Jon Allen HW 03

$$u_t = \alpha^2 u_{xx} \qquad 0 < x < 1 \qquad 0 < t < \infty$$

$$u(0,t) = 0 \qquad u_x(1,t) = 1 \qquad u(x,0) = \sin(\pi x)$$

$$u_t = 0 = \alpha^2 u_{xx} \qquad \int 0 \, \mathrm{d}x = \int \alpha^2 u_{xx} \, \mathrm{d}x \qquad c_1 = \alpha^2 u_x$$

$$\int c_1 \, \mathrm{d}x = \int \alpha^2 u_x \, \mathrm{d}x \qquad c_1 x + c_2 = \alpha^2 U(x) \qquad U(x) = \frac{c_1}{\alpha^2} x + \frac{c_2}{\alpha^2}$$

And simplifying the constants

$$U(x) = c_1 x + c_2$$
  $U(0) = 0 = c_2$   
 $U(x) = c_1 x$   $U'(x) = c_1$   
 $U'(1) = 1 = c_1$   $U(x) = x$ 

A steady state seems plausible to me. We could interpret this math as a laterally insulated rod with the temperature of one end held at 0° and the other receiving a constant flow of heat. At some point it will stabilize to where the end being held at 0° will be cooling at the same rate that the other end is being heated. And in fact that's what we find with the math, because U(x) = x leads to U'(x) = 1.