Design Document: adding key-value store to multithreaded HTTP server

Yujia Li CruzID: yli302

1. Goals

This is a simple multi-threading HTTP server and a simple HTTP client which can only have PUT and GET request. Key-value store is a simple file system to store file block object and data block in a single fvs file. This implementation will avoid open file many times, and improve the performance of server.

2. Changes in client and server

2.1 Client

2.1.1 Implement Content-length in PUT request.

1. Open file check file exist and permission.

```
int32 t fd = open(filename);
```

2. Get Content-length of file by fstat.

```
Struct stat sb;
fstat(fd, &sb);
size t content-length = sb.st size;
```

3. Send header

compose headerbuffer into correct header format.

Header format:

```
// PUT 12345678abcdef... HTTP/1.1\r\n Content-Length: #number\r\n\r\n
```

```
char * headerbuf = parseHeaderbuffer();
send(headerbuf);
```

4. Send data

No change. Same as asg1 and asg2

2.2 Server

2.2.1 System design

The server will only open file once when create or open fvs file, and store the file descriptor fd to global filed. Read and write will be replaced by kvread and kvwrite. The kvsread and the kvswrite will read and write file object to kvs file. (details about kvs see part 3 and part 4)

2.2.2 Global variable

Mutex and semaphore: for concurrency, same as asg2.

int fd is the file descriptor of kvs file.

uint32_t curr_fvs_end is a pointer which points to end of kvs file.

2.2.3 Fvs file setup

Flag [-f filename] specifies the filename of kvs file. User must use -f to specify kvs file filename. If no -f flag detected, print no filename error.

After get filename, process following work:

```
fd = open(filename, O_RDWR | O_CREAT);
// init_fvs_file will set up fvs file, and let
// curr_fvs_end point to file end.
init_fvs_file();
```

See detail of ini fvs file() function in 3.2.

2.2.4 PUT

Delete this because kvs don't have this problem: 403 error when write to httpfile(write permission deny)

Change pwrite to kvwrite.

```
// kvinfo return 1 if create a new file entry
isNewfile = kvinfo(object_name, content_length);
// receive data from client and write to kvs file
offset = 0
count = recv(data);
while true then
   kvwrite(object_name, count, offset, data);
   offset += count;
   if (offset == content_length) then break;
   count = recv(data);
```

2.2.5 **GET**

end

Delete this because kvs don't have this problem:

403 error when read from httpfile(read permission deny, read from a directory)

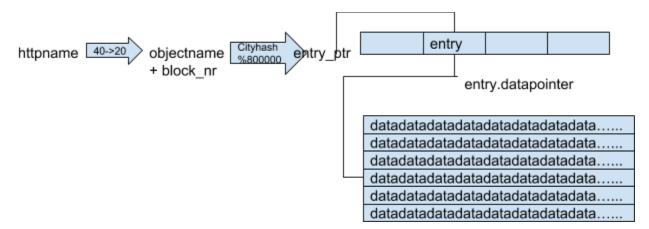
```
// kvinfo return -2 if doesn't find file entry
if ((content_length=kvinfo(name, -1))==-2) then
        error(404 Not Found);
        continue;
end
// receive data from kvs file and send to client
offset = 0;
count=kvread(object_name, sizeof data, offset, data);
while true then
    send(data);
    offset += count;
    if (offset == content_length) then break;
    count=
        kvread(object_name, sizeof data, offset, data);
end
```

2.2.6 Concurrency

Lock when change curr_fvs_end and file object entry.

3. Key-value store system design

3.1 Top level design



kvs file can have max 800,000 entries and 800,000 data blocks.

3.1.1 File object entry

A struct of file object, include: filename, datapointer, datalength, and block nr.

filename is a 20 byte buffer of httpname. Convert from 40 byte hex character buffer. (see 4.2)

datapointer is a pointer points to data block.

datalength if different for block 0 and other blocks. If this entry is block 0, datalength will be the Content Length of whole file. If this entry is not block 0, datalength will be size of data buffer in the data block.

block_nr means the nth block of this file. For example, if content length of file is 10000, there will be 3 blocks of this file: block 0, block 1, and block 2. And block_nr for these blocks are 0, 1, and 2. To get block nr, use offset / 4096.

3.1.2 Data block

The places where really store data. To find correct place of desired data, use datapointer + offset of this block. (see 4.2)

3.1.3 linear probing

Collision of file object entry can happen. Therefore, linear probing is necessary for handle collision.

3.1.3.1 Insert

When collison happen, plus entry_ptr by 32(sizeof entry), until find an empty entry. Then insert to this empty entry.

3.1.3.2 Find

After get entry by entry_ptr, compare filename and block_nr. If different, plus entry_ptr by 32, until find an entry contains same information, or find an empty one.

3.2 initial kvs file

If the kvs file exists, keep track of the pointer to kvs file end, and return 0 to notice this kvs file exists. If the kvs file doesn't exist, create new one, and return 1 to notice this kvs file has been created.

To create kvs file, set 25,600,000 (get by 32 * 800,000) byte as empty entries. See more detail on 4.2.

3.3 ky functions

3.3.1 kvwrite

The way to use kvwrite is the same as pwrite. kvwrite updates file object entry and write data to data block based on offset. See more detail on 4.2.

3.3.2 kyread

The way to use kvread is the same as pread. kvread read data from data block based of offset.

3.3.3 kvinfo

kvinfo return necessary information to process kvwrite and kvread when process PUT and GET request. See more detail on 4.2.

