# Multithread 实验

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#### 一、实验目的

在向 hash 表中插入项时,若使用单线程不会产生遗漏,但是使用多线程会产生遗漏。实验要求向插入过程加入锁,使插入表项在多线程运行的情况下也可以达到正确的结果,并且实现使多线程操作表项的 CPU 效率更高。

## 二、实验原理

并发编程由于不同线程可以访问同一个变量。在资源竞争的情况下就会产生程序运行结果不确定的后果。在 ph.c 中可以看到,在命中 hash 桶之后采取 insert 操作:

```
if(e){
    // update the existing key.
    e->value = value;
} else {
    // the new is new.
    insert(key, value, &table[i], table[i]);
}
static void
insert(int key, int value, struct entry **p, struct entry *n)
{
    struct entry *e = malloc(sizeof(struct entry));
    e->key = key;
    e->value = value;
    e->next = n;
    *p = e;
}
```

而 insert 函数并不是原子的。如果有两个 thread 同时 insert,由于 e->next = n 和\*p = e 两条语句并不原子,可能会丢 entry。如果在执行 insert 函数的时候时间 片结束开始执行另一个线程的 insert 函数,就会导致插入失败。

```
yangmy@ubuntu:~/xv6-labs-2021$ ./ph 1
100000 puts, 19.489 seconds, 5131 puts/second
0: 0 keys missing
100000 gets, 21.583 seconds, 4633 gets/second
```

```
yangmy@ubuntu:~/xv6-labs-2021$ ./ph 2
100000 puts, 9.727 seconds, 10281 puts/second
0: 15617 keys missing
1: 15617 keys missing
200000 gets, 23.546 seconds, 8494 gets/second
```

而 C 语言中 pthread.h 头文件的库中包含的 pthread\_mutex\_lock(&lock)可以让线程获得一个互斥锁,让资源只能由获得锁的线程访问,保证程序执行的确定性。在这个实验中,对于 hash 表的每一个桶,再插入时应该为一个原子操作,因此声明 NKEYS 个锁,对应于 hash 表的所有桶。在加上锁之后只有相应 hash 桶的值可以访问资源,这样就防止插入操作被打断。

#### 三、实验内容

1、上下文进程切换

通过执行 swtch 函数实现该过程: swtch(ctx1, ctx2);

保存 callee 寄存器的内容到 ctx1 中;恢复所有的 ctx2 的内容到 callee 寄存器里。

thread\_switch 只需要保存/恢复 callee-save registers。原因是: switch 是按照一个普通函数来调用的,对于有些寄存器,swtch 函数的调用者默认 swtch 函数会修改。所以调用者已经在自己的栈上保存了这些寄存器,当函数返 回时这些寄存器会自动回恢复。

```
void
sched(void)
{
 int intena;
 struct proc *p = myproc();
 if(!holding(&p->lock))
   panic("sched p->lock");
 if(mycpu()->noff != 1)
   panic("sched locks");
 if(p->state == RUNNING)
   panic("sched running");
 if(intr_get())
   panic("sched interruptible");
 intena = mycpu()->intena;
 swtch(&p->context, &mycpu()->context);
 mycpu()->intena = intena;
}
```

定义 context switches 存储上下文切换时需保存的 14 个 callee 寄存器的结构体。参照了 kernel/proc.h 中的 struct context 的定义,因为 struct context 的注释中写明了 struct context 也是保存 context switches 的结构体。( // Saved registers for kernel context switches.)

```
struct context {
  uint64 ra;
  uint64 sp;

// callee-saved
  uint64 s0;
  uint64 s1;
  uint64 s2;
  uint64 s3;
  uint64 s4;
  uint64 s5;
  uint64 s6;
  uint64 s7;
  uint64 s8;
```

```
uint64 s9;
 uint64 s10;
 uint64 s11;
};
在 thread 结构体中添加 struct context context;用以保存上下文线程切换时
需要恢复的寄存器的值。
struct thread {
 char
           stack[STACK_SIZE]; /* the thread's stack */
                           /* FREE, RUNNING, RUNNABLE */
 int
           state;
 struct context context;
};
在添加函数体值时参考了 kernel/proc.c 中 scheduler(void) 函数的
swtch(&c->context, &p->context); 实现上下文线程切换。
void
thread schedule(void)
 struct thread *t, *next_thread;
 /* Find another runnable thread. */
 next thread = 0;
 t = current_thread + 1;
 for(int i = 0; i < MAX_THREAD; i++){</pre>
   if(t >= all_thread + MAX_THREAD)
     t = all thread;
   if(t->state == RUNNABLE) {
    next_thread = t;
    break;
   }
   t = t + 1;
 }
 if (next_thread == 0) {
   printf("thread_schedule: no runnable threads\n");
   exit(-1);
 }
 */
   next_thread->state = RUNNING;
   t = current_thread;
   current_thread = next_thread;
   /* YOUR CODE HERE
    * Invoke thread_switch to switch from t to next_thread:
```

```
* thread_switch(??, ??);
   */
   thread_switch((uint64)&t->context,
(uint64)&current_thread->context);
 } else
   next_thread = 0;
通过阅读函数体得知 thread_create(void (*func)())函数主要进行线程的初
始化操作: 其先在线程数组中找到一个状态为 FREE 即未初始化的线程, 然后设
置其状态为 RUNNABLE 等进行初始化。传递的 thread_create() 参数 func
需要记录,这样在线程运行时才能运行该函数。这一功能对应于 ra 寄存器。线程
进行调度切换时,需要保存和恢复寄存器状态。这一功能对应于 sp 寄存器。
thread_create(void (*func)())
{
 struct thread *t;
 for (t = all_thread; t < all_thread + MAX_THREAD; t++) {</pre>
   if (t->state == FREE) break;
 t->state = RUNNABLE;
 // YOUR CODE HERE
 t->context.ra = (uint64) func;
 t->context.sp = (uint64) t->stack + STACK_SIZE;
}
```

