

SAFE DRIVER PREDICTION

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#### 1. Problem Statement:

Nothing ruins the thrill of buying a brand new car more quickly than seeing your new insurance bill. The sting's even more painful when you know you're a good driver. It doesn't seem fair that you have to pay so much if you've been cautious on the road for years.

<u>Porto Seguro</u>, one of Brazil's largest auto and homeowner insurance companies, completely agrees. Inaccuracies in car insurance company's claim predictions raise the cost of insurance for good drivers and reduce the price for bad ones.

In this competition, we're challenged to build a model that predicts the probability that a driver will initiate an auto insurance claim in the next year. While Porto Seguro has used machine learning for the past 20 years, they're looking to Kaggle's machine learning community to explore new, more powerful methods. A more accurate prediction will allow them to further tailor their prices, and hopefully make auto insurance coverage more accessible to more drivers.

In this competition, we will predict the probability that an auto insurance policy holder files a claim.

#### 2. Data Used:

We are provided with 2 csv files one for training data and other for testing data. These contain following columns:

```
id
                                                                                                       int64
    target
                                                                                                       int64
    ps ind 01
                                                                                                     uint8
   ps_ind_02_cat
                                                                                                     uint8
   ps ind 03
                                                                                                uint8
  ps_ind_04_cat uint8
ps_ind_05_cat uint8
ps_ind_06_bin uint8
ps_ind_07_bin uint8
ps_ind_08_bin uint8
 ps_ind_08_bin uint8
ps_ind_09_bin uint8
ps_ind_10_bin uint8
ps_ind_11_bin uint8
ps_ind_12_bin uint8
ps_ind_13_bin uint8
ps_ind_14 uint8
ps_ind_15 uint8
ps_ind_16_bin uint8
ps_ind_17_bin uint8
ps_ind_18_bin uint8
ps_ind_14 uint8
ps_ind_15 uint8
ps_ind_16_bin uint8
ps_ind_17_bin uint8
ps_ind_18_bin uint8
ps_reg_01 float64
ps_reg_02 float64
ps_reg_03 float64
ps_car_01_cat uint8
ps_car_02_cat uint8
ps_car_03_cat uint8
ps_car_04_cat uint8
ps_car_05_cat uint8
ps_car_06_cat uint8
ps_car_07_cat uint8
ps_car_08_cat uint8
ps_car_09_cat uint8
ps_car_09_cat uint8
ps_car_09_cat uint8
ps_car_10_cat uint8
ps_car_10_cat uint8
ps_car_11_cat uint8
ps_car_11_cat uint8
ps_car_12 float64
 ps_car_11_cat uint8
ps_car_11 uint8
ps_car_12 float64
ps_car_13 float64
ps_car_14 float64
ps_car_15 float64
```

Test data doesn't contain target variable.

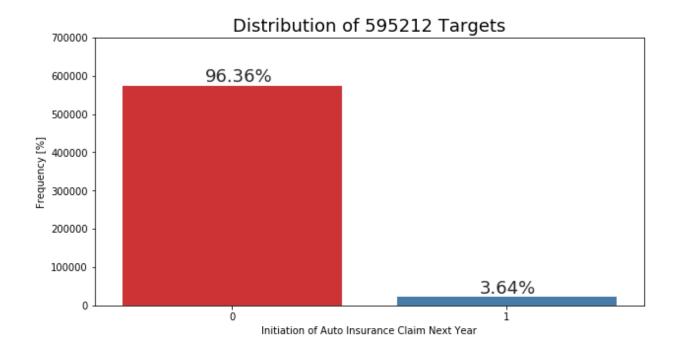
In the train and test data, features that belong to similar groupings are tagged as such in the feature names (e.g., ind, reg, car, calc). In addition, feature names include the postfix bin to indicate binary features and cat to indicate categorical features. Features without these designations are either continuous or ordinal. Values of -1 indicate that the feature was missing from

the observation. The target columns signifies whether or not a claim was filed for that policy holder. Total 595212 rows are there in training data.

