

09. Classification – pt.2

Bayesian methods

Network Data Analysis - NDA'21
Anastasios Giovanidis

Sorbonne-LIP6



November 17, 2021

Bibliography

A. Giovanidis 2021

- B.1 Gareth James, Daniela Witten, Trevor Hastie, Robert Tibshirani. "An introduction to statistical learning: with applications in R". Springer Texts in Statistics. ISBN 978-1-4614-7137-0
[Chapter 2](#), [Chapter 4](#)
DOI 10.1007/978-1-4614-7138-7

Bayes Classifier

Optimal Classifier: (If all misclassifications are equally important) Assign each observation to **the most likely class**, given its predictor values:

$$\max_{1 \leq j \leq M} Pr(Y = j \mid X = x_o)$$

- We consider *conditional probabilities* given the observed x_o .

☞ In a two-class problem

$$Pr(Y = 1 \mid X = x_o) + Pr(Y = 2 \mid X = x_o) = 1:$$

Class 1, if $Pr(Y = 1 \mid X = x_o) > 0.5$

Class 2, if $Pr(Y = 2 \mid X = x_o) > 0.5$

- ☞ Decision boundary $Pr(Y = 1 \mid X = x_o) = Pr(Y = 2 \mid X = x_o)$

Drawback...

There is one problem however: For real data we do not know the conditional distribution $P(Y|X)$,

(unless we have generated data ourselves, in which case we know the joint distribution $P(X, Y)$).

Bayes classifier serves as an unreachable golden standard!

If we do not know exactly $P(Y|X)$ we can try to estimate it.

Naive Bayes

☞ The Naive Bayes classifier:

- ▶ Assumes that the K features are independent.
- ▶ Uses a simple MAP or ML estimator


$$P(Y | \mathcal{D}_n) \propto P(\mathcal{D}_n | Y)P(Y) \quad \textbf{[MAP]}$$

$$P(Y | \mathcal{D}_n) \propto P(\mathcal{D}_n | Y) \quad \textbf{[ML]}$$

where Y is the class label.

We choose MAP or ML, depending on the prior information over the class distribution Y .

Naive Bayes with discrete features

 Let us classify texts (e.g. books, sentences) in one of two classes:

1. History
2. Science

Bag-of-words

To do so, we will use some features from the available data (texts).

These are a certain bag-of-words: {'king', 'food', 'equals', 'proof'}

	Bag-Of-Words				Label	
	1:'king'	2:'food'	3:'equals'	4:'proof'	History	Science
Text 1	No	Yes	Yes	Yes	No	Yes
Text 2	No	No	Yes	No	No	Yes
Text 3	Yes	Yes	No	Yes	Yes	No
...
Text n	Yes	No	Yes	Yes	No	Yes

Forming the variables

✎ If X contains K binary state features, with $X_{t,k} \in \{0, 1\}$, then

$$X_t = (X_{t,1}, \dots, X_{t,K}), \quad t = 1, \dots, n.$$

$X_{t,k}$ says whether feature k appears or not in the t -th data sample of \mathcal{D}_n .

Also, Y is the label of each text. Then, let

$$Y_t = \begin{cases} 0 & \text{if 'History'} \\ 1 & \text{if 'Science'} \end{cases}$$

Discrete Estimators

► Mean estimators

$$p_{\mathbf{1}} = p_{Sc} = P(Y = 1) = \frac{1}{n} \sum_{t=1}^n Y_t,$$

$$p_{\mathbf{0}} = p_{Hi} = P(Y = 0) = \frac{1}{n} \sum_{t=1}^n (1 - Y_t)$$

► ML estimators

$$p_{\mathbf{1},k} = p_{Sc,k} = P(X_k = 1 \mid Y = 1) = \frac{\sum_{t=1}^n Y_t \cdot X_{t,k}}{\sum_{t=1}^n Y_t}$$

$$p_{\mathbf{0},k} = p_{Sc,k} = P(X_k = 1 \mid Y = 0) = \frac{\sum_{t=1}^n (1 - Y_t) \cdot X_{t,k}}{\sum_{t=1}^n (1 - Y_t)}$$

Test likelihood

☞ How does Naive Bayes work in 2 classes ('History'-'Science'), for a **Test sample** (X_o, y_o) ?

- ▶ We make use of the estimated **likelihood**!
- ▶ Suppose the distribution for each feature k per class j is Bernoulli($p_{j,k}$) and **independent** of other features.

