

NDA: Time Series Analysis Part 1: classic approach

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Bibliography

Formal content:

- Peter Brockwell and Richard Davis
Introduction to Time Series and Forecasting
- William Thistlethorn and Tural Sadigov
MOOC Coursera: *Practical Time Series Analysis*

Informal guide in python:

- www.machinelearningplus.com/time-series/

Illustrative datasets:

- data.world/datasets/time-series
- www.kaggle.com/tags/time-series

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Outline

- 1 Problem definition
- 2 Some elementary concepts
- 3 Some elementary models
- 4 Decomposing the time series
- 5 ARMA model for residuals

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What is time series analysis?

Definition

Set of observations $\{x_t\}$, recorded at time $t \in T_0$

Think of each x_t as a realization from a distribution

Specificities of the problem

A unique realization of the process
 \Rightarrow necessary to make assumptions

- observe time series, identify particularities
- choose a family of models X_t to represent data
- check the goodness of the model

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Assumptions for this course

Restrictions to a subfamily of problems

- discrete time series (discrete time set)
- fixed time steps (time resolution)
- univariate (one single variable over time) \neq multivariate
 \rightarrow processes have values in \mathbb{R}

Approaches

- part 1: classic approach (ARMA model)
- part 2: a glimpse at Machine Learning approaches
- but far from comprehensive...

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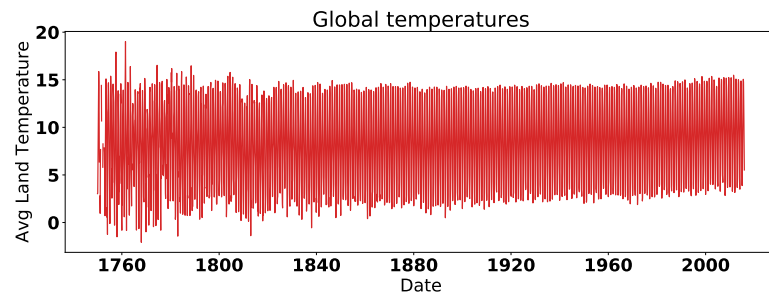
Approaches

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A few examples

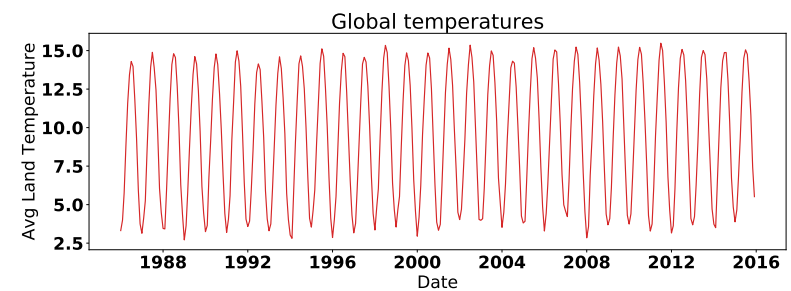
Average global land temperature (per month)



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A few examples

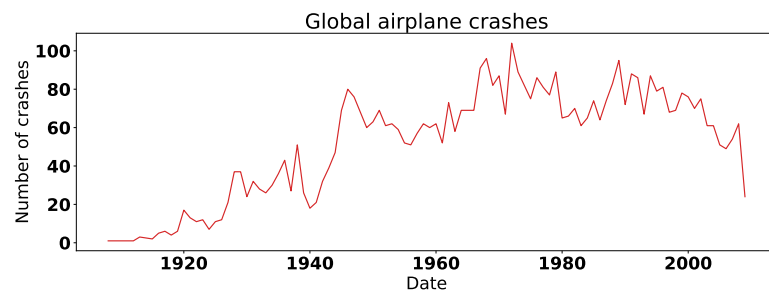
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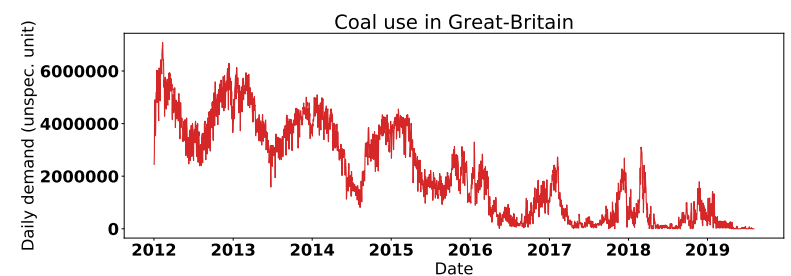
Number of civil airplane crashes (per year)



