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## Housekeeping

```
clear all; close all; clc
%{
     CSCI HW8 main script
     Author: Connor O'Reilly
     Date: 11/5/2021
     email: coor1752@colorado.edu
%}
```

## **Downloading and Storing data**

```
mat = readmatrix('C:\Users\corei\OneDrive\Documents\Classes
\CSCI_3656\mat1-2.txt');

%create cell array containing A matrices
%get size of A
size_mat = size(mat);

%initialize size
A_cell = cell(1 , size_mat(2));

%fill cell

for i = 1:size_mat(2)
    A_cell(i) = mat2cell( mat(: , 1 : i), size_mat(1), i );
end
```

#### Part 1

 $\mbox{\ensuremath{\$}}$  obatain size, rank and condition number for all  $\mbox{\ensuremath{A\_k}}$ 

```
%could make more efficient but low on time lol
%initialize
size_ak = zeros(26 , 2);
rank_ak = zeros(26 , 1);
cond_ak = rank_ak;

for i = 40:65
    curr = cell2mat( A_cell(i) );
    size_ak(i-39, :) = size( curr );
    rank_ak(i-39) = rank(curr);
    cond_ak(i-39) = cond(curr);
end
```

### **Part 2 Initialization**

```
%Generate 100 random vectors for each b_i e R^m
%initilize
b cell = cell(26, 100);
%heavy i know
j = 1;
cnt = 1;
\max_a = 100 * \max(\max, [], 'all');
min_a = 100 * min(mat , [] , 'all');
for i = 1:2600
    %create random vector and store into array, lets get creative
    bmat = rand( size_mat(1) , 1);
    b_cell(j , cnt) = mat2cell( bmat , size_mat(1) , 1);
    if(cnt == 100)
        j = j + 1;
        cnt = 0;
    end
    cnt = cnt + 1;
end
```

#### Part 2 a

```
%Using built-in equation solver, linsolve compute the least-
squares
%minimizer given A_k and b_i

%gonna need another cell array?

%initialize
    x_true = cell(26,100);
    j = 1;
    cnt = 1;
    for i = 1:2600
        x_true(j,cnt) = mat2cell(linsolve( A_cell{j+39} , b_cell{ j, cnt } ), j + 39 , 1 );
```

```
if(cnt == 100)
    j = j + 1;
    cnt = 0;
end
cnt = cnt + 1;
end
```

#### Part 2 b

```
*using normal equation solver located in function section least
 squares
    %minimizer is computed using normal equations
   % i know too many for loops in this code
   %initialize
   x_ne = cell(26,100);
   err ki NE = zeros(26,100);
   j = 1;
   cnt = 1;
   for i = 1:2600
        %least squares minimizer
       x_ne( j , cnt) = mat2cell(method_NormEq_Cholesky( A_cell{j
+39} , b_cell{ j, cnt } ), j + 39 , 1 );
        %relative error
        err_ki_NE(j,cnt) = norm(x_ne{j,cnt} - x_true{j,cnt}) /
norm(x_true{j,cnt});
        if(cnt == 100)
            j = j + 1;
            cnt = 0;
        end
        cnt = cnt + 1;
   end
```

#### Part 2 c

```
%using normal equation solver located in function section least
squares
%minimizer is computed using normal equations
% i know too many for loops in this code
%initialize
x_qr_mine = cell(26,100);
x_qr_matlab = cell(26,100);
err_ki_QR_bad = zeros(26,100);
err_ki_QR_bad = zeros(26,100);
err_ki_QR_good = err_ki_QR_bad;
j = 1;
cnt = 1;
for i = 1:2600
    x_qr_mine( j , cnt) = mat2cell(method_ThinQR( A_cell{j+39}) ,
b_cell{ j, cnt }, 1 ), j + 39, 1 );
```

```
x_qr_matlab( j , cnt) = mat2cell(method_ThinQR( A_cell{j+39} ,
b_cell{ j, cnt }, 0 ), j + 39, 1 );
%relative error
err_ki_QR_bad(j,cnt) = norm(x_qr_mine{j,cnt}-x_true{j,cnt}) /
norm(x_true{j,cnt});
err_ki_QR_good(j,cnt) = norm(x_qr_matlab{j,cnt}-x_true{j,cnt}) /
norm(x_true{j,cnt});
if(cnt == 100)
    j = j + 1;
    cnt = 0;
end
cnt = cnt + 1;
```

#### Part 3

```
%for each of QR and Normal equations compute the average error over
all the
%bi
%initialize
errk_avg_NE = zeros(24,1);
errk_avg_QR_mine = errk_avg_NE;
errk_avg_QR_matlab = errk_avg_NE;
%excluding k = 64 and 65 due to the matrices not being sym pos def

for i = 1:26
    errk_avg_NE(i) = mean(err_ki_NE(i,:));
    errk_avg_QR_mine(i) = mean(err_ki_QR_bad(i,:));
    errk_avg_QR_matlab(i) = mean(err_ki_QR_good(i,:));
end
```

