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Haute Ecole Spécialisée
de Suisse occidentale

Fachhochschule Westschweiz
University of Applied Sciences and Arts
Western Switzerland

Master of Science HES-SO in Engineering
Av. de Provence 6
CH-1007 Lausanne

Master of Science HES-SO in Engineering

Orientation: Information and Communication Technologies (ICT)

IMPROVING COSTS, SAFETY AND LIVENESS IN BLOCKCHAIN SYSTEMS

Author:
Nicolas Huguenin

Under the direction of:
Prof. Dr. Marcelo Pasin
HE-Arc

Information about this report

Contact information

Author: Nicolas Huguenin
MSE Student
HES-SO//Master
Switzerland
Email: *nicolas.huguenin@master.hes-so.ch*

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Signature: _____

Validation

Accepted by the HES-SO//Master (Switzerland, Lausanne) on a proposal from:

Prof. Dr. Marcelo Pasin, project advisor

Place, date: _____

Prof. Dr. Marcelo Pasin
Advisor

Prof. Dr. Philippe Passeraub
Dean, HES-SO//Master

Abstract

TODO: add abstract

Keywords: Algorithms; Blockchain; Distributed Systems; Sharing Economy

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1 | Introduction

1.1 Context

The Ethereum blockchain aims to move from the current PoW consensus protocol to a PoS one. Multiple teams are currently researching ways to describe, and implement such a protocol. One of these teams, lead by Vlad Zamfir, is working on a protocol family called Correct by Construction (CBC) Casper. CBC-Casper describes an abstract set of protocols that can achieve consensus between any kind of value, for example an integer, a vote, or a blockchain. This project aims to find and compare block publishing strategies for a CBC-Casper blockchain consensus.

1.2 Objectives

As the CBC-Casper paper only describes an abstract way of constructing PoS consensus protocols, and does not make any assumptions on synchrony, one of the main challenges of the actual implementation is to find incentive mechanisms and strategies telling the nodes when to produce blocks. The main goals of this project are:

- to propose multiple block producing strategies;
- to create a model that allows one to easily compare said strategies;
- to discuss the advantages and disadvantages of each strategy.

1.3 Contents

TODO: explain what is in this

2 | Background

2.1 PoW and PoS

In Ethereum, PoS is aiming at replacing PoW as a distributed consensus algorithm. This section succinctly describe both methods as well as the main differences between them, and then explains which problems arise when you replace PoW with PoS.

2.1.1 What is PoW?

PoW is the current consensus protocol used to decide on a blockchain in Ethereum. In order To create a new valid block, a node has to solve a cryptographic puzzle and include its solution in the newly created block. The difficulty of the puzzle is parametrized in order to have -on average- a block created at a set interval. A reward is given to the creator of each block. The consensus rule states that the chain with the greatest total difficulty is to be considered the main one. Miners are therefore incentivised to build on the main chain if they want to get rewards for their work. The fact that the difficulty changes to keep a certain interval between blocks means that said work is a proxy for timing; a miner cannot create an arbitrary large number of blocks in a short time because it's inherent to the protocol.

2.1.2 What is PoS?

PoS, on the other hand, selects a new block creator according to its weight (or stake). This weight can be the node's age, wealth, etc. In this report, we will mainly discuss a specific PoS protocol, CBC-Casper.

2.1.3 CBC-Casper

CBC-Casper TODO: cite somewhere is an abstract consensus protocol family which is PoS-ready. Nodes, called validators in this context, send messages to each other, acknowledging they saw other messages by including them in a *justification*, that is attached to each message. Based on its justification as well as a weighted list of validators, each message defines an *estimate*, which is the consensus value proposed by the sender of the message. In the case of a blockchain, messages each point to one older message as their estimate and form a *block-Directed Acyclic Graph (DAG)*. Running a slightly modified version of the Greedy Heaviest Observed Sub-Tree (GHOST) algorithm on the DAG returns a blockchain.

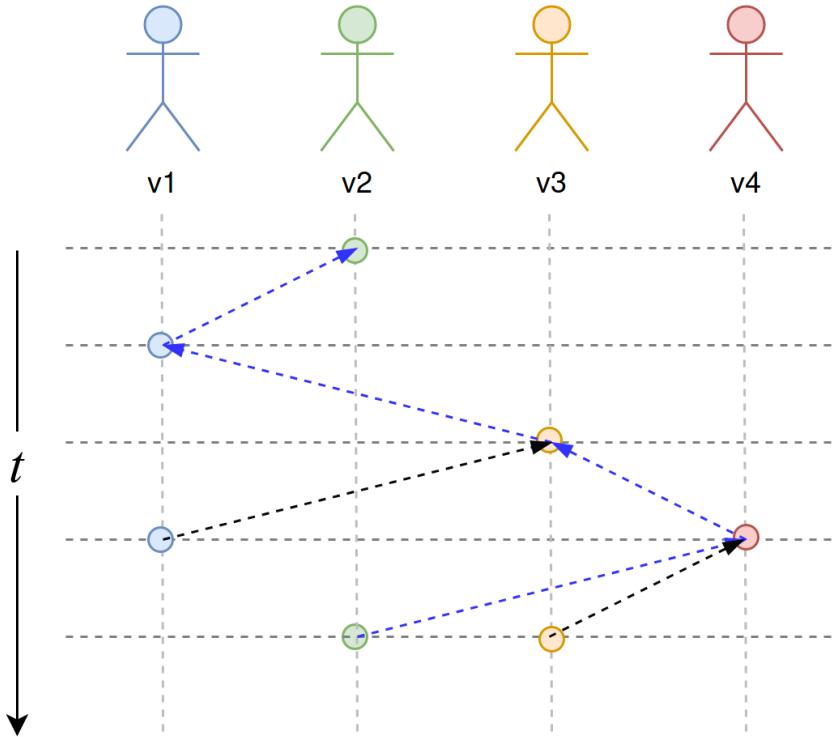


Figure 2.1 CBC blockchain example

The Figure 2.1 shows a small example of a CBC execution over a blockchain. Four nodes are pictured. Colored circles are messages sent by validators, dotted arrows show their justifications. The selected blockchain is depicted with blue arrows. It is obtained by running the GHOST algorithm on the pictured view of the network, and would be the estimate of a new message sent by an honest validator that has this view.

Figure 2.2 exemplifies validator v_1 producing a new message and the resulting new blockchain. An honest node includes all the latest messages it has received (including its own last message). When a validator does not include its own messages in its justification, it is considered as an *equivocator*, does not follow the protocol, and could be punished by the network for such a behavior. Note that validator v_1 does not equivocate because its first message is in the justification of v_2 's first message, and v_1 has this message in the justification of its second message. It is said that v_1 's first message is in the *dependency* of its later messages.

