

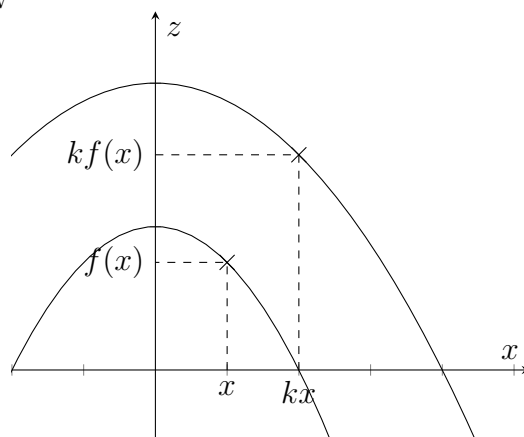
Daya's STEP Mark Scheme

Daya Nidhan Singh

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Question 1

M1M1 Correct graph below



M1A1 Let $g(x)$ be the enlarged graph of $f(x)$.

$$g(kx) = kf(x)$$

$$g(x') = kf\left(\frac{x'}{k}\right)$$

where $x' = \frac{x}{k}$

(4)

M1A1 (i)

$$f(x) = a\left(x + \frac{b}{2a}\right)^2 + c - \frac{b^2}{4a}$$

Let $x' = \frac{x}{a}$

$$h(x') = \frac{1}{a}(a(ax')^2 + b(ax') + c)$$

$$h(x') = (ax')^2 + bx' + \frac{c}{a}$$

$$h(x) = (ax)^2 + bx + \frac{c}{a}$$

(2)

M1A1 (ii) Completing the square:

$$f(x) = a \left(x + \frac{b}{2a} \right)^2 + c - \frac{b^2}{4a}$$

E1A1 The equation can be translated to generalise a parabola further:

$$g(x) = ax^2$$

E1 Hence any enlargement k maps onto a parabola with a different value for $a = a'$:

M1A1

$$\begin{aligned} kg \left(\frac{x}{k} \right) &= ak \left(\frac{x}{a} \right)^2 \\ &= \frac{k}{a} x^2 \\ \therefore a' &= \frac{k}{a} \end{aligned} \tag{7}$$

M1A1 (iii) Applying a general enlargement to map the equation with a to the one to b :

$$\begin{aligned} f(x) &= x^3 + ax \\ kf \left(\frac{x}{k} \right) &= \left(\frac{x}{k} \right)^3 + a \left(\frac{x}{k} \right) \end{aligned}$$

E1A1

$$\begin{aligned} k &= 1 \\ \therefore b &= a \end{aligned}$$

M1A1 Applying an enlargement to $h(x) = ax^n$

$$\begin{aligned} kg \left(\frac{x}{k} \right) &= ak \left(\frac{x}{a} \right)^n \\ &= \frac{k}{a} x^n \\ \therefore a' &= \frac{k}{a^{n-1}} \end{aligned} \tag{7}$$

Question 2

M1M1

$$\begin{aligned} P(t-n) &= a(t-n)^3 + b(t-n)^2 + c(t-n) + d \\ P(t-n) &= at^3 + (-3an+b)t^2 + (3an^2-2bn+c)t + d - nc - an^3 + bn^2 \\ \therefore n &= \frac{b}{3a} \end{aligned}$$

A1A1

$$\begin{aligned} \therefore p &= \frac{1}{a} \left(\frac{b^2}{3a} - \frac{2b^2}{3a} + c \right) \\ &= \frac{3ac - b^2}{3a^2} \\ \therefore q &= \frac{1}{a} \left(d - \frac{bc}{3a} - \frac{ab^3}{27a^3} + \frac{b^3}{9a^2} \right) \\ &= \frac{27a^2d - 9abc + 2b^3}{27a^3} \end{aligned}$$

(4)

M1 (i)

$$\begin{aligned} 0 &= (u+v)^3 + p(u+v) + q \\ &= u^3 + 3u^2v + 3uv^2 + v^3 + pu + pv + q \\ &= u^3 + v^3 + 3uv(u+v) + (u+v)p + q \end{aligned}$$

M1 Generating a pair of equation by comparing coefficients

$$\begin{aligned} u^3 + v^3 &= -q \\ 3uv &= -p \end{aligned}$$

M1A1 Solving simultaneously:

$$\begin{aligned} u^3 - \left(\frac{p}{3u} \right)^3 &= -q \\ u^6 + u^3q - \frac{p^3}{27} &= 0 \\ u^3 &= \frac{-q \pm \sqrt{q^2 + \frac{4p^3}{27}}}{2} \\ u &= \sqrt[3]{\frac{-q - \sqrt{q^2 + \frac{4p^3}{27}}}{2}} = \sqrt[3]{-\frac{q}{2} - \sqrt{\frac{q^2}{4} + \frac{p^3}{27}}} \\ v &= \sqrt[3]{\frac{-q + \sqrt{q^2 + \frac{4p^3}{27}}}{2}} = \sqrt[3]{-\frac{q}{2} + \sqrt{\frac{q^2}{4} + \frac{p^3}{27}}} \end{aligned}$$

