

Non-Vertical Cultural Transmission, Assortment, and the Evolution of Cooperation

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Abstract

8 Cultural evolution of cooperation under vertical and non-vertical cultural transmission is studied,
and conditions are found for fixation and coexistence of cooperation and defection. The evolution
10 of cooperation is facilitated by its horizontal transmission and by an association between social
interactions and horizontal transmission. The effect of oblique transmission depends on the horizontal
12 transmission bias. Stable polymorphism of cooperation and defection can occur, and when it does,
reduced association between social interactions and horizontal transmission evolves, which leads to a
14 decreased frequency of cooperation and lower population mean fitness. The deterministic conditions
are compared to outcomes of stochastic simulations of structured populations. Parallels are drawn
16 with Hamilton's rule incorporating relatedness and assortment.

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30 1 Introduction

Cooperative behavior can reduce an individual's fitness and increase the fitness of its conspecifics or
32 competitors [1]. Nevertheless, cooperative behavior appears to occur in many animals [2], including
humans, primates [3], rats [4], birds [5, 6], and lizards [7]. Evolution of cooperative behavior has
34 been an important focus of research in evolutionary theory since at least the 1930s [8]. Since the work
of Hamilton [9] and Axelrod and Hamilton [1], theories for the evolution of cooperative and altruistic
36 behaviors have been intertwined often under the rubric of *kin selection*. Kin selection theory posits
that natural selection is more likely to favor cooperation between more closely related individuals. The
38 importance of *relatedness* to the evolution of cooperation and altruism was demonstrated by Hamilton
[9], who showed that an allele that determines cooperative behavior will increase in frequency if the
40 reproductive cost to the actor that cooperates, c , is less than the benefit to the recipient, b , times the
relatedness, r , between the recipient and the actor. This condition is known as *Hamilton's rule*:

$$42 \quad c < b \cdot r, \quad (1)$$

where the relatedness coefficient r measures the probability that an allele sampled from the cooperator
44 is identical by descent to one at the same locus in the recipient.

There is an ongoing debate about to what extent kin selection explains evolution of cooperation and
46 altruism. It has been suggested that kin selection to explain the cooperative behaviour of eusocial
insects like the honey bee. The most significant argument against kin selection is that cooperation can
48 evolve with zero relatedness [10]. This makes Hamilton's rule incomplete according to Wilson [10].
Foster et al. [11] reject this claim. They argue that altruism without relatedness can not evolve. They
50 refer us to Hamilton who claimed that relatedness can arise without recent common ancestry. Wilson
also criticises kin selection on the grounds that environmental or ecological factors probably be more
52 important than relatedness in determining social actions. On the other hand, Foster et al. [11] argue
that kin selection does not ignore ecology. Hamilton's rule shows that environmental factors causing
54 a high benefit: cost ratio will favour cooperation.

Beside kin selection, two more major theories were suggested to explain to evolution of coopera-
56 tion.

Reciprocity suggests repeating interactions or individual recognition as key factors for explaining the
58 evolution of cooperation. In *direct reciprocity* there are a repeated encounters between the same two
individuals. In every encounter, each player has a choice between cooperation and defection. If I
60 cooperate now, you may cooperate later. Hence, it may pay off to cooperate. This game-theoretic
framework is known as the repeated Prisoner's Dilemma. Direct reciprocity can only lead to the
62 evolution of cooperation if the cost is smaller than w the probability for another encounter between
the same two individuals multiplied by the benefit.

$$64 \quad c < bw \quad (2)$$

Direct reciprocity assumes that both players are in a position to cooperate. Direct reciprocity can
66 not explain cooperation in asymmetric interactions. In humans, such interactions happen often, for

example humans often donate money. *Indirect reciprocity* has been suggested to explain this behavior.

68 Nowak [12] claims that direct reciprocity is like a barter economy based on the immediate exchange of
goods, while indirect reciprocity resembles the invention of money. The money that "fuels the engines"
70 of indirect reciprocity is reputation. However, Reciprocity assume repeating interactions and therefore,
has difficulty explaining evolution of cooperation if the no repeating interactions occurs.

72 **Group Selection** theory posits that cooperation is favoured because of the advantage to the whole
group, if selection acts at the group level in addition to the individual level. A common model for group
74 selection work as is: the population is divided into groups. In each groups there are cooperators, which
help to other group members and defectors which do not help. Individuals reproduce proportional to
76 their fitness. Offspring are added to the same group. If a group reaches a certain size it can split to two
groups. A group that grow faster will split more often. Groups of cooperators are growing faster than
78 group of defectors. Therefore, cooperation can evolve in this model when the ratio between benefit
b and cost c is more than one plus the ratio between the maximum group size n and the number of
80 groups m:

$$\frac{b}{c} > 1 + \frac{n}{m} \quad (3)$$

82 All three theories mentioned above assume that cooperation is genetically determined. This raise
the question, is it possible that cooperation is determined by environmental or social influences.
84 Cooperative behavior can be subject to *cultural transmission*, which allows an individual to acquire
attitudes or behavioral traits from other individuals in its social group through imitation, learning, or
86 other modes of communication [13, 14]. Cultural transmission may be modeled as vertical, horizontal,
or oblique: vertical transmission occurs between parents and offspring, horizontal transmission occurs
88 between individuals from the same generation, and oblique transmission occurs to offspring from the
generation to which their parents belong (i.e. from non-parental adults). Evolution under either of these
90 transmission models can be be more rapid than under pure vertical transmission [13, 15, 16].

Here, we study models for the cultural evolution of cooperation that include both vertical and non-
92 vertical transmission. In our models behavioral changes are mediated by cultural transmission that
can occur specifically during social interactions. For instance, there may be an association between
94 the choice of partner for social interaction and the choice of partner for cultural transmission, or when
an individual interacts with an individual of a different phenotype, exposure to the latter may lead the
96 former to convert its phenotype. Our results demonstrate that cultural transmission, when associated
with social interactions, can enhance the evolution of cooperation even when genetic transmission
98 cannot, partly because it facilitates the generation of assortment [17], and partly because it diminishes
the effect of selection (due to non-vertical transmission from non-reproducing individuals [16]).

100 To understand the evolution of cooperation we are going to use *replicator dynamics*. The replicator
in replicator dynamics has the ability to make one or more copies of itself. The replicator can be a
102 gene, a phenotype, a stragey in a game and etc. In cooperation context replicator is a different stragey
in the game, whether the individual is a cooperative or a defector. In replicator dynamics we assume
104 large population of replicators, which interact with respect to their proportion. Those interactions of

different replicator affect the fitness acorrding to some payoff matrix. The payoff matrix depends on

106 the game which is played. The most common game to describe cooperation is prisoner's dilemma[18].

Similar to dominant strategies bringing forth Nash equilibria when games are repeated, strategies in

108 replicator dynamics can become evolutionary stable. Such strategies are called *Evolutionarily Stable*

stragey (*ESS*). Such strategies cannot be invaded by any other strategy that is initially rare. One

110 of the main questions in the evolution of cooperation is under what conditions such invasions are

possible.

112 2 Related Work

114 Eshel and Cavalli-Sforza [19] studied a related model for the evolution of cooperative behavior. Their
 116 model included *assortative meeting*, or non-random encounters, where a fraction m of individuals in
 118 the population each interact specifically with an individual of the same phenotype, and a fraction $1 - m$
 interacts with a randomly chosen individual. Such assortative meeting may be due, for example, to
 population structure or active partner choice. In their model, cooperative behavior can evolve if [19,
 eq. 3.2]

$$c < b \cdot m, \quad (4)$$

120 where b and c are the benefit and cost of cooperation¹.

122 The role of assortment in the evolution of altruism was emphasized by Fletcher and Doebeli [17].
 124 They found that in a *public-goods* game, altruism will evolve if cooperative individuals experience
 more cooperation, on average, than defecting individuals, and “thus, the evolution of altruism requires
 (positive) assortment between focal *cooperative* players and cooperative acts in their interaction
 environment.” With some change in parameters, this condition is summarized by [17, eq. 2.3]

$$c < b \cdot (p_C - p_D), \quad (5)$$

126 where p_C is the probability that a cooperator receives help, and p_D is the probability that a defector
 receives help². Bijma and Aanen [20] obtained a result related to inequality 5 for other games.

130 Cooperation can also evolve when interactions are determined by population structure. For example,
 132 Ohtsuki et al. [21] studied populations on graphs with average degree k , that is, the average individual
 has k potential interaction partners. Assuming that selection is weak and that the population size is
 much larger than k (i.e. sparse structure), they found that cooperative behaviour can evolve if [21]

$$c < b \cdot \frac{1}{k}. \quad (6)$$

134 They thus interpret $1/k$ as *social relatedness* or *social viscosity* [21].

136 Feldman et al. [22] introduced the first model for the evolution of altruism by cultural transmission
 with kin selection and demonstrated that if the fidelity of cultural transmission of altruism is φ , then
 the condition for evolution of altruism in the case of sib-to-sib altruism is [22, Eq. 16]

$$c < b \cdot \varphi - \frac{1 - \varphi}{\varphi}. \quad (7)$$

140 In inequality 7, φ replaces relatedness (r in inequality 1) or assortment (m in inequality 4), but the ef-
 fective benefit $b \cdot \varphi$ is reduced by $(1 - \varphi)/\varphi$. This shows that under a cultural transmission, the condition
 for the evolutionary success of altruism entails a modification of Hamilton’s rule (inequality 1).

¹In an extended model, which allows an individual to encounter N individuals before choosing a partner, the right hand side is multiplied by $E[N]$, the expected number of encounters [19, eq. 4.6].

²Inequality 5 generalizes inequalities 1 and 4 by substituting $p_C = r + p$, $p_D = p$ and $p_C = m + (1 - m)p$, $p_D = (1 - m)p$, respectively, where p is the frequency of cooperators.

142 Both Woodcock [23] and Lewin-Epstein et al. [24] demonstrated that non-vertical transmission can help
143 explain the evolution of cooperative behavior, the former using simulations with cultural transmission,
144 the latter using a model where cooperation is mediated by host-associated microbes. Indeed, models
145 in which microbes affect their host's behavior [24, 25, 26] are mathematically similar to models of
146 cultural transmission, and they also emphasize the role of non-vertical transmission [13].

3 Models

148 Consider a large population whose members can be one of two phenotypes: $\phi = A$ for cooperators
 or $\phi = B$ for defectors. An offspring inherits its phenotype from its parent via vertical transmission
 150 with probability v or from a random individual in the parental population via oblique transmission
 with probability $(1 - v)$ (Figure 1a). Following Ram et al. [16], given that the parent's phenotype is
 152 ϕ and assuming uni-parental inheritance [27], the conditional probability that the phenotype ϕ' of the
 offspring is A is

$$154 \quad P(\phi' = A | \phi) = \begin{cases} v + (1 - v)p, & \text{if } \phi = A \\ (1 - v)p, & \text{if } \phi = B \end{cases}, \quad (8)$$

where $p = P(\phi = A)$ is the frequency of A among all adults in the parental generation.

