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## Housekeeping

```
clear all; close all; clc;

%{

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%}

%create loop to change theta value
```

## Part 1: Generating training data

```
%initializing function
f = @(x, thet) 1./( 1 + exp(-thet .* x));
n = 7;

%vector with n evenly spaced points on [-5,5] and initializing theta
to
% one
theta = 1;
x_train = linspace(-5, 5, n);
y_train1 = f(x_train, theta);
y_train1 = y_train1.';

theta = 10;
y_train10 = f(x_train, theta);
y_train10 = y_train10.';
```

## Part 2: Training the model

```
%p(x) = c(1) * x^5 + c(2) *x ^
```

---

```
%create vandermonde matrix, theta = 1
%initialize
V1 = zeros(n,n);
for i = 1:n
    V1(i,:) = x_train(i);
end

%raise elements to power
for i = 0:n-1
    V1(:, i + 1) = V1(:, i + 1).^i;
end

%determine cond number
condition_V1 = cond(V1);
if(condition_V1 <= eps)
    error('Matrix is ill conditioned')
end

%create vandermonde matrix, theta = 10
%initialize
V10 = zeros(n,n);
for i = 1:n
    V10(i,:) = x_train(i);
end
%raise elements to power
for i = 0:n-1
    V10(:, i + 1) = V10(:, i + 1).^i;
end

%determine cond number
condition_V10 = cond(V10);
if(condition_V10 <= eps)
    error('Matrix is ill conditioned')
end

%use code from HW5 to solve for coefficients, theta = 1
theta = 1;
c_theta1 = LU_or_Chol(V1, y_train1);
c_theta1 = flip(c_theta1);

%initialize new grid space for results
x_part2 = linspace(-5, 5, 1000);
y_f1 = f(x_part2, theta);
y_p1 = polyval(c_theta1, x_part2);

%use code from HW5 to solve for coefficients, theta = 10
theta = 10;
c_theta10 = LU_or_Chol(V10, y_train10);
c_theta10 = flip(c_theta10);

y_f10 = f(x_part2, theta);
y_p10 = polyval(c_theta10, x_part2);
```

---

## Part 3: Generating Testing Data

```
%new vector with 101 evenly spacedd points in [-5, 5], x'  
x_part3 = linspace(-5, 5, 101);  
  
%compute y_i' = f_theta(x_i'), theta = 1  
theta = 1;  
y_part31 = f(x_part3, theta);  
  
%compute the mean of y_i'  
mean_theta1 = mean(y_part31, 'all');  
  
%compute the standard deviation of y_i'  
STD_theta1 = std(y_part31);  
  
%compute y_i' = f_theta(x_i'), theta = 10  
theta = 10;  
y_part310 = f(x_part3, theta);  
  
%compute the mean of y_i'  
mean_theta10 = mean(y_part310, 'all');  
  
%compute the standard deviation of y_i'  
STD_theta10 = std(y_part310);
```

## Part 4: Computing testing error

```
%evaluate polynomial, theta = 1  
p_error1 = polyval(c_theta1, x_part3);  
  
abs_error1 = max( abs(y_part31 - p_error1)./abs(y_part31) );  
  
%evaluate polynomial, theta = 10  
p_error10 = polyval(c_theta10, x_part3);  
  
abs_error10 = max( abs(y_part310 - p_error10)./abs(y_part310) );
```

## Extra Credit

```
for n = 8:15
```

## Part 3: Generating Testing Data

```
%new vector with 101 evenly spacedd points in [-5, 5], x'  
x_part3extra = linspace(-5, 5, n);  
  
%compute y_i' = f_theta(x_i'), theta = 1  
theta = 1;  
y_part31extra = f(x_part3extra, theta);
```

---

```

%compute y_i' = f_theta(x_i'), theta = 10
theta = 10;
y_part310extra = f(x_part3extra, theta);

```

## Part 4: Computing testing error

```

%evaluate polynomial, theta = 1
p_errorextra = polyval(c_theta1, x_part3extra);

abs_error1extra(n - 7) = max( abs(y_part31extra - p_errorextra)./
abs(y_part31extra) );

%evaluate polynomial, theta = 10
p_error10extra = polyval(c_theta10, x_part3extra);

abs_error10extra(n - 7) = max( abs(y_part310extra -
p_error10extra)./abs(y_part310extra) );

end