TODO: include a schema showing validators, justifications, estimates, ... in more depth

TODO: talk about finality, safety oracles, ... TODO: change structure; make comparison not between POS and POW but between POW and CBC

2.1.4 PoS vs PoW

TODO: talk about differences between pos and pow

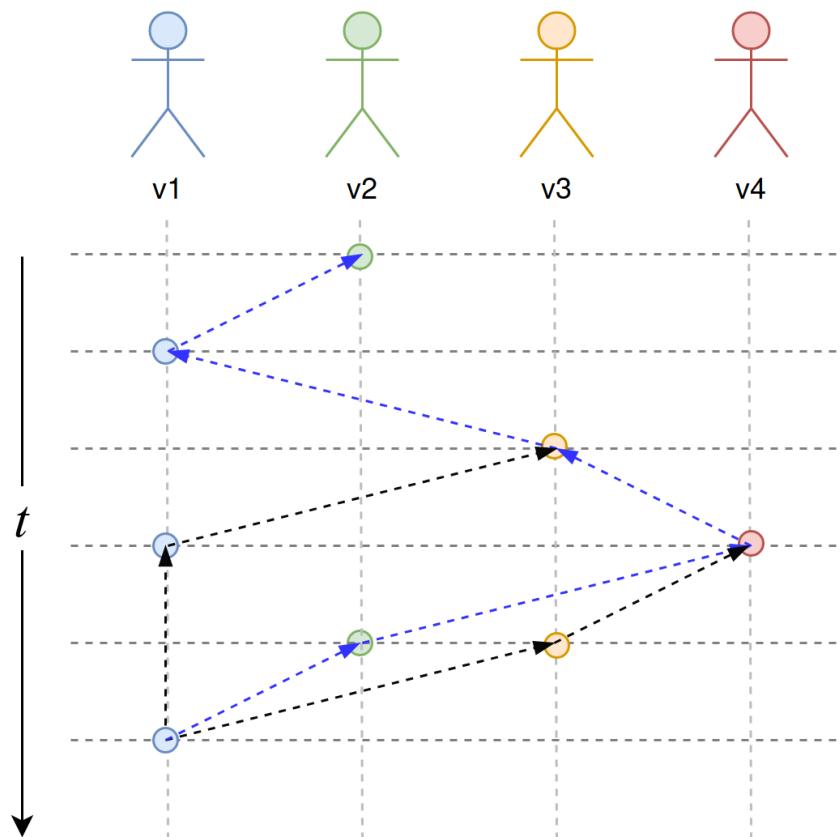


Figure 2.2 CBC blockchain example 2

Chapter 2. Background

	PoW	PoS
Block production	Miners can publish blocks if they can prove they worked for it	Nodes can publish blocks at any time
Timing assumption	Work is a proxy for timing	None
Spam	Work removes the possibility to spam	Negligible computational costs to produce blocks imply potential spam
Economic majority	Work is a proxy for economic majority	Economic majority
Building strategy	Nodes are incentivised to build on the longest chain because they have to work for to build blocks	No clear incentive to build on the longest chain

Table 2.1 Summary of key differences between PoW and PoS

2.1.5 key differences

2.1.6 new problems

TODO: talk about key differences and what this project is about

2.2 CBC casper

TODO: describe the protocol in my own words

TODO: describe liveness, safety

2.3 core_cbc

core_cbc a Rust implementation of the CBC-Casper, made by TrueLevel. It implements the consensus algorithms proposed in the paper and offers an abstract structure that can be used to create consensus on any value.

2.4 the other casper?

2.5 Parity Ethereum

TODO: remove redundancy in this chapter TODO: parity networking/gossiping layer research? Parity is a Rust Ethereum client. It includes a *Pluggable Consensus* module that allows one to easily add new consensus protocols by implementing an interface. At first, the goal of this project was to implement a small bridge between the Parity module and the core cbc implementation to test block creation strategies in a pseudo real-like manner. The implementation of the bridge was not as straight forward as planned so it has been decided to cut it out and test strategies without mimicking the network and client settings.

2.5.1 Background work

During the early stages of this project, a clear objective was set: to be able to run a Casper *testnet* with Parity custom nodes. Some work has been done for the implementation of the `core-cbc` library into Parity, but that was left to people that had a better understanding of the underlying library. Furthermore, **TODO: rephrase "a lot of"** a lot of effort had been injected in the creation of a Docker infrastructure in order to easily deploy, connect and monitor multiple custom Parity nodes on a single machine in order to experiment with different message building strategies. The choice of using Docker was made because there was a possibility to work on the UniNE clusters, which happen to work well with containerized software. After seeing that the Parity implementation would take too much time to be completed, and therefore might be unusable for this thesis, it has been decided to evaluate strategies inside the `core-cbc` library instead of the more real-life-like setting that is a Parity testnet. The main disadvantage of doing the experimentations in the library is that the whole network latencies and topology are not taken into account. However, a non-negligible advantage of implementing strategies in the core library is that it will be easier to test them on consensus values that are not only blockchains. **TODO: add that the lib was not fully tested at this point and that further testing was needed before being able to test parity**

2.5.2 Local testnet

Scripts that create and manage two local nodes have been written. They launch 2 Parity instances with the CBC-Casper consensus engine, and connect them together. Each node has an user account to send transactions, as well as a sender account, that can act as a validator in a Casper sense. Currently, each node produces a block every 10 seconds. This is a basic strategy that enabled further testing of the Parity inclusion of the `core-cbc`.

2.5.3 Docker testnet

Testing at a larger scale than two local instances was needed. The possibility to access a cluster at the UniNE was discussed and the more straightforward way to run programs on the cluster is to have containers. It was therefore decided to create a more complex infrastructure using Docker containers. `docker-compose` scripts were created to achieve this goal. An arbitrary number of containers can be created at once and inter-connected in two different ways:

- fully connected;
- ring.

The created nodes have the same types of accounts as for the local testnet. **TODO: include schemas of fully connected and ring layouts** In the fully connected setting, each node is connected to every other node. In the ring case, each node is connected to two other nodes in a circular manner. Those were the two first layouts that were implemented for simplicity. It was thought to add new layouts afterwards in order to match more precisely the real network topology of the Ethereum *mainnet*. However, because the Parity implementation was deemed too time consuming to be used before the end of this project, no further efforts have been put in that direction.

3 | Strategies Evaluation

3.1 Modelisation

3.1.1 Metrics

A way to rationaly compare strategies is needed in order to discuss their relative strengths and weaknesses. Three main characteristics will be used for that:

- latency;
- number of nodes;
- overhead.

Latency

The latency is the number of messages needed to finalize a block. Ideally, you want to have a latency as low as possible to reach finality as soon as possible. The latency is a way to measure liveness in a blockchain system. If it is low, then the system is considered more "live", as fewer messages are needed in order to confirm a transaction, and therefore less time.

Number of nodes

The number of nodes is quite straightforward; it is the number of nodes that are in the validator set. This number should be as high as possible to guarantee decentralization and therefore safety.

Overhead

The overhead is the number of messages that are sent over the network between one step of the consensus and the next. It should be as low as possible to keep the costs in bandwidth low.