156 Not all adults become parents, and we denote the frequency of phenotype A among parents by \dot{p} .
 Therefore, the frequency \hat{p} of phenotype A among juveniles (after selection and vertical and oblique
 158 transmission) is

$$\hat{p} = \dot{p}[v + (1 - v)p] + (1 - \dot{p})[(1 - v)p] = v\dot{p} + (1 - v)p. \quad (9)$$

160 Individuals are assumed to interact according to a *prisoner's dilemma*. Specifically, individuals interact
 in pairs; a cooperator suffers a fitness cost $0 < c < 1$, and its partner gains a fitness benefit b , where we
 162 assume $c < b$. Figure 1a shows the payoff matrix, i.e. the fitness of an individual with phenotype ϕ_1
 when interacting with a partner of phenotype ϕ_2 . The choice of prisoner's dilemma as the interaction
 164 model was motivated by the fact that prisoner's dilemma is a common game used to study evolution
 of cooperation[1], [28], [18]. Although we decided to focus on prisoner's dilemma, other games such
 166 as stag hunt[29] may be a better explanation of cooperation behavior in humans[30].

Social interactions occur randomly: two juvenile individuals with phenotype A interact with proba-
 168 bility \hat{p}^2 , two juveniles with phenotype B interact with probability $(1 - \hat{p})^2$, and two juveniles with
 different phenotypes interact with probability $2\hat{p}(1 - \hat{p})$. Horizontal cultural transmission occurs
 170 between pairs of individuals from the same generation. It occurs between socially interacting partners
 with probability α , or between a random pair with probability $1 - \alpha$ (see Figure 1b). However,
 172 horizontal transmission is not always successful, as one partner may reject the other's phenotype. The
 probability of successful horizontal transmission of phenotypes A and B are T_A and T_B , respectively
 174 (Table 1, Figure 1d). Thus, the frequency p' of phenotype A among adults in the next generation, after
 horizontal transmission, is

$$176 \quad p' = \hat{p}^2[\alpha + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] + \\ \hat{p}(1 - \hat{p})[\alpha(1 - T_B) + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] + \\ (1 - \hat{p})\hat{p}[\alpha T_A + (1 - \alpha)\hat{p}T_A] + (1 - \hat{p})^2[(1 - \alpha)\hat{p}T_A] \\ = \hat{p}^2(T_B - T_A) + \hat{p}(1 + T_A - T_B). \quad (10)$$

The frequency of A among parents (i.e. after selection) follows a similar dynamic, but also includes

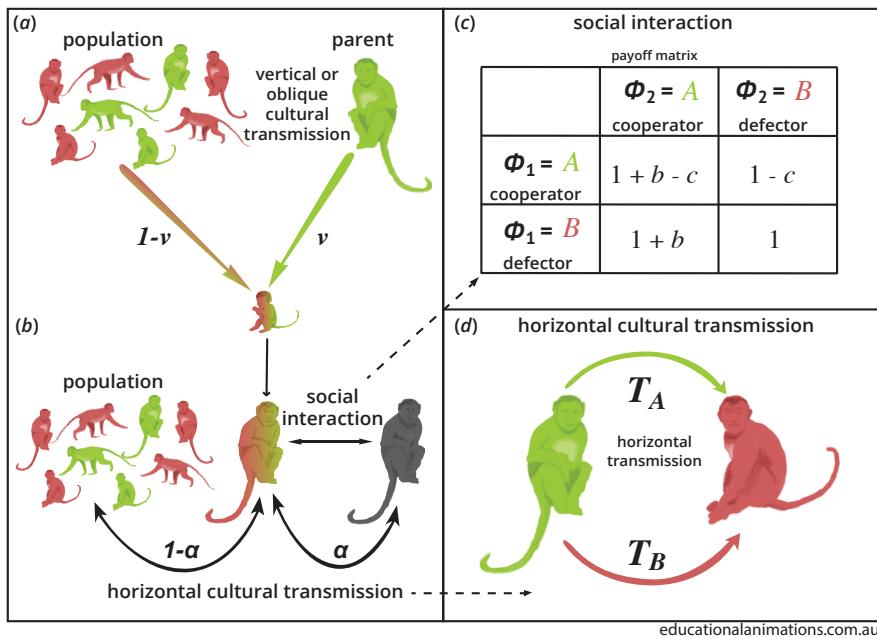


Figure 1: Model illustration. **(a)** First, offspring inherit their parent's phenotype via vertical cultural transmission with probability v , or the phenotype of a random non-parental adult via oblique cultural transmission with probability $1 - v$. **(b)** Second, adults socially interact in pairs in a prisoner's dilemma game. Horizontal cultural transmission occurs from a random individual in the population, with probability $1 - \alpha$, or from the social partner, with probability α , where α is the interaction-transmission association parameter. **(c)** The prisoner's dilemma payoff matrix shows the fitness of phenotype ϕ_1 when interacting with phenotype ϕ_2 . **(d)** The probabilities of successful horizontal cultural transmission of phenotypes A (cooperator) and B (defector) are T_A and T_B , respectively.

178 the effect of natural selection, and is therefore

$$\begin{aligned}\bar{w}\dot{p}' = & \hat{p}^2(1+b-c)\left[\alpha + (1-\alpha)(\hat{p} + (1-\hat{p})(1-T_B))\right] + \\ & \hat{p}(1-\hat{p})(1-c)\left[\alpha(1-T_B) + (1-\alpha)(\hat{p} + (1-\hat{p})(1-T_B))\right] + \\ & (1-\hat{p})\hat{p}(1+b)\left[\alpha T_A + (1-\alpha)\hat{p}T_A\right] + (1-\hat{p})^2\left[(1-\alpha)\hat{p}T_A\right],\end{aligned}\quad (11)$$

180 where fitness values are taken from Figure 1c and Table 1, and the population mean fitness is
 $\bar{w} = 1 + \hat{p}(b - c)$. Starting from Eq. 9 with $\hat{p}' = v\dot{p}' + (1-v)p'$, we substitute p' from Eq. 10 and \dot{p}'
182 from Eq. 11 and obtain

$$\begin{aligned}\hat{p}' = & \frac{v}{\bar{w}}\left[\hat{p}^2(1+b-c)\left(1 - (1-\hat{p})(1-\alpha)T_B\right)\right] + \\ & \frac{v}{\bar{w}}\left[\hat{p}(1-\hat{p})(1-c)\left(\hat{p}(1-\alpha)T_B + 1 - T_B\right)\right] + \\ & \frac{v}{\bar{w}}\left[\hat{p}(1-\hat{p})(1+b)\left(\hat{p}(1-\alpha) + \alpha\right)T_A\right] + \\ & \frac{v}{\bar{w}}(1-\hat{p})^2\hat{p}(1-\alpha)T_A + (1-v)\hat{p}^2(T_B - T_A) + (1-v)\hat{p}(1+T_A - T_B).\end{aligned}\quad (12)$$

184 Table 2 lists the model variables and parameters.

Table 1: Interaction frequency, fitness, and transmission probabilities.

Phenotype ϕ_1	Phenotype ϕ_2	Frequency	Fitness of ϕ_1	$P(\phi_1 = A)$ via horizontal transmission:	
				from partner, α	from population, $(1 - \alpha)$
A	A	\hat{p}^2	$1 + b - c$	1	$\hat{p} + (1 - \hat{p})(1 - T_B)$
A	B	$\hat{p}(1 - \hat{p})$	$1 - c$	$1 - T_B$	$\hat{p} + (1 - \hat{p})(1 - T_B)$
B	A	$\hat{p}(1 - \hat{p})$	$1 + b$	T_A	$\hat{p}T_A$
B	B	$(1 - \hat{p})^2$	1	0	$\hat{p}T_A$

Table 2: Model variables and parameters.

Symbol	Description	Values
A	Cooperator phenotype	
B	Defector phenotype	
p	Frequency of phenotype A among adults	$[0, 1]$
\dot{p}	Frequency of phenotype A among parents	$[0, 1]$
\hat{p}	Frequency of phenotype A among juveniles	$[0, 1]$
v	Vertical transmission rate	$[0, 1]$
c	Cost of cooperation	$(0, 1)$
b	Benefit of cooperation	$c < b$
α	Probability of interaction-transmission association	$[0, 1]$
T_A, T_B	Horizontal transmission rates of phenotype A and B	$(0, 1)$

4 Results

186 We determine the equilibria of the model in Eq. 12 and analyze their local stability. We then analyze
 the evolution of a modifier of interaction-transmission association, α . Finally, we compare derived
 188 conditions to outcomes of stochastic simulations with a structured population.

4.1 Evolution of cooperation

190 To learn about the evolution of cooperation we investigate local stability of the equilibria of the model
 in Eq. 12. The equilibria are the solutions of $\hat{p}' - \hat{p} = 0$. Note that Eq. 12 is not simple polynomial
 192 but a polynomial fraction, therefore the solution is not trivial. The fixed points (equilibria) of the
 recursion (Eq. 12) are $\hat{p} = 0$, $\hat{p} = 1$, and (see Appendix B Eq. B5)

$$194 \quad \hat{p}^* = \frac{\alpha bvT_A - cv(1 - T_B) + (T_A - T_B)}{[c(1 - v) - b(1 - \alpha v)](T_A - T_B)}. \quad (13)$$

Define the following cost thresholds, γ_1 and γ_2 , and the vertical transmission threshold, \hat{v} ,

$$196 \quad \gamma_1 = \frac{bvaT_A + (T_A - T_B)}{v(1 - T_B)}, \quad \gamma_2 = \frac{bvaT_B + (1 + b)(T_A - T_B)}{v(1 - T_B) + (1 - v)(T_A - T_B)}, \quad \hat{v} = \frac{T_B - T_A}{1 - T_A}. \quad (14)$$

Then we have the following result.

198

Result 1. *With vertical, horizontal, and oblique transmission, the cultural evolution of a cooperation follows one of the following scenarios in terms of the cost thresholds γ_1 and γ_2 and the vertical transmission threshold \hat{v} (Eq. 14) :*

- 202 1. Fixation of cooperation: if (i) $T_A \geq T_B$ and $c < \gamma_1$; or if (ii) $T_A < T_B$ and $v > \hat{v}$ and $c < \gamma_2$.
- 2. Fixation of defection: if (iii) $T_A \geq T_B$ and $\gamma_2 < c$; or if (iv) $T_A < T_B$ and $\gamma_1 < c$.
- 204 3. Stable polymorphism: if (v) $T_A < T_B$ and $v < \hat{v}$ and $c < \gamma_1$; or if (vi) $T_A < T_B$ and $v > \hat{v}$ and $\gamma_2 < c < \gamma_1$.
- 206 4. Unstable polymorphism: if (vii) $T_A > T_B$ and $\gamma_1 < c < \gamma_2$.

