

# Cultural Transmission Can Explain the Evolution of Cooperation

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# Introduction

Cooperative behavior can harm an individual's fitness and increase the fitness of its conspecifics or competitors (Axelrod and Hamilton, 1981). Nevertheless, cooperative behavior appears to occur in many non-human animals (Dugatkin, 1997), for example rats (Rice and Gainer, 1962) and birds (Krams et al., 2008). Evolution of cooperative behavior remains an important conundrum in evolutionary biology.

*Kin selection* theory posits that natural selection can favor cooperation between related individuals. The importance of relatedness to the evolution of cooperation and altruism was shown by Hamilton (1964). According to Hamilton, for an allele that determines cooperative behavior to increase in frequency, the reproductive cost to the actor that cooperates,  $c$ , must be less than the benefit to the recipient,  $b$ , times the 'relatedness' between the recipient and the actor,  $r$ . This 'relatedness' coefficient  $r$  measures the correlation between the gene in the actor and the gene in the recipient. This condition is also known as Hamilton's rule:

$$c < b \cdot r. \quad (1)$$

Eshel and Cavalli-Sforza (1982) have studied a relevant model for the evolution of cooperative behavior under vertical transmission. Their model included *assortative meeting*, or non-random encounters. That is, if a fraction  $m$  of the population interacts with an individual of the same phenotype, and  $1 - m$  interacts randomly. Such assortative meeting may be due, for example, to population structure or active partner choice. In their model, cooperative behavior can evolve if <sup>1</sup>. (Eshel and Cavalli-Sforza, 1982, eq. 3.2)

$$c < b \cdot m, \quad (2)$$

where  $b$  and  $c$  are the benefit and cost of cooperation. Here,  $m$  takes the role of the relatedness  $r$ .

Here we attempt to determine to what extent the evolution of cooperative behavior can be explained by *cultural transmission*, which allows an individual to acquire attitudes and behavioral traits from other individuals in its social group through imitation, learning, or other modes of communication (Cavalli-Sforza and Feldman, 1981; Richerson and Boyd, 2008). Feldman et al. (1985) introduced the first model for the evolution of altruism by cultural transmission. They showed that under vertical (parent-to-offspring) cultural transmission, Hamilton's rule does not govern the evolution of parent-to-offspring or sib-to-sib altruism.

*Non-vertical transmission* may be either horizontal or oblique: horizontal transmission occurs between individuals from the same generation, while oblique transmission occurs from adults to unrelated offspring. Evolution under either of these transmission models can be more rapid than under pure vertical transmission (Cavalli-Sforza and Feldman, 1981; Ram et al., 2018). Lewin-Epstein et al. (2017) have demonstrated that non-vertical transmission, mediated by microbes that manipulate their host behavior, can help to explain the evolution of cooperative behavior. Interestingly, some of their analysis can be applied to cultural transmission, because models of cultural transmission are mathematically similar to those for transmission of infectious diseases (Cavalli-Sforza and Feldman, 1981).

We hypothesize that non-vertical cultural transmission can help explain the evolution of cooperation. To test this hypothesis, we suggest a model in which behavioral changes are mediated by cultural transmission that can occur during social interactions. For example, if an individual interacts with a cooperative individual, it might learn that cooperation is a positive behavior and will be cooperative in the future. We develop cultural evolution models that include both vertical and non-vertical transmission of cooperation and investigate these models using mathematical analysis and simulations.

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<sup>1</sup>In an extended model, which allows an individual to encounter  $N$  individuals before choosing a partner, the righthand side is multiplied by  $E[N]$ , the expected number of encounters (Eshel and Cavalli-Sforza, 1982, eq. 4.6).

Our results demonstrate cultural transmission can facilitate the evolution of cooperation even when genetic transmission cannot. These results suggest that further research on the evolution of cooperation should account for non-vertical transmission and that treatment of cooperation as a cultural, rather than genetic trait, can lead to a better understanding of this important and enigmatic phenomenon.

## Models

We focus on the evolution of cooperation in a fully mixed population where cooperation is modeled using the *prisoner's dilemma*.

Consider a very large population whose members are characterized by their phenotype  $\phi$ , which can be of two types,  $\phi = A$  for cooperators or  $\phi = B$  for defectors. An offspring inherits its phenotype from its parent via vertical transmission with probability  $v$  or from a random individual in the parental population via oblique transmission with probability  $(1 - v)$ . Following Ram et al. (2018), given that the parent phenotype is  $\phi$  and assuming uni-parental inheritance, the conditional probability that the phenotype  $\phi'$  of the offspring is  $A$  is

$$P(\phi' = A \mid \phi) = \begin{cases} v + (1 - v)p, & \text{if } \phi = A \\ (1 - v)p, & \text{if } \phi = B \end{cases}, \quad (3)$$

where  $p = P(\phi = A)$  is the frequency of  $A$  among all adults in the parental generation.

Not all adults become parents due to natural selection, and we denote the frequency of phenotype  $A$  among parents with  $\tilde{p}$ . Therefore, the frequency  $\hat{p}$  of phenotype  $A$  among juveniles (after selection and vertical and oblique transmission) is

$$\begin{aligned} \hat{p} &= \tilde{p}[v + (1 - v)p] + (1 - \tilde{p})[(1 - v)p] \\ &= v\tilde{p} + (1 - v)p. \end{aligned} \quad (4)$$

Individuals interact according to a prisoner's dilemma. Specifically, individuals interact in pairs; a cooperator suffers a fitness cost  $0 < c < 1$ , and its partner gains a fitness benefit  $b$ , where we assume  $c < b$ . **Table 1** shows the payoff matrix, i.e. the fitness of an individual with phenotype  $\phi_1$  when interacting with a partner of phenotype  $\phi_2$ .

	$\phi_2 = A$	$\phi_2 = B$
$\phi_1 = A$	$1 + b - c$	$1 - c$
$\phi_1 = B$	$1 + b$	$1$

**Table 1: Payoff matrix for prisoner's dilemma.** The fitness of phenotype  $\phi_1$  when interacting with phenotype  $\phi_2$ .  $A$  is a cooperative phenotype,  $B$  is a defector phenotype,  $b$  is the benefit gained by an individual interacting with a cooperator, and  $c$  is the cost of cooperation.  $b > c > 0$ .

