

Debiased Front-Door Learners for Heterogeneous Effects

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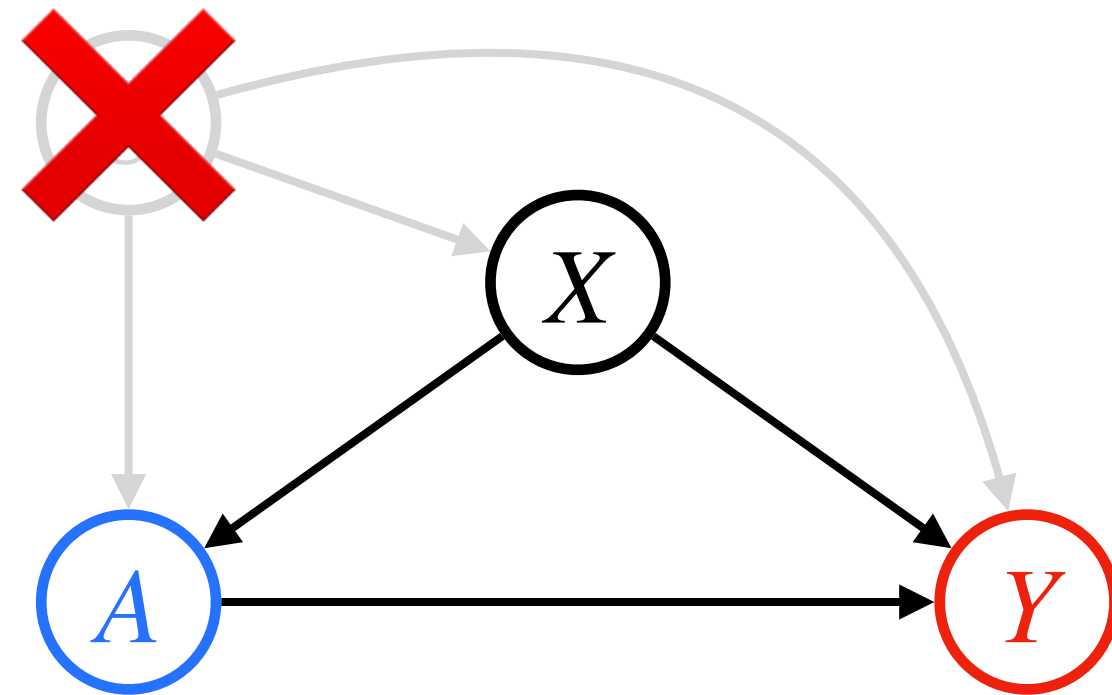
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2025 CDSM

No Unmeasured Confounder Assumptions



Between treatments A and outcomes Y ,
all confounder are measured (as X)

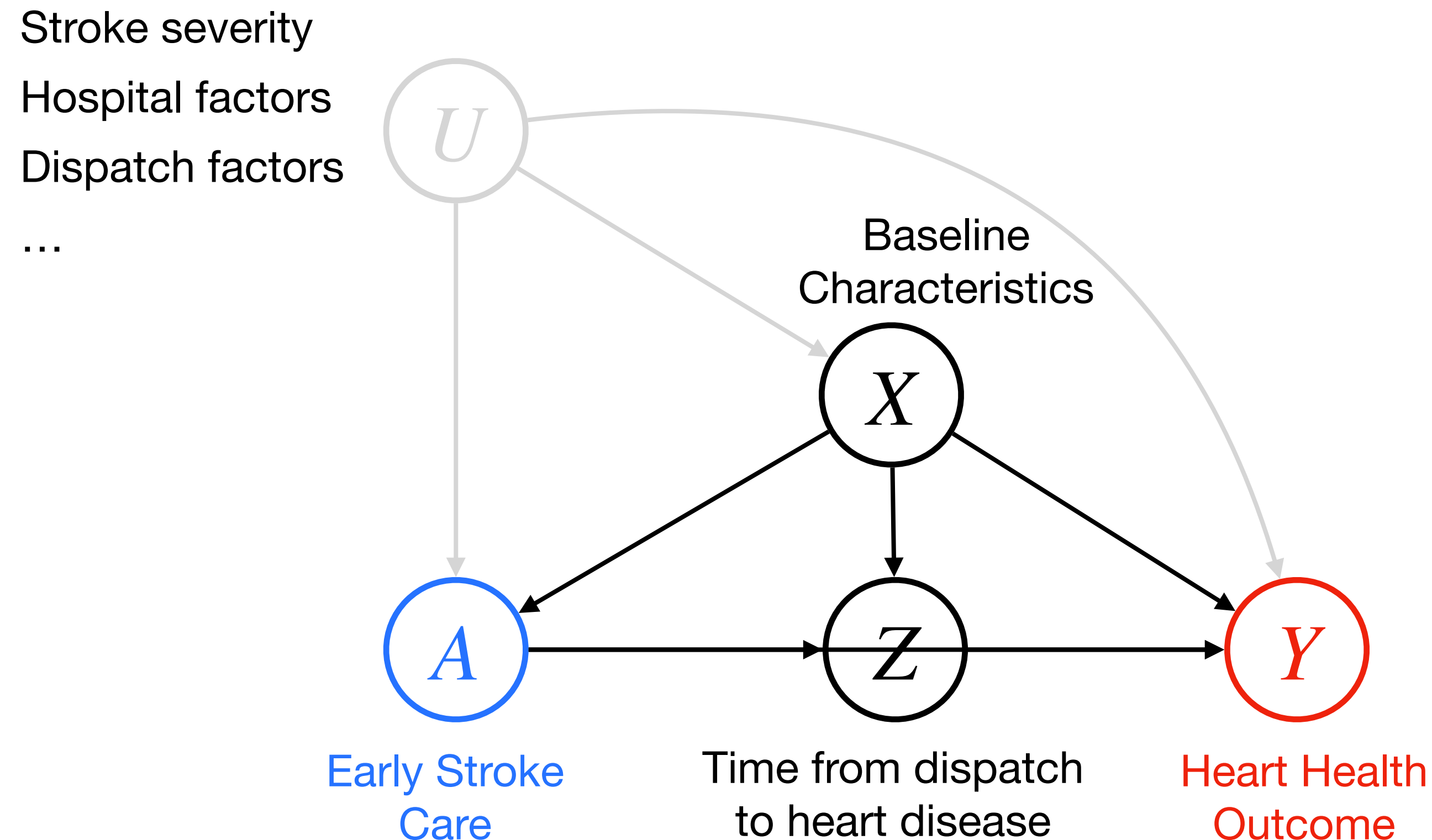
Unmeasured confounders U doesn't exist.