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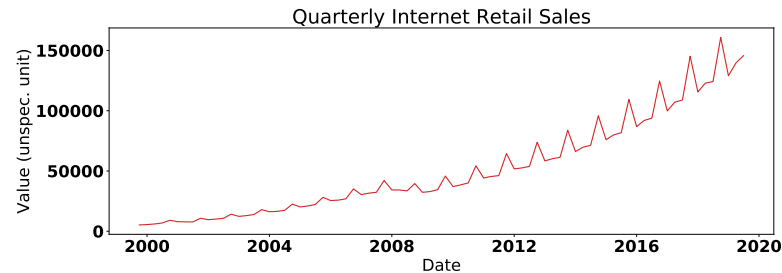
A few examples

Daily demand of power obtained with coal in GB



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A few examples



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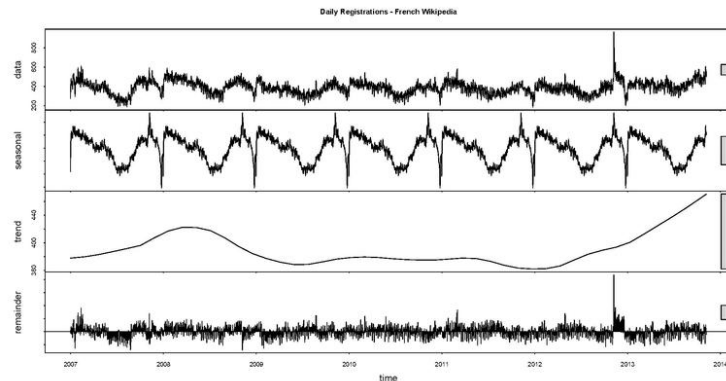
Goals of time series analysis

- Have a **simplified description** of the data
→ improve our understanding (*ex: climate data*)
- **Test** an assumption
ex: is there a significant measurable global warming?
- **Filter**: separate signal from noise
ex: known physical signal broadcast → filter noise
- **Predict** future values
ex: predict the future demand for a product
- **Simulate** a process in a complex model
ex: expectation for the GDP to predict economic activity

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How to analyze a time series? (1)

Analyze from Greek *análusis* ~ unravel \Rightarrow decompose
Decompose the time series into parts, for example:



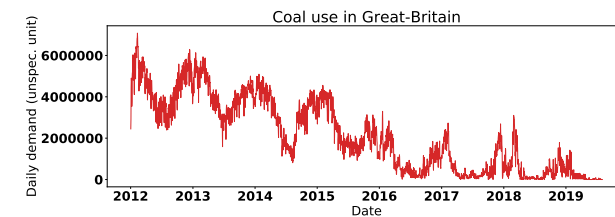
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How to analyze a time series? (1)

First step - visual examination

Plot the time series to:

- identify the existence of a trend (*tendance*)
- uncover seasonal variations (*variations saisonnières*)
- detect changes of behavior
- spot outliers (*valeurs aberrantes*)



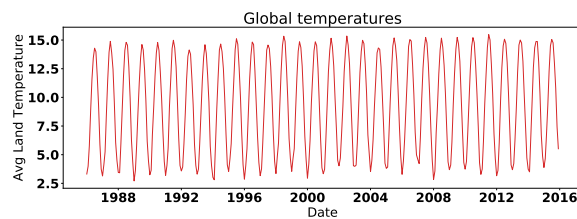
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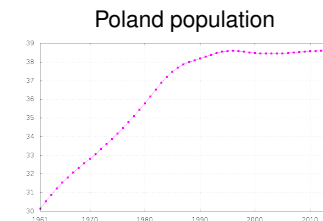
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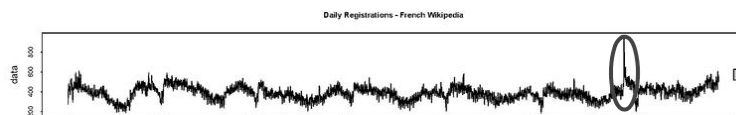
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→ subjective components in this analysis

