

83,337 from 6,019 scenes for testing. NuScenes-QA showcases a wide array of question lengths, reflecting different complexity levels, making it challenging for AI models. Beyond sheer numbers, the dataset ensures a balanced range of question types and categories, from identifying objects to assessing their behavior, such as whether they are moving or parked. This design inhibits the model’s tendency to be biased or rely on linguistic shortcuts.

## 5 Conclusion

In this paper, we have provided a comprehensive survey on LLM4AD. We classify and introduce different applications employing LLMs for autonomous driving and summarize the representative approaches in each category. At the same time, we summarize the latest datasets related to LLM4AD. We will continue to monitor developments in the field and highlight future research directions.

## Ethical Statement

When applying LLMs to the field of autonomous driving, we must deeply consider their potential ethical implications. First, the illusion of the model may cause the vehicle to misunderstand the external environment or traffic conditions, thus causing safety hazards. Second, model discrimination and bias may lead to vehicles making unfair or biased decisions in different environments or when facing different groups. Additionally, false information and errors in reasoning can cause a vehicle to adopt inappropriate or dangerous driving behaviors. Inductive advice may leave the vehicle vulnerable to external interference or malicious behavior. Finally, privacy leakage is also a serious issue, as vehicles may inadvertently reveal sensitive information about the user or the surrounding environment. To sum up, we strongly recommend that before deploying a large language model to an autonomous driving system, an in-depth and detailed ethical review should be conducted to ensure that its decision-making logic is not only technically accurate but also ethically appropriate. At the same time, we call for following the principles of transparency, responsibility, and fairness to ensure the ethics and safety of technology applications. We call on the entire community to work together to ensure reliable and responsible deployment of autonomous driving technology based on large language models.

## Acknowledgments

This work was partly supported by NSFC (92370201, 62222607, 61972250) and Shanghai Municipal Science and Technology Major Project (2021SHZDZX0102).

## References

- [Anderson *et al.*, 2016] Peter Anderson, Basura Fernando, Mark Johnson, and Stephen Gould. Spice: Semantic propositional image caption evaluation, 2016.
- [Atakishiyev *et al.*, 2023] Shahin Atakishiyev, Mohammad Salameh, Hengshuai Yao, and Randy Goebel. Explainable artificial intelligence for autonomous driving: A comprehensive overview and field guide for future research directions, 2023.
- [Banerjee and Lavie, 2005] Satanjeev Banerjee and Alon Lavie. METEOR: An automatic metric for MT evaluation with improved correlation with human judgments. In Jade Goldstein, Alon Lavie, Chin-Yew Lin, and Clare Voss, editors, *Proceedings of the ACL Workshop on Intrinsic and Extrinsic Evaluation Measures for Machine Translation and/or Summarization*, pages 65–72, Ann Arbor, Michigan, June 2005. Association for Computational Linguistics.
- [Bashar *et al.*, 2022] Mk Bashar, Samia Islam, Kashifa Kawaakib Hussain, Md. Bakhtiar Hasan, A. B. M. Ashikur Rahman, and Md. Hasanul Kabir. Multiple object tracking in recent times: A literature review, 2022.
- [Bernardin and Stiefelhagen, 2008] Keni Bernardin and Rainer Stiefelhagen. Evaluating multiple object tracking performance: The clear mot metrics. *EURASIP J. Image Video Process.*, 2008, 2008.
- [Bommasani *et al.*, 2021] Rishi Bommasani, Drew A Hudson, Ehsan Adeli, Russ Altman, Simran Arora, Sydney von Arx, Michael S Bernstein, Jeannette Bohg, Antoine Bosselut, Emma Brunskill, et al. On the opportunities and risks of foundation models. *arXiv preprint arXiv:2108.07258*, 2021.
- [Brohan *et al.*, 2023a] Anthony Brohan, Noah Brown, Justice Carbajal, Yevgen Chebotar, Xi Chen, Krzysztof Choromanski, Tianli Ding, Danny Driess, Avinava Dubey, Chelsea Finn, et al. Rt-2: Vision-language-action models transfer web knowledge to robotic control. *arXiv preprint arXiv:2307.15818*, 2023.
- [Brohan *et al.*, 2023b] Anthony Brohan, Noah Brown, Justice Carbajal, Yevgen Chebotar, Xi Chen, Krzysztof Choromanski, Tianli Ding, Danny Driess, Avinava Dubey, Chelsea Finn, Pete Florence, Chuyuan Fu, Montse Gonzalez Arenas, Keerthana Gopalakrishnan, Kehang Han, Karol Hausman, Alexander Herzog, Jasmine Hsu, Brian Ichter, Alex Irpan, Nikhil Joshi, Ryan Julian, Dmitry Kalashnikov, Yuheng Kuang, Isabel Leal, Lisa Lee, Tsang-Wei Edward Lee, Sergey Levine, Yao Lu, Henryk Michalewski, Igor Mordatch, Karl Pertsch, Kanishka Rao, Krista Reymann, Michael Ryoo, Grecia Salazar, Pannag Sanketi, Pierre Sermanet, Jaspiar Singh, Anikait Singh, Radu Soricut, Huong Tran, Vincent Vanhoucke, Quan Vuong, Ayzaan Wahid, Stefan Welker, Paul Wohlhart, Jialin Wu, Fei Xia, Ted Xiao, Peng Xu, Sichun Xu, Tianhe Yu, and Brianna Zitkovich. Rt-2: Vision-language-action models transfer web knowledge to robotic control, 2023.
- [Brown *et al.*, 2020] Tom Brown, Benjamin Mann, Nick Ryder, Melanie Subbiah, Jared D Kaplan, Prafulla Dhariwal, Arvind Neelakantan, Pranav Shyam, Girish Sastry, Amanda Askell, et al. Language models are few-shot learners. *Advances in neural information processing systems*, 33:1877–1901, 2020.

