# Evolution with Positive Feedback between Phenotype and Inheritance

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#### Abstract

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## 1 Model

## 1.1 Wright-Fisher model

We model evolution of a constant, finite size population with non-overlapping generations using a Wright-Fisher model with natural selection, inheritance, and random genetic drift. This model is based on the simulation description in the final paragraph of the  $Materials\ \mathcal{E}\ Methods$  section of Xue and Leibler (2016). Indeed, a simulation based on this model (https://github.com/yoavram/Milpitas) allowed us to reproduce Figure 2 of Xue and Leibler (2016) (Fig. 1).

## 1.1.1 Definitions

• N: constant population size.

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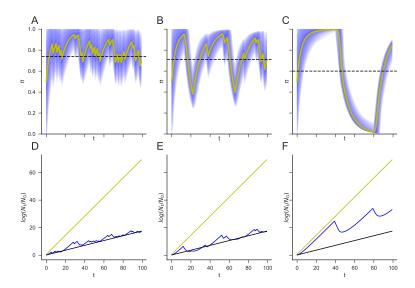


Figure 1: Reproduction of Figure 2 from Xue and Leibler (2016). **A-C**: the average  $\pi$  in the population over time and the distribution in blue; **D-F**: the effective population growth rate. **A,D**: the environment is randomly chosen at each generation such that P(A)=0.7 and P(B)=0.3; **B,E**: the environment flips between A and B, the duration of each is geometrically distributed with p=1/10 for A and p=1/5 for B; **C,F**: the environments flips every 40 generations. Parameters: N=100,000, # generations = 100,  $\eta=0.1$ , W=2, w=0.2.

- $\phi_i$ : phenotype of individual  $i, 1 \le i \le N, \phi_i \in \{A, B\}$ .
- $\epsilon_t$ : the environment at generation  $t, \epsilon_t \in \{A, B\}$ .
- W: individual fitness when phenotype and environment match,  $\phi_i = \epsilon_t$ .
- w: individual fitness when phenotype and environment do not match,  $\phi_i \neq \epsilon_t$ .
- $\omega_i$ : fitness of individual *i* at time *t*,  $\omega_i = W \cdot 1_{\phi_i = \epsilon_t} + w \cdot 1_{\phi_i \neq \epsilon_t}$ .
- $\bar{\omega}$ : population mean fitness.
- $\pi_i$ : phenotype probability, the probability that individual i becomes phenotype  $A, 1 \le i \le N$ .
- $\Pi$ : set of phenotype probabilities in the population,  $\Pi = {\pi_i}_{1 \le i \le N}$
- $\eta$ : phenotypic inheritance rate,  $0 \le \eta \le 1$ .

### 1.1.2 Reproduction

For each offspring in the population of generation t+1 we choose a parent from the population of generation t and this choice depends on the parent relative fitness: the probability that individual i is the parent is relative to its fitness,  $\omega_i$ . Therefore, reproduction is modeled by a multinomial distribution. Therefore, reproduction includes the effects of natural selection and random genetic drift.

#### 1.1.3 Inheritance

The offspring inherits the phenotype probability of the parent with a modification – if the parent became A, then the offspring is even more likely to be A; if the parent was B, then the offspring is less likely to be A. Specifically, for parent k and offspring i:

$$\pi_i = \pi_k \cdot (1 - \eta) + \eta \cdot 1_{\phi_k = A} \tag{1}$$

#### 1.1.3.1 Note

The notation in Eq. 1 is different from Eq. 1 in Xue and Leibler (2016), as i denotes individual, rather than phenotype. But the process is the same.

#### 1.1.3.2 Note

The expected difference between parent and offspring phenotype probability is  $E[\pi_i - \pi_k | \pi_k] = 0$ .

## 1.1.4 Iteration

At each generation t,  $\Pi$  is updated according to the following steps. Initial values can be determined (*i.e.*,  $\forall i$ ,  $\pi_i = 0.5$ ), or values can be drawn from an initial

distribution (i.e.,  $\pi_i \sim TN(0.5, 0.05)$ , TN is the truncated normal distribution). In addition, the sequence  $\epsilon_t$  is independent of the iteration on Pi.

At each generation t:

- 1. **Development**: the phenotypes of all individuals are drawn from corresponding Bernoulli distributions depending on their phenotype probabilities:  $P(\phi_i = A) = \pi_i$ .
- 2. **Fitness**: the fitness of all individuals is set:  $\omega_i = W \cdot 1_{\phi_i = \epsilon_t} + w \cdot 1_{\phi_i \neq \epsilon_t}$ .
- 3. **Reproduction**: the number of offspring of each individual,  $b_i$ , is drawn from a multinomial distribution  $MN(N, \{\frac{\omega_i}{\sum_i \omega_i}\}_{1 \leq i \leq N})$ , such that

$$P(b_1 = x_1, \dots, b_N = x_N) = \frac{N!}{x_1! \cdot \dots \cdot x_N!} \cdot \left(\frac{\omega_1}{\sum_i \omega_i}\right)^{x_1} \cdot \dots \cdot \left(\frac{\omega_N}{\sum_i \omega_i}\right)^{x_N}$$

4. **Inheritance**: the set of phenotype probabilities of the offspring generation is updated using Eq. 1 such that for each i,  $\Pi$  includes exactly  $b_i$  copies of  $(\pi_i \cdot (1 - \eta) + \eta \cdot 1_{\phi_i = A})$ .

#### 1.1.4.1 Note

Only development and reproduction are stochastic; natural selection and drift occur at the reproduction step.

#### 1.1.4.2 Note

If  $\eta = 0$ ,  $\pi_i \in \{0, 1\}$ , and  $\epsilon_t \equiv A$ , then we have a standard single locus bi-allelic selection-drift Wright-Fisher model.

## 1.2 Recurrence equation

We approximate the Wright-Fisher model using a recurrence equation. This approximation is most suitable when the population is composed of a single lineage – for example, when selection is extreme and there is a common ancestor.

Define x to be the probability that a random individual in the population is A. What is x, the probability that a random offspring of that individual is A?

Assuming an "infinite" population undergoing exponential growth, this depends on (i) if the parent was A or B, with probabilities x and 1-x, (ii) on the relative contribution of A and B phenotypes to the next generation in terms of fitness, and (iii) on the probability that offspring of A or B phenotypes eventually become A, according to the inheritance process (Eq. 1):

$$x' = x \cdot \frac{\omega_A}{\bar{\omega}} \cdot ((1 - \eta)x + \eta) + (1 - x) \cdot \frac{\omega_B}{\bar{\omega}} \cdot (1 - \eta)x$$

Where  $\omega_A$  and  $\omega_B$  are the fitness of phenotypes A and B in the current generation (depending on  $\epsilon_t$ ).

When we write a similar recurrence for the probability that an individual is B ((1-x)' = F(1-x)) and sum the two equations, we find that  $\bar{\omega} = x\omega_A + (1-x)\omega_B$  is the mean fitness.

This recurrence equation can be reorganized to:

$$x' = x \frac{x(1-\eta)(\omega_A - \omega_B) + \eta\omega_A + (1-\eta)\omega_B}{x(\omega_A - \omega_B) + \omega_B}$$
 (2)

## 2 Results

To be continued...

## References

Xue, B., and S. Leibler. 2016. Evolutionary learning of adaptation to varying environments through a transgenerational feedback. Proceedings of the National Academy of Sciences 201608756.