

# CHARACTERISATION OF GRAVITATIONAL-WAVE BURSTS TENSOR POLARISATIONS WITH THE BAYESWAVE PIPELINE

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GRAVITATIONAL WAVE DISCOVERY



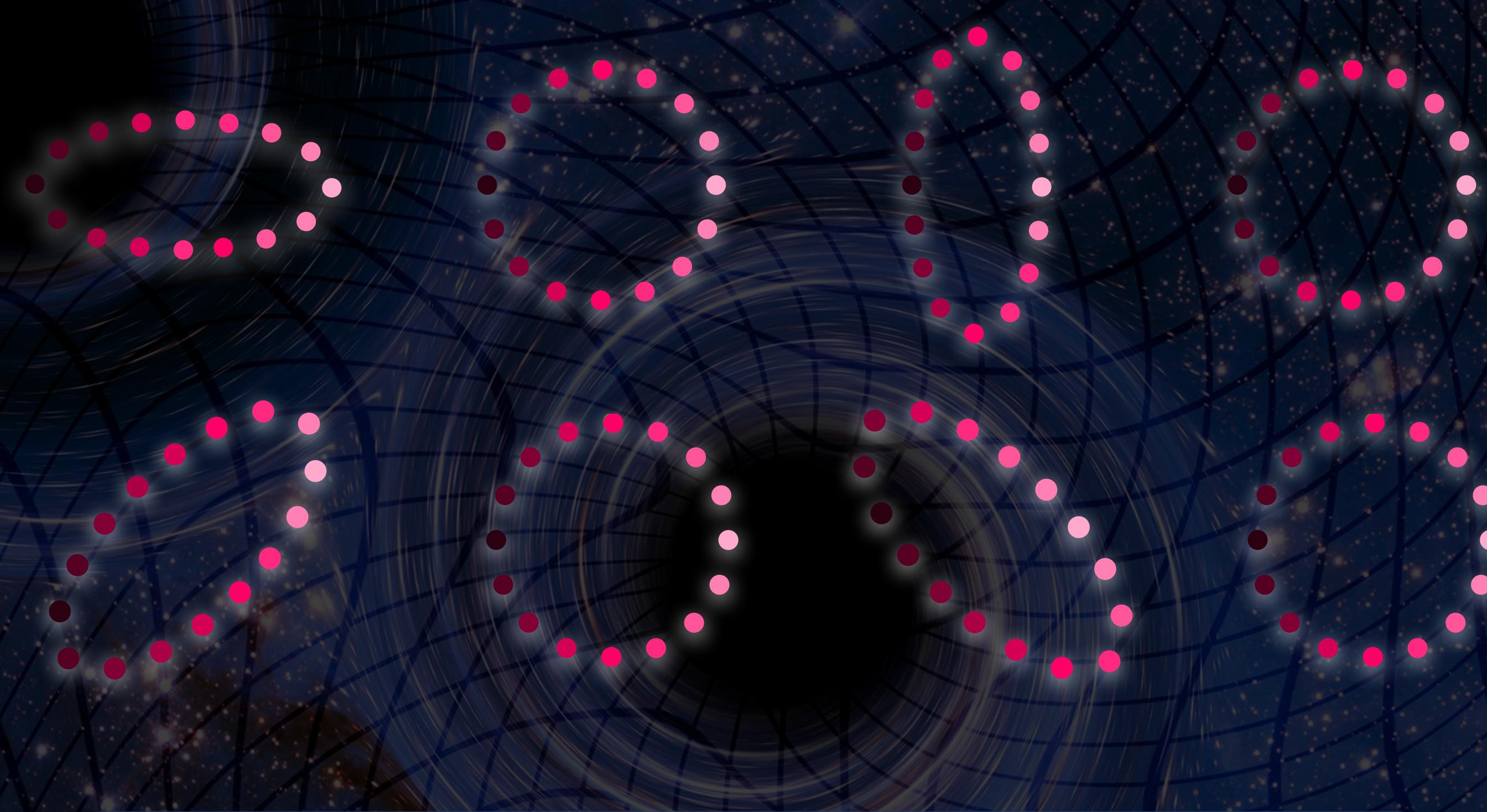
# TALK OVERVIEW

- Gravitational-wave (GW) polarisations
- *BayesWave* signal models: Elliptical ( $E$ ) and relaxed ( $R$ )
- Multi-detector network analyses:
  - **PART I:** Model selection -  $E$  vs.  $R$
  - **PART II:** Measuring tensor polarisation content with  $R$

# GW POLARISATIONS

- According to General Relativity, GWs have two polarisations

- Plus (+)



- Cross (X)

Deformation of a ring of free-falling particles  
by each polarisation modes

# DISENTANGLING GW POLARISATIONS

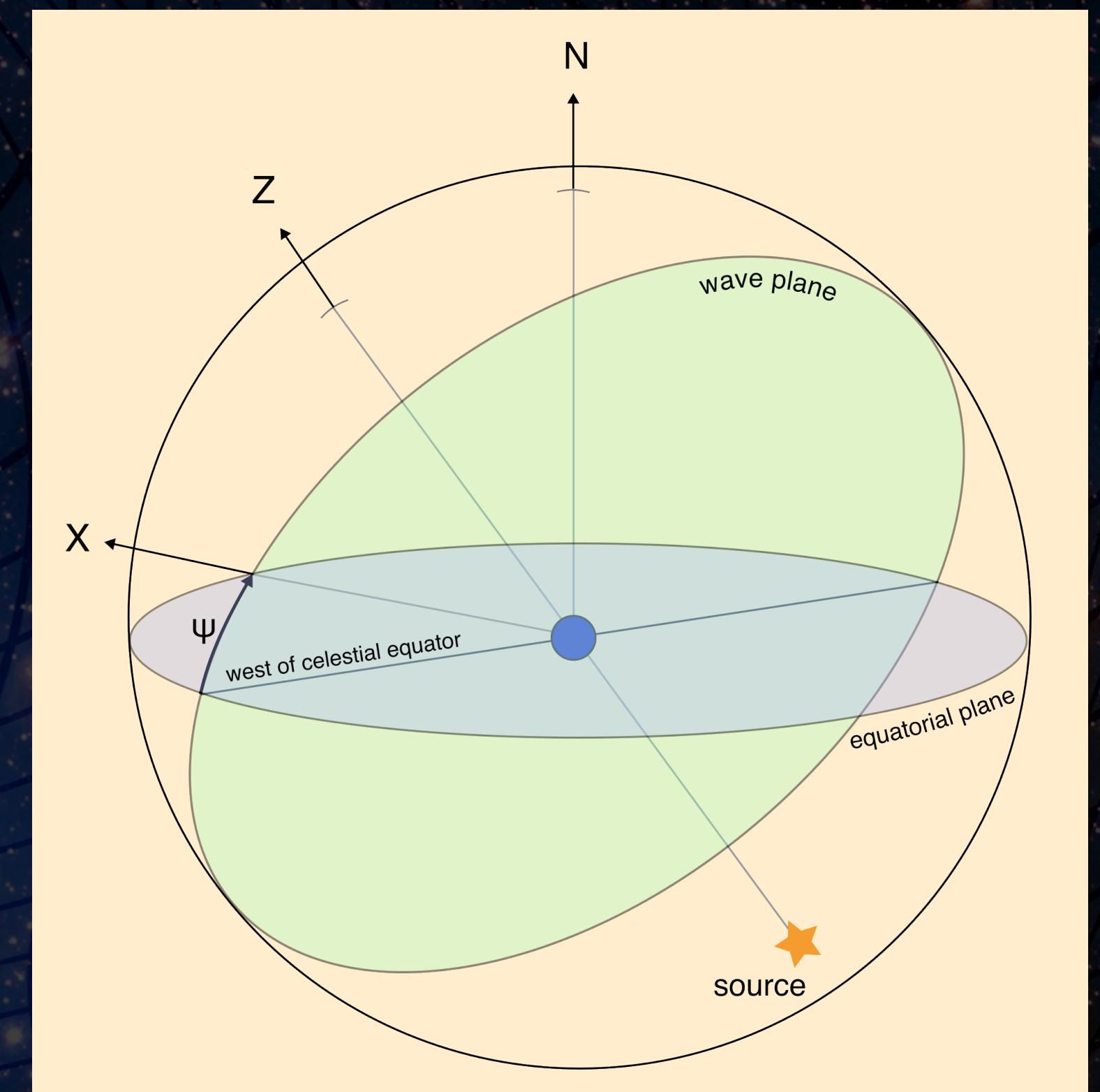
- Antenna pattern functions :  $F_x(\Omega, \psi)$  and  $F_+(\Omega, \psi)$ 
  - Sensitivity of a detector to each polarisation state
  - $\Omega$  = the sky location of the source
  - $\psi$  = the polarisation angle
- Interferometric response of detector  $I$  (in the frequency domain)
  - $\tilde{h}_I = [F_I^x(\Omega, \psi)\tilde{h}^x + F_I^+(\Omega, \psi)\tilde{h}^+] e^{2\pi i f \Delta t_I(\Omega)}$
  - $\tilde{h}_+$  and  $\tilde{h}_x$  = amplitudes at a nominal reference location
  - $\Delta t_I$  = light travel time from the reference location to detector  $I$

# THE POLARISATION ANGLE $\psi$

- Arbitrarily defined w.r.t to a reference direction: west of celestial equator
- $Z$  is the direction of propagation of the GW
- $X$  is the x-axis of the wave plane
- $\psi = 0$  if  $X$  is parallel to the reference direction
- $X$  and  $Y$  are the directional vectors used to define the polarisation components

$$h_+ = \frac{1}{2} (\hat{x}_i \hat{x}_j - \hat{y}_i \hat{y}_j) h^{ij}$$

$$h_X = \frac{1}{2} (\hat{x}_i \hat{y}_j + \hat{y}_i \hat{x}_j) h^{ij}$$



# DISENTANGLING GW POLARISATIONS

$$\tilde{h}_I = \left[ F_I^{\times}(\Omega, \psi) \tilde{h}^{\times} + F_I^{+}(\Omega, \psi) \tilde{h}^{+} \right] e^{2\pi i f \Delta t_I(\Omega)}$$

- Contains up to four unknowns:
  - Two polarisation amplitudes:  $\tilde{h}_{+}$  and  $\tilde{h}_{\times}$
  - Sky location  $\Omega$
  - Source orientation  $\psi$
- Need responses from multiple detectors to extract the polarisation components

# EXPANDING GW DETECTOR NETWORK

- **Existing 2nd-generation ground-based detectors:**

- (1) LIGO - Hanford (H) and Livingston (L), USA
- (2) Virgo (V), Italy
- (3) KAGRA (K), Japan

- **Compare multi-detector performances** in characterising polarisations:

- HL (two-detector)
- HLV (three-detector)
- HLKV (four-detector)



