Essay

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1 Abstract

Solving linear equations appear frequently as we know [1]. A linear equations is $A\vec{x} = \vec{b}$. We assume that we do not need to know \vec{x} itself, but we want to find a value related to \vec{x} such as $\vec{x}^\dagger M \vec{x}$, where M is a certain matrix. In the article which I introduce, consider the case where A is a matrix of $N \times N$ with up to s non-zero components per row and the condition number is κ , the fastest known classical algorithm can calculate $\vec{x}, \vec{x}^\dagger M \vec{x}$ in a time scale of $N \sqrt{\kappa}$. On the other hand, in the quantum algorithm presented here, when the state $|b\rangle$ corresponding to \vec{b} is available, the computational steps to find $|x\rangle$ can be computed on a polynomial time scale of $\log(N)$ and κ .

2 Introduction

A quantum computer is a device that uses quantum mechanics to perform calculations, including calculations that are expected to be faster than currently known algorithms from classical computers. For certain problems, such as Shor's algorithm, a quantum computer can perform calculations much faster than a classical computer. In the paper I introduce, the characteristics of the solution of a linear system of equations is considerd.

Linear systems of equations have applications in almost every field of science, technology, and engineering, and flequently appear [1]. On a classical computer, it generally takes at least N orders of time to solve a N-variable linear equation.

In this paper, we use equation as

$$A\vec{x} = \vec{b}$$
.

If A is a $N \times N$ matrix with up to s non-zero components per row, and the condition number is κ , then it shows that it takes a polynomial time scale of $\log(N)$, κ to compute the values associated with the solution $|x\rangle$ to any precision. This is an exponential speedup compared to a classical computer. Also, in typical cases, accuracy of estimated $|x\rangle$ is not very large [1]. However, the condition number can significantly increase the computational complexity. This is a strong constraint of the algorithm in this paper.

We will consider the same conditions as in the linear equation above. First, we consider \vec{b} to be the matrix representation of the abstract state $|b\rangle$. Note that \vec{b} and $|b\rangle$ are not necessarily equivalent.

3 Preliminary

3.1 Basics of Quantum Computation

A qubit is the smallest unit of storage for quantum information. In a two-level basis, a pure state $|\psi\rangle$ can be expressed as $|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$, with $|0\rangle$, $|1\rangle$ as the bases, where α, β are complex constants, $|\alpha|^2 + |\beta|^2 = 1$. A quantum register is a sequence of qubits prepared in different Hilbert spaces, represented here using tensor products as $|0\rangle \otimes |1\rangle \otimes \cdots |1\rangle$. A quantum gate is an operation on a quantum register, and the desired state is achieved by a combination of several different unitary operators. (which are also known to be unitary operators). A quantum circuit is a sequence of quantum gates in several steps. We difine an quantum gate as an operator which is applied to a quantum register. Measurement is the operation of reading information from the final state. It refers to knowing $p_k = |c_k|^2$ from the final state $\sum_{k=0}^{2^n-1} c_k |k\rangle$, repeating the execution and measurement of the circuit, and recording the number of times $0, 1, \ldots, 2^{n-1}$ is obtained. Estimate $\{p_k\}$ from the histogram.

4 Main Result

Here is the specific algorithm. We difine the algorithm "HHL Algorithm." We assume that A is Hermitian, and difine $\tilde{\lambda}_k$ as $\tilde{\lambda}_k := 2\pi k/t_0$.

1. Prepare the state $|b\rangle$ corresponding to \vec{b} by [2].

¹Condition number is an upper bound on the uncertainty of the solution of a linear equation and is defined as the maximum ratio of the relative error of x divided by the relative error of b.

- 2. By [2], similarly prepares the state $|\Psi_0\rangle := \sqrt{\frac{2}{T}} \sum_{\tau=0}^{T-1} \sin \frac{\pi \left(\tau + \frac{1}{2}\right)}{T} |\tau\rangle$.
- 3. $\sum_{\tau=0}^{T-1} |\tau\rangle\langle\tau| \otimes e^{iA\tau t_0/T} \text{ (unitary) }^2 \text{ on } |\Psi_0\rangle \otimes |b\rangle, \text{ where } t_0 = O(\kappa/\epsilon).$
- 4. Perform Quantum Fourier Transformation on the first register (register with initial state $|\Psi_0\rangle$).
- 5. Add a qubit and apply rotation depending on the value of $\tilde{\lambda}_k$.
- 6. Inverse Fourier Transformation.
- 7. Do the inverse transform of 4.
- 8. Measure the last qubit; a 1 means success and a 0 means failure.