- [Caesar *et al.*, 2019] Holger Caesar, Varun Bankiti, Alex H. Lang, Sourabh Vora, Venice Erin Liong, Qiang Xu, Anush Krishnan, Yu Pan, Giancarlo Baldan, and Oscar Beijbom. nuscenes: A multimodal dataset for autonomous driving. *arXiv preprint arXiv:1903.11027*, 2019.
- [Chen and Krähenbühl, 2022] Dian Chen and Philipp Krähenbühl. Learning from all vehicles. In *CVPR*, 2022.
- [Chen *et al.*, 2023a] Li Chen, Penghao Wu, Kashyap Chitta, Bernhard Jaeger, Andreas Geiger, and Hongyang Li. End-to-end autonomous driving: Challenges and frontiers. *arXiv preprint arXiv:2306.16927*, 2023.
- [Chen *et al.*, 2023b] Long Chen, Oleg Sinavski, Jan Hünermann, Alice Karnsund, Andrew James Willmott, Danny Birch, Daniel Maund, and Jamie Shotton. Driving with llms: Fusing object-level vector modality for explainable autonomous driving, 2023.
- [Cheng *et al.*, 2022] Bowen Cheng, Ishan Misra, Alexander G. Schwing, Alexander Kirillov, and Rohit Girdhar. Masked-attention mask transformer for universal image segmentation. 2022.
- [Chitta *et al.*, 2023] Kashyap Chitta, Aditya Prakash, Bernhard Jaeger, Zehao Yu, Katrin Renz, and Andreas Geiger. Transfuser: Imitation with transformer-based sensor fusion for autonomous driving. *IEEE Pattern Analysis and Machine Intelligence (PAMI)*, 2023.
- [Contributors, 2023] DriveLM Contributors. Drivelm: Drive on language. <https://github.com/OpenDriveLab/DriveLM>, 2023.
- [Cui *et al.*, 2023a] Can Cui, Yunsheng Ma, Xu Cao, Wenqian Ye, and Ziran Wang. Drive as you speak: Enabling human-like interaction with large language models in autonomous vehicles. *arXiv preprint arXiv:2309.10228*, 2023.
- [Cui *et al.*, 2023b] Can Cui, Yunsheng Ma, Xu Cao, Wenqian Ye, and Ziran Wang. Receive, reason, and react: Drive as you say with large language models in autonomous vehicles. *arXiv preprint arXiv:2310.08034*, 2023.
- [Dauner *et al.*, 2023] Daniel Dauner, Marcel Hallgarten, Andreas Geiger, and Kashyap Chitta. Parting with misconceptions about learning-based vehicle motion planning. In *CoRL*, 2023.
- [Deo *et al.*, 2021] Nachiket Deo, Eric M. Wolff, and Oscar Beijbom. Multimodal trajectory prediction conditioned on lane-graph traversals, 2021.
- [Deruyttere *et al.*, 2019] Thierry Deruyttere, Simon Vandenhende, Dusan Grujicic, Luc Van Gool, and Marie-Francine Moens. Talk2car: Taking control of your self-driving car. In *Proceedings of the 2019 Conference on Empirical Methods in Natural Language Processing and the 9th International Joint Conference on Natural Language Processing (EMNLP-IJCNLP)*. Association for Computational Linguistics, 2019.
- [Devlin *et al.*, 2018] Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. Bert: Pre-training of deep bidirectional transformers for language understanding. *arXiv preprint arXiv:1810.04805*, 2018.