⚠ Hardly satisfied in practice

Non-identifiable causal effects

A	U	Y
Smoking	Genetic Factor	Cancer
Attendance	Motivation	GPA
Treatment	Disease history	Recovery
Job training	Economic trend	Hiring status

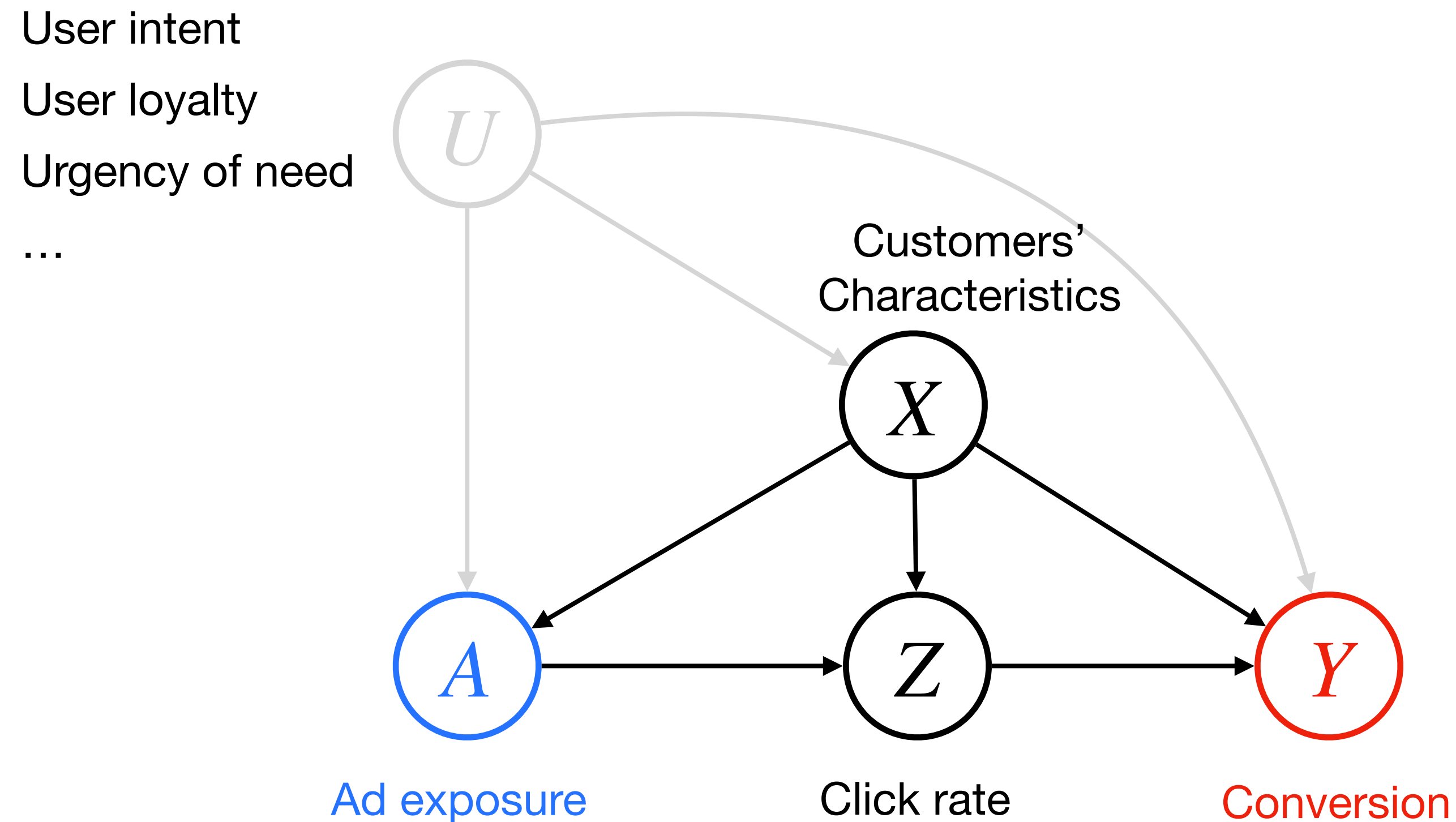
Leveraging Mediators: Public Health



$$\mathbb{E}[Y \mid \text{do}(a)] = \sum_{z, a', x} \mathbb{E}[Y \mid \text{do}(a)] P(z \mid a, x) P(a', x)$$

