

**first order linear**

$$\frac{dy}{dt} + p(t)y = q(t) \quad \mu(t) = e^{\int p(t) dt} \quad \frac{d}{dt}(\mu(t)y) = \mu(t)\frac{dy}{dt} + p(t)\mu(t)y \quad \mu(t)y = \int \mu(t)q(t) dt$$

$$\text{exact} \quad 0 = M(t, y) dt + N(t, y) dy \quad \frac{\partial M}{\partial y} = \frac{\partial N}{\partial t} \quad \int M(t, y) dt + \phi(y) = f(t, y)$$

$$\phi'(y) = N(x, y) - \frac{d}{dy} \left( \int M(t, y) dt \right) \quad f(t, y) = \int M(t, y) dt + \int \phi'(y) dy$$

Solution is  $f(t, y) = C$

$$\text{bernoulli} \quad \frac{dy}{dt} + p(t)y = q(t)y^n \quad \frac{1}{y^n} \frac{dy}{dt} + p(t)y^{1-n} = q(t)$$

$$w = y^{1-n} \quad \frac{dw}{dt} = (1-n) \frac{1}{y^n} \frac{dy}{dt} \quad \frac{dw}{dt} + (1-n)p(t)w = (1-n)q(t)$$

Solve as first order linear, then back substitute

**homogeneous**

$$M(t, y) dt + N(t, y) dy = 0 \quad M(xt, xy) + N(xt, xy) = x^n (M(t, y) + N(t, y))$$

$$dy = w dt + t dw \quad dt = w dy + y dw$$

Substitute with  $y = wt$  if  $N(t, y)$  is simpler and  $t = wy$  if  $M(t, y)$  is simpler. Solve as a separable equation

$$\text{population} \quad \text{growth and decay} \quad \text{Logistical equation}$$

$$y(t) = y_0 e^{kt} \quad y = \frac{ry_0}{ay_0 + (r - ay_0)e^{-rt}}$$

$$\text{Newton's law of cooling} \quad T(t) = (T_0 - T_s) e^{kt} + T_s$$

$$\text{Newton's laws of motion} \quad v = v_0 + at \quad s = v_0 t + \frac{1}{2} at^2 \quad v^2 = v_0^2 + 2as$$

Acceleration is  $a = g = 9.8\text{m/sec}^2 = 32\text{ft/sec}^2$  and position is  $s$  and velocity is  $v$ .

**reduction of order** given  $y'' + p(t)y' + q(t)y = 0$  and a known solution  $y_1$  then full solution is given by

$$y_s = c_1 y_1 + c_2 y_2 = c_1 y_1 + c_2 v(t) y_1 \quad v(t) = \int \frac{1}{y_1^2} e^{-\int p(t) dt} dt$$

**second order linear homogeneous with constant coefficient**

$$ay'' + by' + cy = 0 \rightarrow ar^2 + br + c = 0$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \quad y_s = \begin{cases} c_1 e^{r_1 t} + c_2 e^{r_2 t} & r_1 \neq r_2 \\ (c_1 + c_2 t) e^{rt} & r_1 = r_2 \\ e^{\alpha t} [c_1 \cos(\beta t) + c_2 \sin(\beta t)] & r = \alpha \pm \beta i \end{cases}$$

**method of undetermined coefficients** solution of  $ay'' + by' + cy = f(t)$  is  $y_s = y_h + y_p$  where  $y_h$  is solution to corresponding homogeneous equation

$$f(t) = t^m e^{\alpha t} \quad \text{or} \quad f(t) = t^m e^{\alpha t} \sin \beta t \quad \text{or} \quad f(t) = t^m e^{\alpha t} \cos \beta t$$

$$S = \{e^{\alpha t}, e^{\alpha t} t, e^{\alpha t} t^2, \dots, e^{\alpha t} t^m\} \quad S = \left\{ e^{\alpha t} \sin \beta t, e^{\alpha t} \cos \beta t, t e^{\alpha t} \sin \beta t, t e^{\alpha t} \cos \beta t, \right. \\ \left. t^2 e^{\alpha t} \sin \beta t, t^2 e^{\alpha t} \cos \beta t, \dots, t^m e^{\alpha t} \sin \beta t, t^m e^{\alpha t} \cos \beta t \right\}$$

if  $S_h \cap S_p \neq \emptyset$  then  $S_p \rightarrow t^n S_p$ . This will make  $y_h$  and  $y_p$  linearly independent. If  $f(t)$  has more than one term then  $S_p$  is the union of the solution set for each term. Throw out constant coefficients in  $f(t)$

$$y_p = a_1 S_p[1] + a_2 S_p[2] + \dots + a_m S_p[m] \quad \text{Solve for all } a_n \text{ and we are done.}$$

**variation of parameters**  $y'' + p(t)y' + q(t)y = f(t)$  for any  $f(t)$ . More general than undetermined coefficients.  $W$  refers to the Wronskian. Need to be able to find homogeneous solution for this to work.

$$y_s = y_h + y_p \quad y_h = c_1 y_1 + c_2 y_2 \quad y_p = u_1 y_1 + u_2 y_2 \quad u_1' = -\frac{y_2 f}{W} \quad u_2' = \frac{y_1 f}{W}$$

$$\text{cauchy-euler} \quad ax^2 \frac{d^2 y}{dx^2} + bx \frac{dy}{dx} + cy = f(x) \quad x = e^t \quad t = \ln x \quad x^2 \frac{d^2 y}{dx^2} = \frac{d^2 y}{dt^2} - \frac{dy}{dt} \quad x \frac{dy}{dx} = \frac{dy}{dt}$$

