

Locking

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Linear elasticity

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- ▶ Equation from Hooke's Law (small deformations, isotropic media)
 - ▶ $-2\mu\nabla \cdot \epsilon(u) + \lambda\nabla(\nabla \cdot u) = f$

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- ▶ λ and μ are the material-dependent Lamé parameters
 - ▶ λ is tied to compressibility, larger λ means harder to change the volume ratio
 - ▶ μ is tied to stiffness, larger μ means harder to deform keeping the same volume ratio

Simplest form

- ▶ Dirichlet boundary conditions
- ▶ The elasticity equation is given by:

$$\begin{aligned} -2\mu \nabla \cdot \epsilon(u) - \lambda \nabla \nabla \cdot u &= f \text{ in } \Omega, \\ u &= g \text{ on } \partial\Omega \end{aligned}$$

Weak form

Multiply by test function and integrate:

$$-2\mu \int_{\Omega} (\nabla \cdot \epsilon(u)) \cdot v \, dx - \lambda \int_{\Omega} \nabla(\nabla \cdot u) \cdot v \, dx = \int_{\Omega} f \cdot v \, dx$$

Integration by parts:

$$2\mu \int_{\Omega} \epsilon(u) \cdot \nabla v \, dx + \lambda \int_{\Omega} (\nabla \cdot u)(\nabla \cdot v) \, dx = \int_{\Omega} f \cdot v \, dx$$

$A : B = A : B_S$ if $A = A^T$:

$$2\mu \int_{\Omega} \epsilon(u) \cdot \epsilon(v) \, dx + \lambda \int_{\Omega} (\nabla \cdot u)(\nabla \cdot v) \, dx = \int_{\Omega} f \cdot v \, dx$$

Weak form cont.

Find $u \in H_0^1$ such that

$$a(u, v) = f(v), \forall v \in H_0^1$$

where

$$a(u, v) = 2\mu(\epsilon(u), \epsilon(v)) + \lambda(\nabla \cdot u, \nabla \cdot v),$$

$$f(v) = (f, v)$$

Locking

- ▶ Locking arises from numerical errors when $\lambda \gg \mu$
- ▶ Difficulty in optimizing:
 - ▶ $\nabla(u - u_h)$
 - ▶ $\nabla \cdot (u - u_h) = 0$

at the same time

Locking from an optimisation standpoint

Solving the elasticity equation with the finite element method is equivalent to solving

$$\min_{u_h \in U_h} \|u - u_h\|_a^2 = \min_{u_h \in U_h} (\mu \|\nabla(u - u_h)\|_{L^2}^2 + \lambda \|\nabla \cdot (u - u_h)\|_{L^2}^2). \quad (1)$$

To understand locking, we let $\lambda \rightarrow \infty$ and obtain

$$\begin{aligned} \min_{u_h \in U_h} \|\nabla(u - u_h)\|_{L^2}^2 \\ \text{s.t. } (\nabla \cdot (u - u_h), \nabla \cdot v_h) = 0 \quad \text{for all } v_h \in U_h. \end{aligned} \quad (2)$$

We can introduce a solid pressure, p , to circumvent locking

We introduce the solid pressure variable

$$p = \lambda \nabla \cdot u, \quad (3)$$

which, when used in the linear elastic equations becomes

$$\begin{aligned} -\mu \Delta u - \nabla p &= f, \\ \nabla \cdot u - \frac{1}{\lambda} p &= 0, \end{aligned}$$

which, as $\lambda \rightarrow \infty$ becomes Stokes equation.

We want to use the finite element method and need the weak form

Find $u \in H_0^1$ and $p \in L^2$ such that

$$a(u, v) + b(p, v) = (f, v) \quad \forall v \in H^1$$

$$b(q, u) - c(p, q) = 0 \quad \forall q \in \mathbb{R}$$

where

$$a(u, v) = (\epsilon(u), \epsilon(v))$$

$$b(p, v) = (p, \nabla \cdot v)$$

$$c(p, q) = \frac{1}{\lambda}(p, q)$$

To understand why c is stabilising, we use the saddle point formulation

Solving the weak form of the two-field linear elastic equations is equivalent to solving the saddle point problem

$$\max_{p \in Q_h} \min_{u \in V_h} \left\{ \overbrace{a(u, u) - (f, u) + b(p, u)}^{\text{Bounded below}} - \underbrace{\frac{1}{\lambda}(p, p)}_{\text{Bounded above}} \right\}$$

where λ^{-1} works as a regulariser which means that we can circumvent the inf-sup condition.

