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1 Basic Test Results

```
"MacBook Pro" is in the tree.
1
    "iPod" is not in the tree.
    "iPhone" is in the tree.
    "iPad" is in the tree.
4
    "Apple Watch" is in the tree.
    "Apple TV" is not in the tree.
    The number of products in the tree is 4.
9
10
    Name: Apple Watch.
                           Price: 299.00
                          Price: 1499.00
    Name: MacBook Pro.
11
                   Price: 499.00
    Name: iPad.
12
    Name: iPhone.
                     Price: 599.00
    test passed
14
15
   Running...
16
   Opening tar file
17
18
    OK
   Tar extracted O.K.
19
20
21
    Checking files...
22
   Making sure files are not empty...
23
24
   Compilation check...
25
26
   Compiling...
27
   Compiling...
28
29
   OK
   Compiling...
30
   OK
31
    Compiling...
   OK
33
34
    {\tt Compiling...}
35
   Compilation seems OK! Check if you got warnings!
36
37
38
   ===============
39
    Public test cases
41
42
    43
    ~ ProductExample output: ~
44
45
46
    Running test...
47
    ~ End of ProductExample output ~
49
    50
51
52
53
   Test Succeeded.
54
55
56
    **********
57
       presubmission script passed *
58
```

```
60 ****************
61
62
63 = Checking coding style =
64
RBTree.c(472, 5): fname_case {Do not start function name(RBTreeContains) with uppercase}
66
   RBTree.c(472, 5): fname_case {Do not start function name(RBTreeContains) with uppercase}
   RBTree.c(472, 5): fname_case {Do not start function name(RBTreeContains) with uppercase}
67
    ** Total Violated Rules : 3

** Total Errors Occurs : 3
68
   ** Total Errors Occurs
69
   ** Total Violated Files Count: 1
70
```

2 RBTree.c

```
#include <stdio.h>
1
2
    #include "stdlib.h"
    #include "RBTree.h"
    #include "string.h"
4
    #define RIGHT 0
6
    #define LEFT 1
8
    #define SUCCESS 1
    #define FAILURE 0
9
10
    //EX3 - RED BLACK TREES by your eshed 305384869
11
12
13
    int deleteFromTree(Node *M, RBTree *tree);
14
15
     * A function that checks if a nodes color is black, null nodes counts as black
16
     * Oparam node : the node which is being tested
17
     * @return : 1 if the node is black, 0 if not
18
19
    int isBlack(Node *node)
20
21
         if ((node == NULL) || (node->color == BLACK))
22
23
24
            return SUCCESS;
25
        return FAILURE;
26
27
28
29
30
     * A function that checks if a nodes color is red
31
     * Oparam node : the node which is being tested
     * Oreturn : 1 if the node is red, 0 if not
33
34
    int isRed(Node *node)
35
36
         if (node == NULL)
37
38
            return FAILURE;
39
40
        return node->color == RED;
41
42
    }
43
44
     * A function that retrieves the Parent node of a node
45
     * Oparam node : the node whose Parent will be retrieved
46
     * @return: node if found , else returns NULL
47
48
    Node *getParent(Node *node)
49
50
         if (node == NULL)
51
52
            return NULL;
53
54
55
        return node->parent;
56
    }
57
58
    * A function that retrieves the sibling of a node
```

```
60
       st Oparam node : the node whose sibling will be returned
 61
       st Oreturn: node if found , else returns NULL
 62
 63
     Node *getSibling(Node *node)
 64
         Node *parent = getParent(node);
 65
 66
         if (parent == NULL)
 67
 68
              return NULL;
 69
         }
 70
 71
          if (node == parent->left)
 72
         {
              return parent->right;
 73
 74
         }
         return parent->left;
 75
     }
 76
 77
 78
 79
      * A function that retrieves the grandparent of the node
 80
      * @param node :node
      * @return : the grand parent node
 81
 82
     Node *getUncle(Node *node)
 83
 84
         if (node != NULL)
 85
 86
              return getSibling(getParent(node));
 87
 88
 89
         return NULL;
 90
     }
91
 92
 93
      * A function that retrieves the grandparent of the node
      * @param node :node
 94
 95
      * Oreturn : the grand parent node
 96
     Node *getGrandParent(Node *node)
97
 98
         if (node != NULL)
99
100
              return getParent(getParent(node));
101
102
103
         return NULL;
     }
104
105
106
      * A function that gets a successor for a node in an bst
107
108
      * Oparam node : the node that will get a successor
