

# NDA: Time Series Analysis - part 1

Lionel Tabourier

LIP6 – CNRS and Sorbonne University

`first_name.last_name@lip6.fr`

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## Bibliography

Formal content:

- Peter Brockwell and Richard Davis  
*Introduction to Time Series and Forecasting*
- William Thistleton and Tural Sadigov  
MOOC Coursera: *Practical Time Series Analysis*

Informal guide in python:

- [www.machinelearningplus.com/time-series/](http://www.machinelearningplus.com/time-series/)

Illustrative datasets:

- [data.world/datasets/time-series](https://data.world/datasets/time-series)
- [www.kaggle.com/tags/time-series](https://www.kaggle.com/tags/time-series)

# Outline

- 1 Problem definition
- 2 Some elementary concepts
- 3 Some elementary models
- 4 Decomposing the time series

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# What is time series analysis?

## Definition

Set of observations  $\{x_t\}$ , recorded at time  $t \in T_0$

Think of each  $x_t$  as a realization from a distribution

## Specificities of the problem

A unique realization of the process

⇒ necessary to make assumptions

- observe time series, identify particularities
- choose a family of models  $X_t$  to represent data
- check the goodness of the model

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# Assumptions for this course

## Restrictions to a subfamily of problems

- discrete time series (discrete time set)
- fixed time steps (time resolution)
- univariate (one single variable over time)  $\neq$  multivariate  
→ processes have values in  $\mathbb{R}$

## And only a few approaches (Box-Jenkins)

- *e.g.* no Fourier analysis

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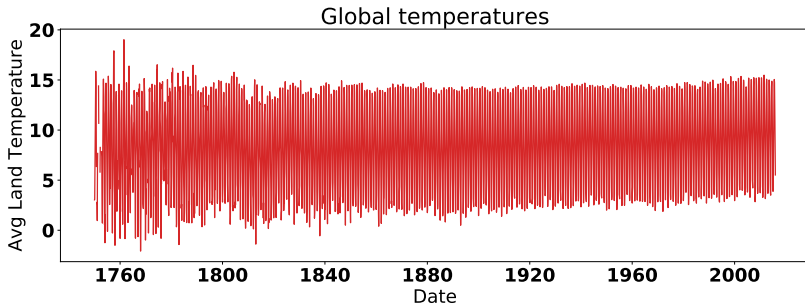
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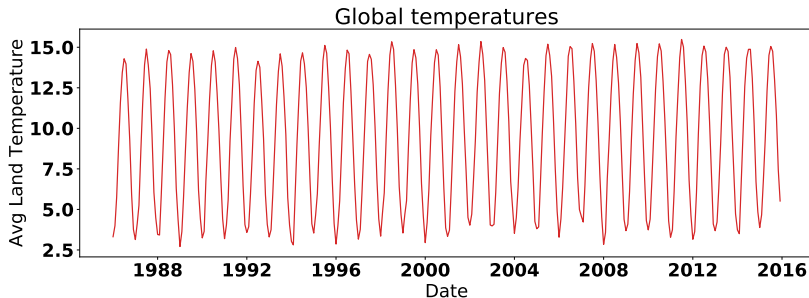
## A few examples

