separable

$$g(y) dy = f(t) dt$$

$$\int g(y) dy = \int f(t) dt$$

first order linear

$$\frac{\mathrm{d}y}{\mathrm{d}t} + p(t)y = q(t) \qquad \qquad \mu(t) = e^{\int p(t) \, \mathrm{d}t}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} (\mu(t)y) = \mu(t) \frac{\mathrm{d}y}{\mathrm{d}t} + p(t)\mu(t)y \qquad \qquad \mu(t)y = \int \mu(t)q(t) \, \mathrm{d}t$$

exact

$$M(t,y) dt + N(t,y) dy = 0$$

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial t}$$

$$\int M(t,y) dt + \phi(y) = f(t,y)$$

$$\phi'(y) = N(x,y) - \frac{d}{dy} \left(\int M(t,y) dt \right)$$

$$\int M(t,y) dt + \int \phi'(y) dy = f(t,y)$$

Solution is f(t, y) = C

bernoulli

$$\frac{\mathrm{d}y}{\mathrm{d}t} + p(t)y = q(t)y^n \qquad \qquad \frac{1}{y^n} \frac{\mathrm{d}y}{\mathrm{d}t} + p(t)y^{1-n} = q(t)$$

$$w = y^{1-n} \qquad \qquad \frac{\mathrm{d}w}{\mathrm{d}t} = (1-n)\frac{1}{y^n} \frac{\mathrm{d}y}{\mathrm{d}t}$$

$$\frac{\mathrm{d}w}{\mathrm{d}t} + (1-n)p(t)w = (1-n)q(t)$$

Solve as first order linear, then back substitute

homogeneous

$$M(t,y) dt + N(t,y) dy = 0$$

$$dy = w dt + t dw$$

$$M(xt,xy) + N(xt,xy) = x^n (M(t,y) + N(t,y))$$

$$dt = w dy + y dw$$

Substitute with y = wt if N(t, y) is simpler and t = wy if M(t, y) is simpler. Solve as a separable equation

population

growth and decay Logistical equation
$$y(t)=y_0e^{kt} \qquad \qquad y=\frac{ry_0}{ay_0+(r-ay_0)e^{-rt}}$$

Newton's law of cooling

$$T(t) = (T_0 - T_s)e^{kt} + T_s$$

Newton's laws of motion

Acceleration is $a = g = 9.8 \text{m/sec}^2 = 32 \text{ft/sec}^2$ and position is s and velocity is v.

$$v = v_0 + at$$

$$s = v_0 t + \frac{1}{2}at^2$$

$$v^2 = v_0^2 + 2as$$

trigonometric identities

$$\sin x = \frac{1}{\csc x} \qquad \sin(-x) = -\sin x \qquad \cos(-x) = \cos x$$

$$\sin(u \pm v) = \sin u \cos v \pm \cos u \sin v \qquad \cos(u \pm v) = \cos u \cos v \mp \sin u \sin v \qquad \sin 2u = 2\sin u \cos u$$

$$\cos 2u = \cos^2 u - \sin^2 u \qquad \cos 2u = 2\cos^2 u - 1 \qquad \cos 2u = 1 - 2\sin^2 u$$

$$\sin^2 u = \frac{1 - \cos 2u}{2} \qquad \cos^2 u = \frac{1 + \cos 2u}{2}$$

$$\sin u \pm \sin(v) = 2\sin\left(\frac{u \pm v}{2}\right)\cos\left(\frac{u \mp v}{2}\right) \qquad \cos u + \cos v = 2\cos\left(\frac{u + v}{2}\right)\cos\left(\frac{u - v}{2}\right)$$

$$\cos u - \cos v = -2\sin\left(\frac{u + v}{2}\right)\sin\left(\frac{u - v}{2}\right) \qquad \sin u \sin v = \frac{1}{2}[\cos(u - v) - \cos(u + v)]$$

$$\cos u \cos v = \frac{1}{2}[\cos(u - v) + \cos(u + v)] \qquad \sin u \cos v = \frac{1}{2}[\sin(u + v) + \sin(u - v)]$$

integration rules

$$\int e^{au} \sin(bu) du = e^{au} \frac{a \sin(bu) - b \cos(bu)}{b^2 + a^2} \qquad \int e^{au} \cos(bu) du = e^{au} \frac{b \sin(bu) + a \cos(bu)}{b^2 + a^2}$$