“Front-door adjustment”

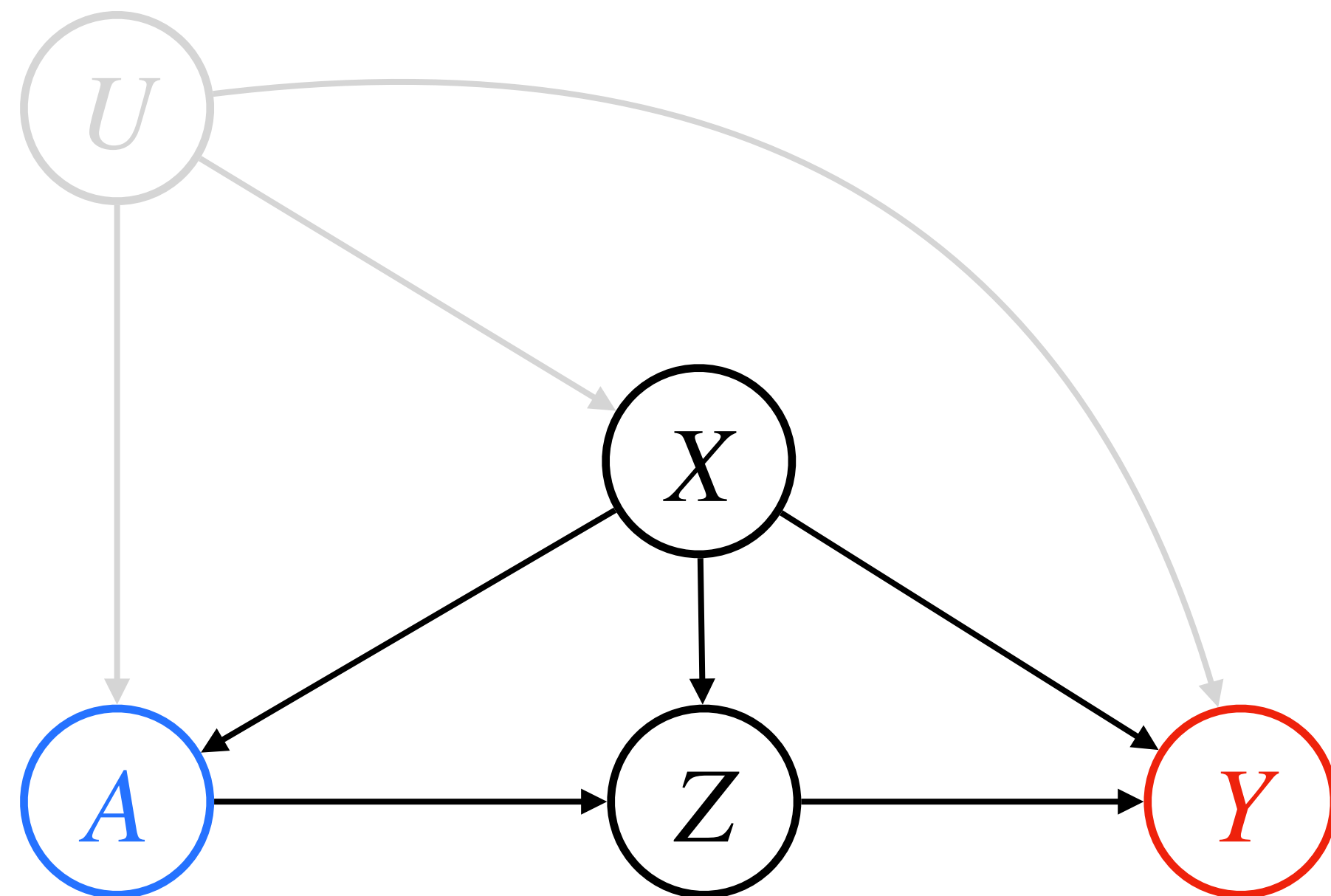
Leveraging Mediators: Digital Experiments



$$\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{a})] = \sum_{z, a', x} \mathbb{E}[\textcolor{red}{Y} \mid z, a', x] P(z \mid \textcolor{blue}{a}, x) P(a', x)$$

“Front-door adjustment”