Example

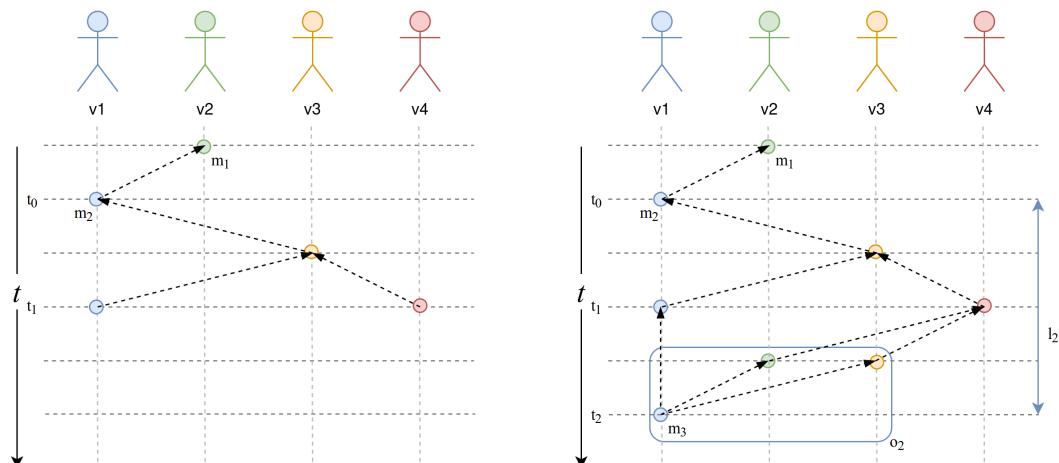


Figure 3.1 Metrics computation example

Figure 3.1 describes how the computation of the metrics takes place. The left half of the figure shows an initial view of the system. At time t_1 , message m_1 is finalized. The right half of the figure shows a view of the system at t_2 , time at which m_2 is finalized. The latency of m_2 is l_2 , the difference of heights between m_3 and m_2 . In this example, $l_2 = 4$. o_2 , the overhead for m_2 , is the number of messages that have been sent between t_1 and t_2 , t_1 being the time at which the previous message has been finalized and t_2 the time at which the current message is finalized. In the example, $o_2 = 3$.

3.1.2 Tradeoff triangle/Trilemma

In a standard consensus protocol, the three metrics form a trade-off triangle in kind of a "pick two" fashion. **TODO: not a pick two** CBC-Casper has no assumptions on timings, sources, contents, destinations of the messages that are exchanged, and can therefore explore the whole trade-off space. This project aims to find strategies that span the entierty of the triangle and **TODO: finish sentence what**

3.1.3 Basic model

The first model that has been chosen for the evaluation is the following:

$$1 = s_n \cdot \frac{1}{n} + s_l \cdot l + s_o \cdot o$$

This model binds 3 scores s_x to their respective variables x . Variables are as follows:

- n the number of nodees;
- l the latency;
- o the overhead.

The higher the score s_x is, the more its related variable is dominant in the strategy and therefore the closer to a corner of the triangle the strategy is. $\frac{1}{n}$ is used because a large number of nodes is wanted. This model is a basic one, where everything is linear. It is probably not accurate but will serve as a base for a closer to reality one once data have been plotted using this model. **TODO: why 1/n, why everything linear?**

3.1.4 Model Evaluation

After running the strategies in the simulation environment, metrics for n , l and o will be recorded. Then, for multiple runs, a linear regression will be performed in order to find the scores s_x .

3.2 Strategies

The following strategies were proposed in order to visit the entierty of the trade-off triangle:

- round-robin;
- randomness;

- double round-robin;
- triple round-robin;
- overhead.

These strategies should allow one to visit the whole triangle and to discuss their respective strength and weaknesses. The following sections describe the strategies as well as their expected locations in the triangle.

3.2.1 Round-robin

The first strategy that comes to mind is a simple round-robin. Nodes send messages one after the other, in a fixed order. **TODO: talk about real life implications? aka synchronize all nodes?... and that for every strategy**

3.2.2 Randomness

The next strategy is the simplest to think of: complete randomness. Using fixed probability density functions, nodes chose when to create messages and to which other validator to send them.

3.2.3 Double Round-robin

In this setting, two nodes send messages at the same time, in a fixed order. If the two nodes that send messages at the same step are at opposite places in the set of validators **TODO: explain better**, the latency to finality is supposedly half as much as the simple round-robin strategy. The overhead is however doubled.**TODO: add that we could have a triple rr, quadrr, ...**

3.2.4 Triple Round-robin

This strategy is similar to the Double round-robin, except that three nodes send a message a each step. It was decided to add this strategy at a later stage of the project in order to have intermediate comparison points between the Double round-robin and the Maximal overhead strategy. As for the Double round-robin strategy, the latency should be divided by three compared to the simple round-robin and the overhead should be three times higher.

3.2.5 Maximal Overhead

This strategy is the most expensive in terms of bandwidth; at each step, each validator sends a message to the others. This example strategy should give a baseline value for the maximum overhead that is reachable in the tradeoff triangle.

3.2.6 Bottom-up strategies

All the previous strategies (except the Arbitrary one) can be viewed as "top-down" strategies, as there has to be a way for nodes to be synchronized. Strategies that are easier to implement from a real-life point of view would be strategies that only depend on the data available on a node. For exemple, a node could keep track of the whole state of the finalization of messages, and only publish a message itself when it facilitates the finalization. That kind of strategy has not been implemented but the testing and scoring framework allows one to easily add them.

Such strategies should implement incentives for the nodes not to spam the network and include mechanisms to slash nodes not following some rules the strategies dictate.

3.3 Experiments

Over the duration of this thesis, the `core-cbc` library has included a test framework called `proptest`. The testing framework that has been implemented includes ways to simulate the behavior of the Casper protocol over multiple nodes and thousands **TODO: numbers** of blocks. At the time of the writing, the simulations do not include networking latencies.

3.3.1 proptest

The `proptest` implementation is able to run blockchain simulations off the following parameters:

- Number of validators;
- Terminating condition;
- Sender strategy;
- Receiver strategy.

Number of validators

This parameter is quite straightforward, it is the number of nodes that can validate blocks.

Terminating condition

The terminating condition is a predicate that tells whether or not the simulation has reached an end. In our case, the end of the simulation is reached when at least one node finds a safety oracle for a blockchain that has a height of 4. **TODO: why 4**

Sender strategy

The sender strategy selects one or more nodes that will create new messages and forward them to the rest of the network. All the basic strategies that have been presented in Section 3.2 are implemented as Sender strategies. New strategies (including bottom-up ones) can be easily implemented as well.

Receiver strategy

Receiver strategies select a set of validators that receive messages created by Sender strategies. Two strategies have been implemented for now:

- All receivers;
- Some receivers.

The *all receivers* strategy broadcasts messages to each other validator. The *some receivers* strategy sends a message to 1 or more validator, using an uniform probability density function. As of now, none of the implemented strategies are a

good modelisation of a typical Ethereum network and this will be fixed at a later iteration. Nonetheless, these strategies offer two extreme points on the spectrum of the network topology: a fully connected one without latency (*all receivers*), and a random one (*some receivers*) and will be both taken into account to compare the sender strategies.

3.3.2 Metrics measurements

Metrics are not computed as-is in the `proptest` implementation. Simpler datas are logged into `csv` files, and are processed by a `Python` script. **TODO: what data** This two steps processing permitted the generation of data before having a precise definition of the metrics. It also permits to vary the way metrics are recorded. For example, from the same log file, you could extract metrics only when the last step of the consensus is reached, or have an average of the metrics at each step of the consensus.

3.3.3 Tests

Table 3.2 summarizes which tests have been run. All of them have the same terminating condition, which is reached when at least a node finds a safety oracle at height 4. The number of nodes is chosen at random in the interval [1, 20]. It has been decided to perform tests on this interval because it is large enough to give an insight on the behavior of the relations between the metrics, and small enough to reach the terminating condition in a reasonable time (1 run with a number of nodes chosen at random takes on average 1 hour with the Maximal overhead strategy).