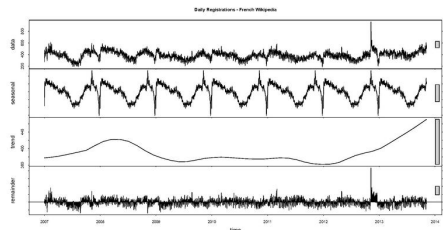
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The classic decomposition

Classic decomposition of the time series

$$X_t = s_t + m_t + r_t$$

- seasonality s_t (periodic and null on average)
- trend m_t (no periodicity)
- residual r_t



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Mean and covariance of a time series

Two fundamental definitions

Let $\{X_t\}$ a time series with $\mathbb{E}[X_t^2] < \infty$ (finite variance)
rk: here we consider X_t as a *random variable* (model)

- **mean function** of X_t , defined for all t :

$$\mu_X(t) = \mathbb{E}[X_t]$$

- **covariance function** of X_t , defined for all r, s :

$$\gamma_X(r, s) = \text{Cov}(X_r, X_s) = \mathbb{E}[(X_r - \mu_X(r))(X_s - \mu_X(s))]$$

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Stationarity

Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

Remarks:

- stationarity is a property of a model (not of data)
- stationary processes are simpler to investigate
⇒ usual to transform a TS to obtain a stationary process

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Stationarity

Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

Formal definition

A process is said to be **weakly stationary** if

- the mean function $\mu_X(t)$ is independent of $t \Rightarrow \mu_X$
- $\gamma_X(t+h, t)$ is independent of t for any h (including $h=0$)
 h is called the *lag* (*retard, décalage*)

$$\gamma_X(t+h, t) = \mathbb{E}[(X_{t+h} - \mu_X)(X_t - \mu_X)] = \gamma_X(h)$$

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Stationarity

Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

Formal definition

A process is said to be **strictly (or strongly) stationary** if

- $\forall n$ and $\forall h$

$$P(X_1 = x_1, \dots, X_n = x_n) = P(X_{1+h} = x_1, \dots, X_{n+h} = x_n)$$

Unless specified otherwise, we talk about weak stationarity in the following

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Autocorrelation function

Notice that for a stationary time series: $\gamma_X(t+h, t) = \gamma_X(h)$
 \Rightarrow the covariance function γ_X has one variable (the lag)

Definition

For a stationary time series:

- the **autocovariance function** at lag h is:

$$\gamma_X(h) = \text{Cov}(X_{t+h}, X_t)$$

- the **autocorrelation function** (ACF) at lag h is:

$$\rho_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)}$$

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Equivalent on real data

Concepts well defined on models, but what about real data?
Let $\{x_1, \dots, x_n\}$ be a series of observations

Sample mean

- the **sample mean** estimator is

$$\bar{x} = \frac{1}{n} \sum_{t=1}^n x_t$$

Equivalent on real data

Concepts well defined on models, but what about real data?
Let $\{x_1, \dots, x_n\}$ be a series of observations

Sample autocovariance function

- the **sample autocovariance function** estimator is

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (x_{t+|h|} - \bar{x}) \cdot (x_t - \bar{x}), \quad -n < h < n$$

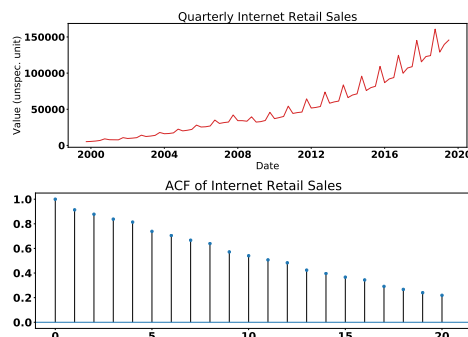
remark: notice the denominator (because of mathematical properties)

- the **sample autocorrelation function** estimator is

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}, \quad -n < h < n. \text{ Note that } \hat{\rho}(h) \in [-1; 1]$$

Equivalent on real data

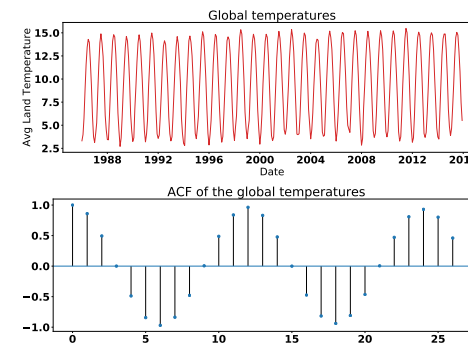
Data with strong trend:



slow decay of correlations with h

Equivalent on real data

Data with strong seasonality:



periodicity on the ACF (here monthly measures \Rightarrow period = 12)

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What is a time series model?

