



**VI Semester B.E. (E&E) Degree Examination, December 2016
(2K11 Scheme)**

EE – 603 : ELECTRIC DRIVES

Time : 3 Hours

Max. Marks : 100

Instruction : Answer any five full questions choosing atleast two from each Part.

PART – A

1. a) Explain the speed torque conventions and four quadrant operation of a motor driving a hoist load. **10**
b) A drive has the following parameters : $T = 150 - 0.1 N$, N-m where N is the speed in rpm. Load torque $T_L = 100$ N-m. Initially the drive is operating in steady state. The characteristics of the load torque are changed to $T_L = -100$ N-m. Calculate initial and final equilibrium speed. **10**
2. a) Describe the operation of single phase fully controlled rectifier control of DC separately excited motor. **10**
b) A 440 V, 3 phase, 50 Hz, 6 pole, 945 rpm, delta connected I.M. has following parameters referred to the stator.
 $R_s = 2.0 \Omega$, $R_r' = 2.0 \Omega$, $X_s = 3 \Omega$, $X_r' = 4 \Omega$
When driving a fan load at rated voltage it runs at rated speed. The motor speed is controlled by stator voltage control. Calculate :
i) Motor terminal voltage, current and torque at 800 rpm.
ii) Motor speed, current and torque for the terminal voltage of 280 V. **10**
3. a) With a neat block diagram explain closed loop system of a multimotor drives. **10**
b) A 4 pole, 10 HP, 460 V, motor is supplying its rated power to a centrifugal load at a 60 Hz frequency. Its rated speed is 1746 rpm calculate its speed, slip frequency and slip when it is supplied by a 230 V, 30 Hz source. **10**
4. a) Explain the operation of variable frequency control from voltage source. **10**
b) Describe the speed control of 3ϕ Induction motor by static rotor resistance control. **10**



PART – B

5. a) Explain in detail BLDC drives for servo applications and mention its advantages. 10
- b) Describe the operation of a variable reluctance stepper motor. What is micro-stepping ? 10
6. a) Write a short notes on : (5+5)
- a) Permanent Magnet Synchronous Machine.
- b) Current source inverter fed S.M.
- b) Describe the principle of operation of a switched reluctance motor. What are the difference b/w this motor and synchronous reluctance motor ? 10
7. a) Develop an expression for the temperature rise in case of motors. Draw heating and cooling curves. 10
- b) On the basis of heating select a suitable motor for the following intermitted duty.
- 1) $P_1 = 35 \text{ Kw}$ for $t_1 = 3 \text{ Sec}$. $P_2 = 17 \text{ Kw}$ for $t_2 = 20 \text{ Sec}$
- 2) $P_3 = 35 \text{ kw}$ for $t_3 = 2 \text{ Sec}$. $P_4 = 13 \text{ kw}$ for $t_4 = 15 \text{ Sec}$.
- Between the operating periods 1) and 2) above, there is a rest period of 37 sec. and at the end of the cycle there is another rest period of 40 sec. plot the load curve. 10
8. a) With a neat sketch, explain paper mill drive system. 10
- b) Draw and explain schematic diagram of various stages in the reversing hot rolling mills. 10
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