Numerical experiments

Let's consider a concrete example, where we have a true u given by

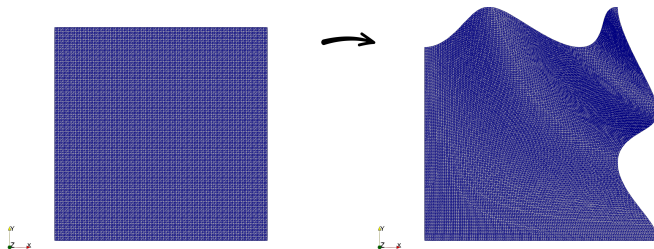
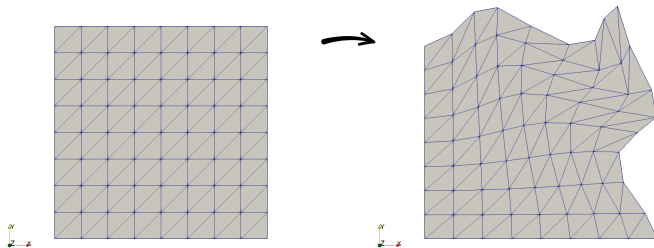
$$u = \left(\frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial x} \right)$$

where

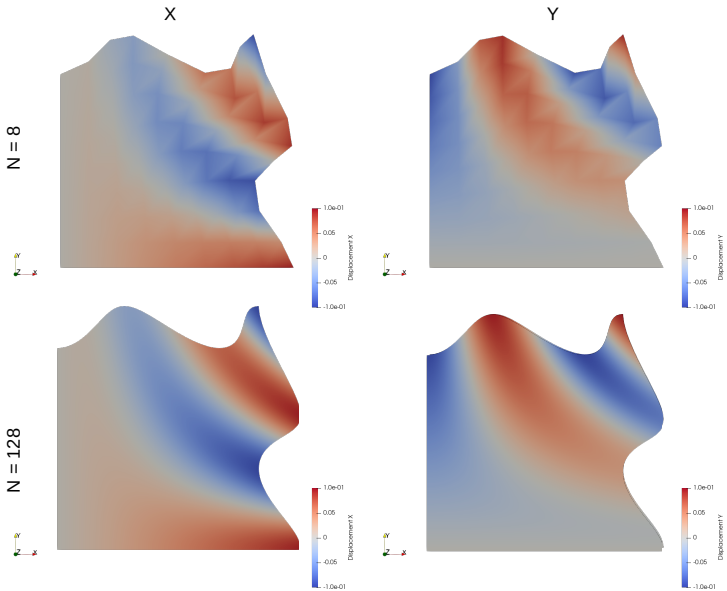
$$\phi = \frac{1}{100} \sin(3xy\pi)$$

implemented in FEniCS with assigned Dirichlet boundary conditions. Here the true divergence should be 0, meaning our solution should be dependent on μ only.