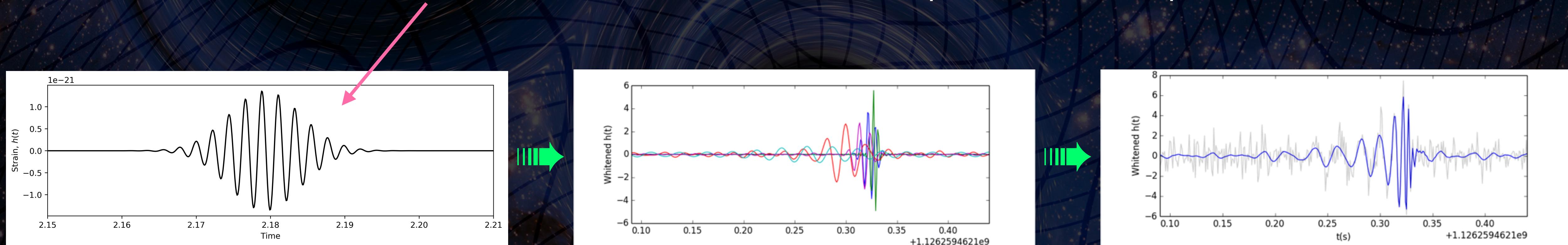
Livingston

Hanford

[Image credits: LIGO Lab Caltech]

# BAYESWAVE: ALGORITHM OVERVIEW

- An unmodelled transient gravitational wave (burst) analysis algorithm
- Enables joint characterization of instrumental glitches and GW bursts
- Reconstructs transient, non-Gaussian features in the data by summing a set of sine-Gaussian wavelets, with no *a priori* assumptions



Images courtesy of Meg Millhouse

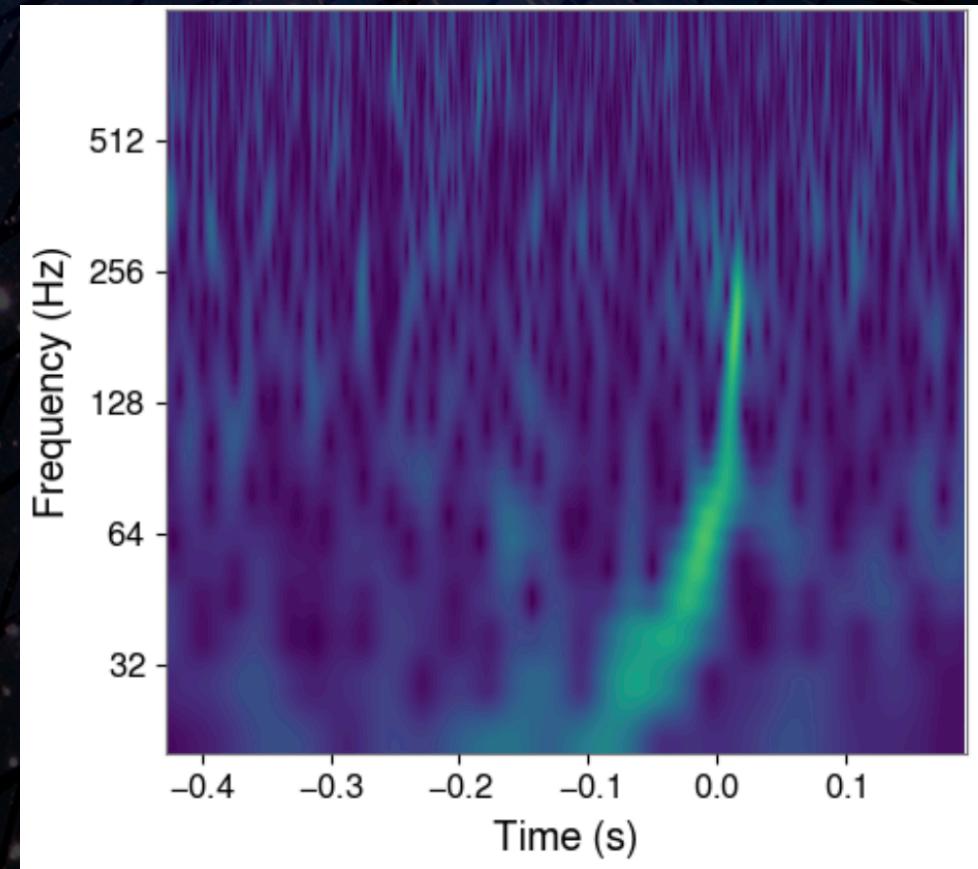
## BayesWave publications:

Cornish + Littenberg, Class. Quant. Grav 32, 130512 (2015)

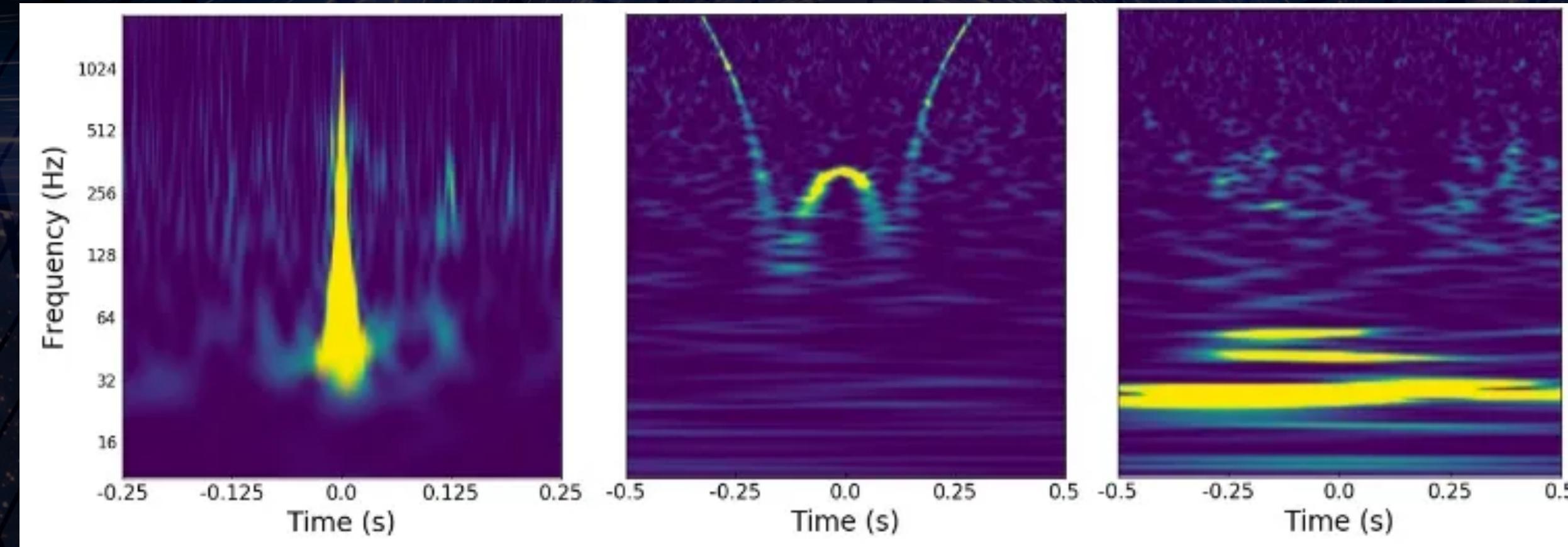
Cornish et al., Phys. Rev. D 103, 044006 (2021)

# BAYESWAVE MODELS

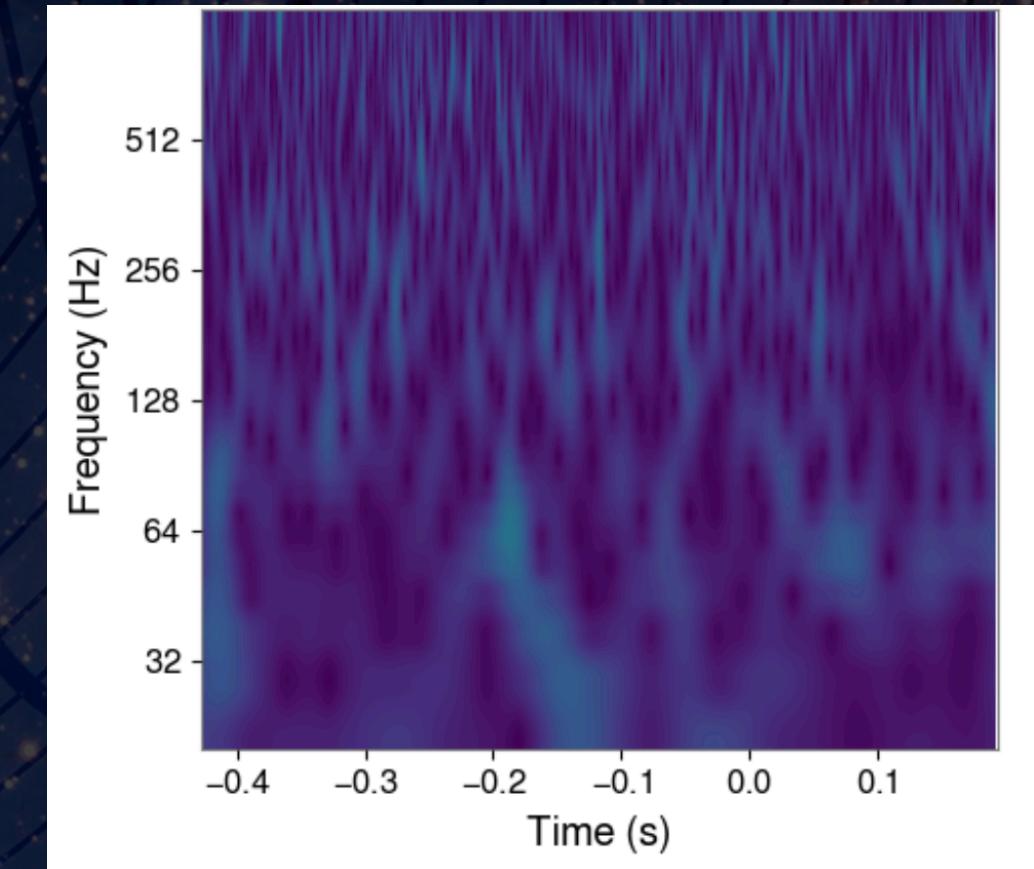
- Reconstructing transient features with three independent models:
  - Signal plus Gaussian-noise model,  $\mathcal{S}$
  - Glitch plus Gaussian-noise model,  $\mathcal{G}$
  - Gaussian-noise only model,  $\mathcal{N}$



Signal



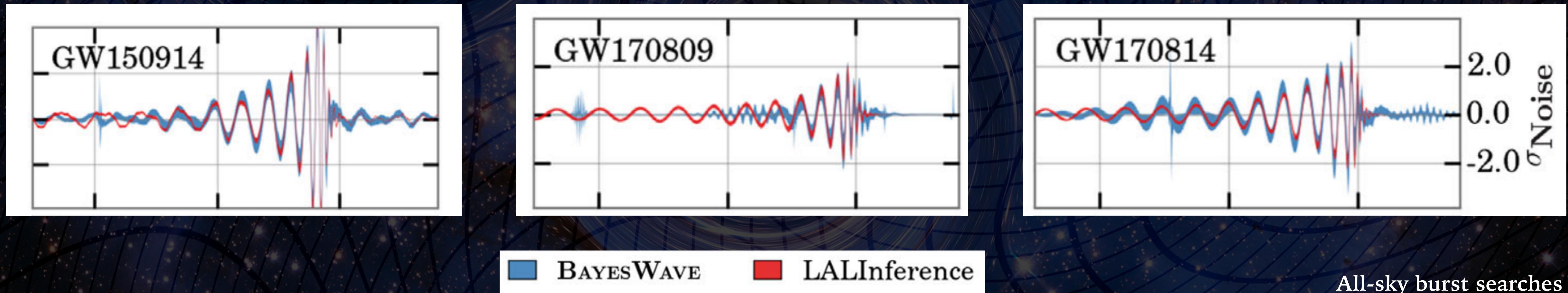
Glitches



Gaussian noise

# BAYESWAVE: ROLE IN GW BURST SEARCHES

- Used to follow-up searches for GW events in O1, O2 and O3 \*  
To assess consistency with matched-filter (model-based) searches
- Also used to follow-up trigger events found by coherent WaveBurst (cWB) to increase detection confidence



GWTC-1: Phys. Rev. X 9, 031040 (2019),  
GWTC-2: Phys. Rev. X 11, 021053 (2021),  
X GWTC-3: arXiv:2111.03606 (2021).