### Average global land temperature (per month)



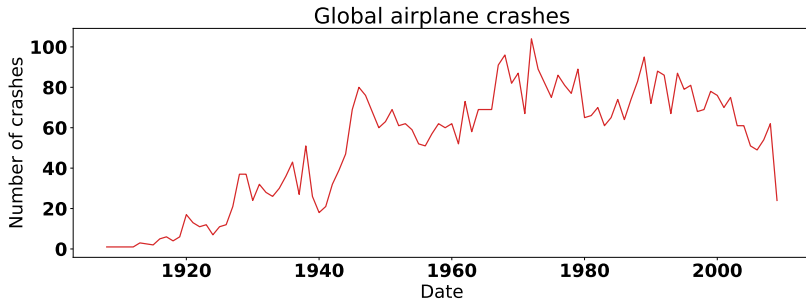
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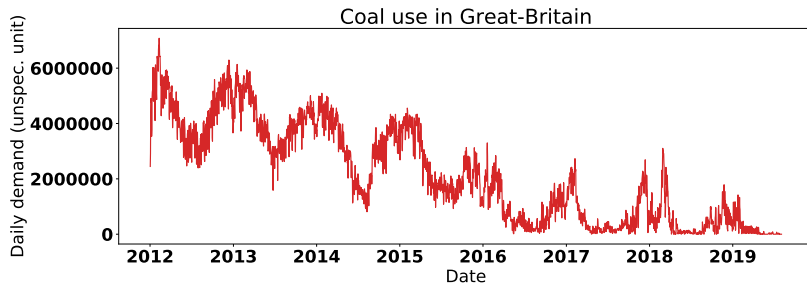
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### Number of civil airplane crashes (per year)

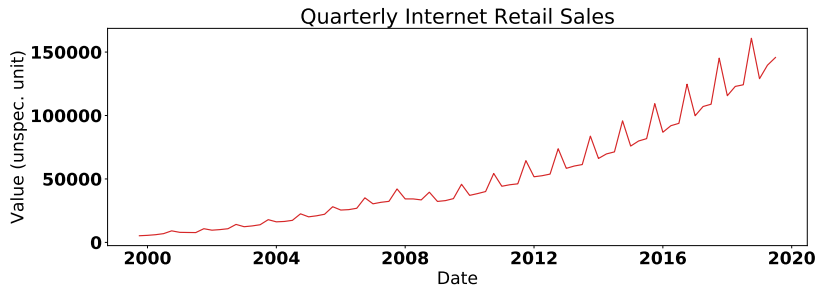


## A few examples

### Daily demand of power obtained with coal in GB



## A few examples



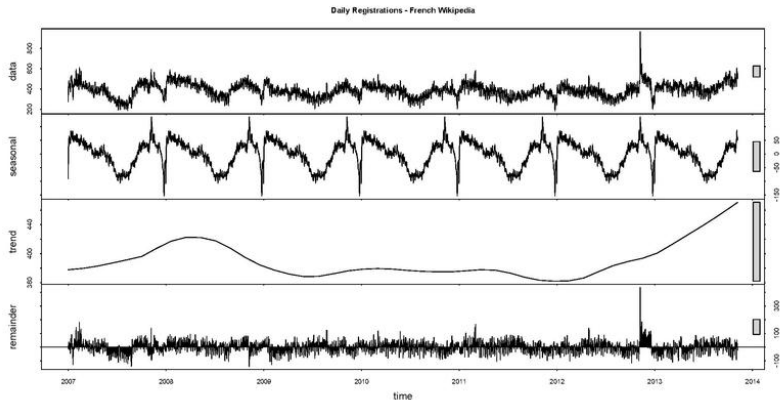
# Goals of time series analysis

- Have a **simplified description** of the data  
→ improve our understanding (*ex: climate data*)
- **Test** an assumption  
*ex: is there a significant measurable global warming?*
- **Filter**: separate signal from noise  
*ex: known physical signal broadcast → filter noise*
- **Predict** future values  
*ex: predict the future demand for a product*
- **Simulate** a process in a complex model  
*ex: expectation for the GDP to predict economic activity*

## How to analyze a time series? (1)

**Analyze** from Greek *análusis*  $\sim$  unravel  $\Rightarrow$  decompose

Decompose the time series into parts, for example:

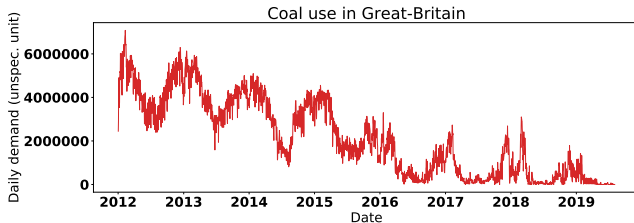


# How to analyze a time series? (1)

## First step

Plot the time series to:

- identify the existence of a trend (*tendance*)
- uncover seasonal variations (*variations saisonnières*)
- detect changes of behavior
- spot outliers (*valeurs aberrantes*)



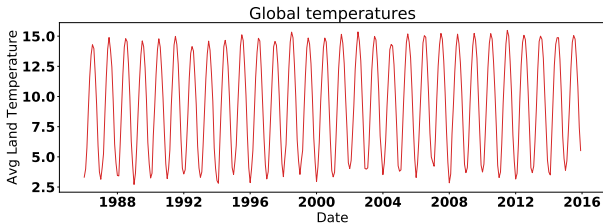


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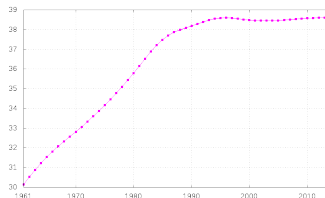
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Poland population



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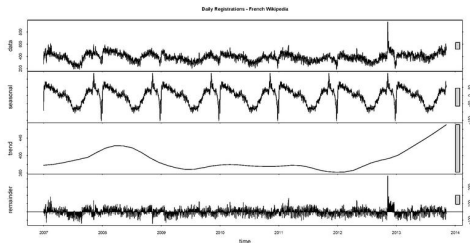
→ subjective components in this analysis

# The classical decomposition

## Classical decomposition of the time series

$$X_t = s_t + m_t + r_t$$

- seasonality  $s_t$
- trend  $m_t$
- remainder  $r_t$



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# Mean and covariance of a time series

## Two fundamental definitions

Let  $\{X_t\}$  a time series with  $\mathbb{E}[X_t^2] < \infty$  (finite variance)  
*rk: here we consider  $X_t$  as a model*

- **mean function** of  $X_t$ , defined for all  $t$ :

$$\mu_X(t) = \mathbb{E}[X_t]$$

- **covariance function** of  $X_t$ , defined for all  $r, s$ :

$$\gamma_X(r, s) = \text{Cov}(X_r, X_s) = \mathbb{E}[(X_r - \mu_X(r))(X_s - \mu_X(s))]$$

# Stationarity

## Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

Remarks:

- stationarity is a property of a model (not of data)
- stationary processes are simpler to investigate  
⇒ usual to transform a TS to obtain a stationary process



# Stationarity

## Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

## Formal definition

A process is said to be **weakly stationary** if

- the mean function  $\mu_X(t)$  is independent of  $t \Rightarrow \mu_X$
- $\gamma_X(t+h, t)$  is independent of  $t$  for any  $h$  (including  $h=0$ )  
 $h$  is called the *lag* (*décalage*)

$$\gamma_X(t+h, t) = \mathbb{E}[(X_{t+h} - \mu_X)(X_t - \mu_X)] = \gamma_X(h)$$

# Stationarity

## Informal definition

A process is **stationary** (*stationnaire*) if its statistical properties are similar when shifted in time

## Formal definition

A process is said to be **strictly (or strongly) stationary** if

- $\forall n$  and  $\forall h$

$$P(X_1 = x_1, \dots, X_n = x_n) = P(X_{1+h} = x_1, \dots, X_{n+h} = x_n)$$

*Unless specified otherwise, we talk about weak stationarity in the following*

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## Autocorrelation function

Notice that for a stationary time series:  $\gamma_X(t+h, t) = \gamma_X(h)$   
 $\Rightarrow$  the covariance function  $\gamma_X$  has one variable (the lag)

### Definition

For a stationary time series:

- the **autocovariance function** at lag  $h$  is:

$$\gamma_X(h) = \text{Cov}(X_{t+h}, X_t)$$

- the **autocorrelation function** (ACF) at lag  $h$  is:

$$\rho_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)}$$

## Equivalent on real data

Concepts well defined on models, but what about real data?