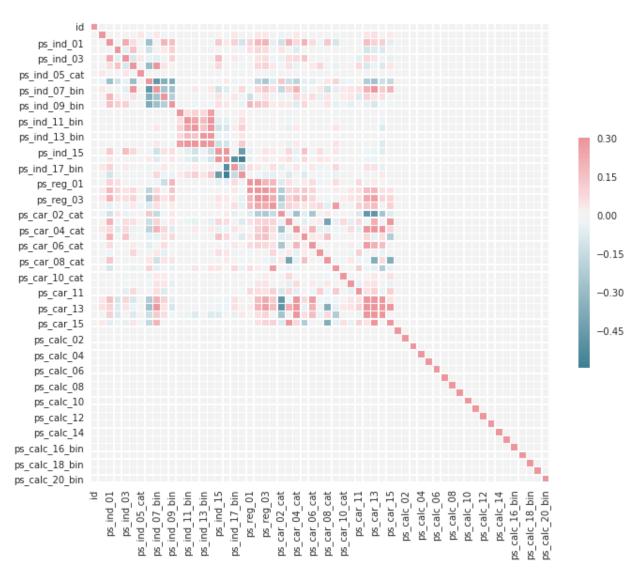
# 3. Exploration of Numerical variables:

# 3.1. Distribution of target variable:

Initially we will check our first variable that is target variable. We can see that it has most of the value as zero and only 3.64% values as 1 in our training data.



# **3.2.** Checking correlation between variables:



We can see all ps\_calc\* variables are not related to others at all. We will remove them completely to have a better prediction.

## 3.3. Checking percent of null values:

#### Training data:

```
id 0.0
target 0.0
ps ind 01 0.0
ps ind 02 cat 0.0362895909357
ps ind 03 0.0
ps ind 04 cat 0.0139446113318
ps ind 05 cat 0.975954785858
ps ind 06 bin 0.0
ps ind 07 bin 0.0
ps_ind 08 bin 0.0
ps ind 09 bin 0.0
ps ind 10 bin 0.0
ps ind 11 bin 0.0
ps ind 12 bin 0.0
ps ind 13 bin 0.0
ps ind 14 0.0
ps ind 15 0.0
ps ind 16 bin 0.0
ps ind 17 bin 0.0
ps ind 18 bin 0.0
ps reg 01 0.0
ps reg 02 0.0
ps reg 03 18.1064897885
ps car 01 cat 0.0179767881024
ps car 02 cat 0.000840036827215
ps_car_03_cat 69.0898368984
ps car 04 cat 0.0
ps car 05 cat 44.7825312662
ps car 06 cat 0.0
ps car 07 cat 1.93023662157
ps car 08 cat 0.0
ps car 09 cat 0.095596190937
ps_car_10_cat 0.0
ps car 11 cat 0.0
ps car 11 0.000840036827215
ps car 12 0.000168007365443
ps_car_13 0.0
ps car 14 7.16047391518
ps car 15 0.0
ps calc 01 0.0
ps_calc_02 0.0
ps calc 03 0.0
ps calc 04 0.0
ps calc 05 0.0
ps calc 06 0.0
ps calc 07 0.0
ps calc 08 0.0
ps calc 09 0.0
ps calc 10 0.0
```

```
ps_calc_11 0.0
ps_calc_12 0.0
ps_calc_13 0.0
ps_calc_14 0.0
ps_calc_15_bin 0.0
ps_calc_16_bin 0.0
ps_calc_17_bin 0.0
ps_calc_18_bin 0.0
ps_calc_19_bin 0.0
ps_calc_20_bin 0.0
```