All-sky burst searches

O1: Phys. Rev. D 95, 042003 (2017)  
O2: Phys. Rev. D 100, 024017 (2019)  
O3: Phys. Rev. D 104, 122004 (2021)

# BAYESWAVE SIGNAL MODELS

Elliptical polarisation,  $E$

$$\tilde{h}_+ = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^n, \phi^n)$$

$$\tilde{h}_\times = i\epsilon \tilde{h}_+$$

$\Lambda$  : sine-Gaussian wavelet

$\epsilon$  : ellipticity

$N$  : number of wavelets

Relaxed polarisation,  $R$

$$\tilde{h}_+ = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^{n,+}, \phi^{n,+})$$

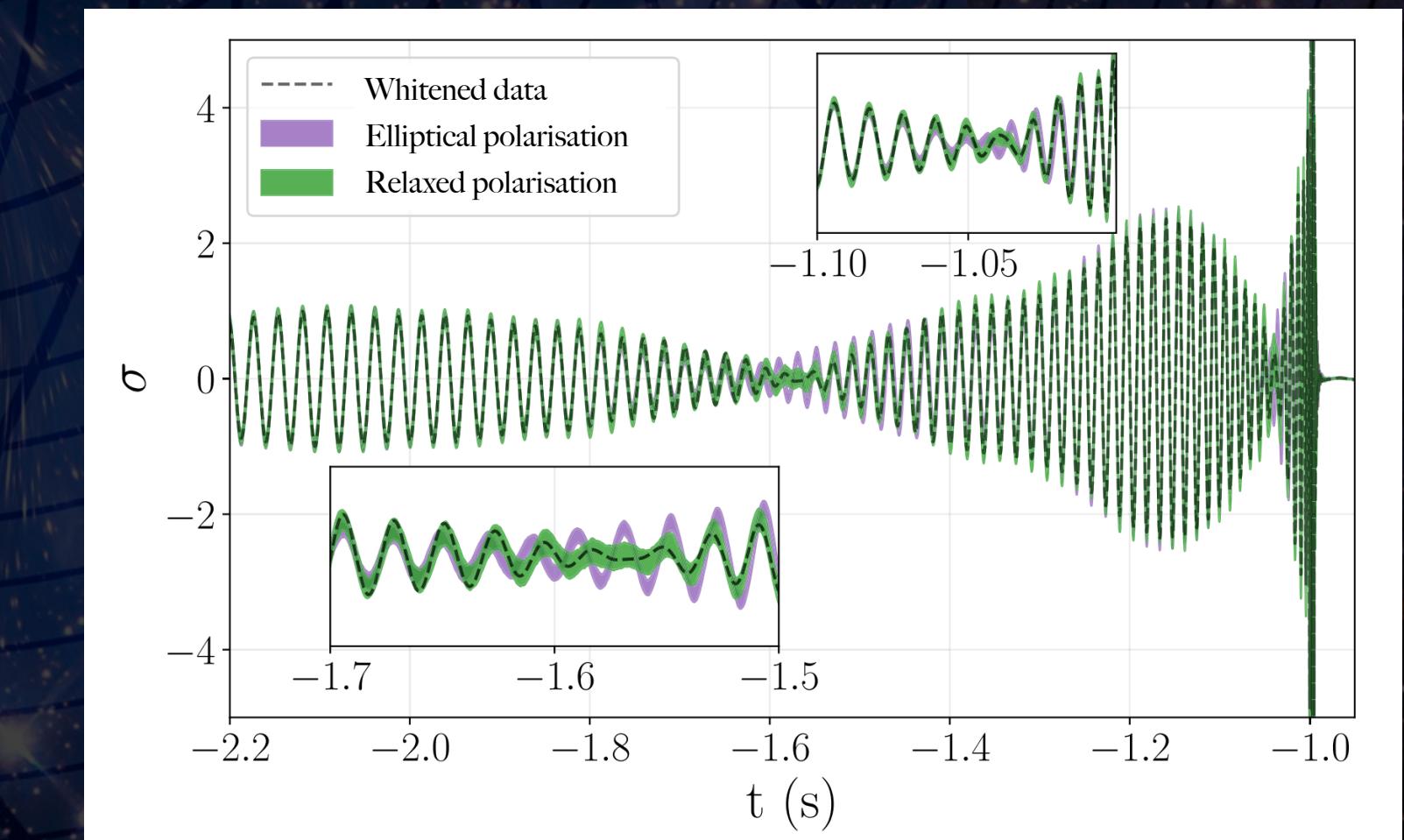
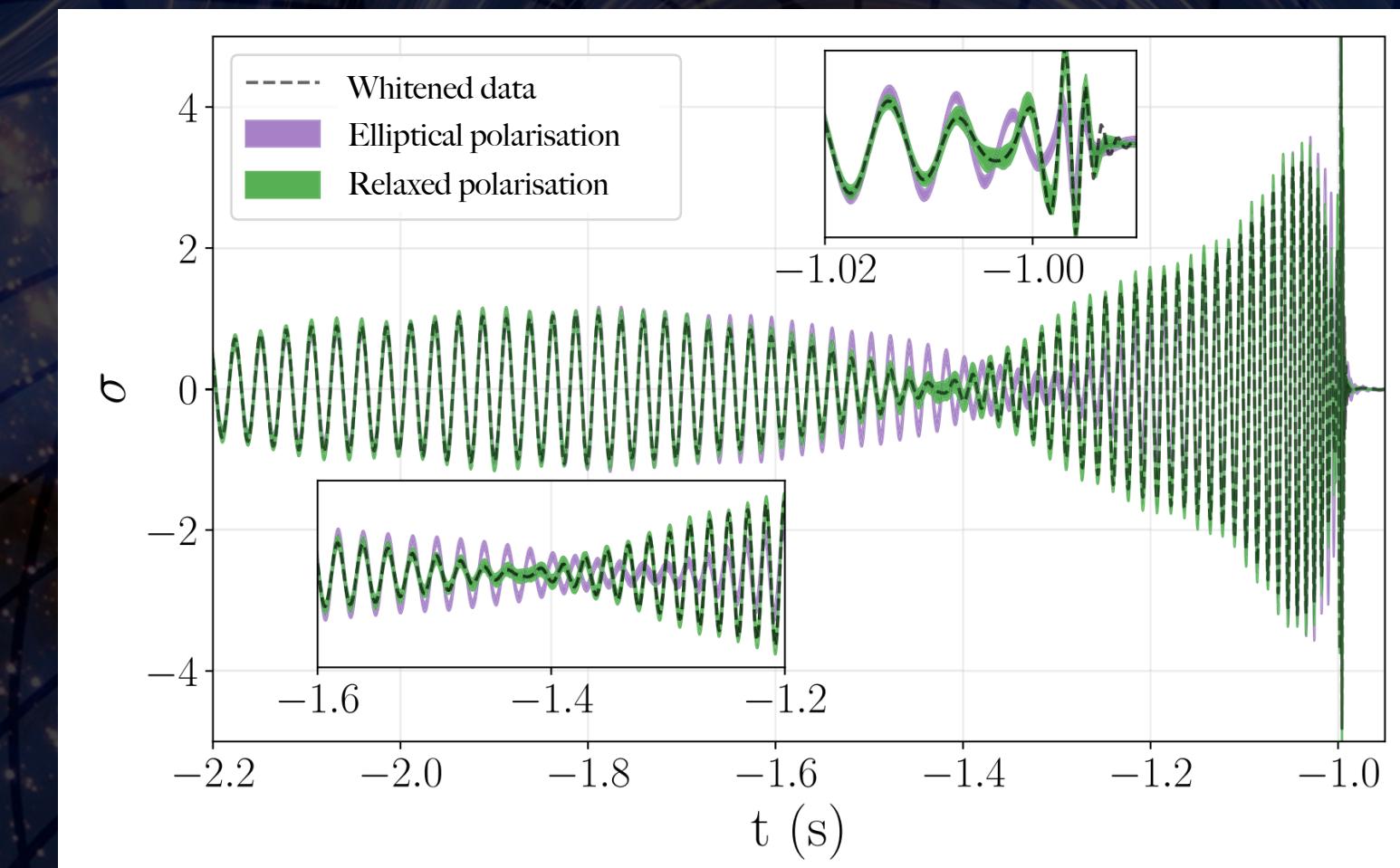
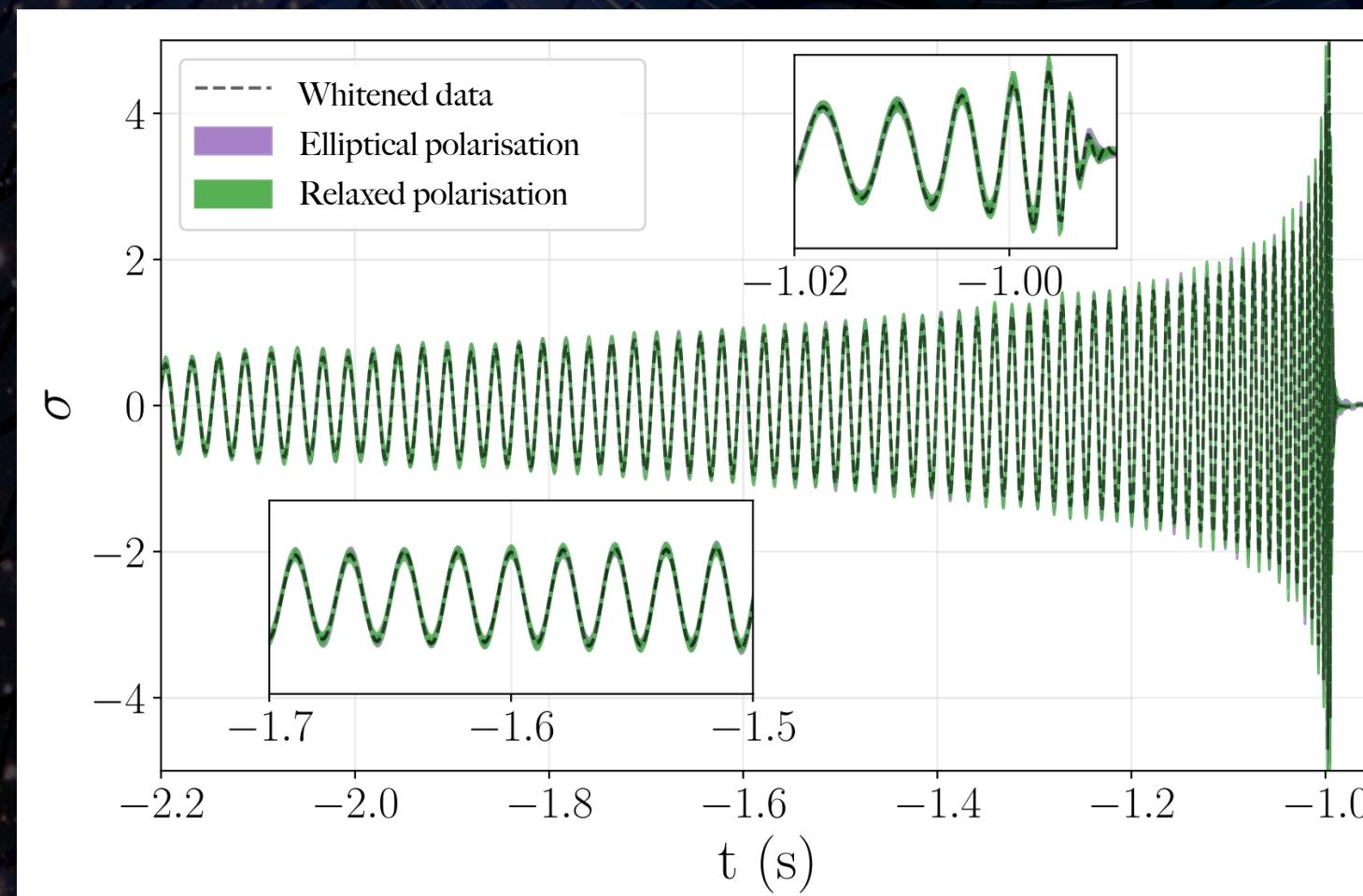
$$\tilde{h}_\times = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^{n,\times}, \phi^{n,\times})$$