Social interactions occur randomly: two individuals with phenotype  $A$  interact with probability  $\hat{p}^2$ , two individuals with phenotype  $B$  interact with probability  $(1 - \hat{p})^2$ , and two individuals with different phenotypes interact with probability  $2\hat{p}(1 - \hat{p})$ .

Horizontal cultural transmission occurs between pairs of individuals from the same generation. It occurs between social partners with probability  $\alpha$ , or between a random pair with probability  $1 - \alpha$  (see **Figure 1**). The assortment parameter  $\alpha$  is therefore the fraction of population that receives (horizontal transmission) from the social interaction partner, and  $1 - \alpha$  receives randomly. Horizontal transmission is not always successful, as one partner may reject the other's phenotype. The

Phenotype $\phi_1$	Phenotype $\phi_2$	Frequency	Fitness of $\phi_1$	$P(\phi_1 = A)$ via horizontal transmission:	
				from partner, $\alpha$	from population, $(1 - \alpha)$
A	A	$\hat{p}^2$	$1 + b - c$	1	$\hat{p} + (1 - \hat{p})(1 - T_B)$
A	B	$\hat{p}(1 - \hat{p})$	$1 - c$	$1 - T_B$	$\hat{p} + (1 - \hat{p})(1 - T_B)$
B	A	$\hat{p}(1 - \hat{p})$	$1 + b$	$T_A$	$\hat{p}T_A$
B	B	$(1 - \hat{p})^2$	1	0	$\hat{p}T_A$

Table 2: **Interaction frequency, fitness, and transmission probabilities.**

84 probability for successful horizontal transmission of phenotypes A and B are  $T_A$  and  $T_B$ , respectively  
(**Table 2**).

86 Therefore, the frequency  $p'$  of phenotype A among adults in the next generation, after horizontal  
transmission, is

$$\begin{aligned}
 p' = & \hat{p}^2[\alpha + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] \\
 & + \hat{p}(1 - \hat{p})[\alpha(1 - T_B) + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] \\
 & + (1 - \hat{p})\hat{p}[\alpha T_A + (1 - \alpha)\hat{p}T_A] \\
 & + (1 - \hat{p})^2[(1 - \alpha)\hat{p}T_A] ,
 \end{aligned} \tag{5}$$

which simplifies to

$$p' = \hat{p}^2(T_B - T_A) + \hat{p}(1 + T_A - T_B). \tag{6}$$

The frequency of A among parents (i.e. after selection) follows a similar dynamic, but also includes  
the effect of natural selection, and is therefore

$$\begin{aligned}
 \bar{w}\tilde{p}' = & \hat{p}^2(1 + b - c)[\alpha + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] \\
 & + \hat{p}(1 - \hat{p})(1 - c)[\alpha(1 - T_B) + (1 - \alpha)(\hat{p} + (1 - \hat{p})(1 - T_B))] \\
 & + (1 - \hat{p})\hat{p}(1 + b)[\alpha T_A + (1 - \alpha)\hat{p}T_A] \\
 & + (1 - \hat{p})^2[(1 - \alpha)\hat{p}T_A] ,
 \end{aligned} \tag{7}$$

94 where fitness values are taken from **Table 1** and **Table 2**, and the population mean fitness is

$$\bar{w} = 1 + \hat{p}(b - c). \tag{8}$$

96 Equation 7 can be simplified to

$$\begin{aligned}
 \bar{w}\tilde{p}' = & \hat{p}^2(1 + b - c)(1 - (1 - \hat{p})(1 - \alpha)T_B) \\
 & + \hat{p}(1 - \hat{p})(1 - c)(\hat{p}(1 - \alpha)T_B + 1 - T_B) \\
 & + (1 - \hat{p})\hat{p}(1 + b)(\hat{p}(1 - \alpha) + \alpha)T_A \\
 & + (1 - \hat{p})^2\hat{p}(1 - \alpha)T_A .
 \end{aligned} \tag{9}$$

## 98 Results

### Oblique and Horizontal Transmission

100 With only oblique and horizontal transmission, i.e.  $v = 0$ , Equation 4 becomes  $\hat{p} = p$  and Equation 6  
becomes

$$p' = p^2(T_B - T_A) + p(1 + T_A - T_B), \tag{10}$$

which gives the following result.

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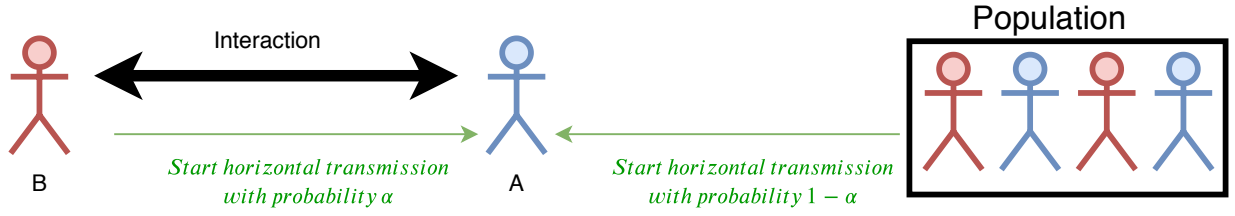


Figure 1: **Cultural horizontal transmission.** Transmission occurs between interacting partners with probability  $\alpha$  (left) or between two random peers with probability  $1 - \alpha$ .

**Result 1** (Oblique and horizontal transmission of cooperation). *Without vertical transmission ( $v = 0$ ), if there is a horizontal transmission bias in favor of cooperation, namely*

$$T_A > T_B, \quad (11)$$

*then  $p' > p$ , and the frequency of the cooperator phenotype among adults increases every generation.*

Therefore, in the absence of vertical transmission, selection plays no role in the evolution of cooperation. Hence, cooperation will evolve if the cooperator phenotype has a horizontal transmission bias (see ??).