- [Dewangan *et al.*, 2023] Vikrant Dewangan, Tushar Choudhary, Shivam Chandhok, Shubham Priyadarshan, Anushka Jain, Arun K. Singh, Siddharth Srivastava, Krishna Murthy Jatavallabhula, and K. Madhava Krishna. Talk2bev: Language-enhanced bird’s-eye view maps for autonomous driving, 2023.
- [Ding *et al.*, 2023] Xinpeng Ding, Jianhua Han, Hang Xu, Wei Zhang, and Xiaomeng Li. Hilm-d: Towards high-resolution understanding in multimodal large language models for autonomous driving, 2023.
- [Driess *et al.*, 2023] Danny Driess, Fei Xia, Mehdi S. M. Sajjadi, Corey Lynch, Aakanksha Chowdhery, Brian Ichter, Ayzaan Wahid, Jonathan Tompson, Quan Vuong, Tianhe Yu, Wenlong Huang, Yevgen Chebotar, Pierre Sermanet, Daniel Duckworth, Sergey Levine, Vincent Vanhoucke, Karol Hausman, Marc Toussaint, Klaus Greff, Andy Zeng, Igor Mordatch, and Pete Florence. Palm-e: An embodied multimodal language model, 2023.
- [Fong *et al.*, 2021] Whye Kit Fong, Rohit Mohan, Juana Valeria Hurtado, Lubing Zhou, Holger Caesar, Oscar Beijbom, and Abhinav Valada. Panoptic nuscenes: A large-scale benchmark for lidar panoptic segmentation and tracking. *arXiv preprint arXiv:2109.03805*, 2021.
- [Fu *et al.*, 2023a] Daocheng Fu, Xin Li, Licheng Wen, Min Dou, Pinlong Cai, Botian Shi, and Yu Qiao. Drive like a human: Rethinking autonomous driving with large language models, 2023.
- [Fu *et al.*, 2023b] Jinlan Fu, See-Kiong Ng, Zhengbao Jiang, and Pengfei Liu. Gptscore: Evaluate as you desire, 2023.
- [Gao *et al.*, 2023] Ruiyuan Gao, Kai Chen, Enze Xie, Lanqing Hong, Zhenguo Li, Dit-Yan Yeung, and Qiang Xu. Magicdrive: Street view generation with diverse 3d geometry control, 2023.
- [Gilles *et al.*, 2021] Thomas Gilles, Stefano Sabatini, Dmitry Tsishkou, Bogdan Stanculescu, and Fabien Moutarde. Gohome: Graph-oriented heatmap output for future motion estimation, 2021.
- [Goodfellow *et al.*, 2014] Ian J. Goodfellow, Jean Pouget-Abadie, Mehdi Mirza, Bing Xu, David Warde-Farley, Sherjil Ozair, Aaron Courville, and Yoshua Bengio. Generative adversarial networks, 2014.
- [Henderson and Ferrari, 2017] Paul Henderson and Vittorio Ferrari. End-to-end training of object class detectors for mean average precision, 2017.
- [Ho *et al.*, 2020] Jonathan Ho, Ajay Jain, and Pieter Abbeel. Denoising diffusion probabilistic models, 2020.
- [Höfer *et al.*, 2021] Sebastian Höfer, Kostas Bekris, Ankur Handa, Juan Camilo Gamboa, Melissa Mozifian, Florian Golemo, Chris Atkeson, Dieter Fox, Ken Goldberg, John Leonard, et al. Sim2real in robotics and automation: Applications and challenges. *IEEE transactions on automation science and engineering*, 18(2):398–400, 2021.