### Testing data:

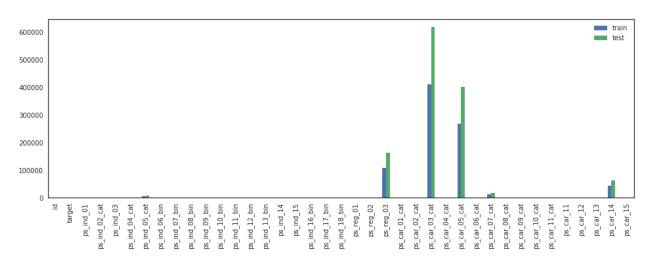
```
id 0.0
ps_ind 01 0.0
ps ind 02 cat 0.0343855844877
ps ind 03 0.0
ps ind 04 cat 0.0162407483737
ps ind 05 cat 0.975564954033
ps_ind_06_bin 0.0
ps ind 07 bin 0.0
ps ind 08 bin 0.0
ps ind 09 bin 0.0
ps ind 10 bin 0.0
ps ind 11 bin 0.0
ps ind 12 bin 0.0
ps ind 13 bin 0.0
ps_ind_14 0.0
ps_ind_15 0.0
ps ind 16 bin 0.0
ps ind 17 bin 0.0
ps ind 18 bin 0.0
ps reg 01 0.0
ps reg 02 0.0
ps reg 03 18.1094424831
ps_car_01_cat 0.0179208257917
ps car 02 cat 0.000560025805989
ps car 03 cat 69.0972159997
ps car 04 cat 0.0
ps_car_05_cat 44.842274332
ps car 06 cat 0.0
ps car 07 cat 1.94116144872
ps car 08 cat 0.0
ps car 09 cat 0.0982285263705
ps car 10 cat 0.0
ps car 11 cat 0.0
ps car 11 0.000112005161198
ps car 12 0.0
ps_car 13 0.0
ps car 14 7.14648931023
ps car 15 0.0
ps calc 01 0.0
```

#### Safe Driver Prediction

```
ps calc 02 0.0
ps calc 03 0.0
ps calc 04 0.0
ps_calc_05 0.0
ps_calc_06 0.0
ps_calc_07 0.0
ps calc 08 0.0
ps calc 09 0.0
ps calc 10 0.0
ps_calc_11 0.0
ps_calc_12 0.0
ps_calc_13 0.0
ps calc 14 0.0
ps_calc_15_bin 0.0
ps calc 16 bin 0.0
ps calc 17 bin 0.0
ps calc 18 bin 0.0
ps_calc_19_bin 0.0
ps_calc_20_bin 0.0
```

# 3.4 Checking for missing values

## Visualization of missing data:



### **Treatment of missing values:**

We have replaced missing values with the mode of the variable by above code.

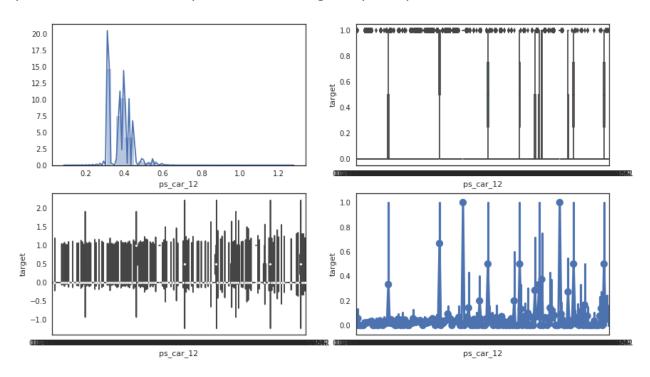
### 3.5. Checking for outliers:

We have 4 numerical variables 'ps\_reg\_03', 'ps\_car\_12', 'ps\_car\_13', 'ps\_car\_14'. We can do exploratory analysis on them:

```
train['ps reg 03'].describe()
count 595212.000000
              0.846950
mean
std
              0.328237
min
              0.061237
25%
              0.633936
50%
              0.720677
75%
              1.000000
              4.037945
max
Name: ps_reg_03, dtype: float64
train['ps_car_12'].describe()
count
       595212.000000
mean
             0.379947
             0.058300
std
             0.100000
min
25%
             0.316228
50%
             0.374166
75%
             0.400000
max
             1.264911
Name: ps car 12, dtype: float64
train['ps car 13'].describe()
        595212.000000
count
             0.813265
mean
std
             0.224588
             0.250619
min
25%
             0.670867
             0.765811
50%
75%
             0.906190
              3.720626
Name: ps_car_13, dtype: float64
train['ps car 14'].describe()
        595212.000000
count
            0.373748
mean
std
             0.044078
```

```
min 0.109545
25% 0.353553
50% 0.368782
75% 0.396485
max 0.636396
Name: ps_car_14, dtype: float64
```

We tried making some plots of the variable to get some more insights of our variables. We can see in image upper left is distribution plot, upper right is box plot, lower left is violin plot and lower right is point plot.



There are outliers in numerical variables so we have to do the treatment of those variables. We treat it in the following way:

```
def outlier(df,columns):
    for i in columns:
        quartile_1,quartile_3 = np.percentile(df[i],[25,75])
        quartile_f,quartile_l = np.percentile(df[i],[1,99])
        IQR = quartile_3-quartile_1
        lower_bound = quartile_1 - (1.5*IQR)
        upper_bound = quartile_3 + (1.5*IQR)
        print(i,lower_bound,upper_bound,quartile_f,quartile_l)
        df[i].loc[df[i] < lower_bound] = quartile_f</pre>
```

```
df[i].loc[df[i] > upper_bound] = quartile_l

outlier(train,num_col)
outlier(test,num_col)
```

We convert all variables except 'ps\_reg\_03', 'ps\_car\_12', 'ps\_car\_13', 'ps\_car\_14' into uint8. It would be easier to process them with uint8.

## 4. Exploration of Categorical Variables:

Our target variable is a categorical variable. We will convert it into category type and drop id column from both training and testing data.

```
X = train.drop(['target','id'],axis=1)
y = train['target'].astype('category')
x_test = test.drop('id',axis=1)
```

### 5. Building Predictive Models:

#### 5.1. XGBoost Classifier:

XGBoost is an implementation of gradient boosted decision trees designed for speed and performance. The library is laser focused on computational speed and model performance, as such there are few frills. Nevertheless, it does offer a number of advanced features. We have defined one function for it as:

```
def runXGB(xtrain, xvalid, ytrain, yvalid, xtest, eta=0.1, num rounds=100, max de
pth=4):
    params = {
        'objective': 'binary:logistic',
        'max depth':max depth,
        'learning rate':eta,
        'eval metric': 'auc',
        'min child weight':6,
        'subsample':0.8,
        'colsample bytree':0.8,
        'seed':45,
        'reg lambda':1.3,
        'reg alpha':8,
        'gamma':10,
        'scale pos weight':1.6
        #'n thread':-1
    dtrain = xgb.DMatrix(xtrain, label=ytrain)
    dvalid = xgb.DMatrix(xvalid, label=yvalid)
    dtest = xqb.DMatrix(xtest)
    watchlist = [(dtrain, 'train'), (dvalid, 'test')]
    model = xgb.train(params,dtrain,num rounds,watchlist,early stopping ro
unds=50, verbose eval=50)
    pred = model.predict(dvalid,ntree limit=model.best ntree limit)
    pred test = model.predict(dtest,ntree limit=model.best ntree limit)
  return pred test, model
```