(4)

M1 (ii) A) Generating a geometric series:

$$x^5 + x^4 + x^3 + x^2 + x + 1 = x^3 + x^2 + x$$

$$\frac{x^6 - 1}{x - 1} = x(x^2 + x + 1)$$

B1

$$x \neq 1$$

A1A1

$$x^6 - 1 = x(x^3 - 1)$$

$$(x^3 + 1)(x^3 - 1) - x(x^3 - 1) = 0$$

$$(x^3 - 1)(x^3 - x + 1) = 0$$

$$x_1 = e^{\frac{\pi}{3}i}$$

$$x_2 = e^{-\frac{\pi}{3}i}$$

$$x_3 = \sqrt[3]{-\frac{1}{2} + \sqrt{\frac{1}{4} - \frac{1}{27}}} + \sqrt[3]{-\frac{1}{2} - \sqrt{\frac{1}{4} - \frac{1}{27}}}$$

M1A1

$$|x_4| = |x_5| = 1$$

$$x_4 x_5 x_3 = 1$$

$$x_4 = x_5^*$$

$$\therefore x_4 = \sqrt{x_3} + \sqrt{1 - x_3^2}i$$

$$x_5 = \sqrt{x_3} - \sqrt{1 - x_3^2}i$$

(6)

M1 (ii) B) Generating a geometric series:

$$x^5 + x^4 + x^3 + x^2 + x + 1 = x^4 + x^3 + x^2$$

$$\frac{x^6 - 1}{x - 1} = x^2(x^2 + x + 1)$$

$$x \neq 1$$

$$x^6 - 1 = x^2(x^3 - 1)$$

$$(x^3 + 1)(x^3 - 1) - x^2(x^3 - 1) = 0$$

$$(x^3 - 1)(x^3 - x^2 + 1) = 0$$

$$x_1 = e^{\frac{\pi}{3}i}$$

$$x_2 = e^{-\frac{\pi}{3}i}$$

M1

$$x^3 - x^2 + 1 = t^3 - \frac{1}{3}t + \frac{25}{27}, \quad \text{where } t = x - \frac{1}{3}$$

A1A1

$$x_3 = \sqrt[3]{-\frac{25}{2} + \sqrt{\frac{\left(\frac{25}{27}\right)^2 + \frac{\left(\frac{1}{3}\right)^3}{27}}} + \sqrt[3]{-\frac{25}{2} - \sqrt{\frac{\left(\frac{25}{27}\right)^2 + \frac{\left(\frac{1}{3}\right)^3}{27}}}$$

$$|t_4| = |t_5| = 1$$

$$t_4 t_5 t_3 = 1$$

$$t_4 = t_5^*$$

$$\therefore x_4 = \sqrt{x_3 - \frac{1}{3} + \frac{1}{3}} + \sqrt{1 - \left(x_3 - \frac{1}{3}\right)^2} i$$

$$\therefore x_5 = \sqrt{x_3 - \frac{1}{3} + \frac{1}{3}} - \sqrt{1 - \left(x_3 - \frac{1}{3}\right)^2} i$$

(6)

Question 3

M1M1 (i) Consider a has factors a_1, a_2, a_3, \dots and b has factors b_1, b_2, b_3, \dots
The factors of ab can be written as such:

\times	a_1	a_2	a_3	\dots
b_1	$b_1 a_1$	$b_1 a_2$	$b_1 a_3$	\dots
b_2	$b_2 a_1$	$b_2 a_2$	$b_2 a_3$	\dots
b_3	$b_3 a_1$	$b_3 a_2$	$b_3 a_3$	\dots
\dots	\dots	\dots	\dots	\dots

E1A2 Each cell must be unique as all a_i is unique and no factor of b is common with a .
Hence the number of cells of the table is ab hence $\sigma_0(ab) = \sigma_0(a)\sigma_0(b)$

(5)

E1A2 (ii) p^k only has the factor 1, and p^n for $n \leq k$. Hence there are $k + 1$ factors.

(3)

M1M1 (iii)
$$\sigma_0(n^k) = \sigma_0 \left(\prod_{i=1}^{\infty} (p_i^{a_i})^k \right)$$

E1M1M1A2 Every term is coprime in the product hence we can apply the result in (i):

$$\begin{aligned} \sigma_0(n^k) &= \prod_{i=1}^{\infty} \sigma_0(p_i^{a_i k}) \\ &= \prod_{i=1}^{\infty} (a_i k + 1) \end{aligned}$$

(6)