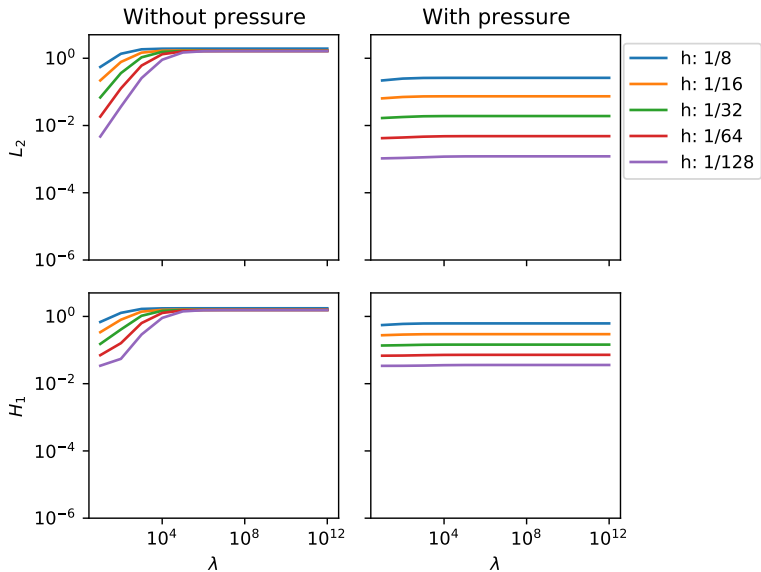
Deformation and meshes



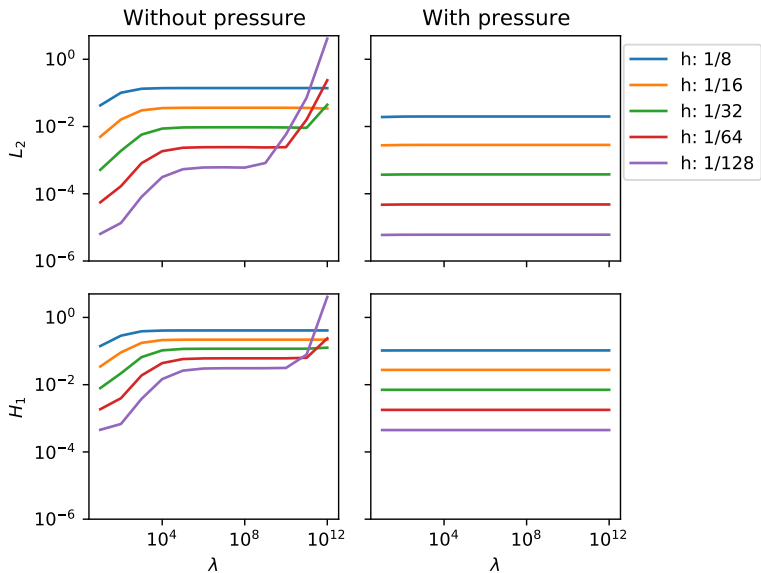
Deformation, component-wise



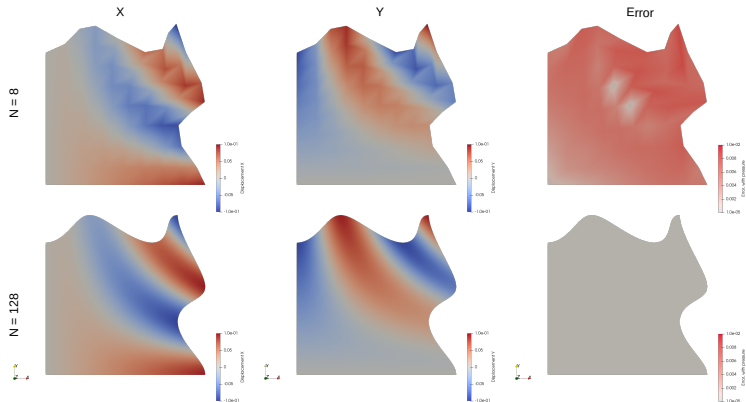
Relative Error, both u and p in CG-1



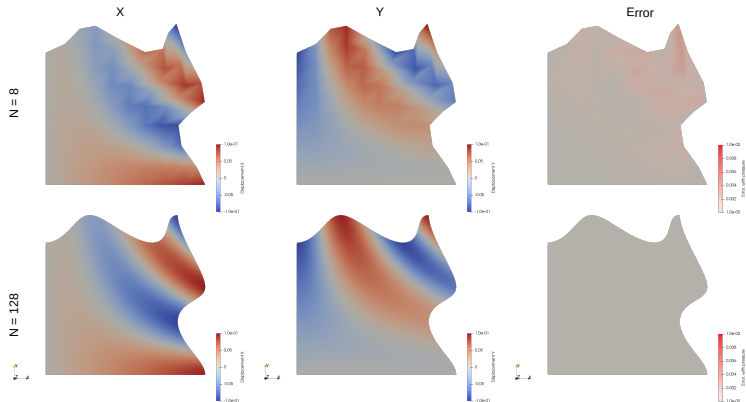
Relative Error, u in CG-2 and p in CG-1



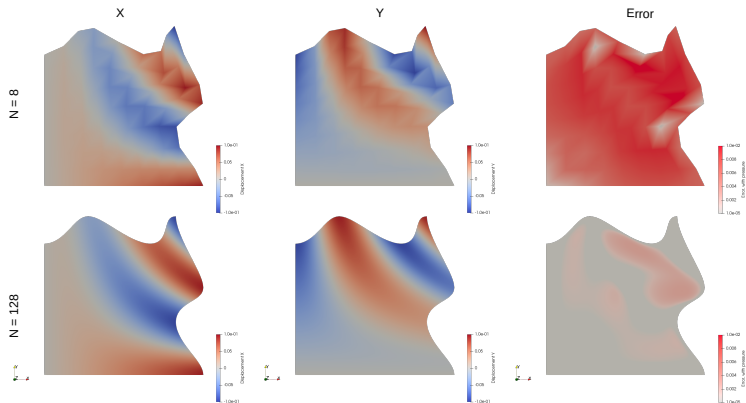
Spatial plot of u , $\lambda = 10$ without solid pressure



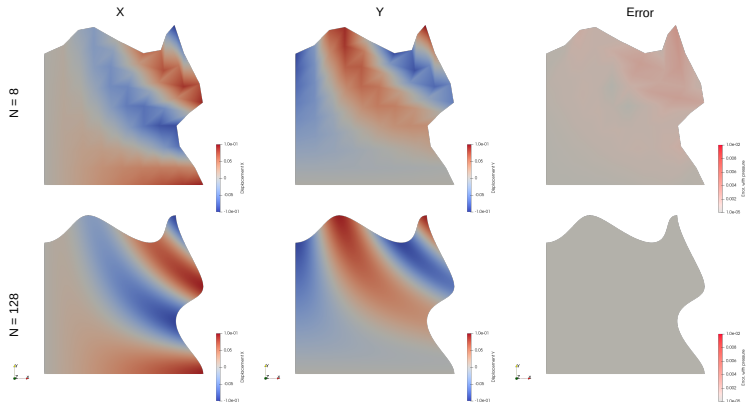