4. Key-value store data structure & algorithm

4.1 data structure

```
// see 3.1.1 for explain of file_object_entry
struct file_object_entry{
  uint8_t httpname[20];
  uint32_t datapointer;
  int32_t datalength;
  uint32_t blocknr;
}
// key for cityhash
struct key {
  uint8_t httpname[20];
  uint32_t blocknr;
}
```

4.2 algorithm

Initial kvs file

```
// if kvs file exists, keep track of pointer to file
end, return 0 to notice exist.
// if kvs file doesn't exist, create new one, return 1
// to notice created.
int32_t init_fvs_file() {
  file_object_entry init_entry;
  offset = 0;
  curr_fvs_end=
    (((file_sz-25600000)/4096)+1)*4096)+25600000;
  if (file_sz == 0) {
    for (int i = 0; i < 800000; ++i) {
       pwrite(fd, &init_entry, 32, offset);
    }
}</pre>
```

```
offset += 32;
         curr fvs end = file sz;
         return 1;
      return 0;
     }
Cityhash
    uint32 t hash(const uint8 t *object name, uint32 t
    block nr) {
       struct key key;
      key.httpname = object name;
      key.block nr = block nr;
      return CityHash32(key, 24) % 800000;
Convert 40 bytes hex char to 20 bytes ascii
     void hex to ascii (uint8 t *object name, const char
     *httpname) {
       for (i = 0; i < 20; ++i) {
         Char * temp;
         temp[0] = httpname[i * 2];
         temp[1] = httpname[i * 2 + 1];
         uint8 t ascii value = convert this two hex char to
                                  one ascii char;
         object name[i] = ascii value;
       }
     }
kvwrite
    ssize t kvwrite(const uint8 t *object name, size t
    length, size t offset, const uint8 t *data) {
      block nr = offset / 4096;
      data offset = offset % 4096;
      entry ptr = hash(object name, block nr);
       // loop for linear probing, iterate entil empty or
     find object.
       for (;;) {
```

```
if (pread(fd, &entry, 32, entry ptr * 32) == -1) {
      Read error;
      return -1;
    // if object doesn't exist, create entry object and
update data.
    if (object doesn't exist) {
      entry.block nr = block nr;
      entry.length = length;
      entry.datapointer = curr fvs end;
      curr fvs end += 4096;
      if (pwrite (fd, &entry, 32, entry ptr * 32) == -1) {
        Write error;
        return -1;
      return pwrite(fd, data, length, entry.datapointer
                        + data offset);
    }
    // if this entry contains correct object, write data
    if (entry.httpname == object name &&
        entry.block nr == block nr) {
      // if this is not block 0, update length.
      // if write a new data, overwrite the Length
      // if continue write data in a block, plus this
     // length
      if (block nr != 0) {
        if (data offset == 0) {
          entry.length = length;
        } else {
          entry.length = data offset + length;
        }
      if (pwrite (fd, &entry, 32, entry ptr * 32) == -1) {
        Write error;
        return -1;
      }
```

kvread

```
ssize t kvread(const uint8 t *object name, size t
length, size t offset, uint8 t *data) {
 block nr = offset / 4096;
 entry ptr = Hash(object name, block nr);
 // loop for linear probing, iterate entil empty or
find object.
  for (;;) {
    if (pread(fd, &entry, 32, entry ptr * 32) == -1) {
     Read error
     return -1;
    // if object doesn't exists, return -2.
    if (object doesn't exists) == 0) {
     return -2;
    // if this entry contains correct object, read data
    if (entry.httpname == object name &&
        entry.block nr == block nr) {
      // if this is block 0, and length greater than
      // 4096, return 4096
      if (block nr == 0 \&\& entry.length > 4096) {
       pread(fd, data, 4096, entry.datapointer);
       return length;
      } else {
       pread(fd, data, entry.length,
```

```
entry.datapointer);
             return entry.length;
          }
         }
         // if this entry is not the correct object or empty,
    find next one
        entry ptr += 1 * 32;
       return -2;
kvinfo
    ssize t kvinfo(const uint8 t *object name, ssize t
    length) {
      entry ptr = hash(object name, 0);
      // for get length
       if (length == -1) {
         // loop for linear probing, iterate entil empty or
        // find object.
         for (;;) {
           if (pread(fd, &entry, 32, entry ptr * 32) == -1) {
             Read error
             return -1;
           }
           // if object doesn't exist, return -2;
           if (object doesn't exist) {
            return -2;
           // if this entry contains correct object, return
           // its length
           if (entry.httpname == object name) {
             return entry.length;
           // if this entry is not the correct object, find
           // next one
          entry ptr += 1 * 32;
         }
```

```
}
// for set length
if (length >= 0) {
  // loop for linear probing, iterate entil empty or
  // find object.
  for (;;) {
    if (pread(fd, &entry, 32, entry ptr * 32) == -1) {
      Read error;
      return -1;
    }
    // if object doesn't exist, create it and return
   // 1.
    if (object doesn't exist) {
      entry.block nr = 0;
      entry.length = length;
      entry.datapointer = curr fvs end;
      curr fvs end += 4096;
      if (pwrite (fd, &entry, 32, entry ptr * 32) ==-1) {
        Write error;
        return -1;
      }
      return 1;
    }
    // if this entry contain this object, update
    // length and return 0
    if (entry.httpname == object name) {
      entry.length = length;
      if (pwrite (fd, &entry, 32, entry ptr * 32) == -1) {
        Write error;
        return -1;
      }
      return 0;
    // if this entry is not the correct object, find
    // next one
    entry ptr += 1 * 32;
```

```
}
}
return -2;
}
```