M1 (iv) Correct prime factorisation $720 = 2^4 \times 3^2 \times 5$

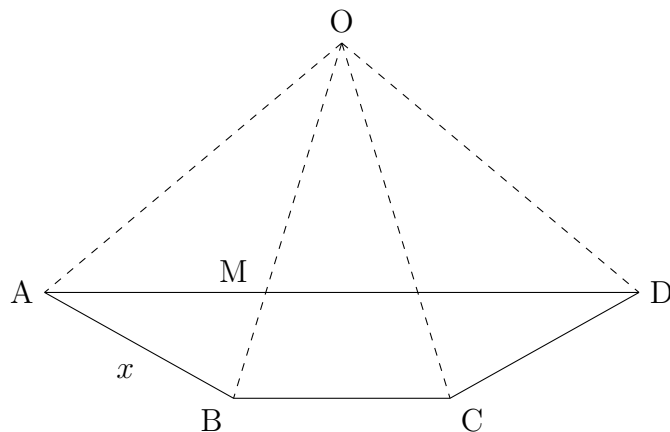
M2 Correct factor Equation
$$\sigma_0(720^k) = (4k + 1)(3k + 1)(k + 1)$$

M2A1 Substitution
$$\begin{aligned} \sigma_0(720^3) &= (4(3) + 1)(2(3) + 1)(3 + 1) \\ &= 13 \times 7 \times 4 \\ &= 364 \end{aligned}$$

(6)

Question 4

M1M1 Correct diagram below



M1M1

$$\begin{aligned}
 \angle OBC = \angle OCD &= \pi - \frac{1}{2} \cdot \frac{2\pi}{10} \\
 &= \frac{2\pi}{5} \\
 \therefore \angle DCB &= \frac{4\pi}{5} \\
 2\pi - 2\left(\frac{4\pi}{5}\right) &= 2\angle ADC \\
 \angle MAB &= \frac{\pi}{5} \\
 \angle BMD &= 2\pi - \frac{4\pi}{5} - \frac{2\pi}{5} - \frac{\pi}{5} \\
 &= \frac{3\pi}{5} \\
 \angle MAB = \angle MBA &= \frac{2\pi}{5}
 \end{aligned}$$

E1 Hence AMB is isosceles therefore $AM = x$.

E1 OAB and AMB are similar triangles. Hence, let $\cos \frac{\pi}{5} = y$

M1 $OAB : \quad x^2 = 1^2 + 1^2 - 2(1)(1)y \quad (1)$

M1

$$\begin{aligned} \hat{AMO} &= \frac{3\pi}{5} \\ M\hat{AO} &= \frac{\pi}{5} \end{aligned}$$

E1 Hence AMO is isosceles and $OM = x$, and $BM = 1 - x$

M1

$$AMO : (1 - x)^2 = x^2 + x^2 - 2(x)(x)y \quad (2)$$

M1M1 Solving simultaneously:

$$x^2 = 2 - 2y \quad (1)$$

$$x^4 - 2x^2 = -2x^2y$$

$$x^2 - 2x + 1 = 2x^2(1 - y) \quad (2)$$

$$1 - 2x - x^2 = -2x^2y$$

$$1 - 2x - x^2 = x^4 - 2x^2$$

$$x^4 - (x^2 - 2x + 1) = 0$$

$$x^2 - (x - 1)^2 = 0$$

$$(x^2 - x + 1)(x^2 + x - 1) = 0$$

A1

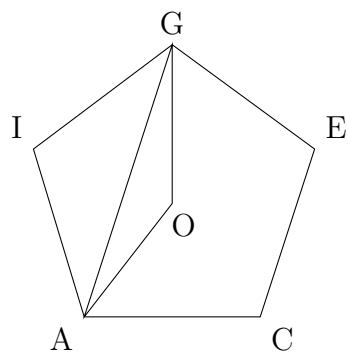
$$\begin{aligned} x &= \frac{-1 \pm \sqrt{5}}{2} \\ x &= \frac{1 \pm \sqrt{-3}}{2} \end{aligned}$$

B1A1 Only valid solution for $x \geq 0, x \in \mathbb{R}$ is $x = \frac{-1+\sqrt{5}}{2}$.

M1A1 Solving for y :

$$\begin{aligned} 2y &= 2 - x^2 \\ &= 2 - \left(\frac{-1 + \sqrt{5}}{2} \right)^2 \\ &= 2 - \frac{1 + 5 - 2\sqrt{5}}{4} \\ &= \frac{2\sqrt{5} + 4}{4} \\ y &= \frac{\sqrt{5} + 1}{4} \end{aligned}$$

M1 Correct diagram below



M1A1

$$\begin{aligned}
 \angle AOG &= \frac{4\pi}{5} \\
 \cos(\angle AOG) &= -\cos \frac{\pi}{5} \\
 AG^2 &= 1^2 + 1^2 - 2(1)(1) \left(-\cos \frac{\pi}{5} \right) \\
 AG &= \sqrt{2 + 2 \left(\frac{1 + \sqrt{5}}{4} \right)} \\
 &= \sqrt{\frac{\sqrt{5} + 5}{2}}
 \end{aligned}$$

Question 5

M1M1A1 (i)

$$\begin{aligned}\int \sec(\arctan(x))dx &= \int \sqrt{1 + \tan^2(\arctan(x))}dx \\ &= \int \sqrt{1 + x^2}dx\end{aligned}$$