To avoid degeneracies with the glitch model

# WHY RELAXED POLARISATION ( $R$ ) MODEL?

- $E$  does not hold for CBCs with time-varying polarisations, e.g.
  - Distinctive higher-order modes
  - Spin-precessing
- Amplitude modulation
- Other transient signals like supernovae are also generally unpolarised



## PART 1

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

How well do the  $E$  and  $R$  polarisation models represent elliptical and nonelliptical GW signals?

Is there a preferred model?

Is the preference affected by the size of detector network?

# TWO INJECTION SETS

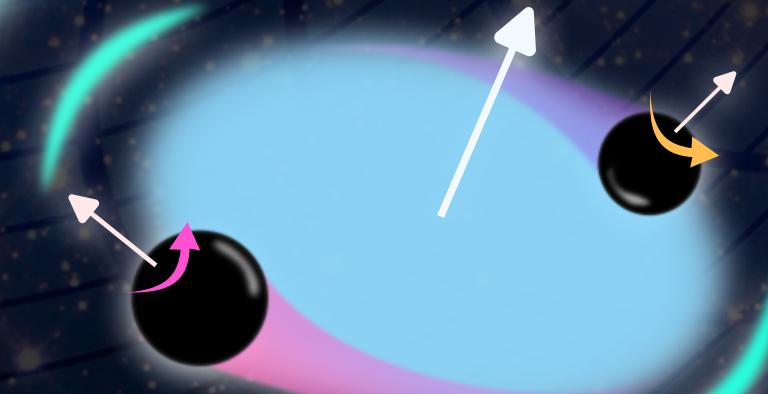
- 200 injections
- High mass ratio  $40M_{\odot} - 8M_{\odot}$
- High network signal-to-noise ratio: SNR  $\sim 50$  (HLV)
- Uniform sky location and polarisation angle
- **Injected into** simulated detector noise

Nonprecessing (elliptical)



Zero-spin

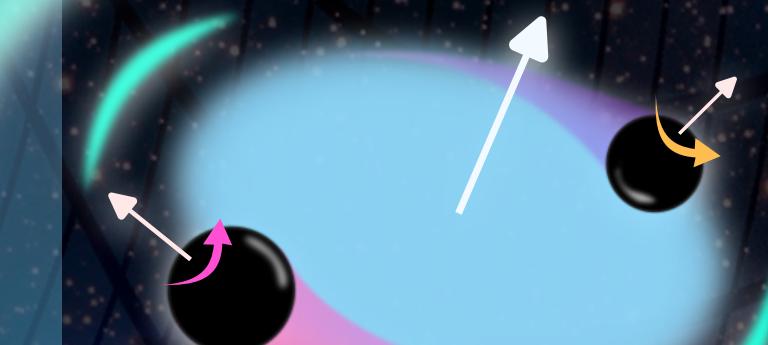
Precessing (nonelliptical)



Non-zero ***in-plane*** spin

# TWO INJECTION SETS

- 200 injections
- High mass ratio  $40M_{\odot} - 8M_{\odot}$
- Sampled distances such that the HLV  $\text{SNR}_{\text{net}} \sim 50$  (loud and ideal!)
- Uniform sky location and polarisation angle
- **Injected into** simulated detector noise



## Nonprecessing (elliptical)

- Fixed inclination at  $45^{\circ}$
- Zero component spin i.e.  $\chi_i = 0$  for  $i = 1, 2$   
where  $\chi_i = |\vec{\chi}_i| = |s_i|/m_i^2$  is the dimensionless spin magnitude

## Precessing (nonelliptical)

- Fixed *initial* inclination at  $45^{\circ}$
- *Initial* spin for each component mass is independently sampled within  $0.1 \leq \chi_i \leq 1.0$

# WHY $0.1 \leq \chi_i \leq 1.0$ ?

Effective precession spin parameter

$$\chi_p := \frac{\max(A_1 m_1^2 \chi_{i\perp}, A_2 m_2^2 \chi_{i\perp})}{A_1 m_1^2}$$

In-plane spin magnitude

$$\chi_{i\perp} \leq \chi_i = \chi_{i\perp} + \chi_{i\parallel}$$

Where  $A_1 = 2 + \frac{3}{2q}$ ,  $A_2 = 2 + \frac{3q}{2}$ ,  $q = \frac{m_1}{m_2} \geq 1$

Angular momentum of in-plane spin components is approximated as  $S_{\perp} \simeq m_1^2 \chi_p$

$$0 \leq \chi_p \leq 1$$

Non-zero when in-plane spin is present

i.e. spin components that are not (anti)parallel to the orbital angular momentum

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ ): FIGURE OF MERITS

Bayes Factor

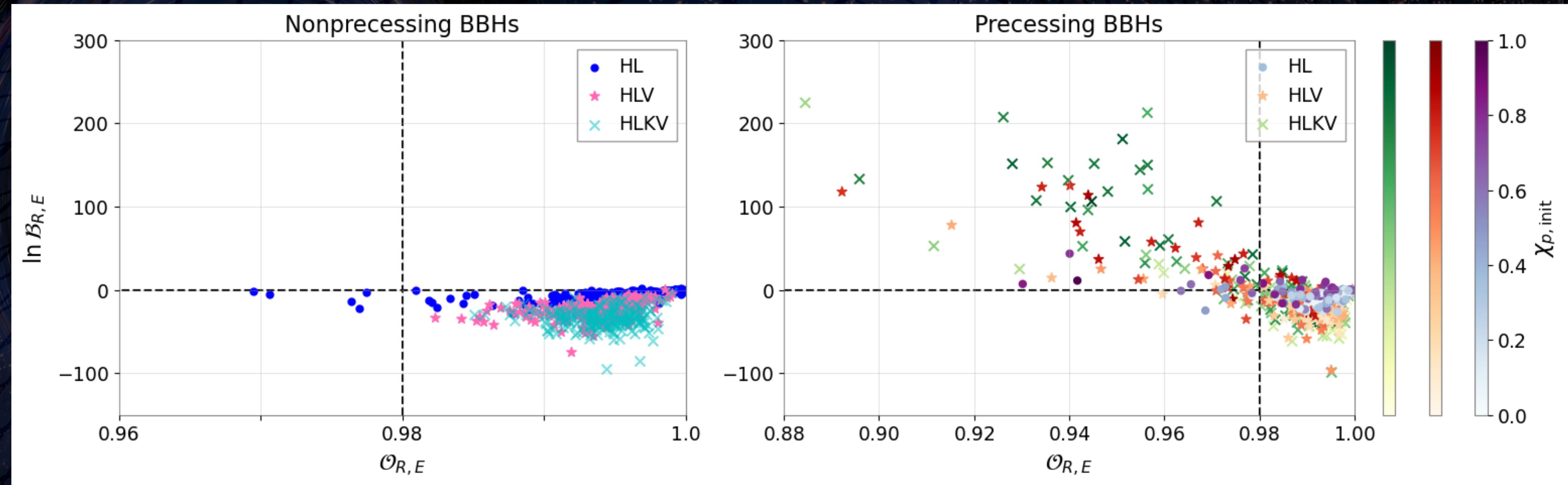
$$\ln \mathcal{B}_{R,E} = \ln p(\vec{s} | R) - \ln p(\vec{s} | E)$$

Network overlap (i.e. match)

$$\mathcal{O}_{R,E} = \frac{\sum_i (h_R^i | h_E^i)}{\sqrt{\sum_i (h_R^i | h_R^i) \sum_i (h_E^i | h_E^i)}}$$

where  $h^i$  is the BayesWave-recovered waveform for the  $i$ -th detector

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )



Only include detected signals in the analysis

Not Gaussian noise

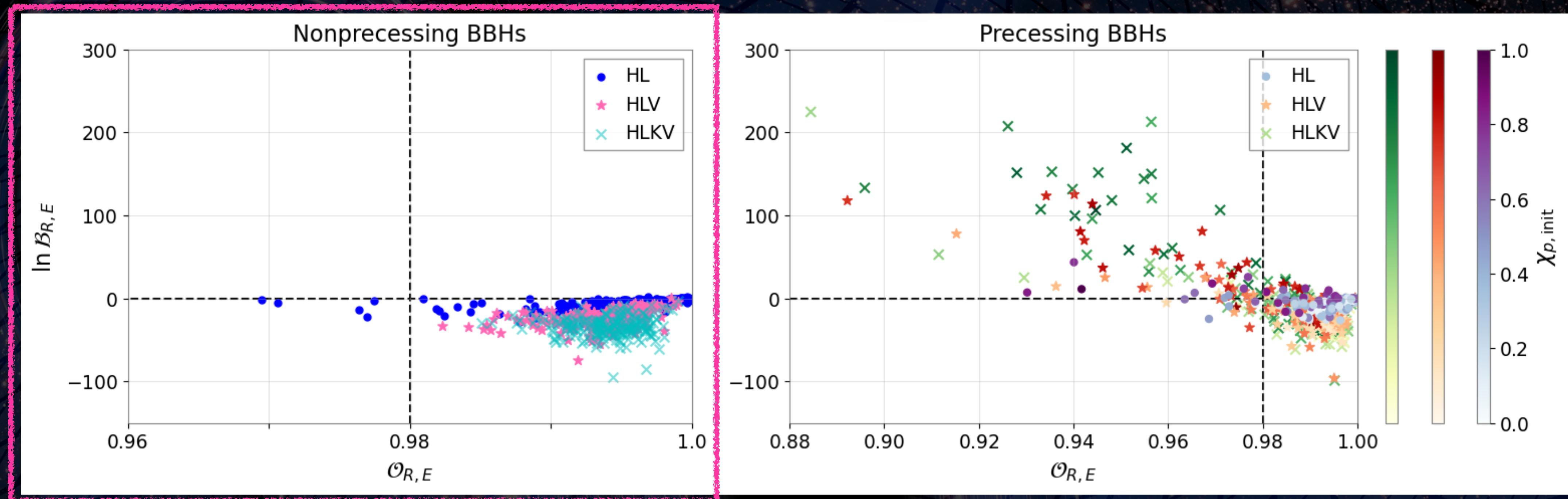
$$\ln \mathcal{B}_{R,\mathcal{N}} \text{ and } \ln \mathcal{B}_{E,\mathcal{N}} \geq 0$$