Definition

Time series model: specification of the joint distributions of a sequence of random variables X_t of which the observed data is supposed to be the realization

Remarks:

- suppose to know $\forall t$ the distribs $P(x_1, \dots, x_t, \dots, x_n)$
 \Rightarrow in most case too many parameters to handle
- in practice, we focus on first and second order moments:
 - expected values $\mathbb{E}[X_t]$
 - and expected products $\mathbb{E}[X_{t+h}X_t]$, $h = 1, 2, \dots$

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Independent Identically Distributed noise model

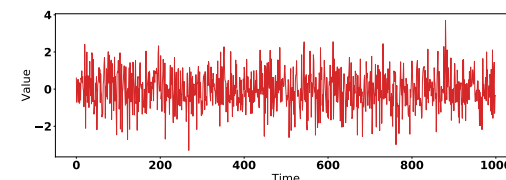
IID noise

- independent:

$$P(X_1 = x_1, \dots, X_n = x_n) = P(X_1 = x_1) \cdot \dots \cdot P(X_n = x_n)$$
- identically distributed: $P(X_t = x) = P(X_{t'} = x)$

IID noise is obviously stationary

ex: repeated coin flipping with heads=1, tails=-1 should be IID noise



Independent Identically Distributed noise model

IID noise

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White noise (*bruit blanc*)

Special case IID noise with

- 0 mean: $E[X_t] = 0$
- autocovariance function:
 $\gamma_X(h) = \sigma^2$ if $h = 0$ and $\gamma_X(h) = 0$ if $h \neq 0$

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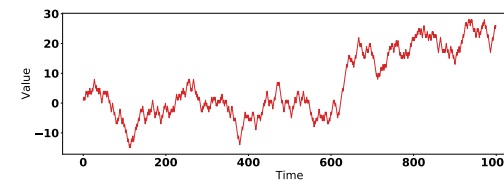
Random Walk model

How to build a random walk? (*marche aléatoire*)

Suppose $\{X_t\}$ is IID noise, then $\{S_t\}$ defined as:

$$S_t = X_1 + \dots + X_t$$

is a random walk



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Remarks:

- is a random walk stationary?
- it's a summation of an IID process
- and conversely $X_t = S_t - S_{t-1}$, or $S_t = S_{t-1} + X_t$

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Remarks:

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How to analyze a time series? (2)

Second step - Decomposition

- (if necessary) transform data
- remove the trend and seasonal components to get stationary residuals (*résidus*)

Residual time series obtained should be stationary, but not necessarily IID noise...

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About pre-processing

Second step - Decomposition

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When is it necessary to transform data?

Some cases

- if outliers → if justified, discard them
ex: external stimulus, mistake in data acquisition, ...
- if obvious different regimes
→ break data into homogeneous segments
- if noise or seasonality increase with trend level
→ logarithmic transformation of the data

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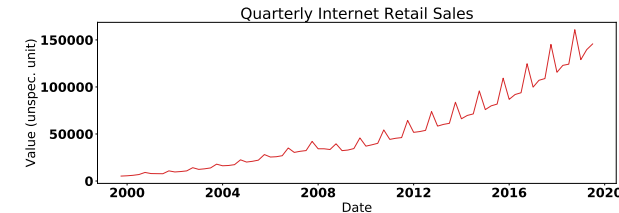
Some cases

- if outliers → if justified, **discard them**
ex: *external stimulus, mistake in data acquisition, ...*
- if obvious different regimes
→ **break data** into homogeneous segments
- if noise or seasonality increase with trend level
→ **logarithmic transformation** of the data

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Logarithmic transformation

If fluctuations (seasonality, noise) grow with magnitude. . .