TODO: remove table

	All receivers	Some receivers
Round-robin	✓	✓
Double round-robin	✓	✓
Maximal overhead	(✓)	(✓)
Arbitrary	✓	✓

Table 3.1 Summary of tests that have been run. A tick in parenthesis implies that tests were run but that there are not many data points or big disparities in the distribution of the number of nodes

TODO: schema with what to measure **TODO: how the measurements take place in the code**

3.4 Visualization I: All receivers

This chapter presents a visualization of the datas obtained through the multiple test runs with the All receivers strategy. Each subsection shows the results using 3 histograms, representing the raw data, followed by 3 scatter plots picturing each metric against each other. These graphs also show a simple linear regression as an attempt to find a relation between each metric. At the end of the discussion of each strategy a linear regression is performed in order to find the scores of each variable according to the model presented in Subsection 3.1.3.

TODO: 3D plotting? **TODO: undersampling issue?**

3.4.1 Round-robin

The distributions of the number of nodes and the latency (Figure 3.2 left and center) have the same shapes except for the gaps every 3 steps. The resemblance in shape is explained by the fact that the latency is strictly correlated to the number of nodes, as expected. The gaps will be explained in the next section, using the graphs that show relations between variables. **TODO: explain gaps**

TODO: fix center/left/right in captions and text

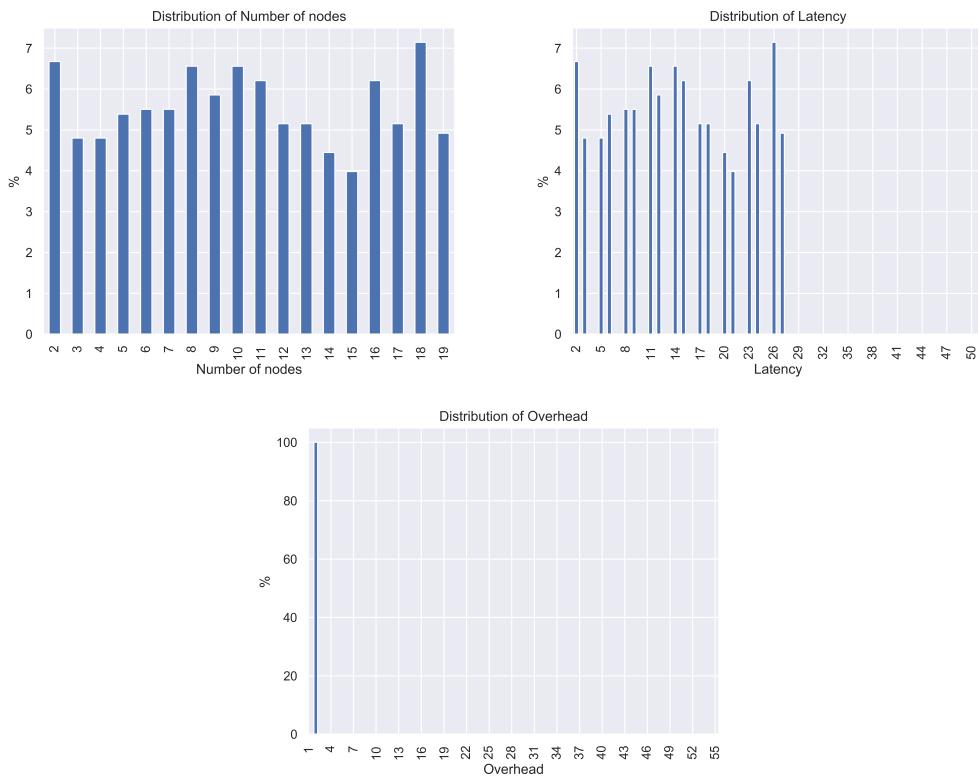


Figure 3.2 Distributions of the dataset. Number of nodes (left), latency (center) and overhead (right) **TODO: change xticks label frequency**

The histogram for the overhead is easy to analyse as well; the overhead is expected to be 1 because once consensus is obtained for the genesis block, only one message from the next validator is needed to finalize the next block.

3.4. Visualization I: All receivers

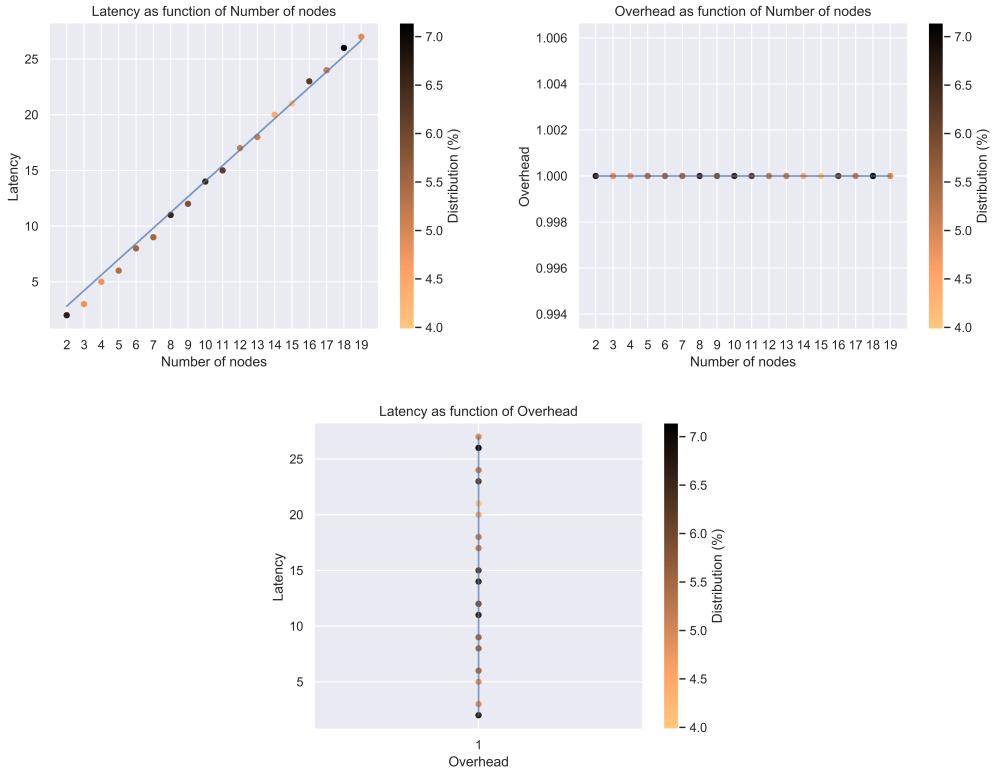


Figure 3.3 Relations between all the variables. Latency/Number of nodes (left), Overhead/Number of nodes (center) and Latency/Overhead (right)

The right and center graphs on Figure 3.3 do not give more insight on the data, as the Overhead is always 1. On the other hand, the graph on the left shows a clear linear relationship between the latency and the number of nodes. The fitted line has the following equation:

$$l = 1.403402 \cdot n$$

The latency is expected to be around $1.5 \cdot n$ because the finality is reached when at least 50% of the network has acknowledged that the whole network has the finalized message in its justification. As pictured in the top-left graph of Figure 3.3, the fitted line has a slightly small slope compared to the data points due to the fact that the line is fitted to be linear and the data points are close the origin. **TODO: insert line with $1.5 \cdot n$?**