Thus, cooperation can take over the population if it has either a horizontal transmission advantage, or
 208 if it has a horizontal transmission disadvantage, but the vertical transmission rate is high enough. In
 either case, the cost of cooperation must be small enough. A stable polymorphism can exist between
 210 cooperation and defection only if defection has a horizontal transmission advantage. In this case,
 the existence of a stable polymorphism depends on the interplay between the benefit and cost of
 212 cooperation and the vertical transmission rate. These conditions are illustrated in Figures 2a, 2b, 3a,
 and 3b, and the analysis is in Appendix B. Note that *stable* and *unstable* polymorphism are also called,
 214 respectively, *coexistence* and *bistable competition*.

Much of the literature on evolution of cooperation focuses on conditions for an initially rare coopera-
 216 tive phenotype to invade a population of defectors. The following remarks address this condition.

218 **Remark 1.** If the initial frequency of cooperation is very close to zero, then its frequency will increase if the cost of cooperation is low enough,

220

$$c < \gamma_1 = \frac{bvaT_A + (T_A - T_B)}{v(1 - T_B)} . \quad (15)$$

This unites the conditions for fixation of cooperation and for stable polymorphism, both of which
222 entail instability of the state where defection is fixed, $\hat{p} = 0$.

Importantly, increasing interaction-transmission association α increases the cost threshold ($\partial\gamma_1/\partial\alpha >$
224 0), making it easier for cooperation to increase in frequency when initially rare. Similarly, increasing
the horizontal transmission of cooperation, T_A , increases the threshold ($\partial\gamma_1/\partial T_A > 0$), facilitating
226 the evolution of cooperation ((Figure 3a and 3b). However, increasing the horizontal transmission of
defection, T_B , can increase or decrease the cost threshold, but it increases the cost threshold when
228 the threshold is already above one ($c < 1 < \gamma_1$): $\partial\gamma_1/\partial T_B$ is positive when $T_A > \frac{1}{1+\alpha bv}$, which
gives $\gamma_1 > 1/v$. Therefore, increasing T_B decreases the cost threshold and limits the evolution of
230 cooperation, but only if $T_A < \frac{1}{1+\alpha bv}$.

Increasing the vertical transmission rate, v , can either increase or decrease the cost threshold, depending
232 on the horizontal transmission bias, $T_A - T_B$, because $\text{sign}(\partial\gamma_1/\partial v) = -\text{sign}(T_A - T_B)$. When $T_A < T_B$
we have $\partial\gamma_1/\partial v > 0$, and as the vertical transmission rate increases, the cost threshold increases,
234 making it easier for cooperation to increase when rare (Figure 2b). In contrast, when $T_A > T_B$ we get
 $\partial\gamma_1/\partial v < 0$, and therefore as the vertical transmission rate increases, the cost threshold decreases,
236 making it harder for cooperation to increase when rare (Figure 2a).

In general, this condition cannot be formulated in the form of Hamilton's rule due to the bias in
238 horizontal transmission, represented by $T_A - T_B$. If $T_A = T_B$, then, from Result 1 and inequality 15,
cooperation will take over the population from any initial frequency if the cost is low enough,

240

$$c < b \cdot \frac{\alpha T}{1 - T} , \quad (16)$$

and regardless of the vertical transmission rate, v . This condition can be interpreted as a version of
242 Hamilton's rule ($c < b \cdot r$, inequality 1) or as a version of inequality 5, where $\alpha T/(1 - T)$ can be
regarded as the *effective relatedness* or *effective assortment*, respectively. Note that the right-hand side
244 of inequality 16 equals γ_1 when $T = T_A = T_B$.

From inequality 15, without interaction-transmission association ($\alpha = 0$), cooperation will increase
246 when it is rare if there is horizontal transmission bias for cooperation, $T_A > T_B$, and

$$c < \frac{T_A - T_B}{v(1 - T_B)} . \quad (17)$$

248 Figure 3a illustrates this condition (for $v = 1$), which is obtained by setting $\alpha = 0$ in inequality 15.
In this case, the benefit of cooperation, b , does not affect the evolution of cooperation, and the
250 outcome is determined only by cultural transmission. Further, inequality 15 shows that with perfect
interaction-transmission association ($\alpha = 1$), cooperation will increase when rare if

252

$$c < \frac{bvT_A + (T_A - T_B)}{v(1 - T_B)} . \quad (18)$$

In the absence of oblique transmission, $v = 1$, the only equilibria are the fixation states, $\dot{p} = 0$ and

254 $\dot{p} = 1$, and cooperation will evolve from any initial frequency (i.e. $\dot{p}' > \dot{p}$) if inequality 18 applies
(Figure 3). This is similar to case of microbe-induced cooperation studied by Lewin-Epstein et al.
256 [24]; therefore when $v = 1$, this remark is equivalent to their eq. 1.

It is interesting to examine the general effect of interaction-transmission association α on the evolution

258 of cooperation. Define the interaction-transmission association thresholds, a_1 and a_2 , as

$$a_1 = \frac{c \cdot v(1 - T_A) - (T_A - T_B)(1 + b - c)}{b \cdot v \cdot T_B}, \quad a_2 = \frac{c \cdot v(1 - T_B) - (T_A - T_B)}{b \cdot v \cdot T_A}. \quad (19)$$

260 **Remark 2.** Cooperation will increase when rare if interaction-transmission association is high
enough, specifically if $a_2 < \alpha$.

262 Figures 2c and 2d illustrate this condition. With horizontal transmission bias for cooperation, $T_A > T_B$,
cooperation can fix from any initial frequency if $a_2 < \alpha$ (green area in the figures). With horizontal
264 bias favoring defection, $T_A < T_B$, cooperation can fix from any frequency if α is large enough, $a_1 < \alpha$
(green area with $T_A < T_B$), and can reach stable polymorphism if α is intermediate, $a_2 < \alpha < a_1$
266 (yellow area). Without horizontal bias, $T_A = T_B$, fixation of cooperation occurs if α is high enough,
 $\frac{c}{b} \cdot \frac{1-T}{T} < \alpha$ (inequality 16; in this case $a_1 = a_2$).

268 Interestingly, because $\text{sign}(\partial a_2 / \partial v) = \text{sign}(T_A - T_B)$, the effect of the vertical transmission rate v
on a_1 and a_2 depends on the horizontal transmission bias. That is, if $T_A > T_B$, then evolution of
270 cooperation is facilitated by oblique transmission, whereas if $T_A < T_B$, then evolution of cooperation
is facilitated by vertical transmission (Figures 2c and 2d).

272

Next, we examine the roles of vertical and oblique transmission in the evolution of cooperation.

274 Fixation of cooperation is possible only if the vertical transmission rate is high enough,

$$v > \hat{v} = \frac{T_B - T_A}{1 - T_A}. \quad (20)$$

276 This condition is necessary for fixation of cooperation, but it is not sufficient. If horizontal transmission
is biased for cooperation, $T_A > T_B$, cooperation can fix with any vertical transmission rate (because
278 $\hat{v} < 0$). In contrast, if horizontal transmission is biased for defection, $T_A < T_B$, cooperation can fix
only if the vertical transmission rate is high enough: in this case oblique transmission can prevent
280 fixation of cooperation (see Figures 2b and 2d).

With only vertical transmission ($v = 1$), from inequality 15, cooperation increases when rare if

$$282 \quad c < \frac{baT_A + (T_A - T_B)}{1 - T_B}, \quad (21)$$

which can also be written as

$$284 \quad \frac{c(1 - T_B) - (T_A - T_B)}{bT_A} < \alpha. \quad (22)$$

In the absence of vertical transmission ($v = 0$), from recursion 12 we see that the frequency of the

286 cooperator phenotype among adults increases every generation, i.e. $p' > p$, if there is a horizontal

transmission bias in favor of cooperation, namely $T_A > T_B$. That is, if $v = 0$, then selection plays no
288 role in the evolution of cooperation (i.e. b and c do not affect \hat{p}'). The dynamics are determined solely
by differential horizontal transmission of the two phenotypes. With no bias in horizontal transmission,
290 $T_A = T_B$, phenotype frequencies do not change, $\hat{p}' = \hat{p}$.

Cooperation and defection can coexist at frequencies \hat{p}^* and $1 - \hat{p}^*$ (Eq. 13). When it is feasible, this
292 equilibrium is stable or unstable under the conditions of Result 1, parts 3 and 4, respectively. The
yellow and blue areas in Figures 3 and 2 show cases of stable and unstable polymorphism, respectively.
294 When \hat{p}^* is unstable, cooperation will fix if its initial frequency is $\hat{p} > \hat{p}^*$, and defection will fix if
 $\hat{p} < \hat{p}^*$. \hat{p}^* is unstable when there is horizontal transmission bias for cooperation, $T_A > T_B$, and the
296 cost is intermediate, $\gamma_1 < c < \gamma_2$. Figure 3d shows $\hat{p}' - \hat{p}$ as a function of \hat{p} .