```

## Plotting

```

n = 7;
%Part 1, theta = 1
fprintf('\n-----\n\n')
fprintf('Part 1: Generating training data')
fprintf('\n-----\n\n')
fprintf('theta = 1\n')
fprintf('      xi      |      f_theta(xi)\n')
fprintf('-----\n')
for i = 1:n
    fprintf(' %0.4f | %0.4f \n', x_train(i), y_train1(i));
end
fprintf('\n');

%Part 1, theta = 10
fprintf('theta = 10\n')
fprintf('      xi      |      f_theta(xi) \n')
fprintf('-----\n')
for i = 1:n
    fprintf(' %0.4f | %0.4e \n', x_train(i), y_train10(i));
end

%Part 2: plot of f_theta and p_p
%theta = 1
figure(1)
scatter(x_train, y_train1, 'Linewidth', 1.25);
hold on;
plot(x_part2, y_p1, 'r', 'Linewidth', 1.5)

```

---

```

plot(x_part2, y_f1, 'k--', 'Linewidth', 1.5);
grid on;
xlabel('$\mathbf{x_i}$','Interpreter','latex');
legend('$(\mathbf{x_i},y_i)$', '$p_6(\mathbf{x_i})$', '$f_{\theta}(\mathbf{x_i})$',
    'Interpreter','latex', 'Location', 'southeast');
title('$f_{\theta}(\mathbf{x_i}), \theta = 1$', 'Interpreter','latex')
hold off;

%theta = 10
figure(2)
scatter(x_train, y_train10, 'Linewidth', 1.25);
hold on;
plot(x_part2, y_p10, 'r', 'Linewidth', 1.5)
plot(x_part2, y_f10, 'k--', 'Linewidth', 1.5);
grid on;
xlabel('$\mathbf{x_i}$','Interpreter','latex');
legend('$(\mathbf{x_i},y_i)$', '$p_6(\mathbf{x_i})$', '$f_{\theta}(\mathbf{x_i})$',
    'Interpreter','latex', 'Location', 'southeast');
title('$f_{\theta}(\mathbf{x_i}), \theta = 10$', 'Interpreter','latex')
hold off;

%Part 2: table of coefficients
fprintf('\n-----\n')
fprintf('Part 2: Training the model')
fprintf('\n-----\n\n')

%theta = 1
fprintf('theta = 1\n')
fprintf('    Table of ci coefficients \n')
fprintf('-----\n')
for i = 1:n
    fprintf(' c%i = %0.3e \n', i-1 , c_theta1(i));
end

%theta = 10
fprintf('theta = 10\n')
fprintf('    Table of ci coefficients \n')
fprintf('-----\n')
for i = 1:n
    fprintf(' c%i = %0.3e \n', i - 1, c_theta10(i));
end

%Part 2: Assessment
fprintf('\nPart 2: Assessment: Although the vandermonde system is
    ill-conditioned (When Theta = 1),\n the approximation is adequate
    and i would consider accurate. The vandermonde system accurately
    approximates the function on the interval of -3.3333 to 3.3333 \n but
    loses accuracy towards the endpoints shown as a minor blow up but due
    to its shallow slope adding more equally points would increase the
    accuracy of the approximation. \n')