## Vertical and Horizontal Transmission

With only vertical and horizontal transmission, i.e.  $v = 1$ , Equation 4 becomes  $\hat{p} = \tilde{p}$ , and Equation 9 for the frequency of the cooperative phenotype among parents in the next generation  $\tilde{p}'$  can be written as

$$\begin{aligned} \bar{w}\tilde{p}' &= \tilde{p}^2(1+b-c)[1-(1-\tilde{p})(1-\alpha)T_B] \\ &\quad + \tilde{p}(1-\tilde{p})(1-c)[\tilde{p}(1-\alpha)T_B + 1 - T_B] \\ &\quad + \tilde{p}(1-\tilde{p})(1+b)[\tilde{p}(1-\alpha) + \alpha]T_A \\ &\quad + (1-\tilde{p})^2\tilde{p}(1-\alpha)T_A. \end{aligned} \quad (12)$$

The fixation of either cooperation or defection,  $\tilde{p} = 0$  and  $\tilde{p} = 1$ , are equilibria of Equation 12, that is, they solve  $\tilde{p}' = \tilde{p}$ . We therefore assume for the remainder of the analysis that  $0 < \tilde{p} < 1$ .

If  $\alpha = 1$ , then  $\tilde{p}' = \tilde{p}$  is reduced to

$$\tilde{p}(1-\tilde{p})[(1+b)T_A + (1-c)(1-T_B) - 1] = 0, \quad (13)$$

and there are no additional equilibria.

Therefore, for cooperation to take over the population (for  $\tilde{p} = 1$  to be globally stable) we require  $\tilde{p}' > \tilde{p}$ , that is,

$$\tilde{p}^2(1+b-c) + \tilde{p}(1-\tilde{p})[(1-c)(1-T_B) + (1+b)T_A] > \bar{w}\tilde{p}. \quad (14)$$

We divide by  $\tilde{p}$ , set  $\bar{w} = 1 + \tilde{p}(b-c)$ , and rearrange to get

$$(1-\tilde{p})[(1-c)(1-T_B) + (1+b)T_A] > 1 - \tilde{p}. \quad (15)$$

Dividing by  $(1-\tilde{p})$  we find that  $\tilde{p}' > \tilde{p}$  if

$$(1-c)(1-T_B) + (1+b)T_A > 1 \quad (16)$$

If  $\alpha < 1$ , we want to determine a condition for  $\tilde{p}' > \tilde{p}$ . We divide Equation 12 by  $\tilde{p}$  and set  $\tilde{w} = 1 + \tilde{p}(b - c)$  to get

$$\begin{aligned} 1 + \tilde{p}(b - c) &< \tilde{p}(1 + b - c)(1 - (1 - \tilde{p})(1 - \alpha)T_B) \\ &+ (1 - \tilde{p})(1 - c)(\tilde{p}(1 - \alpha)T_B + 1 - T_B) \\ &+ (1 - \tilde{p})(1 + b)(\tilde{p}(1 - \alpha) + \alpha)T_A \\ &+ (1 - \tilde{p})^2(1 - \alpha)T_A. \end{aligned} \quad (17)$$

Rearranging, we get

$$\begin{aligned} 1 - \tilde{p} &< -\tilde{p}(1 + b - c)(1 - \tilde{p})(1 - \alpha)T_B \\ &+ (1 - \tilde{p})(1 - c)(\tilde{p}(1 - \alpha)T_B + 1 - T_B) \\ &+ (1 - \tilde{p})(1 + b)(\tilde{p}(1 - \alpha) + \alpha)T_A \\ &+ (1 - \tilde{p})^2(1 - \alpha)T_A. \end{aligned} \quad (18)$$

Dividing by  $(1 - \tilde{p})$  and rearranging so that free terms are on the left and terms with  $\tilde{p}$  are on the right, we have

$$\begin{aligned} 1 - (1 - \alpha)T_A - (1 + b)\alpha T_A - (1 - T_B)(1 - c) &< \\ \tilde{p}[-(1 + b - c)(1 - \alpha)T_B + (1 - c)(1 - \alpha)T_B + (1 + b)(1 - \alpha)T_A - (1 - \alpha)T_A]. \end{aligned} \quad (19)$$

Simplifying, we find that  $\tilde{p}' > \tilde{p}$  if and only if

$$c(1 - T_B) - b\alpha T_A - (T_A - T_B) < \tilde{p} \cdot b(1 - \alpha)(T_A - T_B). \quad (20)$$

Following the same steps to solve  $\tilde{p}' = \tilde{p}$ , we find that there can be a third, polymorphic equilibrium

$$\tilde{p}^* = \frac{c(1 - T_B) - b\alpha T_A - (T_A - T_B)}{b(1 - \alpha)(T_A - T_B)}. \quad (21)$$

Note that this is a legitimate equilibrium only if  $0 < \tilde{p}^* < 1$ .

Note that all parameters are positive. So, applying Equation 20, for  $\tilde{p}' > \tilde{p}$  we require that either

$$T_A > T_B \quad \text{and} \quad \tilde{p} > \tilde{p}^*, \quad \text{or} \quad (22)$$

$$T_A < T_B \quad \text{and} \quad \tilde{p} < \tilde{p}^*. \quad (23)$$

We therefore have the following result and corollaries.

146

**Result 2** (Vertical and horizontal transmission of cooperation). *Without oblique transmission ( $v = 1$ ), fixation, extinction, and coexistence of both phenotypes are possible.*

We define the initial frequency as  $\tilde{p}_0$  and the cost boundaries

$$\gamma_1 = \frac{b\alpha T_A + (T_A - T_B)}{1 - T_B}, \quad \gamma_2 = \frac{b\alpha T_B + (1 + b)(T_A - T_B)}{1 - T_B}. \quad (24)$$

Applying eqs. 21, 22, and 23 we can summarize the possible outcomes (Figure 2):

1. Fixation of cooperation, if  $T_A > T_B$  and  $c < \gamma_1$ ; or if  $T_A > T_B$  and  $\gamma_1 < c < \gamma_2$  and  $\tilde{p}_0 > \tilde{p}^*$ ; or if  $T_A < T_B$  and  $c < \gamma_2$ .
2. Fixation of defection, if  $T_A > T_B$  and  $\gamma_2 < c$ ; or if  $T_A > T_B$  and  $\gamma_1 < c < \gamma_2$  and  $\tilde{p}_0 < \tilde{p}^*$ ; or if  $T_A < T_B$  and  $\gamma_1 < c$ .