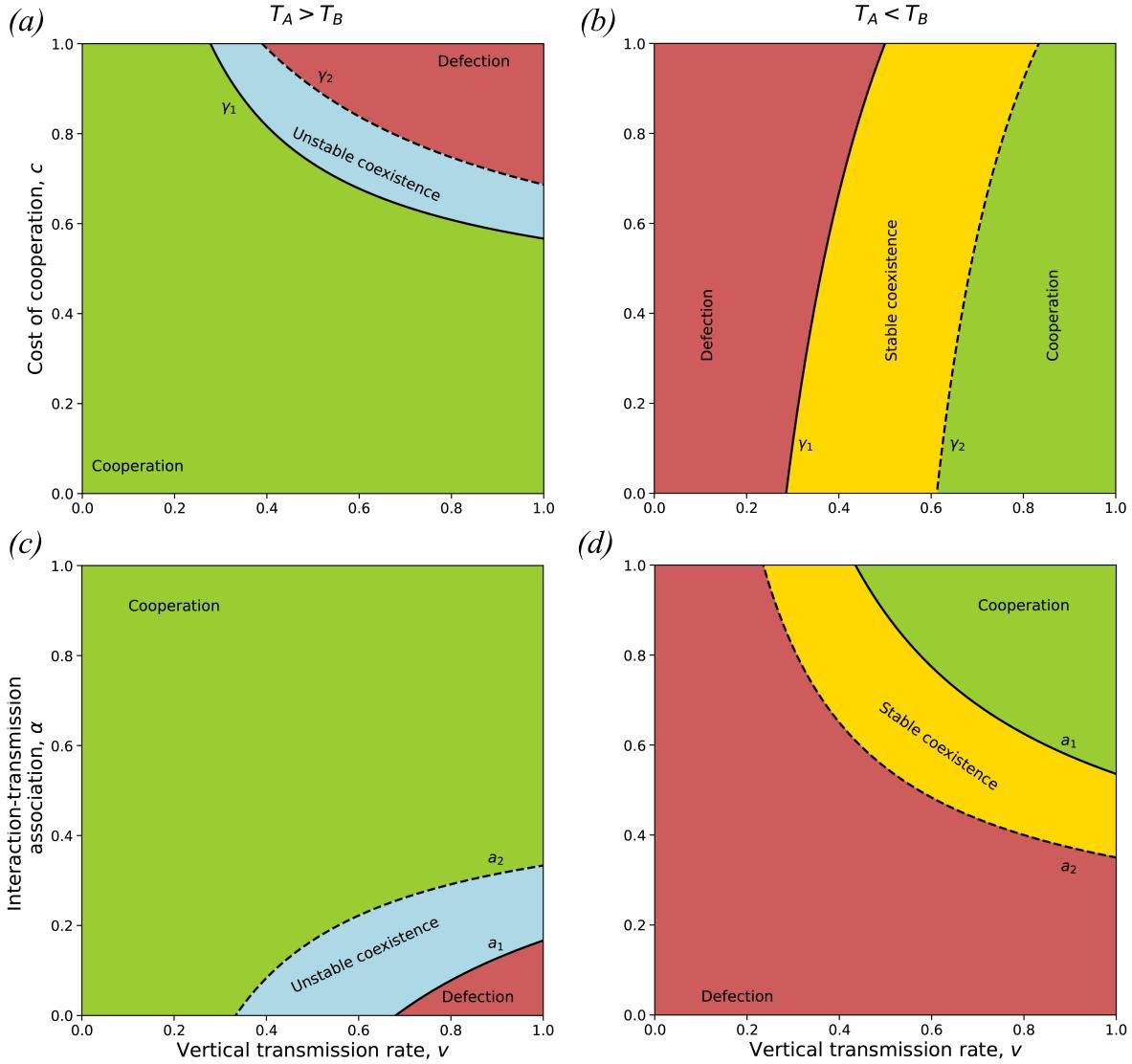


Figure 2: Evolution of cooperation under vertical, oblique, and horizontal cultural transmission.

The figure shows parameter ranges for global fixation of cooperation (green), global fixation of defection (red), fixation of either cooperation or defection depending on the initial conditions, i.e. unstable polymorphism (blue), and stable polymorphism of cooperation and defection (yellow). In all cases the vertical transmission rate v is on the x-axis. **(a-b)** Cost of cooperation c is on the y-axis and the cost thresholds γ_1 and γ_2 (Eqs. 14) are represented by the solid and dashed lines, respectively. **(c-d)** Interaction-transmission association α is on the y-axis and the interaction-transmission association thresholds a_1 and a_2 (Eqs. 19) are represented by the solid and dashed lines, respectively. Horizontal transmission is biased in favor of cooperation, $T_A > T_B$, in **(a)** and **(c)**, or defection, $T_A < T_B$, in **(b)** and **(d)**. Here, $T_A = 0.5$, and **(a)** $b = 1.2$, $T_B = 0.4$, $\alpha = 0.4$; **(b)** $b = 2$, $T_B = 0.7$, $\alpha = 0.7$; **(c)** $b = 1.2$, $T_B = 0.4$, $c = 0.5$; **(d)** $b = 2$, $T_B = 0.7$, $c = 0.5$.

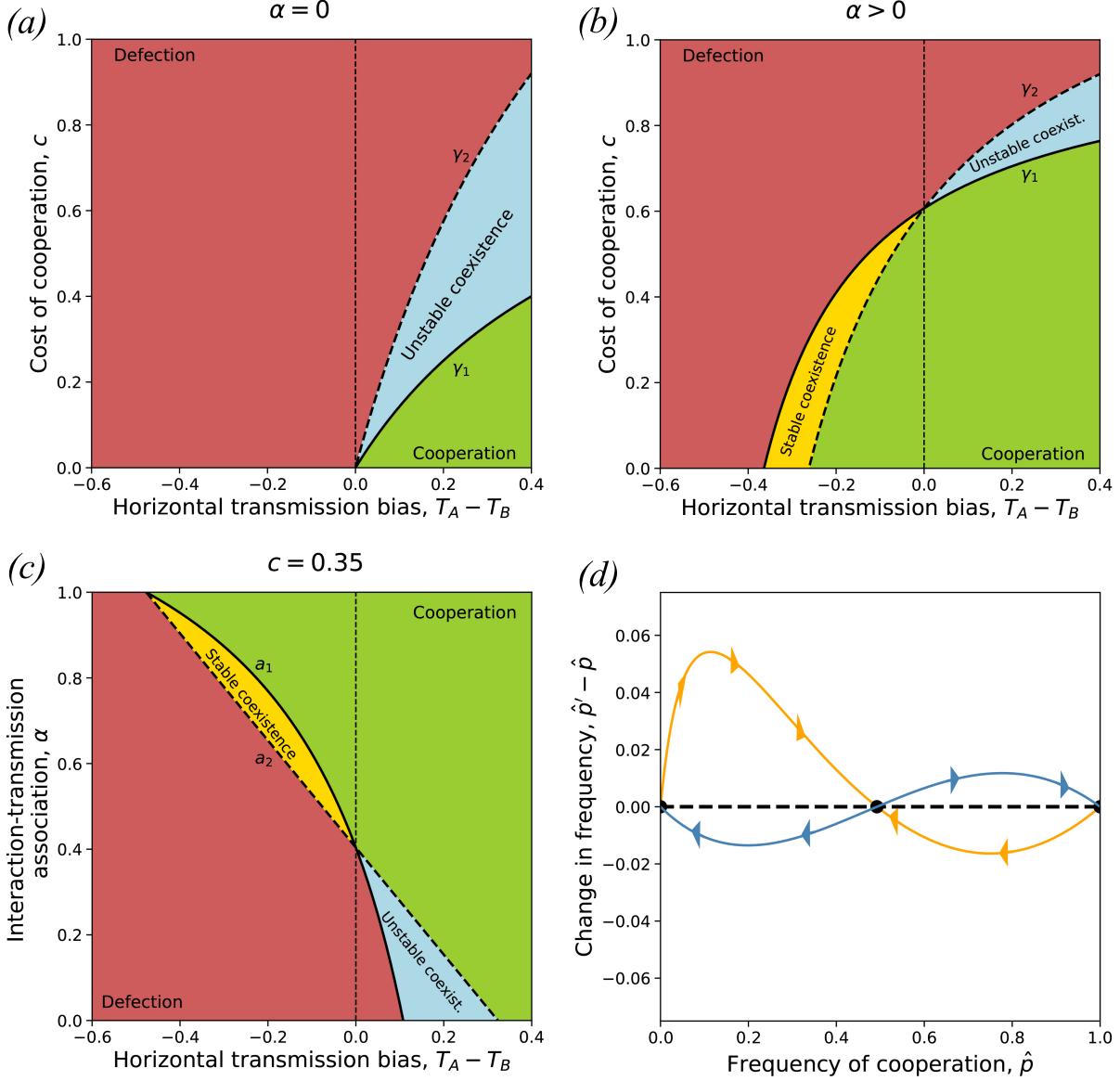


Figure 3: Evolution of cooperation under vertical and horizontal cultural transmission ($v=1$).

The figure shows parameter ranges for global fixation of cooperation (green), global fixation of defection (red), fixation of either cooperation or defection depending on the initial conditions, i.e. unstable polymorphism (blue), and stable polymorphism of cooperation and defection (yellow). **(a-c)** The horizontal transmission bias ($T_A - T_B$) is on the x-axis. In panels **(a)** and **(b)**, the cost of cooperation c is on the y-axis and the cost thresholds γ_1 and γ_2 (Eq. 14) are the solid and dashed lines, respectively. In panel **(c)**, interaction-transmission association α is on the y-axis and the interaction-transmission association thresholds a_1 and a_2 (Eqs. 19) are the solid and dashed lines, respectively. Here, $b = 1.3$, $T_A = 0.4$, $v = 1$, (a) $\alpha = 0$, (b) $\alpha = 0.7$, (c) $c = 0.35$. **(d)** Change in frequency of cooperation among juveniles ($\hat{p}' - \hat{p}$) as a function of the frequency (\hat{p}), see Eq. 12. The orange curve shows convergence to a stable polymorphism ($T_A = 0.4$, $T_B = 0.9$, $b = 12$, $c = 0.35$, $v = 1$, and $\alpha = 0.45$). The blue curve shows fixation of either cooperation or defection, depending on the initial frequency ($T_A = 0.5$, $T_B = 0.1$, $b = 1.3$, $c = 0.904$, $v = 1$, and $\alpha = 0.4$). Black circles show the three equilibria.

4.2 Evolution of interaction-transmission association

298 We now focus on the evolution of interaction-transmission association under perfect vertical transmission, $v = 1$, assuming that the population is initially at a stable polymorphism of the two phenotypes,
 300 cooperation A and defection B , where the frequency of A among juveniles is \hat{p}^* (Eq. 13). Note that
 302 for a stable polymorphism, there must be horizontal bias for defection, $T_A < T_B$, and an intermediate
 304 cost of cooperation, $\gamma_2 < c < \gamma_1$ (Eq. 14), see Figure 3b. The equilibrium population mean fitness is
 $\bar{w}^* = 1 + \hat{p}^*(b - c)$, which is increasing in \hat{p}^* , and \hat{p}^* is increasing in α (Appendix C). Therefore, \bar{w}^*
 increases as α increases. But can this population-level advantage lead to the evolution of α ?

To answer this question, we add a “modifier locus” [31, 32, 33, 34] that determines the value of α
 306 but has no direct effect on fitness. This locus has two alleles, M and m , which induce interaction-
 308 transmission associations α_1 and α_2 , respectively. Suppose that the population has evolved to a stable
 equilibrium \hat{p}^* when only allele M is present. We study the local stability of this equilibrium to inva-
 sion by the modifier allele m ; this is called “external stability” [33, 35] and obtain the following result.

310

Result 2. *From a stable polymorphism between cooperation and defection, a modifier allele can
 312 successfully invade the population if it decreases the interaction-transmission association α .*

The analysis is in Appendix D. This reduction principle entails that successful invasions will reduce
 314 the frequency of cooperation, as well as the population mean fitness (Figure 4). Furthermore, if we a
 modifier allele that decreases α appears and invades the population from time to time, then the value
 316 of α will continue to decrease, further reducing the frequency of cooperation and the population mean
 fitness. This evolution will proceed as long as there is a stable polymorphism, that is, as long as
 318 $a_2 < \alpha < a_1$ (Remark 2, Figure 3c). Thus, we can expect the value of α to approach a_2 , the frequency
 of cooperation to fall to zero, and the population mean fitness to decrease to one (Figure 4).