For each feature the test-data **likelihood** is:

$$L(p_{j,k}; X_{o,k}) = p_{j,k}^{X_{o,k}} (1 - p_{j,k})^{1-X_{o,k}}, \quad \text{for class } j \in \{0, 1\}$$

Posteriors

- ▶ Then for ML posteriors (with feature independence):

$$P(Y = 0 \mid X_o) \propto P(X_o \mid Y = 0) = \prod_{k=1}^K p_{\mathbf{0},k}^{X_{o,k}} (1 - p_{\mathbf{0},k})^{1-X_{o,k}},$$

$$P(Y = 1 \mid X_o) \propto P(X_o \mid Y = 1) = \prod_{k=1}^K p_{\mathbf{1},k}^{X_{o,k}} (1 - p_{\mathbf{1},k})^{1-X_{o,k}}$$

- ▶ For MAP posteriors we need also the **Prior distribution** over classes, i.e. $p_{\mathbf{0}} = P(Y = 0)$ and $p_{\mathbf{1}} = P(Y = 1)$,

$$P(Y = j \mid \mathcal{D}_n) = P(\mathcal{D}_n \mid Y = j) \cdot P(Y = j), \quad j \in \{0, 1\}.$$

Example

Calculate the Naive Bayes classification for the following example:

	Bag-Of-Words				Label	
	1:'king'	2:'food'	3:'equals'	4:'proof'	History	Science
Text 1	No	Yes	Yes	Yes	No	Yes
Text 2	No	No	Yes	No	No	Yes
Text 3	Yes	Yes	No	Yes	Yes	No
Text 4	Yes	No	Yes	Yes	No	Yes
Test	No	No	Yes	Yes	??	??

Naive Bayes with continuous features

- ✎ Suppose that X contains K continuous state features.
- ▶ Suppose the distribution for each feature k per class j is **Gaussian** $\mathcal{N}(\mu_{j,k}, \sigma_{j,k}^2)$.
 - ▶ **Prior distribution** over classes, is assumed **uniform**, i.e. $P(Y = 0) = P(Y = 1) = 0.5$, non-uniform arbitrary, or estimated from dataset (as before).

Continuous estimates

- ▶ ML estimates for mean.

$$\begin{aligned}n_1 &= \sum_{t \in \mathcal{D}_n} \mathbf{1}(Y_t = 1), & \bar{X}_{1,k} &= \frac{1}{n_1} \sum_{t \in \mathcal{D}_n, Y_t=1} X_{t,k}, \\n_0 &= \sum_{t \in \mathcal{D}_n} \mathbf{1}(Y_t = 0), & \bar{X}_{0,k} &= \frac{1}{n_0} \sum_{t \in \mathcal{D}_n, Y_t=0} X_{t,k}\end{aligned}$$

- ▶ ML estimates for variance.

$$\begin{aligned}\bar{S}_{1,k}^2 &= \frac{1}{n_1 - 1} \sum_{t \in \mathcal{D}_n, Y_t=1} (X_{t,k} - \bar{X}_{1,k})^2, \\ \bar{S}_{0,k}^2 &= \frac{1}{n_0 - 1} \sum_{t \in \mathcal{D}_n, Y_t=0} (X_{t,k} - \bar{X}_{0,k})^2.\end{aligned}$$

ML and MAP estimators

Given a Test sample (X_o, y_o) , the estimated class is the one which maximizes the Likelihood (ML) estimator, i.e. the maximum between

$$P(Y = 0 \mid \mathcal{D}_n) = \prod_{k=1}^K \frac{1}{(2\pi \bar{S}_{0,k}^2)^{1/2}} \exp \left(-\frac{(X_{o,k} - \bar{X}_{0,k})^2}{2\bar{S}_{0,k}^2} \right) \quad \text{for Class 0}$$

$$P(Y = 1 \mid \mathcal{D}_n) = \prod_{k=1}^K \frac{1}{(2\pi \bar{S}_{1,k}^2)^{1/2}} \exp \left(-\frac{(X_{o,k} - \bar{X}_{1,k})^2}{2\bar{S}_{1,k}^2} \right) \quad \text{for Class 1}$$

and similarly as in the discrete case for MAP estimators

$$P(Y = j \mid \mathcal{D}_n) = P(\mathcal{D}_n \mid Y = j) \cdot P(Y = j), \quad j \in \{0, 1\}.$$

Linear Discriminant Analysis (LDA)

For classification of two or multiple classes, we often use **LDA**:

- ▶ Instead of modelling $Pr(Y = j|X = x)$ directly as in Logistic Regression, it does this indirectly by modelling $Pr(X = x|Y = j)$ (**Likelihood** again!).
- ▶ Makes use of the **Bayes' Theorem** and the **Bayes classifier**.
- ▶ Assumes the distribution of X 's is approximately **Gaussian**.

