

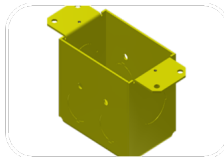
USE OF NEURAL NETWORKS FOR GEOMETRIC PROBLEMS

Yogesh Haribhau Kulkarni

Introduction To Midcurve



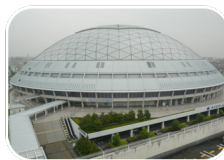
Aerospace



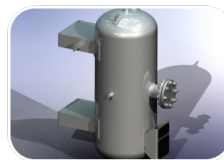
Machinery

Consumer
Products

Energy

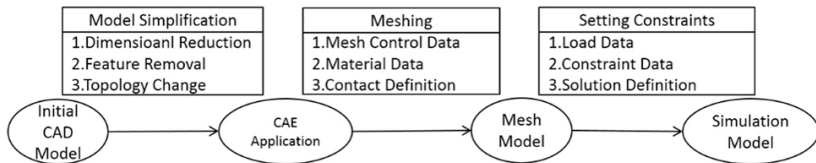


Construction

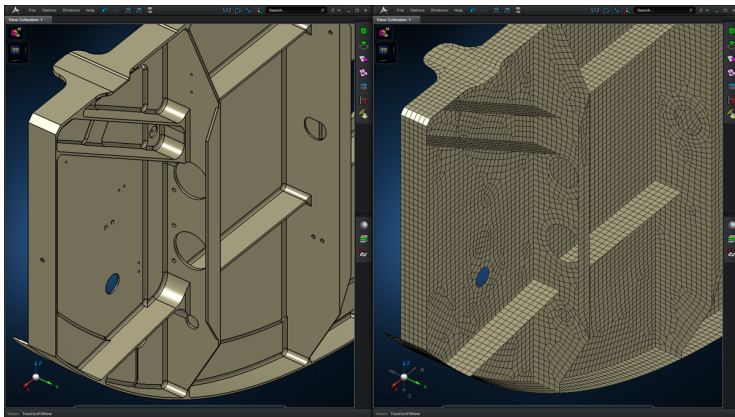
Industrial
equipment

Can we use shapes directly?

- ▶ CAD : Designing Shapes
- ▶ CAE : Engineering Analysis
- ▶ CAD→CAE: Simplification for quicker results.



CAD-CAE

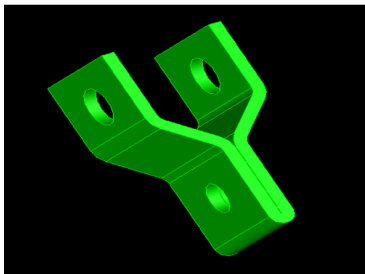


For Shapes like Sheet Metal ...

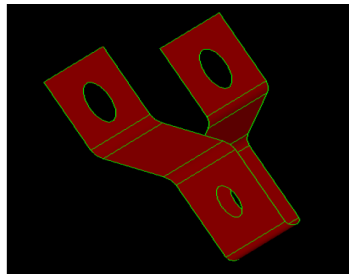
	Solid mesh	Shell+Solid mesh	Difference (%)
Element number	344,330	143,063	-58%
Node Number	694,516	75,941	-89%
Total Degrees of freedom	2,083,548	455,646	-78%
Maximum Von. Mises Stress	418.4 MPa	430 MPa	+3%
Meshing + Solving time	Out of memory	22 mins	N/A (4G RAM)
Meshing + Solving time	30 mins	17 mins	-43% (12G RAM)

Half the computation time, but similar accuracy

Midsurface is?



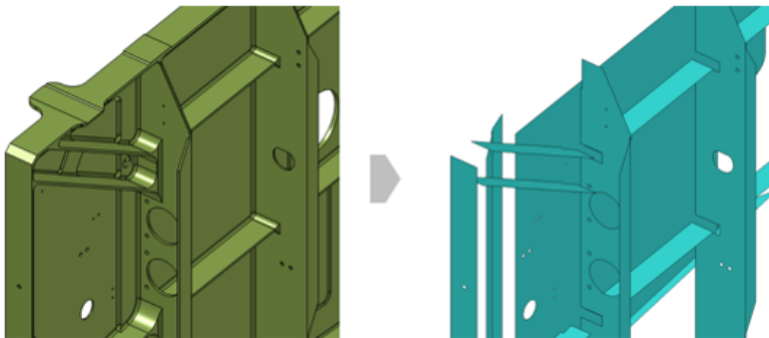
Input: Solid



Output: Midsurface

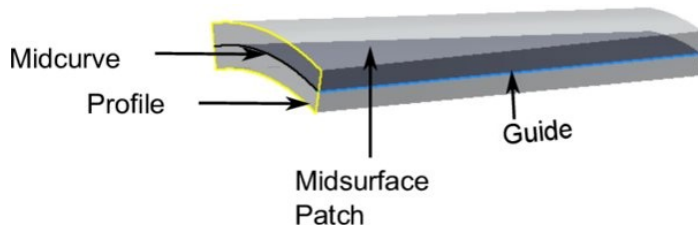
- ▶ Widely used for CAE of Thin-Walled parts
- ▶ Computation is challenging and still unsolved

