

Vovk's aggregating algorithm

Mixable and unmixable loss functions

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Section 3.5 in “Prediction, Learning and Games”

Outline

Log Loss and Absolute loss

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The general prediction game

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Vovk's algorithm

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Square loss using simple averaging

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Summary table

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- ▶ The goal is to minimize the regret.

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- ▶ Is there an advantage to the algorithm relative to DTOL?

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3. Nature chooses an outcome $\omega^t \in \Omega$
4. Each expert incurs loss $\ell_t(i) = \lambda(\omega^t, \gamma_i^t)$
The learner incurs loss $\ell_t(A) = \lambda(\omega^t, \gamma^t)$

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- ▶ We say that the pair (a, c) is **achievable**.

The set of achievable bounds

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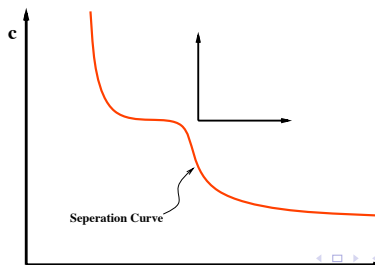
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- ▶ If $P[\omega^t = 1] = q$, $P[\omega^t = 0] = 1 - q$, then the optimal prediction is

$$\gamma^t = \begin{cases} 1 & \text{if } q > 1/2, \\ 0 & \text{otherwise} \end{cases}$$

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- ▶ Which losses behave like **entropy loss** and which behave like **hedge loss**?

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- ▶ There is **no universally optimal prediction**
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- Vovk's result: **yes!** a good choice for γ_t always exists!

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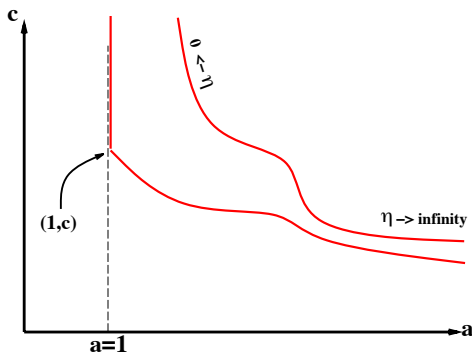
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- ▶ Equivalently - the image of the set Γ under the mapping $F(\gamma) = \langle e^{-\eta \lambda(\omega, \gamma)} \rangle_{\omega \in \Omega}$ is concave.

convexity condition: Pictorially

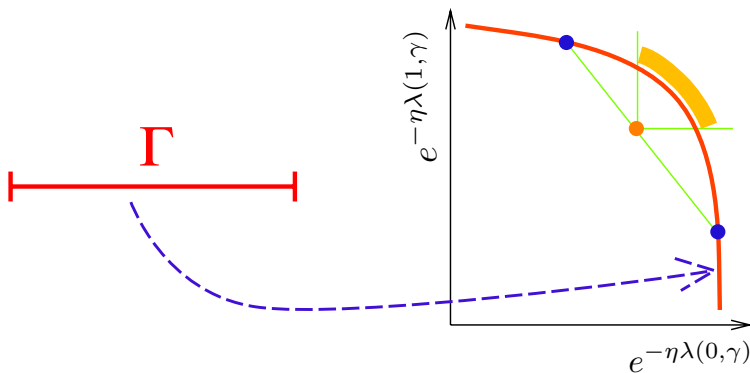
- **Example:** Suppose $\Omega = \{0, 1\}$, $\Gamma = [0, 1]$. then

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- ▶ We are back to the online Bayes algorithm.

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Summary of bounds for mixable losses

Loss Functions:	c values: ($\eta = 1/c$)	
	$\text{pred}_{\text{wmean}}(v, x)$	$\text{pred}_{\text{Vovk}}(v, x)$
$L_{\text{sq}}(p, q)$	2	$1/2$
$L_{\text{ent}}(p, q)$	1	1
$L_{\text{hel}}(p, q)$	1	$1/\sqrt{2}$

Figure 2. $(c, 1/c)$ -realizability: c values for loss and prediction