M1M1A1

$$\begin{aligned}u &= \sinh(x) \\ \int \sqrt{1 + x^2}dx &= \int \cosh^2(u)du \\ &= \int \frac{\cosh(2u) - 1}{2}du \\ &= \frac{\sinh(2u)}{2} - \frac{u}{2} + C \\ &= \frac{\sinh(2 \operatorname{arsinh}(x))}{2} - \frac{\operatorname{arsinh}(x)}{2} + C\end{aligned}$$

M1M1M1A1 Attempt to evaluate $\operatorname{gd}(x)$:

$$\begin{aligned}\operatorname{gd}(x) &= \int_0^x \operatorname{sech}(t)dt \\ &= \int_0^x \frac{\cosh(t)}{\cosh^2(t)}dt \\ &= \int_0^x \frac{\cosh(t)}{1 + \sinh^2(t)}dt \\ &= \arctan(\sinh(x)) - 0 \\ &= \arctan(\sinh(x))\end{aligned}$$

M1M1M1A1

$$\begin{aligned}\int \sec(\operatorname{gd}(x))dx &= \int \sec(\arctan(\sinh(x)))dx \\ &= \int \sqrt{1 + \sinh^2(x)}dx \\ &= \int \cosh(x)dx \\ &= \sinh(x) + C\end{aligned}$$

M1A1 (ii) Correct substitution

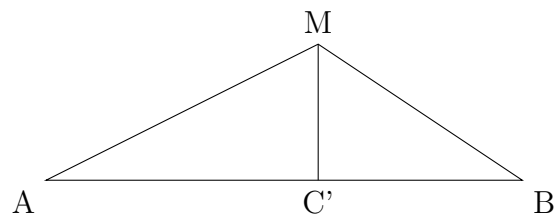
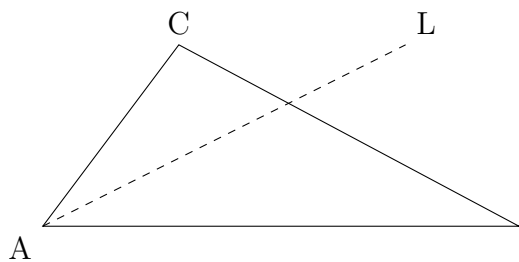
$$\begin{aligned}\operatorname{gd}(u) &= x \\ dx &= \operatorname{sech}(u)du\end{aligned}$$

M1M1A1A1

$$\begin{aligned}\int \sec(x) \operatorname{arsinh}(\tan(x)) dx &= \int u \operatorname{sech}(u) \sec(\operatorname{gd}(u)) du \\&= \int u \operatorname{sech}(u) \sec(\arctan(\sinh(u))) du \\&= \int u \operatorname{sech}(u) \sqrt{1 + \tan^2(\arctan(\sinh(u)))} du \\&= \int u \operatorname{sech}(u) \sqrt{1 + \sinh^2(u)} du \\&= \int u \operatorname{sech}(u) \cosh(u) du \\&= \int u du \\&= \frac{u^2}{2} + C \\&= \frac{(\operatorname{gd}^{-1}(x))^2}{2} + C\end{aligned}$$

Question 6

M1M1M1 Correct transformation

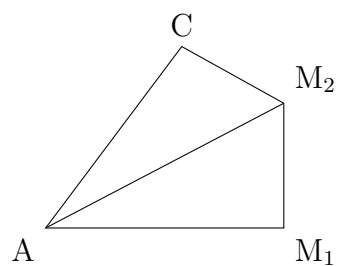
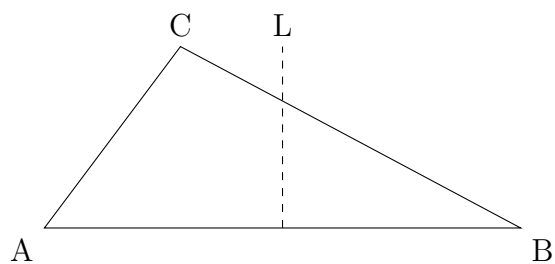


M1M1A1

$$\begin{aligned}
 \hat{BAM} &= \frac{A}{2} \\
 \tan \frac{A}{2} &= \frac{MC'}{C'A} \\
 \sin B &= \frac{MC'}{BM} \\
 a &= MC' + BM \\
 &= \frac{MC'}{\sin B} + C'A \tan \frac{A}{2} \\
 &= \frac{C'A \tan \frac{A}{2}}{\sin B} + b \tan \frac{A}{2} \\
 &= \frac{b \tan \frac{A}{2}}{\sin B} + b \tan \frac{A}{2} \\
 &= b \tan \frac{A}{2} \left(1 + \frac{1}{\sin B} \right)
 \end{aligned}$$