Look at the output



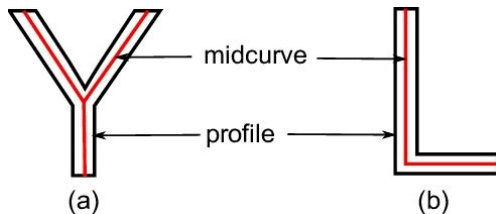
Midsurface Computation

- Midsurface of a Patch is Midcurve of its profile extruded.
- So, it boils down to computing 1D midcurve of a 2D profile



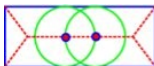
What is a Midcurve?

- Midsurface : From 3D thin Solid to 2D Surface
- Midcurve : From 2D Profile to 1D Curve

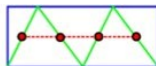


Many Approaches

- ▶ More than 6 decades of research. . .
- ▶ Most CAD-CAE packages. . .
- ▶ Rule-based!! Heuristic!! Case-by-case basis!!



MAT



CAT

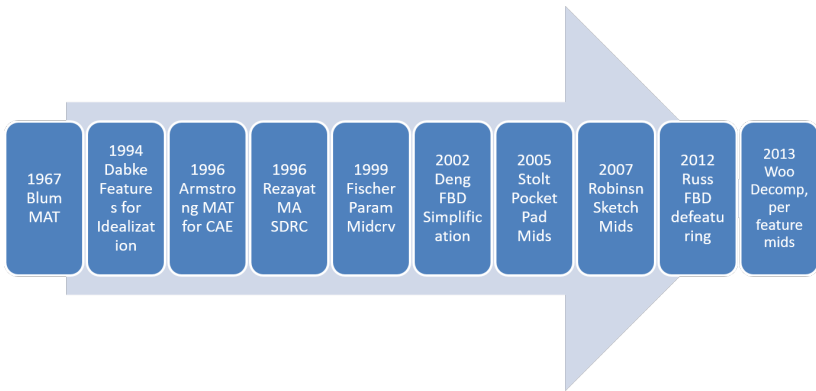


Thinning

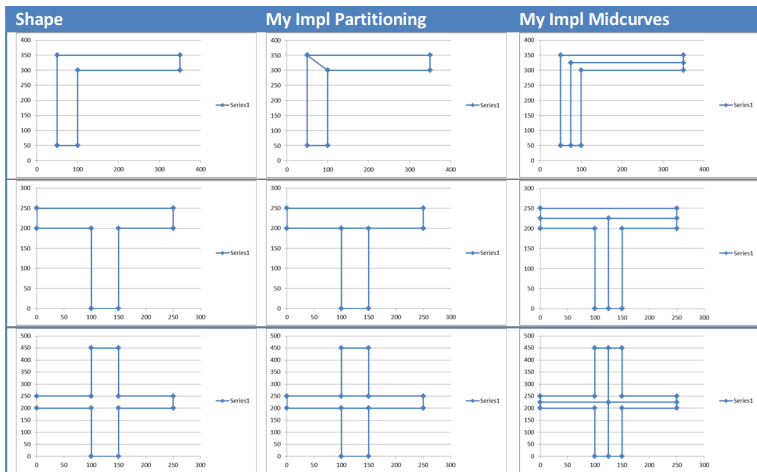


Pairs

When-What?



2017: My PhD Work: Rule-based



Limitations

- ▶ Fully rule-based
- ▶ Need to adjust for new shapes
- ▶ So, not scalable



Midcurve : The Problem

- ▶ **Goal:** Given a 2D closed shape (closed polygon) find its midcurve (polyline, closed or open)
- ▶ **Input:** set of points or set of connected lines, non-intersecting, simple, convex, closed polygon
- ▶ **Output:** another set of points or set of connected lines, open/branched polygons possible

Midcurve : Graph 2 Graph

- ▶ **Input:** Graph of Input profile with vertices at nodes and lines/curves as edges
- ▶ **Output:** another Graph of Output profile with vertices at nodes and lines/curves as edges, open/branched polygons possible
- ▶ Both, input and output shapes have different topologies (number of nodes and edges are different) but geometry also, nodes and edges have different positions and shapes. So its network 2 network problem.
- ▶ Existing Graph algorithms like node prediction and link prediction are not useful here as, there, topology of input and output is more or less similar.
- ▶ Graph to Graph translation does not seem to evolved enough to do the expected transformation.

