

```
In [1]: #Project => face Reconnition.... by (YOGESH BAGHEL)
#Python script to capture images from web cam video streame...
#Face Reconnize to store in array When the same face reconnize it's give
# the name of person"
```

```
In [2]: #===== (Require Modules are..) =====
#opencv => To recognize from image, web cam, video etc
#numpy => array to store the face data"
```

```
In [9]: #STEP-1 => Read and show video streame and capture images.....

import cv2
import numpy as np

#intialise the camera
cap = cv2.VideoCapture(0)

#Face Detection
face_cascade = cv2.CascadeClassifier("haarcascade_frontalface_alt.xml")

#CascadeClasifier method in cv2 module support the loading haar cascade file.
#Haar Cascade is a machine learning-based approach where a lot of positive and negative images are
#used to train the classifier. \n",
# => its capture the face image, and inside eye's images and mouth's images..
```

```
[ WARN:0@0.145] global /io/opencv/modules/videoio/src/cap_v4l.cpp (889) open VIDE0I0(V4L2:/dev/video0): can't open camera by index
```

```
In [ ]: #===== Step-3 => Flatten the largest face and store in numpy
array..=====
```

```
#Create an empty list to store the coordinate of face...
```

```
face_data = []
```

```
#store that list at location.
```

```
data_path = "/Desktop/"
```

```
filename = input("Enter your name who scann the face =")
```

```
skip=0
```

```
while True:
```

```
#Read information from webcam
```

```
    ret,frame = cap.read()
```

```
#Due to any reasn web cannot be capture the images i.e\n
```

```
    if ret==False:
```

```
        continue
```

```
#STEP=2 => Detect face and Show Boundary Box (haarcascade)..
```

```
    #===== (Step-2) =====
```

```
    faces = face_cascade.detectMultiScale(frame,1.3,5)
```

```
    #===== (Step-3) =====
```

```
# now, convert image into grayscale....
```

```
    #WHY => Because Our image has RGB has three different layer and gray has one layer  
    #      from 0-255, its recognize each pixel very well...
```

```
gray_frame = cv2.cvtColor(frame,cv2.COLOR_BGR2GRAY)
```

```
    # if multiple faces are occur then you find largest face => {area of Rectangle} => sorted the  
width and height
```

```
    # on the bases of area....
```

```
faces = sorted(faces, key=lambda f: f[2] * f[3], reverse=True)
```

```
#                                     index->    [0,1,2,3]
```

```
# pick the last face (because its larger face of area [x,y,w,h] => f[2] * f[3] => (w*h) area
```

```
for face in faces:
```

```
    x,y,w,h=face
```

```
    cv2.rectangle(frame, (x,y), (x+w,y+h), (0,255,255), 2)
```

```
#now, Create a new window to display only face => need to extract crop the face images
```

```
    offset = 10
```

```
    face_section = frame[y-offset:y+h+offset, x-offset:x+w+offset]
```

```
    face_section = cv2.resize(face_section, (100,100))
```

```
    skip+=1
```

```
    if skip%10==0:
```

```
        face_data.append(face_section)
```

```
        print(len(face_data))
```

```
cv2.imshow("Frame", frame)
cv2.imshow("Face section",face_section)
```

```
#===== (Step-4) =====
```

```
face_data = np.asarray(face_data)
face_data = face_data.reshape((face_data.shape[0],-1))
print(face_data.shape)
```

```
#save this array data in at location
```

```
np.save(data_path+filename+'.numpy',face_data)
```

```
print("Data Successfully save at"+data_path+filename+'.numpy')
```

```
# if person enter => A then => Desktop/A.npy
```

```
# if person enter => B then => Desktop/B.npy
```

```
# if person enter => C then => Desktop/C.npy
```

```
#detectMultiScale() => Detect object of difrent sizes in input images.eturn a list of position  
#of rectangle on the face...
```

```
# (x,y,w,h)
```

```
# -----
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```
# | |
```

```
# | | => Its has (x,y) coordinate for rectangle and width and height.
```

```
# | | => in rectangle inside the face which size detect by detectMultiScale()..
```

```
# | | => Ex= face1 ->(10,20,30,40) and face2 -> (20,50,30,40)
```

```
# | |
```

```
# -----
```

```

# print(faces)

# #Store every 10th face..
# if(skip%10==0):
#     pass

# for face in faces:
#     x,y,w,h=face
#     cv2.rectangle(frame, (x,y), (x+w,y+h), (0,255,255), 2)

cv2.imshow("Frame", frame)
#imshow() => used to add image in window..Itself adjust to size of images

#=====(Step-2) complete=====

#when the user press 'q' key then, break the program
key_press = cv2.waitKey(1) & 0xFF
if key_press==ord('q'):
    break

#ord('q') => return the Unicode code point of 'q'
#cv2.waitKey(1) => return the 32-bits integer corresponding to the user press key
# & 0xFF => is bit mask which sets the 24-bits to zero (its use to check corresponding key)

cap.release()
cv2.destroyAllWindows()

#=====STEP-1
COMPLETE=====

```

In [ ]: # Completed the Backend work.....