OSC Messages read: OSC: /page/command parameters

FADER (1,2,3,4)   Ex: /1/fader1   f,   XXXX   => lenght:20, Param: float (0.0-1.0)

XY (1,2)   Ex: /1/xy1   f,f,   XXXXXXXX => length: 24 Params: float,float (0.0-1.0)

PUSH (1,2,3,4)   Ex: /1/push1   f,   XXXX => length:20 Param: float

TOGGLE (1,2,3,4)   Ex: /1/toggle1   f,   XXXX => length:20 Param: float

MOVE   Ex: /1/m XXXX XXXX XXXX => length:16 Params: speed, steps1, steps2 (all float)

OSC Message send:

string to send + param (float)[last 4 bytes]

OSC controls:

fader1: Throttle (0.0-1.0) OSC message: /1/fader1

fader2: Steering (0.0-1.0) OSC message: /1/fader2

push1: Move servo arm (and robot raiseup) OSC message /1/push1