

### **DataLoggerCommands**

START\_RECORD  
STOP\_RECORD  
START\_REPLAY  
STOP\_REPLAY  
SET\_TOPICS

### **RobotCommands**

CONNECT  
DISCONNECT  
START\_DEMONSTRATE  
STOP\_DEMONSTRATE

### **Event**

+ event\_type: EventType  
+ command:  
Union[DataLoggerCommands,  
RobotCommands]  
+args: dict

### **DataLoggerStates**

IDLE  
RECORDING  
REPLAYING

### **RobotStates**

CONNECTED  
DISCONNECTED

### **EventType**

DATA\_LOGGING  
ROBOT\_CONTROL  
TERMINATE