Not a glitch

$$\ln \mathcal{B}_{R,\mathcal{G}} \text{ and } \ln \mathcal{B}_{E,\mathcal{G}} \geq 0$$

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

## Non-precessing BBHs



$$\text{Evidence of model } \mathcal{M} \simeq \text{Likelihood} \times \frac{\Delta V_{\mathcal{M}}}{V_{\mathcal{M}}}$$

$$\text{Bayes factor, } \mathcal{B}_{R,E} \simeq \text{Likelihood ratio} \times \frac{\Delta V_R}{\Delta V_E} \frac{V_E}{V_R}$$

$\Delta V_{\mathcal{M}}$  : Posterior volume  
 $V_{\mathcal{M}}$  : Total parameter space volume of model  $\mathcal{M}$

# COMPLEXITY OF SIGNAL MODELS

$$\tilde{h}_I = \left[ F_I^{\times}(\Omega, \psi) \tilde{h}^{\times} + F_I^{+}(\Omega, \psi) \tilde{h}^{+} \right] e^{2\pi i f \Delta t_I(\Omega)}$$

Elliptical polarisation,  $E$

$$\tilde{h}_{+} = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^n, \phi^n)$$

$$\tilde{h}_{\times} = i\epsilon \tilde{h}_{+}$$

$5N + 4$  extrinsic parameters

$$\epsilon, \psi, \Omega = (\alpha, \delta)$$

Relaxed polarisation,  $R$

$$\tilde{h}_{+} = \sum_{n=1}^N \Lambda(f; t_0^n, f_0^n, Q^n, A^{n,\times}, \phi^{n,\times})$$

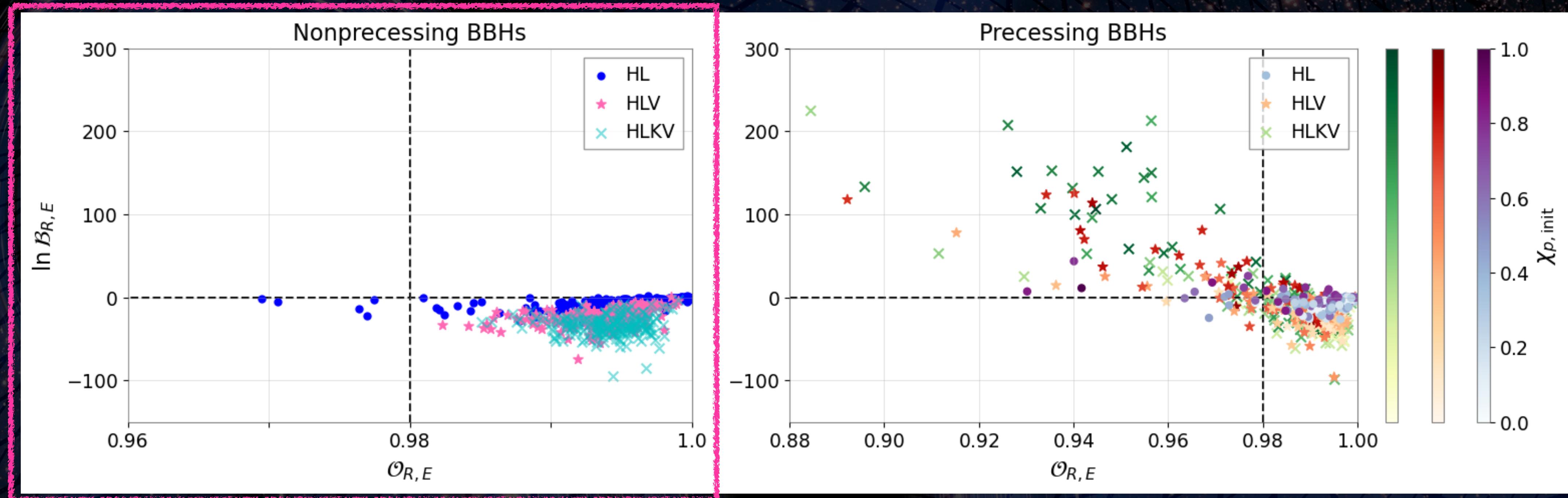
HIGHER COMPLEXITY FOR  $N \geq 1$

$7N + 2$  extrinsic parameters

$$\Omega = (\alpha, \delta)$$

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

## Non-precessing BBHs (cont.)



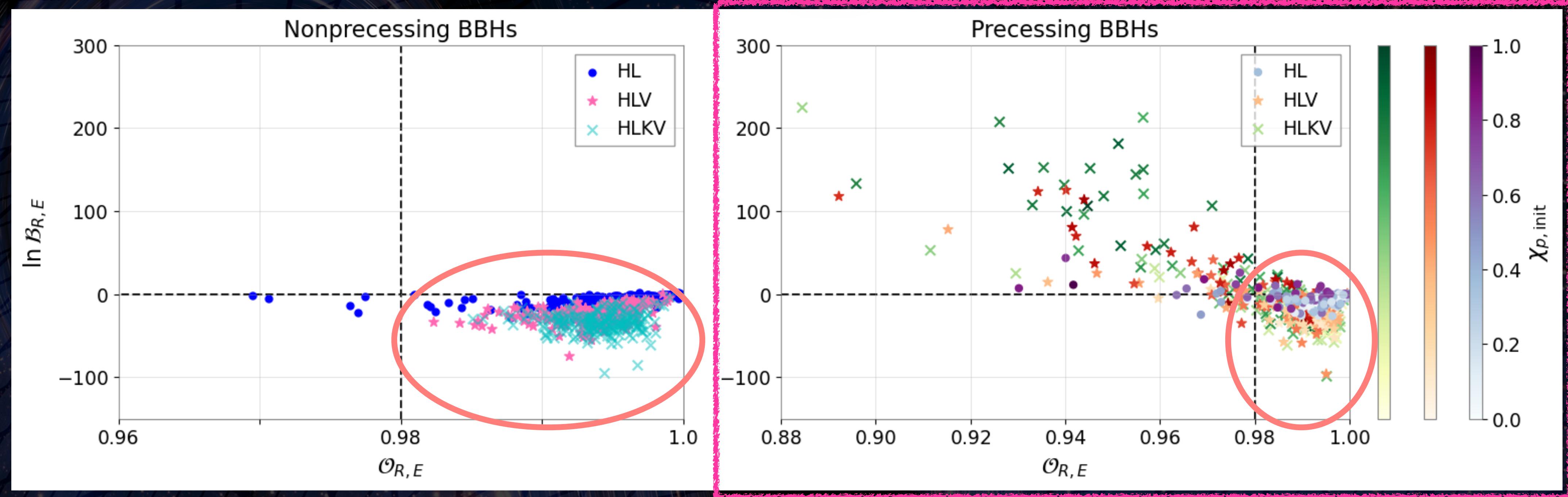
$\mathcal{O}_{R,E} \sim 1 \Rightarrow$  Appx. equal likelihood and posterior volumes (i.e.  $\Delta V_E \approx \Delta V_R$ )

Bayes factor,  $\mathcal{B}_{R,E} \sim 1 \times 1 \times \frac{V_E}{V_R} \Rightarrow \ln \mathcal{B}_{R,E} \lesssim 0$  for  $V_E < V_R$

$\Delta V_{\mathcal{M}}$ : Posterior volume  
 $V_{\mathcal{M}}$ : Total parameter space volume of model  $\mathcal{M}$

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

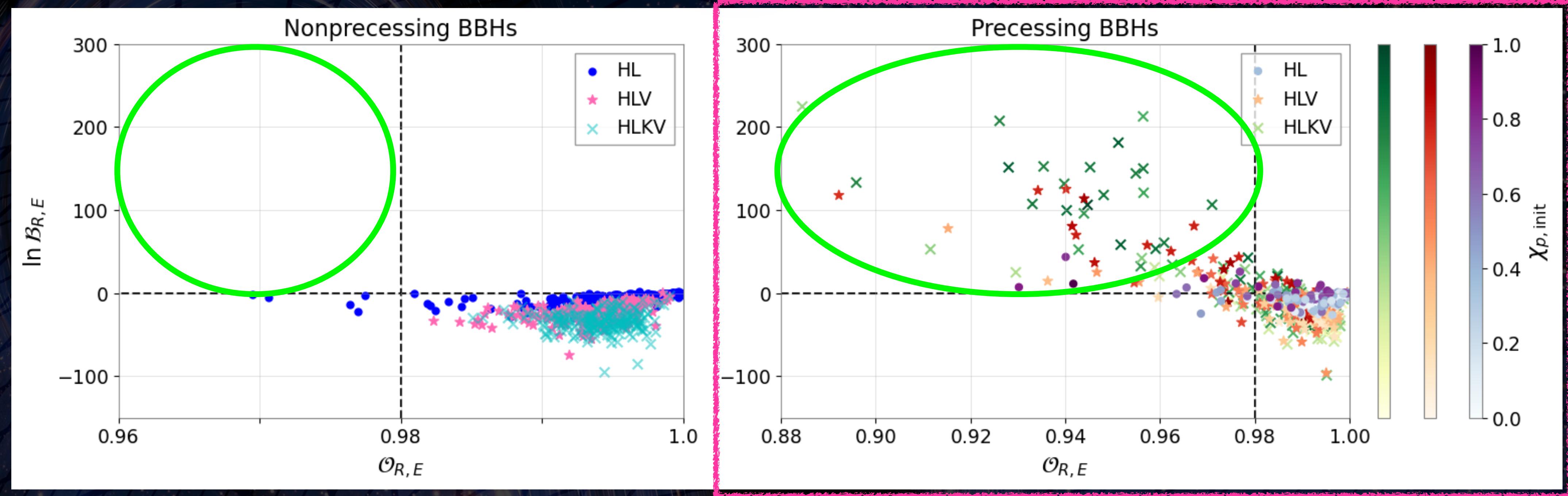
## Precessing BBHs



$\mathcal{O}_{R,E} \geq 0.98 \sim 1 \Rightarrow$  Similar behaviour (i.e.  $\ln \mathcal{B}_{R,E} \lesssim 0$ ) for both non-precessing and precessing BBHs