#### Part 4

%plotting done in plotting section

## **Display**

```
rank_ak(i), cond_ak(i));
fprintf('-----
\n')
end
%explanation
fprintf('\n-----
\n')
fprintf('Discussion: ')
fprintf('\n-----
n n'
%1: the relationship between the error using QR versus the normal
equations
fprintf('1:\n Average error increases for both QR and the normal
equations as k increases. Least squares error using normal equations
increases\n more drastically than the error using thin qr even with
the for k = 64 and k = 65 being ignored\n\n');
%2: What is the relationship between the errors and the condition
number of Ak?
fprintf('2:\nas stated before, as the condition number of A k
increases the least squares error also increases \n\n')
%3: Suppose your matrix A is ill-conditioned. Which method is more
favorable?
fprintf('3:\n looking at the matlab impolementation of thin QR vs
NE thin QR is more favorable for ill-conditioned matrices. \n as the
condition number increases there is noticiable round off error using
cholesky factorization. \nFor this homeowrk, cholesky factorization
could not be used for matrices A 64 and A 65 due to them not being
sym pos definite. ');
Problem 1:
               Size (M x N) | Rank | Condition
           1
    A\_k
Number [ K ]
______
 ___ |
74.8767 |
                                / 40
              101 x 40
 / 41
______
          /
                                       42
 A_42
               101 x 42
                                /
 152.2856 |
 A 43
           101 x 43
                                 /
                                      43
 217.5604
```

A_44 328.8920	/ /	101 x 44	1	44	
A_45 483.7805	/	101 x 45	l	45	1
A_46 753.0465	/ /	101 x 46		46	
A_47 1140.0742	/ /	101 x 47		47	
A_48 1826.7931	/ /	101 x 48		48	
A_49 2846.4223	/ /	101 x 49		49	
A_50 4695.0874	/	101 x 50	l	50	1
A_51 7530.5483	/ /	101 x 51		51	
A_52 12789.3765	/ /	101 x 52		52	
A_53 21122.7169	/	101 x 53	l	53	1
A_54 36949.4832	/	101 x 54	l	54	1
A_55 62868.3337	/	101 x 55	1	55	/
A_56 113329.3575	1	101 x 56	l	56	1
A_57 198770.6821	,	101 x 57	l	57	1
A_58 369475.9187	1	101 x 58		58	
A_59 668493.2863	/	101 x 59		59	
A_60 1282274.0197	,	101 x 60 		60	
A_61 2395303.2393	,	101 x 61 		61	   

A_62 4745459.9263	/	101 x	62	/	62	/
A_63 9161533.4668	<i>'</i>	101 x	63		63	
A_64 18765737.9716	,	101 x 	64		64	/
A_65 37486287.3234	•	101 x 	65	   	65	
increases. Lea	nst squar Lly than	res eri the ei	both QR and the for using norma fror using thin	l equati	ons increases	5
2: as stated befor squares error				f A_k in	creases the I	least
more favorable as the conditiusing cholesky	e for ill on number factori erk, cho	l-condi er inci izatior lesky f		s. noticia ould not	ble round off	