- [Hu *et al.*, 2023a] Anthony Hu, Lloyd Russell, Hudson Yeo, Zak Murez, George Fedoseev, Alex Kendall, Jamie Shotton, and Gianluca Corrado. Gaia-1: A generative world model for autonomous driving. *arXiv preprint arXiv:2309.17080*, 2023.
- [Hu *et al.*, 2023b] Yihan Hu, Jiazhi Yang, Li Chen, Keyu Li, Chonghao Sima, Xizhou Zhu, Siqi Chai, Senyao Du, Tianwei Lin, Wenhai Wang, et al. Planning-oriented autonomous driving. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pages 17853–17862, 2023.
- [Huang *et al.*, 2023] Junchao Huang, Xiaoqi He, and Sheng Zhao. The detection and rectification for identity-switch based on unfalsified control, 2023.
- [Jain *et al.*, 2021] Ashesh Jain, Luca Del Pero, Hugo Grimmer, and Peter Ondruska. Autonomy 2.0: Why is self-driving always 5 years away? *arXiv preprint arXiv:2107.08142*, 2021.
- [Jia *et al.*, 2021] Xiaosong Jia, Liting Sun, Masayoshi Tomizuka, and Wei Zhan. Ide-net: Interactive driving event and pattern extraction from human data. *IEEE Robotics and Automation Letters*, 6(2):3065–3072, 2021.
- [Jia *et al.*, 2022a] Xiaosong Jia, Li Chen, Penghao Wu, Jia Zeng, Junchi Yan, Hongyang Li, and Yu Qiao. Towards capturing the temporal dynamics for trajectory prediction: a coarse-to-fine approach. In *CoRL*, 2022.
- [Jia *et al.*, 2022b] Xiaosong Jia, Liting Sun, Hang Zhao, Masayoshi Tomizuka, and Wei Zhan. Multi-agent trajectory prediction by combining egocentric and allocentric views. In *Conference on Robot Learning*, pages 1434–1443. PMLR, 2022.
- [Jia *et al.*, 2023a] Xiaosong Jia, Yulu Gao, Li Chen, Junchi Yan, Patrick Langechuan Liu, and Hongyang Li. Driveadapter: Breaking the coupling barrier of perception and planning in end-to-end autonomous driving, 2023.
- [Jia *et al.*, 2023b] Xiaosong Jia, Penghao Wu, Li Chen, Yu Liu, Hongyang Li, and Junchi Yan. Hdgt: Heterogeneous driving graph transformer for multi-agent trajectory prediction via scene encoding. *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, 2023.
- [Jia *et al.*, 2023c] Xiaosong Jia, Penghao Wu, Li Chen, Jiangwei Xie, Conghui He, Junchi Yan, and Hongyang Li. Think twice before driving: Towards scalable decoders for end-to-end autonomous driving, 2023.
- [Jin *et al.*, 2023a] Bu Jin, Xinyu Liu, Yupeng Zheng, Pengfei Li, Hao Zhao, Tong Zhang, Yuhang Zheng, Guyue Zhou, and Jingjing Liu. Adapt: Action-aware driving caption transformer, 2023.
- [Jin *et al.*, 2023b] Ye Jin, Xiaoxi Shen, Huiling Peng, Xiaohan Liu, Jingli Qin, Jiayang Li, Jintao Xie, Peizhong Gao, Guyue Zhou, and Jiangtao Gong. Surrealdriver: Designing generative driver agent simulation framework in urban contexts based on large language model, 2023.