Front-Door Model



Front-Door Criterion

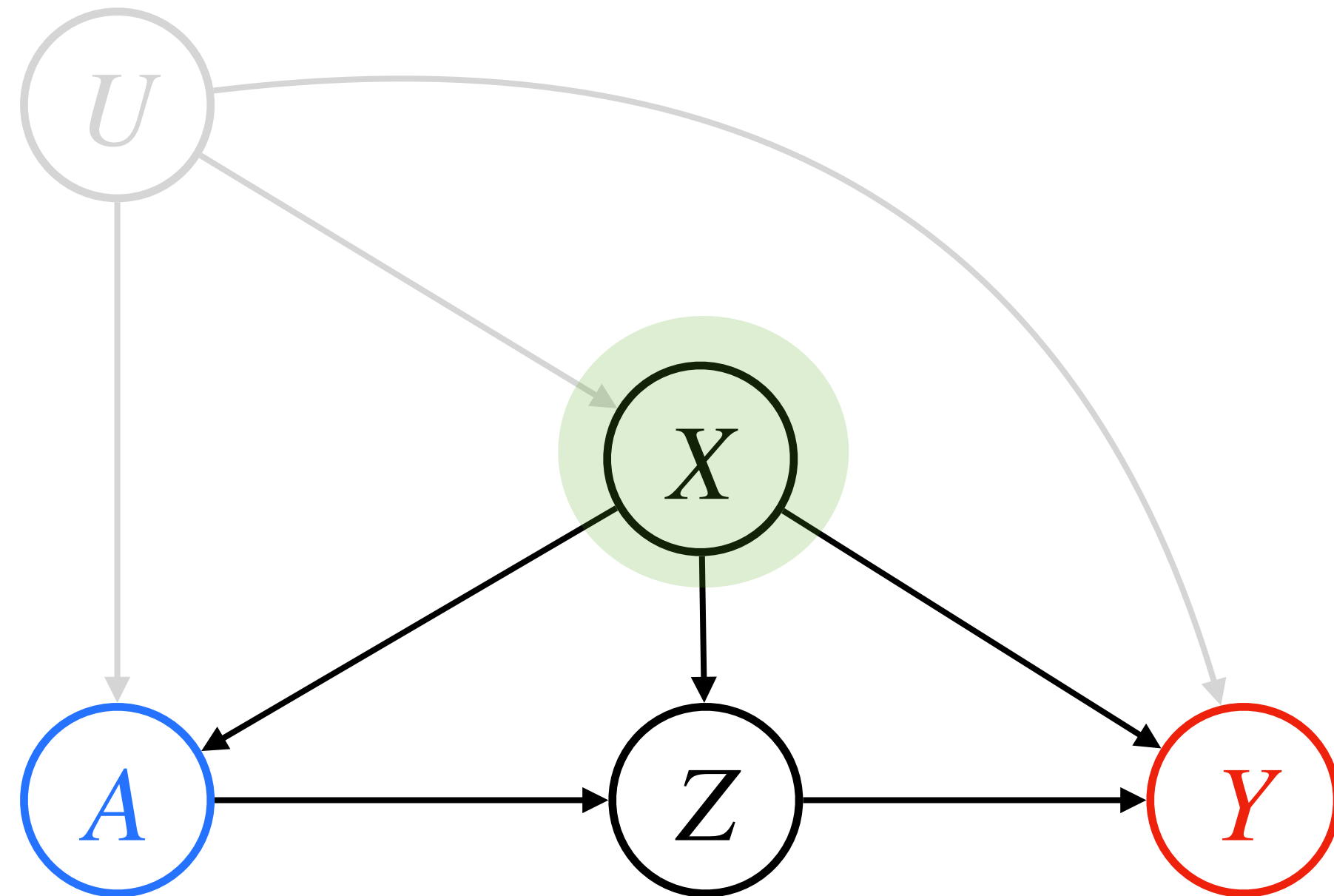
“Good Mediator Z ”

- 1 Z blocks all directed path from A to Y
- 2 No unmeasured confounders of $A \rightarrow Z$
- 3 No unmeasured confounders of $Z \rightarrow Y$

$$\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{a})] = \sum_{z, a', x} \mathbb{E}[\textcolor{red}{Y} \mid z, a', x] P(z \mid \textcolor{blue}{a}, x) P(a', x)$$

FD Heterogeneous Treatment Effect

NEW



Front-door effect at characteristics $X = x$

$$\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{a}), \textcolor{green}{x}]$$

$$= \sum_{z, a', x} \mathbb{E}[\textcolor{red}{Y} \mid z, a', x] P(z \mid \textcolor{blue}{a}, x) P(a' \mid x)$$

$$\mathbf{FD-CATE:} \mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{A} = 1), x] - \mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{A} = 0), x]$$

Front-door Heterogeneous Treatment Effect

$$\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{a}), x] = \sum_{z, a', x} \mathbb{E}[Y \mid z, a', x] P(z \mid \textcolor{blue}{a}, x) P(a' \mid x) = \sum_{z, a', x} m(z, a', x) q(z \mid \textcolor{blue}{a}, x) e_{a'}(x)$$

$$\textbf{FD-CATE } \tau(X): \frac{\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{A} = \textcolor{blue}{1}), X]}{\tau_1(X)} - \frac{\mathbb{E}[\textcolor{red}{Y} \mid \text{do}(\textcolor{blue}{A} = \textcolor{blue}{0}), X]}{\tau_0(X)}$$

$$= \sum_{z, a'} \{ q(z \mid \textcolor{blue}{1}, x) - q(z \mid \textcolor{blue}{0}, x) \} e_{a'}(x) m(z, a', x)$$

FD-DR-Learner: Doubly Robust Learner for FD

$$\begin{aligned}
 \xi_a(ZAX) &= \frac{q(Z \mid aX)}{q(Z \mid AX)} \\
 \pi_a(AX) &= \frac{\mathbb{I}(A = a)}{e_A(X)} \\
 r_{me}(ZX) &= \sum_{a'} m(Z, a', X) e_{a'}(X) \\
 \nu_{meq}(AX) &= \sum_z r_{me}(zX) q(z \mid A, X) \\
 s_{mq_a}(AX) &= \sum_z m(z, A, X) q(z \mid a, X)
 \end{aligned}$$