320 We can do similiar analysis for the general case where $0 < v < 1$ as we did in Appendix D. First we
 found the value of the characteristic polynomial at 1, $R(1)$ using SymPy [36], a Python library for
 322 symbolic mathematics.

$$R(1) = \frac{cv\hat{p}^*[T_A b\hat{p}^{*2}(v\alpha_2 - 1) - 2T_A b\hat{p}^*v\alpha_2 + T_A b\hat{p}^*(1 + v\alpha_2)]}{b\hat{p}(b\hat{p}^* - 2\hat{p}^* + 2) + c\hat{p}^*(c\hat{p}^* - 2) + 1} \\ + \frac{cv\hat{p}^*[T_A c\hat{p}^{*2}(1 - v) + T_A c\hat{p}^*(v - 1) - T_A \hat{p}^*(1 - c) + T_A]}{b\hat{p}(b\hat{p}^* - 2\hat{p}^* + 2) + c\hat{p}^*(c\hat{p}^* - 2) + 1} \\ + \frac{cv\hat{p}^*[T_B b\hat{p}^{*2}(1 - v\alpha_2) + T_B b\hat{p}^2(v\alpha_2 - 1) + T_B c\hat{p}^{*2}(v - 1)]}{b\hat{p}(b\hat{p}^* - 2\hat{p}^* + 2) + c\hat{p}^*(c\hat{p}^* - 2) + 1} \\ + \frac{cv\hat{p}^*[T_B c\hat{p}^*(1 - v) + T_B cv(1 - \hat{p}^* + T_B(\hat{p}^* - 1) + cv(\hat{p}^* - 1))]}{b\hat{p}(b\hat{p}^* - 2\hat{p}^* + 2) + c\hat{p}^*(c\hat{p}^* - 2) + 1} \quad (23)$$

324 Similarly to what we did in Appendix D, we should find when $R(1) < 0$. However, when adding the
 vertical transmission into the system the math is more complicated. Therefore, we will use a different
 326 technique. We know that when $\alpha_1 = \alpha_2$, $R(1) = 0$. Now, let’s assume that $\alpha_2 = \alpha_1 + \epsilon$. The derivative

of $R(1)$ by ϵ will give us better understand about the sign of $R(1)$ when $\alpha_2 < \alpha_1$.

328

$$\frac{\partial R(1)}{\partial \epsilon} = \frac{cbv^2\hat{p}^*[T_A\hat{p}^{*2} - 2T_A\hat{p}^* + T_A - T_B\hat{p}^{*2} + T_B\hat{p}^*]}{b\hat{p}(b\hat{p}^* - 2\hat{p}^* + 2) + c\hat{p}^*(c\hat{p}^* - 2) + 1} \quad (24)$$

We can simplify Eq. 24

330

$$\frac{\partial R(1)}{\partial \epsilon} = \frac{cbv^2\hat{p}^*[(T_A - T_B)\hat{p}^{*2} + (T_B - 2T_A)\hat{p}^* + T_A]}{(b\hat{p}^* - c\hat{p}^*)^2 + 2\hat{p}^*(b - c) + 1} \quad (25)$$

Since $b > c$ the denominator is always positive. The numerator is quadratic polynomial of \hat{p}^* with
332 the following roots:

$$\hat{p}_1^* = \frac{T_A}{T_A - T_B}\hat{p}_2^* = 1 \quad (26)$$

334 $\hat{p}_1^* < 0$ since $T_B > T_A$ and since the quadratic polynomial has negative leading coefficient then the
numerator is positive for every $\hat{p}_1^* < \hat{p}^* < 1$ which is always true. We found that derivative of $R(1)$
336 by ϵ is positive for every ϵ . Therefore, $R(1)$ grows as ϵ grows, or in other words as $\alpha_2 - \alpha_1$ grows.
Thus, $R(1) < 0$ if and only if $\alpha_2 < \alpha_1$. Therefore, different value of vertical transmission does not
338 change the evolution of social-interaction association and invasion is possible when $\alpha_2 < \alpha_1$.

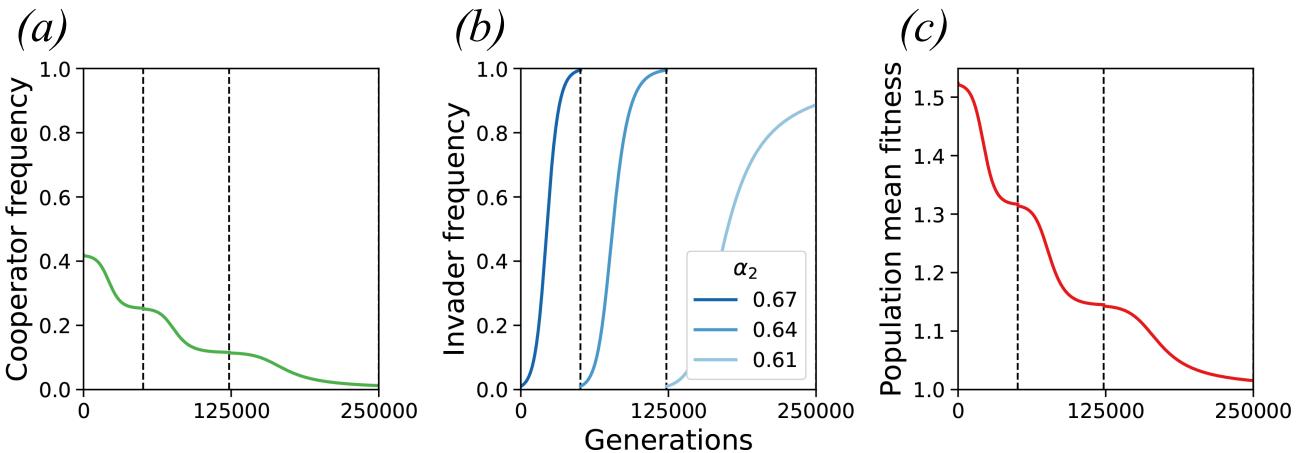


Figure 4: Reduction principle for interaction-transmission association. Consecutive fixation of modifier alleles that reduce interaction-transmission association α in numerical simulations of evolution with two modifier alleles (Eq. D1). When an invading modifier allele is established in the population (frequency $> 99.95\%$), a new modifier allele that reduces interaction-transmission association by 5% is introduced (at initial frequency 0.5%). **(a)** The frequency of the cooperative phenotype A over time. **(b)** The frequency of the invading modifier allele m over time. **(c)** The population mean fitness (\bar{w}) over time. Here, $v = 1$, $c = 0.05$, $b = 1.3$, $T_A = 0.4 < T_B = 0.7$, initial interaction-transmission association $\alpha_1 = 0.7$, lower interaction-transmission association threshold $\alpha_2 = 0.605$.

4.3 Population structure

All the simulations in this section were made by Ohad Lewin-Epstein from Tel Aviv University. Interaction-transmission association may also emerge from population structure. Consider a population colonizing a two-dimensional grid of size 100-by-100, where each site is inhabited by one individual, similarly to the model of Lewin-Epstein and Hadany [25]. Each individual is characterized by its phenotype: either cooperator, A , or defector, B . Initially, each site in the grid is randomly colonized by either a cooperator or a defector, with equal probability. In each generation, half of the individuals are randomly chosen to "initiate" interactions, and these initiators interact with a random neighbor (i.e. individual in a neighboring site) in a prisoners' dilemma game (Figure 1c) and a random neighbor (with replacement) for horizontal cultural transmission (Figure 1b). The expected number of each of these interactions per individual per generation is one, but the realized number of interactions can be zero, one, or even more than one, and in every interaction both individuals are affected, not just the initiator. The effective interaction-transmission association α in this model is the probability that the same neighbor is picked for both interactions, or $\alpha = 1/M$, where M is the number of neighbors. On an infinite grid, $M = 8$ (i.e. Moore neighbourhood [37]), but on a finite grid M can be lower in neighbourhoods close to the grid border. As before, T_A and T_B are the probabilities of successful horizontal transmission of phenotypes A and B , respectively.

The order of the interactions across the grid at each generation is random. After all interactions take place, an individual's fitness is determined by $w = 1 + b \cdot n_b - c \cdot n_c$, where n_b is the number of interactions that individual had with cooperative neighbors, and n_c is the number of interactions in which that individual cooperated (note that the phenotype may change between consecutive interactions due to horizontal transmission). Then, a new generation is produced, and the sites can be settled by offspring of any parent, not just the neighboring parents. Selection is global, rather than local, in accordance with our deterministic model: The parent is randomly drawn with probability proportional to its fitness, divided by the sum of the fitness values of all potential parents. Offspring are assumed to have the same phenotype as their parents (i.e. $v = 1$).

The outcomes of stochastic simulations with such a structured population are shown in Figure 5, which demonstrates that the highest cost of cooperation c that permits the evolution of cooperation agrees with the conditions derived above for our model without population structure or stochasticity. An example of stochastic stable polymorphism is shown in Figure 5c. Changing the simulation so that selection is local (i.e. sites can only be settled by offspring of neighboring parents) had only a minor effect on the agreement with the derived conditions (Figure 6).

These comparisons between the deterministic unstructured model and the stochastic structured model show that the conditions derived for the deterministic model can be useful for predicting the dynamics under complex scenarios. Moreover, this structured population model demonstrates that our parameter for interaction-transmission association, α , can represent local interactions between individuals.