Let  $\{x_1, \dots, x_n\}$  be a series of observations

### Sample mean

- the **sample mean** estimator is

$$\bar{x} = \frac{1}{n} \sum_{t=1}^n x_t$$

## Equivalent on real data

Concepts well defined on models, but what about real data?

Let  $\{x_1, \dots, x_n\}$  be a series of observations

### Sample autocovariance function

- the **sample autocovariance function** estimator is

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (x_{t+|h|} - \bar{x}) \cdot (x_t - \bar{x}), \quad -n < h < n$$

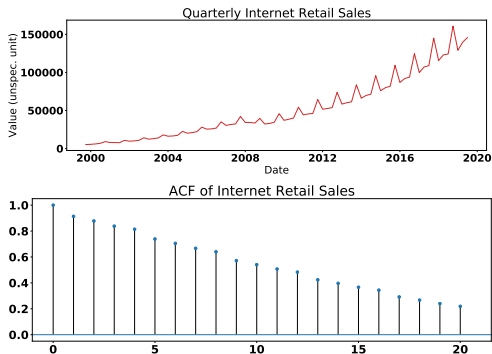
*remark: notice the denominator (because of mathematical properties)*

- the **sample autocorrelation function** estimator is

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}, \quad -n < h < n. \text{ Note that } \hat{\rho}(h) \in [-1; 1]$$

## Equivalent on real data

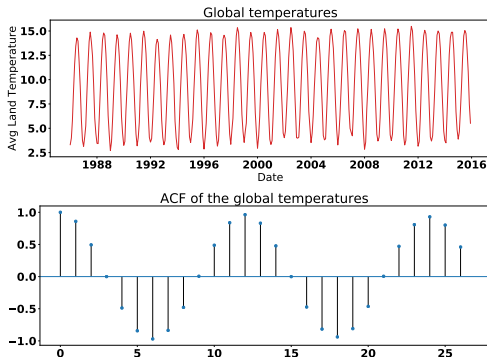
Data with strong trend:



slow decay of correlations with  $h$

## Equivalent on real data

Data with strong seasonality:



periodicity on the ACF (here monthly measures  $\Rightarrow$  period = 12)



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# What is a time series model?

## Definition

**Time series model:** specification of the joint distributions of a sequence of random variables  $X_t$  of which the observed data is supposed to be the realization

Remarks:

- suppose to know  $\forall t$  the distribs  $P(x_1, \dots, x_t, \dots, x_n)$   
 $\Rightarrow$  in most case too many parameters to handle
- in practice, we focus on first and second order moments:
  - expected values  $\mathbb{E}[X_t]$
  - and expected products  $\mathbb{E}[X_{t+h}X_t]$ ,  $h = 1, 2, \dots$

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# Independent Identically Distributed noise model

## IID noise

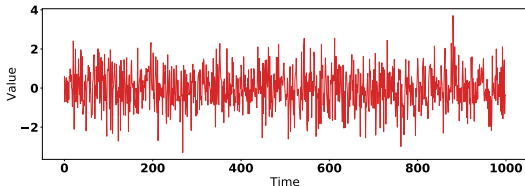
- independent:

$$P(X_1 = x_1, \dots, X_n = x_n) = P(X_1 = x_1) \cdot \dots \cdot P(X_n = x_n)$$

- identically distributed:  $P(X_t = x) = P(X_{t'} = x)$

IID noise is obviously stationary

*ex: repeated coin flipping with heads=1, tails=-1 should be IID noise*



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## IID noise

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## White noise (*bruit blanc*)

Special case IID noise with

- 0 mean:  $E[X_t] = 0$
- autocovariance function:

$$\gamma_X(h) = \sigma^2 \text{ if } h = 0 \text{ and } \gamma_X(h) = 0 \text{ if } h \neq 0$$