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

## Precessing BBHs (cont.)



(1)  $\mathcal{O}_{R,E} < 0.98 \Rightarrow \ln \mathcal{B}_{R,E} > 0$  for some precessing BBHs

Mostly high  $\chi_{p,\text{init}}$  events

(2)  $\ln \mathcal{B}_{R,E}$  is more positive with larger detector networks

Better reconstruction of non-elliptical features with  $R$

# KEY TAKEAWAYS

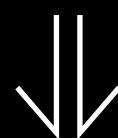
## ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

- Non-precessing BBHs are equally well-represented by both  $E$  and  $R$ , so if we had to choose one...  
Occams Razor says to pick the simpler one ( $E$ )
- Same for most precessing BBHs, BUT...  
High in-plane spin  $\Rightarrow$  likely to have more precession,  
so generally better represented by  $R$

# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

## with real data - O3 events

$$\mathcal{O}_{R,E} \gtrsim 0.90$$

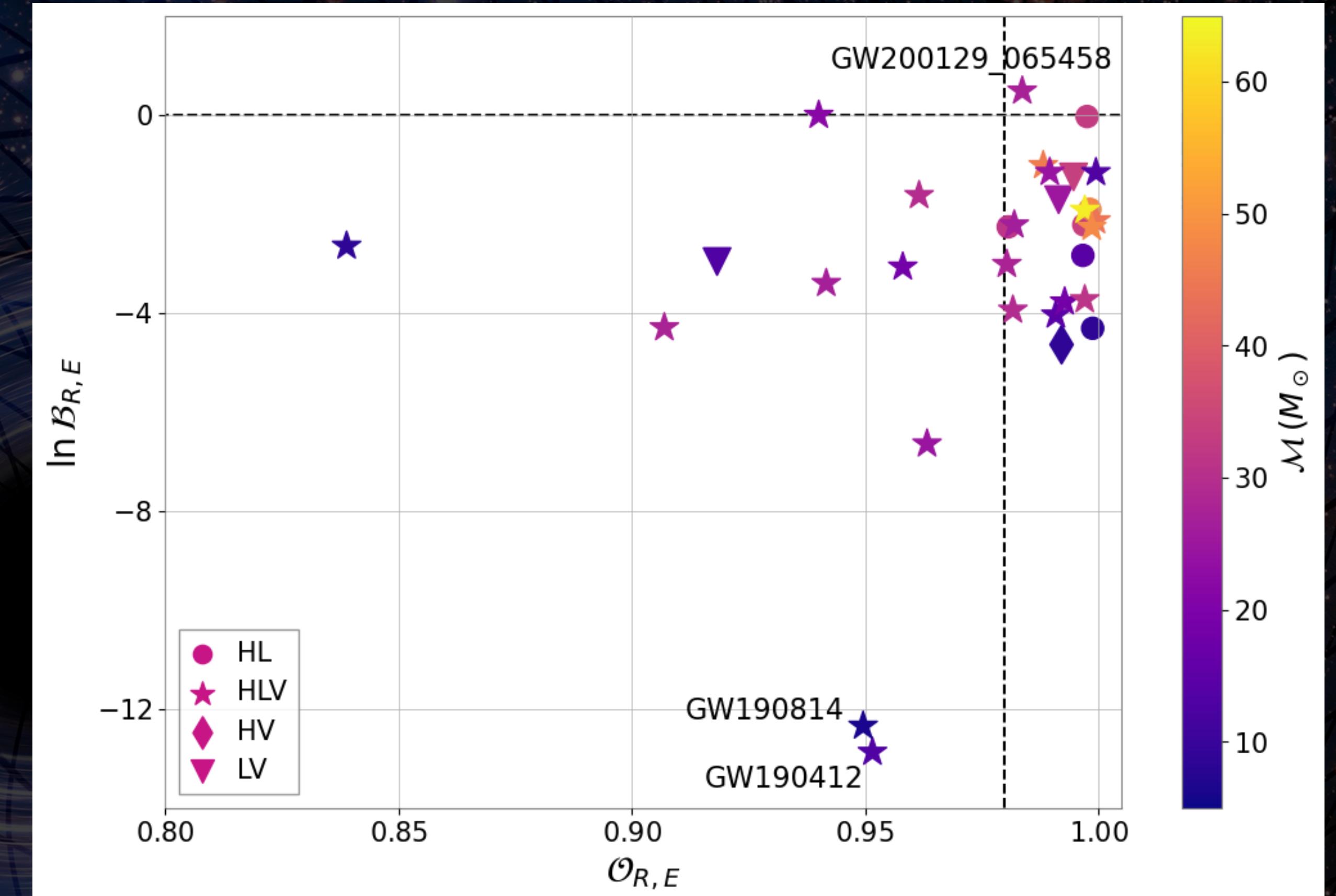


$E$  and  $R$  reconstructions are comparable

$$\ln \mathcal{B}_{R,E} < 0$$



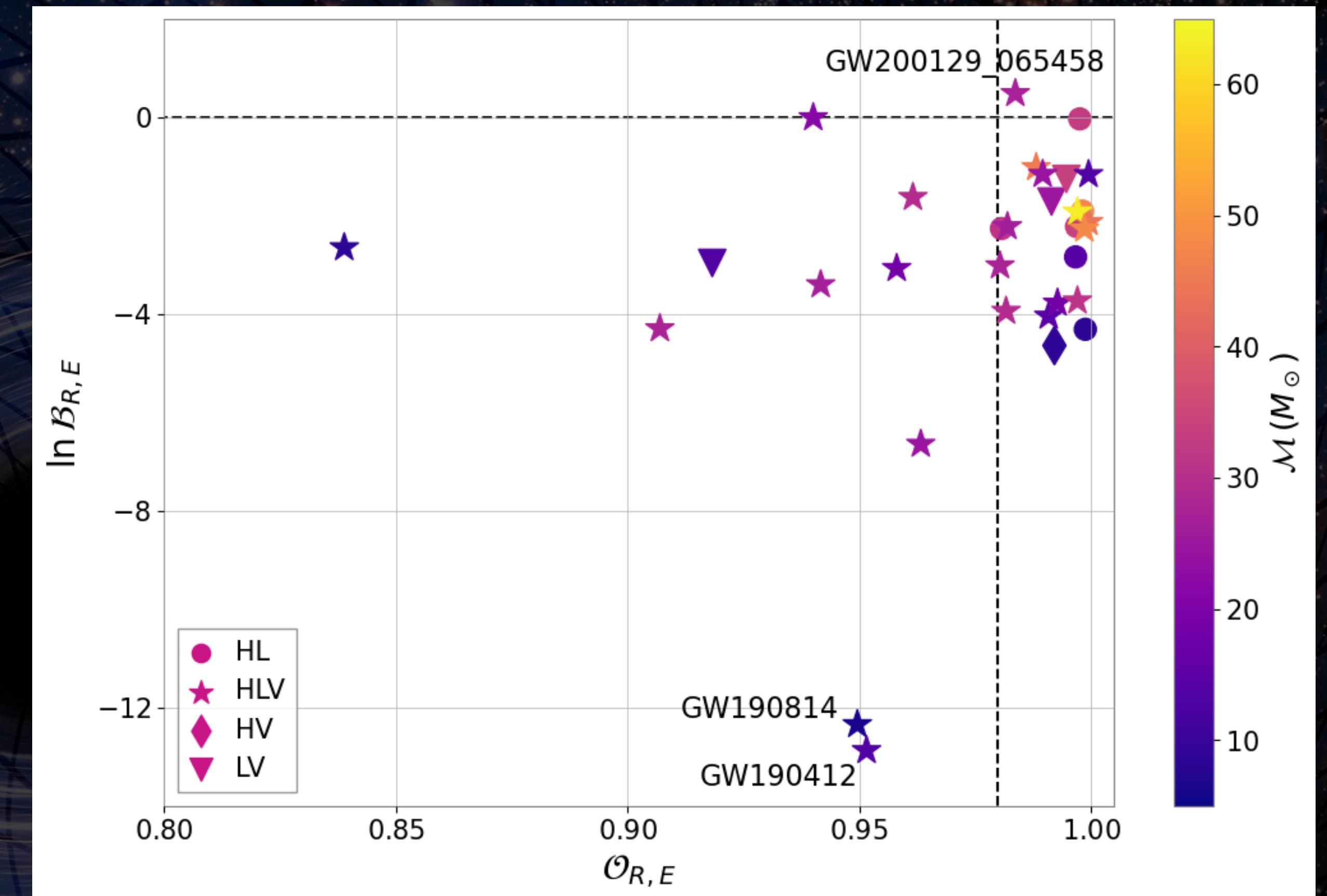
O3 events are generally prefers the elliptical polarisation model  $E$



# ELLIPTICAL ( $E$ ) VS. RELAXED ( $R$ )

## with O3 events - EVENT REMARKS

- $\ln \mathcal{B}_{R,E} < 0$  for all events, except GW200129\_065458:
  - Spin precession? Poorly modelled instrumental glitch?
  - $\ln \mathcal{B}_{R,E} = 0.48 \dots$  insufficient evidence
- GW190412 and GW190814:
  - $\ln \mathcal{B}_{R,E} \sim -12$
  - High SNR ( $\sim 20$ )
  - Low  $\mathcal{M}$  ( $\sim 10 M_{\odot}$ ) = long duration signals
  - More wavelets



GW200129\_065458:

Hannam *et al.* (2022), Payne *et al.* (2022)