FD effect $\tau_a(X) = \mathbb{E}[Y \mid \text{do}(a)]$

FD Pseudo-Outcome $\varphi_{mqe,a}(YZAX)$

$\mathbb{E}[\xi_a(ZAX) \times \{Y - m(ZAX)\}]$
 $+ \mathbb{E}[\pi_a(AX) \times \{r_{me}(ZX) - \nu_{meq}(AX)\}]$
 $+ \mathbb{E}[s_{mq_a}(AX)]$

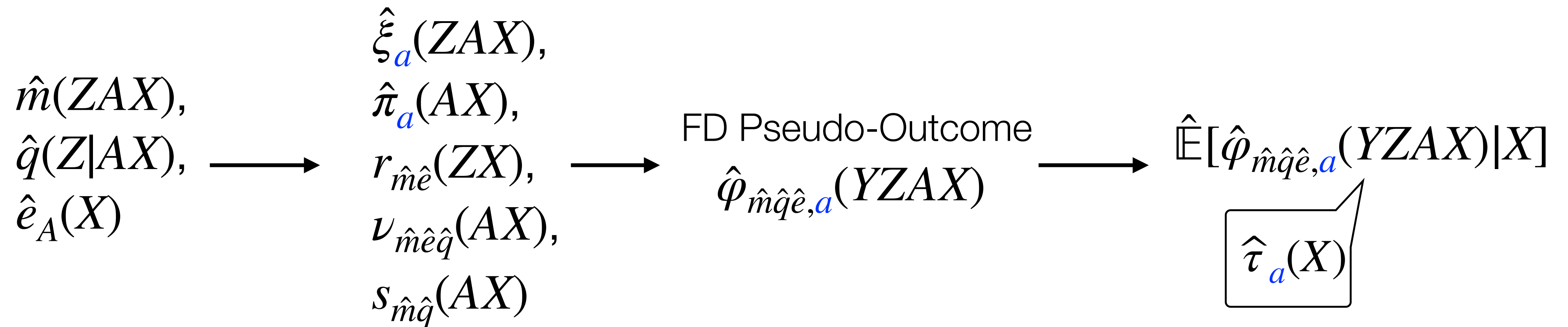
FD-DR-Learner: Doubly Robust Learner for FD

Learn nuisances
from D_{train}

Evaluate
functions

Evaluate PO
from D_{eval}

Regress $\hat{\phi}$ onto X



$$\text{FD-DR-Learner: } \hat{\tau}_{\text{DR}}(X) = \hat{\tau}_1(X) - \hat{\tau}_0(X)$$

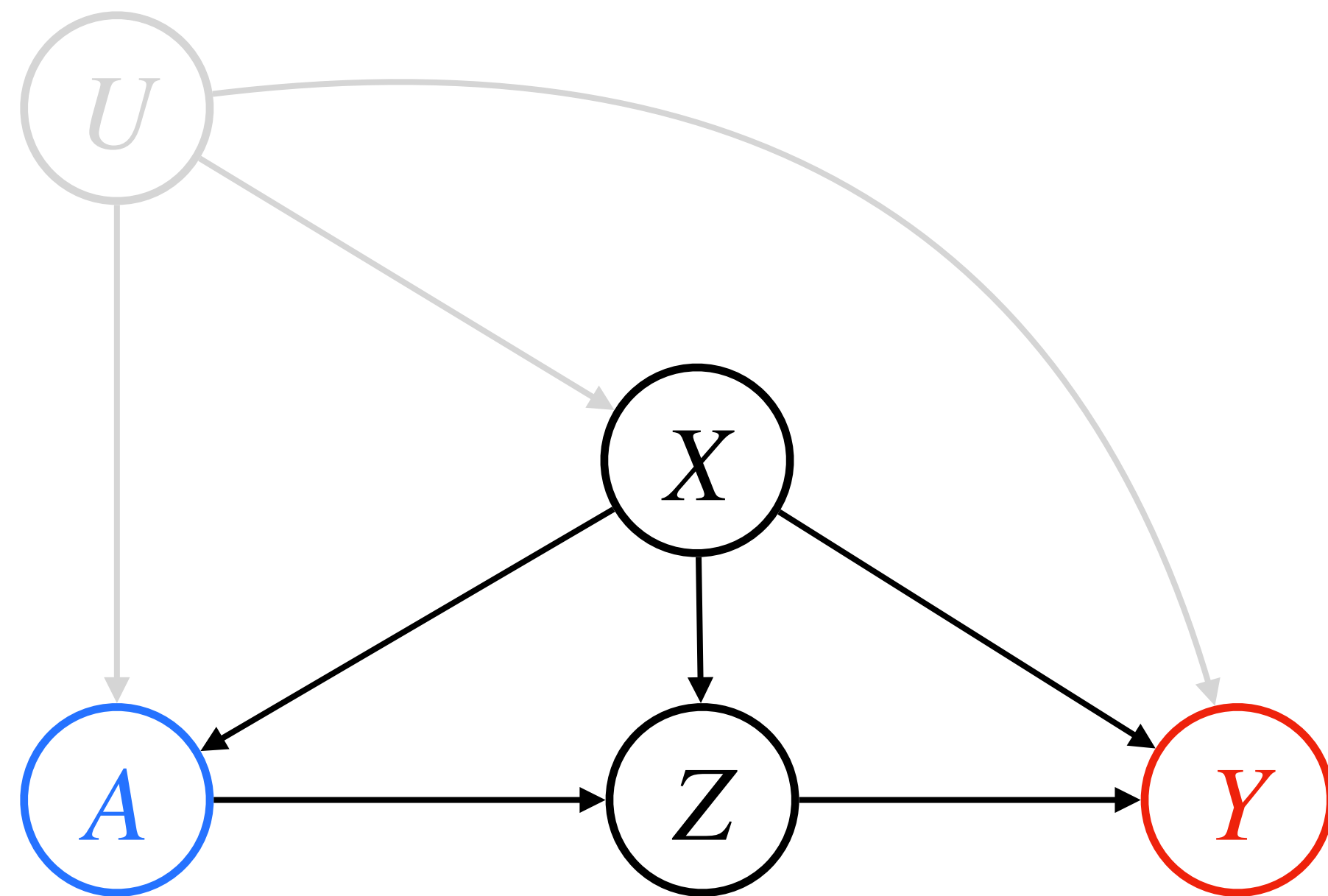
FD-DR-Learner: Doubly Robust Learner for FD