M1M1M1 (ii)

reflect along the perpendicular bisector of AB



M1M1A1

$$M_2\hat{A}C = A - B$$

$$a = AM_2 + CM_2$$

$$CM_2 = b \tan(M_2\hat{A}C)$$

$$CM_2 = b \tan(A - B)$$

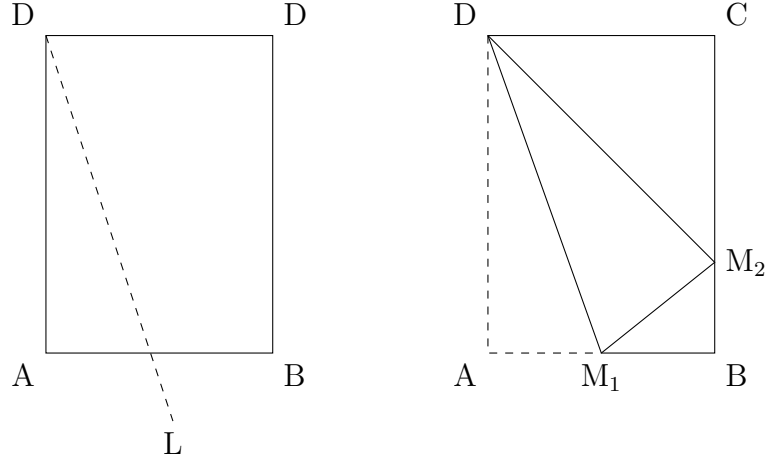
$$AM_2 = \frac{b}{\cos(M_2\hat{A}C)}$$

$$AM_2 = \frac{b}{\cos(A - B)}$$

$$a = \frac{b}{\cos(A - B)} + b \tan(A - B)$$

M1M1M1

Reflect along the perpendicular bisector of AB



M1M1M1A1

$$\text{Let } \alpha = \angle DM_1M_2 \quad \beta = \angle BM_1M_2$$

$$\angle DM_1A = \pi - \alpha - \beta$$

$$DA = DM_1 \sin(\pi - \alpha - \beta) = DM_1 \sin(\alpha + \beta)$$

$$DM_2 = DM_1 \sin(\alpha)$$

$$\angle CM_2D = \beta$$

$$CM_1 = DM_2 \cos(\beta)$$

$$= DM_1 \sin(\alpha) \cos(\beta)$$

$$M_1M_2 = DM_1 \sin(\alpha)$$

$$BM_2 = M_1M_2 \sin(\beta)$$

$$= DM_1 \cos(\alpha) \sin(\beta)$$

$$DA = CM_2 + M_2B$$

$$DM_1 \sin(\alpha + \beta) = DM_1 \cos(\alpha) \sin(\beta) + DM_1 \sin(\alpha) \cos(\beta)$$

$$\sin(\alpha + \beta) = \cos(\alpha) \sin(\beta) + \sin(\alpha) \cos(\beta)$$

B1 Because it's a reflection of a rectangle, $A + B = \pi$. However, the same argument could be made for any value of α, β by varying the height of the rectangle, and changing the dimensions of the right angled triangle on the LHS. This further extends to any α, β due to the periodicity of the sine and cosine function

Question 7

M1M1A1 This transformation is the same as a transformation mapping $y = x \tan(\theta)$ to the x -axis, reflecting, and then rotating back again:

$$\begin{aligned} \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{pmatrix} &= \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ \sin(\theta) & -\cos(\theta) \end{pmatrix} \\ &= \begin{pmatrix} \cos^2(\theta) - \sin^2(\theta) & 2\sin(\theta)\cos(\theta) \\ 2\sin(\theta)\cos(\theta) & \sin^2(\theta) - \cos^2(\theta) \end{pmatrix} \\ &= \begin{pmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{pmatrix} \end{aligned}$$

A2A2A2 (i) Considering these three cases:

Case 1: $\theta = 2\pi k$

Any curve works as it is the identity matrix

Case 2: $\theta = 2\pi k + \pi$

$y = mx$ for all m .

Case 3: $\theta \in \mathbb{R}$

$y^2 + x^2 = e^2$ for all r .

M1M1A1 (ii) Using a general matrix:

$$\begin{aligned} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ x^2 \end{pmatrix} &= \begin{pmatrix} ax + bx^2 \\ cx + dx^2 \end{pmatrix} \\ (ax + bx^2)^2 &= cx + dx^2 \\ b^2x^4 + 2abx^3 + (a^2 - d)x^2 - cx &= 0 \end{aligned}$$

The equation must be independent of x :

$$c = 0$$

$$b = 0$$

$$a^2 = d$$

$$\begin{pmatrix} \pm r & 0 \\ 0 & r^2 \end{pmatrix}$$

M1M1A1 Using a general matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ x^n \end{pmatrix} = \begin{pmatrix} ax + bx^n \\ cx + dx^n \end{pmatrix}$$

$$(ax + bx^n)^n = cx + dx^n$$

Comparing co-efficients $b = c = 0$ as before:

$$a^n x^n + dx^n a^n = d$$

$$\begin{pmatrix} \pm r & 0 \\ 0 & r^n \end{pmatrix} \text{ For even } n$$

$$\begin{pmatrix} r & 0 \\ 0 & r^n \end{pmatrix} \text{ For odd } n$$

M1A1 The general co-ordinate of a point of the curve can be written as a vector:

$$\begin{pmatrix} t \cos\left(\frac{\pi}{3}\right) - t^2 \sin\left(\frac{\pi}{3}\right) \\ t \cos\left(\frac{\pi}{3}\right) + t^2 \sin\left(\frac{\pi}{3}\right) \end{pmatrix} = \begin{pmatrix} \cos\left(\frac{\pi}{3}\right) & -\sin\left(\frac{\pi}{3}\right) \\ \sin\left(\frac{\pi}{3}\right) & \cos\left(\frac{\pi}{3}\right) \end{pmatrix} \begin{pmatrix} t \\ t^2 \end{pmatrix}$$

