## **Week 1.3 Parameter Learning**

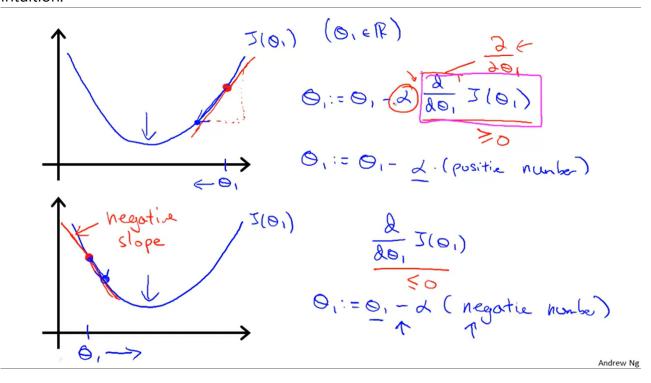
## **Gradient Descent**

- 1. Start with some  $\theta_0, \theta_1$
- 2. Keep changing  $\theta_0, \theta_1$  to reduce  $J(\theta_0, \theta_1)$  until we hopefully end up at a minimum
- repeat until convergence {

$$heta_j := heta_j - lpha rac{\partial}{\partial heta_j} J( heta_0, heta_1)$$

} for (j = 0 and j = 1)

- $\alpha$ : learning rate
- Simultaneously: update  $\theta_0$  and  $\theta_1$
- Intuition:



## **Intuition**

• too small

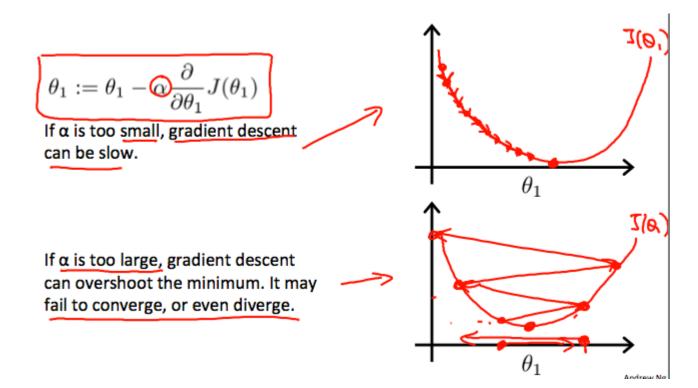
if  $\alpha$  is too small, gradient descent can be slow

• too large:

if  $\alpha$  is too large, gradient descent can overshoot minimum. It may fail to converge, or even diverge.

• Gradient descent can converge to a local minimum, even with the learning rate  $\alpha$  fixed

As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease  $\alpha$  over time.



## **Gradient Descent for Linear Regression**

$$rac{\partial}{\partial heta_0} J( heta_0, heta_1) = rac{1}{m} \sum_{i=1}^m (h_ heta(x^{(i)}) - y^{(i)})$$

$$rac{\partial}{\partial heta_1}J( heta_0, heta_1) = rac{1}{m}\sum_{i=1}^m (h_ heta(x^{(i)})-y^{(i)})x^{(i)}$$

- "convex function": bowl-shaped, only one global optimum
- "Batch" Gradient Descent: each step of gradient descent uses all the training examples