3. Coexistence of both phenotypes at  $\tilde{p}^*$ , if  $T_A < T_B$  and  $\gamma_2 < c < \gamma_1$ .

It is interesting to note that cooperation and defection can stably coexist if there is horizontal bias for defection and the cost of cooperation is large but not too large. The recurrence for this case is illustrated in Figure 3.

Much of the literature on evolution of cooperation focuses on conditions for cooperation to invade a population of defectors. The next corollary deals with such a condition, followed by a corollary that deals with symmetric horizontal transmission, i.e.  $T_A = T_B$ .

**Corollary 1** (Condition for cooperation to increase from rarity). *If the initial frequency of the cooperative phenotype is very close to zero,  $\tilde{p}_0 \approx 0$ , then its frequency will increase if*

$$T_A > T_B \text{ and } c < \gamma_1, \quad \text{or} \quad T_A < T_B \text{ and } \gamma_2 < c < \gamma_1. \quad (25)$$

In general, these conditions cannot be formulated in the form of Hamilton's rule ( $c < b \cdot r$ ) due to the horizontal transmission bias  $T_A - T_B$ . Without horizontal transmission bias, we get the following corollary that does have the form of Hamilton's rule.

**Corollary 2** (Symmetric horizontal transmission). *If  $T = T_A = T_B$ , then cooperation will take over the population if*

$$c < b \cdot \frac{\alpha T}{1 - T}. \quad (26)$$

To verify, set  $T_A = T_B$  in Equation 20.

This can be interpreted as a version of Hamilton's rule (Equation 1), where  $\alpha T / (1 - T)$  is the 'effective relatedness'. Figure ?? demonstrates this condition.

**Corollary 3** (No assortment of transmission and cooperation). *When  $\alpha = 0$ , then if there is horizontal bias for cooperation ( $T_A > T_B$ ) and (1) the cost is low compared to the bias ( $c < (T_A - T_B) / (1 - T_B)$ ), then cooperation will fix from any positive frequency; or (2) the cost is low compared to the benefit ( $c < (1 + b)(T_A - T_B)(1 - T_B)$ ), then cooperation will fix if the initial frequency is high enough ( $\tilde{p}_0 > \tilde{p}^*$ ).*

Figure 2b demonstrates these conditions.

Here, the third equilibrium is

$$\tilde{p}^*(\alpha = 0) = \frac{c(1 - T_B) - (T_A - T_B)}{b(T_A - T_B)}, \quad (27)$$

and the cost boundaries are

$$\gamma_1(\alpha = 0) = \frac{T_A - T_B}{1 - T_B}, \quad \gamma_2(\alpha = 0) = (1 + b) \frac{T_A - T_B}{1 - T_B}. \quad (28)$$

If  $T_A > T_B$  then  $0 < \gamma_1(\alpha = 0) < \gamma_2(\alpha = 0)$ . So either  $c < \gamma_1(\alpha = 0)$  or  $\gamma_1(\alpha = 0) < c < \gamma_2(\alpha = 0)$  will allow fixation of cooperation, the latter only if the initial frequency is high enough. If  $T_A < T_B$  then  $\gamma_2(\alpha = 0) < \gamma_1(\alpha = 0) < 0 < c$ . So defection will fix in any case.

192 **Corollary 4** (Complete assortment of transmission and cooperation). *When  $\alpha = 1$ , there are only two*  
 equilibria,  $\tilde{p} = 0$  and  $\tilde{p} = 1$ . *The condition for evolution of cooperation (i.e. global stability of  $\tilde{p} = 1$ )*  
 194 *is found by setting  $\tilde{p}' > \tilde{p}$ , which gives*

$$c < \frac{b \cdot T_A + (T_A - T_B)}{1 - T_B}. \quad (29)$$

196 This is proven in Equation 16. In this case there is complete assortment, and horizontal transmission  
 always occurs together with the cooperative interaction. The same occurs in Lewin-Epstein et al.  
 198 (2017), and therefore this corollary is equivalent to their result, see their eq. 1.

In terms of the cost boundaries, Equation 29 is equivalent to  $c < \gamma_1$ . If  $T_A > T_B$  then that suffices  
 200 for fixation of cooperation. If  $T_B > T_A$  then  $\gamma_2(\alpha = 1) < 0$  and again, Equation 29 is sufficient for  
 increase in frequency of  $A$  up to  $\tilde{p}^*(\alpha = 1) \approx \infty$ .

202 Equation 29 can be written as

$$1 - (1 - c)(1 - T_B) < (1 + b)T_A, \quad (30)$$

204 which provides an interesting interpretation for the success of cooperation. Consider an interaction  
 between two individuals: a cooperator and a defector.  $(1 - c)(1 - T_B)$  is the probability that the  
 206 cooperator remains cooperative and also reproduces. Therefore,  $1 - (1 - c)(1 - T_B)$  is the probability  
 that either the cooperator becomes a defector, *or* that it fails to reproduce. This is the effective  
 208 cost for cooperation from this interaction.  $(1 + b)T_A$  is the probability that the defector becomes  
 cooperative and reproduces. This is the effective benefit for cooperation from this interaction. So,  
 210 Equation 29 means that cooperation can evolve if the effective cost for cooperation is less than the  
 effective benefit.

## 212 With Vertical and Oblique Transmission

In this case  $0 < v < 1$ , and the recursion system is more complex. Therefore, we focus on local  
 214 stability, rather than global stability. To proceed, we note that Equation 4 can give  $\hat{p}'$  as a function of  
 both  $p'$  and  $\tilde{p}'$ , Equation 6 gives  $p'$  as a function of  $\tilde{p}$ , and Equation 9 gives  $\tilde{p}'$  as a function of  $\hat{p}$ .  
 216 Combining these equations, we find an equation for  $\hat{p}'$  as a function of  $\hat{p}$ , see Appendix Appendix A.  
 We then determine the equilibria, which are solutions of  $\hat{p}' = \hat{p}$ , and analyse their local stability.