3.4.2 Double round-robin

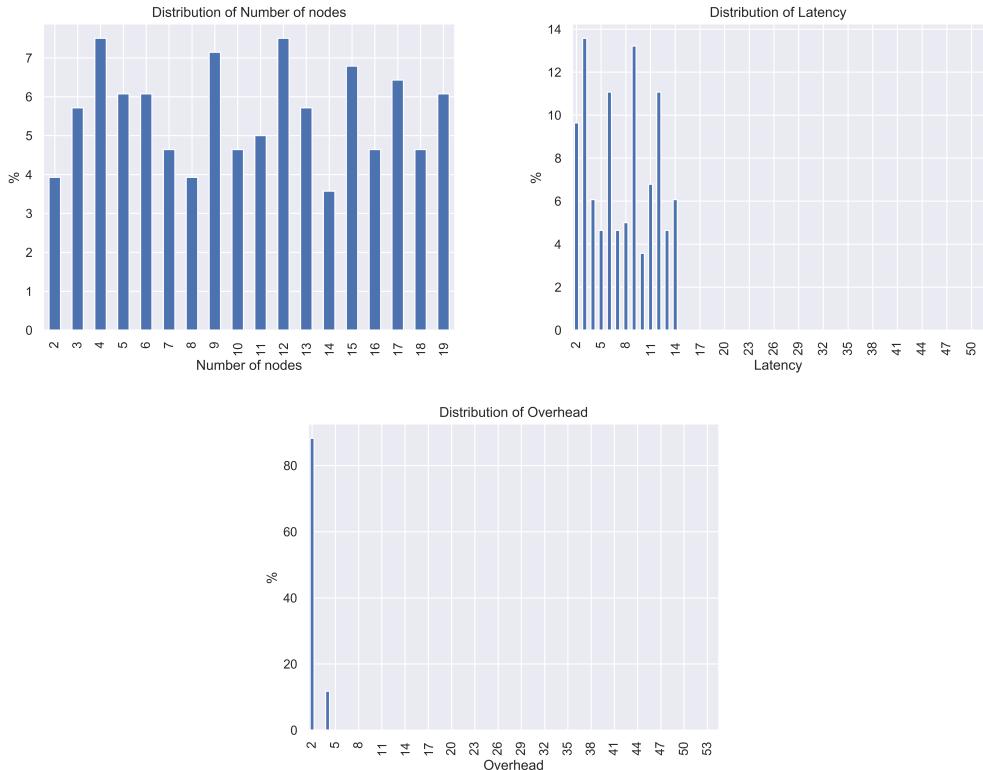


Figure 3.4 Distribution of the dataset. Number of nodes (left), latency (center) and overhead (right)

As for the simple round-robin case, the latency and number of nodes distributions show a similar shape. The latency is less spread than for the singl round-robin, which explains some dissimilarities between the distributions. The distribution of the overhead presents a peak at 2, which is expected but also shows that there are some messages that have double this overhead, at 4. This will be explained using the following graphs. **TODO: explain outliers**

3.4. Visualization I: All receivers

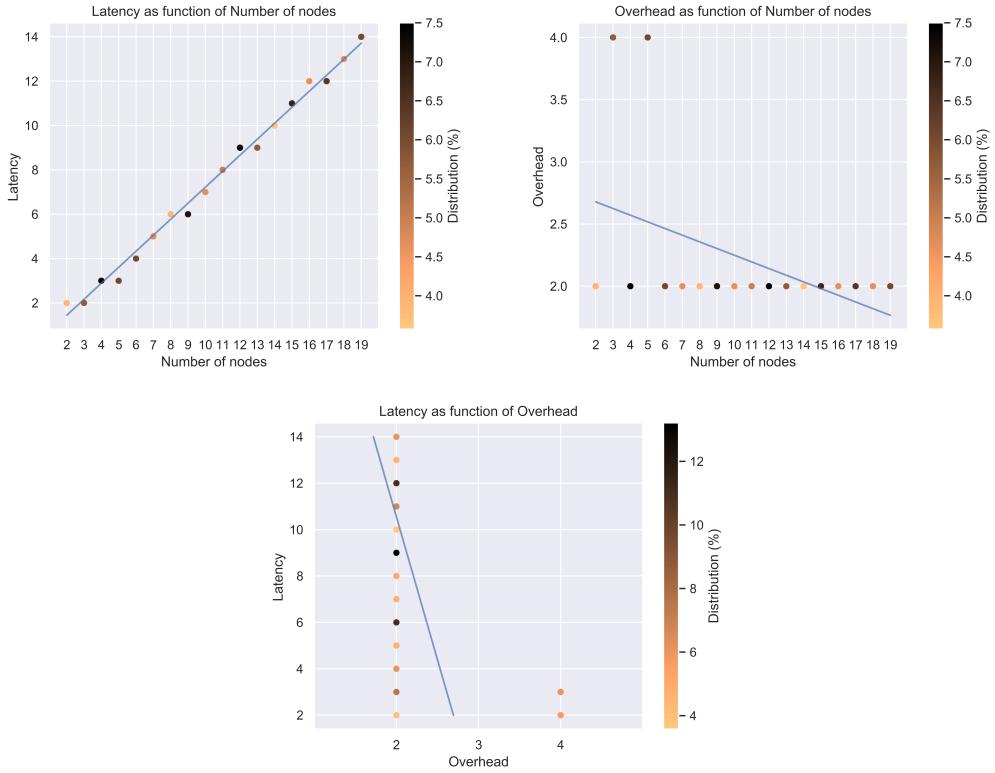


Figure 3.5 Relations between all the variables. Latency/Number of nodes (left), Overhead/Number of nodes (center) and Latency/Overhead (right)

As for the simple round-robin strategy, the plots including the Overhead are not of much use here, except they show that its value is 2, as it is expected. On the other hand, the plot on the top-left of Figure 3.5 shows a linear relation between the number of nodes and the latency:

$$l = 0.721750 \cdot n$$

This value is about half of the slope obtained for the same relation with the round-robin strategy. The double round-robin strategy was supposed to show half the latency with respect to the simple round-robin and this value is therefore correct. The value of 2 for the overhead is also twice the overhead for the single round-robin and confirms the hypothesis.

3.4.3 Triple round-robin

The triple round-robin strategy shows the same kind of information as the double round-robin one. The overhead is 3 for almost all cases (this will be discussed later), and the number of nodes and latency are linearly correlated.

