

D

C

B

A

D

C

B

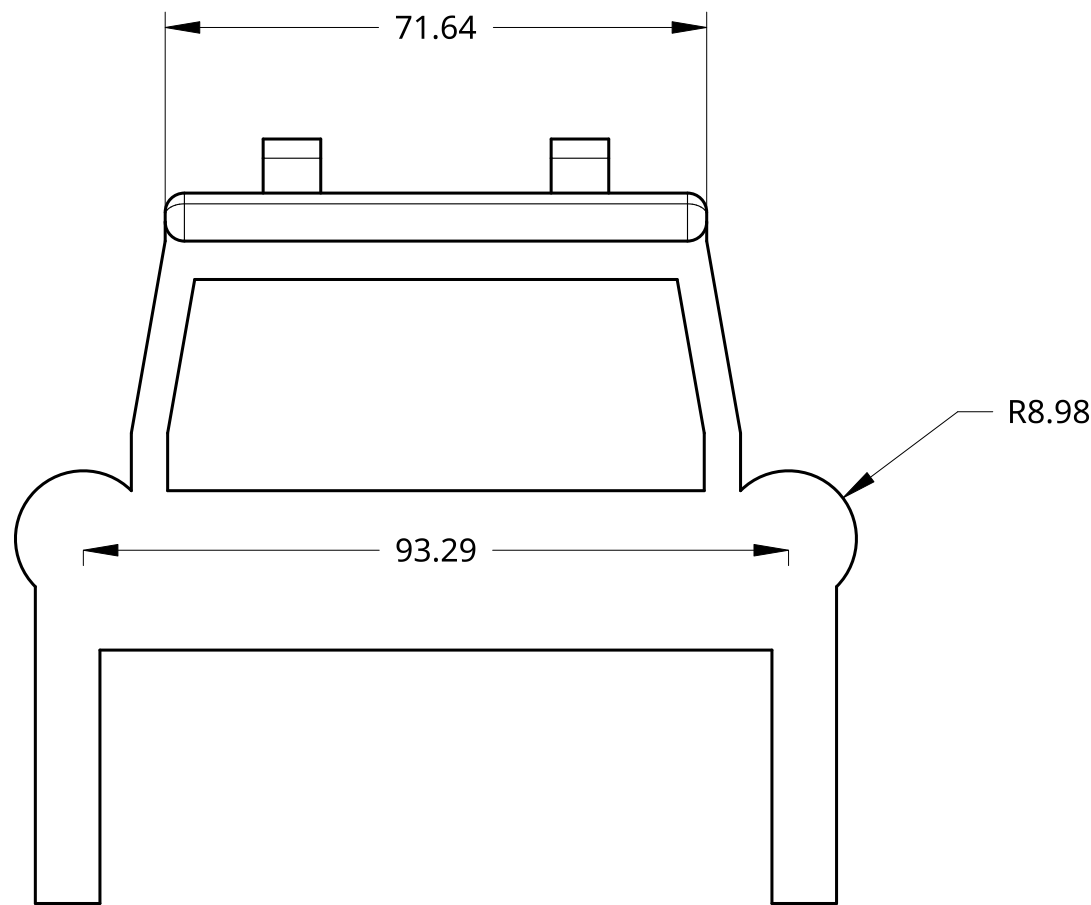
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4