**spring motion** initial position is  $\alpha$  initial velocity is  $\beta$  stretch is  $s$   $g = 32 \text{ ft/s}^2$  force(weight) is lb or N, mass is slugs or kg, length is ft or m,  $k$  is lb/ft or N/m and time is s. down is positive, up is negative

$$m \frac{d^2 x}{dt^2} + kx = 0 \quad x(0) = \alpha \quad x'(0) = \beta \quad x(t) = \alpha \cos \omega t + \frac{\beta}{\omega} \sin \omega t \quad \omega = \sqrt{\frac{k}{m}} \quad F = ks \quad F = mg = ma$$

**Laplace**

$$\begin{aligned} \mathcal{L}\{f(t)\} &= \int_0^t e^{-st} f(t) dt & \mathcal{L}\{1\} &= \frac{1}{s} & \mathcal{L}\{e^{at}\} &= \frac{1}{s-a} & \mathcal{L}\{\sin kt\} &= \frac{k}{s^2 + k^2} \\ \mathcal{L}\{\cos kt\} &= \frac{s}{s^2 + k^2} & \mathcal{L}\{t^n\} &= \frac{n!}{s^{n+1}} & \mathcal{L}\{e^{at} f(t)\} &= F(s-a) & \mathcal{L}\{t^n f(t)\} &= (-1)^n \frac{d^n F(s)}{ds^n} \end{aligned}$$

$$\mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0) \quad \mathcal{L}\{f''(t)\} = s^2 \mathcal{L}\{f(t)\} - sf(0) - f'(0)$$

$$\mathcal{L}\{f'''(t)\} = s^3 \mathcal{L}\{f(t)\} - s^2 f(0) - sf'(0) - f''(0) \quad f(t) * g(t) = \int_0^t f(t-v)g(v) dv$$

$$\mathcal{L}\{f(t) * g(t)\} = \mathcal{L}\{f(t)\} \mathcal{L}\{g(t)\}$$

**matrice**

$$\begin{aligned} \mathbf{A}\mathbf{v} &= \lambda \mathbf{v} & (-1)^n \det(\mathbf{A} - \lambda \mathbf{I}) &= 0 & (\mathbf{A} - \lambda_n \mathbf{I})\mathbf{v}_n &= 0 & \lambda_{1,2} &= \alpha \pm \beta i, \beta \neq 0 & \mathbf{v}_{1,2} &= \mathbf{a} \pm \beta \mathbf{b} \\ \mathbf{X}' &= \mathbf{A}\mathbf{X} \rightarrow \mathbf{X}(t) &= c_1 \mathbf{v}_1 e^{\lambda_1 t} + c_2 \mathbf{v}_2 e^{\lambda_2 t} + \dots + c_n \mathbf{v}_n e^{\lambda_n t} & \mathbf{X}_{1,2} &= e^{\alpha t} (\mathbf{a} \cos \beta t \pm \mathbf{b} \sin \beta t) \end{aligned}$$

**trigonometric identities**

$$\begin{aligned} \sin x &= \frac{1}{\csc x} & \sin(-x) &= -\sin x & \cos(-x) &= \cos x \\ \sin(u \pm v) &= \sin u \cos v \pm \cos u \sin v & \cos(u \pm v) &= \cos u \cos v \mp \sin u \sin v & \sin 2u &= 2 \sin u \cos u \\ \cos 2u &= \cos^2 u - \sin^2 u & \cos 2u &= 2 \cos^2 u - 1 & \cos 2u &= 1 - 2 \sin^2 u \\ \sin^2 u &= \frac{1 - \cos 2u}{2} & \cos^2 u &= \frac{1 + \cos 2u}{2} \end{aligned}$$

$$\begin{aligned} \sin u \pm \sin v &= 2 \sin \left( \frac{u \pm v}{2} \right) \cos \left( \frac{u \mp v}{2} \right) & \cos u + \cos v &= 2 \cos \left( \frac{u+v}{2} \right) \cos \left( \frac{u-v}{2} \right) \\ \cos u - \cos v &= -2 \sin \left( \frac{u+v}{2} \right) \sin \left( \frac{u-v}{2} \right) & \sin u \sin v &= \frac{1}{2} [\cos(u-v) - \cos(u+v)] \\ \cos u \cos v &= \frac{1}{2} [\cos(u-v) + \cos(u+v)] & \sin u \cos v &= \frac{1}{2} [\sin(u+v) + \sin(u-v)] \end{aligned}$$

**separable**

$$g(y) \, dy = f(t) \, dt$$

$$g(y)y' = f(t)$$

$$\int g(y) \, dy = \int f(t) \, dt$$

**integration rules**

$$\int e^{au} \sin(bu) \, du = e^{au} \frac{a \sin(bu) - b \cos(bu)}{b^2 + a^2}$$

$$\int e^{au} \cos(bu) \, du = e^{au} \frac{b \sin(bu) + a \cos(bu)}{b^2 + a^2}$$

**Wronskian**

$$W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_2 y_1'$$

$y_1$  and  $y_2$  are linearly independent if  $W \neq 0$