- [Keysan *et al.*, 2023] Ali Keysan, Andreas Look, Eitan Kosman, Gonca Gürsun, Jörg Wagner, Yu Yao, and Barbara Rakitsch. Can you text what is happening? integrating pre-trained language encoders into trajectory prediction models for autonomous driving, 2023.
- [Khachatryan *et al.*, 2023] Levon Khachatryan, Andranik Movsisyan, Vahram Tadevosyan, Roberto Henschel, Zhangyang Wang, Shant Navasardyan, and Humphrey Shi. Text2video-zero: Text-to-image diffusion models are zero-shot video generators, 2023.
- [Kim *et al.*, 2018] Jinkyu Kim, Anna Rohrbach, Trevor Darrell, John Canny, and Zeynep Akata. Textual explanations for self-driving vehicles. *Proceedings of the European Conference on Computer Vision (ECCV)*, 2018.
- [Kim *et al.*, 2019a] Jinkyu Kim, Teruhisa Misu, Yi-Ting Chen, Ashish Tawari, and John Canny. Grounding human-to-vehicle advice for self-driving vehicles, 2019.
- [Kim *et al.*, 2019b] Jinkyu Kim, Teruhisa Misu, Yi-Ting Chen, Ashish Tawari, and John Canny. Grounding human-to-vehicle advice for self-driving vehicles. In *The IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2019.
- [Kingma and Welling, 2022] Diederik P Kingma and Max Welling. Auto-encoding variational bayes, 2022.
- [Li *et al.*, 2022a] Hongyang Li, Chonghao Sima, Jifeng Dai, Wenhai Wang, Lewei Lu, Huijie Wang, Jia Zeng, Zhiqi Li, Jiazhi Yang, Hanming Deng, Hao Tian, Enze Xie, Jiangwei Xie, Li Chen, Tianyu Li, Yang Li, Yulu Gao, Xiaosong Jia, Si Liu, Jianping Shi, Dahua Lin, and Yu Qiao. Delving into the devils of bird’s-eye-view perception: A review, evaluation and recipe. *arXiv preprint arXiv:2209.05324*, 2022.
- [Li *et al.*, 2022b] Junnan Li, Dongxu Li, Caiming Xiong, and Steven Hoi. Blip: Bootstrapping language-image pre-training for unified vision-language understanding and generation, 2022.
- [Li *et al.*, 2022c] Zhiqi Li, Wenhai Wang, Hongyang Li, Enze Xie, Chonghao Sima, Tong Lu, Yu Qiao, and Jifeng Dai. Bevformer: Learning bird’s-eye-view representation from multi-camera images via spatiotemporal transformers. In *ECCV*, pages 1–18. Springer, 2022.
- [Li *et al.*, 2023a] Junnan Li, Dongxu Li, Silvio Savarese, and Steven Hoi. Blip-2: Bootstrapping language-image pre-training with frozen image encoders and large language models, 2023.
- [Li *et al.*, 2023b] Tianyu Li, Li Chen, Huijie Wang, Yang Li, Jiazhi Yang, Xiangwei Geng, Shengyin Jiang, Yuting Wang, Hang Xu, Chunjing Xu, Junchi Yan, Ping Luo, and Hongyang Li. Graph-based topology reasoning for driving scenes. *arXiv preprint arXiv:2304.05277*, 2023.
- [Li *et al.*, 2023c] Xiaofan Li, Yifu Zhang, and Xiaoqing Ye. Drivingdiffusion: Layout-guided multi-view driving scene video generation with latent diffusion model. *arXiv preprint arXiv:2310.07771*, 2023.
- [Liang *et al.*, 2020] Ming Liang, Bin Yang, Wenyuan Zeng, Yun Chen, Rui Hu, Sergio Casas, and Raquel Urtasun.