      * @return the successor node if found , null if not
109
110
111
     Node *getSuccessor(Node *node)
112
         if (node != NULL)
113
114
              Node *successor = node;
115
116
                  while (successor->left != NULL)
117
118
119
                      successor = successor->left;
120
121
                  return successor;
122
              }
123
         return NULL;
124
125
126
127 /**
```

```
128
      * A function that retrieves a node as a successor to a node in a bst
129
      * @param node: the node to find a successor to
      * Creturn: A node - if the node has two leaves the function returns the most left node
130
131
      st At the right sub tree, ,if the node has two leaves it returns null;
132
133
     Node *bstSuccessor(Node *node)
134
          if (node->left != NULL && node->right != NULL)
135
136
             return getSuccessor(node->right);
137
         }
138
139
          if (node->left == NULL && node->right == NULL)
140
         {
             return NULL;
141
142
         }
         if (node->left != NULL)
143
144
145
             return node->left;
146
147
          return node->right;
148
     }
149
150
151
152
      * A function the rotates a node inside a tree by moving the node and its parent and grand parent
153
      * nodes to the right while conserving the tree balancing attributes of the tree
      * @param node: the node to be rotated
154
155
     void rotateRight(Node *node)
156
157
158
          Node *newNode = node->left;
         Node *P = node->parent;
159
         if (newNode->right != NULL)
160
161
             newNode->right->parent = node;
162
163
         }
         node->left = newNode->right;
164
         node->parent = newNode;
165
         newNode->right = node;
166
         newNode->parent = P;
167
         if (P != NULL)
168
169
              if (P->right == node)
170
171
                  P->right = newNode;
172
             }
173
174
              else
              {
175
176
                  P->left = newNode;
177
         }
178
     }
179
180
181
      * A function the rotates a node inside a tree by moving the node and its parent and grand parent
182
      * nodes to the left while conserving the tree balancing attributes of the tree
183
      * Oparam node: the node to be rotated
184
185
     void rotateLeft(Node *node)
186
187
         Node *newNode = node->right;
188
189
         Node *P = node->parent;
190
          if (newNode->left != NULL)
191
         {
             newNode->left->parent = node;
192
         }
193
         node->right = newNode->left;
194
195
         node->parent = newNode;
```

```
196
         newNode->left = node;
197
         newNode->parent = P;
         if (P != NULL)
198
199
              if (P->left == node)
200
201
              {
                  P->left = newNode;
202
              }
203
204
              else
              {
205
                  P->right = newNode;
206
              }
207
         }
208
     }
209
210
211
      * A an aiding function for case 4 of insertion
212
213
      * @param tree:
      * Oparam node: the node to be inserted
214
215
216
     void caseFour(RBTree *tree, Node *node)
217
218
         Node *G = getGrandParent(node);
         Node *P = node->parent;
219
220
         //phase A
         if (node == P->left)
221
222
223
              rotateRight(G);
              if (getGrandParent(node) == NULL)
224
225
              {
226
                  tree->root = node->parent;
              }
227
         }
228
229
         else
              //phase B
230
231
              rotateLeft(G);
232
              if (getGrandParent(node) == NULL)
233
234
              {
                  tree->root = node->parent;
235
              }
236
237
          //phase C
238
         P->color = BLACK;
239
          G->color = RED;
240
     }
241
242
243
244
      * A function the re-aligns a red black tree and repairs any violations
      * @param root : the tree root
^{245}
      * Oparam curNode: the node that needs to be checked for violations
246
247
248
     void fixTree(RBTree *tree, Node *node)
249
250
          Node *U = getUncle(node);
         Node *P = getParent(node);
251
         Node *G = getGrandParent(node);
252
253
         if (tree->compFunc(tree->root->data, node->data) == 0)
254
255
              node->color = BLACK;
^{256}