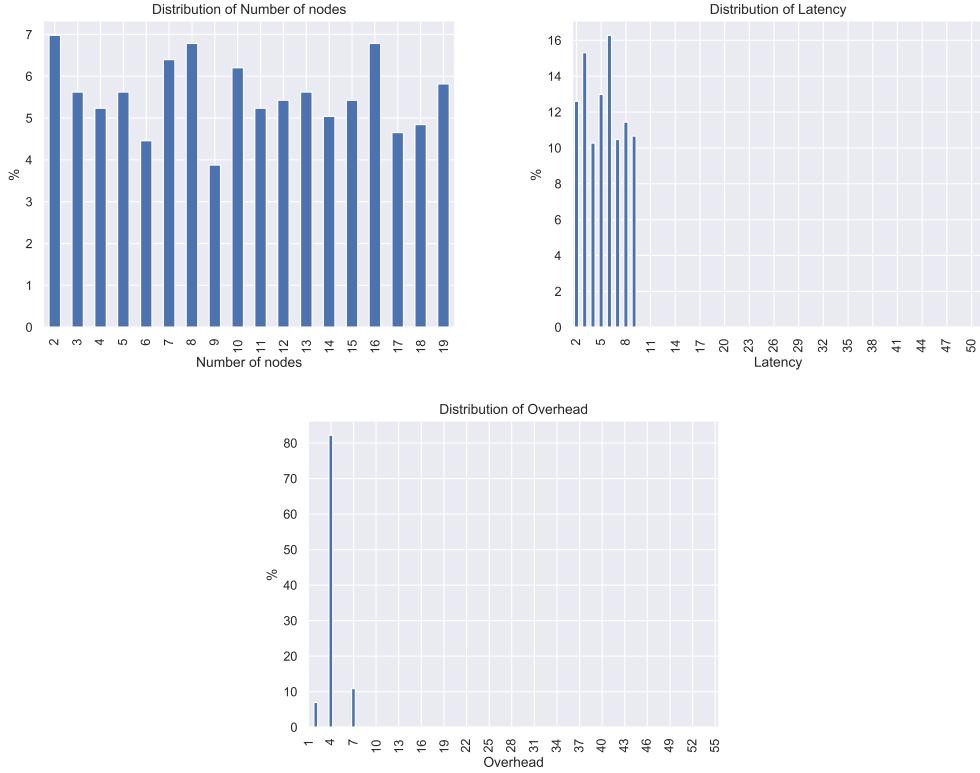


Figure 3.6 Distributions of the dataset. Number of nodes (left), latency (center) and overhead (right)

The relationship with the overhead are again not of much use because its value is always 3. Again, there is a linear relationship between the latency and the number of nodes, which follows this equation:

$$l = 0.496152 * n$$

The slope is a third as the slope for the simple round-robin strategy. Moreover the overhead is three times larger for the triple round-robin than it is for the simple.

3.4. Visualization I: All receivers

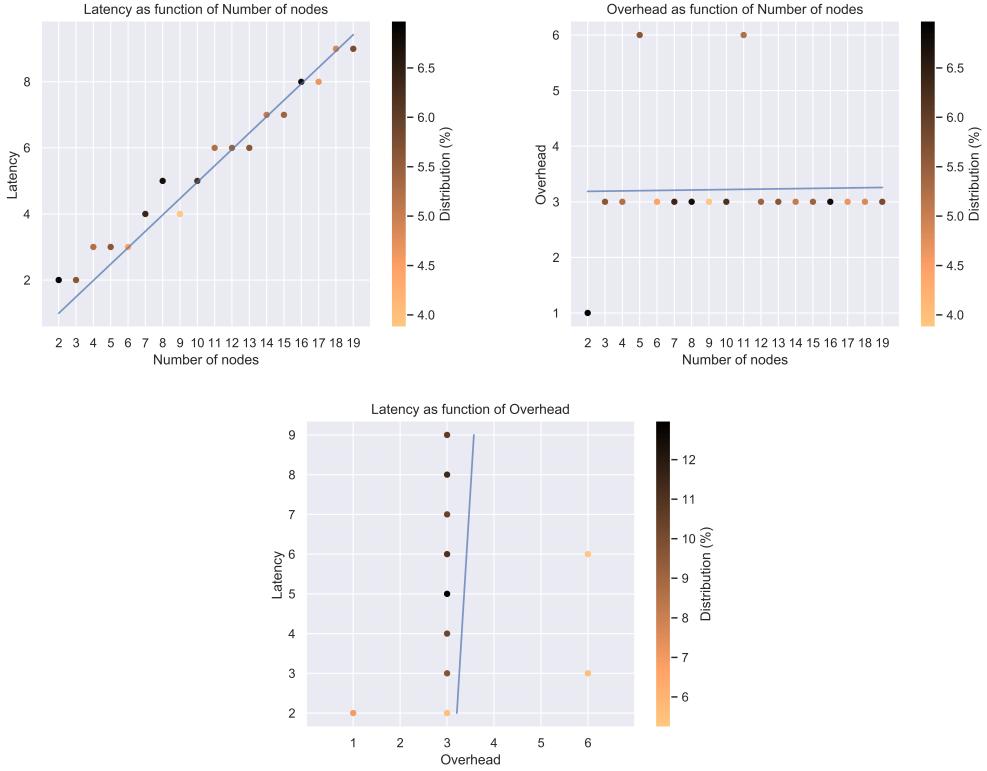


Figure 3.7 Relations between all the variables. Latency/Number of nodes (left), Overhead/Number of nodes (center) and Latency/Overhead (right)

3.4.4 Maximal overhead

This strategy aims to reduce latency to its minimum, which is shown in the top-right plot on Figure 3.8. The distributions of the number of nodes and overhead are of the same shape because they are linearly correlated, as will be shown in the next paragraph. Note that the experiments have been run with a lower number of nodes because the simulations for a large number of nodes takes a large amount of time. The simulations are currently implemented following the mathematical formulae found in [TODO: VLADS PAPER](#) and not yet optimized. For completeness's sake, a few runs have been performed with the same amount of nodes as for the other experiments to show whether or not there were divergences. It turned out that there was not such divergences. [TODO: talk about why the number of nodes is not even](#)

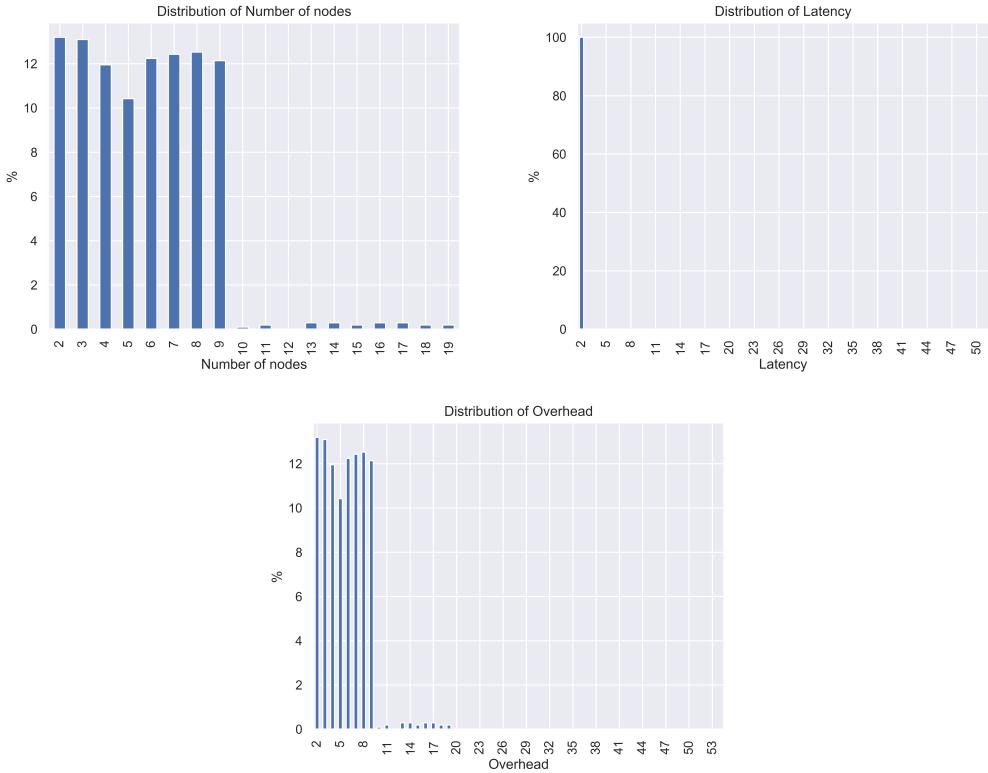


Figure 3.8 Distribution of the dataset. Number of nodes (left), latency (center) and overhead (right)

The top-right plot on Figure 3.9 clearly shows a linear dependency between the number of nodes and the overhead. The relation is $o = n$, as it is expected. The two other plots on the same Figure only confirm that the latency equals 2, which is the minimum that can be reached, as there needs to be two steps to finalize a message. During the first step, all nodes acknowledge they have seen a message, and the second step confirms that everyone has seen the other nodes acknowledgments.