```

---

---

```

%Part 3:
fprintf('\n-----
\n')
fprintf('Part 3: Generating testing data')
fprintf('\n-----
\n\n')

%theta = 1
fprintf('theta = 1\n')
fprintf(' Mean from the set of points y_i'', mean = %0.04f\n ',
    mean_theta1);
fprintf(' STD from the set of points y_i'', mean = %0.04f\n ',
    STD_theta1);

%theta = 10
fprintf('\ntheta = 10\n')
fprintf(' Mean from the set of points y_i'', mean = %0.04f\n ',
    mean_theta10);
fprintf(' STD from the set of points y_i'', mean = %0.04f\n ',
    STD_theta10);

%Part 4:
fprintf('\n-----
\n')
fprintf('Part 4: Computing the testing error')
fprintf('\n-----
\n\n')

%theta = 1
fprintf('theta = 1\n')
fprintf('Absolute testing error = %0.4e\n\n',abs_error1)

%theta = 10
fprintf('theta = 10\n')
fprintf('Absolute testing error = %0.4e\n\n',abs_error10)

%Part 4: approximation
fprintf('Part 4 Assessment: as stated in lecture, if xi are equally
    spaced the vandermonde system is ill conditioned. \n\n It is not
    a problem for the smooth function when theta = 1, but the error
    explodes when theta = 10 shown by the blown upn oscillations towards
    the end points which is a good example of the Runge''s Phenomenom,
    \n to fix problem for when theta = 10 we can use chebyshev points to
    increase the density of points towards the endpoints.')
fprintf(' to accurately depict the steep slope of the theta = 10
    function, i cant explain it well. but as theta increases, the harder
    it is to fit a higher degree polynomial to the function due to the
    increase of oscillations towards the endpoints');

%extra credit

```

---

*Part 1: Generating training data*

---

---

```

theta = 1
      xi      /      f_theta(xi)
-----
-5.0000 / 0.0067
-3.3333 / 0.0344
-1.6667 / 0.1589
 0.0000 / 0.5000
 1.6667 / 0.8411
 3.3333 / 0.9656
 5.0000 / 0.9933

```

```

theta = 10
      xi      /      f_theta(xi)
-----
-5.0000 / 1.9287e-22
-3.3333 / 3.3382e-15
-1.6667 / 5.7777e-08
 0.0000 / 5.0000e-01
 1.6667 / 1.0000e+00
 3.3333 / 1.0000e+00
 5.0000 / 1.0000e+00

```

---

## Part 2: Training the model

---

```

theta = 1
  Table of ci coefficients

```

```

-----
c0 = -9.344e-20
c1 = 2.182e-04
c2 = 4.514e-18
c3 = -1.083e-02
c4 = -5.224e-17
c5 = 2.331e-01
c6 = 5.000e-01

```

```

theta = 10
  Table of ci coefficients

```

```

-----
c0 = -3.453e-19
c1 = 6.480e-04
c2 = 1.464e-17
c3 = -2.700e-02
c4 = -1.500e-16
c5 = 3.700e-01
c6 = 5.000e-01

```

Part 2: Assessment: Although the vandermonde system is ill-conditioned (When Theta = 1), the approximation is adequate and i would consider accurate. The vandermonde system accurately approximates the function on the interval of -3.3333 to 3.3333

---

but loses accuracy towards the endpoints shown as a minor blow up but due to its shallow slope adding more equally points would increase the accuracy of the approximation.

-----  
Part 3: Generating testing data  
-----

theta = 1  
Mean from the set of points  $y_i'$ , mean = 0.5000  
STD from the set of points  $y_i'$ , mean = 0.3921

theta = 10  
Mean from the set of points  $y_i'$ , mean = 0.5000  
STD from the set of points  $y_i'$ , mean = 0.4924