- Pnpnet: End-to-end perception and prediction with tracking in the loop. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pages 11553–11562, 2020.
- [Lin *et al.*, 2023] Zhiqiu Lin, Samuel Yu, Zhiyi Kuang, Deepak Pathak, and Deva Ramanan. Multimodality helps unimodality: Cross-modal few-shot learning with multi-modal models, 2023.
- [Liu *et al.*, 2023a] Haotian Liu, Chunyuan Li, Qingyang Wu, and Yong Jae Lee. Visual instruction tuning, 2023.
- [Liu *et al.*, 2023b] Jiaqi Liu, Peng Hang, Xiao qi, Jianqiang Wang, and Jian Sun. Mtd-gpt: A multi-task decision-making gpt model for autonomous driving at unsignalized intersections, 2023.
- [Liu *et al.*, 2023c] Yang Liu, Dan Iter, Yichong Xu, Shuo-hang Wang, Ruochen Xu, and Chenguang Zhu. G-eval: Nlg evaluation using gpt-4 with better human alignment, 2023.
- [Liu *et al.*, 2023d] Zhijian Liu, Haotian Tang, Alexander Amini, Xingyu Yang, Huizi Mao, Daniela Rus, and Song Han. Bevfusion: Multi-task multi-sensor fusion with unified bird’s-eye view representation. In *ICRA*, 2023.
- [Luo *et al.*, 2018] Wenjie Luo, Bin Yang, and Raquel Urtasun. Fast and furious: Real time end-to-end 3d detection, tracking and motion forecasting with a single convolutional net. In *Proceedings of the IEEE conference on Computer Vision and Pattern Recognition*, pages 3569–3577, 2018.
- [Luo *et al.*, 2023a] Ruipu Luo, Ziwang Zhao, Min Yang, Junwei Dong, Da Li, Pengcheng Lu, Tao Wang, Linmei Hu, Minghui Qiu, and Zhongyu Wei. Valley: Video assistant with large language model enhanced ability, 2023.
- [Luo *et al.*, 2023b] Zhengxiong Luo, Dayou Chen, Yingya Zhang, Yan Huang, Liang Wang, Yujun Shen, Deli Zhao, Jingren Zhou, and Tieniu Tan. Videofusion: Decomposed diffusion models for high-quality video generation, 2023.
- [Malla *et al.*, 2023] Srikanth Malla, Chiho Choi, Isht Dwivedi, Joon Hee Choi, and Jiachen Li. Drama: Joint risk localization and captioning in driving. In *Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision*, pages 1043–1052, 2023.
- [Mao *et al.*, 2023] Jiageng Mao, Yuxi Qian, Hang Zhao, and Yue Wang. Gpt-driver: Learning to drive with gpt. *arXiv preprint arXiv:2310.01415*, 2023.
- [OpenAI, 2023] OpenAI. Gpt-4 technical report, 2023.
- [Ouyang *et al.*, 2022] Long Ouyang, Jeff Wu, Xu Jiang, Diogo Almeida, Carroll L. Wainwright, Pamela Mishkin, Chong Zhang, Sandhini Agarwal, Katarina Slama, Alex Ray, John Schulman, Jacob Hilton, Fraser Kelton, Luke Miller, Maddie Simens, Amanda Askell, Peter Welinder, Paul Christiano, Jan Leike, and Ryan Lowe. Training language models to follow instructions with human feedback, 2022.
- [P *et al.*, 2023] Jishnu Jaykumar P, Kamalesh Palanisamy, Yu-Wei Chao, Xinya Du, and Yu Xiang. Proto-clip: Vision-language prototypical network for few-shot learning, 2023.
- [Papineni *et al.*, 2002] Kishore Papineni, Salim Roukos, Todd Ward, and Wei-Jing Zhu. Bleu: a method for automatic evaluation of machine translation. In *Proceedings of the 40th annual meeting on association for computational linguistics*, pages 311–318. Association for Computational Linguistics, 2002.
- [Parmar *et al.*, 2022] Gaurav Parmar, Richard Zhang, and Jun-Yan Zhu. On aliased resizing and surprising subtleties in gan evaluation, 2022.
- [Qian *et al.*, 2023] Tianwen Qian, Jingjing Chen, Linhai Zhuo, Yang Jiao, and Yu-Gang Jiang. Nuscenes-qa: A multi-modal visual question answering benchmark for autonomous driving scenario. *arXiv preprint arXiv:2305.14836*, 2023.
- [Radford *et al.*, 2018] Alec Radford, Karthik Narasimhan, Tim Salimans, Ilya Sutskever, et al. Improving language understanding by generative pre-training. 2018.
- [Radford *et al.*, 2019] Alec Radford, Jeffrey Wu, Rewon Child, David Luan, Dario Amodei, Ilya Sutskever, et al. Language models are unsupervised multitask learners. *OpenAI blog*, 1(8):9, 2019.
- [Radford *et al.*, 2021] Alec Radford, Jong Wook Kim, Chris Hallacy, Aditya Ramesh, Gabriel Goh, Sandhini Agarwal, Girish Sastry, Amanda Askell, Pamela Mishkin, Jack Clark, Gretchen Krueger, and Ilya Sutskever. Learning transferable visual models from natural language supervision, 2021.
- [Ramesh *et al.*, 2022] Aditya Ramesh, Prafulla Dhariwal, Alex Nichol, Casey Chu, and Mark Chen. Hierarchical text-conditional image generation with clip latents, 2022.
- [Rezatofighi *et al.*, 2019] Hamid Rezatofighi, Nathan Tsoi, JunYoung Gwak, Amir Sadeghian, Ian Reid, and Silvio Savarese. Generalized intersection over union: A metric and a loss for bounding box regression, 2019.
- [Rezende and Mohamed, 2016] Danilo Jimenez Rezende and Shakir Mohamed. Variational inference with normalizing flows, 2016.
- [Rombach *et al.*, 2021] Robin Rombach, Andreas Blattmann, Dominik Lorenz, Patrick Esser, and Björn Ommer. High-resolution image synthesis with latent diffusion models, 2021.
- [Ronneberger *et al.*, 2015] Olaf Ronneberger, Philipp Fischer, and Thomas Brox. U-net: Convolutional networks for biomedical image segmentation, 2015.
- [Sachdeva *et al.*, 2023] Enna Sachdeva, Nakul Agarwal, Suhas Chundi, Sean Roelofs, Jiachen Li, Behzad Dariush, Chiho Choi, and Mykel Kochenderfer. Rank2tell: A multimodal driving dataset for joint importance ranking and reasoning. *arXiv preprint arXiv:2309.06597*, 2023.
- [Sadat *et al.*, 2020] Abbas Sadat, Sergio Casas, Mengye Ren, Xinyu Wu, Pranaab Dhawan, and Raquel Urtasun. Perceive, predict, and plan: Safe motion planning

