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# Deep Langevin FTS

Langevin Field-Theoretic Simulation (L-FTS) Accelerated by Deep Learning (DL)

### **Features**

- L-FTS incorporated with DL
- · AB Diblock Copolymer Melt
- · Chain Model: Continuous, Discrete
- · Periodic Boundaries
- Pseudospectral Method
- · Platforms: CUDA

# Dependencies

Linux System

Anaconda

Langevin FTS

L-FTS for Python

https://github.com/yongdd/langevin-fts

## Installation

Langevin FTS, PyTorch and PyTorch-lightning should be installed in the same virtual environment. For instance, if you have installed Langevin FTS in virtual environment lfts, install PyTorch and PyTorch-lightning after activating lfts using the following commands. (Assuming the name of your virtual environment is lfts)

```
conda activate lfts
git clone https://github.com/yongdd/deep-langevin-fts.git
conda install pip protobuf=3.19 matplotlib pytorch \
torchvision torchaudio cudatoolkit=11.3 -c pytorch
pip install pytorch-lightning
```

The above commands will install the following libraries.

**PyTorch** 

An open source machine learning framwork https://pytorch.org/get-started/locally/

PyTorch-lightning

High-level interface for PyTorch

https://www.pytorchlightning.ai/

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After the installation, you can run python test\_performance.py in examples/Gyroid folder, which performs a L-FTS with a pretrained model to test your installation. You can compare its performance with Anderson mixing by repeating simulation after setting use\_deep\_learning=False in test\_performance.py.

## Usage

#### 1. Set Simulation Parameters

```
vi input_parameters.yaml
```

Edit input\_parameters.yaml. All the system parameters are stored in this file. If you do not want to touch the DL part, only edit this file and proceed. If you want to use a pre-trained model stored in examples folder, go to step 4.

2. Generate Training Data

```
python make_training_data.py
```

Initial fields are currently for gyroid phase. You may need to change the initial fields by modifying w\_plus and w\_minus in make\_training\_data.py. Training data will be stored in data\_training folder, and it will generate LastTrainingStep.mat file. A sample LastTrainingStep.mat file already exists, and this file or the generated file will be used as inital field for find\_best\_epoch.py and run\_simulation.py.

3. Train a Neural Network

```
python train.py
```

If you are plan to use multiple GPUs for training, edit gpus in train.py. To obtain the same training results using multiple GPUs, you need to change batch\_size so that gpus \* batch\_size does not change. For example, if you use 4 GPUs, set gpus=4 and batch\_size=8, which is effectively the same as setting gpus=1 and batch\_size=32. For each epoch, the weights of model will be stored in saved\_model\_weights folder.

```
python find_best_epoch.py
```

Lastly, find\_best\_epoch.py will tell you which training result is the best, and it will copy the weights of best epoch as best\_epoch.pth. A sample file already exists. The training result is not always the same. If you are not satisfied with the result, run train.py once again.

4. Run Simulation

```
python run_simulation.py
```

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This will use best\_epoch.pth obtained at the previous step. You can use a pre-trained model in examples folder instead. For example, set model\_file = "example/Gyroid/gyroid\_atr\_cas\_mish\_32.pth" if you want to run simulation for gyroid phase. Polymer density, fields and structure function will be recored in data\_simulation folder.

### **Notes**

- Matlab and Python scripts for visualization and renormalization are provided in tools folder of yongdd/langevin-fts repository.
- In examples folder, input fields obatained using SCFT, yaml files for input parameters, pre-trained model weights, and field configurations at equilibrium states for several known BCP morphologies are provided.
- Currently, the best neural network model is LitAtrousCascadeMish in model/model/atr\_cas\_mish.py, and it is set as default model in train.py and inference\_net.py.

## Citation

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