Any ideas?

Variable Size Encoder Decoder

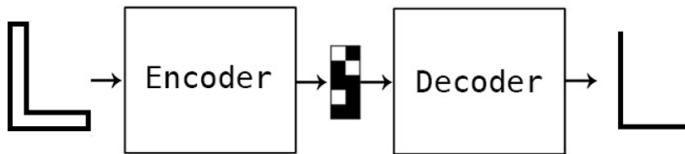
- ▶ OK for NLP, say Machine Translations, where padding values like “-1” can be added along with other words (vectors or indices)
- ▶ But in Geometry, its not OK.
- ▶ Because any value can represent a Valid Input, even though we don't want it to be the input.

A Twist to the problem

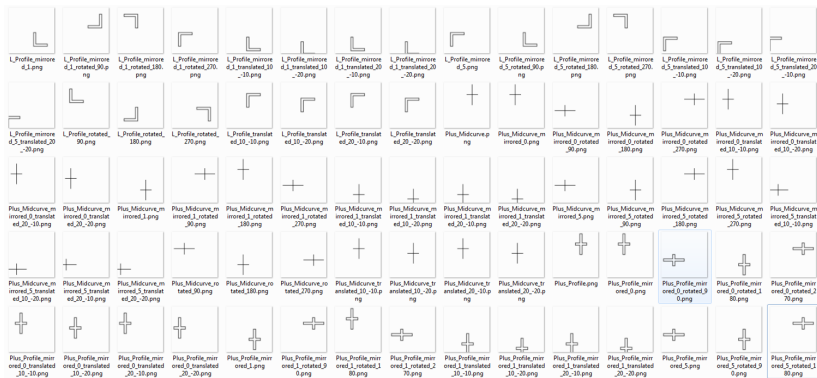
- ▶ Input: Black & White Image of 2D profile
- ▶ Output: Black & White Image of 1D midcurve



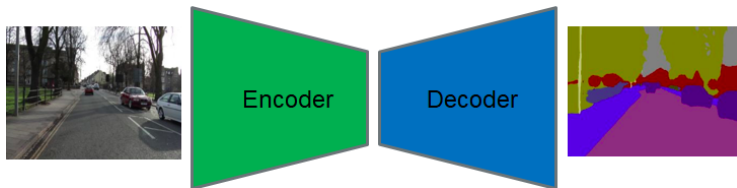
For Dimension Reduction



Training Data Samples



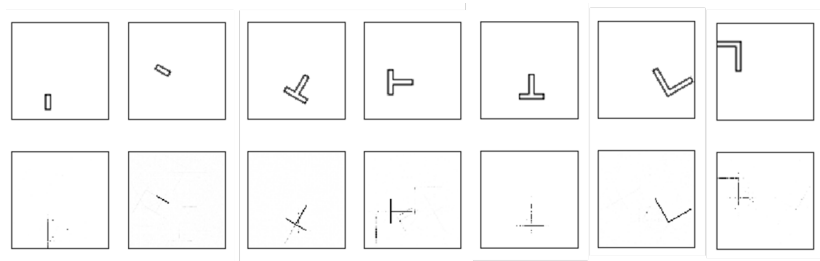
Simple Encoder Decoder



Keras Implementation

```
1 input_img = Input(shape=(input_dim,))
3 encoded = Dense(encoding_dim,
    activation='relu', activity_regularizer=regularizers.l1(10e-5))(input_img)
    decoded = Dense(input_dim, activation='sigmoid')(encoded)
5
    autoencoder = Model(input_img, decoded)
7
    encoder = Model(input_img, encoded)
9    encoded_input = Input(shape=(encoding_dim,))
    decoder_layer = autoencoder.layers[-1]
11    decoder = Model(encoded_input, decoder_layer(encoded_input))
13
    autoencoder.compile(optimizer='adadelta', loss='binary_crossentropy')
```

Results



Idea



Can Large Language Models “learn” the dimension reduction transformation?