. . . after logarithmic transform

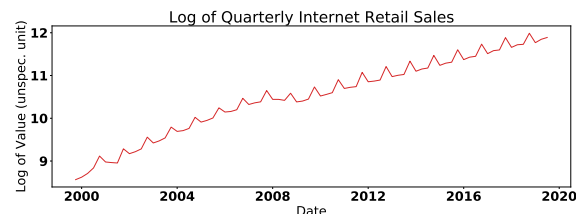
→ c.f. course *Regression (heteroscedasticity)*

Conduct similar analysis on the transformed time series and **reverse the transformations** in the end to model the original data

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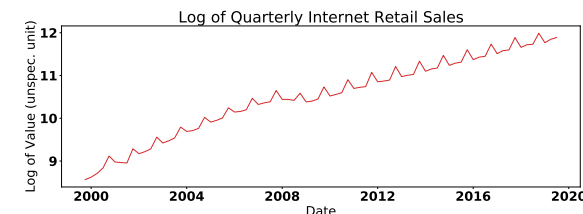
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Back to the classic decomposition

Classic decomposition of the time series

$$X_t = s_t + m_t + r_t$$

- seasonality s_t
- trend m_t
- residual r_t

What is the difference between seasonality and trend?

- seasonality is **periodic**
- seasonality is **null on average**

$$s_{t+d} = s_t$$

$$\sum_{j=1}^d s_j = 0$$

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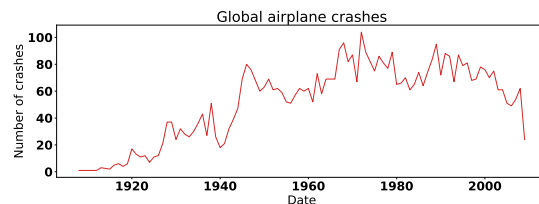
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Isolate the trend component

Model and regression

→ cf. course *Regression*

eg. 2nd order polynomial model with least squares regression



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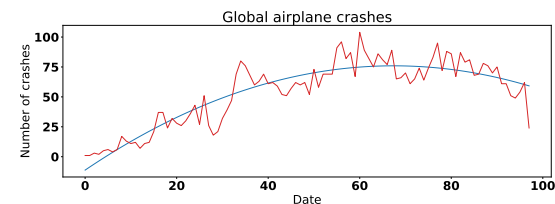
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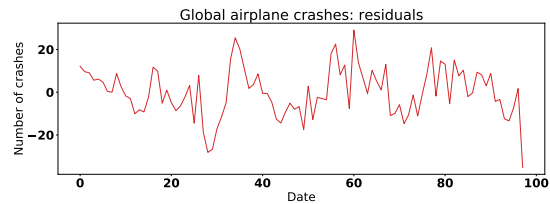
Minimize $\sum_{t=1}^n (x_t - m_t)^2$, with $m_t = a_0 + a_1 t + a_2 t^2$



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Isolate the trend component

Then we plot the residuals $\{x_t - m_t\}$



Questions to ask oneself:

- Is there a perceptible trend? Is it smooth? Do we see stretches (*séquences*) of values of the same sign?
- Does it look stationary? Does it look like noise?

Isolate seasonal component

Model and regression

Which model?

Isolate seasonal component

Model and regression

Which model? **Harmonic regression**

$$s_t = (a_0 +) \sum_{j=1}^k a_j \cos\left(\frac{2\pi t}{T_j}\right) + b_j \sin\left(\frac{2\pi t}{T_j}\right)$$

where T_j are the expected periods of the process

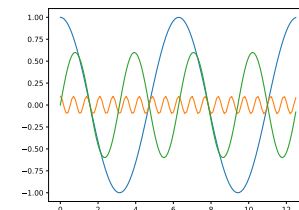
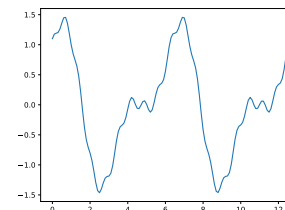
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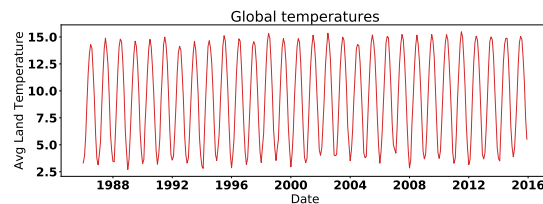
Isolate seasonal component (2)