With the above algorithm, when the state $|b\rangle$ corresponding to the quantity \vec{x} can be prepared, the computation step to find the remaining $\vec{x}^{\dagger}M\vec{x}$.

5 Discussion

Subsection 5.1 and 5.2 are based on 'Quantum Computation and Quantum Information' (QCQI).

²Make the operator $e^{iA\tau t_0/T}$ by [3].

5.1 Quantum Fourier Transformation

Quantum Fourier transformation (QFT) is a operation which converts $|j\rangle$ as

$$\begin{split} |j\rangle &\to \frac{1}{2^{n/2}} \sum_{k=0}^{2^{n}-1} e^{2\pi i j k/2^{n}} |k\rangle \\ &= \frac{1}{2^{n/2}} \sum_{k_{1}=0}^{1} \cdots \sum_{k_{n}=0}^{1} e^{2\pi i j \left(\sum_{l=1}^{n} k_{l} 2^{-l}\right)} |k_{1} \dots k_{n}\rangle \\ &= \frac{1}{2^{n/2}} \sum_{k_{1}=0}^{1} \cdots \sum_{k_{n}=0}^{1} \bigotimes_{l=1}^{n} e^{2\pi i j k_{l} 2^{-l}} |k_{l}\rangle \\ &= \frac{1}{2^{n/2}} \bigotimes_{l=1}^{n} \left[\sum_{k_{l}=0}^{1} e^{2\pi i j k_{l} 2^{-l}} |k_{l}\rangle\right] \\ &= \frac{1}{2^{n/2}} \bigotimes_{l=1}^{n} \left[|0\rangle + e^{2\pi i j 2^{-l}} |1\rangle\right] \\ &= \frac{\left(|0\rangle + e^{2\pi i 0.j_{n}} |1\rangle\right) \left(|0\rangle + e^{2\pi i 0.j_{n-1}j_{n}} |1\rangle\right) \cdots \left(|0\rangle + e^{2\pi i 0.j_{1}j_{2}\cdots j_{n}} |1\rangle\right)}{2^{n/2}}. \end{split}$$

This operation is implemented by

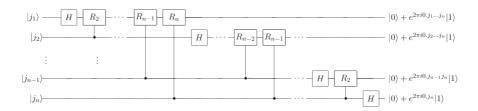


Figure 1: Example of QFT

5.2 **Quantum Phase Estimation**

Quantum Phase Estimation (QPE) is an algorithm for estimating the phase of eigenvalue of unitary operator U, which is calculated by applying QFT. The specific algorithm is as follows.

Inputs:

- (1) A black box wich performs a controlled- U^{j} operation, for integer j
 - (2) an eigenstate $|u\rangle$ of U with eigenvalue $e^{2\pi i \varphi_u}$
 - (3) $t = n + \lceil \log(2 + \frac{1}{2\epsilon}) \rceil$ qubits initialized to $|0\rangle$.

Outputs: An *n*-bit approximation $\widetilde{\varphi_u}$ to φ_u .

Runtime: $O(t^2)$ operations and one call to controlled- U^j black box. Succeeds with probability at least $1 - \epsilon$.

Procedure:

- 1. $|0\rangle|u\rangle$
- 2. $\rightarrow \frac{1}{\sqrt{2^t}} \sum_{j=0}^{2^t-1} |j\rangle |u\rangle$ create superposition 3. $\rightarrow \frac{1}{\sqrt{2^t}} \sum_{j=0}^{2^t-1} |j\rangle U^j |u\rangle = \frac{1}{\sqrt{2^t}} \sum_{j=0}^{2^t-1} e^{2\pi i j \varphi_u} |j\rangle |u\rangle$ apply black
- 4. $\rightarrow |\widetilde{\varphi_u}\rangle |u\rangle$ apply inverse Fourier transform 5. $\rightarrow \widetilde{\varphi_u}$ measure first register

If this is realized by a quantum circuit, it is as follows.