257
         }
258
          //case 2
         else if (isBlack(P))
259
260
          {
261
              return;
262
         //case 3
263
```

```
264
          else if (isRed(P) && isRed(U))//alarm
265
             P->color = BLACK;
266
267
             U->color = BLACK;
             G->color = RED;
268
269
             fixTree(tree, G);
270
         }
         else
271
272
         {
              if (node == P->right && P == G->left)
273
274
275
                  rotateLeft(P);
                  if (getGrandParent(node) == NULL)
276
277
278
                      tree->root = node->parent;
279
280
                  node = node->left;
281
              else if (node == P->left && P == G->right)
282
283
284
                  rotateRight(P);
                  if (getGrandParent(node) == NULL)
285
286
                      tree->root = node->parent;
287
                  7
288
                  node = node->right;
289
290
291
              caseFour(tree, node);
292
     }
293
294
295
296
      * An Aiding function for inserting nodes into an bst search tree
297
      * @param root : root of the three
      * Oparam node: the node which is going to be inserted
298
299
      * Oparam tree : Red black tree object
      * Oreturn: the node if the insertion is successful , NULL if not
300
301
302
     Node *insertNode(Node *root, Node *node, RBTree *tree)
303
304
          if (root == NULL)
305
306
          {
307
             return node;
308
         int res = tree->compFunc(root->data, node->data);
309
310
          if (res > 0)
311
312
             root->left = insertNode(root->left, node, tree);
             root->left->parent = root;
313
         }
314
315
         else if (res < 0)
316
         {
              root->right = insertNode(root->right, node, tree);
317
             root->right->parent = root;
318
319
320
         return root;
     }
321
322
323
      * A function for removing a node entirely from a red black tree
324
325
      * @param root :three root
326
      * Oparam tree : Red black tree object
327
     void deleteNode(Node **root, RBTree *tree)
328
329
         if (*root == NULL)
330
331
          {
```

```
332
             return;
333
         deleteNode(&(*root)->left, tree);
334
335
          deleteNode(&(*root)->right, tree);
          tree->freeFunc((*root)->data);
336
         free(*root);
337
     }
338
339
340
      * A function that swaps data between two nodes
341
      * @param a : first data object
342
343
      * @param b : second data object
344
     void swapNodes(Node *a, Node *b)
345
346
          if (a == NULL || b == NULL)
347
348
349
             return;
350
351
         void *tmp = a->data;
352
         a->data = b->data;
         b->data = tmp;
353
     }
354
355
356
      * A function that traverses the tree recursively and checks if there value exists in it.
357
      * Oparam root : the root of the tree been searched on.
358
359
      * Oparam data : that data that is being searched
      * Oparam compFunc: a comparison function
360
361
      * Oreturn: 1 if the value exists in the tree, 0 if not.
362
     Node *searchTree(Node *root, const void *data, CompareFunc compFunc)
363
364
365
          if (root == NULL)
366
          ₹
367
             return NULL;
368
         int res = compFunc(root->data, data);
369
          if (res == 0)
370
         {
371
372
             return root;
         }
373
         if (res > 0)
374
375
             return searchTree(root->left, data, compFunc);
376
         }
377
378
          if (res < 0)
379
         {
380
             return searchTree(root->right, data, compFunc);
381
         return EXIT_SUCCESS;
382
     }
383
384
385
      * A function that preforms in order traverse on the tree and executes a function for each node
386
      * Oparam root : A node of the tree
387
      * Oparam func : A function to be applied
388
      * Oparam args : Arguments to the function if it needs them
389
390
     void inOrderPass(Node *root, forEachFunc func, void *args)
391
392
          if (root == NULL)
393
394
          {
395
             return:
         }
396
          inOrderPass(root->left, func, args);
397
         func(root->data, args);
398
399
         inOrderPass(root->right, func, args);
```

```
400 }
401
402
403
      * constructs a new RBTree with the given CompareFunc.