2D Brep Representation

Leverage a geometry representation similar to that found in 3D B-rep (Boundary representation), but in 2D. It can be shown as:

```
1 {  
  'ShapeName': 'I',  
  'Profile': [(5.0, 5.0), (10.0, 5.0), (10.0, 20.0), (5.0, 20.0)],  
  'Midcurve': [(7.5, 5.0), (7.5, 20.0)],  
  'Profile_brep': {  
    'Points': [(5.0, 5.0), (10.0, 5.0), (10.0, 20.0), (5.0, 20.0)], # list of  
      (x,y) coordinates  
    'Lines': [[0, 1], [1, 2], [2, 3], [3, 0]], # list of point ids (ie index  
      in the Points list)  
    'Segments': [[0, 1, 2, 3]] # list of line ids (ie index in  
      Lines list)  
  },  
  'Midcurve_brep': {  
    'Points': [(7.5, 5.0), (7.5, 20.0)],  
    'Lines': [[0, 1]],  
    'Segments': [[0]]  
  },  
}
```

Data

ShapeName	Profile	Midcurve	Profile_brep	Midcurve_brep
I	[[[5.0, 5.0], [10.0, 5.0], [10.0, 20.0], [5.0, 20.0]]]	[[[7.5, 5.0], [7.5, 20.0]]]	["Points": [[[5.0, 5.0], [10.0, 5.0], [10.0, 20.0], [5.0, 20.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 0]], "Segments": [[0, 1, 2, 3]]]	["Points": [[[7.5, 5.0], [7.5, 20.0]], "Lines": [[0, 1]], "Segments": [[0]]]
L	[[[5.0, 5.0], [10.0, 5.0], [10.0, 30.0], [15.0, 30.0], [15.0, 35.0], [5.0, 35.0]]]	[[[7.5, 5.0], [7.5, 32.5], [15.0, 32.5]]]	["Points": [[[5.0, 5.0], [10.0, 5.0], [10.0, 30.0], [15.0, 30.0], [15.0, 35.0], [5.0, 35.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 4], [4, 5], [5, 0]], "Segments": [[0, 1, 2, 3, 4, 5]]]	["Points": [[[7.5, 5.0], [7.5, 32.5], [15.0, 32.5]], "Lines": [[0, 1], [1, 2]], "Segments": [[0, 1]]]
Plus	[[[0.0, 25.0], [10.0, 25.0], [10.0, 45.0], [15.0, 45.0], [15.0, 25.0], [25.0, 25.0], [25.0, 20.0], [15.0, 20.0], [15.0, 0.0], [10.0, 0.0], [10.0, 20.0], [0.0, 20.0]]]	[[[12.5, 0.0], [12.5, 22.5], [12.5, 45.0], [0.0, 22.5], [25.0, 22.5]]]	["Points": [[[0.0, 25.0], [10.0, 25.0], [10.0, 45.0], [15.0, 45.0], [15.0, 25.0], [25.0, 25.0], [25.0, 20.0], [15.0, 20.0], [15.0, 0.0], [10.0, 0.0], [10.0, 20.0], [0.0, 20.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 4], [4, 5], [5, 6], [6, 7], [7, 8], [8, 9], [9, 10], [10, 11], [11, 0]], "Segments": [[0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11]]]	["Points": [[[12.5, 0.0], [12.5, 22.5], [12.5, 45.0], [0.0, 22.5], [25.0, 22.5]], "Lines": [[0, 1], [4, 1], [2, 1], [3, 1]], "Segments": [[0], [1], [2], [3]]]
T	[[[0.0, 25.0], [25.0, 25.0], [25.0, 20.0], [15.0, 20.0], [15.0, 0.0], [10.0, 0.0], [10.0, 20.0], [0.0, 20.0]]]	[[[12.5, 0.0], [12.5, 22.5], [25.0, 22.5], [0.0, 22.5]]]	["Points": [[[0.0, 25.0], [25.0, 25.0], [25.0, 20.0], [15.0, 20.0], [15.0, 0.0], [10.0, 0.0], [10.0, 20.0], [0.0, 20.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 4], [4, 5], [5, 6], [6, 7], [7, 0]], "Segments": [[0, 1, 2, 3, 4, 5, 6, 7]]]	["Points": [[[12.5, 0.0], [12.5, 22.5], [25.0, 22.5], [0.0, 22.5]], "Lines": [[0, 1], [1, 2], [3, 1]], "Segments": [[0], [1], [2]]]
I_scaled_2	[[[10.0, 10.0], [20.0, 10.0], [20.0, 40.0], [10.0, 40.0]]]	[[[15.0, 10.0], [15.0, 40.0]]]	["Points": [[[10.0, 10.0], [20.0, 10.0], [20.0, 40.0], [10.0, 40.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 0]], "Segments": [[0, 1, 2, 3]]]	["Points": [[[15.0, 10.0], [15.0, 40.0]], "Lines": [[0, 1]], "Segments": [[0]]]
L_scaled_2	[[[10.0, 10.0], [20.0, 10.0], [20.0, 60.0], [70.0, 60.0], [70.0, 70.0], [10.0, 70.0]]]	[[[15.0, 10.0], [15.0, 65.0], [70.0, 65.0]]]	["Points": [[[10.0, 10.0], [20.0, 10.0], [20.0, 60.0], [70.0, 60.0], [70.0, 70.0], [10.0, 70.0]], "Lines": [[0, 1], [1, 2], [2, 3], [3, 4], [4, 5], [5, 0]], "Segments": [[0, 1, 2, 3, 4, 5]]]	["Points": [[[15.0, 10.0], [15.0, 65.0], [70.0, 65.0]], "Lines": [[0, 1], [1, 2]], "Segments": [[0, 1]]]

