

Exponential Weights Algorithms for Online Learning

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Probably Approximately Correct (PAC) Learning

- ▶ Sample space X with a fixed but unknown distribution P .
- ▶ Concept class C , with $c \in C$ and $c : X \rightarrow \{0, 1\}$.
- ▶ **Learning Input:** A training set $\{(x_1, y_1), \dots, (x_n, y_n)\}$ drawn i.i.d. according to P , labeled by some $c \in C$.
- ▶ **Learning Output:** A concept c' such that

$$P(c(x) \neq c'(x)) \leq \epsilon$$

- ▶ **Strong PAC Learning** of C : There exists an algorithm such that for all ϵ, δ , the algorithm runs in time polynomial in $1/\epsilon$ and $1/\delta$ and outputs c' with

$$P(c(x) \neq c'(x)) \leq \epsilon$$

- ▶ **Weak PAC Learning:** Same as strong PAC, but only required to hold for a single $\epsilon < \frac{1}{2}$.

Boosting

- ▶ A boosting algorithm can translate a weak PAC learner into a strong pac learner.
- ▶ How it is done: by giving the weak learner different distributions.

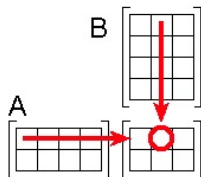
Zero sum games in matrix form

- ▶ Game between two players.
- ▶ Defined by $n \times m$ matrix \mathbf{M}
- ▶ Row player chooses $i \in \{1, \dots, n\}$
- ▶ Column player chooses $j \in \{1, \dots, m\}$
- ▶ Row player gains $\mathbf{M}(i, j) \in [0, 1]$
- ▶ Column player loses $\mathbf{M}(i, j)$
- ▶ Game repeated many times.

Pure vs. mixed strategies

- ▶ Choosing a **single** action = **pure** strategy.
- ▶ Choosing a **Distribution** over actions = **mixed** strategy.
- ▶ **Row** player chooses dist. over rows **P**
- ▶ **Column** player chooses dist. over columns **Q**
- ▶ **Row** player gains **$M(P, Q)$** .
- ▶ **Column** player loses **$M(P, Q)$** .

Mixed strategies in matrix notation



$$(A \times B)_{12} = \sum_{r=1}^4 a_{1r} b_{r2} = a_{11}b_{12} + a_{12}b_{22} + a_{13}b_{32} + a_{14}b_{42}$$

Q is a **column** vector. **P^T** is a row vector.

$$\mathbf{M}(\mathbf{P}, \mathbf{Q}) = \mathbf{P}^T \mathbf{M} \mathbf{Q} = \sum_{i=1}^n \sum_{j=1}^m \mathbf{P}(i) \mathbf{M}(i, j) \mathbf{Q}(j)$$

The minmax Theorem

When using pure strategies, second player has an advantage.

John von Neumann, 1928.

$$\min_P \max_Q \mathbf{M}(\mathbf{P}, \mathbf{Q}) = \max_Q \min_P \mathbf{M}(\mathbf{P}, \mathbf{Q})$$

In words: for **mixed** strategies, choosing second gives no advantage.

The learning game matrix

| | Example 1 | Example 2 | Example 3 |
|--------|-----------|-----------|-----------|
| Rule 1 | 0 | 1 | 0 |
| Rule 2 | 1 | 1 | 0 |
| Rule 3 | 0 | 0 | 1 |
| Rule 4 | 1 | 0 | 1 |
| Rule 5 | 0 | 1 | 1 |

entries: 1 = rule is correct on example, 0= incorrect

Boosting is implied by min/max theorem

- ▶ For any distribution **Q** over the examples there exists a row (rule) that is correct on $\frac{1}{2} + \gamma$ of the (dist over the) examples.
- ▶ From min/max theorem we get that there exists a distribution **P** over the rules such that for any example at least $\frac{1}{2} + \gamma$ of the rules are correct.
- ▶ The weighted majority is always correct.
- ▶ Existence proof, but not an algorithm.