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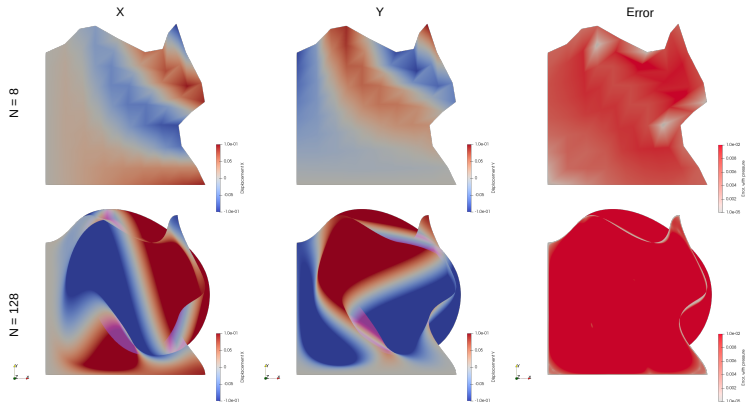
Spatial plot of u , $\lambda = 10^6$, without solid pressure



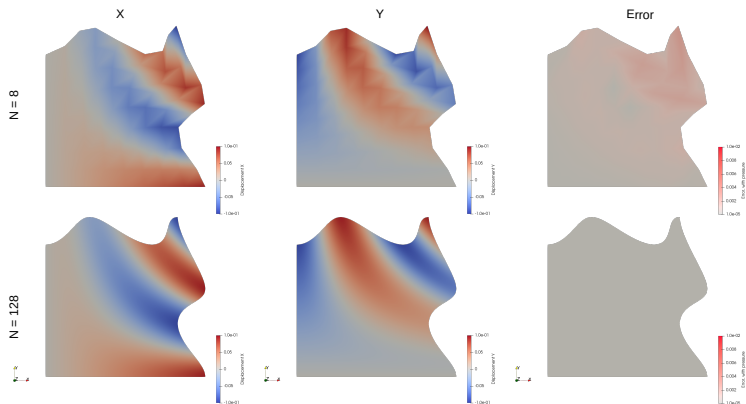
Spatial plot of u , $\lambda = 10^6$, with solid pressure



Spatial plot of u , $\lambda = 10^{12}$, without solid pressure



Spatial plot of u , $\lambda = 10^{12}$, with solid pressure



Conclusions

If in doubt, use a solid pressure formulation.

Code is available at:

<https://github.com/yngvem/MEK9250-Elastic-Locking>