#### We have also done a k-cross validation on our model:

```
kf = StratifiedKFold(n_splits=cv,random_state=45)
pred_test_full =0
cv_score = []
i=1

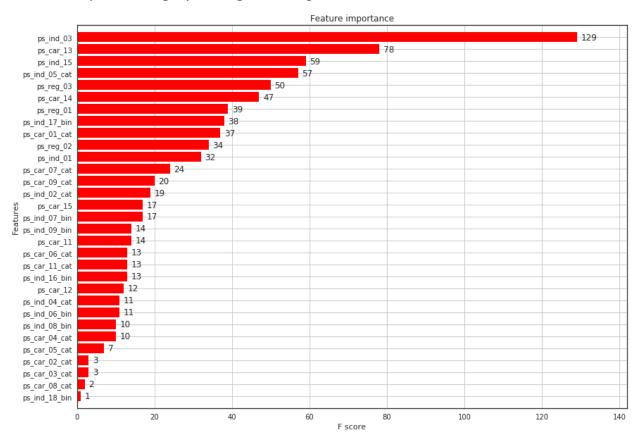
for train_index,test_index in kf.split(X,y):
    print('{} of KFold {}'.format(i,kf.n_splits))
    xtr,xvl = X.loc[train_index],X.loc[test_index]
    ytr,yvl = y[train_index],y[test_index]

    pred_test,xg_model = runXGB(xtr,xvl,ytr,yvl,x_test,num_rounds=100,eta=0.1)
```

```
pred_test_full += pred_test
cv_score.append(xg_model.best_score)
i+=1
```

We got mean cv score as 0.6367985.

### Feature importance graph in xgboost algorithm:



### 5.2 Logistic Regression:

Logistic regression is a statistical method for analyzing a dataset in which there are one or more independent variables that determine an outcome. The outcome is measured with a dichotomous variable (in which there are only two possible outcomes).

In logistic regression, the dependent variable is binary or dichotomous, i.e. it only contains data coded as 1 (TRUE, success, pregnant, etc.) or 0 (FALSE, failure, non-pregnant, etc.).

By applying grid search cv we get value of c in logistic regression as 0.1

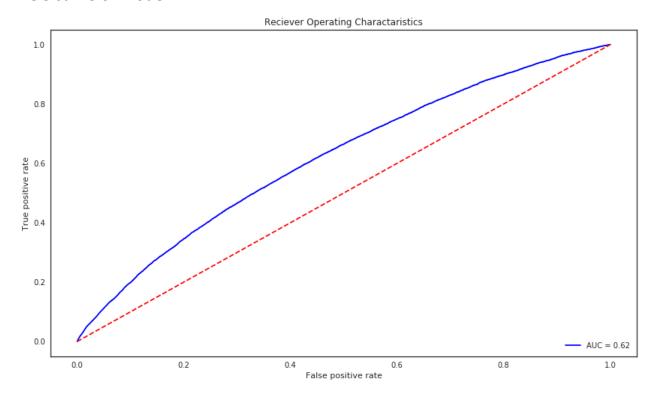
```
logreg = LogisticRegression(class_weight='balanced')
param = {'C':[0.001,0.003,0.005,0.01,0.03,0.05,0.1,0.3,0.5,1]}
clf = GridSearchCV(logreg,param,scoring='roc_auc',refit=True,cv=3)
clf.fit(X,y)
print('Best roc_auc: {:.4}, with best C: {}'.format(clf.best_score_, clf.best_params_['C']))
Best roc auc: 0.6207, with best C: 0.1
```

We used cross validation to fit our logistic regression model got mean cv score for the model as 0.620810304967.

Confusion matrix of model:

```
[[179931 106828]
[ 4974 5873]]
```

# ROC curve of model:



#### 6. Conclusion:

In the 2 models we prepared, our 1<sup>st</sup> model is quiet good as compared to our 2<sup>nd</sup> model so XGBoost classifier is very good in predicting probabilities of claim as compared to logistic regression model. In XGBoost we get roc score more than 0.636 while in logistic regression it was near to 0.62. We used roc to compare our models perfection.

### 7. Recommendations:

We can kept the value of cv as 2 in cross validation score, if we increase the value of this to 5 we will definitely get better model but it will increase the time to train the classifier.