Schapire's boosting algorithm

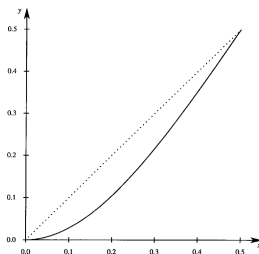
Calls the weak learner 3 times, on 3 different distributions, combines the rules using a majority.

The distributions are

- ▶ h_1 : use the training set as is.
- ▶ h_2 : Filter examples so that $P(h_1(x) = c(x)) = \frac{1}{2}$
- ▶ h_3 Filter out examples such that $h_1(x) = h_2(x)$

Idea of proof

- ▶ If errors of weak rules are at most $x < 1/2$ then error of combined rule is at most $3x^2 - 2x^3$.



- ▶ *Figure 1.* A graph of the function $g(x) = 3x^2 - 2x^3$.
- ▶ Let the available rules have error $\frac{1}{2} - \gamma$ and assume we want a rule whose error is ϵ .
- ▶ Using 3-combiner recursively for depth at most $O(\frac{1}{\gamma^2} \log \frac{1}{\epsilon})$ achieves the error ϵ .

Boost By Majority

Majority vote over many weak rules, rather than 3.

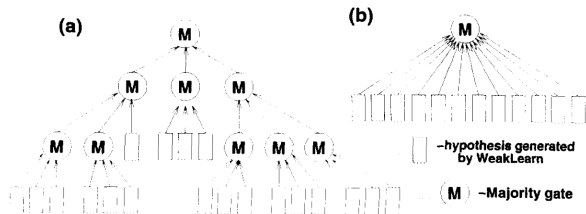


FIG. 1. Final concepts structure: (a) Schapire, (b) a one-layer majority circuit.

Game between booster and learner

- ▶ Booster chooses distribution over examples.
- ▶ Weak learner chooses where weak rules makes a mistake.
- ▶ Weak learner constrained to make weighted error smaller than $(1/2) - \gamma$

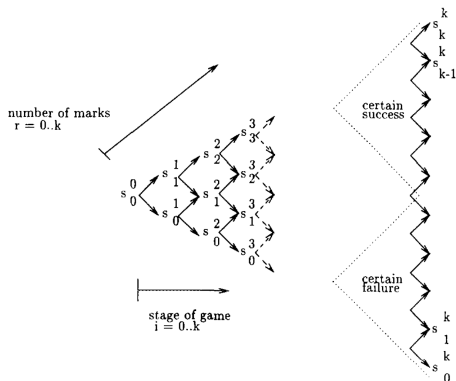


FIG. 2. Transitions between consecutive partitions.

Potential function

loss set and which are in the reward set; it is reasonable to define the potential for $i = k$ as

$$\beta_r^k = \begin{cases} 0 & \text{if } r > \frac{k}{2} \\ 1 & \text{if } r \leq \frac{k}{2}. \end{cases} \quad (4)$$

For $i < k$ we define the potential recursively:

$$\beta_r^i = (\tfrac{1}{2} - \gamma) \beta_r^{i+1} + (\tfrac{1}{2} + \gamma) \beta_{r+1}^{i+1}. \quad (5)$$

Weight function

The weighting factor is defined inductively as

$$\alpha_r^{k-1} = \begin{cases} 1 & \text{if } r = \left\lfloor \frac{k}{2} \right\rfloor \\ 0 & \text{otherwise.} \end{cases}$$

and for $0 \leq i \leq k-2$,

$$\alpha_r^i = \left(\frac{1}{2} - \gamma\right) \alpha_r^{i+1} + \left(\frac{1}{2} + \gamma\right) \alpha_{r+1}^{i+1}.$$

Potential is non increasing

- ▶ Let q_r^i be the fraction of the examples that have r mistakes on iteration i .
- ▶ Then if the booster uses the weights α_r^i then

$$\beta_0^0 > \sum_{r=0}^1 q_r^1 \beta_r^1 > \sum_{r=0}^2 q_r^2 \beta_r^2 > \dots > \sum_{r=0}^k q_r^k \beta_r^k.$$

Error bound

Given a weak learner with error $(1/2) - \gamma$, find k that satisfies

$$\sum_{j=0}^{\lfloor \frac{k}{2} \rfloor} \binom{k}{j} \left(\frac{1}{2} + \gamma\right)^j \left(\frac{1}{2} - \gamma\right)^{k-j} \leq \epsilon.$$

Then running Boost-by-majority for k iterations will generate a rule with error at most ϵ .