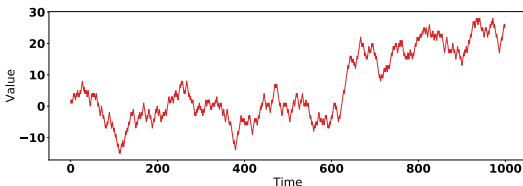
## Random Walk model

### How to build a random walk? (*marche aléatoire*)

Suppose  $\{X_t\}$  is IID noise, then  $\{S_t\}$  defined as:

$$S_t = X_1 + \dots + X_t$$

is a random walk



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Remarks:

- is a random walk stationary?
- it's a summation of an IID process
- and conversely  $X_t = S_t - S_{t-1}$ , or  $S_t = S_{t-1} + X_t$

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Remarks:

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- it's a summation of an IID process
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## How to analyze a time series? (2)

### Second step:

- (if necessary) transform data
- remove the trend and seasonal components to get stationary residuals (*résidus*)

Residual time series obtained (remainder) should be stationary,  
but not necessarily IID noise...

## Back to the classical decomposition

### Classical decomposition of the time series

$$X_t = s_t + m_t + r_t$$

- seasonality  $s_t$
- trend  $m_t$
- remainder  $r_t$

What is the difference between seasonality and trend?

- seasonality is **periodic**
- seasonality is **null on average**

$$s_{t+d} = s_t$$
$$\sum_{j=1}^d s_j = 0$$

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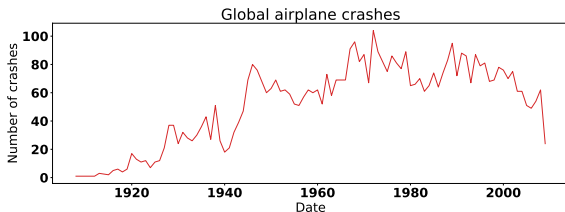
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# Isolate the trend component

## Model and regression

→ cf. course *Regression*

eg.  $2^{\text{nd}}$  order polynomial model with least squares regression



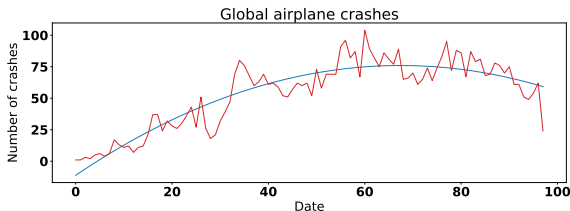
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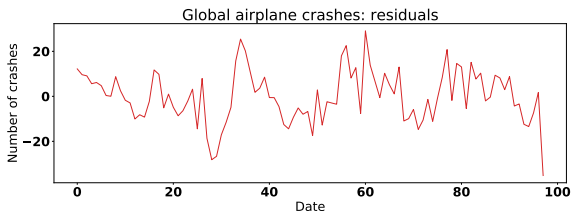
eg.  $2^{nd}$  order polynomial model with least squares regression

Minimize  $\sum_{t=1}^n (x_t - m_t)^2$ , with  $m_t = a_0 + a_1 t + a_2 t^2$



## Isolate the trend component

Then we plot the residuals  $\{x_t - m_t\}$



Questions to ask oneself:

- Is there a perceptible trend? Is it smooth? Do we see stretches (séquences) of values of the same sign?
- Does it look stationary? Does it look like noise?

# Isolate seasonal component

## Model and regression

Which model?



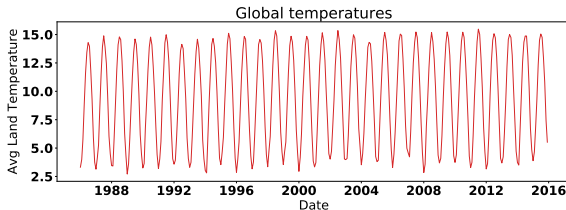
# Isolate seasonal component

## Model and regression

Which model? **Harmonic regression**

$$s_t = (a_0 +) \sum_{j=1}^k a_j \cos\left(\frac{2\pi t}{T_j}\right) + b_j \sin\left(\frac{2\pi t}{T_j}\right)$$

