# Bayesian, Logistic Regression, Naive Bayesian

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September 2018

Bayesian Formula:

$$P(l|d) = \frac{P(d|l)P(l)}{P(d)} = \frac{P(d|l)P(l)}{\sum_{i} P(d|l_{i})P(l_{i})}$$
(1)

#### Two Classes 1

For a two class problem, the posterior probability for class  $L_1$  given data d can be written as

$$P(L_1|d) = \frac{P(d|L_1)P(L_1)}{P(d|L_1)P(L_1) + P(d|L_2)P(L_2)}$$
(2)

$$= \frac{1}{1 + \frac{P(d|L_2)P(L_2)}{P(d|L_1)P(L_1)}} \tag{3}$$

$$= \frac{1}{1 + \frac{P(d|L_1)P(L_2)}{P(d|L_1)P(L_1)}}$$

$$= \frac{1}{1 + \exp\left(-\ln\frac{P(d|L_1)P(L_1)}{P(d|L_2)P(L_2)}\right)}$$
(4)

Let's define the **logistic sigmoid** function  $\sigma(z)$  by

$$\sigma(z) = \frac{1}{1 + \exp(-z)} \tag{5}$$

The inverse of the logistic sigmoid, known as the logit function is given by

$$z = \ln\left(\frac{\sigma}{1 - \sigma}\right) \tag{6}$$

which represents the log of the ratio of probabilities  $\ln(P(L_1|d)/P(L_2|d))$  for the two classes. This is known as the log odds.

Now, let's make a linear model for the log odds:

$$z = \ln \frac{P(d|L_1)P(L_1)}{P(d|L_2)P(L_2)} = \sum_i w_i f_i + w_0 = \boldsymbol{w}^{\top} \boldsymbol{f}$$
 (7)

where  $f_i$  is i-th feature value of the data d,  $w_i$  and  $w_0$  are parameters for linear modeling. This model is known as logistic regression in the terminology of statistics.

### 1.1 Problem Solving

For a data set  $\{d_n, y_n\}$  where  $y_n \in \{0, 1\}$ , and n = 1, ..., N. The likelihood function can be written

$$P(y_1, ..., y_n | w_0, ..., w_n) = \prod_{n=1}^{N} p_n^{y_n} (1 - p_n)^{1 - y_n}$$
(8)

where  $p_n = P(L_1|d_n)$ .

As usual, we can define an error function by taking the negative logarithm of the likelihood, which gives the **cross-entropy** error function in the form

$$E(\mathbf{w}) = -\ln P(\mathbf{y}|\mathbf{w}) = -\sum_{n=1}^{N} \{y_n \ln p_n + (1 - y_n) \ln(1 - p_n)\}$$
(9)

where  $p_n = P(L_1|d_n) = \sigma(z_n)$  and  $z_n = \boldsymbol{w}^{\top} \boldsymbol{f}$ .

## 2 Naive Bayes

Conditional independence property:

$$p(f_1, f_2|L) = p(f_1|L)p(f_2|L)$$
(10)

Then the posterior probability is given by

$$p(L_k|f_1, f_2) = \frac{p(f_1, f_2|L_k)p(L_k)}{\sum_i p(f_1, f_2|L_i)p(L_i)}$$
(11)

$$\propto p(f_1, f_2 | L_k) p(L_k) \tag{12}$$

$$\propto p(f_1|L_k)p(f_2|L_k)p(L_k) \tag{13}$$

This is utilized for Naive Bayes Models. That is, the posterior distribution over the class variable L under the conditional independence assumption is given by

$$p(L_k|f_1, ..., f_n) = \frac{1}{Z}p(L_k) \prod_{i=1}^n p(f_i|L_k)$$
(14)

where Z is the **evidence** 

$$Z = p(f_1, ..., f_n) = \sum_{i} p(L_i) p(f_1, ..., f_n | L_i)$$
(15)

which is a scaling factor dependent only on  $f_1, ..., f_n$ . Note that Z is a constant if the values of the feature variables  $f_i$  are known and fixed.

## 2.1 Problem solving

$$\hat{L} = \underset{k \in \{1, \dots, K\}}{\arg \max} \quad p(L_k) \prod_{i=1}^{n} p(f_i | L_k)$$
(16)

The class probability  $L_k$  can be estimated from the data population, and the feature likelihood  $p(f|L_k)$  is modeled based on the characteristics of the features.

• Gaussian naive Bayes

$$p(f = f|L_k) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left[-\frac{(f - \mu_k)^2}{2\sigma_k^2}\right]$$
 (17)

• Bernoulli naive Bayes

$$p(f_1, ..., f_n) = \prod_{i=1}^n p_{ki}^{f_i} (1 - p_{ki})^{(1 - f_i)}$$
(18)

where  $f_i$  is a boolean variable expressing the occurrence or absence of the i-th feature from the feature vocabulary, and  $p_{ki}$  is the probability of class  $L_k$  generating the feature  $f_i$ . The probability  $p_{ki}$  must be learned before inference.

• Multinomial naive Bayes.

# Bibliography

https://en.wikipedia.org/wiki/Naive\_Bayes\_classifier

Bishop, Pattern Recognition and Machine Learning, Springer 2006.