☞ The class boundaries are **linear**, as in Logistic Regression.

Applies to **continuous** feature variables $X_n = (X_{n,1}, \dots, X_{n,K})$

Bayes' Theorem in Classification

We want to calculate the conditional probability for each class

$$\begin{aligned}
 Pr(Y = j | X = x) &\stackrel{\text{Bayes'}}{=} \frac{Pr(X = x | Y = j) Pr(Y = j)}{Pr(X = x)} \\
 &\stackrel{\text{Total}}{=} \frac{Pr(X = x | Y = j) Pr(Y = j)}{\sum_{m=1}^M Pr(X = x | Y = m) Pr(Y = m)} \\
 &= \frac{f_j(x) \cdot \pi_j}{\sum_{m=1}^M f_m(x) \cdot \pi_m}
 \end{aligned}$$

☞ We need the conditional probability of X given the class, and the frequency of each class.

Bayes' Theorem in Classification

We want to calculate the conditional probability for each class

$$\begin{aligned}
 Pr(Y = j|X = x) &\stackrel{\text{Bayes'}}{=} \frac{Pr(X = x|Y = j) Pr(Y = j)}{Pr(X = x)} \\
 &\stackrel{\text{Total}}{=} \frac{Pr(X = x|Y = j) Pr(Y = j)}{\sum_{m=1}^M Pr(X = x|Y = m) Pr(Y = m)} \\
 &= \frac{f_j(x) \cdot \pi_j}{\sum_{m=1}^M f_m(x) \cdot \pi_m}
 \end{aligned}$$

☞ We need the **conditional probability of X** given the class, and the **frequency** of each class.

☞ Given these, we can choose for $X = x_o$, the class with $\max_{1 \leq j \leq M} Pr(Y = j|X = x_o)$ (**Bayes classifier**).

LDA for 1 predictor $K = 1$

We can **assume** that $f_k(x)$ is **normal** or **Gaussian**.

- ▶ For $K = 1$ feature:

$$f_k(x) = \frac{1}{\sigma_k \sqrt{2\pi}} \exp \left(-\frac{1}{2\sigma_k^2} (x - \mu_k)^2 \right),$$

μ_k and σ_k^2 are the **mean** and **variance** for the k -th class.

- ▶ Let us further assume that $\sigma_1^2 = \sigma_2^2 = \dots = \sigma_M^2 = \sigma^2$, hence there is a shared variance among all classes.
- ▶ The π_m 's are also called **prior probabilities**.

Q: Is the gaussian assumption reasonable?

LDA ($K = 1$)

A. Giovanidis 2021

Plugging in (1), we get:

$$Pr(Y = j | X = x) = \frac{\frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu_j)^2\right) \cdot \pi_j}{\sum_{m=1}^M \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu_m)^2\right) \cdot \pi_m}$$

Unknowns:

- ▶ prior probabilities π_m ,
- ▶ means μ_m , $m = 1, \dots, M$, and
- ▶ common variance σ .

LDA ($K = 1$) classification

Let us take the log in the above expression.

We assign for $X = x$, the class m^* such that

$$\begin{aligned} m^* &= \arg \max_{1 \leq m \leq M} \Pr(Y = m | X = x) \\ &= \arg \max_{1 \leq m \leq M} \log \Pr(Y = m | X = x) \\ &= \arg \max_{1 \leq m \leq M} \left\{ x \cdot \frac{\mu_m}{\sigma^2} - \frac{\mu_m^2}{2\sigma^2} + \log(\pi_m) \right\} \\ &= \arg \max_{1 \leq m \leq M} \{x \cdot c_{1,m} + c_{0,m}\} \quad (\text{linear!}) \end{aligned}$$