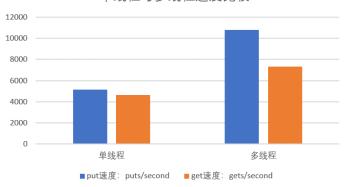
```
thread_a 89
thread_b 89
thread_c 90
thread_b 90
thread_b 90
thread_c 91
thread_a 91
thread_a 91
thread_a 91
thread_a 91
thread_a 92
thread_a 92
thread_a 92
thread_b 92
thread_b 93
thread_b 93
thread_b 93
thread_b 93
thread_a 94
thread_a 94
thread_a 94
thread_a 95
thread_a 95
thread_a 95
thread_a 95
thread_a 95
thread_a 96
thread_a 96
thread_b 96
thread_b 96
thread_b 97
thread_b 98
thread_c 98
thread_b 99
thread_c 99
thread_c 99
thread_b 99
thread_b 99
thread_b 99
thread_b 99
thread_b 99
thread_c exit after 100
thread_b: exit after 100
thread_schedule: no runnable threads
```

2、pthread\_mutex\_t lock[NKEYS]将所声明为全局变量,并在 main 函数中将其初始化: pthread\_mutex\_init(lock, NULL)。对竞争资源 table 加上锁,如图所示:

```
static
       void put(int key, int value)
          int i = key % NBUCKET;
        // is the key already present?
          struct entry *e = 0;
          for (e = table[i]; e != 0; e = e->next) {
            if (e->key == key)
              break;
          pthread_mutex_lock(&lock[i]);  // acquire lock
          if(e){
            // update the existing key.
            e->value = value;
          } else {
            // the new is new.
            insert(key, value, &table[i], table[i]);
          pthread mutex unlock(&lock[i]);  // release lock
       1}
        static struct entry*
        get(int key)
          int i = key % NBUCKET;
          //pthread_mutex_lock(&lock[i]); // acquire lock
          struct entry *e = 0;
          for (e = table[i]; e != 0; e = e->next) {
            if (e->key == key) break;
          //pthread mutex unlock(&lock[i]); // release lock
          return e;
    结果如图所示:
        yangmy@ubuntu:~/xv6-labs-2021$ ./ph 2
100000 puts, 9.273 seconds, 10784 puts/second
0: 0 keys missing
1: 0 keys missing
200000 gets, 27.268 seconds, 7335 gets/second
    运行 make grade 的结果如下:
make[1]: Leaving directory '/home/yangmy/xv6-labs-2021'
ph safe: OK (19.8s)
== Test ph_fast == make[1]: Entering directory '/home/yangmy/xv6-labs-
make[1]: 'ph' is up to date.
make[1]: Leaving directory '/home/yangmy/xv6-labs-2021'
ph fast: OK (56.4s)
    成功通过准确性和速度测试。
    将单线程和多线程的运行结果的速度进行比较,做出速度对比图如下:
```

2021'

## 单线程与多线程速度比较



可见单线程速度远低于多线程。

#### 3 barrier

```
通过阅读实验要求和代码得知 barrier.c 文件的要求是使创建的线程循环 loop
次,每次循环需要使所有线程都进行过一遍之后再开始下一轮循环。因此可知,
播报条件为 bstate.nthread==nthread,此时
pthread_cond_broadcast(&bstate.barrier_cond)。否则线程在此等待,并
将 bstate.nthread 自增 1,表示进行过 barrier 的线程数量增加 1.
static void
barrier()
{
 pthread_mutex_lock(&bstate.barrier_mutex);
 bstate.nthread++;
 if (bstate.nthread < nthread) {</pre>
   pthread cond wait(&bstate.barrier cond,
&bstate.barrier_mutex);
 }
 else {
   bstate.round++;
   bstate.nthread = 0;
   pthread_cond_broadcast(&bstate.barrier_cond);
 }
 pthread_mutex_unlock(&bstate.barrier_mutex);
}
执行结果:
  gmy@ubuntu:~/xv6-labs-2021$ ./barrier 2
```

