

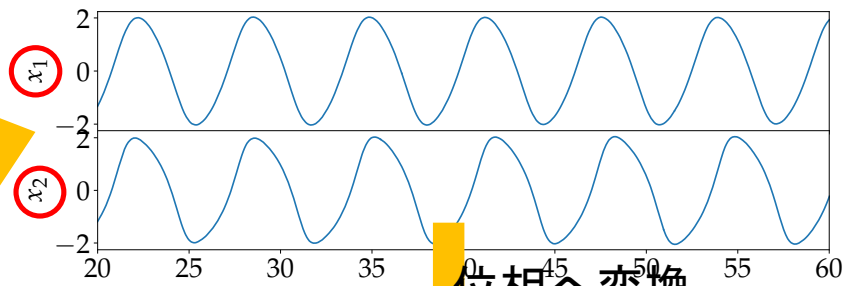
$$\dot{x}_1 = y_1 + K(x_2 - x_1) + \zeta_{x_1}(t),$$

$$\dot{y}_1 = \varepsilon_1(1 - x_1^2)y_1 - x_1 + Kx_2^2y_2 + \zeta_{y_1}(t),$$

$$\dot{x}_2 = y_2 - Kx_1^2y_1 + \zeta_{x_2}(t),$$

$$\dot{y}_2 = \varepsilon_2(1 - x_2^2)y_2 - x_2 + Kx_1y_1^2 + \zeta_{y_2}(t),$$

観測



位相へ変換