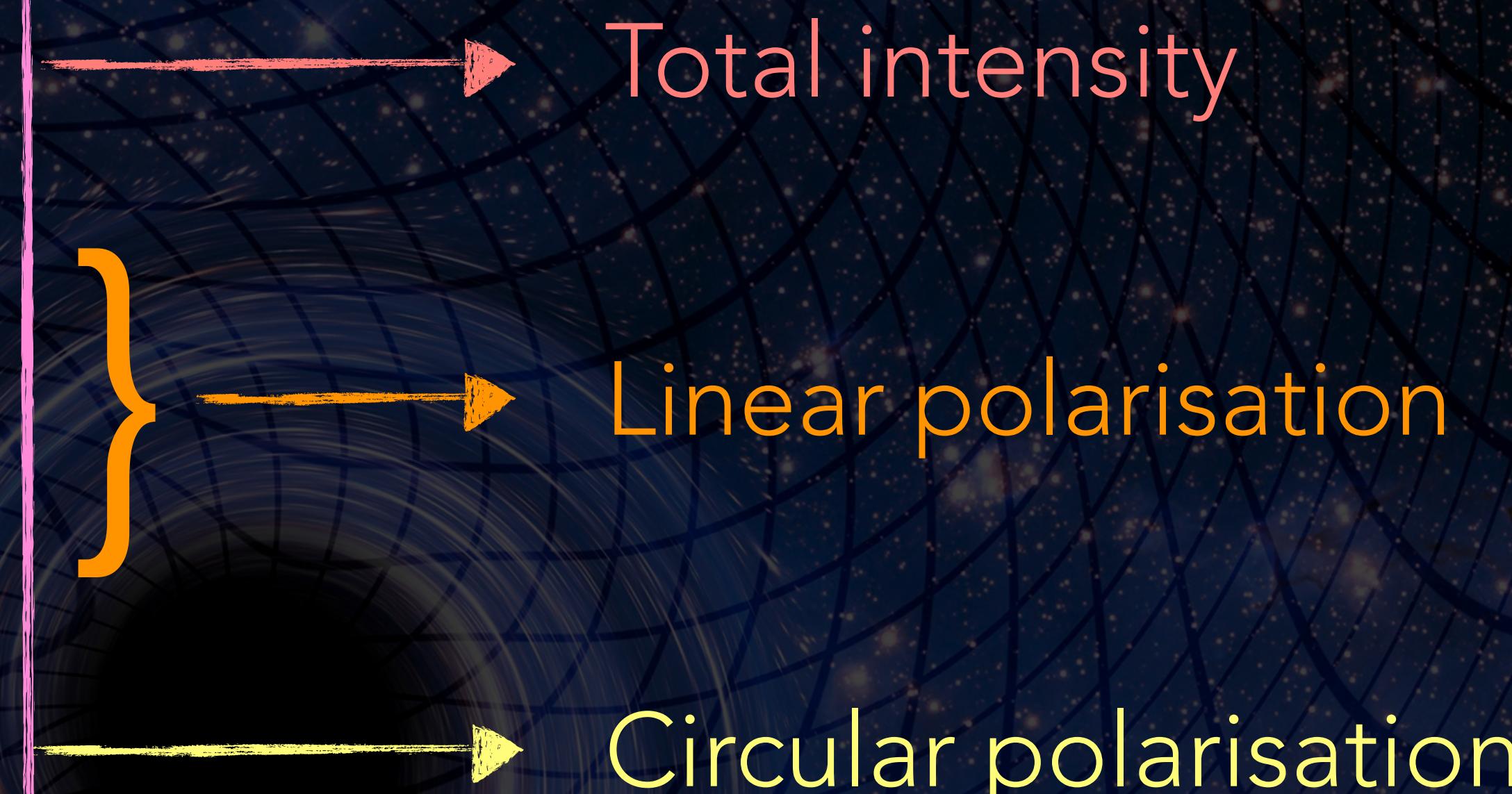
## PART 2

# WHAT ELSE CAN THE RELAXED POLARISATION ( $R$ ) MODEL DO?

- $E$  assumes that the GW signal is elliptical by constraining
$$\tilde{h}_x = i\epsilon \tilde{h}_+$$
- $R$  models  $\tilde{h}_+$  and  $\tilde{h}_x$  separately  
i.e. no prior assumption of the polarisation structure
- So  $R$  can be used to measure generic polarisation content

# STOKES PARAMETERS (IN LINEAR BASIS)

$$\boxed{\begin{aligned} I &= |\tilde{h}_+|^2 + |\tilde{h}_\times|^2 \\ Q &= |\tilde{h}_+|^2 - |\tilde{h}_\times|^2 \\ U &= \tilde{h}_+ \tilde{h}_\times^* + \tilde{h}_\times \tilde{h}_+^* \\ V &= i(\tilde{h}_+ \tilde{h}_\times^* - \tilde{h}_\times \tilde{h}_+^*) \end{aligned}}$$



**GWs are polychromatic**

$\therefore I, Q, U, V$  are functions of frequency

# FRACTIONAL POLARISATION

Linear fraction

$$F_L = \frac{\sqrt{Q^2 + U^2}}{I}$$

Circular fraction

$$F_C = \frac{V}{I}$$

(Total) degree of polarisation

$$F_T = \frac{\sqrt{Q^2 + U^2 + V^2}}{I}$$

$I, Q, U, V$  are real numbers

$$I^2 \leq Q^2 + U^2 + V^2$$

$$0 \leq F_{\mathcal{P}} \leq 1 \text{ for } \mathcal{P} \in \{L, C, T\}$$

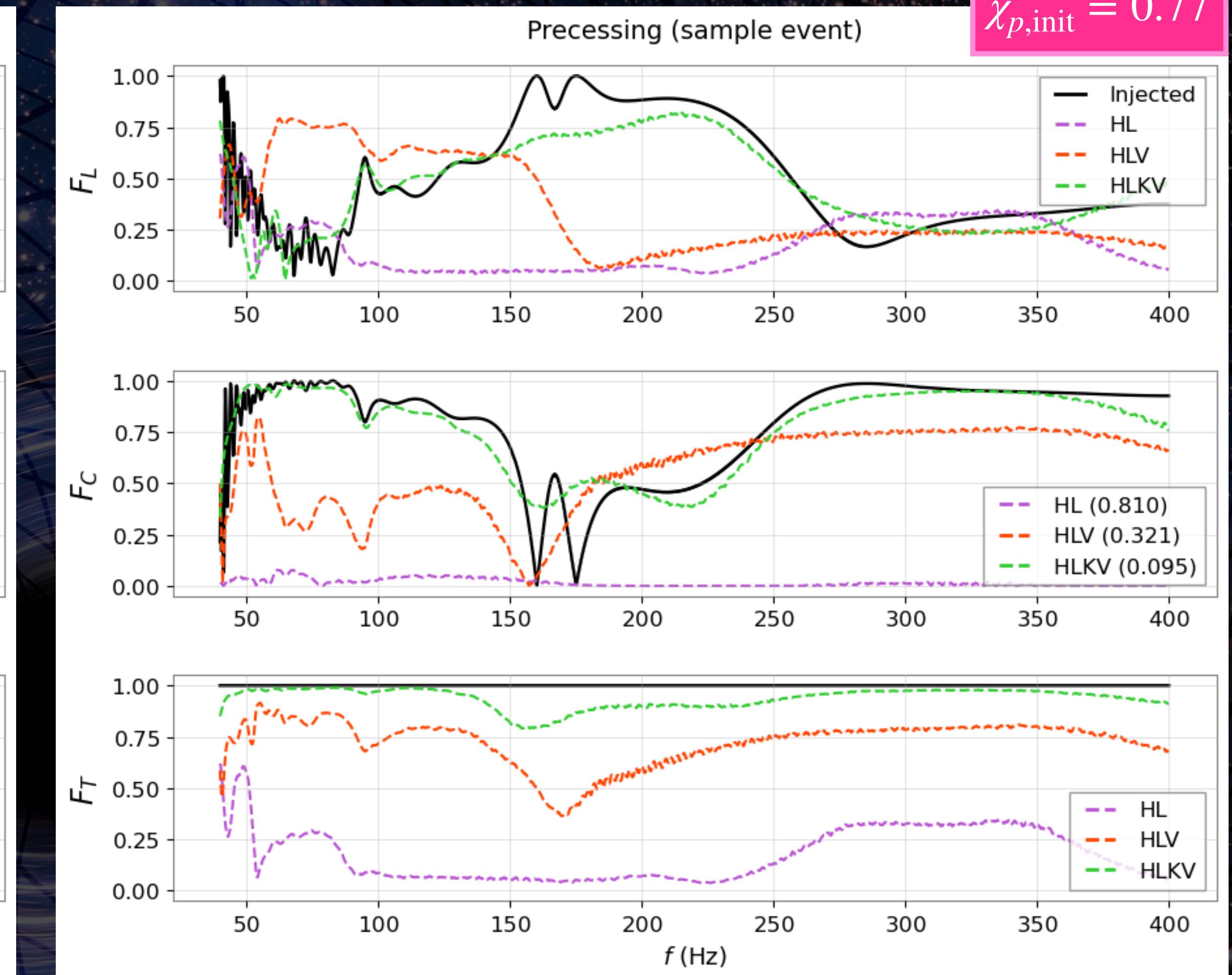
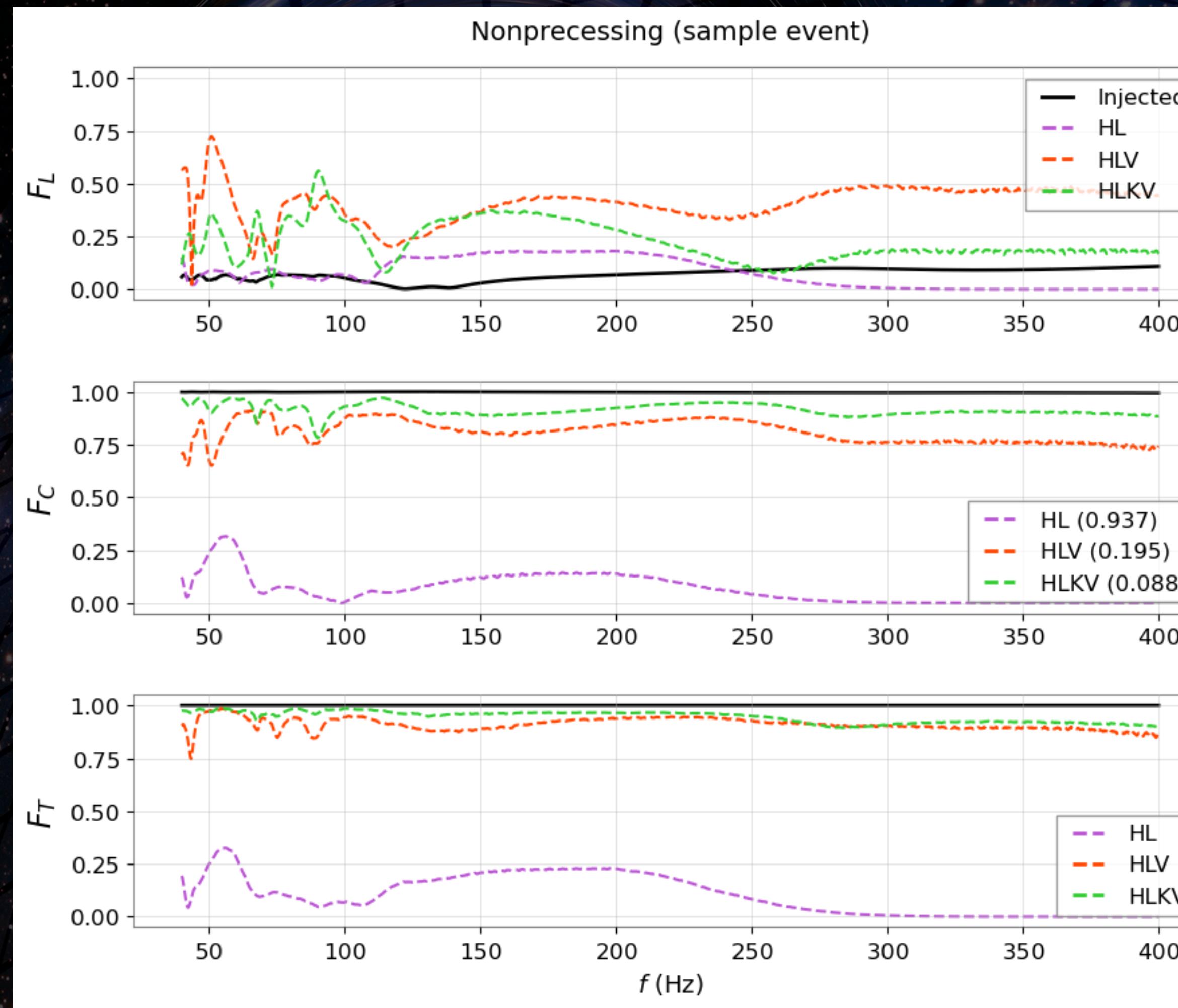
# MEASUREMENT ACCURACY: ROOT MEAN SQUARED RESIDUALS, $\mathcal{R}_{\text{RMS}}$

