

1. Let

$$B = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \end{pmatrix} \right\} \text{ and } C = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

be bases of \mathbb{R}^2 and \mathbb{R}^3 (resp). Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be given by

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + 2y \\ -x \\ y \end{pmatrix}$$

and let

$$\mathbf{x} = \begin{pmatrix} -7 \\ 7 \end{pmatrix}$$

(a) Find the image $T(\mathbf{x})$ of the vector \mathbf{x} under the action of T .

$$T(\mathbf{x}) = \begin{pmatrix} 7 \\ 7 \\ 7 \end{pmatrix}$$

(b) Find the change of basis matrices $P = M(1_{\mathbb{R}^2}, S_2, B)$ and $Q = M(1_{\mathbb{R}^3}, S_3, C)$.

$$P = \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}^{-1} \Rightarrow \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & -1 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & -7 & -2 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{cc|cc} 1 & 0 & 1/7 & 3/7 \\ 0 & 1 & 2/7 & -1/7 \end{array} \right]$$

$$Q = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \Rightarrow \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right]$$

$$P = \frac{1}{7} \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} \quad Q = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

(c) Use part (b) to compute $[\mathbf{x}]_B$ and $[T(\mathbf{x})]_C$.

$$[\mathbf{x}]_B = P\mathbf{x} = \frac{1}{7} \begin{pmatrix} 14 \\ -21 \end{pmatrix} = \begin{pmatrix} 2 \\ -3 \end{pmatrix}$$

$$[T(\mathbf{x})]_C = QT(\mathbf{x}) = \begin{pmatrix} 0 \\ 0 \\ 7 \end{pmatrix}$$

(d) Find $M(T, B, C)$ using the method of Example 7.

$$\begin{aligned} T \begin{pmatrix} 1 \\ 2 \end{pmatrix} &= \begin{pmatrix} 5 \\ -1 \\ 2 \end{pmatrix} = c_{11} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_{21} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c_{31} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ &= 6 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + -3 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ T \begin{pmatrix} 3 \\ -1 \end{pmatrix} &= \begin{pmatrix} 1 \\ -3 \\ -1 \end{pmatrix} = c_{12} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_{22} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c_{32} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ &= 4 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + -2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + -1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ M(T, B, C) &= \begin{bmatrix} 6 & 4 \\ -3 & -2 \\ 2 & -1 \end{bmatrix} \end{aligned}$$

(e) Find $M(T, B, C)$ using the method of example 10.

$$M(T, B, C) = QA_T P^{-1} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 6 & 4 \\ -3 & -2 \\ 2 & -1 \end{bmatrix}$$

(f) Check our answer in part (c) by verifying that $M(T, B, C)[\mathbf{x}]_B = [T(\mathbf{x})]_C$.

$$\begin{bmatrix} 6 & 4 \\ -3 & -2 \\ 2 & -1 \end{bmatrix} \begin{pmatrix} 2 \\ -3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 7 \end{pmatrix}$$

2. Let

$$B = \left\{ \begin{pmatrix} -3 \\ 2 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \text{ and } C = \left\{ \begin{pmatrix} -1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ -2 \end{pmatrix} \right\}$$

be bases of \mathbb{R}^2 . If

$$M(T, B, B) = \begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix}$$

find $M(T, B, B)$.

Maybe we are meant to find $M(T, C, C)$?

$$\begin{aligned} M(T, B, B) &= \begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix} \\ &= \begin{bmatrix} -3 & 4 \\ 2 & -2 \end{bmatrix}^{-1} T \begin{bmatrix} -3 & 4 \\ 2 & -2 \end{bmatrix} \\ T &= \begin{bmatrix} -3 & 4 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix} \begin{bmatrix} -3 & 4 \\ 2 & -2 \end{bmatrix}^{-1} \\ T &= \begin{bmatrix} -3 & 4 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & \frac{3}{2} \end{bmatrix} \\ M(T, C, C) &= \begin{bmatrix} -1 & 2 \\ 2 & -2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -\frac{3}{2} \\ 2 & 4 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 2 & -2 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix} \end{aligned}$$

3. Prove Theorem 11. Let B_1, B_2 be bases for \mathbb{R}^n and let C_1, C_2 be bases for \mathbb{R}^m . If $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation, then $\text{rank}(M(T, B_1, C_1)) = \text{rank}(M(T, B_2, C_2))$.

Now $M(T, B_1, C_1)[\mathbf{x}]_{B_1} = [T(\mathbf{x})]_{C_1}$ and $M(T, B_2, C_2)[\mathbf{x}]_{B_2} = [T(\mathbf{x})]_{C_2}$. But $[T(\mathbf{x})]_{C_1}$ and $[T(\mathbf{x})]_{C_2}$

Let $B_1 = \{\mathbf{v}_{11}, \dots, \mathbf{v}_{1n}\}$ and $B_2 = \{\mathbf{v}_{21}, \dots, \mathbf{v}_{2n}\}$ while $C_1 = \{\mathbf{w}_{11}, \dots, \mathbf{w}_{1m}\}$ and $C_2 = \{\mathbf{w}_{21}, \dots, \mathbf{w}_{2m}\}$

4. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation and suppose that $V \leq \mathbb{R}^n$ is invariant under T (that is $T(V) \subseteq V$). Prove that there exists a basis B such that

$$M(T, B, B) = \begin{bmatrix} A & B \\ 0 & C \end{bmatrix}$$

where A is a $\dim(V) \times \dim(V)$ matrix.

5. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation of $\text{rank}(T) = r$. Prove there exist bases B, C of $\mathbb{R}^n, \mathbb{R}^m$ (resp) such that

$$M(T, B, C) = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$$

Do you see how this establishes the Rank Nullity Theorem?

6. Prove that \sim is an equivalence relation on \mathcal{M}_n

If we have some matrix A then $A = I_n A I_n = I_n A I_n^{-1}$ and so we have reflexivity. Now if $B = P A P^{-1}$ then $P^{-1} B P = A$ and so if $A \sim B$ then $B \sim A$. Now if $C = Q B Q^{-1}$ and $B = P A P^{-1}$ then $C = (Q P) A (P^{-1} Q^{-1})$. Because $Q P$ and $Q^{-1} P^{-1}$ are inverses, we know that $C \sim A$. Thus we have an equivalence relation.

7. Prove that $A \sim A'$ if and only if A and A' represent the same linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$. That is, $A \sim A'$ if and only if $A = M(T, B, B)$ and $A' = M(T, B', B')$ for some bases B, B' of \mathbb{R}^n .

If $A = M(T, B, B)$ then $A = M(I_n, E_n, B) M(T, E_n, E_n) M(I_n, E_n, B)^{-1}$. And $A' = M(T, B', B') = M(I_n, E_n, B') M(T, E_n, E_n) M(I_n, E_n, B')^{-1}$. Thus $A \sim M(T, E_n, E_n) \sim A'$ and so by transitivity we have $A \sim A'$.

If $A \sim A'$ then

8. Prove that if $A \sim B$, then $A^{-1} \sim B^{-1}$ and $A^T \sim B^T$.

If $A \sim B$ then $A = P B P^{-1}$ for some P . Now $P B P^{-1} P B^{-1} P^{-1} = I$ and so $A^{-1} = P B^{-1} P^{-1}$. Thus $A^{-1} \sim B^{-1}$.

If $A \sim B$ then $A = P B P^{-1}$. Taking the transpose of both sides we have $A^T = (P B P^{-1})^T = (P^{-1})^T (P B)^T = (P^{-1})^T B^T P^T$ and so $A^T \sim B^T$.