404
      * compFunc: a function two compare two variables.
      * freeFunc: a function that frees allocated memory
405
406
     RBTree *newRBTree(CompareFunc compFunc, FreeFunc freeFunc)
407
408
          if (compFunc == NULL || freeFunc == NULL)
409
410
          {
411
              return NULL;
412
         RBTree *tree = (RBTree *) malloc(sizeof(RBTree));
413
414
          if (tree != NULL)
415
416
              tree->root = NULL;
              tree->compFunc = compFunc;
tree->freeFunc = freeFunc;
417
418
419
              tree->size = 0;
420
              return tree;
         }
421
         return NULL;
422
     }
423
424
425
      * add an item to the tree
426
427
      * Oparam tree: the tree to add an item to.
      * Oparam data: item to add to the tree.
428
      st Oreturn: 0 on failure, other on success. (if the item is already in the tree - failure).
429
430
     int insertToRBTree(RBTree *tree, void *data)
431
432
433
          if (tree == NULL || data == NULL)
434
          ₹
435
              return FAILURE;
436
         Node *new = (Node *) malloc(sizeof(Node));
437
          Node *tmp = tree->root;
438
         if (new == NULL)
439
440
          {
              return FAILURE;
441
         }
442
443
          if (RBTreeContains(tree, data))
444
          {
445
              free(new);
446
              return FAILURE;
         }
447
448
         new->data = data, new->color = RED, new->parent = NULL, new->left = NULL, new->right = NULL;
         if (tmp == NULL)
449
450
451
              new->color = BLACK, tree->root = new;
452
              fixTree(tree, new);
453
              tree->size++:
              return SUCCESS;
454
          }
455
         if (insertNode(tree->root, new, tree))
456
457
              fixTree(tree, new);
458
459
              tree->size++;
              return SUCCESS;
460
461
462
          free(new);
         return FAILURE;
463
     }
464
465
466
467
      * check whether the tree RBTreeContains this item.
```

```
468
      * Oparam tree: the tree to add an item to.
469
      * @param data: item to check.
      * Oreturn: O if the item is not in the tree, other if it is.
470
471
     int RBTreeContains(const RBTree *tree, const void *data)
472
473
          if (tree == NULL || data == NULL)
474
475
476
             return FAILURE;
477
         if (searchTree(tree->root, data, tree->compFunc) == NULL)
478
479
480
             return FAILURE;
         }
481
482
         return SUCCESS;
     }
483
484
485
486
487
      * A function that disconnects A node from a treee
488
      * Oparam tree : Red black tree object
      * Oparam node : The node to be removed
489
490
     void disconnect(RBTree *tree, Node *node)
491
492
493
          Node *Parent = getParent(node);
          if (Parent->right == node)
494
495
             Parent->right = NULL;
496
497
         }
498
          else if (Parent->left == node)
499
500
             Parent->left = NULL;
501
         tree->freeFunc(node->data);
502
503
     }
504
505
      * A function that handles the double black cases.