-----  
Part 4: Computing the testing error  
-----

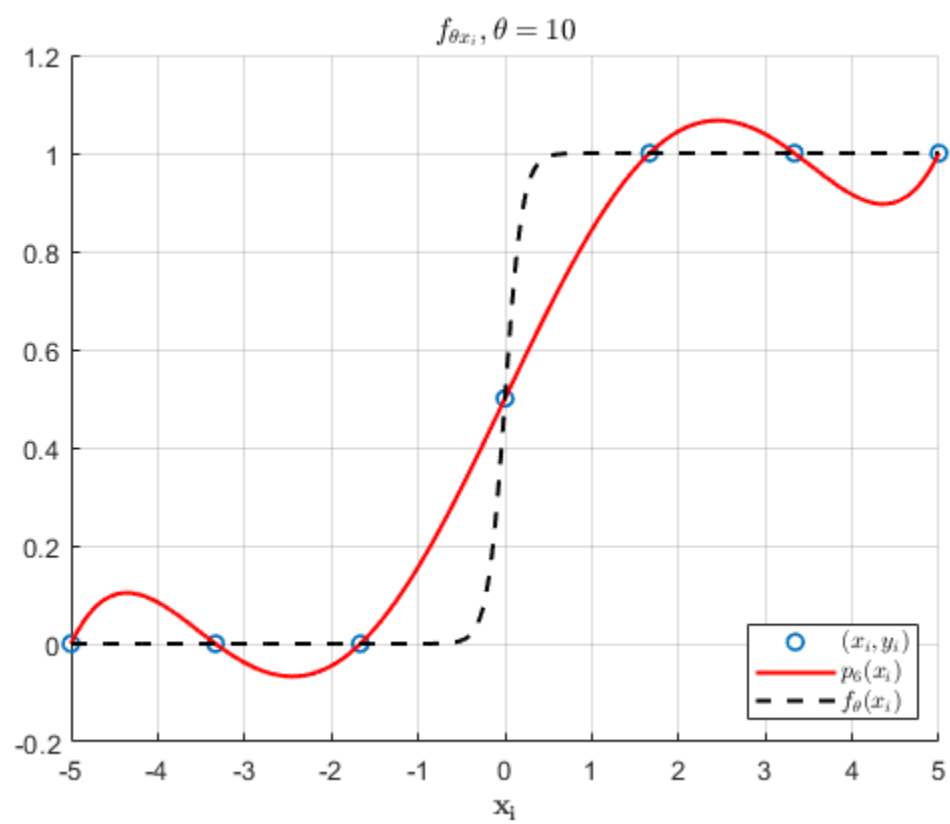
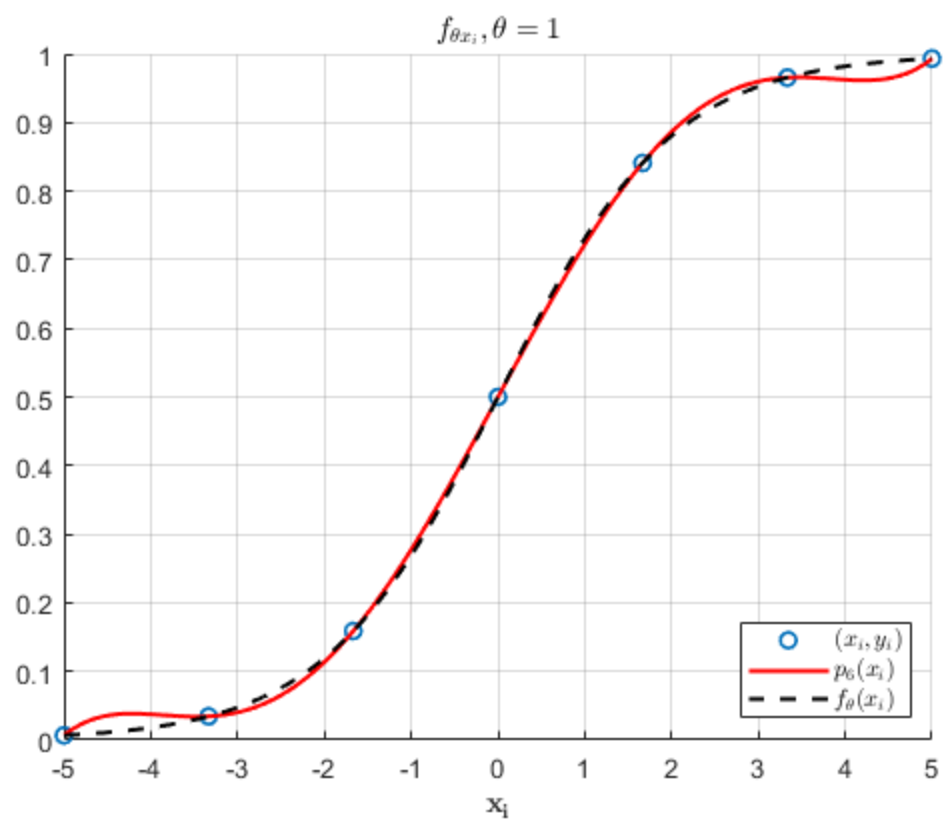
theta = 1  
Absolute testing error = 2.2898e+00

theta = 10  
Absolute testing error = 6.3101e+19

Part 4 Assessment: as stated in lecture, if  $x_i$  are equally spaced the vandermonde system is ill conditioned.