E1A1 This is a rotation of $\frac{\pi}{3}$ radians of an $y = x^2$ curve hence the invariant lines follows:

$$\begin{pmatrix} \pm t & 0 \\ 0 & t^2 \end{pmatrix} \begin{pmatrix} \cos\left(\frac{\pi}{3}\right) & -\sin\left(\frac{\pi}{3}\right) \\ \sin\left(\frac{\pi}{3}\right) & \cos\left(\frac{\pi}{3}\right) \end{pmatrix} = \begin{pmatrix} \pm t \cos\left(\frac{\pi}{3}\right) & \mp t \sin\left(\frac{\pi}{3}\right) \\ t^2 \sin\left(\frac{\pi}{3}\right) & t^2 \cos\left(\frac{\pi}{3}\right) \end{pmatrix}$$

Question 8

M1A1

$$\begin{aligned}ij &= k \\ij \times j &= k \times j \\-i &= kj\end{aligned}$$

M1A1

$$\begin{aligned}ji &= -k \\k \times ji &= k \times -k \\kji \times i &= -i \\-kj &= -i \\kj &= i\end{aligned}$$

A1A1 Any evidence of having calculated below:

$$\begin{aligned}ik &= j \\ki &= -j\end{aligned}$$

M2M2M2 i) Attempt to evaluate each term:

$$\begin{aligned}iqi &= iai - ib + icji + idki \\&= iia - ib - ikc - ijd \\&= -a - ib - jc - kd \\jqj &= jaj + jbij - jc + jdkj \\&= -a + jkb - jc - jid \\&= -a + ib - jc + kd \\kqk &= kak + kbik + kcjk - kd \\&= -a + kjb - kic - kd \\&= -a + ib + jc - kd\end{aligned}$$

M1A1 Summing them up and multiplying by $-\frac{1}{2}$

$$\begin{aligned}-\frac{1}{2}(q + iqi + jqj + kqk) &= -\frac{1}{2}(-2a + 2bi + 2cj + 2dk) \\&= a - b - bj - ck \\&= q^*\end{aligned}$$

M1A1 (ii) Correct factorisation

$$\begin{aligned}a + bi + cj + dk &= a + bi + (cj + dij) \\&= a + bi + (c + di)j\end{aligned}$$

M1M1A1A1

$$\begin{aligned}qq^* &= (z + wj)(z^* - wj) \\&= zz^* + w^2 - zwj + wjz^* \\(qq^*)^* &= zz^* + (w^*)^2 + z^*w^*j - w^*jz \\a^2 + b^2 + c^2 + d^2 &= qq^* \\&= zz^* + (w^*)^2 + z^*w^*j - w^*jz \\&= a^2 + b^2 + (w^*)^2 + z^*w^*j - w^*jz \\c^2 + d^2 &= (w^*)^2 + z^*w^*j - w^*jz\end{aligned}$$

Question 9

M1M1M1A1

$$\begin{aligned}\int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx &= \int_{x^{-1}(a)}^{x^{-1}(b)} \sqrt{1 + \left(\frac{\frac{dy}{dr}}{\frac{dx}{dr}}\right)^2} \frac{dx}{dr} dr \\ &= \int_{x^{-1}(a)}^{x^{-1}(b)} \sqrt{\left(\frac{dx}{dr}\right)^2 \left(1 + \left(\frac{\frac{dy}{dr}}{\frac{dx}{dr}}\right)^2\right)} dr \\ &= \int_{x^{-1}(a)}^{x^{-1}(b)} \sqrt{\left(\frac{dy}{dr}\right)^2 + \left(\frac{dx}{dr}\right)^2} dr\end{aligned}$$

M1M1

$$\begin{aligned}\frac{dx}{dr} &= 1 - \cos(\theta) \\ \frac{dy}{dr} &= -\sin(\theta)\end{aligned}$$

M2M2M2A1

Any evidence of having calculated below:

$$\begin{aligned}\int_0^\pi \sqrt{\sin^2(\theta) + (1 - \cos(\theta))^2} d\theta &= \int_0^\pi \sqrt{\sin^2(\theta) + \cos^2(\theta) + 1 - 2\cos(\theta)} d\theta \\ &= \int_0^\pi \sqrt{2 - 2\cos(\theta)} d\theta \\ &= \sqrt{2} \int_0^\pi \sqrt{1 - \cos(\theta)} d\theta \\ &= \sqrt{2} \int_0^\pi \sqrt{1 - \left(1 - 2\sin^2\left(\frac{\theta}{2}\right)\right)} d\theta \\ &= 2 \int_0^\pi \sin\left(\frac{\theta}{2}\right) d\theta \\ &= -4 \cos\left(\frac{\theta}{2}\right) \Big|_0^\pi \\ &= 4\end{aligned}$$