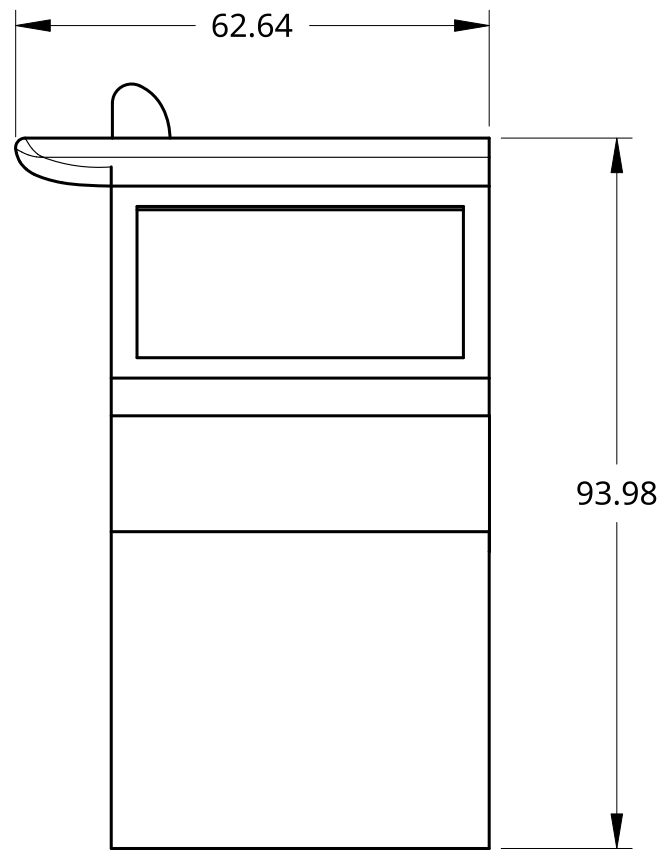
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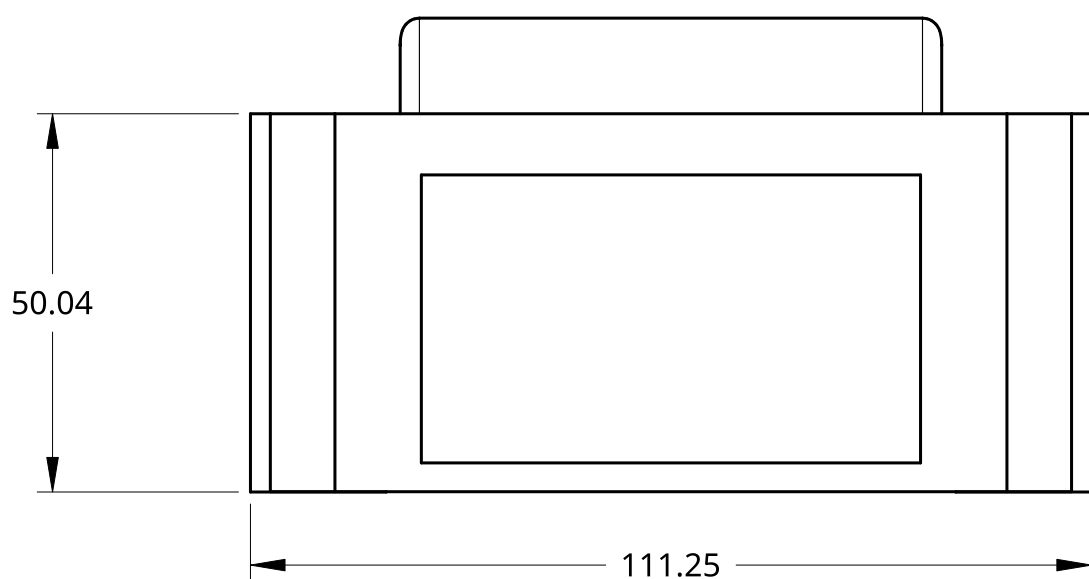
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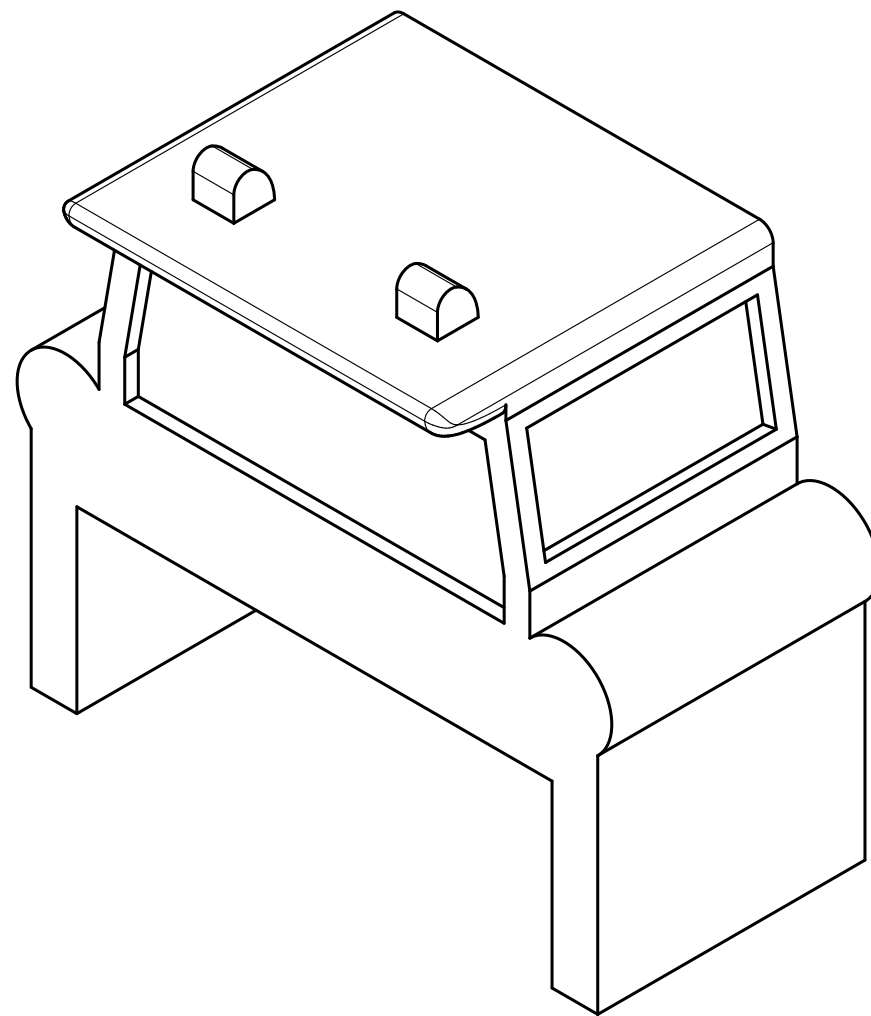
FRONT VIEW




RIGHT SIDE VIEW



TOP VIEW



ISOMETRIC VIEW

	COMPANY NAME:	NAME:	ACTIVITY NO. / ACTIVITY NAME: Task 3: 2D and 3D Design of Mobile Articulated Manipulator Robot	DESIGNED BY: RAYNIEL LESTER PINEDA	REVISIONS:	DATE:	SUBMITTED TO:	SHEET CONTENTS:	SHEET NUMBER:	
		COMPANY 4 - CARTESIAN MANIPULATOR							Part 1 of Mobile Articulated Manipulator Robot All units are in millimeters.	2 OUT OF 3
		PROGRAM:		CADD BY: BRYAN EVANGELISTA						
		BS MECHATRONICS ENGINEERING		CHECKED BY: ENGR. MIKKO DE TORRES						
		ECE 415 - MICROPROCESSOR AND MICROCONTROLLER SYSMTMS AND DESIGN		DATE: JULY 24, 2023						



Task 3: 2D and 3D
Design of Mobile
Articulated
Manipulator Robot

ENGR. MIKKO DE TORRES

Part 1 of Mobile
Articulated
Manipulator
Robot
All units are in
millimeters.

2 OUT OF 3

4

3

2

1