$$\text{error}(\hat{\tau}_{\text{DR}}) \lesssim \text{oracle-rate} + \underbrace{\{\text{error}(\hat{m}) \times \text{error}(\hat{q})\}}_{n^{-1/4}} + \underbrace{\{\text{error}(\hat{q}) \times \text{error}(\hat{e})\}}_{n^{-1/4}}$$

- **Double Robustness:** error $\rightarrow 0$ *fast* if either $\text{error}(\hat{m})=0$ & $\text{error}(\hat{e})=0$; or $\text{error}(\hat{q})=0$

- **Fast Convergence:** error $\rightarrow 0$ *fast* even when $\text{error}(\hat{m}), \text{error}(\hat{e}), \text{error}(\hat{q})$ goes to zero slowly

FD-R-Learner



FD Parametrization

$$A = e_A(X) + \epsilon_A$$

$$Z = \alpha(X) + A \cdot \beta(X) + \epsilon_Z$$

$$Y = f(AX) + Z \cdot g(AX) + \epsilon_Y$$

$$\mathbb{E}[\epsilon_A \mid X] = 0$$

$$\mathbb{E}[\epsilon_Z \mid AX] = 0$$

$$\mathbb{E}[\epsilon_Y \mid ZAX] = 0$$

FD-R-Learner

$$\text{FD-CATE } \tau(X): \mathbb{E}[Y \mid \text{do}(A = 1), X] - \mathbb{E}[Y \mid \text{do}(A = 0), X]$$

FD Parametrization

$$A = e_A(X) + \epsilon_A$$

$$Z = \alpha(X) + A \cdot \beta(X) + \epsilon_Z$$

$$Y = f(AX) + Z \cdot g(AX) + \epsilon_Y$$

$$\mathbb{E}[\epsilon_A \mid X] = 0$$

$$\mathbb{E}[\epsilon_Z \mid AX] = 0$$

$$\mathbb{E}[\epsilon_Y \mid ZAX] = 0$$

$$\beta(X) = \mathbb{E}[Z \mid \text{do}(A = 1), X] - \mathbb{E}[Z \mid \text{do}(A = 0), X]$$

$$g(AX) = \mathbb{E}[Y \mid \text{do}(Z = 1), AX] - \mathbb{E}[Y \mid \text{do}(Z = 0), AX]$$

FD-R-Learner Representation

$$\tau(X) = \beta(X) \mathbb{E}[g(AX) \mid X]$$

FD-R-Learner

Learn nuisances
from D_{train}

Evaluate with
 D_{eval}

FD-R-Learner Representation

$$\tau(X) = \beta(X) \mathbb{E}[g(AX) | X]$$

$$\hat{m}_Z(X) = \mathbb{E}[Z | X]$$

BD-R-Learner

(Nie and Wager, 2021)

$$\hat{\beta}(X)$$

$$\hat{e}_A(X) = \mathbb{E}[A | X]$$

$$\hat{m}_Y(AX) = \mathbb{E}[Y | AX]$$

BD-R-Learner

(Nie and Wager, 2021)