M2M2M2A1 Setting y to be the zero-point for gravitational potential energy.

$$\begin{aligned}\frac{1}{2}mv^2 &= mg(-y) \\ v &= \frac{ds}{dt} = \sqrt{-2gy} \\ t &= \int_0^4 \frac{1}{\sqrt{-2gy}} ds \\ &= \frac{1}{\sqrt{-2g}} \int_0^4 \frac{1}{\sqrt{y}} dy \\ &= \frac{1}{\sqrt{-2g}} \int_0^\pi \frac{1}{\sqrt{y}} \frac{ds}{d\theta} d\theta \\ &= \frac{1}{\sqrt{-2g}} \int_0^\pi \frac{\sqrt{2}\sqrt{1-\cos(\theta)}}{\sqrt{\cos(\theta)-1}} d\theta \\ &= \frac{1}{\sqrt{-2g}} \int_0^\pi \sqrt{-2} d\theta \\ &= \pi \sqrt{\frac{1}{g}}\end{aligned}$$

Question 10

M1A1A1 Any evidence of having calculated below:

$$\begin{aligned}
 e &= \frac{c}{a} = c \\
 e &= \sqrt{1 - \frac{b^2}{a^2}} \\
 c &= \sqrt{1 - b^2} \\
 \sqrt{1 - c^2} &= b
 \end{aligned}$$

E1M1M1A1 i) Horizontal component of velocity is the same. Let the angle of approach be α and of deflection β . For a co-efficient of restitution e' :

$$\begin{aligned}
 \text{NLR:} \quad e' &= \frac{u \sin \beta}{v \sin \alpha} \\
 \text{COE:} \quad \frac{1}{2}mu^2 &= \frac{1}{2}mv^2 \\
 u &= v \\
 \text{COM:} \quad u \sin \alpha &= v \sin \beta \\
 \therefore e' &= 1 \\
 \therefore \alpha &= \beta
 \end{aligned}$$

M1M1A1 ii) Let (x, y) be a point on the ellipse during the collision. The direction vector of the gradient:

$$\begin{aligned}
 x^2 + \frac{y^2}{b^2} &= 1 \\
 2x + 2y \frac{dy}{dx} \frac{1}{1 - c^2} &= 0 \\
 \frac{dy}{dx} &= \frac{x}{y}(c^2 - 1) \\
 &\rightarrow \begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix}
 \end{aligned}$$

M1M1 The direction vector of the line connecting the two foci can be written as such:

$$\begin{pmatrix} x - c \\ y \end{pmatrix} \quad \begin{pmatrix} -c - x \\ -y \end{pmatrix}$$

M1M1A1 Use of the dot product to find α :

$$\begin{aligned}
 \left| \begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \right| \cos \alpha &= \frac{\begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \cdot \begin{pmatrix} x - c \\ y \end{pmatrix}}{\sqrt{(x - c)^2 + y^2}} \\
 &= \frac{y(x(c^2 - 1) + x - c)}{\sqrt{x^2 - 2cx + c^2 + (1 - x^2)(1 - c^2)}} \\
 &= \frac{y(xc^2 - x + x - c)}{\sqrt{x^2c^2 - 2cx + 1}} \\
 &= \frac{yc(xc - 1)}{xc - 1} \\
 &= yc
 \end{aligned}$$

M1A1 Use of the dot product to find β :

$$\begin{aligned}
 \left| \begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \right| \cos \beta &= \frac{\begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \cdot \begin{pmatrix} -c - x \\ -y \end{pmatrix}}{\sqrt{(-x - c)^2 + y^2}} \\
 &= \frac{-y(x(c^2 - 1) + (x + c))}{\sqrt{x^2 + 2cx + c^2 + (1 - x^2)(1 - c^2)}} \\
 &= \frac{-y(xc^2 - x + x + c)}{\sqrt{x^2c^2 + 2cx + 1}} \\
 &= \frac{-yc(xc + 1)}{xc + 1} \\
 &= -yc
 \end{aligned}$$

M1E1A1

$$\begin{aligned}
 \left| \begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \right| \cos \alpha &= - \left| \begin{pmatrix} y \\ x(c^2 - 1) \end{pmatrix} \right| \cos \beta \\
 \cos \alpha &= -\cos \beta
 \end{aligned}$$

Cosine is an even function, hence $\alpha = \beta$ hence this the path given by an elastic collision.