218 We apply Equation 4, Equation 6, and Equation 9 to obtain the function  $f(\hat{p})$ , see Appendix Ap-  
 pendix A:

$$220 \quad f(\hat{p}) = \bar{w}(\hat{p}' - \hat{p}) = \beta_1 \hat{p}^3 + \beta_2 \hat{p}^2 + \beta_3 \hat{p}, \quad (31)$$

where

$$\begin{aligned} \beta_1 &= [c(1 - v) - b(1 - \alpha v)](T_A - T_B), \\ \beta_2 &= -\beta_1 - \beta_3, \\ \beta_3 &= \alpha b v T_A - c v (1 - T_B) + (T_A - T_B). \end{aligned} \quad (32)$$

If  $T = T_A = T_B$  then  $\beta_1 = 0$  and  $\beta_3 = -\beta_2 = \alpha b v T - c v (1 - T)$ . Therefore,  $f(\hat{p})$  is a quadratic  
 224 polynomial,

$$f(\hat{p}) = \hat{p}(1 - \hat{p})[\alpha b v T - c v (1 - T)]. \quad (33)$$

226 Clearly the only two equilibria are the fixations of either phenotype,  $\hat{p} = 0$  and  $\hat{p} = 1$ . These equilibria  
 are locally stable if  $f'(\hat{p}) < 0$  (Appendix Appendix B). Therefore, we find the derivative,

$$228 \quad f'(\hat{p}) = (1 - 2\hat{p})[\alpha b v T - c v (1 - T)], \quad (34)$$



and investigate its sign at the equilibria,

$$\begin{aligned} f'(0) &= \alpha b v T - c v (1 - T), \\ f'(1) &= -\alpha b v T + c v (1 - T). \end{aligned} \quad (35)$$

Therefore with symmetric horizontal transmission, fixation of the cooperative phenotype ( $\hat{p} = 1$ ) occurs under the same condition as Corollary 1.1, Equation 26.

In the general case where  $T_A \neq T_B$ , the coefficient  $\beta_1$  is not necessarily zero, and  $f(\hat{p})$  is a cubic polynomial. Therefore, three equilibria may exist, two of which are  $\hat{p} = 0$  and  $\hat{p} = 1$ . By solving  $f(\hat{p})/[\hat{p}(1 - \hat{p})] = \beta_3 - \beta_1 \hat{p} = 0$  we find the third equilibrium

$$\hat{p}^* = \frac{\beta_3}{\beta_1}. \quad (36)$$

Note that the sign of this cubic at positive (negative) infinity is equal (opposite) to the sign of  $\beta_1$ . If  $T_A > T_B$ , then

$$\beta_1 < [c(1 - \alpha v) - b(1 - \alpha v)](T_A - T_B) = (1 - \alpha v)(c - b)(T_A - T_B) < 0, \quad (37)$$

since  $c < b$  and  $1 > \alpha v$ , the sign of the cubic at positive and negative infinity is negative and positive, respectively. First, if  $\beta_3 < \beta_1$  then  $1 < \hat{p}^*$  and therefore  $f'(0) < 0$  and  $f'(1) > 0$ , that is, fixation of the defector phenotype  $B$  is the only locally stable legitimate (i.e. between 0 and 1) equilibrium. Second, if  $\beta_1 < \beta_3 < 0$  then  $0 < \hat{p}^* < 1$  and therefore  $f'(0) < 0$  and  $f'(1) < 0$ , that is, both fixations are locally stable and  $\hat{p}^*$  separates the domains of attraction. Third, if  $0 < \beta_3$  then  $\hat{p}^* < 0$  and therefore  $f'(0) > 0$  and  $f'(1) < 0$ , that is, fixation of the cooperator phenotype  $A$  is the only locally stable legitimate equilibrium.

Similarly, if  $T_B > T_A$ , then

$$\beta_1 > [c(1 - \alpha v) - b(1 - \alpha v)](T_A - T_B) = (1 - \alpha v)(c - b)(T_A - T_B) > 0, \quad (38)$$

since  $c < b$ , and  $1 > \alpha v$ . So the sign of the cubic at positive and negative infinity is positive and negative, respectively. First, if  $\beta_3 < 0$  then  $\hat{p}^* < 0$  and therefore  $f'(0) < 0$  and  $f'(1) > 0$ , that is, fixation of the defector phenotype  $A = B$  is the only locally stable legitimate equilibrium. Second, if  $0 < \beta_3 < \beta_1$  then  $0 < \hat{p}^* < 1$  and therefore  $f'(0) > 0$  and  $f'(1) > 0$ , that is, both fixations are locally unstable and  $\hat{p}^*$  is a stable polymorphic equilibrium. Third, if  $\beta_1 < \beta_3$  then  $\hat{p}^* > 1$  and therefore  $f'(0) > 0$  and  $f'(1) < 0$ , that is, fixation of the cooperator phenotype  $A$  is the only locally stable legitimate equilibrium.

The following result summarizes these findings.

**Result 3** (Vertical, oblique, and horizontal transmission of cooperation). *The cultural evolution of a cooperator phenotype will follow one of the following scenarios, depending on the horizontal transmission bias  $T_A - T_B$  and the coefficients  $\beta_1$  and  $\beta_3$ :*

1. Fixation of cooperation, if  $T = T_A = T_B$  and  $c < b \cdot \frac{\alpha T}{1-T}$ ; or if  $T_A > T_B$  and  $0 < \beta_3$ ; or if  $T_A < T_B$  and  $\beta_1 < \beta_3$ .
2. Fixation of the defection, if  $T = T_A = T_B$  and  $c > b \cdot \frac{\alpha T}{1-T}$ ; or if  $T_A > T_B$  and  $\beta_3 < \beta_1 < 0$ ; or if  $T_A < T_B$  and  $\beta_3 < 0$ .
3. Coexistence of both phenotypes at  $\hat{p}^*$ , if  $T_A < T_B$  and  $0 < \beta_3 < \beta_1$ .
4. Fixation of either phenotype depending on initial frequency, if  $T_A > T_B$  and  $\beta_1 < \beta_3 < 0$ .