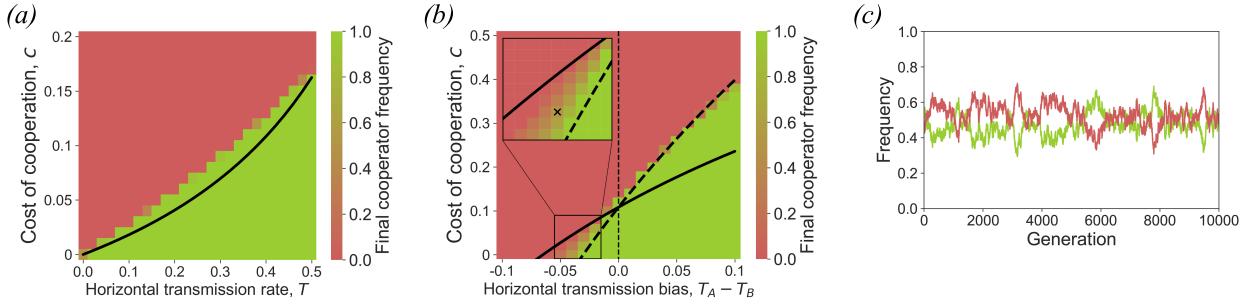


Figure 5: Evolution of cooperation in a structured population. (a-b) The expected frequency of cooperators in a structured population after 10,000 generations is shown (red for 0%, green for 100%) as a function of both the cost of cooperation, c , on the y-axis, and either the symmetric horizontal transmission rate, $T = T_A = T_B$, on the x-axis of panel (a), or the transmission bias, $T_A - T_B$, on the x-axis of panel (b). Black curves represent the cost thresholds for the evolution of cooperation in a well-mixed population with interaction-transmission association, where $\alpha = 1/8$ in inequality 16 for panel (a) and in Eqs. 14 for panel (b). The inset in panel (b) focuses on an area of the parameter range in which neither phenotype is fixed throughout the simulation, maintaining a stochastic locally stable polymorphism [38]. This stochastic polymorphism is illustrated in panel (c), which shows the frequency of cooperators (green) and defectors (red) over time for the parameter set marked by an x in panel (b). In all cases, the population evolves on a 100-by-100 grid. Cooperation and horizontal transmission are both local between neighbouring sites, and each site has 8 neighbours. Selection operates globally (see Figure S2 for results from a model with local selection). Simulations were stopped at generation 10,000 or if one of the phenotypes fixed. 50 simulations were executed for each parameter set. Benefit of cooperation, $b = 1.3$; perfect vertical transmission $v = 1$. (a) Symmetric horizontal transmission, $T = T_A = T_B$; (b) Horizontal transmission rate T_A is fixed at 0.4, and T_B varies, $0.3 < T_B < 0.5$. (c) Horizontal transmission rates $T_A = 0.4 < T_B = 0.435$ and cost of cooperation $c = 0.02$.

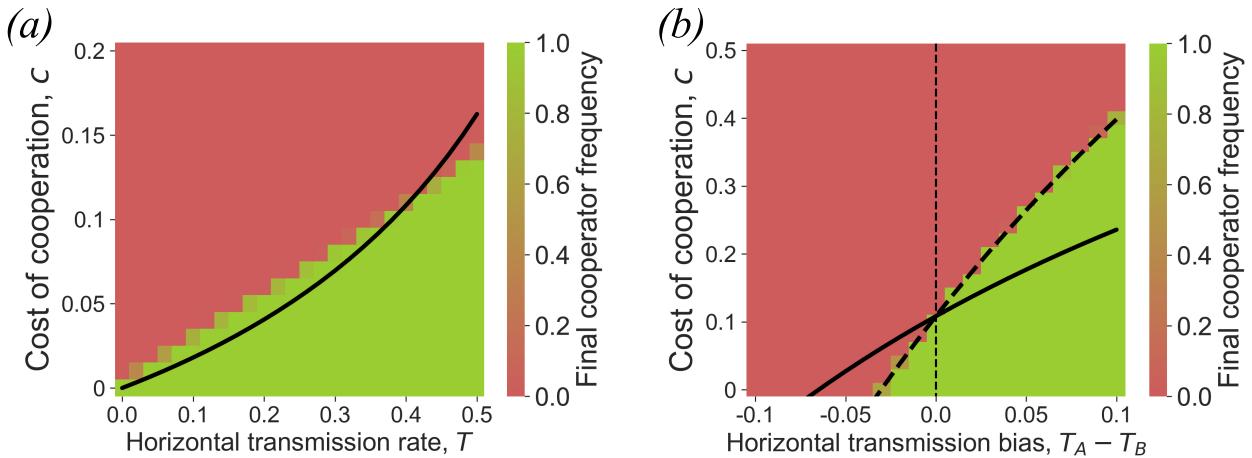


Figure 6: Evolution of cooperation in a structured population with local selection. The expected frequency of cooperators in a structured population after 10,000 generations is shown (red for 0%, green for 100%) as a function of both the cost of cooperation (c) on the y-axis, and the symmetric horizontal transmission rate ($T = T_A = T_B$) on the x-axis of panel (a), or the transmission bias $T_A - T_B$ on the x-axis of panel (b). Cooperation and horizontal transmission are both local between neighbouring sites, and each site had 8 neighbours. Selection operates locally (see Figure 4 for results from a model with global selection). The black curves represent the cost thresholds for the evolution of cooperation in a well-mixed population with interaction-transmission association, where $\alpha = 1/8$ in inequality 14 for panel (a) and in Eqs. 12 for panel (b). The population evolves on a 100-by-100 grid. Simulations were stopped at generation 10,000 or if one of the phenotypes fixed. 50 simulations were executed for each parameter set. Here, benefit of cooperation, $b = 1.3$; perfect vertical transmission $v = 1$. (a) Symmetric horizontal transmission, $T = T_A = T_B$. (b) Horizontal transmission rate T_A is fixed at 0.4, and T_B varies, $0.3 < T_B < 0.5$.

5 Discussion

376 Under a combination of vertical, oblique, and horizontal transmission with payoffs in the form
377 of a prisoner’s dilemma game, cooperation or defection can either fix or coexist, depending on
378 the relationship between the cost and benefit of cooperation, the horizontal transmission bias, and
379 the association between social interaction and horizontal transmission (Result 1, Figures 2 and 3).
380 Importantly, cooperation can increase when initially rare (i.e. invade a population of defectors) if and
381 only if, rewriting inequality 15, $c \cdot v(1 - T_B) < b \cdot v\alpha T_A + (T_A - T_B)$, namely, the effective cost of
382 cooperation (left-hand side) is smaller than the effective benefit plus the horizontal transmission bias
383 (right-hand side). This condition cannot be formulated in the form of Hamilton’s rule, $c < b \cdot r$, due to
384 the effect of biased horizontal transmission, represented by $(T_A - T_B)$. Remarkably, a polymorphism
385 of cooperation and defection can be stable if horizontal transmission is biased in favor of defection
386 ($T_A < T_B$) and both c and α are intermediate (yellow areas in Figures 2 and 3).

We find that stronger interaction-transmission association α leads to evolution of higher frequency
388 of cooperation and increased population mean fitness. Nevertheless, when cooperation and defection
389 coexist, α is expected to be reduced by natural selection, leading to extinction of cooperation and
390 decreased population mean fitness (Result 2, Figure 4). With $\alpha = 0$, the benefit of cooperation cannot
facilitate its evolution; it can only succeed if horizontal transmission is biased in its favor.

392 Indeed, in our model, horizontal transmission plays a major role in the evolution of cooperation:
393 increasing the transmission of cooperation, T_A , or decreasing the transmission of defection, T_B , facil-
394 tates the evolution of cooperation. However, the effect of oblique transmission is more complicated.
When there is horizontal transmission bias in favor of cooperation, $T_A > T_B$, increasing the rate of
396 oblique transmission, $1 - v$, will facilitate the evolution of cooperation. In contrast, when the bias is
397 in favor of defection, $T_A < T_B$, higher rates of vertical transmission, v , are advantageous for cooper-
398 ation, and the rate of vertical transmission must be high enough ($v > \hat{v}$) for cooperation to fix in the
population.

400 Our deterministic model provides a good approximation to outcomes of simulations of a complex
stochastic model with population structure in which individuals can only interact with and transmit
402 to their neighbors. In these structured populations interaction-transmission association arises due to
both social interactions and horizontal cultural transmission being local (Figure 5).

404 Feldman et al. [22] studied the dynamics of an altruistic phenotype with vertical cultural transmission
and a gene that modifies the transmission of the phenotype. Their results are very sensitive to
406 this genetic modification: without it, the conditions for invasion of the altruistic phenotype reduce
to Hamilton’s rule. Further work is needed to incorporate such genetic modification of cultural
408 transmission into our model. Woodcock [23] stressed the significance of non-vertical transmission for
the evolution of cooperation and carried out simulations with prisoner’s dilemma payoffs but without
410 horizontal transmission or interaction-transmission association ($\alpha = 0$). Nevertheless, his results
demonstrated that it is possible to sustain altruistic behavior via cultural transmission for a substantial
412 length of time. He further hypothesized that horizontal transmission can play an important role in the

evolution of cooperation, and our results provide strong evidence for this hypothesis.

- 414 To understand the role of horizontal transmission, we first review the role of *assortment*. Eshel and
415 Cavalli-Sforza [19] showed that altruism can evolve when the tendency for *assortative meeting*, i.e.
416 for individuals to interact with others of their own phenotype, is strong enough. Fletcher and Doebeli
417 [17] further argued that a general explanation for the evolution of altruism is given by *assortment*: the
418 correlation between individuals that carry an altruistic trait and the amount of altruistic behavior in
419 their interaction group (see also Bijma and Aanen [20]). They suggested that to explain the evolution of
420 altruism, we should seek mechanisms that generate assortment, such as population structure, repeated
421 interactions, and individual recognition. Our results highlight another mechanism for generating
422 assortment: an association between social interactions and horizontal transmission that creates a
423 correlation between one's partner for interaction and the partner for transmission. This mechanism
424 does not require repeated interactions, population structure, or individual recognition. We show that
425 high levels of such interaction-transmission association greatly increase the potential for evolution of
426 cooperation. With enough interaction-transmission association, cooperation can increase in frequency
when initially rare even when there is horizontal transmission bias against it ($T_A < T_B$).
- 428 How does non-vertical transmission generate assortment? Lewin-Epstein et al. [24] and Lewin-
429 Epstein and Hadany [25] suggested that microbes that induce their hosts to act altruistically can
430 be favored by selection, which may help to explain the evolution of cooperation. From the kin
431 selection point-of-view, if microbes can be transmitted *horizontally* from one host to another during
432 host interactions, then following horizontal transmission the recipient host will carry microbes that
433 are closely related to those of the donor host, even when the two hosts are (genetically) unrelated.
434 From the assortment point-of-view, infection by behavior-determining microbes during interactions
435 effectively generates assortment because a recipient of help may be infected by a behavior-determining
436 microbe and consequently become a helper. Cultural horizontal transmission can similarly generate
437 assortment between cooperators and enhance the benefit of cooperation if cultural transmission and
438 helping interactions occur between the same individuals, i.e. when there is interaction-transmission
439 association, so that the recipient of help may also be the recipient of the cultural trait for cooperation.
440 Thus, with horizontal transmission, “assortment between focal cooperative players and cooperative
441 acts in their interaction environment” [17] is generated not because the helper is likely to be helped,
442 but rather because the helped is likely to become a helper.

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528 **Appendices**

Appendix A Local stability criterion

530 Let $f(p) = \lambda \cdot (p' - p)$, where $\lambda > 0$, and 0 and 1 are equilibria, that is, $f(0) = 0$ and $f(1) = 0$.