$$\hat{g}(AX)$$

$$\hat{e}_Z(AX) = \mathbb{E}[Z | AX]$$

$$\hat{\zeta}(AX)$$

Regress
 $\hat{\zeta}$ onto X

$$\hat{\gamma}(X)$$

$$\hat{\tau}_R(X)$$

$$= \hat{\beta}(X) \hat{\gamma}(X)$$

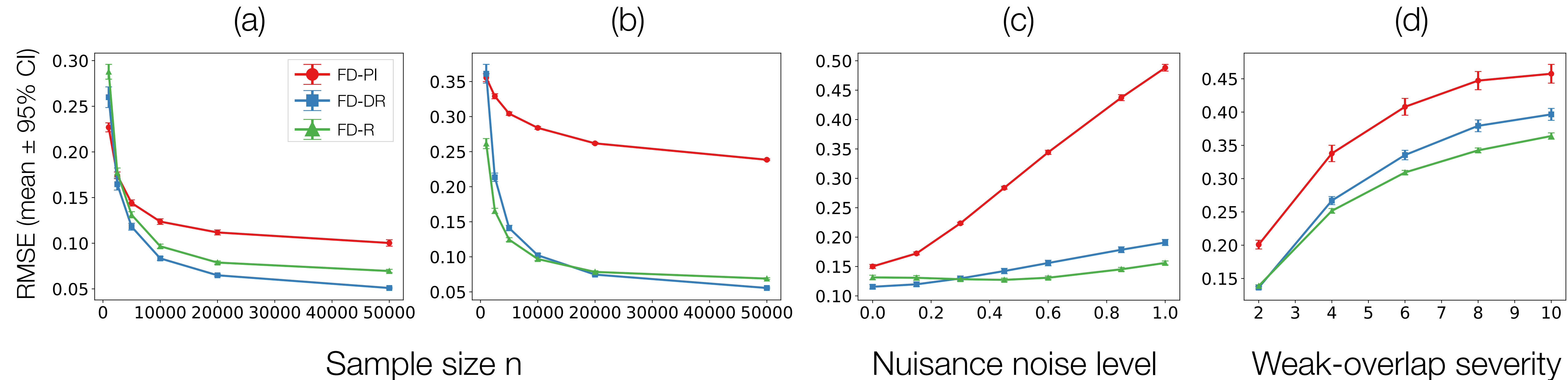
$$\sum_a \hat{e}_a(X) \hat{g}(aX) + \{A - \hat{e}_A(X)\} \{\hat{g}(1X) - \hat{g}(0X)\}$$

FD-R-Learner: Doubly Robust Learner for FD

$$\begin{aligned} \text{error}(\hat{\tau}_R) &\lesssim \text{oracle-rate} + \overset{n^{-1/4}}{\text{error}(\hat{e}_A)^2} + \{ \overset{n^{-1/4}}{\text{error}(\hat{e}_A)} \times \overset{n^{-1/4}}{\text{error}(\hat{m}_Z)} \} \\ &\quad + \overset{n^{-1/4}}{\text{error}(\hat{e}_Z)^2} + \{ \overset{n^{-1/4}}{\text{error}(\hat{e}_Z)} \times \overset{n^{-1/4}}{\text{error}(\hat{m}_Y)} \} \end{aligned}$$

- **Fast Convergence:** error $\rightarrow 0$ fast even when
error(\hat{e}_A), error(\hat{m}_Z), error(\hat{e}_Z), error(\hat{m}_Y)
goes to zero slowly