- through interpretable semantic representations. In *Computer Vision–ECCV 2020: 16th European Conference, Glasgow, UK, August 23–28, 2020, Proceedings, Part XXIII 16*, pages 414–430. Springer, 2020.
- [Sha *et al.*, 2023] Hao Sha, Yao Mu, Yuxuan Jiang, Li Chen, Chenfeng Xu, Ping Luo, Shengbo Eben Li, Masayoshi Tomizuka, Wei Zhan, and Mingyu Ding. Languagempc: Large language models as decision makers for autonomous driving. *arXiv preprint arXiv:2310.03026*, 2023.
- [Shi *et al.*, 2022] Shaoshuai Shi, Li Jiang, Dengxin Dai, and Bernt Schiele. Motion transformer with global intention localization and local movement refinement. *Advances in Neural Information Processing Systems*, 35:6531–6543, 2022.
- [Shukor *et al.*, 2023] Mustafa Shukor, Corentin Dancette, and Matthieu Cord. ep-alm: Efficient perceptual augmentation of language models, 2023.
- [Swerdlow *et al.*, 2023] Alexander Swerdlow, Runsheng Xu, and Bolei Zhou. Street-view image generation from a bird’s-eye view layout. *arXiv preprint arXiv:2301.04634*, 2023.
- [Tang *et al.*, 2023] Yun Tang, Antonio A. Bruto da Costa, Jason Zhang, Irvine Patrick, Siddhartha Khastgir, and Paul Jennings. Domain knowledge distillation from large language model: An empirical study in the autonomous driving domain, 2023.
- [Taran *et al.*, 2018] Vlad Taran, Nikita Gordienko, Yuriy Kochura, Yuri Gordienko, Alexandr Rokovyi, Oleg Alienin, and Sergii Stirenko. Performance evaluation of deep learning networks for semantic segmentation of traffic stereo-pair images. In *Proceedings of the 19th International Conference on Computer Systems and Technologies*. ACM, sep 2018.
- [Touvron *et al.*, 2023] Hugo Touvron, Thibaut Lavril, Gautier Izacard, Xavier Martinet, Marie-Anne Lachaux, Timothée Lacroix, Baptiste Rozière, Naman Goyal, Eric Hambro, Faisal Azhar, Aurelien Rodriguez, Armand Joulin, Edouard Grave, and Guillaume Lample. Llama: Open and efficient foundation language models, 2023.
- [Treiber *et al.*, 2000] Martin Treiber, Ansgar Hennecke, and Dirk Helbing. Congested traffic states in empirical observations and microscopic simulations. *Physical review E*, 62(2):1805, 2000.
- [Unterthiner *et al.*, 2019] Thomas Unterthiner, Sjoerd van Steenkiste, Karol Kurach, Raphael Marinier, Marcin Michalski, and Sylvain Gelly. Towards accurate generative models of video: A new metric and challenges, 2019.
- [Vedantam *et al.*, 2015] Ramakrishna Vedantam, C. Lawrence Zitnick, and Devi Parikh. Cider: Consensus-based image description evaluation, 2015.
- [Wang *et al.*, 2023a] Jiaan Wang, Yunlong Liang, Fandong Meng, Zengkui Sun, Haoxiang Shi, Zhixu Li, Jinan Xu, Jianfeng Qu, and Jie Zhou. Is chatgpt a good nlg evaluator? a preliminary study, 2023.
- [Wang *et al.*, 2023b] Xiaofeng Wang, Zheng Zhu, Guan Huang, Xinze Chen, and Jiwen Lu. Drivedreamer: Towards real-world-driven world models for autonomous driving. *arXiv preprint arXiv:2309.09777*, 2023.
- [Wen *et al.*, 2023] Licheng Wen, Daocheng Fu, Xin Li, Xinyu Cai, Tao Ma, Pinlong Cai, Min Dou, Botian Shi, Liang He, and Yu Qiao. Dilu: A knowledge-driven approach to autonomous driving with large language models. *arXiv preprint arXiv:2309.16292*, 2023.