506
      * Oparam M: current node - the one marked double black
507
      * Oparam P: the node's parents node
508
      * Oparam S: the node's sibling node
509
      * Oparam C: the node's descendant node
510
511
      * Oparam tree : Red black tree object
      * Oreturn: deleted node if deletion was successful , null if not
512
513
514
     Node *doubleBlack(Node *M, Node *P, Node *S, Node *C, RBTree *tree)
515
516
          //case A
         if (M->parent == NULL)
517
518
519
             if (C != NULL)
520
             {
521
                  return C;
             }
522
             return M;
523
         }
524
         //case B
525
         if ((S == NULL) || ((isBlack(S)) && (isBlack(S->left)) && (isBlack(S->right))))
526
527
              if (isRed(P))
528
529
              {
530
                  // case B.I
                  P->color = BLACK;
531
                  if (S != NULL)
532
533
                  {
                      S->color = RED;
534
                  }
535
```

```
536
                  return M;
              }
537
                  // case B.II
538
539
              else if (isBlack(P))
              {
540
                  S->color = RED;
541
                  return doubleBlack(P, getParent(P), getSibling(P), bstSuccessor(P), tree);
542
              }
543
544
          }
545
              //case C
546
547
          else if (isRed(S))
548
              Color temp = P->color;
P->color = S->color;
549
550
              S->color = temp;
551
              if (M == P->left)
552
553
                  rotateLeft(P);
554
555
                  rotateRight(P);
                  return doubleBlack(M, P, S, C, tree);
556
              }
557
              else if (M == P->right)
558
559
              {
560
                  rotateRight(P);
                  return doubleBlack(M, P, S, C, tree);
561
              }
562
          }
563
          else
564
              //S is black
565
566
              int direction = RIGHT;
567
568
              Node *SF = NULL;
569
              Node *SC = NULL;
              if (S == P->right)
570
571
                  SF = S->right;
572
                  SC = S->left;
573
              }
574
              else if (S == P -> left)
575
576
                  SF = S->left;
577
                  SC = S->right;
578
579
                  direction = LEFT;
              }
580
              //case 3.4
581
582
              if (isBlack(SF) == 1 \&\& isRed(SC) == 1)
583
584
                  SC->color = BLACK;
                  S->color = RED;
585
586
                  if (S != NULL && S == P->right)
587
588
                      SF = S->right;
589
590
                       SC = S->left;
                  }
591
                  else if (S != NULL && S == P->right)
592
593
                  {
                      SF = S->left;
594
                      SC = S->right;
595
                      direction = LEFT;
596
                  }
597
598
                  if (direction == RIGHT)
                  {
599
                      rotateRight(S);
600
                  }
601
                  else
602
603
                  {
```

```
604
                      rotateLeft(S);
                  }
605
                  S = getSibling(M);
606
607
                  if (S != NULL && S == P->right)
                  {
608
                      SF = S->right;
609
                      SC = S->left;
610
                  }
611
612
                  else if (S != NULL && S == P->right)
613
                      SF = S->left;
614
                      SC = S->right;
615
                      direction = LEFT;
616
                  }
617
618
              }
              //case 3.5
619
              if (isRed(SF))
620
621
                  Color temp = P->color;
622
                  P->color = S->color;
623
624
                  S->color = temp;
                  SF->color = BLACK;
625
                  if (direction == RIGHT)
626
627
                  {
628
                      rotateLeft(P);
                  }
629
                  else
630
631
                  {
                      rotateRight(P);
632
                  }
633
634
                  return M;
              }
635
         }
636
637
         return NULL;
     }
638
639
640
641
642
      * A function that deletes a node from a tree
      * Oparam M : node to be replaced
643
      * @param tree : Red black tree object
644
      * @return
645
      */
646
647
     int deleteFromTree(Node *M, RBTree *tree)
648
         Node *C = bstSuccessor(M); // descendant
649
          Node *P = M->parent;
650
         Node *S = getSibling(M);
651
652
          //Case A
          swapNodes(M, C);
653
         if (isRed(M))
654
655
656
              if (C == NULL)
657
              {
658
                  disconnect(tree, M);
                  fixTree(tree, P);
659
                  return SUCCESS;
660
661
              disconnect(tree, C);
662
663
              fixTree(tree, M);
              return SUCCESS;
664
665
666
          //Case B
667
          if ((isBlack(M) == 1) && (isRed(C) == 1))
668
669
          {
              disconnect(tree, C);
670
671
              return SUCCESS;
```

```
672
         }
673
         //Case C
         if ((isBlack(M) == 1) && (isBlack(C) == 1))
674
675
              disconnect(tree, doubleBlack(M, P, S, C, tree));
676
             return SUCCESS;
677
         }
678
         return FAILURE;
679
680
     }
681
682
683
      * remove an item from the tree
      * Oparam tree: the tree to remove an item from.