Simulation: Synthetic Data

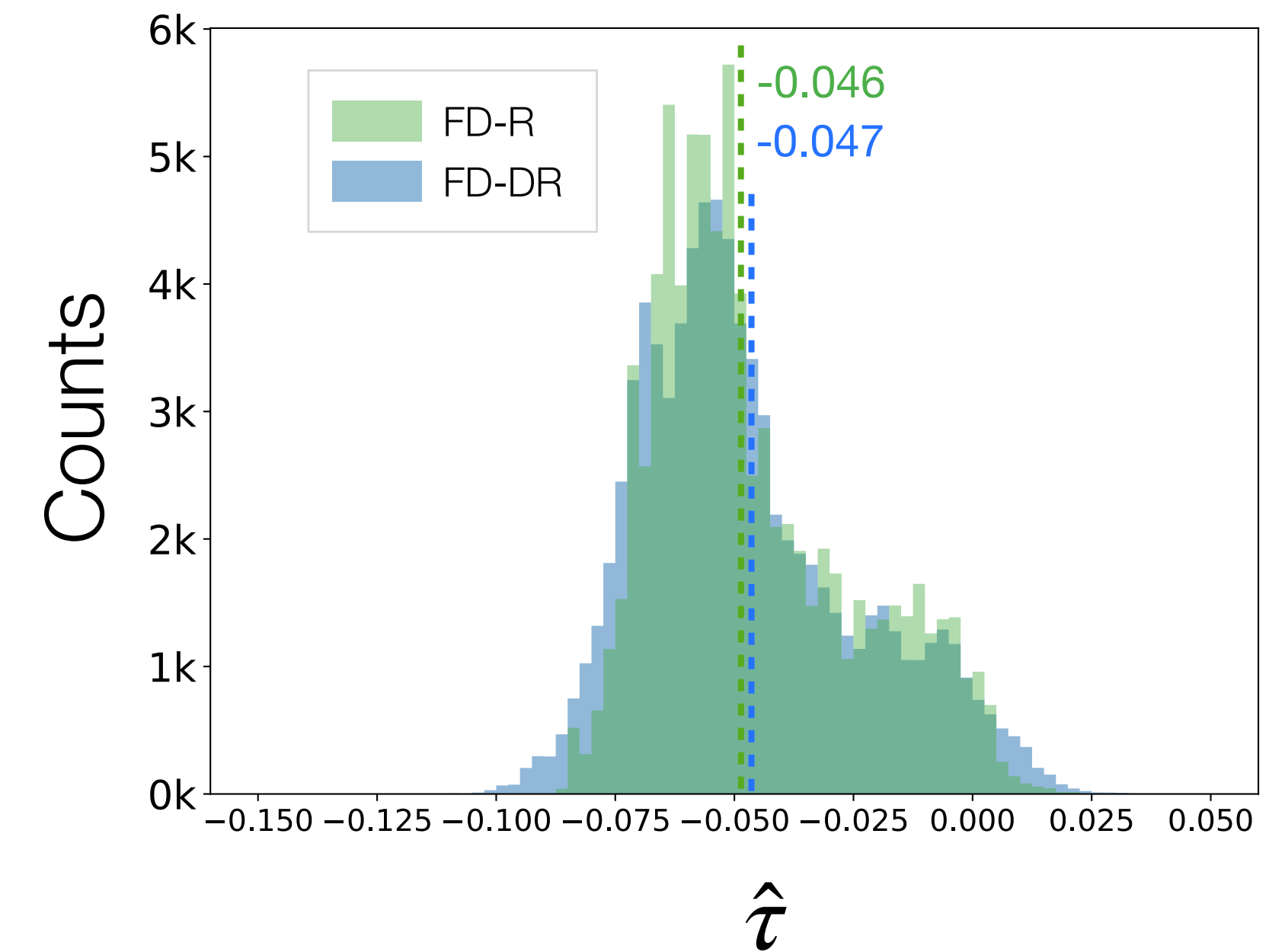
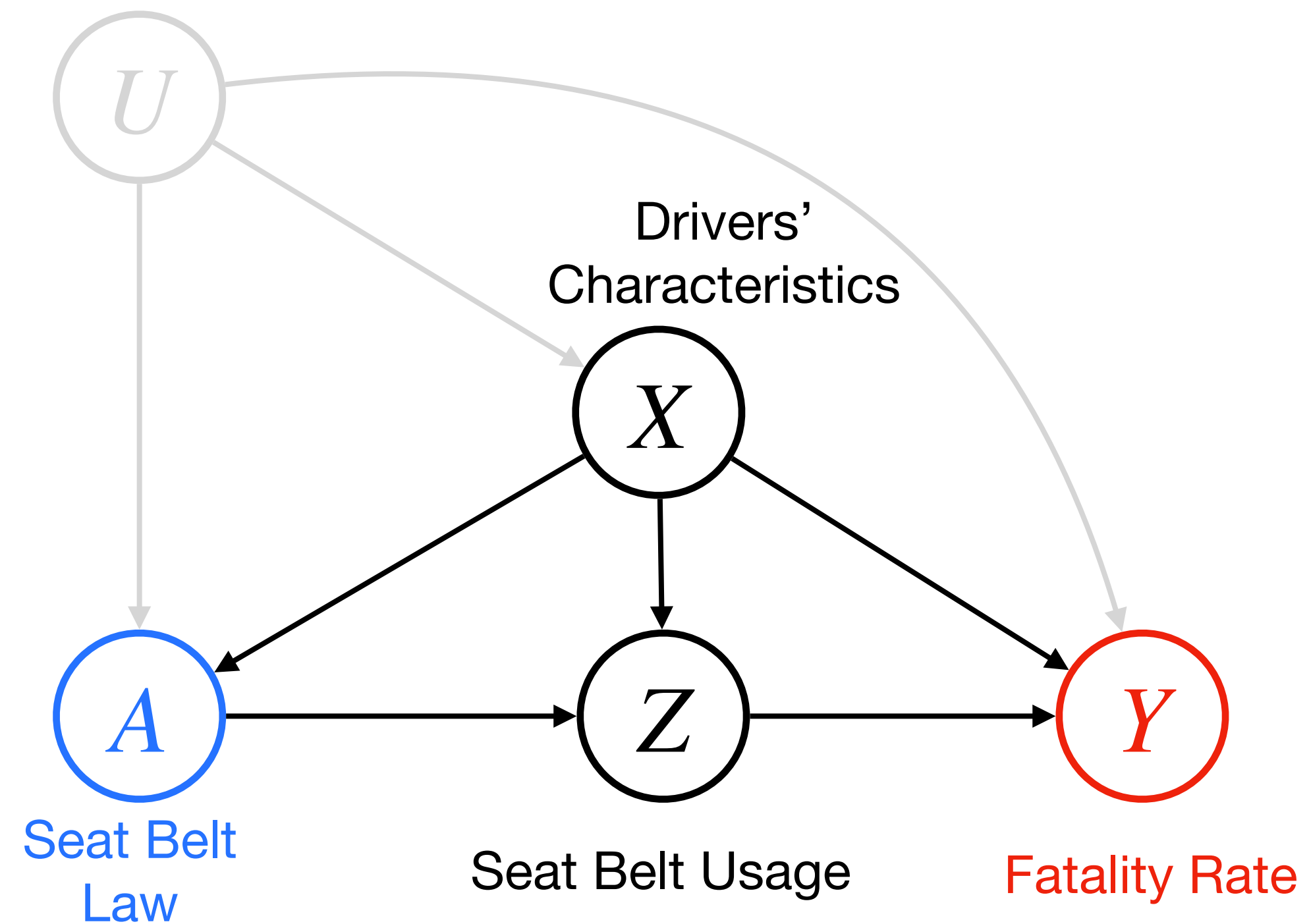


FD-DR & FD-R learners outperforms the plug-in estimator.

FD-DR & FD-R learners are more robust to slow convergences of nuisances

FD-DR & FD-R learners are more robust to weak overlap.

Simulation: NHTSA Dataset



Summary

- Front-door models are increasingly applied in real-world causal analyses.
- ATE estimators have been well-developed.
- However, CATE/HTE estimators have been largely unexplored.

We introduce two CATE estimators for FD:
(FD-DR-Learner, FD-R-Learner)