Estimating the decision function

For each class m we have the **linear discriminant function** of x :

$$\delta_m(x) = x \cdot \frac{\mu_m}{\sigma^2} - \frac{\mu_m^2}{2\sigma^2} + \log(\pi_m),$$

and to calculate it from the dataset D_n we use the estimates:

$$\hat{\mu}_m = \frac{1}{n_m} \sum_{t: y_t=m} x_t,$$

$$\hat{\sigma}^2 = \frac{1}{n - M} \sum_{m=1}^M \sum_{t: y_t=m} (x_t - \hat{\mu}_m)^2,$$

$$\hat{\pi}_m = \frac{n_m}{n}.$$

2-class example

For $M = 2$ classes, suppose $\pi_1 = \pi_2$ additionally (uniform prior).

Then the discriminant functions become:

$$\delta_1(x) = x \cdot \frac{\mu_1}{\sigma^2} - \frac{\mu_1^2}{2\sigma^2} + \log(\pi_1)$$

$$\delta_2(x) = x \cdot \frac{\mu_2}{\sigma^2} - \frac{\mu_2^2}{2\sigma^2} + \log(\pi_2)$$

so that x is assigned class 1, if $\delta_1(x) > \delta_2(x)$ or,

$$2x(\mu_1 - \mu_2) > \mu_1^2 - \mu_2^2$$

The decision boundary are the points x , s.t.

$$x = \frac{\mu_1 + \mu_2}{2}.$$

A. Giovanidis 2021

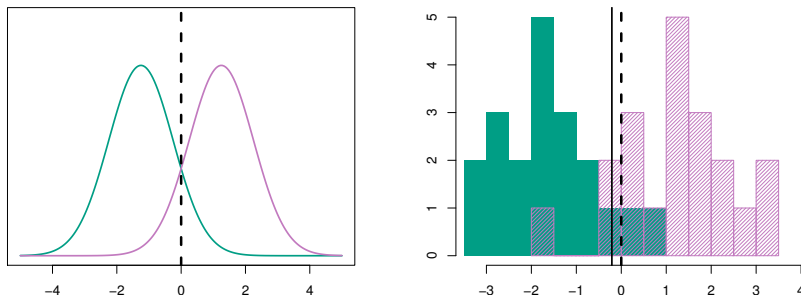


Figure: Two normal density functions and decision boundary. ¹

¹Source [B.1]

LDA for $K > 1$ dimensions

How does the LDA perform, when the predictors X have more than 1 dimension? say $X = (X_1, \dots, X_K)$.

☞ Assume a **multivariate Gaussian distribution** instead of a 1-dimensional $X \sim \mathcal{N}(\mu, \Sigma)$.

$$f(x) = \frac{1}{(2\pi)^{K/2} |\Sigma|^{1/2}} \exp \left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right).$$

- ▶ **mean** $\mu = (\mu_1, \dots, \mu_K)^T$,
- ▶ **common covariance matrix** Σ .

Bivariate Gaussian distribution

Two random variables X and Z are said to have a **bivariate Gaussian distribution** with parameters

$$\mu_X, \sigma_X^2, \mu_Z, \sigma_Z^2, \rho,$$

if their joint PDF is given by

$$f_{XZ}(x, z) = \frac{1}{2\pi\sigma_X\sigma_Z\sqrt{1-\rho^2}} \cdot \exp \left\{ -\frac{1}{2(1-\rho^2)} \left[\left(\frac{x-\mu_X}{\sigma_X} \right)^2 + \left(\frac{z-\mu_Z}{\sigma_Z} \right)^2 - 2\rho \frac{(x-\mu_X)(z-\mu_Z)}{\sigma_X\sigma_Z} \right] \right\},$$

where $\rho \in (-1, 1)$ the **correlation coefficient** $\rho = \frac{\text{Cov}(X, Z)}{\sqrt{\text{Var}(X)\text{Var}(Z)}} = \frac{\sigma_{XZ}}{\sigma_X\sigma_Z}$.