Hedge(η)

└ Adaboost

Adaboost

Algorithm AdaBoost (Setup)

Input:

- ▶ Sequence of N labeled examples $\langle (x_1, y_1), \dots, (x_N, y_N) \rangle$
- ▶ Distribution D over the N examples
- ▶ Weak learning algorithm *WeakLearn*
- ▶ Integer T specifying number of iterations

Initialize:

$$w_i^1 = D(i) \quad \text{for } i = 1, \dots, N.$$

Algorithm AdaBoost (Main Loop)

For $t = 1, 2, \dots, T$:

1. $p^t = \frac{w^t}{\sum_{i=1}^N w_i^t}$.
2. Call *WeakLearn*, providing the distribution p^t . Get back a hypothesis $h_t : X \rightarrow \{0, 1\}$.
3. Calculate the error of h_t :

$$\epsilon_t = \sum_{i=1}^N p_i^t |h_t(x_i) - y_i|.$$

4. Set

$$\beta_t = \frac{\epsilon_t}{1 - \epsilon_t}.$$

5. Update the weights:

$$w_i^{t+1} = w_i^t \beta_t^{(1 - |h_t(x_i) - y_i|)}.$$

Algorithm AdaBoost (Final Output)

Output the final hypothesis h_f , defined by:

$$h_f(x) = \begin{cases} 1, & \text{if } \sum_{t=1}^T (\ln \frac{1}{\beta_t}) h_t(x) \geq \frac{1}{2} \sum_{t=1}^T \ln \frac{1}{\beta_t}, \\ 0, & \text{otherwise.} \end{cases}$$

Main Theorem

Theorem 6 Suppose the weak learning algorithm **WeakLearn**, when called by **AdaBoost**, generates hypotheses with errors $\epsilon_1, \dots, \epsilon_T$. Then the error $\epsilon = \Pr_{i \sim \mathcal{D}}[h_f(x_i) \neq y_i]$ of the final hypothesis h_f is bounded above by

$$\epsilon \leq 2^T \prod_{t=1}^T \sqrt{\epsilon_t (1 - \epsilon_t)}.$$

Upper bound on total weight

$$\begin{aligned}\sum_{i=1}^N w_i^{t+1} &= \sum_{i=1}^N w_i^t \beta_t^{(1 - |h_t(x_i) - y_i|)} \\ &\leq \sum_{i=1}^N w_i^t \left(1 - (1 - \beta_t)(1 - |h_t(x_i) - y_i|)\right) \\ &\leq \left(\sum_{i=1}^N w_i^t\right) \left(1 - (1 - \epsilon_t)(1 - \beta_t)\right).\end{aligned}$$

Combining over iterations

Combining the weight-update inequality over $t = 1, \dots, T$, we get

$$\sum_{i=1}^N w_i^{T+1} \leq \prod_{t=1}^T \left(1 - (1 - \epsilon_t)(1 - \beta_t) \right). \quad (16)$$

Lower bound on total weight

The final hypothesis h_f makes a mistake on instance i only if

$$\prod_{t=1}^T \beta_t^{(1-|h_t(x_i)-y_i|)} \geq \left(\prod_{t=1}^T \beta_t\right)^{-\frac{1}{2}}. \quad (17)$$

The final weight of instance i is

$$w_i^{T+1} = D(i) \prod_{t=1}^T \beta_t^{(1-|h_t(x_i)-y_i|)}. \quad (18)$$

By comparing the sum of all final weights to those on examples where h_f is incorrect, one obtains

$$\sum_{i=1}^N w_i^{T+1} \geq \sum_{i:h_f(x_i) \neq y_i} w_i^{T+1} \geq e \left(\prod_{t=1}^T \beta_t\right)^{1/2},$$

where e is the error of h_f .