684
      * @param data: item to remove from the tree.
685
686
      * Oreturn: O on failure, other on success. (if data is not in the tree - failure).
687
     int deleteFromRBTree(RBTree *tree, void *data)
688
689
     {
         Node *SUCCESSOR = searchTree(tree->root, data, tree->compFunc);
690
691
          if (SUCCESSOR == NULL || tree == NULL || data == NULL)
692
          {
             return FAILURE;
693
         }
694
         if (!RBTreeContains(tree, data))
695
696
          {
697
             return FAILURE;
         }
698
699
          if (!deleteFromTree(SUCCESSOR, tree))
700
         {
701
             return FAILURE;
702
         }
         tree->size--;
703
         return EXIT_SUCCESS;
704
705
     }
706
707
      * Activate a function on each item of the tree. the order is an ascending order. if one of the
708
      * activations of the
709
      * function returns 0, the process stops.
710
      * Oparam tree: the tree with all the items.
711
      * Oparam func: the function to activate on all items.
712
      * Oparam args: more optional arguments to the function (may be null if the given function
713
      * support it).
714
715
      * Oreturn: O on failure, other on success.
716
     int forEachRBTree(const RBTree *tree, forEachFunc func, void *args)
717
718
          if (tree->root == NULL)
719
720
          {
             return FAILURE;
721
722
723
          inOrderPass(tree->root, func, args);
724
         return SUCCESS;
     }
725
726
727
      * free all memory of the data structure.
728
      * Oparam tree: pointer to the tree to free.
729
730
731
     void freeRBTree(RBTree **tree)
732
          if (tree != NULL)
733
734
              deleteNode(&(*tree)->root, *tree);
735
736
             free(*tree);
         }
737
     }
738
739
```

 $741 \\ 742$

3 Structs.c

```
#include "Structs.h"
1
2
    #include "stdlib.h"
   #include "math.h"
   #include "string.h"
4
    #define SUCCESS 1
6
    #define FAILURE 0
8
    #define B -1
    #define A 1
9
    #define EQUAL 0
    #define SUCCESS 1
11
    #define FAILURE 0
12
13
14
     * CompFunc for Vectors, compares element by element, the vector that has the first larger
15
     * element is considered larger. If vectors are of different lengths and identify for the length
16
     * of the shorter vector, the shorter vector is considered smaller.
17
18
     * @param a - first vector
     * @param b - second vector
19
     * \bar{\text{Oreturn}} equal to 0 iff a == b. lower than 0 if a < b. Greater than 0 iff b < a.
20
21
    int vectorCompare1By1(const void *a, const void *b)
22
23
24
         if (a == NULL || b == NULL)
25
        {
26
            return FAILURE;
27
        Vector *vecA = (Vector *) a;
28
29
        Vector *vecB = (Vector *) b;
         int longerVector = B;
30
31
        int len = vecA->len;
         if (vecA->len > vecB->len)
33
        {
34
             len = vecB->len;
            longerVector = A;
35
36
         for (int i = 0; i < len; i++)
37
38
            if (vecA->vector[i] != vecB->vector[i])
39
40
                 if (vecA->vector[i] > vecB->vector[i])
41
42
                     longerVector = A;
43
44
45
                 longerVector = B;
            }
46
            if (vecA->len == vecB->len)
47
                 longerVector = 0;
49
            }
50
51
            return longerVector;
52
        return FAILURE;
53
    }
54
55
56
    * A function that gets the norm of a given vector
57
58
     * Oparam vector : the vector that norm is going to be calculated
     * @return : the vectors norm
```

```
60
 61
     double getNorm(Vector *vector)
 62
 63
          double sum = 0;
         for (int i = 0; i < vector->len; i++)
 64
 65
             sum += pow(vector->vector[i], 2);
 66
 67
 68
         return sum;
     }
 69
 70
 71
      st copy pVector to pMaxVector if : 1. The norm of pVector is greater then the norm of pMaxVector.