OK; passed

实验结果:

## 四、实验中遇到的问题

**}**;

1、由于需要存储线程切换时的状态,所以需要在

结构体中添加存储寄存器的结构 struct context context; 从 kernel/proc.h 中可以找到功能一样的结构体 struct context,因此刚开始的想法是直接使用 #include "kernel/proc.h" 从而使用已经定义好的 struct context。但是会产生以下报错信息:

```
/uthread.c
In file included from user/uthread.c:4:
./kernel/proc.h:29:24: error: 'NCPU' undeclared here (not in a function)
29 | extern struct cpu cpus[NCPU];
./kernel/proc.h:86:19: error: field 'lock' has incomplete type
86 | struct spinlock lock',
./kernel/proc.h:101:3: error: unknown type name 'pagetable_t'
101 | pagetable_t pagetable; // User page table
./kernel/proc.h:104:22: error: 'NOFILE' undeclared here (not in a function); did you mean 'T_FILE'?
104 | struct file *ofile[NoFILE]: // Open files
user/uthread.c: In function 'thread_schedule':
user/uthread.c:68:20: error: passing argument 1 of 'thread_switch' makes integer from pointer without a cast [-Werror=int conversion]
68 | thread_switch(st->context, &current_thread->context);

user/uthread.c:23:27: note: expected 'uint64' (aka 'long unsigned int') but argument is of type 'struct context *'
23 | extern void thread_switch(uint64, uint64);
user/uthread.c:68:33: error: passing argument 2 of 'thread_switch' makes integer from pointer without a cast [-Werror=int conversion]
68 | thread_switch(&t->context, &current_thread->context);

user/uthread.c:23:35: note: expected 'uint64' (aka 'long unsigned int') but argument is of type 'struct context *'
23 | extern void thread_switch(uint64, uint64);
ccl: all warnings being treated as errors
make: *** | cbuiltin>: user/uthread.o] Error 1
```

于是不引入 kernel/proc.h, 直接在 uthread.c 中再定义 context 结构体。成功解决问题。

2、 在修改 thread\_schedule(void)函数时,刚开始使用 thread\_switch 的方式是: thread\_switch(&t->context, &current\_thread->context);从逻辑上没有问题,但是会出现以下报错:

通过阅读报错信息得知是输入参数的类型与定义不符。因此使用强制类型转换:

thread\_switch((uint64)&t->context,

(uint64)&current\_thread->context); 修改后成功解决问题。

3、由于书上所给的例子都为对线程加锁, 所以一开始也尝试对线程加锁:

Put 函数的第二个参数为线程数。运行结果如图:

```
yangmy@ubuntu:~/xv6-labs-2021$ ./ph 2
100000 puts, 3.530 seconds, 28328 puts/second
1: 15048 keys missing
0: 15048 keys missing
200000 gets, 10.019 seconds, 19962 gets/second
```

发现依然出现未命中的情况。这是由于加锁应该保护的是访问的变量而不是线程。后 改为给每个桶加上锁。

2、在实验中给桶枷锁时,还尝试了加在遍历桶之前并在 get 函数中也加入锁。这时实验结果是正确的,但是速度比加在 insert 函数中慢。这是因为遍历桶环节和 get 函数对键值插入 hash 桶没有影响,因为在退出线程时寄存器会记录线程运行状态。在遍历之前加锁会使遍历环节无法并行执行,因此速度变慢。代码和执行情况如图:

```
static
void put(int key, int value)
  int i = key % NBUCKET;
  // is the key already present?
  pthread_mutex_lock(&lock[i]);
                                        // acquire lock
  struct entry \overline{*}e = 0;
  for (e = table[i]; e != 0; e = e->next) {
     if (e->key == key)
       break;
  if(e){
     // update the existing key.
     e->value = value;
   } else {
     // the new is new.
     insert(key, value, &table[i], table[i]);
                                        // release lock
  pthread mutex unlock(&lock[i]);
static struct entry*
get(int key)
  int i = key % NBUCKET;
  struct entry *e = 0;
  for (e = table[i]; e != 0; e = e->next) {
     if (e->key == key) break;
  pthread_mutex_unlock(&lock[i]); // release lock
  return e;
}
gcc -o ph -g -O2 -DSOL_THREAD -DLAB_THREAD notxv6/ph.c -pthread make[1]: Leaving directory '/home/yangmy/xv6-labs-2021'
ph_safe: OK (35.5s)
== Test ph_fast == make[1]: Entering directory '/home/yangmy/xv6-labs-2021'
make[1]: 'ph' is up to date.
make[1]: Leaving directory '/home/yangmy/xv6-labs-2021'
ph_fast: OK (83.2s)
```

## 五、实验总结

在实验过程中,我对锁的使用条件和使用方式有了更深刻的理解,了解了加锁对多线程程序正确进行的重要作用,并学着分析应当在那些地方加锁。