

A Projected Lloyd's Algorithm for Coverage Control Problems

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Introduction

Mathematical Background

Problem Solution

Simulations



Introduction



About Me

- ➤ Yoav Palti, B.Sc in Aerospace Engineering, Technion, 2012
- Aeronautical algorithms engineer, IAF, since 2013
- M.Sc student since 2014



Motivation

Covering an area - (relatively) easy



Motivation

- Covering an area (relatively) easy
- Covering an area with not sufficient amount of sensors not so easy
 - Requires better definition of behaviour



Motivation

- Covering an area (relatively) easy
- Covering an area with not sufficient amount of sensors not so easy
 - Requires better definition of behaviour
- Maintain contact with home base (at least in steady state) hard



Introduction

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Problem Formulation



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Problem Formulation



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Lyaponov Stability



Voronoi Partitioning

Voronoi Partitioning



Central Voronoi Tessellations



Voronoi Partitioning

Lloyd's Algorithm



Formation Control



Projection Operator



Problem Solution



Problem Solution 000000

Lloyd's Algorithm and Formation Control

Lloyd's Algorithm and Formation Control



Proof



Problem Solution 000000

Projected Lloyd's Algorithm



Proof



Problem Solution 000000

Problem Solution Algorithm



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Some Simulation

Some Simulation