Harmonic regression on global temperature

Model:

$$s_t = a_0 + a_1 \cos\left(\frac{2\pi t}{12}\right) + b_1 \sin\left(\frac{2\pi t}{12}\right)$$

Only 1 period ($T \equiv 1 \text{ year} \Rightarrow 12 \text{ datapoints}$)



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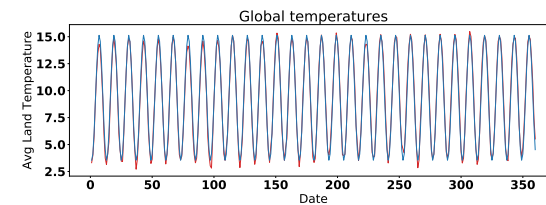
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Harmonic regression on global temperature

Model:

$$s_t = 9.34 - 4.82 \cos\left(\frac{2\pi t}{12}\right) - 3.25 \sin\left(\frac{2\pi t}{12}\right)$$

Only 1 period ($T \equiv 1 \text{ year} \Rightarrow 12 \text{ datapoints}$)



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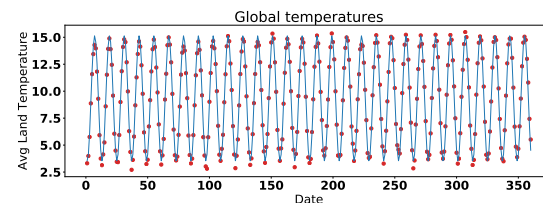
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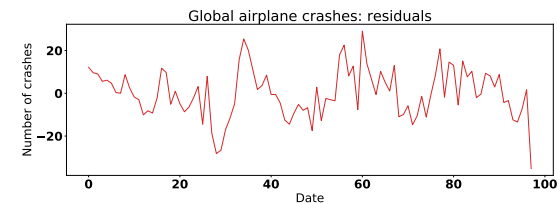
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Stationarity of the residuals

Trend and seasonal components modeled \rightarrow residuals



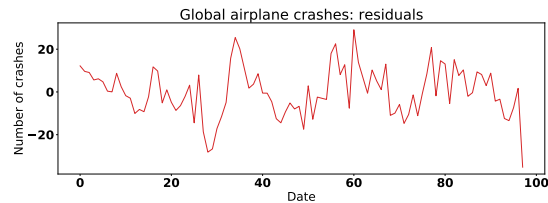
Visual evaluation of stationarity

- Is there a perceptible trend? Is it smooth? Do we see stretches of values of the same sign?
- Does it look stationary? Does it look like noise?

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Stationarity of the residuals

Trend and seasonal components modeled → residuals



Quantitative evaluation of stationarity?

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Testing stationarity of a time series

A general method in Time Series Analysis:

- assume a model
- compute consequences of this model
- test if observations are compatible

→ c.f. course *Hypothesis testing*

Remember that a test can only reject an assumption

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Testing stationarity of a time series

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Illustration: RW and AR(1) processes

Autoregressive processes

Consider the random walk model (not stationary):

$$X_t = X_{t-1} + W_t \text{ where } W_t \text{ is the "error", some white noise}$$

A specific kind of autoregressive model: AR(1)

$$X_t = \phi X_{t-1} + W_t$$

⇒ Random Walk is AR(1) with $\phi = 1$

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Illustration: RW and AR(1) processes

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$X_t = X_{t-1} + W_t$ where W_t is the “error”, some white noise

A specific kind of **autoregressive model**: AR(1)

$$X_t = \phi X_{t-1} + W_t$$

⇒ Random Walk is AR(1) with $\phi = 1$

Illustration: RW and AR(1) processes

AR(1) processes

$$X_t = \phi X_{t-1} + W_t$$

W_t is a white noise (mean 0, variance σ^2)

Stationary? (necessary conditions)

- $\mathbb{E}[X_t] = 0$
- $\gamma_X(h) = \phi^{|h|} \gamma_X(0) = \phi^{|h|} \frac{\sigma^2}{1-\phi^2} \rightarrow$ **problem if $\phi = 1$**

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Testing for unit roots

Notion of characteristic equation

$$X_t - \phi X_{t-1} - W_t = 0$$

$$\rightarrow 1 - \phi x = 0$$

here, 1 is a root of this equation if $\phi = 1$

More generally, if we have a process modeled by the equation:

$$X_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} + \dots - \phi_p X_{t-p} - W_t = 0$$

$$\rightarrow 1 - \phi_1 x - \phi_2 x^2 + \dots - \phi_p x^p = 0$$

if 1 is a root, the process is not stationary (admitted)

