

D

C

B

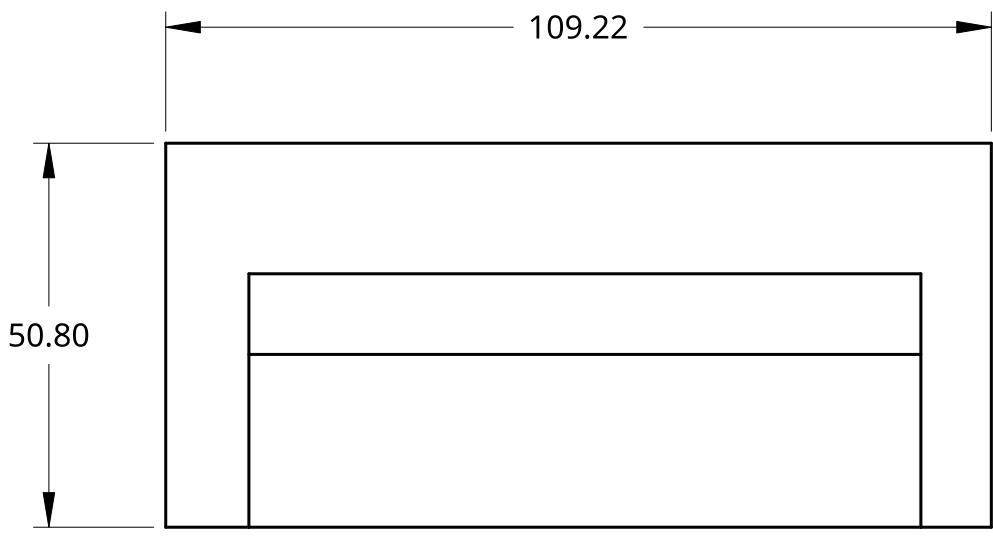
A

D

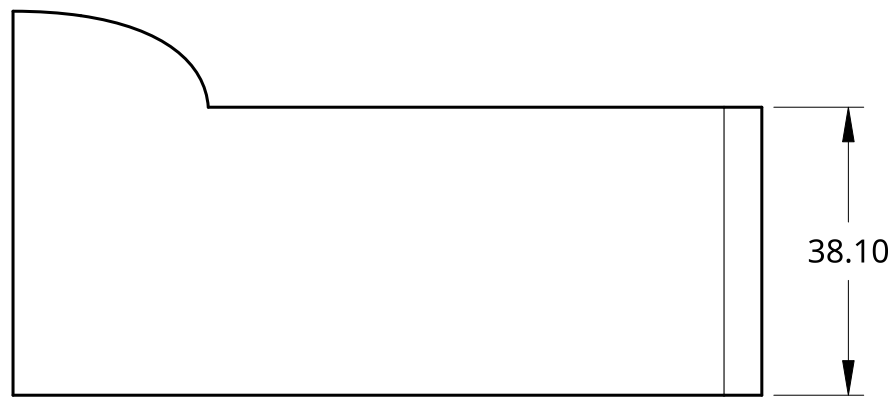
C

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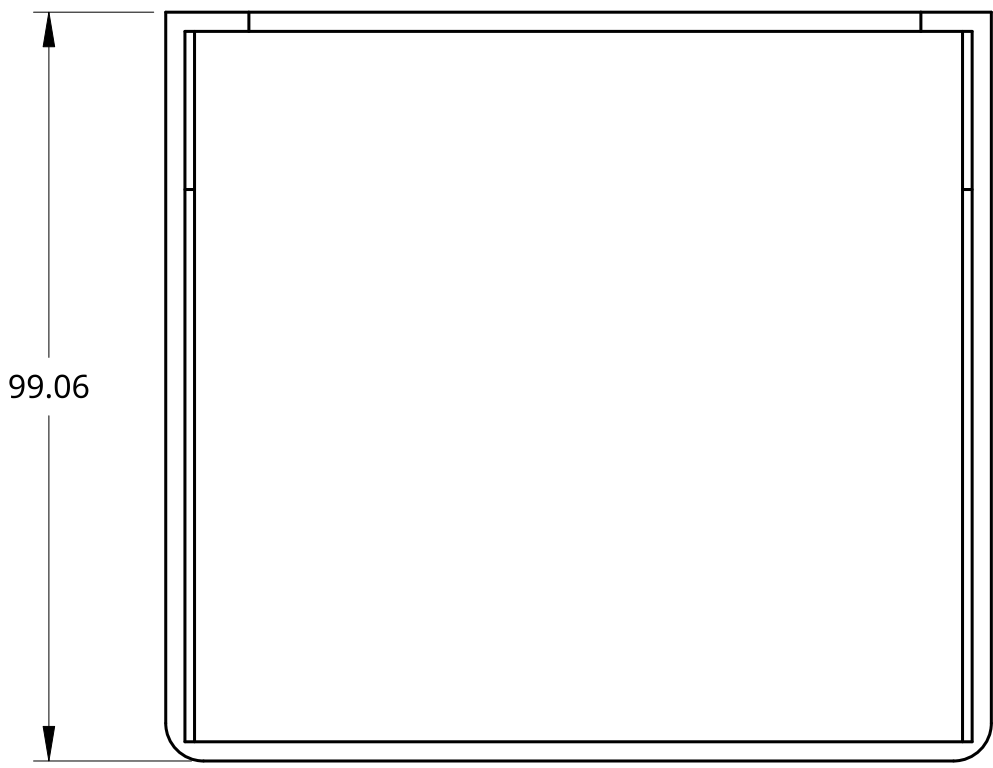
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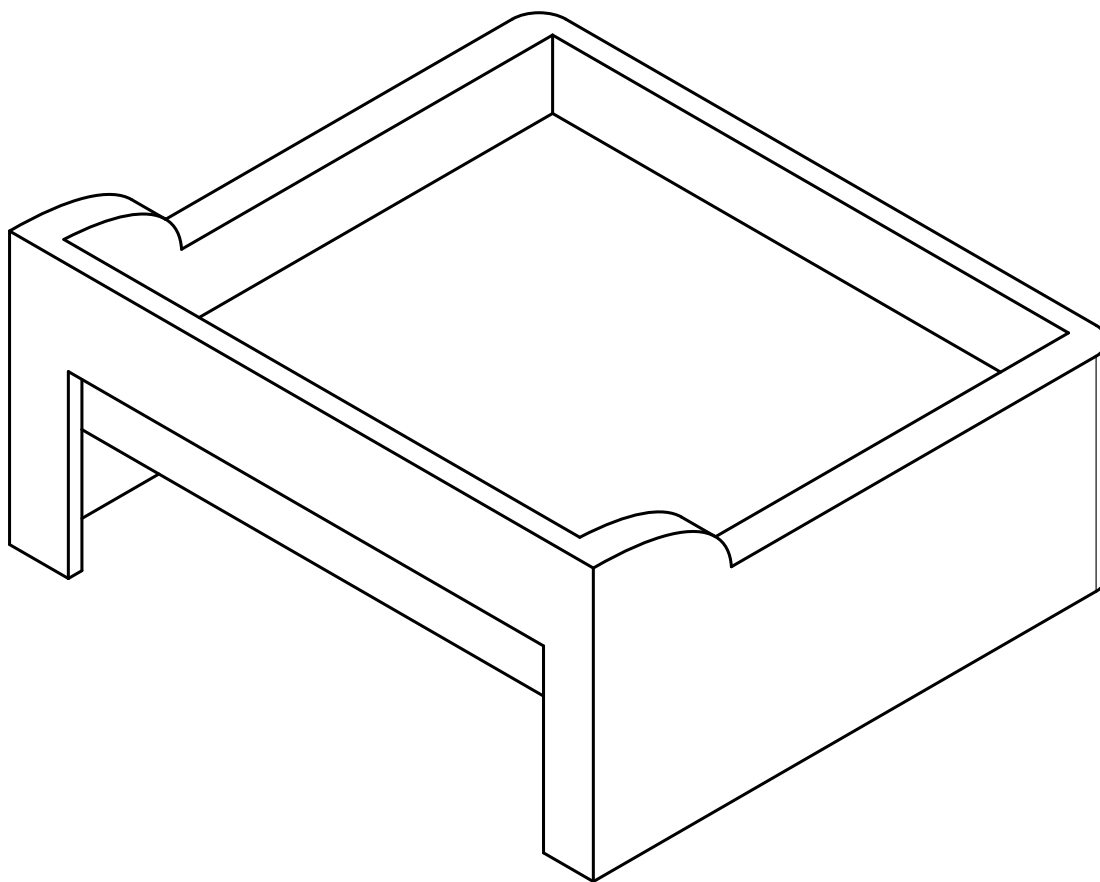
FRONT VIEW



RIGHT SIDE VIEW



TOP VIEW



ISOMETRIC VIEW

	COMPANY NAME:	NAME:	ACTIVITY NO. / ACTIVITY NAME:  <b>Task 3: 2D and 3D Design of Mobile Articulated Manipulator Robot</b>	DESIGNED BY: <b>RAYNIEL LESTER PINEDA</b>	REVISIONS:	DATE:	SUBMITTED TO:	SHEET CONTENTS:	SHEET NUMBER:	
		<b>COMPANY 4 - CARTESIAN MANIPULATOR</b>						<b>ENGR. MIKKO DE TORRES</b>	<b>Part 1 of Mobile Articulated Manipulator Robot</b>  All units are in millimeters.	3 OUT OF 3
		PROGRAM:		CADD BY: <b>BRYAN EVANGELISTA</b>						
		BS MECHATRONICS ENGINEERING		CHECKED BY: <b>ENGR. MIKKO DE TORRES</b>						
		ECE 415 - MICROPROCESSOR AND MICROCONTROLLER SYSMTMS AND DESIGN		DATE: <b>JULY 24, 2023</b>						