- BayesWave → discrete frequency  $f_i$
- RMS residuals between injected and recovered  $F_{\mathcal{P}}$

$$\mathcal{R}_{\text{RMS}}(F_{\mathcal{P}}) = \sqrt{\frac{1}{n} \sum_{i=1}^n [F_{\mathcal{P},\text{rec}}(f_i) - F_{\mathcal{P},\text{inj}}(f_i)]^2}$$

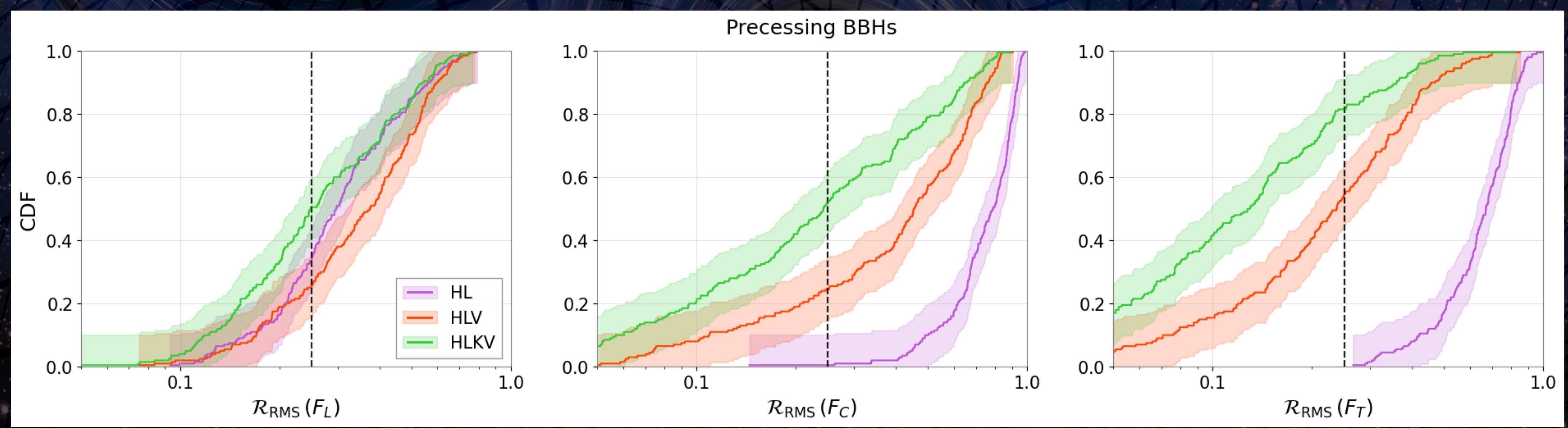
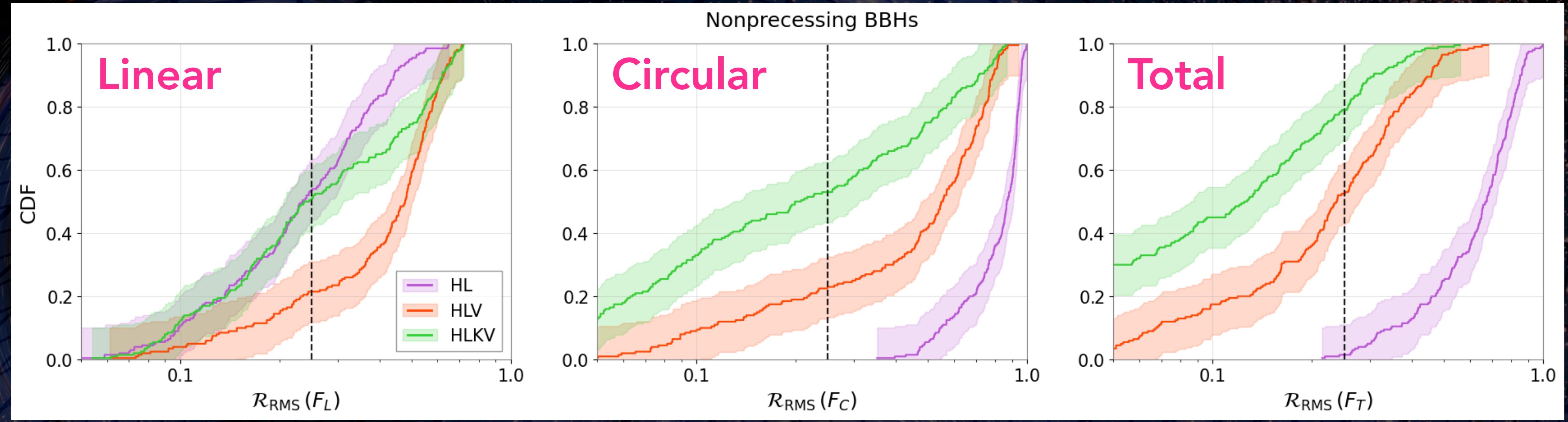
- $n$  = Number of frequency intervals

# ROOT MEAN SQUARED RESIDUALS, $\mathcal{R}_{\text{RMS}}$

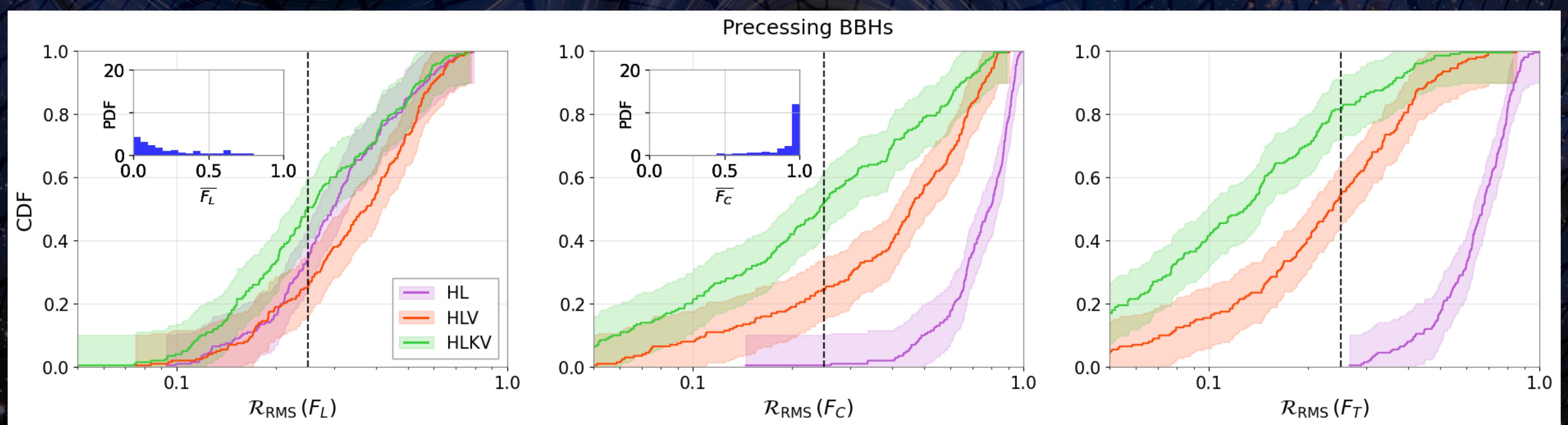
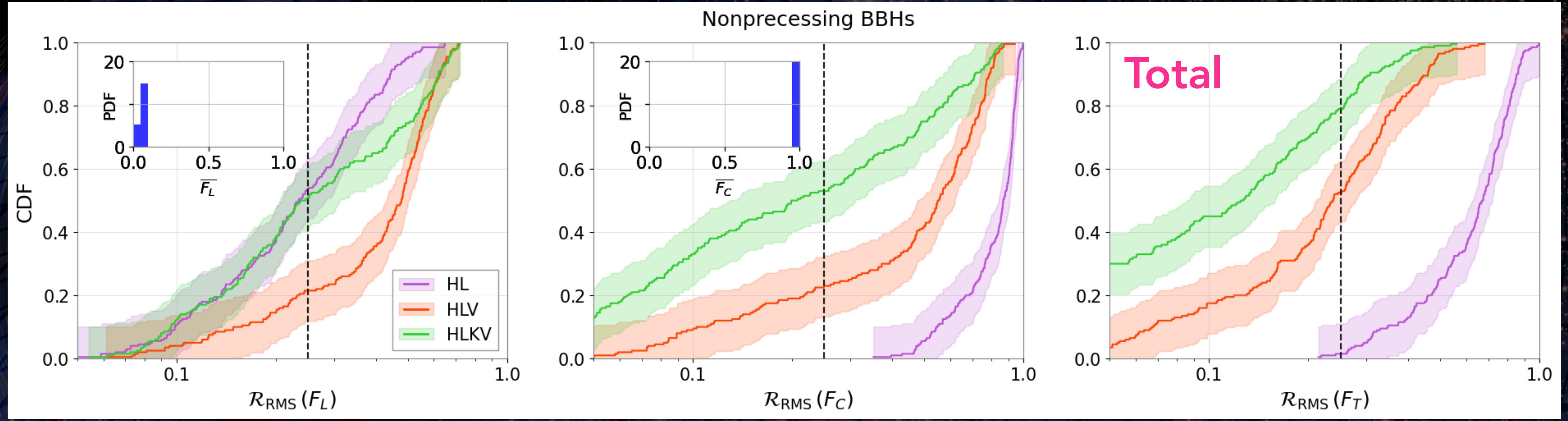


Lower  $\mathcal{R}_{\text{RMS}}(F_{\mathcal{P}})$  = Higher measurement accuracy

# MEASURING FRACTIONAL POLARISATIONS WITH $R$



# MEASURING FRACTIONAL POLARISATIONS WITH $R$



# KEY TAKEAWAYS

## MEASURING POLARISATION CONTENT WITH $R$

- $R$  recovers fractional polarisations more accurately as the detector network expands
  - When detector network is sufficiently large:  
Accuracy of polarisation measurements is not affected by signal morphology
- ⚠ H and L are approximately coaligned

# SUMMARY

- BayesWave can potentially distinguish between elliptical and nonelliptical GW signals through model selection via  $\ln \mathcal{B}_{R,E}$
- The  $R$  model can be used to measure tensor polarisation content of GW burst signals
- Both of the above are enhanced by expanded detector networks
- **FUTURE WORK:**
  - Extend analyses to generic burst signals e.g. CCSN or WNB
  - Model selection between tensor (GR) and non-tensor (non-GR) polarisations