where  $T_j$  are the expected periods of the process



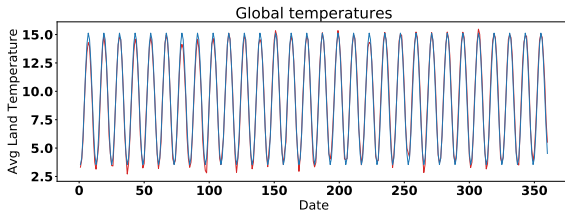
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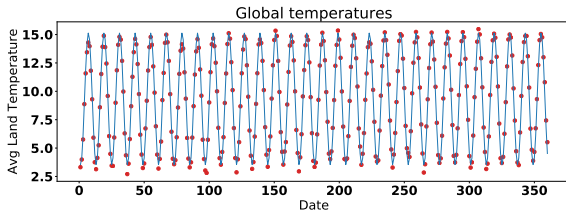
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## About pre-processing

### Second step:

- (if necessary) transform data
- remove the trend and seasonal components to get stationary residuals

When is it necessary to transform data?

### Some cases

- if outliers → if justified, **discard them**  
*ex: external stimulus, mistake in data acquisition, ...*
- if obvious different regimes  
→ **break data** into homogeneous segments
- if noise or seasonality increase with trend level  
→ **logarithmic transformation** of the data

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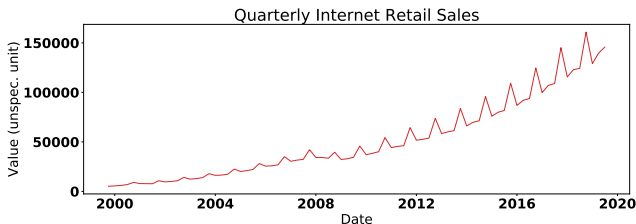
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## Logarithmic transformation

If fluctuations (seasonality, noise) grow with magnitude...



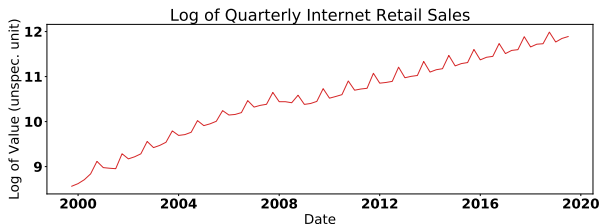
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→ c.f. course *Regression (heteroscedasticity)*

Conduct similar analysis on the transformed time series and  
**reverse the transformations** in the end to model the original data

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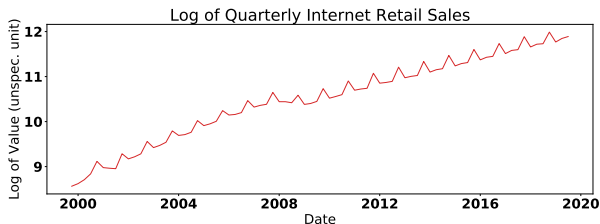
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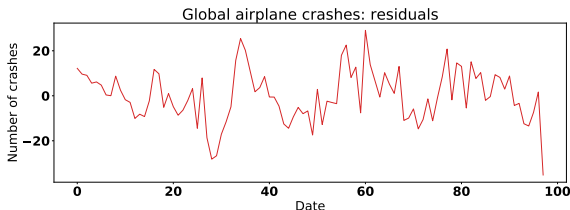
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## Stationarity of the residuals

Trend and seasonal components modeled  $\rightarrow$  residuals

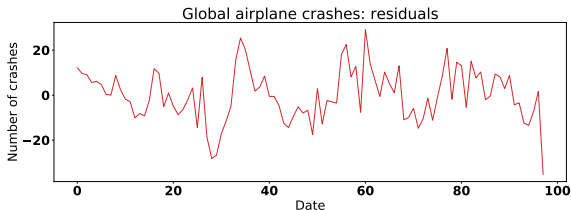


Visual evaluation of stationarity

- Is there a perceptible trend? Is it smooth? Do we see stretches (séquences) of values of the same sign?
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## Stationarity of the residuals

Trend and seasonal components modeled  $\rightarrow$  residuals



Quantitative evaluation of stationarity?