Stationarity tests look for unit roots

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Stationarity tests look for unit roots

Process of thought

- assume a model
 $\rightarrow AR(p)$ model
- compute consequences of this model
 \rightarrow if stationary 1 is not a root of the charac. equation
- test if observations are compatible
 \rightarrow parameters $\phi_1 \dots \phi_p$ that fit the data

Outline

- 1 Problem definition
- 2 Some elementary concepts
- 3 Some elementary models
- 4 Decomposing the time series
- 5 ARMA model for residuals

How to analyze a time series? (3)

Third step - fit the residuals

- Find a stationary model for the residuals

Option 0: test if IID

- correlogram test*:
if IID \Rightarrow 95% of the $\hat{\rho}(h)$ values should fall in $\left[-\frac{1.96}{\sqrt{n}}, \frac{1.96}{\sqrt{n}}\right]$
- many others are available: *turning-point test*, *sign test*, ...

If the residuals is an **IID time series**, nothing else to model...

Otherwise: ARMA models
AutoRegressive Moving Average Models

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Autoregressive models

What is autoregression?

auto means self \Rightarrow regression from itself

AR(p) model

Autoregressive with a memory of length p :

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

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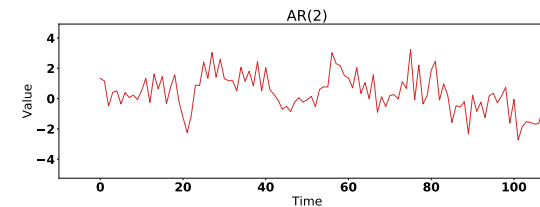
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Autoregressive models

Some characteristics

- **Stationary process** if characteristic polynomial has no unit root
- ACF typical shape: **smooth decay, no cut-off**

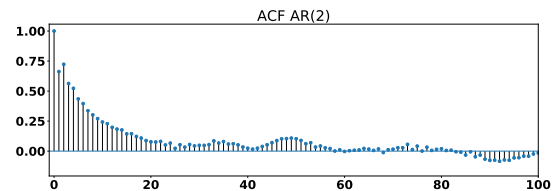


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Moving Average models

Why Moving Average?

The model can be seen as the **weighted moving average** of white noise

MA(1) model

signal = weighted average of noise at t and of noise at $t - 1$

$$X_t = \beta_0 W_t + \beta_1 W_{t-1}$$

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Moving Average models

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MA(q) model

signal = weighted average of noise at t and q previous steps

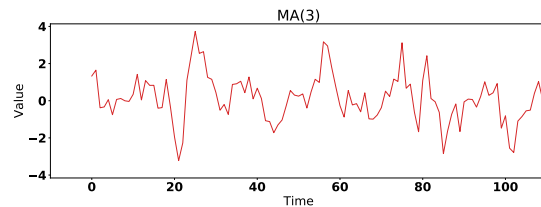
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Moving Average models

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- Stationary process
- ACF typical shape: **cut-off at lag q**

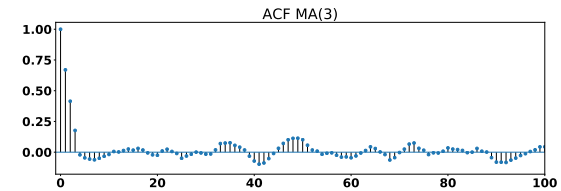


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ARMA models

ARMA(p,q) model

ARMA(p,q) model is a combination of AR(p) and MA(q) model:

$$X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + W_t + \beta_1 W_{t-1} + \dots + \beta_q W_{t-q}$$

nb: ARMA coefficients are found with the ACF → Yule-Walker equations

In practice

- fit the residuals with several (low) values of p and q
- select what is the *best* model
- ⇒ complete model:
trend + seasonality + ARMA(p,q) residuals

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Studying time series in python

Among several options, [pandas library](#)

A few useful functions:

- Load data as dataframe:
`read_csv` from `pandas` library
- Fitting:
`curve_fit` in `scipy.optimize` library
- Autocorrelation function:
`plot_ACF` in `statsmodels` library

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