Question 11

M1M1A1

$$\begin{aligned}
 \int_0^\infty x e^{-x} dx &= \int_0^\infty x \frac{d}{dx} [-e^{-x}] dx \\
 &= -x e^{-x} - \int -e^{-x} dx \Big|_0^\infty \\
 &= e^{-x} dx \Big|_0^\infty \\
 &= 1
 \end{aligned}$$

M1A1 i) The probability that a relationship will be a success:

$$\int_1^\infty e^{-x} dx = -e^{-x} \Big|_1^\infty = \frac{1}{e}$$

E1A1 The number of relationships, N , is geometrically distributed by $N \sim \text{Geo}\left(\frac{1}{e}\right)$, hence the expected number of relationships is e

M1M1A1 The expected time given a relationship has failed:

$$\begin{aligned}
 \int_0^1 x e^{-x} dx &= \int_0^1 x \frac{d}{dx} [-e^{-x}] dx \\
 &= -x e^{-x} - \int -e^{-x} dx \Big|_0^1 \\
 &= -(1+x) e^{-x} dx \Big|_0^1 \\
 &= 1 - \frac{2}{e}
 \end{aligned}$$

M1A1 Multiplying it by $E(N)$ yields $e - 2$. Including the additional successful year $E(t) = e - 1$.

E1A1 The expected number of relationships required will remain unchanged as the probability for each trial is the same, hence it remains e .

M1M1A1 Finding the expected time for a new relationship to start:

$$\begin{aligned}
 \int_0^\infty x^2 e^{-x} dx &= \int_0^\infty x^2 \frac{d}{dx} [-e^{-x}] dx \\
 &= -x^2 e^{-x} - \int -2x e^{-x} dx \Big|_0^\infty \\
 &= -x^2 e^{-x} + 2 \left(-x e^{-x} - \int -e^{-x} dx \right) dx \Big|_0^\infty \\
 &= 2
 \end{aligned}$$

E2A1 There are $N - 1$ waiting periods for the next relationship hence the expected time waiting is $2(e - 1)$. The overall waiting time is $e - 2 + 2(e - 1) = 3e - 4$. With the additional year for the last relationship to be a year, the overall time is $3e - 3$.

Question 12

M1M1M1M1

$$\begin{aligned}\frac{\sin(x)}{x} &= \left(1 - \frac{x}{\pi}\right) \left(1 + \frac{x}{\pi}\right) \left(1 - \frac{x}{2\pi}\right) \left(1 + \frac{x}{2\pi}\right) \left(1 - \frac{x}{3\pi}\right) \left(1 + \frac{x}{3\pi}\right) \dots \\ &= \left(1 - \left(\frac{x}{\pi}\right)^2\right) \left(1 - \left(\frac{x}{2\pi}\right)^2\right) \left(1 - \left(\frac{x}{3\pi}\right)^2\right)\end{aligned}$$

The mclaurin expansion of $\frac{\sin(x)}{x}$:

$$\begin{aligned}\frac{\sin(x)}{x} &= \frac{x - \frac{x^3}{3!} + \frac{x^5}{5!} \dots}{x} \\ &= 1 - \frac{x^2}{6} + \frac{x^4}{120} \dots\end{aligned}$$

M2A1 Comparing co-efficients of the x^2 term

$$\begin{aligned}-\frac{1}{\pi^2} - \frac{1}{4\pi^2} - \frac{1}{9\pi^2} \dots &= -\frac{1}{6} \\ 1 + \frac{1}{4} + \frac{1}{9} \dots &= \frac{\pi^2}{6}\end{aligned}$$

E1A1 i) The probability that a random integer is a multiple of 2 is $\frac{1}{2}$. The chance that 2 is $\frac{1}{4}$. Hence the chance that neither is $1 - \frac{1}{4}$

E1A1 The probability that a random integer is a multiple of p is $\frac{1}{p}$. The chance that 2 is $\frac{1}{p^2}$. Hence the chance that neither is $1 - \frac{1}{p}$

E2M2 Let p_n be the n th prime. The probability that they have no prime factors in common is given by:

$$\left(1 - \frac{1}{p_1^2}\right) \left(1 - \frac{1}{p_2^2}\right) \left(1 - \frac{1}{p_3^2}\right) \dots = \left[\left(\frac{1}{1 - \frac{1}{p_1^2}}\right) \left(\frac{1}{1 - \frac{1}{p_2^2}}\right) \left(\frac{1}{1 - \frac{1}{p_3^2}}\right) \dots \right]^{-1}$$

M2 By a geometric series:

$$\left[\left(\frac{1}{1 - \frac{1}{p_1^2}}\right) \left(\frac{1}{1 - \frac{1}{p_2^2}}\right) \left(\frac{1}{1 - \frac{1}{p_3^2}}\right) \dots \right]^{-1} = \left[\left(1 + \frac{1}{p_1^2} + \frac{1}{p_1^4} \dots\right) \left(1 + \frac{1}{p_2^2} + \frac{1}{p_2^4} \dots\right) \left(1 + \frac{1}{p_3^2} + \frac{1}{p_3^4} \dots\right) \right]^{-1}$$

E2A1 You can generate any number squared by multiplying it's prime numbers in the expansion. The expansion is unique to each number hence:

$$\left[\left(1 + \frac{1}{p_1^2} + \frac{1}{p_1^4} \dots \right) \left(1 + \frac{1}{p_2^2} + \frac{1}{p_2^4} \dots \right) \left(1 + \frac{1}{p_3^2} + \frac{1}{p_3^4} \dots \right) \right]^{-1} = \left[1 + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} \dots \right]^{-1} = \frac{6}{\pi^2}$$