## 266 Discussion

268 We hypothesized that non-vertical transmission can explain the evolution of cooperation. We studied fully mixed and very large populations with a prisoner's dilemma payoff. We found that under oblique and horizontal transmission, horizontal transmission bias for the cooperative phenotype is 270 sufficient and necessary for evolution of cooperation (Result 1). Under horizontal and vertical cultural transmissions, cooperation or defection can fix, or coexist in a stable polymorphism, depending on 272 the relationship between the cost and benefit of cooperation, the horizontal bias, and the correlation between cooperation and transmission (Result 2). Under a combination of vertical, oblique, and 274 horizontal transmission the dynamics are further complicated. We find again that under some conditions cooperation can evolve, and can even be maintained in a stable coexistence with defection 276 (Result 3).

This study was partially inspired by Lewin-Epstein et al. (2017). They hypothesised that microbes 278 that manipulate their hosts to act altruistically can be favored by selection, and may play a role in the widespread occurrence of cooperative behavior. Indeed, it has been shown that microbes can 280 mediate behavioral changes in their hosts (Dobson, 1988; Poulin, 2010). Therefore, natural selection on microbes may favor manipulation of the host so that it cooperates with others. Microbes can be 282 transmitted *horizontally* from one host to another during host interactions, and following horizontal transfer, the recipient host may carry microbes that are closely related to the microbes of the donor 284 host, even when the two hosts are (genetically) unrelated (Lewin-Epstein et al., 2017). Microbes can also be transferred vertically, from parent to offspring, and a microbe that induces its host to cooperate 286 with another host and thereby increases the latter's fitness will increase the vertical transmission of the microbes of the receiving individual. Kin selection among microbes could therefore favor microbes 288 that induce cooperative behavior in their hosts, thereby increasing the transmission of their microbial kin.

290 Eshel and Cavalli-Sforza (1982) have shown that with assortative meeting, i.e. probability  $m$  that individuals interact with within their phenotypic group, cooperation can evolve if  $c < b \cdot m$ . Our results 292 highlight another possibility for assortative meeting, in which individuals interact with probability  $\alpha$  with their cultural partners, i.e. during horizontal transmission. We show that high levels of assortative 294 meeting ( $\alpha$ ) significantly increase the potential for evolution of cooperation. With a high enough  $\alpha$ , cooperation can increase from rarity, although not fix, even when there is horizontal bias against 296 cooperation ( $\alpha > (c(1 - T_B) + (T_B - T_A))/bT_A$ , see Result 2)

Importantly, we demonstrate that cooperation can evolve even in a fully mixed population (i.e. in an un- 298 structured population), without repeating interactions or individual recognition. Our results highlight the potential importance of non-vertical cultural transmission for explaining complex evolutionary 300 phenomena, and significantly further our understating of the cultural evolution of cooperation.

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# 304 Appendices

## Appendix A

306 We want to find the frequency of juveniles with phenotype  $A$  in next generation  $\hat{p}'$  as a function of frequency of juveniles with phenotype  $A$  in the current generation  $\hat{p}$ . Starting from Equation 4,

$$308 \quad \hat{p}' = v\tilde{p}' + (1-v)p', \quad (\text{A1})$$

we substitute  $p'$  using Equation 6 and  $\tilde{p}'$  using Equation 9, we have

$$\begin{aligned} \hat{p}' = & \frac{v}{\bar{w}} \left\{ \hat{p}^2(1+b-c) [1 - (1-\hat{p})(1-\alpha)T_B] \right\} \\ & + \frac{v}{\bar{w}} \left\{ \hat{p}(1-\hat{p})(1-c) [\hat{p}(1-\alpha)T_B + 1 - T_B] \right\} \\ 310 \quad & + \frac{v}{\bar{w}} \left\{ \hat{p}(1-\hat{p})(1+b) [\hat{p}(1-\alpha) + \alpha] T_A \right\} \\ & + \frac{v}{\bar{w}} (1-\hat{p})^2 \hat{p}(1-\alpha)T_A \\ & + (1-v)\hat{p}^2(T_B - T_A) + (1-v)\hat{p}(1+T_A - T_B), \end{aligned} \quad (\text{A2})$$

where  $\bar{w} = 1 + \hat{p}(b-c)$ . We define  $f(\hat{p})$  as

$$312 \quad f(\hat{p}) = \bar{w}(\hat{p}' - \hat{p}) \quad (\text{A3})$$

Using *SymPy* (Meurer et al., 2017), a Python library for symbolic mathematics, we simplify Equation A3 to eqs. 31-32.

## Appendix B

316 Denote  $f(p) = \lambda(p' - p)$ , where  $\lambda > 0$ , and assume  $f(p^*) = 0$ . We want a condition for  $|p' - p^*| < |p - p^*|$ .

318 If  $p > p^* = 0$ , we want a condition for  $p' < p$ , or  $\frac{p'}{p} < 1$ , or  $\lambda \frac{p'-p}{p} < 0$ , or  $\frac{f(p)}{p} < 0$ . Using a linear approximation for  $f(p)$  near 0, we have

$$\begin{aligned} p' < p & \Leftrightarrow \\ 320 \quad \frac{f'(0) \cdot p + O(p^2)}{p} & < 0 \Leftrightarrow \\ & f'(0) + O(p) < 0. \end{aligned} \quad (\text{B1})$$

Therefore, by definition of big-O notation, if  $f'(0) < 0$  then there exists  $\epsilon > 0$  such that for any  $0 < p < \epsilon$  it is guaranteed that  $0 < p' < p$ , that is,  $p'$  is closer than  $p$  to zero.

If  $p < p^* = 1$ , we want a condition for  $1 - p' < 1 - p$ , or  $\frac{1-p'}{1-p} < 1$ , or  $\lambda \frac{-(p'-p)}{1-p} < 0$ , or  $-\frac{f(p)}{1-p} < 0$ .

324 Using a linear approximation for  $f(p)$  near 1, we have

$$\begin{aligned} 1 - p' < 1 - p & \Leftrightarrow \\ \frac{f'(1)(p-1) + O((p-1)^2)}{p-1} & < 0 \Leftrightarrow \\ & f'(1) - O(1-p) < 0. \end{aligned} \quad (\text{B2})$$

326 Therefore, if  $f'(1) < 0$  then there exists  $\epsilon > 0$  such that for any  $1 - \epsilon < 1 - p < 1$  it is guaranteed that  $1 - p' < 1 - p$ , that is,  $p'$  is closer than  $p$  to one.

