

STAT 5010 Tutorial 4*

Nov. 2022

Definitions

1. Let \mathfrak{S} be a class of decision rules (randomized or nonrandomized). A decision rule $T \in \mathfrak{S}$ is called *\mathfrak{S} -admissible* (or *admissible* when \mathfrak{S} contains all possible rules) if and only if there does not exist any $S \in \mathfrak{S}$ that is better than T (in terms of the risk).
2. Now we consider an average of $R_T(P)$ over $P \in \mathcal{P}$:

$$r_T(\Pi) = \int_{\mathcal{P}} R_T(P) d\Pi(P),$$

where Π is a known probability measure on $(\mathcal{P}, \mathcal{F}_{\mathcal{P}})$ with an appropriate σ -field $\mathcal{F}_{\mathcal{P}}$. $r_T(\Pi)$ is called the *Bayes risk* of T w.r.t. Π . If $T_* \in \mathfrak{S}$ and $r_{T_*}(\Pi) \leq r_T(\Pi)$ for any $T \in \mathfrak{S}$, then T_* is called a *\mathfrak{S} -Bayes rule* (or *Bayes rule* when \mathfrak{S} contains all possible rules) w.r.t. Π . The second method is to consider the worst situation, i.e., $\sup_{P \in \mathcal{P}} R_T(P)$. If $T_* \in \mathfrak{S}$ and $\sup_{P \in \mathcal{P}} R_{T_*}(P) \leq \sup_{P \in \mathcal{P}} R_T(P)$ for any $T \in \mathfrak{S}$, then T_* is called a *\mathfrak{S} -minimax rule* (or *minimax rule* when \mathfrak{S} contains all possible rules).

3. To test the hypotheses H_0 versus H_1 , there are only two types of statistical errors we may commit: rejecting H_0 when H_0 is true (called the *type I error*) and accepting H_0 when H_0 is wrong (called the *type II error*). In statistical inference, a test T , which is a statistic from \mathcal{X} to $\{0, 1\}$, is assessed by the probabilities of making two types of errors:

$$\alpha_T(P) = P(T(X) = 1) \quad P \in \mathcal{P}_0$$

and

$$1 - \alpha_T(P) = P(T(X) = 0) \quad P \in \mathcal{P}_1,$$

which are denoted by $\alpha_T(\theta)$ and $1 - \alpha_T(\theta)$ if P is in a parametric family indexed by θ . Note that these are risks of T under the 0 – 1 loss in statistical decision theory. However, an optimal decision rule (test) does not exist even for a very simple problem with a very simple class of tests (Example).

4. A common approach to finding an "optimal" test is to assign a small bound α to one of the error probabilities, say $\alpha_T(P), P \in \mathcal{P}_0$, and then to attempt to minimize the other error probability $1 - \alpha_T(P), P \in \mathcal{P}_1$, subject to

$$\sup_{P \in \mathcal{P}_0} \alpha_T(P) \leq \alpha.$$

The bound α is called the *level of significance*. The left-hand side above is called the *size* of the test T . Note that the level of significance should be positive, otherwise no test satisfies the inequality above except the silly test $T(X) \equiv 0$ a.s. \mathcal{P} .

5. For most tests satisfying the inequality above, a small α leads to a "small" rejection region. It is good practice to determine not only whether H_0 is rejected or accepted for a given α and a chosen test T_α , but also the smallest possible level of significance at which H_0 would be rejected for the computed $T_\alpha(x)$, i.e., $\hat{\alpha} = \inf \{\alpha \in (0, 1) : T_\alpha(x) = 1\}$. Such an $\hat{\alpha}$, which depends on x and the chosen test and is a statistic, is called the *p-value* for the test T_α .

Propositions and Theorems

1. (TPE Lemma 5.1.13) If δ_Λ is the Bayes estimator of $g(\theta)$ with respect to Λ and if

$$r_\Lambda = E[\delta_\Lambda(\mathbf{X}) - g(\Theta)]^2$$

is its Bayes risk, then

$$r_\Lambda = \int \text{var}[g(\Theta) \mid \mathbf{x}] dP(\mathbf{x}).$$

In particular, if the posterior variance of $g(\Theta) \mid \mathbf{x}$ is independent of \mathbf{x} , then

$$r_\Lambda = \text{var}[g(\Theta) \mid \mathbf{x}].$$

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2. (TPE Theorem 5.1.12) Suppose that $\{\Lambda_n\}$ is a sequence of prior distributions with Bayes risks r_n satisfying $r_n \leq r = \lim_{n \rightarrow \infty} r_n$ and that δ is an estimator for which

$$\sup_{\theta} R(\theta, \delta) = r.$$

Then (i) δ is minimax and (ii) the sequence $\{\Lambda_n\}$ is least favorable.

3. For $X \sim N(\theta, I_p)$ ($p \geq 3$) with θ unknown. Under loss $L(\theta, a) = \|a - \theta\|^2 = \sum_{i=1}^p (a_i - \theta_i)^2$, X is a minimax estimator. But X is inadmissible and dominated by the James-Stein estimator $\delta_c = X - \frac{p-2}{\|X-c\|^2}(X-c)$
4. Following the previous proposition, the James-Stein estimator with any c is still inadmissible and dominated by $\delta_c^+ = X - \min\{1, \frac{p-2}{\|X-c\|^2}\}(X-c)$.

Question 1

1. Let X be an observation from the Poisson distribution with unknown mean $\theta > 0$. Consider the estimation of θ under the squared error loss.
- (i) Show that $\sup_{\theta} R_T(\theta) = \infty$ for any estimator $T = T(X)$, where $R_T(\theta)$ is the risk of T .
- (ii) Let $\mathfrak{S} = \{aX + b : a \in \mathcal{R}, b \in \mathcal{R}\}$. Show that 0 is an admissible estimator of θ within \mathfrak{S} .

Solution:

(i) When the gamma distribution with shape parameter α and scale parameter γ is used as the prior for θ , the Bayes estimator is $\delta(X) = \gamma(X + \alpha)/(\gamma + 1)$ with Bayes risk $r_\delta = \alpha\gamma^2/(\gamma + 1)$. Then, for any estimator T ,

$$\sup_{\theta > 0} R_T(\theta) \geq r_\delta = \frac{\alpha\gamma^2}{\gamma + 1} \rightarrow \infty$$

as $\gamma \rightarrow \infty$.

(ii) The risk of 0 is θ^2 . The risk of $aX + b$ is

$$a^2 \text{Var}(X) + [aE(X) + b - \theta]^2 = (a-1)^2\theta^2 + [2(a-1)b + a^2]\theta + b^2.$$

If 0 is inadmissible, then there are a and b such that

$$\theta^2 \geq (a-1)^2\theta^2 + [2(a-1)b + a^2]\theta + b^2$$

for all $\theta > 0$. Letting $\theta \rightarrow 0$, we obtain that $b = 0$. Then

$$\theta \geq (a-1)^2\theta + a^2$$

for all $\theta > 0$. Letting $\theta \rightarrow 0$ again, we conclude that $a = 0$. This shows that 0 is admissible within the class \mathfrak{S} .