Set $p > p^* = 0$. Using a linear approximation for $f(p)$ near 0, we have

$$532 \quad p' < p \Leftrightarrow f(p)/p < 0 \Leftrightarrow \frac{f'(0) \cdot p + O(p^2)}{p} < 0 \Leftrightarrow f'(0) + O(p) < 0. \quad (\text{A1})$$

Therefore, by definition of big-O notation, if $f'(0) < 0$ then there exists $\epsilon > 0$ such that for any local
534 perturbation $0 < p < \epsilon$, it is guaranteed that $0 < p' < p$; that is, p' is closer to zero than p .

Set $p < p^* = 1$ Using a linear approximation for $f(p)$ near 1, we have

$$536 \quad 1 - p' < 1 - p \Leftrightarrow -\frac{f(p)}{1 - p} < 0 \Leftrightarrow \frac{f'(1)(p - 1) + O((p - 1)^2)}{p - 1} < 0 \Leftrightarrow f'(1) - O(1 - p) < 0. \quad (\text{A2})$$

Therefore, if $f'(1) < 0$ then there exists $\epsilon > 0$ such that for any $1 - \epsilon < 1 - p < 1$ we have $1 - p' < 1 - p$;
538 that is, p' is closer to one than p .

Appendix B Equilibria and stability

540 Let $f(\hat{p}) = \bar{w}(\hat{p}' - \hat{p})$. Then, using SymPy [36], a Python library for symbolic mathematics, this simplifies to

$$542 \quad f(\hat{p}) = \bar{w}(\hat{p}' - \hat{p}) = \beta_1 \hat{p}^3 + \beta_2 \hat{p}^2 + \beta_3 \hat{p} , \quad (\text{B1})$$

where

$$\begin{aligned} 544 \quad \beta_1 &= [c(1 - v) - b(1 - \alpha v)](T_A - T_B) , \\ \beta_2 &= -\beta_1 - \beta_3 , \\ \beta_3 &= \alpha b v T_A - c v (1 - T_B) + (T_A - T_B) . \end{aligned} \quad (\text{B2})$$

If $T = T_A = T_B$ then $\beta_1 = 0$ and $\beta_3 = -\beta_2 = \alpha b v T - c v (1 - T)$, and $f(\hat{p})$ becomes a quadratic polynomial,

$$546 \quad f(\hat{p}) = \hat{p}(1 - \hat{p})[\alpha b v T - c v (1 - T)] . \quad (\text{B3})$$

548 Clearly the only two equilibria are the fixations $\hat{p} = 0$ and $\hat{p} = 1$, which are locally stable if $f'(\hat{p}) < 0$ near the equilibrium (see Appendix A), where $f'(\hat{p}) = (1 - 2\hat{p})[\alpha b v T - c v (1 - T)]$, so 550 that

$$\begin{aligned} f'(0) &= \alpha b v T - c v (1 - T) , \\ f'(1) &= -\alpha b v T + c v (1 - T) . \end{aligned} \quad (\text{B4})$$

552 In the general case where $T_A \neq T_B$, the coefficient β_1 is not necessarily zero, and $f(\hat{p})$ is a cubic polynomial. Therefore, three equilibria may exist, two of which are $\hat{p} = 0$ and $\hat{p} = 1$, and the third 554 is

$$\hat{p}^* = \frac{\beta_3}{\beta_1} = \frac{\alpha b v T_A - c v (1 - T_B) + (T_A - T_B)}{[c(1 - v) - b(1 - \alpha v)](T_A - T_B)} . \quad (\text{B5})$$

556 Note that the sign of the cubic (Eq. B1) at positive (negative) infinity is equal (opposite) to the sign of β_1 . If $T_A > T_B$, then

$$558 \quad \beta_1 < [c(1 - \alpha v) - b(1 - \alpha v)](T_A - T_B) = (1 - \alpha v)(c - b)(T_A - T_B) < 0 , \quad (\text{B6})$$

since $c < b$ and $\alpha v < 1$. Hence the signs of the cubic at positive and negative infinity are negative and 560 positive, respectively. First, if $\beta_3 < \beta_1$ then $1 < \hat{p}^*$. Also, $f'(0) < 0$ and $f'(1) > 0$; that is, fixation 562 of the defector phenotype B is the only locally stable feasible equilibrium. Second, if $\beta_1 < \beta_3 < 0$ then $0 < \hat{p}^* < 1$ and therefore $f'(0) < 0$ and $f'(1) < 0$ so that both fixations are locally stable 564 and \hat{p}^* separates the domains of attraction. Third, if $0 < \beta_3$ then $\hat{p}^* < 0$ and therefore $f'(0) > 0$ and $f'(1) < 0$; that is, fixation of the cooperator phenotype A is the only locally stable legitimate equilibrium.

566 Similarly, if $T_A < T_B$, then

$$\beta_1 > [c(1 - \alpha v) - b(1 - \alpha v)](T_A - T_B) = (1 - \alpha v)(c - b)(T_A - T_B) > 0 , \quad (\text{B7})$$

568 since $c < b$ and $\alpha v < 1$, and the signs of the cubic at positive and negative infinity are positive and negative, respectively. First, if $\beta_3 < 0$ then $\hat{p}^* < 0$ and therefore $f'(0) < 0$ and $f'(1) > 0$; that

570 is, fixation of the defector phenotype A is the only locally stable legitimate equilibrium. Second, if
 $0 < \beta_3 < \beta_1$ then $0 < \hat{p}^* < 1$ and therefore $f'(0) > 0$ and $f'(1) > 0$; that is, both fixations are locally
572 unstable and \hat{p}^* is a stable polymorphic equilibrium. Third, if $\beta_1 < \beta_3$ then $\hat{p}^* > 1$ and therefore
 $f'(0) > 0$ and $f'(1) < 0$, and fixation of the cooperator phenotype A is the only locally stable feasible
574 equilibrium.

This analysis can be summarized as follows:

- 576 1. *Fixation of cooperation*: if (i) $T = T_A = T_B$ and $c < b \cdot \frac{\alpha T}{1-T}$; or if (ii) $T_A > T_B$ and $0 < \beta_3$; or if
 $(iii) T_A < T_B$ and $\beta_1 < \beta_3$.
- 578 2. *Fixation of the defection*: if (iv) $T = T_A = T_B$ and $c > b \cdot \frac{\alpha T}{1-T}$; or if (v) $T_A > T_B$ and $\beta_3 < \beta_1 < 0$;
or if (vi) $T_A < T_B$ and $\beta_3 < 0$.
- 580 3. *polymorphism of both phenotypes at \hat{p}^** : if (vii) $T_A < T_B$ and $0 < \beta_3 < \beta_1$.
4. *Fixation of either phenotype depending on initial frequency*: if (viii) $T_A > T_B$ and $\beta_1 < \beta_3 < 0$.

582 We now proceed to use the cost thresholds, γ_1 and γ_2 , and the vertical transmission threshold, \hat{v} (Eq. 14).
First, assume $T_A < T_B$. $\beta_3 < 0$ requires $\gamma_1 < c$. For $\beta_3 < \beta_1$ we need $c[v(1-T_B)+(1-v)(T_A-T_B)] >$
584 $b\alpha T_B + (1+b)(T_A - T_B)$. Note that the expression in the square brackets is positive if and only if
 $v > \hat{v}$. Thus, for $\beta_3 < \beta_1$ we need $v > \hat{v}$ and $\gamma_2 < c$ or $v < \hat{v}$ and $c < \gamma_2$, and for $0 < \beta_3 < \beta_1$ we need
586 $v > \hat{v}$ and $\gamma_2 < c < \gamma_1$, or $v < \hat{v}$ and $c < \min(\gamma_1, \gamma_2)$. For $\beta_1 < \beta_3$ we need $v > \hat{v}$ and $c < \gamma_2$ or $v < \hat{v}$
and $\gamma_2 < c$. However, some of these conditions cannot be met, since $v < \hat{v}$ implies $c < 1 < \gamma_2$.

588 Second, assume $T_A > T_B$. $\beta_3 > 0$ requires $\gamma_1 > c$. For $\beta_1 < \beta_3$ we need $c[v(1-T_B)+(1-v)(T_A-T_B)] <$
 $b\alpha T_B + (1+b)(T_A - T_B)$. Thus for $\beta_1 < \beta_3$ we need $v > \hat{v}$ and $c < \gamma_2$ or $v < \hat{v}$ and $c > \gamma_2$. But $\hat{v} < 0$
590 when $T_A > T_B$, and therefore we have $\beta_1 < \beta_3$ if $c < \gamma_2$. Similarly, we have $\beta_3 < \beta_1$ if $c > \hat{\gamma}_2$.

This analysis is summarized in Result 1.

592 **Appendix C Effect of interaction-transmission association on mean fitness**

594 To determine the effect of increasing α on the stable population mean fitness, $\bar{w}^* = 1 + (b - c)\hat{p}^*$, we must analyze its effect on \hat{p}^* ,

$$596 \quad \frac{\partial \hat{p}^*}{\partial \alpha} = \frac{bT_A - c(1 - T_B) + (T_A - T_B)}{b(1 - \alpha)^2(T_B - T_A)}. \quad (\text{C1})$$

Note that stable polymorphism implies $c < \gamma_1$, and because $\alpha < 1$, we have

$$598 \quad c < \gamma_1 = \frac{b\alpha T_A + (T_A - T_B)}{1 - T_B} < \frac{bT_A + (T_A - T_B)}{1 - T_B}. \quad (\text{C2})$$

Therefore, the numerator in Eq. C1 is positive. Since $T_A < T_B$, the denominator in Eq. C1 is also
600 positive, and hence the derivative $\partial \hat{p}^*/\partial \alpha$ is positive. Thus, the population mean fitness increases as interaction-transmission association α increases.