Matrix form (general)

For any number of features $K > 1$

$$f_{\mathbf{x}}(X_1 = x_1, \dots, X_K = x_K) = \frac{\exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)}{\sqrt{(2\pi)^K |\boldsymbol{\Sigma}|}},$$

- ▶ The covariance matrix $\boldsymbol{\Sigma}$ should be positive definite.
- ▶ The mean vector $\boldsymbol{\mu} = (\mu_1, \dots, \mu_K)^T$.
- ▶ In the case $K = 2$ with $(X_1, X_2) = (X, Z)$

$$\boldsymbol{\mu} = (\mu_X, \mu_Z)^T, \quad \boldsymbol{\Sigma} = \begin{pmatrix} \sigma_X^2 & \rho\sigma_X\sigma_Z \\ \rho\sigma_X\sigma_Z & \sigma_Z^2 \end{pmatrix}$$

Bivariate properties

Property 1

Suppose X and Z follow a bivariate Gaussian distribution.

Then, given $X = x$, the variable Z is **Gaussian distributed**, with

$$\begin{aligned}\mathbb{E}[Z \mid X = x] &= \mu_Z + \rho\sigma_Z \frac{x - \mu_X}{\sigma_X}, \\ \text{Var}(Z \mid X = x) &= (1 - \rho^2)\sigma_Z^2.\end{aligned}$$

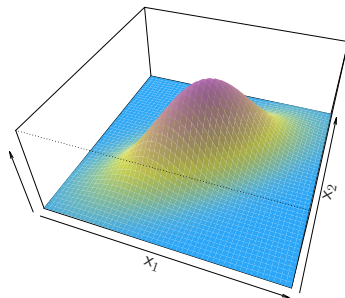
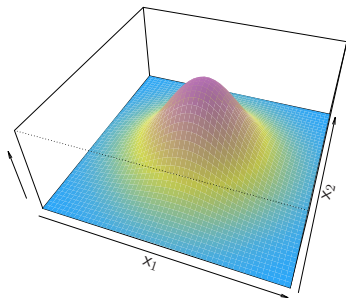
Property 2

Suppose X and Z follow a bivariate Gaussian distribution.

Then, if X , Z are uncorrelated $\rho = 0$ they are independent.

$$\mu = (\mu_X, \mu_Z)^T, \quad \Sigma = \begin{pmatrix} \sigma_X^2 & 0 \\ 0 & \sigma_Z^2 \end{pmatrix}$$

Example bivariate



In the following we will make use of the expressions

$$\begin{aligned} |\Sigma| &= (1 - \rho^2) \sigma_X^2 \sigma_Z^2, \\ \Sigma^{-1} &= \frac{1}{|\Sigma|} \begin{pmatrix} \sigma_Z^2 & -\rho \sigma_X \sigma_Z \\ -\rho \sigma_X \sigma_Z & \sigma_X^2 \end{pmatrix} \end{aligned}$$

Linear discriminant function (general)

Linear Discriminant Function for K features:

$$\delta_k(\mathbf{x}) = \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mu_k - \frac{1}{2} \mu_k^T \boldsymbol{\Sigma}^{-1} \mu_k + \log(\pi_k)$$

Q: Is it linear? Check for $K = 2$.

A. Giovanidis 2021

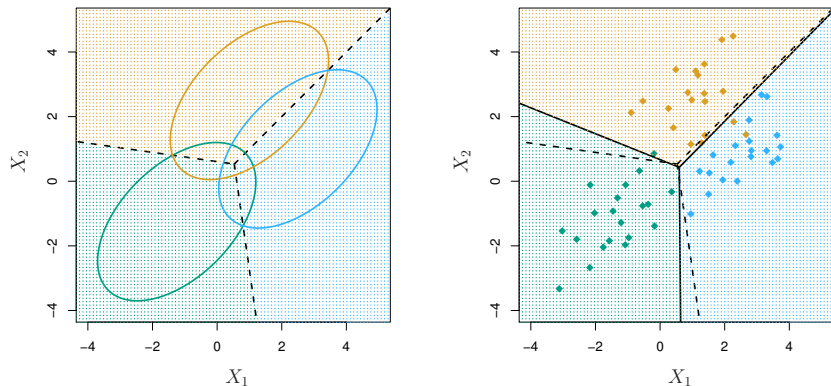


Figure: Classification for $M = 3$ classes and $K = 2$ dimensions. ²

²Source [B.1]

Quadratic Discriminant Analysis (QDA)

A. Giovanidis 2021

LDA assumed for each class a different mean μ_k and same covariance matrix Σ .

☞ QDA assumes **different covariance matrix per class**. That is, an observation from the k -th class is of the form $X \sim \mathcal{N}(\mu_k, \Sigma_k)$.