Wronskian

$$W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_2 y_1'$$

 y_1 and y_2 are linearly independent if $W \neq 0$

reduction of order

given y'' + p(t)y' + q(t)y = 0 and a known solution y_1 then full solution is given by

$$y_s = c_1 y_1 + c_2 y_2 = c_1 y_1 + c_2 v(t) y_1$$

$$v(t) = \int \frac{1}{y_1^2} e^{-\int p(t) dt} dt$$

second order linear homogeneous with constant coefficient

$$ay'' + by' + cy = 0 \to ar^2 + br + c = 0$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y_s = \begin{cases} c_1 e^{r_1 t} + c_2 e^{r_2 t} & r_1 \neq r_2 \\ (c_1 + c_2 t) e^{rt} & r_1 = r_2 \\ e^{\alpha t} \left[c_1 \cos(\beta t) + c_2 \sin(\beta t) \right] & r = \alpha \pm \beta i \end{cases}$$

method of undetermined coefficients

solution of ay'' + by' + cy = f(t) is $y_s = y_h + y_p$ where y_h is solution to corresponding homogeneous equation

$$f(t) = t^m e^{\alpha t} \qquad \text{or} \quad f(t) = t^m e^{\alpha t} \sin \beta t \quad \text{or} \quad f(t) = t^m e^{\alpha t} \cos \beta t$$

$$S = \left\{ e^{\alpha t}, e^{\alpha t}t, e^{\alpha t}t^2, ..., e^{\alpha t}t^m \right\} \qquad S = \left\{ e^{\alpha t} \sin \beta t, e^{\alpha t} \cos \beta t, te^{\alpha t} \sin \beta t, te^{\alpha t} \cos \beta t, \\ t^2 e^{\alpha t} \sin \beta t, t^2 e^{\alpha t} \cos \beta t, ..., t^m e^{\alpha t} \sin \beta t, t^m e^{\alpha t} \cos \beta t \right\}$$

if $S_h \cap S_p \neq \emptyset$ then $S_p \to t^n S_p$. This will make y_h and y_p linearly independent. If f(t) has more than one term then S_p is the union of the solution set for each term. Throw out constant coefficients in f(t)

$$y_p = a_1 S_p[1] + a_2 S_p[2] + \dots + a_m S_p[m]$$

Solve for all a_n and we are done.

variation of parameters

y'' + p(t)y' + q(t)y = f(t) for any f(t). More general than undetermined coefficients. W refers to the Wronskian. Need to be able to find homogeneous solution for this to work.

$$y_s = y_h + y_p$$
 $y_h = c_1 y_1 + c_2 y_2$ $y_p = u_1 y_1 + u_2 y_2$ $u_1' = -\frac{y_2 f}{W}$ $u_2' = \frac{y_1 f}{W}$

cauchy-euler

$$ax^{2}\frac{d^{2}y}{dx^{2}} + bx\frac{dy}{dx} + cy = f(x) \qquad \text{or} \qquad ax^{2}y'' + bxy' + cy = f(x)$$

$$x = e^{t} \qquad t = \ln x \qquad x^{2}\frac{d^{2}y}{dx^{2}} = \frac{d^{2}y}{dt^{2}} - \frac{dy}{dt} \qquad x\frac{dy}{dx} = \frac{dy}{dt}$$

spring motion

$$m\frac{\mathrm{d}^2 x}{\mathrm{d}t^2} + kx = 0$$
 $x(0) = \alpha$ $x'(0) = \beta$ $x(t) = \alpha \cos \omega t + \frac{\beta}{\omega} \sin \omega t$ $\omega = \sqrt{\frac{k}{m}}$ $F = ks$ $F = mg = ma$

initial position is α initial velocity is β stretch is $g = 32ft/s^2$ force(weight) is lb or N, mass is slugs or kg, length is ft or m, k is lb/ft or N/m and time is s. down is positive, up is negative

Laplace

$$\mathcal{L}\{f(t)\} = \int_{0}^{t} e^{-st} f(t) dt \qquad \mathcal{L}\{1\} = \frac{1}{s} \qquad \mathcal{L}\{e^{at}\} = \frac{1}{s-a} \qquad \mathcal{L}\{\sin kt\} = \frac{k}{s^{2}+k^{2}}$$

$$\mathcal{L}\{\cos kt\} = \frac{s}{s^{2}+k^{2}} \qquad \mathcal{L}\{t^{n}\} = \frac{n!}{s^{n+1}} \qquad \mathcal{L}\{e^{at}f(t)\} = F(s-a) \qquad \mathcal{L}\{t^{n}f(t)\} = (-1)^{n} \frac{d^{n}F(s)}{ds^{n}}$$

$$\mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0) \qquad \qquad \mathcal{L}\{f''(t)\} = s^{2}\mathcal{L}\{f(t)\} - sf(0) - f'(0)$$

$$\mathcal{L}\{f'''(t)\} = s^{3}\mathcal{L}\{f(t)\} - s^{2}f(0) - sf'(0) - f''(0) \qquad f(t) * g(t) = \int_{0}^{t} f(t-v)g(v) dv$$

$$\mathcal{L}\{f(t) * g(t)\} = \mathcal{L}\{f(t)\}\mathcal{L}\{g(t)\}$$

matrice

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{v} \quad \det(\mathbf{A} - \lambda \mathbf{I}) = 0 \quad (\mathbf{A} - \lambda_n \mathbf{I})\mathbf{v}_n = 0 \quad \mathbf{X}' = \mathbf{A}\mathbf{X} \to \mathbf{X}(t) = c_1 \mathbf{v}_1 e^{\lambda_1 t} + c_2 \mathbf{v}_2 e^{\lambda_2 t} + \cdots + c_n \mathbf{v}_n e^{\lambda_n t}$$