 72
                                            2. pMaxVector \rightarrow vector == NULL.
 73
 74
      * Oparam pVector pointer to Vector
      * Oparam pMaxVector pointer to Vector
 75
      * Oreturn 1 on success, 0 on failure (if pVector == NULL: failure).
 76
 77
     int copyIfNormIsLarger(const void *pVector, void *pMaxVector)
 78
 79
         if (pVector == NULL || pMaxVector == NULL)
 80
 81
          }
             return FAILURE;
 82
 83
 84
         Vector *vecP = (Vector *) pVector;
         Vector *vecMax = (Vector *) pMaxVector;
 85
         if (vecP == NULL || vecMax == NULL)
 86
 87
             return FAILURE;
 88
 89
         }
 90
          if (getNorm(vecP) > getNorm(pMaxVector))
 91
 92
             vecMax->len = vecP->len;
 93
             vecMax->vector = realloc(vecMax->vector, vecMax->len * sizeof(double));
             if (vecMax->vector == NULL)
 94
 95
 96
                  return FAILURE;
             }
 97
             memcpy(&vecMax->vector, &vecP->vector, vecP->len * sizeof(double));
 98
99
         return SUCCESS;
100
     }
101
102
103
      * A function that finds the vector with the maximal norm in an RBtree
104
      * Oparam tree a pointer to a tree of Vectors
105
106
      * @return pointer to a *copy* of the vector that has the largest norm (L2 Norm).
107
108
     Vector *findMaxNormVectorInTree(RBTree *tree)
109
         if (tree == NULL)
110
111
112
             return NULL;
113
         Vector *maxVec = (Vector *) malloc(sizeof(Vector));
114
         maxVec->vector = malloc(maxVec->len * sizeof(double *));
115
         maxVec->vector = NULL, maxVec->len = 0;
116
         if (maxVec == NULL | | maxVec->vector == NULL)
117
         {
118
119
              return NULL;
         }
120
         if (!forEachRBTree(tree, copyIfNormIsLarger, maxVec))
121
122
             freeVector(maxVec);
123
124
             return NULL;
         }
125
         return maxVec;
126
127 }
```

```
128
129
130
131
      * FreeFunc for vectors
132
     void freeVector(void *pVector)
133
134
          if (pVector != NULL)
135
136
              Vector *vecP = (Vector *) pVector;
137
              free(vecP->vector);
138
139
              free(pVector);
              pVector = NULL;
140
141
142
     }
143
144
145
      * CompFunc for strings (assumes strings end with "\0")
146
147
      * @param a - char* pointer
      * @param b - char* pointer
148
      * @return equal to 0 iff a == b. lower than 0 if a < b. Greater than 0 iff b < a. (lexicographic
149
150
      */
151
     int stringCompare(const void *a, const void *b)
152
153
          char *string1 = (char *) a;
char *string2 = (char *) b;
154
155
          return strcmp(string1, string2);
156
157
     }
158
159
      * ForEach function that concatenates the given word and \n to pConcatenated. pConcatenated is
160
161
      * already allocated with enough space.
      * @param word - char* to add to pConcatenated
162
163
      * @param pConcatenated - char*
164
      * Oreturn O on failure, other on success
      */
165
     int concatenate(const void *word, void *pConcatenated)
166
167
          char *word1 = (char *) word;
168
          if (word1 == NULL || pConcatenated == NULL)
169
170
171
              return FAILURE;
         }
172
         if (strcat(pConcatenated, word1) == NULL)
173
174
          {
              return FAILURE;
175
176
         }
          strcat(pConcatenated, "\n");
177
         return SUCCESS;
178
     }
179
180
181
182
      * A function to free string allocated memory
      * @param s:string to be freed
183
184
185
     void freeString(void *s)
186
187
          char *string = (char *) s;
188
         if (s != NULL)
189
190
              free(string);
191
         }
192
     }
193
194
```