3.4. Visualization I: All receivers

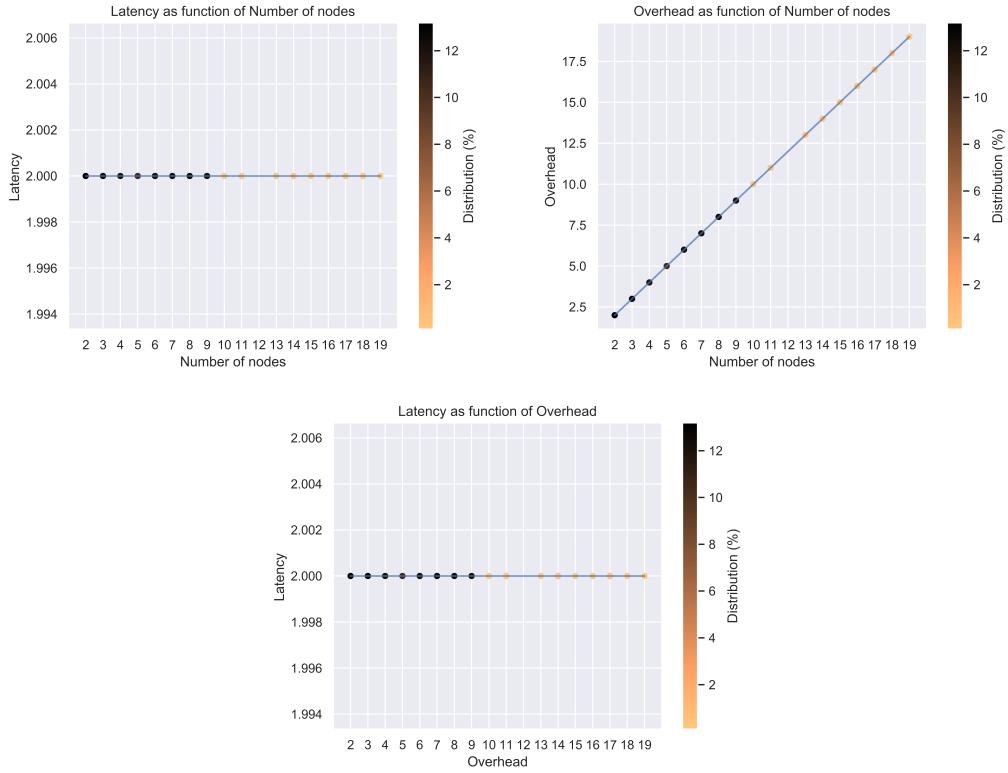


Figure 3.9 Relations between all the variables. Latency/Number of nodes (left), Overhead/Number of nodes (center) and Latency/Overhead (right)

3.4.5 Arbitrary

This strategy is the only one that uses a random factor and that can be considered as a "bottom-up" strategy.

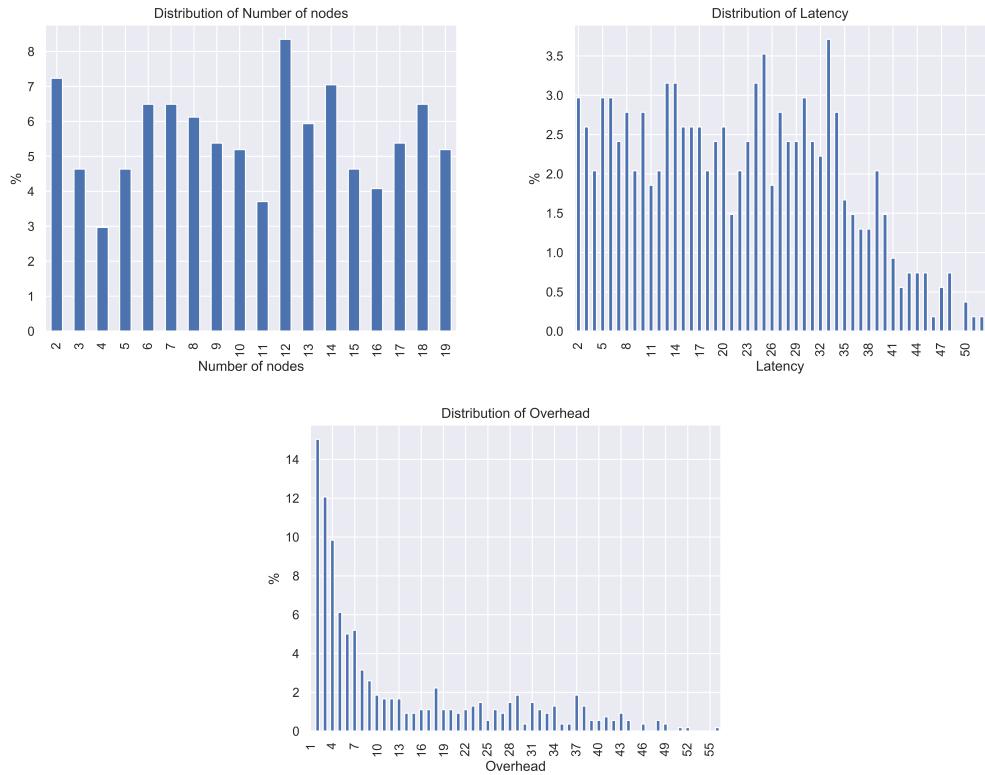


Figure 3.10 Distribution of the dataset. Number of nodes (left), latency (center) and overhead (right)

