



**VII Semester B.E. (E&E) Degree Examination, December 2014/January 2015
(2K6 Scheme)
(2K6EE704) : DIGITAL SIGNAL PROCESSING**

Time : 3 Hours

Max. Marks : 100

Instruction : Answer *any five full* questions.

1. a) State and prove the following properties of DFT
 - i) Convolution in Time Domain
 - ii) Circular Frequency shift. 10
- b) Compute N point DFT of the sequences
 - i) $x(n) = a^n$ $0 \leq n \leq N - 1$
 - ii) $x(n) = 1$ for n even 10
 $= 0$ for n odd
2. a) Obtain Linear convolution of the following sequences using overlap add and overlap save method with $N = 6$ and verify the Results.
 $x(n) = \{1, 2, 0, -3, 4, 2, -1, 1, -2, 3, 2, 1, -3\}$
 $h(n) = \{1, 1, 1\}$ 10
- b) Determine DFT for a continuous time signal $x(t) = \sin 2\pi f t$; with $f = 50$ Hz.
Use 8 point DIT-FFT algorithm. 10
3. a) The even samples of the 11-point DFT of length 11 real sequences are given by
 $X(0) = 2,$ $X(2) = -1 - j3,$ $X(4) = 1 + j4$
 $X(6) = 9 + j3,$ $X(8) = 5,$ $X(10) = 2 + j2$
Determine the missing odd samples. 6
- b) Compare the number of complex multiplications required to compute $N = 64$ point sequence using Direct computations of DFT versus FFT algorithms.
Also obtain speed improvement factor for the above case. 4
- c) Realize the following systems using direct form and cascade form with

P.T.O.



minimum number of multipliers

i) $H(z) = \left(1 + \frac{1}{2}z^{-1} + \frac{1}{2}z^{-2} + z^{-3}\right)(1 + z^{-1})$

ii) $H(z) = \left(\frac{1}{2} + z^{-1} + \frac{1}{2}z^{-2}\right)\left(1 + \frac{1}{3}z^{-1} + z^{-2}\right).$ 10

4. a) Obtain cascade and parallel realization of the system function

$$H(z) = \frac{(1 + z^{-1})}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}\right)}.$$
 6

b) Sketch the ladder structure for the system $H(z) = \frac{1 - 0.6z^{-1} + 1.2z^{-2}}{1 + 0.15z^{-1} - 0.64z^{-2}}.$ 6

c) Determine order and poles of low pass Butterworth filter that has a 3 dB attenuation at 500 Hz and an attenuation of 40 dB at 1000 Hz. 8

5. a) Design a digital Chebyshev filter to satisfy the constraints, $T = 1$ sec.

$$0.8 \leq |H(e^{j\omega})| \leq 1, \quad 0 \leq \omega \leq 0.2\pi$$

$$|H(e^{j\omega})| \leq 0.2, \quad 0.6\pi \leq \omega \leq \pi$$

using Bilinear transformations. 12

b) An Analog filter has a transfer function $H(s) = \frac{10}{s^2 + 7s + 10}$. Design a digital filter to realize this using Impulse Invariant Method. Take $T = 1$ Sec. 8

6. a) List the advantages and disadvantages of Bilinear transformations. 5

b) Derive the transformations of IIR filter using approximation of derivatives by backward difference and verify whether it satisfies the sufficient and necessary conditions of mapping. 5

c) Convert the following low pass Butterworth filter with system function

$$H(s) = \frac{s + 0.3}{s^2 + 3s + 5} \text{ into}$$

i) High Pass filter

ii) Band stop filter. 10



7. a) Compare FIR and IIR filters. **5**
b) Discuss the merits and demerits of window function based filter design. **5**
c) Design a FIR filter with $H_d(e^{j\omega}) = \begin{cases} e^{-j3\omega} - \pi/4 \leq \omega \leq \pi/4 \\ 0 & \pi/4 \leq |\omega| \leq \pi \end{cases}$. use Hanning window. **10**
8. a) Explain different addressing modes with examples as related to a DSP processor. **8**
b) With a Block diagram, describe the architecture of TMS – 320 DSP processor. **12**
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