

YIMING XIE

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EDUCATION

Zhejiang University, Hangzhou, China

Sep. 2015 - June. 2019

- *Bachelor of Opto-Electronics Information Science and Engineering* *Jr./Sr. GPA:3.57/4.0*
- **Related Courseworks:** Advanced Data Structures & Algorithm Analysis, Object-Oriented Programming, Linux Application, Computer Networks

RESEARCH INTERESTS

- Correspondence estimation: multi view stereo, optical flow, disparity, feature detector and descriptor
- 3D object/scene understanding and reconstruction: 3D object detection and tracking, scene reconstruction

PUBLICATIONS

- **Yiming Xie***, Jiaming Sun*, and Xiaowei Zhou. Neural fusion: Real-time 3d scene reconstruction from monocular images. In submission
- **Yiming Xie***, Jiaming Sun*, Siyu Zhang, Hujun Bao, and Xiaowei Zhou. You don't only look once: Constructing visuospatial working memory for integrated 3d object detection and tracking. In submission
- Jiaming Sun*, Linghao Chen*, **Yiming Xie**, Siyu Zhang, Qinhong Jiang, Xiaowei Zhou, and Hujun Bao. Disp r-cnn: Stereo 3d object detection via shape prior guided instance disparity estimation. In *CVPR*, June 2020

Note: * above denotes equal contribution

RESEARCH EXPERIENCE

ZJU-SenseTime Joint Lab of 3D Vision

Zhejiang University, Hangzhou

Supervisor: *Prof. Xiaowei Zhou, Jiaming Sun*

Real-Time 3D Scene Reconstruction from Monocular Images

Feb. 2020 - Present

- Design a real-time, high accuracy and memory-efficient method for RGB scene reconstruction.
- Proposed a view-independent part volume and incremental deep fusion pipeline to avoid redundant computations and decrease memory consuming.
- Directly regress TSDF rather than an intermediate representation of depth maps.

3D Object Detection and Tracking via Constructing Visuospatial Working Memory

Feb. 2019 - Nov. 2019

- Designed a novel framework for integrated 3D detection and tracking.
- Proposed an early integration scheme based on a new representation to speed up object detection.
- Proposed a novel way to fuse predictions from previous frames with estimations at the current frame.
- Achieved better detection performance and truncation or occlusion handling.

Shape Prior Guided Instance Disparity Estimation for Stereo 3D Object Detection

June. 2019 - Nov. 2019

- Proposed a novel framework to estimate object instance disparity in 3D object detection with stereo images.
- Proposed a pseudo-ground-truth generation process to supervise the instance disparity estimation network.
- Guided the disparity estimation to learn object shape prior that is suitable for object detection.
- Outperformed state-of-the-art baselines on both accuracy and runtime speed.

State Key Laboratory of CAD&CG

Zhejiang University, Hangzhou

Supervisor: *Prof. Xiaowei Zhou*

Deep Scene Flow Estimation with Iterative Soft-argmin and Edge-aware Regression

July. 2018 - Jan. 2019

- Explored methods of improving the performance of scene flow estimation based on PWCNet.
- Proposed an iterative soft argmin to cope with the multi-modal distributions of cost volume.
- Proposed an edge-aware policy to improve the over-smoothing problem and utilized contrastive loss to learn a more discriminative descriptor.
- Conducted experiments to show that our proposed methods leads to improvement in terms of both optical flow and disparity estimation.

National Engineering Research Center of Optical Instrumentation

Zhejiang University, Hangzhou

Supervisor: *Prof. Bin Lin*

Robust Stereo Face Recognition Using Convolutional Neural Networks

Nov. 2017 - May. 2018

- Proposed a simple CNN-based face recognition approach that incorporates disparity information.
- Proposed to utilize RGB-D fusion at different levels and adaboost to combine RGB-D information.
- Conducted experiments to show that our model improves the robustness and the performance compared to RGB input.

SKILLS

Programming Languages: C, C++, Python, LaTeX

Technical: Pytorch, Git, Linux, Blender, Final cut pro