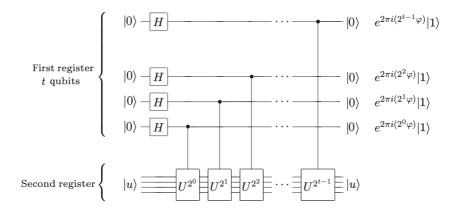


Figure 2: Examples of a part of QPE

5.3 Detail analysis of HHL Algorithm

In the following, we will explain why the algorithm introduced in the Main Result works well. First, in [3], the matrix A can be computed in $\exp(iAt)$ with $O(\log(N)s^2t)$ as the upper bound.

Next, we divide the cases according to whether the matrix A is Hermitian or not.

If A is not Hermitian, then

$$\tilde{A} := \left(\begin{array}{cc} 0 & A \\ A^{\dagger} & 0 \end{array} \right).$$

Since \tilde{A} is Hermitian by definition,

$$\tilde{A}\vec{y} = \begin{pmatrix} \vec{b} \\ 0 \end{pmatrix}.$$

By solving above,

$$\vec{y} = \begin{pmatrix} 0 \\ \vec{x} \end{pmatrix}.$$

is obtained. Thus, when A is not Hermitian, the series of operations to define \tilde{A} and make it solvable is called reduction.

In the following, we consider the case where A is Hermitian. By [2], if b_i and $\sum_{i=i_1}^{i_2} |b_i|^2$ are efficiently computable, then state $|b\rangle$ can be converted to a superposition for any probability amplitude in any basis. We will denote $|b\rangle$ by the superposition of the eigenvectors (choose a unit vector) of A. For the probability amplitude, we consider assigning a component of \vec{b} . Now we also define $|u_j\rangle$ as the eigenvectors of A, and λ_j as the corresponding eigenvalues. Define a state $|\Psi_0\rangle$ as

$$|\Psi_0\rangle := \sqrt{\frac{2}{T}} \sum_{\tau=0}^{T-1} \sin \frac{\pi \left(\tau + \frac{1}{2}\right)}{T} |\tau\rangle.$$

where T is assumed to be a very large value. Then, apply step of 3 in Main Result. By Fourier Transformation of the first register (the register whose initial state is $|\Psi_0\rangle$), we get

$$\sum_{j=1}^{N} \sum_{k=0}^{T-1} \alpha_{k|j} \beta_j |k\rangle |u_j\rangle.$$

We can add a qubit and rotate by the value of $\tilde{\lambda}_k$ to get

$$\sum_{j=1}^{N} \sum_{k=0}^{T-1} \alpha_{k|j} \beta_j |k\rangle |u_j\rangle \left(\sqrt{1 - \frac{C^2}{\tilde{\lambda}_k^2}} |0\rangle + \frac{C}{\tilde{\lambda}_k} |1\rangle \right).$$

However, C is $O(1/\kappa)$. Phase estimation allows us to calculate $|k\rangle$ backwards. If phase estimation is perfect, then $\alpha_{k|j} = 1$ if $\tilde{\lambda}_k = \lambda_j$, and 0 otherwise.

Then,

$$\sum_{j=1}^{N} \beta_j |u_j\rangle \left(\sqrt{1 - \frac{C^2}{\lambda_j^2}} |0\rangle + \frac{C}{\lambda_j} |1\rangle \right).$$

If we measure the last qubit, we get last

$$\sqrt{\frac{1}{\sum_{j=1}^{N} C^2 \left|\beta_j\right|^2 / \left|\lambda_j\right|^2}} \sum_{j=1}^{N} \beta_j \frac{C}{\lambda_j} \left|u_j\right\rangle.$$

This corresponds to $|x\rangle = \sum_{j=1}^{n} \beta_j \lambda_j^{-1} |u_j\rangle$.

6 Conclusion

Solving the linear system of equations $A\vec{x} = \vec{b}$ is an important problem in any field [1], and it is not necessary to know \vec{x} itself, but if we want to find a quantity related to \vec{x} , such as $\vec{x}^{\dagger}M\vec{x}$, we can use Quantum Fourier Transformation to find it probabilistically. The success probability depends on the condition number κ . When the state $|b\rangle$ corresponding to \vec{b} is ready, the computational step to find $|x\rangle$ can be computed on a polynomial time scale of $\log(N), \kappa$. This is an exponential speedup compared to the fastest known algorithm on a classical computer if $|b\rangle$ is available.

7 Reference

References

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