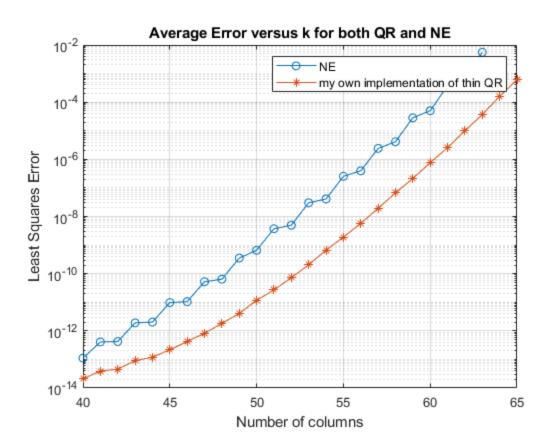
## **Plotting**

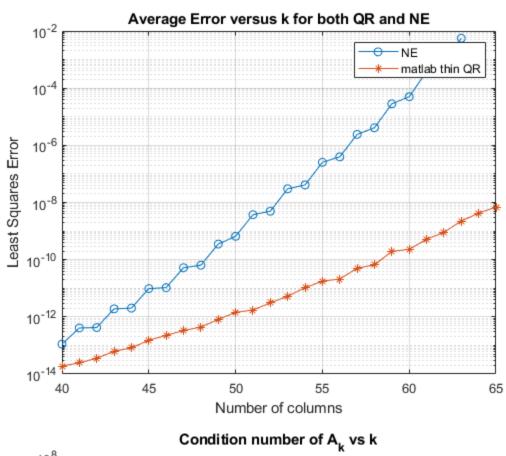
```
%average error versus k for both QR and Normal Equations using
semilogy

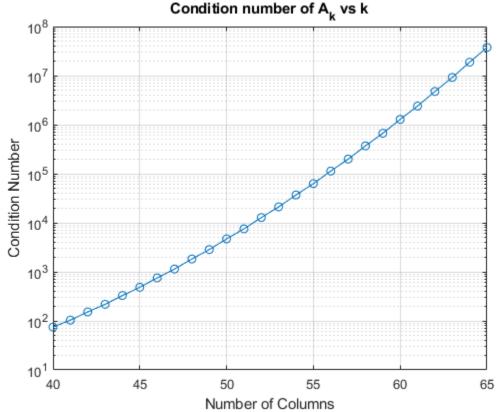
%my implementation of thin QR
figure(1)
semilogy(40:65, errk_avg_NE, '-o', 40:65, errk_avg_QR_mine,'-*')
hold on;
title('Average Error versus k for both QR and NE')
ylabel('Least Squares Error')
xlabel('Number of columns')
legend('NE' , 'my own implementation of thin QR');
grid on;
hold off;

%matlab implementation of thin QR
figure(2)
```

```
semilogy(40:65, errk_avg_NE, '-o', 40:65, errk_avg_QR_matlab,'-*')
hold on;
title('Average Error versus k for both QR and NE')
ylabel('Least Squares Error')
xlabel('Number of columns')
legend('NE' , 'matlab thin QR');
grid on;
hold off;
%condition number of A_k vs k
figure(3)
semilogy(40:65, cond_ak,'-o');
hold on;
grid on;
title('Condition number of A_k vs k')
ylabel('Condition Number')
xlabel('Number of Columns')
hold off;
```







## **Functions**

```
function [x] = method_NormEq_Cholesky(A,b)
    Prupose: Matlab implementation of method to solve least squares
problem using normal
    equations with cholesky
    Inputs:
       A: LHS matrix for Ax = b
       b: RHS matrix for Ax = b
    output:
        x: variable matrix x in Ax = b (x) which minimizes
        ||b-Ax||_2^2
응 }
%form A^T*A e R^n*n and A^T*b e R^n
    ata = A'*A;
    atb = A'*b;
Solve normal eqns, (A^T*A)x = A^T*b for x
%first lets double check
%get size to make sure A = n x n
    size A = size(ata);
%check rank
   r_ata = rank(ata);
    if( (size_A(1) == size_A(2) ) && ( r_ata == size_A(1) )
        %matrix is sym, pos def, compute and solve cholesky
 factorization (
        %determine variable vector using cholesky factorization
        R = chol(ata);
        x = R \setminus (R' \setminus atb);
    else
        %cant use error func for this homework so itll break, if using
        %outside of hw uncomment
        %error('Matrix is not Symmetric Positive Definite')
        %if this error occurs create nan array maybe later could be
used as a flag in
        %error calc
        siz_atb = size(atb);
       warning('Error not accounted for due to A_%i'' x A is not pos
def', siz_atb(1))
        x = NaN(siz atb);
   end
end
function [ x ] = method ThinQR(A, b, bool)
응 {
    Purpose: Matlab implementation to solve the linear least-squares
```

```
problem using a method based on Thin QR factorization
   Input:
       A: LHS matrix, Ax = b
       b: RHS matrix, Ax = b
       bool: boolean value, 1 if you want to use my janky code which
 seems
       wrong, or built in gr function that works
   Output:
       x: variable matrix x in Ax = b (x) which minimizes
        ||b-Ax||_2^2
응}
%alright so because i am trying to do both the homeowkrs this weekend
%assuming the grant-schmidt orthogonalization and least squares is
%to that of the thin QR decomp in lecture. Sauer's numerical analysis
%https://ocw.mit.edu/courses/mathematics/18-06-linear-algebra-
spring-2010/related-resources/MIT18 06S10 gramschmidtmat.pdf
%were used as a reference
%compute the thin QR decomposition
   if bool
        %obtain size of A
            size_A = size(A);
       %initialize r matrix. upper right traingular n x n
            r = zeros(size_A(2),size_A(2));
       %initialize q tall matrixx orthonormal columns, m x n
            q = zeros( size_A );
       %Grant-Schmidt orthogonalization
            for j = 1 : size A(2)
               y = A(:,j);
                for i = 1 : j-1
                    r(i,j) = q(:, i)' * A(:, j);
                    y = y - r(i,j) * q(:, i);
                end
               r(j, j) = norm(y);
               q(:,j) = y/r(j, j);
            end
   else
        % if this doesnt work just use qr matlab
        [q,r] = qr(A, 0);
```

# end % After thin QR is computed, finish computation b\_til = q'\*b; % Solve x = r\b\_til;

#### end

Warning: Error not accounted for due to  $A_64' \times A$  is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to  $A_64'$  x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to  $A_64'$  x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A 64' x A is not pos def Warning: Error not accounted for due to A\_64' x A is not pos def

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Warning: Error not accounted for due to A 65' x A is not pos def
Warning: Error not accounted for due to A_65' \times A is not pos def
Warning: Error not accounted for due to A_65' x A is not pos def
Warning: Error not accounted for due to A_65' x A is not pos def
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Published with MATLAB® R2021a