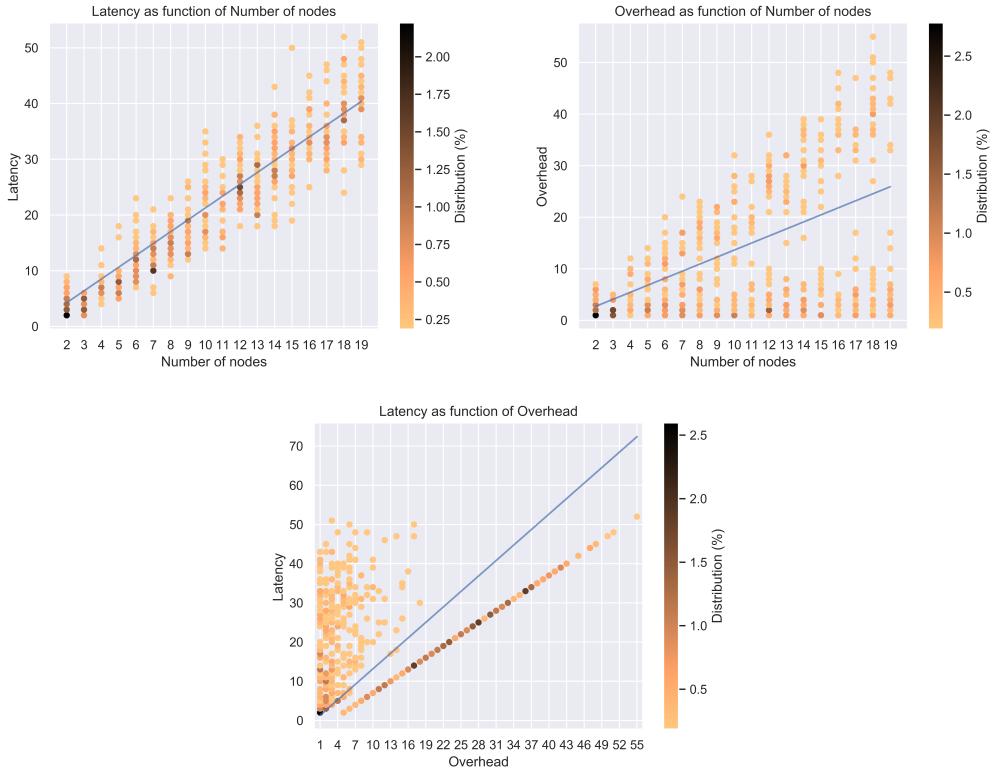


Figure 3.11 Relations between all the variables. Latency/Number of nodes (left), Overhead/Number of nodes (center) and Latency/Overhead (right)

3.4.6 Fitting of the basic model

Fitting the basic model described in [TODO: section](#) to the data gives the following result.

Sending Strategy	s_n	s_l	s_o
Round-robin	0.0	0.0	1.0
Double round-robin	1.435	0.055	0.162
Triple round-robin	1.686	0.084	0.091
Maximal overhead	0.0	0.5	0.0
Arbitrary	2.556	0.026	0.002

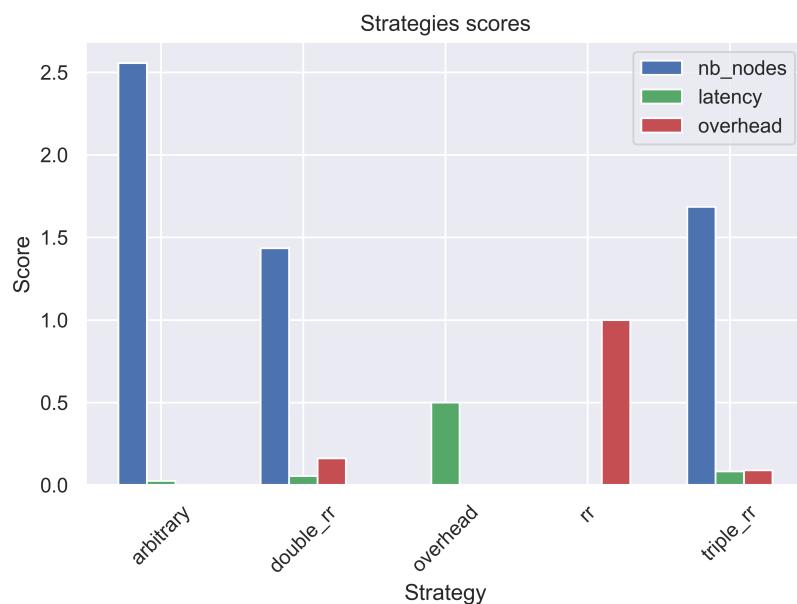
Table 3.2 Raw fitted values for the simple model, rounded to the 3rd decimal place

The scores obtained for the round-robin and the maximal overhead strategies are the expected ones. The round-robin strategy optimizes the overhead (one message per new finalized block) and the latency evolves linearly with the number of nodes and is therefore bad. The score for the number of nodes will be discussed later in this chapter. The maximal overhead strategy shows that it maximizes the latency (which is 2, the minimal value for the latency) and therefore the rest of the scores are non influential. For the double and triple round-robin strategies, the variation for the overhead and the latency scores, compared to the ones for the round-robin are

also in accordance with what is expected; the latency decreases when the number of round augments and the overhead increases along with the number of nodes sending messages in a single round.

Number of nodes

The main problem with these results is the evolution of the score for the number of nodes, particularly for the arbitrary strategy. Based on the observations made in **TODO: section**, the arbitrary strategy clearly is worse than the other ones for the latency and overhead. That is reflected with the values obtained for their respective scores. The main issue with it is that the score for the number of nodes is used as a buffer for how well the two other variables perform in a set strategy. Indeed, the model forces the relation between the scores and the variables, and if the scores for both the latency and the overhead are low, the score for the number of nodes is forced to be high.



*Figure 3.12 Raw fitted values for the simple model. The strategies are listed on the x-axis and their scores are plotted along the y-axis. **TODO:** prettify the x-axis and bar legend*

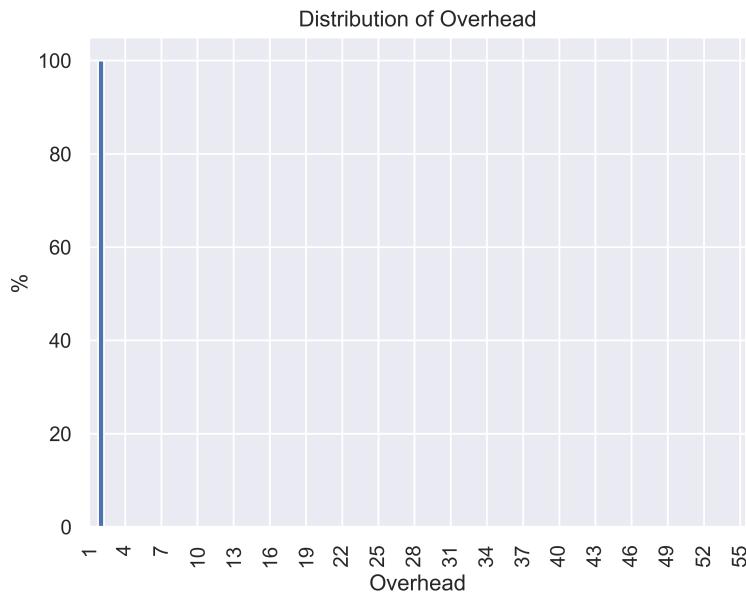


Figure 3.13 Histogram of the overhead. Round-robin and all receivers strategies

3.4.7 Improvements of the basic model and new fitting

3.5 Analysis

TODO: why the model is bad according to the number of nodes

TODO: here will be a table containing all the fitted lines values and a comparison and explanation of the behaviors that are observed

3.6 Future works

4 | Conclusion

working comparison framework easy to implement new strategies, new ending conditions, ... well new test cases

however: model not that good no networking assumptions bottom up strategies to be implemented **TODO: insert conclusion**

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Glossary

CBC Correct by Construction. 1, 3–5, 7

DAG Directed Acyclic Graph. 3

GHOST Greedy Heaviest Observed Sub-Tree. 3

PoS Proof-of-Stake. vii, 1, 3, 4, 13

PoW Proof-of-Work. vii, 1, 3, 4, 13