Resulting Error Bound

Combining (16) and the above,

$$e \leq \prod_{t=1}^T \frac{1 - (1 - \epsilon_t)(1 - \beta_t)}{\sqrt{\beta_t}}. \quad (20)$$

Minimizing each factor leads to $\beta_t = \epsilon_t / (1 - \epsilon_t)$. Plugging back yields

$$e \leq 2^T \prod_{t=1}^T \sqrt{\epsilon_t (1 - \epsilon_t)},$$

Alternative forms of the bound

$$\begin{aligned} e &\leq \prod_{t=1}^T \sqrt{1 - 4\gamma_t^2} = \exp\left(-\sum_{t=1}^T \text{KL}\left(\frac{1}{2} \parallel \frac{1}{2} - \gamma_t\right)\right) \\ &\leq \exp\left(-2\sum_{t=1}^T \gamma_t^2\right). \end{aligned}$$

Comparing Hedge vs Adaboost

Hedge

- ▶ Each iteration adds an Example
- ▶ Weights assigned to Experts
- ▶ Upper bound on potential: Loss of alg.
- ▶ Lower bound on potential: Loss of best expert

Adaboost

- ▶ Each iteration adds a Weak Rule
- ▶ Weights assigned to examples.
- ▶ Upper bound on Potential: Edges of weak rules.
- ▶ Lower bound on Potential: Error of majority vote.

The Hedge(η)Algorithm

Consider action i at time t

- Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

- Weight:

$$w_i^t = w_i^1 e^{-\eta L_i^t}$$

Note freedom to choose initial weight (w_i^1) $\sum_{i=1}^n w_i^1 = 1$.

- $\eta > 0$ is the learning rate parameter. Halving: $\eta \rightarrow \infty$
- Probability:

$$p_i^t = \frac{w_i^t}{\sum_{j=1}^N w_j^t}, \quad \mathbf{p}^t = \frac{\mathbf{w}^t}{\sum_{j=1}^N w_j^t}$$

Bound on the loss of **Hedge**(η) Algorithm

Theorem (main theorem)

For any sequence of loss vectors ℓ_1, \dots, ℓ_T , and for any $i \in \{1, \dots, N\}$, we have

$$L_{\text{Hedge}(\eta)} \leq \frac{-\ln(w_i^1) + \eta L_i}{1 - e^{-\eta}}.$$

- Note effect of the limits $\eta \rightarrow 0$ and $\eta \rightarrow \infty$
- **Proof**: by combining upper and lower bounds on

$$\ln \sum_{i=1}^N w_i^{T+1} = \ln \left(\sum_{i=1}^N e^{-\eta L_i^T} \right)$$

Hedge(η)

└ Bound on total loss

└ Upper bound on $\sum_{i=1}^N w_i^{T+1}$

Upper bound on $\sum_{i=1}^N w_i^{T+1}$

Lemma (upper bound)

For any sequence of loss vectors ℓ_1, \dots, ℓ_T we have

$$\ln \left(\sum_{i=1}^N w_i^{T+1} \right) \leq -(1 - e^{-\eta}) L_{\text{Hedge}(\eta)}.$$

Hedge(η)

└ Bound on total loss

└ Lower bound on $\sum_{i=1}^N w_i^{T+1}$

Lower bound on $\sum_{i=1}^N w_i^{T+1}$

For any $j = 1, \dots, N$:

$$\sum_{i=1}^N w_i^{T+1} \geq w_j^{T+1} = w_j^1 e^{-\eta L_j}$$

Combining Upper and Lower bounds

- ▶ Combining bounds on $\ln \left(\sum_{i=1}^N w_i^{T+1} \right)$

$$\ln w_j^1 - \eta L_j \leq \ln \sum_{i=1}^N w_i^{T+1} \leq -(1 - e^{-\eta}) \sum_{t=1}^T \mathbf{p}^t \cdot \ell_t$$

- ▶ Reversing signs, using $L_{\text{Hedge}(\eta)} = \sum_{t=1}^T \mathbf{p}^t \cdot \ell_t$ and reorganizing we get

$$L_{\text{Hedge}(\eta)} \leq \frac{-\ln(w_i^1) + \eta L_i}{1 - e^{-\eta}}$$