It is not a problem for the smooth function when  $\theta = 1$ , but the error explodes when  $\theta = 10$  shown by the blown up oscillations towards the end points which is a good example of the Runge's Phenomenon,  
to fix problem for when  $\theta = 10$  we can use chebyshev points to increase the density of points towards the endpoints. to accurately depict the steep slope of the  $\theta = 10$  function, i cant explain it well. but as  $\theta$  increases, the harder it is to fit a higher degree polynomial to the function due to the increase of oscillations towards the endpoints





---

## this was rushed my bad

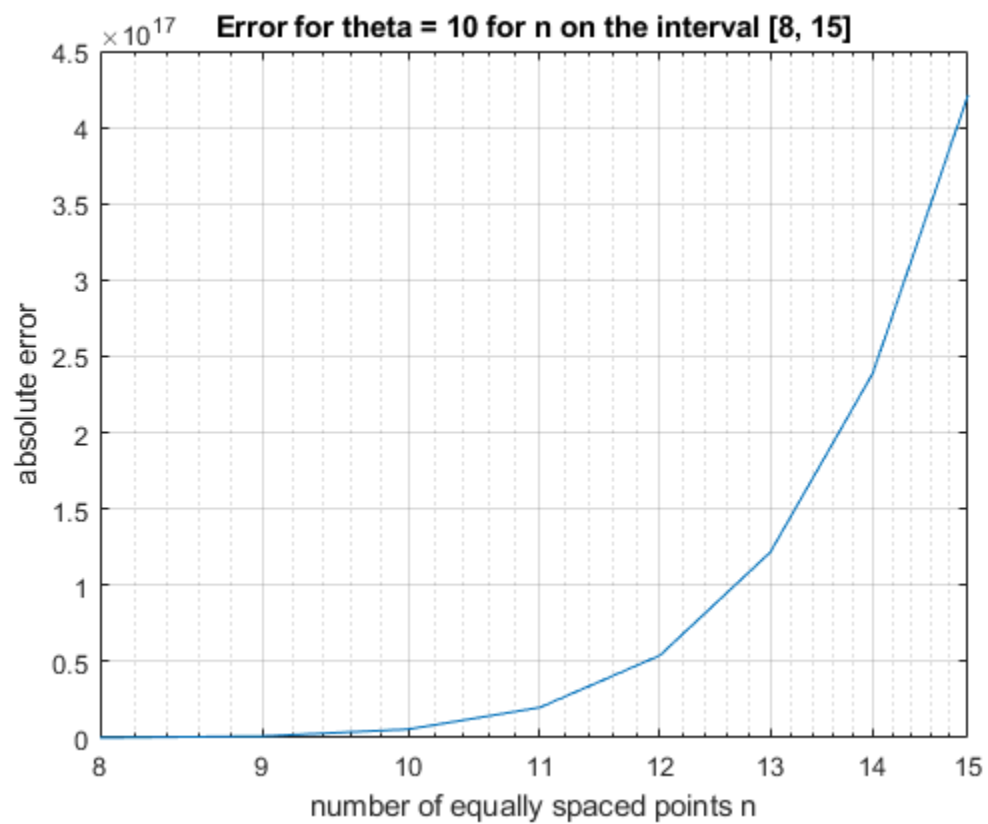
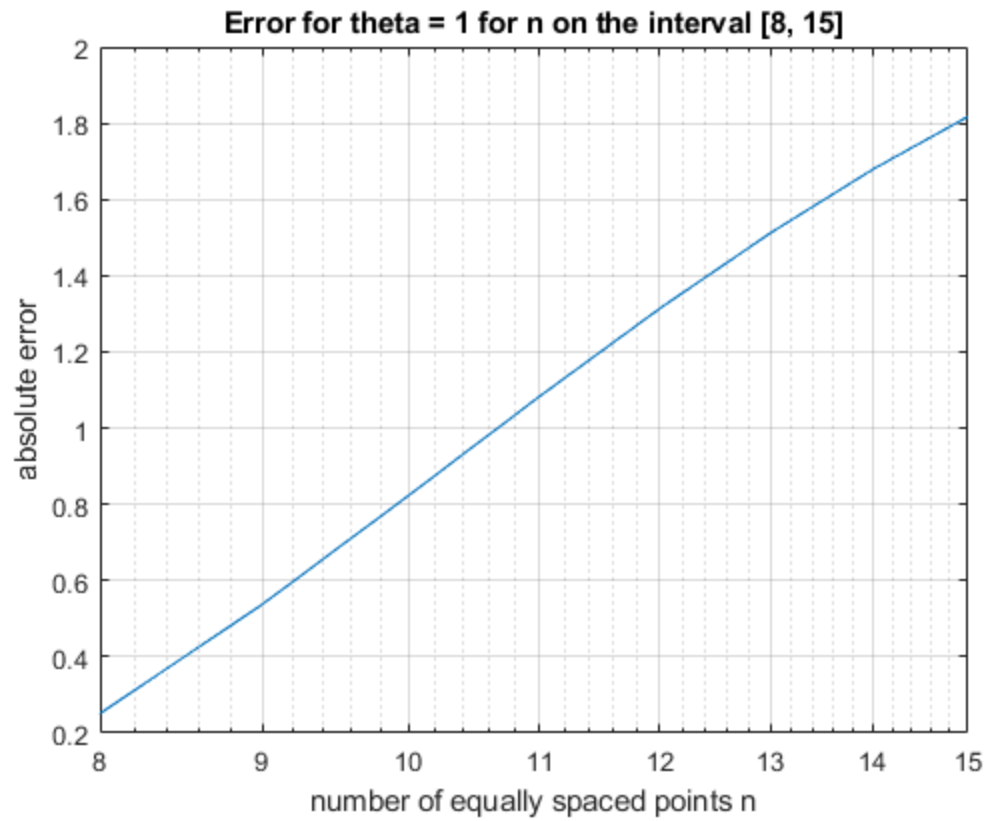
```
figure(3)
semilogx(8:15, abs_error1extra)
hold on;
grid on;
title('Error for theta = 1 for n on the interval [8, 15]')
xlabel('number of equally spaced points n')
ylabel('absolute error')
hold off;

figure(4)
semilogx(8:15, abs_error10extra)
hold on;
grid on;
title('Error for theta = 10 for n on the interval [8, 15]')
xlabel('number of equally spaced points n')
ylabel('absolute error')
hold off;

fprintf('\n-----\n')
fprintf('Extra Credit: ')
fprintf('\n-----\n\n')
fprintf('the assesment of this part was rushed last minute, but
  for the function when theta = 10  the plot does not shor the error
  converging but continuously increasing exponentially as n increasse