## Testing stationarity of a time series

A general method in Time Series Analysis:

- assume a model
- compute consequences of this model
- test if observations are compatible

→ c.f. course *Hypothesis testing*

We illustrate this logic with the Dickey-Fuller test

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## Illustration: RW and AR(1) processes

### Auto-regressive processes

Consider the random walk model (not stationary):

$$X_t = X_{t-1} + W_t \text{ where } W_t \text{ is the "error", some white noise}$$

A specific kind of **auto-regressive models**: AR(1)

$$X_t = \phi X_{t-1} + W_t$$

⇒ Random Walk is AR(1) with  $\phi = 1$

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$W_t$  is a white noise (0 means,  $\sigma^2$  variance)

Stationary? (necessary conditions)

- $\mathbb{E}[X_t] = 0$
- $\gamma_X(h) = \phi^{|h|} \gamma_X(0) = \phi^{|h|} \frac{\sigma^2}{1-\phi^2} \rightarrow \text{problem if } \phi = 1$

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## Testing for unit roots

### Notion of characteristic equation

$$X_t - \phi X_{t-1} - W_t = 0$$

$$\longrightarrow x - \phi = 0$$

1 is a root of this equation if  $\phi = 1$

More generally, if we have a process modeled by the equation:

$$X_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} + \dots - \phi_p X_{t-p} - W_t = 0$$

$$\longrightarrow x^p - \phi_1 x^{p-1} - \phi_2 x^{p-2} + \dots - \phi_p = 0$$

if 1 is a root, the process is not stationary (admitted)

Stationarity tests look for unit roots

## Testing for unit roots

### Notion of characteristic equation

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Do we have  $X_t = X_{t-1} + W_t$ ?

(and actually some other models that we ignore in this course)

We suppose that we follow this model and we test for  $\phi = 1$

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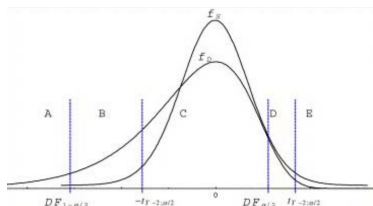
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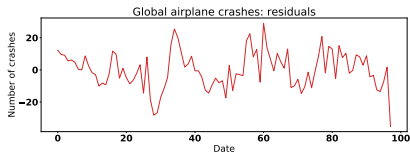
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Estimate  $(\phi - 1)$  from data

compute  $\frac{\hat{\phi} - 1}{\hat{\sigma}/\sqrt{N}}$  and compare to Dickey-Fuller distribution



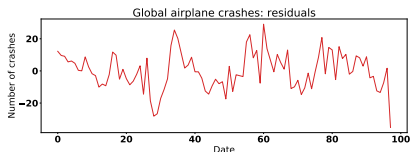
## Testing in practice (airplane crashes residuals)



$$\frac{\hat{\phi}-1}{\sigma/\sqrt{N}} = -2.39 \text{ from data}$$

critical value from table (for  $p = 0.05$ ):  $\frac{\hat{\phi}-1}{\sigma/\sqrt{N}} < -1.944$

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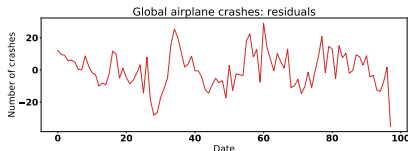


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### Remarks

- other tests available, with other models  
*Augmented Dickey-Fuller, Phillips-Perron, ...*
- in general implemented in statistic software



## Toward ARMA models

A very standard process model:

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

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$\rightarrow$  family of ARMA models (next course)

## Studying time series in python

Among several options, `pandas` library

A few useful functions:

- Load data as dataframe:  
`read_csv` from `pandas` library
- Fitting:  
`curve_fit` in `scipy.optimize` library
- Autocorrelation function:  
`plot_ACF` in `statsmodels` library