **R** with the precessing BBHs, especially when the overlap of **R** and **E** reduces. Increasing evidence is especially prominent with larger detector networks.
- Larger networks recover fractional polarizations more accurately, using SSE as the metric.
- FUTURE WORK: Expand to more generic transient signals

KEY TAKEAWAY

As the global detector network continues to expand, there is a promising outlook for *BayesWave* in:

- (i) more accurately reconstruct precessing and non-precessing binaries with the **R** and **E** models respectively
- (ii) more accurately probing the polarization content of GW bursts