  due to the runge''s phenonenom, but looking at the error plot for
  when theta = 1, the error converges quadratically towards 2 as n
  increases')
```

-----  
*Extra Credit:*  
-----

*the assesment of this part was rushed last minute, but for the  
function when theta = 10 the plot does not shor the error converging  
but continuously increasing exponentially as n increasse due to the  
runge's phenonenom, but looking at the error plot for when theta = 1,  
the error converges quadratically towards 2 as n increases*



---

# Functions

```
%part 2

function [exe, chol_bool] = LU_or_Chol(mat, RHS)
%{
    Purpose: solves  $Ax = b$  using LU decomposition or cholesky
    factorization
    depending on whether the matrix is symmetric or not

    Inputs:
        mat: A matrix
        RHS: right hand side

    Outputs:
        exe: matrix of computed solution x
        chol_bool: boolean determining if LU decomposition or Cholesky
        factorization was used
%}

tf = issymmetric(mat);
chol_bool = false;
if(tf)
    d = eig(mat);
    chol_bool = all(d > 0);
end

if(chol_bool)
    %if matrix is positive definite use Cholesky factorization to
    solve
    %Ax = b
    R = chol(mat);
    exe = R \ (R' \ RHS);

else
    %if matrix is not positive definite use LU decomposition
    [L, U, P] = lu(mat);
    y = L \ (P * RHS);
    exe = U \ y;

end

end
```

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