602 Appendix D Reduction principle

We assume here that $v = 1$, i.e. no oblique transmission, and therefore $\hat{p} = \dot{p}$. Denote the frequencies 604 of the pheno-genotypes AM , BM , Am , and Bm by $\mathbf{p} = (\dot{p}_1, \dot{p}_2, \dot{p}_3, \dot{p}_4)$. The frequencies of the pheno-genotypes in the next generation are defined by the recursion system,

$$\begin{aligned}
\bar{w}\dot{p}'_1 &= \dot{p}_1x(1+b-c)(1-(1-\alpha_1)(1-x)T_B) + \\
&\quad \dot{p}_1(1-x)(1-c)(1-\alpha_1T_Bx-T_B(1-x)) + \\
&\quad \dot{p}_2x(1+b)T_A(x+\alpha_1(1-x)) + \\
&\quad \dot{p}_2(1-x)x(1-\alpha_1)T_A, \\
\bar{w}\dot{p}'_2 &= \dot{p}_1x(1+b-c)(1-\alpha_1)(1-x)T_B + \\
&\quad \dot{p}_1(1-x)(1-c)(\alpha_1T_B+(1-\alpha_1)(1-x)T_B) + \\
&\quad \dot{p}_2x(1+b)(1-\alpha_1T_A(1-x)-T_AX) + \\
&\quad \dot{p}_2(1-x)(1-(1-\alpha_1)xT_A), \\
\bar{w}\dot{p}'_3 &= \dot{p}_3x(1+b-c)(1-(1-\alpha_2)(1-x)T_B) + \\
&\quad \dot{p}_3(1-x)(1-c)(1-\alpha_2T_Bx-T_B(1-x)) + \\
&\quad \dot{p}_4x(1+b)T_A(x+\alpha_2(1-x)) + \\
&\quad \dot{p}_4(1-x)x(1-\alpha_2)T_A, \\
\bar{w}\dot{p}'_4 &= \dot{p}_3x(1+b-c)(1-\alpha_2)(1-x)T_B + \\
&\quad \dot{p}_3(1-x)(1-c)(\alpha_2T_B+(1-\alpha_2)(1-x)T_B) + \\
&\quad \dot{p}_4x(1+b)(1-\alpha_2T_A(1-x)-T_AX) + \\
&\quad \dot{p}_4(1-x)(1-(1-\alpha_2)xT_A),
\end{aligned} \tag{D1}$$

606

where $x = \dot{p}_1 + \dot{p}_3$ is the total frequency of the cooperative phenotype A , and $\bar{w} = 1 + (b - c)x$ is the 608 population mean fitness.

The equilibrium where only allele M is present is $\mathbf{p}^* = (\dot{p}^*, 1 - \dot{p}^*, 0, 0)$, where

$$610 \quad \dot{p}^* = \frac{c(1 - T_B) - b\alpha_1 T_A - (T_A - T_B)}{b(1 - \alpha_1)(T_A - T_B)}, \tag{D2}$$

setting $\alpha = \alpha_1$ and $v = 1$ in Eq. 13. When $v = 1$, \dot{p}^* is a feasible polymorphism ($0 < \dot{p}^* < 1$) if 612 $T_A < T_B$ and $\gamma_2 < c < \gamma_1$ (Result 1).

The local stability of \mathbf{p}^* to the introduction of allele m is determined by the linear approximation \mathbf{L}^* 614 of the transformation in Eq. D1 near \mathbf{p}^* (i.e. the Jacobian of the transformation at the equilibrium).

\mathbf{L}^* is known to have a block structure, with the diagonal blocks occupied by the matrices \mathbf{L}_{in}^* and \mathbf{L}_{ex}^* 616 [33, 35]. The latter is the external stability matrix: the linear approximation to the transformation near \mathbf{p}^* involving only the pheno-genotypes Am and Bm , derived from Eq. D1, with $\bar{w}^* = 1 + (b - c)\dot{p}^*$ as

618 the stable population mean fitness,

$$\mathbf{L}_{ex}^* = \frac{1}{\bar{w}^*} \begin{bmatrix} l_{11} & l_{12} \\ l_{21} & l_{22} \end{bmatrix} = \frac{1}{\bar{w}^*} \begin{bmatrix} \frac{\partial \bar{w} \dot{p}_3'}{\partial \dot{p}_3}(\mathbf{p}^*) & \frac{\partial \bar{w} \dot{p}_3'}{\partial \dot{p}_4}(\mathbf{p}^*) \\ \frac{\partial \bar{w} \dot{p}_4'}{\partial \dot{p}_3}(\mathbf{p}^*) & \frac{\partial \bar{w} \dot{p}_4'}{\partial \dot{p}_4}(\mathbf{p}^*) \end{bmatrix} = \frac{1}{\bar{w}^*} \begin{bmatrix} (1 + b\dot{p}^* - c)(1 - T_B(1 - \dot{p}^*)) + b\dot{p}^*\alpha_2 T_B(1 - \dot{p}^*) & (1 + b\dot{p}^*)T_A \dot{p}^* + b\dot{p}^*\alpha_2 T_A(1 - \dot{p}^*) \\ (1 + b\dot{p}^* - c)T_B(1 - \dot{p}^*) - b\dot{p}^*\alpha_2 T_B(1 - \dot{p}^*) & (1 + b\dot{p}^*)(1 - T_A \dot{p}^*) - b\dot{p}^*\alpha_2 T_A(1 - \dot{p}^*) \end{bmatrix}. \quad (\text{D3})$$

620 Because we assume that \mathbf{p}^* is internally stable (i.e. locally stable to small perturbations in the frequencies of AM and BM), the stability of \mathbf{p}^* is determined by the eigenvalues of the external
622 stability matrix \mathbf{L}_{ex}^* . This is a positive matrix, and due to the Perron-Frobenius theorem, the leading
624 eigenvalue of \mathbf{L}_{ex}^* is real and positive. Thus, if the leading eigenvalue is less (greater) than one, then the
626 equilibrium \mathbf{p}^* is externally stable (unstable) and allele m cannot (can) invade the population of allele
628 M . The eigenvalues of \mathbf{L}_{ex}^* are the roots of the characteristic polynomial, $R(\lambda)$, which is a quadratic
with a positive leading coefficient. Therefore, $\lim_{\lambda \rightarrow \pm\infty} R(\lambda) = \infty$, and the leading eigenvalue is less
than one (implying stability) if and only if $R(1) > 0$ and $R'(1) > 0$. Thus, a sufficient condition for
external instability of \mathbf{p}^* is $R(1) < 0$.

$R(\lambda)$ is defined as a determinant, $R(\lambda) = \det(\mathbf{L}_{ex}^* - \lambda\mathbf{I})$, where \mathbf{I} is the 2-by-2 identity matrix. Since
630 multiplication by a positive factor doesn't change the sign, and using the properties of the determinant,
we have

$$632 \quad \begin{aligned} \text{sign } R(1) &= \text{sign } \det(\mathbf{L}_{ex}^* - \mathbf{I}) = \text{sign } (\bar{w}^*)^2 \det(\mathbf{L}_{ex}^* - \mathbf{I}) = \\ \text{sign } \det(\bar{w}^* \mathbf{L}_{ex}^* - \bar{w}^* \mathbf{I}) &= \text{sign } \det \begin{bmatrix} l_{11} - \bar{w}^* & l_{12} \\ l_{21} & l_{22} - \bar{w}^* \end{bmatrix}, \end{aligned} \quad (\text{D4})$$

where l_{ij} are defined in Eq. D3. Adding the second row in Eq. D4 to the first row, which does not
634 change the determinant, and substituting $\bar{w}^* = 1 + (b - c)\dot{p}^*$, we get

$$\begin{aligned} \text{sign } R(1) &= \text{sign } \det \begin{bmatrix} -c(1 - \dot{p}^*) & c\dot{p}^* \\ (1 - \dot{p}^*)[(1 + b\dot{p}^* - c)T_B - b\alpha_2 T_B \dot{p}^*] & \dot{p}^*[-(1 + b\dot{p}^*)T_A - b\alpha_2 T_A(1 - \dot{p}^*) + c] \end{bmatrix} = \\ &= \text{sign} \left[c\dot{p}^*(1 - \dot{p}^*) \cdot \det \begin{bmatrix} -1 & 1 \\ (1 + b\dot{p}^* - c)T_B - b\alpha_2 T_B \dot{p}^* & -(1 + b\dot{p}^*)T_A - b\alpha_2 T_A(1 - \dot{p}^*) + c \end{bmatrix} \right] = \\ &= \text{sign } \det \begin{bmatrix} -1 & 1 \\ (1 + b\dot{p}^* - c)T_B - b\alpha_2 T_B \dot{p}^* & -(1 + b\dot{p}^*)T_A - b\alpha_2 T_A(1 - \dot{p}^*) + c \end{bmatrix}, \end{aligned} \quad (\text{D5})$$

636 since $c > 0, 0 < \dot{p}^* < 1$. That is,

$$\begin{aligned} \text{sign } R(1) &= \text{sign} \left[(1 + b\dot{p}^*)T_A + b\alpha_2 T_A(1 - \dot{p}^*) - c - (1 + b\dot{p}^* - c)T_B + b\dot{p}^*\alpha_2 T_B \right] = \\ &\quad \text{sign} \left[(1 + b(1 - \alpha_2)\dot{p}^*)(T_A - T_B) + b\alpha_2 T_A - c(1 - T_B) \right]. \end{aligned} \quad (\text{D6})$$

638 Substituting \dot{p}^* from Eq. D2, we get

$$\begin{aligned}
R(1) < 0 \Leftrightarrow & [c(1 - T_B) - b\alpha_1 T_A - (T_A - T_B)] \frac{1 - \alpha_2}{1 - \alpha_1} - c(1 - T_B) + b\alpha_2 T_A + (T_A - T_B) < 0 \Leftrightarrow \\
& (1 - \alpha_2)[c(1 - T_B) - b\alpha_1 T_A - (T_A - T_B)] < (1 - \alpha_1)[c(1 - T_B) - b\alpha_2 T_A - (T_A - T_B)] \Leftrightarrow \\
& -b\alpha_1 T_A - \alpha_2 c(1 - T_B) + \alpha_2 (T_A - T_B) < -b\alpha_2 T_A - \alpha_1 c(1 - T_B) + \alpha_1 (T_A - T_B) \Leftrightarrow \\
& \alpha_1[c(1 - T_B) - bT_A - (T_A - T_B)] < \alpha_2[c(1 - T_B) - bT_A - (T_A - T_B)] \Leftrightarrow \\
& \alpha_1[bT_A + (T_A - T_B) - c(1 - T_B)] > \alpha_2[bT_A + (T_A - T_B) - c(1 - T_B)] .
\end{aligned} \tag{D7}$$

640 We assumed $c < \gamma_1$, and since $0 \leq \alpha_1 \leq 1$,

$$\begin{aligned}
c < \gamma_1 = \frac{b\alpha_1 T_A + (T_A - T_B)}{1 - T_B} \Leftrightarrow \\
0 < b\alpha_1 T_A + (T_A - T_B) - c(1 - T_B) \Rightarrow \\
0 < bT_A + (T_A - T_B) - c(1 - T_B) .
\end{aligned} \tag{D8}$$

642 Combining inequalities D7 and D8, we find that $R(1) < 0$ if and only if $\alpha_1 > \alpha_2$, which is a sufficient condition for external instability. Therefore, if α_2 , the interaction-transmission association of the 644 invading modifier allele m , is less than α_1 , the interaction-transmission association of the resident allele M , then invasion will be successful.

646 Determining a necessary and sufficient condition for successful invasion is more complicated, requiring analysis of the sign of $R'(1)$. However, we have numerically validated that the leading eigenvalue is 648 greater than one if and only if $\alpha_1 > \alpha_2$.