- [Wu *et al.*, 2022a] Penghao Wu, Li Chen, Hongyang Li, Xiaosong Jia, Junchi Yan, and Yu Qiao. Policy pre-training for autonomous driving via self-supervised geometric modeling. In *The Eleventh International Conference on Learning Representations*, 2022.
- [Wu *et al.*, 2022b] Penghao Wu, Xiaosong Jia, Li Chen, Junchi Yan, Hongyang Li, and Yu Qiao. Trajectory-guided control prediction for end-to-end autonomous driving: A simple yet strong baseline, 2022.
- [Wu *et al.*, 2023] Dongming Wu, Wencheng Han, Tiancai Wang, Yingfei Liu, Xiangyu Zhang, and Jianbing Shen. Language prompt for autonomous driving, 2023.
- [Xu *et al.*, 2021a] Li Xu, He Huang, and Jun Liu. Sutd-trafficqa: A question answering benchmark and an efficient network for video reasoning over traffic events. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, pages 9878–9888, June 2021.
- [Xu *et al.*, 2021b] Li Xu, He Huang, and Jun Liu. Sutd-trafficqa: A question answering benchmark and an efficient network for video reasoning over traffic events, 2021.
- [Xu *et al.*, 2022] Danfei Xu, Yuxiao Chen, Boris Ivanovic, and Marco Pavone. Bits: Bi-level imitation for traffic simulation, 2022.
- [Xu *et al.*, 2023] Zhenhua Xu, Yujia Zhang, Enze Xie, Zhen Zhao, Yong Guo, Kwan-Yee K. Wong, Zhenguo Li, and Hengshuang Zhao. Drivegpt4: Interpretable end-to-end autonomous driving via large language model, 2023.
- [Yang *et al.*, 2023a] Kairui Yang, Enhui Ma, Jibin Peng, Qing Guo, Di Lin, and Kaicheng Yu. Bevcontrol: Accurately controlling street-view elements with multi-perspective consistency via bev sketch layout. *arXiv preprint arXiv:2308.01661*, 2023.
- [Yang *et al.*, 2023b] Zhengyuan Yang, Linjie Li, Kevin Lin, Jianfeng Wang, Chung-Ching Lin, Zicheng Liu, and Lijuan Wang. The dawn of Imms: Preliminary explorations with gpt-4v(ision), 2023.
- [Yin *et al.*, 2021] Tianwei Yin, Xingyi Zhou, and Philipp Krähenbühl. Center-based 3d object detection and tracking, 2021.
- [Zeng *et al.*, 2022] Fangao Zeng, Bin Dong, Yuang Zhang, Tiancai Wang, Xiangyu Zhang, and Yichen Wei. Motr: End-to-end multiple-object tracking with transformer. In *European Conference on Computer Vision (ECCV)*, 2022.
- [Zhang *et al.*, 2023a] Hang Zhang, Xin Li, and Lidong Bing. Video-llama: An instruction-tuned audio-visual

language model for video understanding. *arXiv preprint arXiv:2306.02858*, 2023.

[Zhang *et al.*, 2023b] Siyao Zhang, Daocheng Fu, Zhao Zhang, Bin Yu, and Pinlong Cai. Trafficgpt: Viewing, processing and interacting with traffic foundation models. *arXiv preprint arXiv:2309.06719*, 2023.

[Zhong *et al.*, 2022] Ziyuan Zhong, Davis Rempe, Danfei Xu, Yuxiao Chen, Sushant Veer, Tong Che, Baishakhi Ray, and Marco Pavone. Guided conditional diffusion for controllable traffic simulation, 2022.

[Zhong *et al.*, 2023] Ziyuan Zhong, Davis Rempe, Yuxiao Chen, Boris Ivanovic, Yulong Cao, Danfei Xu, Marco Pavone, and Baishakhi Ray. Language-guided traffic simulation via scene-level diffusion, 2023.