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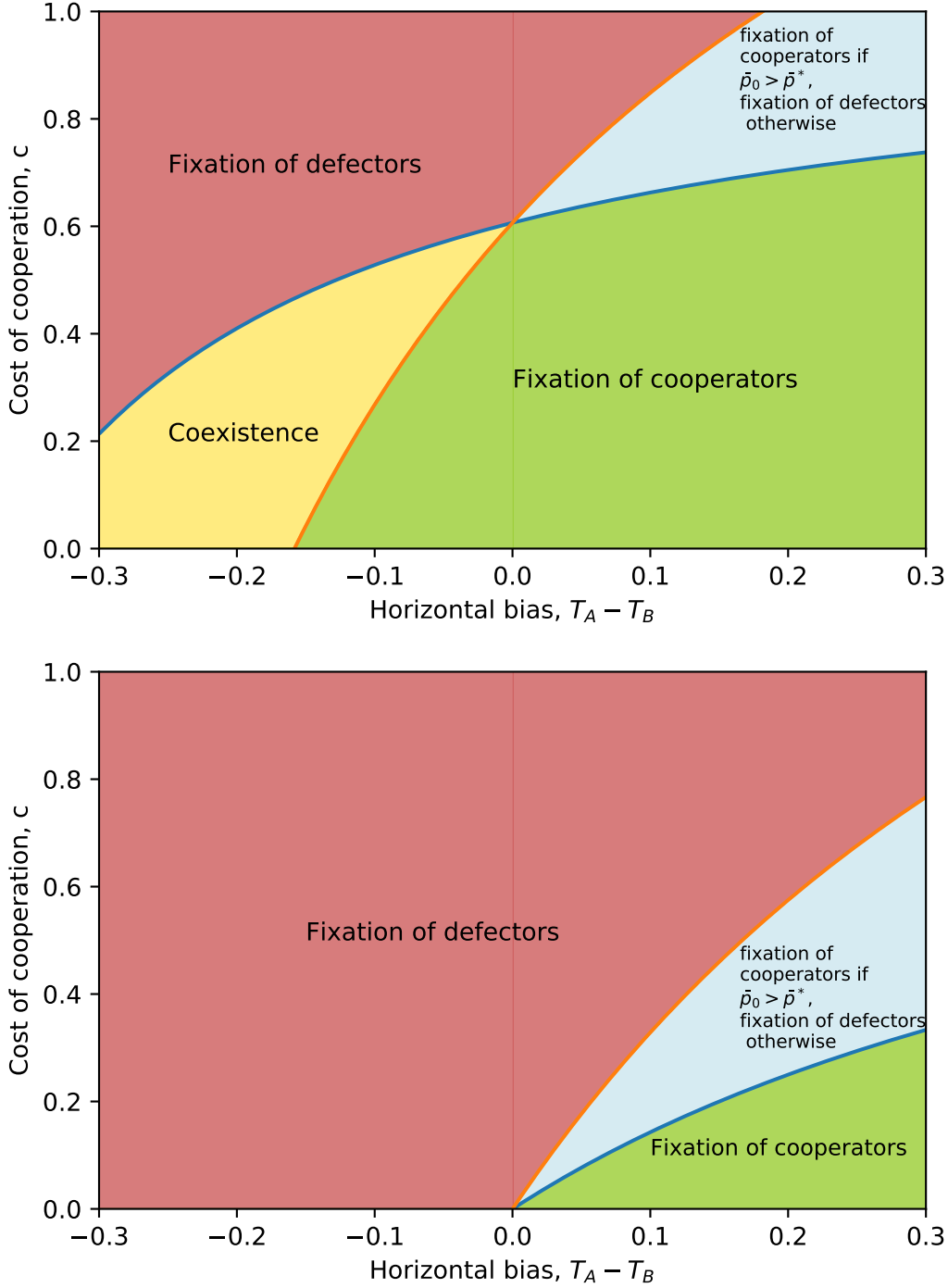


Figure 2: **Vertical and horizontal transmission.** The figure illustrates combinations of horizontal bias,  $T_A - T_B$ , and cost of cooperation,  $c$ , that lead to either global fixation of cooperation (green), global fixation of defection (red), fixation of either cooperation or defection depending on the initial frequencies (blue), or coexistence of cooperation and defection (yellow). The blue and orange curves show the cost boundaries  $\gamma_1$  and  $\gamma_2$  (Equation 24). Here, benefit of cooperation is  $b = 1.3$ , horizontal transmission of cooperation  $T_A = 0.4$ ,  $c$  and  $T_B$  vary on the y- and x-axes. **Up:** With  $\alpha = 0.7 > 0$ , coexistence is possible (yellow). **Down:** With  $\alpha = 0$ , coexistence is not possible.

