OPERATING SYSTEMS HOMEWORK #1

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The Dining Philosophers Problem

Comments on this homework:

To be written

References:

1. Full HW description:

https://github.com/yoloseem/os-homeworks/blob/master/hw1/README.md

2. Raw source codes:

https://github.com/yoloseem/os-homeworks/tree/master/hw1

3. Commit history:

https://github.com/yoloseem/os-homeworks/commits/master/hw1

Screenshots:

To be added

Source codes:

Makefile

```
1  # Makefile
2  #
3  all: philo
4
5  clean:
6    ${RM} philo
7
8  philo:
9   ${CC} -o philo philo.c -Wno-int-to-void-pointer-cast
```

philo.c (Main source code)

```
1  /* philo.c */
2  #include <stdio.h>
3  #include <stdlib.h>
4  #include <limits.h>
5  #include <unistd.h>
6  #include <sys/time.h>
```

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```
#include <pthread.h>
    #include <semaphore.h>
9
    #define DEBUG O
10
    #define debug_print(fmt, ...) \
11
        do { if (DEBUG) fprintf(stderr, fmt, \__VA\_ARGS\_\_); } while (0)
12
    #define MAX(a, b) (a)>(b)?(a):(b)
15
    #define MIN(a, b) (a)<(b)?(a):(b)
16
    #define HUNGRY O
17
    #define EATING 1
18
    #define THINKING 2
19
20
    #define NUM_PHIL 5
21
    #define EXEC_TIME 600
22
23
    typedef struct philosopher {
^{24}
25
        unsigned short numEat;
        int state;
26
27
        long wait;
28
    } philosopher;
    philosopher phil[NUM_PHIL];
29
    char *verboseStates[] = {"HUNGRY", "EATING", "THINKING"};
30
31
    sem_t chopstick[NUM_PHIL];
32
    sem_t lock;
33
34
    int idlewait () // 10~500 msec wait
35
    {
36
        int sleepTimeMS = (rand() % 491 + 10);
37
        usleep(sleepTimeMS * 1000);
38
        return sleepTimeMS;
39
40
    }
41
    unsigned int tick () { // get current time (msec)
42
        struct timeval tv;
43
        gettimeofday(&tv, (void*)0);
44
        return tv.tv_sec * (unsigned int)1000 + tv.tv_usec / 1000;
45
    }
46
47
    void initPhil (void) {
48
        unsigned short i;
49
        for (i=0; i<NUM_PHIL; i++) {</pre>
50
            phil[i].numEat = 0;
51
            phil[i].state = THINKING;
52
            phil[i].wait = 0;
            sem_init(&chopstick[i], 0, 1);
54
55
        }
    }
56
57
```

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```
void* dining (void* arg) {
58
         unsigned short i;
59
         unsigned short left, right;
60
         unsigned int start_time;
61
 62
         unsigned int start_hungry, end_hungry;
         unsigned short phil_i = (int)arg;
63
         philosopher* curphil = &phil[phil_i];
         left = phil_i;
 65
66
         right = (phil_i + 1) % NUM_PHIL;
67
         start_time = tick();
68
         while ((tick() - start_time) / 1000 < EXEC_TIME) {</pre>
69
             // initially/still THINKING
70
             idlewait();
71
72
             // HUNGRY
73
             curphil->state = HUNGRY;
74
             start_hungry = tick();
 75
76
             // HUNGRY -- To eat, acquires chopsticks
             sem_wait(&lock);
             sem_wait(&chopstick[left]);
78
             sem_wait(&chopstick[right]);
79
             end_hungry = tick();
80
81
             // EATING
82
             curphil->state = EATING;
83
             curphil->wait += (end_hungry - start_hungry);
84
             curphil->numEat++;
85
             idlewait();
 86
             // EATING -- To think(and not hungry), release chopsticks
87
             sem_post(&chopstick[left]);
             sem_post(&chopstick[right]);
 89
             sem_post(&lock);
91
             // Stop EATING and go THINKING
92
             curphil->state = THINKING;
93
94
95
         return (void*)NULL;
96
    }
97
98
     int main (void) {
99
         pthread_t t[NUM_PHIL];
100
         unsigned short i, args[NUM_PHIL], minCount = USHRT_MAX, maxCount =0;
101
         long start, end, minWait = LONG_MAX, maxWait = 0, waitAVG = 0, waitVar = 0;
102
         double countAVG = 0, countVar = 0;
103
         void *t_return = NULL;
104
105
106
         srand(time(NULL));
         start = tick();
107
         initPhil();
108
```

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```
sem_init(&lock, 0, NUM_PHIL - 1);
109
110
         for (i=0; i<NUM_PHIL; i++) {</pre>
111
             args[i] = i;
112
113
             pthread_create(&t[i], NULL, dining, (void*)args[i]);
         }
114
         for (i=0; i<NUM_PHIL; i++) {</pre>
115
             pthread_join(t[i], &t_return);
116
         end = tick();
118
119
         for (i=0; i<NUM_PHIL; i++)</pre>
120
             sem_destroy(&chopstick[i]);
121
         sem_destroy(&lock);
122
123
         for (i=0; i<NUM_PHIL; i++) {</pre>
124
             printf("Philosopher %d eating count : %d\n", i, phil[i].numEat);
125
             printf("Philosopher %d waiting time in HUNGRY state : %ld.%03ld sec",
126
127
                     i, phil[i].wait / 1000, phil[i].wait % 1000);
             printf("\n\n");
128
             countAVG += phil[i].numEat;
129
130
             minCount = MIN(minCount, phil[i].numEat);
131
             maxCount = MAX(maxCount, phil[i].numEat);
132
             waitAVG += phil[i].wait;
133
             minWait = MIN(minWait, phil[i].wait);
134
             maxWait = MAX(maxWait, phil[i].wait);
135
136
         countAVG /= NUM_PHIL;
137
         waitAVG /= NUM_PHIL;
138
139
         for (i=0; i<NUM_PHIL; i++) {</pre>
140
             countVar += (countAVG - phil[i].numEat) * (countAVG - phil[i].numEat);
141
             waitVar += (waitAVG - phil[i].wait) * (waitAVG - phil[i].wait);
142
         countVar /= (NUM_PHIL - 1);
144
         waitVar /= (NUM_PHIL - 1);
145
146
         printf("Min count : %d\n", minCount);
147
         printf("Max count : %d\n", maxCount);
148
         printf("AVG count : %.3f\n", countAVG);
149
         printf("Count variance : %.3f\n\n", countVar);
150
         printf("Min wait time in HUNGRY state : %ld.%03ld sec\n",
151
                minWait / 1000, minWait % 1000);
152
         printf("Max wait time in HUNGRY state : %ld.%03ld sec\n",
153
                maxWait / 1000, maxWait % 1000);
154
         printf("AVG wait time in HUNGRY state : %ld.%03ld sec\n",
155
                 waitAVG / 1000, waitAVG % 1000);
157
         printf("Variance wait time in HUNGRY state : %ld.%06ld sec\n\n",
                 waitVar / 1000000, (waitVar % 1000000) / 1000);
158
         printf("Total run time : %ld.%03ld sec\n\n",
159
```

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