Quadratic Discriminant Function:

$$\begin{aligned}\delta_k(\mathbf{x}) = & -\frac{1}{2}\mathbf{x}^T \Sigma_k^{-1} \mathbf{x} + \mathbf{x}^T \Sigma_k^{-1} \mu_k - \frac{1}{2} \mu_k^T \Sigma_k^{-1} \mu_k - \\ & -\frac{1}{2} \log |\Sigma_k| + \log(\pi_k)\end{aligned}$$

QDA is more flexible than LDA: Bias vs Variance tradeoff !

QDA examples

A. Giovanidis 2021

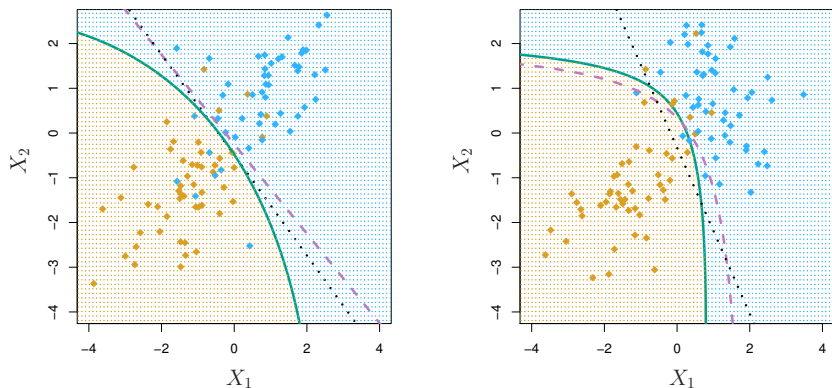


Figure: (left:) Truth common Σ , (right:) Truth different Σ_1, Σ_2 .³

³Source [B.1]

Method comparison: linear

A. Giovanidis 2021

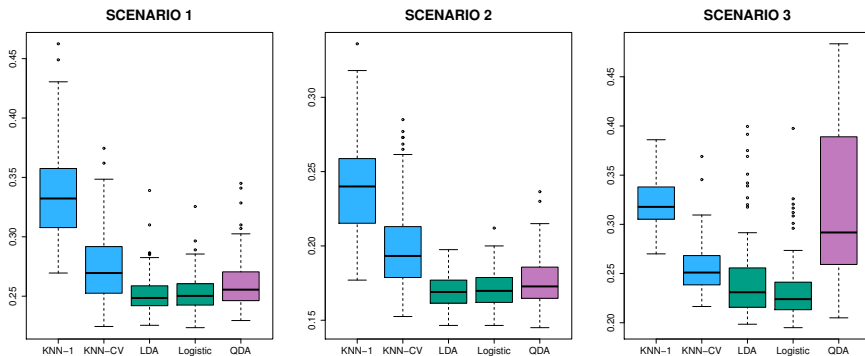


Figure: (1) uncorr., \mathcal{N} , $\mu_1 \neq \mu_2$, (2) corr., \mathcal{N} , (3) uncorr., t-distr.⁴

⁴Source [B.1]

Method comparison: non-linear

A. Giovanidis 2021

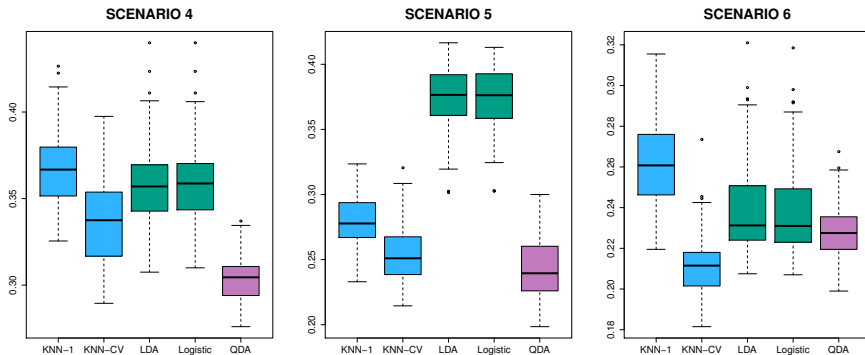


Figure: (4) corr. \mathcal{N} , $\Sigma_1 \neq \Sigma_2$, (5) X_1^2, X_2^2, X_1X_2 (6) more-NL. ⁵

⁵Source [B.1]

A. Giovanidis 2021

END