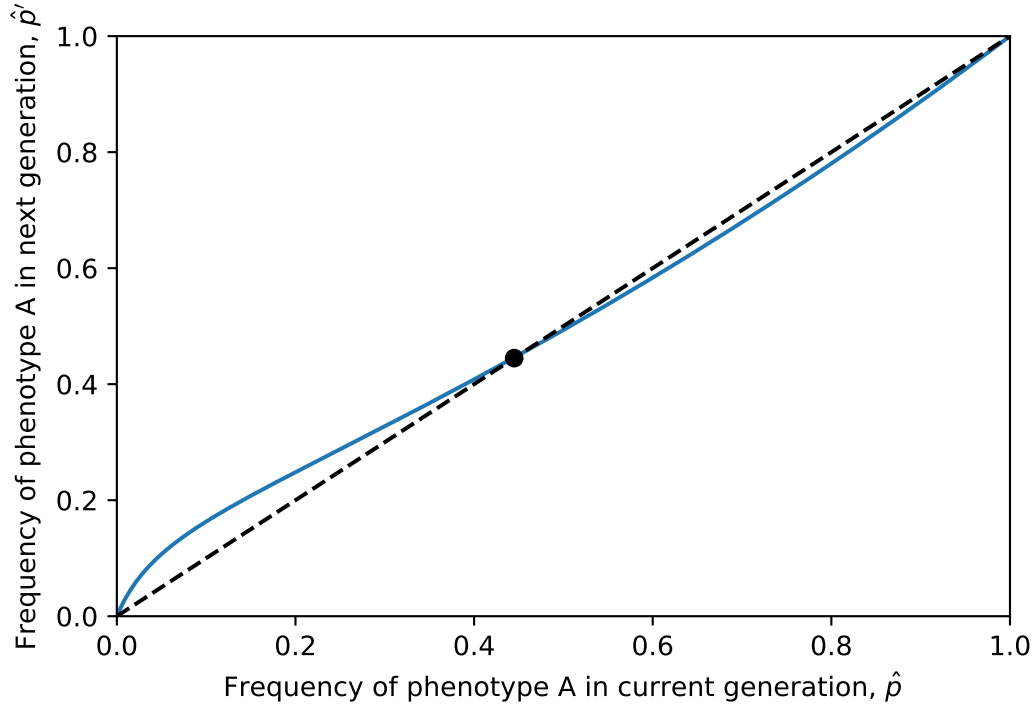


Figure 3: **Stable coexistence between cooperation and defection.** The frequency of the cooperative phenotype  $A$  among juveniles in the next generation  $\hat{p}'$  is plotted in blue as a function of the frequency in the current generation  $\hat{p}$  for  $T_A < T_B$  and  $\gamma_2 < c < \gamma_1$ . The line of  $\hat{p}' = \hat{p}$  is in dashed black. The curve and dashed line intersect at the equilibrium  $\hat{p}^*$ . The blue curve is above the black dashed line  $\hat{p} < \hat{p}^*$ , so that the frequency increases towards  $\hat{p}^*$ . The blue curve is below the black dashed line when  $\hat{p} > \hat{p}^*$ , so that the frequency decreases towards  $\hat{p}^*$ .

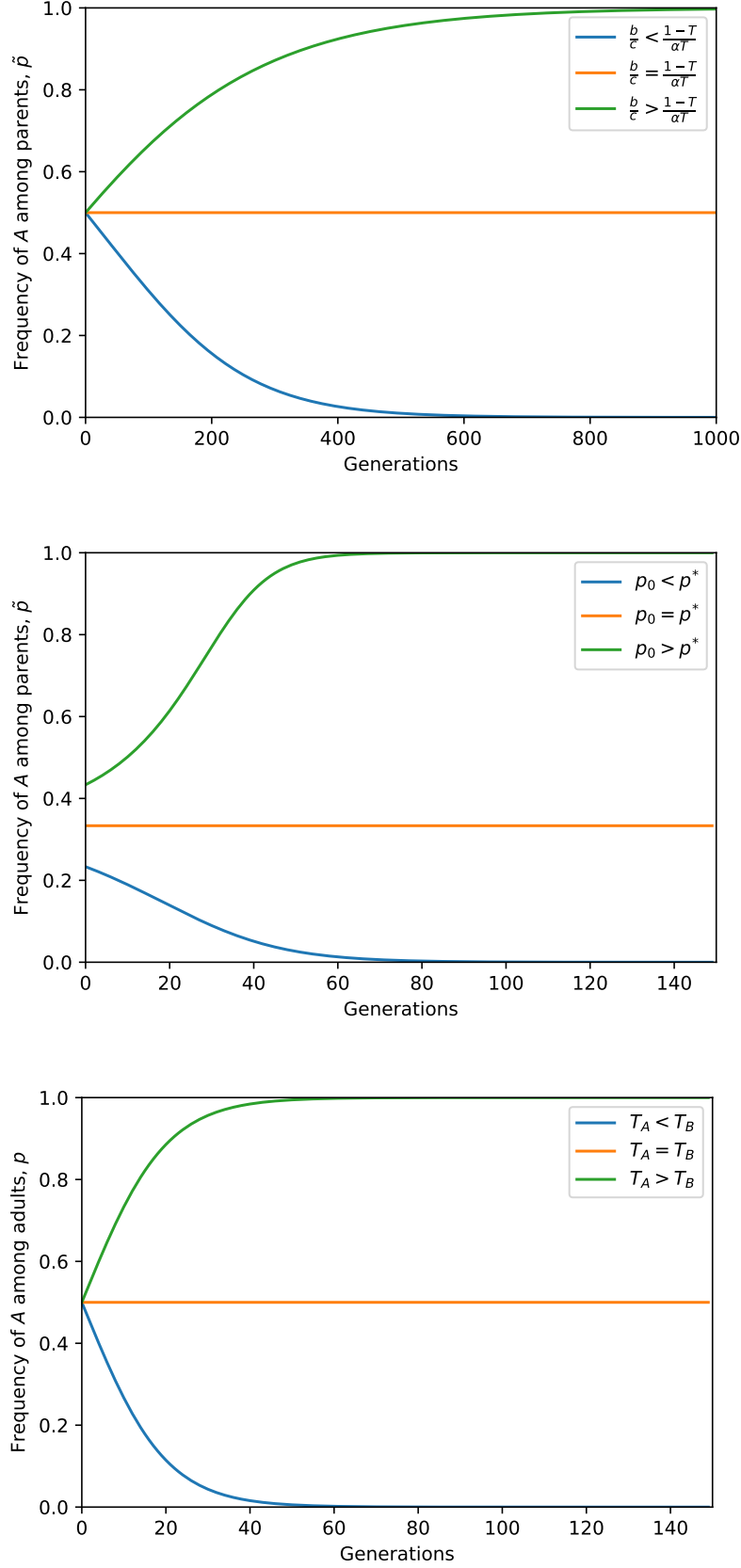


Figure 4: **Numerical results for cultural evolution of cooperation.** Shown are dynamics of (a-b)  $\tilde{p}$ , the frequency of parents with cooperative phenotype A; (c)  $p'$ , the frequency of adults with cooperative phenotype A. The figure demonstrates fixation of cooperation (green), extinction of cooperation (blue), and stable coexistence of cooperators and defectors (orange). Parameters: (a)  $v = 1, T_A = T_B = T, \alpha \neq 0$ ; (b)  $v = 1, \alpha = 0$ ; (c)  $v = 0$ .