Few Shots Prompt

```
1 You are a geometric transformation program that transforms input 2D polygonal
  profile to output 1D polyline profile. Input 2D polygonal profile is
  defined by set of connected lines with the format as: ...

3 Below are some example transformations, specified as pairs of 'input' and the
  corresponding 'output'. After learning from these examples, predict the
  'output' of the last 'input' specified.
  Do not write code or explain the logic but just give the list of lines with
  point coordinates as specified for the 'output' format.

5 input:[((5.0,5.0), (10.0,5.0)), ... ((5.0,35.0), (5.0,5.0))]
7 output: [((7.5,5.0), (7.5, 32.5)), ... ((35.0, 32.5) (7.5, 32.5))]

9 input: [((5,5), (10, 5)), ... (5, 20)), ((5, 20),(5,5))]
  output: [((7.5, 5), (7.5, 20))]

11 :
13 input:[((0, 25.0), (25.0,25.0)),... ((0,20.0),(0, 25.0))]
  output:
```

Output

And the outputs computed by various LLMs (ChatGPT, Perplexity AI, Bard) , along with the real/actual answer:

```
Actual: [((12.5,0), (12.5,22.5)), ((12.5,22.5),(25.0,22.5)),  
         ((12.5,22.5),(0,22.5))]  
2 ChatGPT: [((2.5, 0), (2.5, 22.5)), ((2.5, 22.5), (2.5, 45.0)), ((2.5, 22.5),  
            (25.0, 22.5)), ((2.5, 22.5), (12.5, 22.5)), ((2.5, 22.5), (0, 22.5)),  
            ((2.5, 22.5), (25.0, 22.5))]  
Perplexity: [((12.5,0), (12.5, 22.5)), ((12.5, 22.5),(12.5,45.0)), ((12.5,  
            22.5), (0,22.5)), ((12.5, 22.5), (25.0,22.5))]  
4 Bard: [((12.5, 0), (12.5, 25.0)), ((12.5, 25.0), (25.0, 25.0)), ((25.0, 25.0),  
         (25.0, 0))]
```

Output

Visually here is how results from different LLMs look:

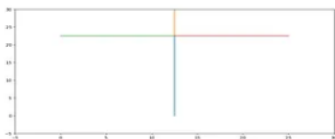
Actual/Expected



ChatGPT



Perplexity AI



Bard



References

- ▶ Kulkarni, Y. H.; Deshpande, S. Medial Object Extraction - A State of the Art In International Conference on Advances in Mechanical Engineering, SVNIT, Surat, 2010.
- ▶ Kulkarni, Y. H.; Sahasrabudhe, A.D.; Kale, M.S Dimension-reduction technique for polygons In International Journal of Computer Aided Engineering and Technology, Vol. 9, No. 1, 2017.
- ▶ Chollet, F. Building Autoencoders in Keras In <https://blog.keras.io/building-autoencoders-in-keras.html> , 2019.
- ▶ Video: <https://www.youtube.com/embed/ZY0nuykqgoE?feature=oembed>
- ▶ Presentation: https://drive.google.com/file/d/1Tx5JJk1_LUfIMTW-B43HNN2GDMKJMOxR/preview
- ▶ Short paper: <https://vixra.org/abs/1904.0429>
- ▶ Github repo, source code: <https://github.com/yogeshhk/MidcurveNN>

Thanks ...

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(<https://www.linkedin.com/in/yogeshkulkarni/>, QR by Hugging Face

QR-code-AI-art-generator, with prompt as "Follow me")

