Report on Data Centers

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I. MOTIVATION

With the increasing demand of traffic loads and user requirements, it is a great challenge to make data centers agile and energy-efficient. A basic solution is to allow dynamic resource allocation based on flexible data center networks. The recent development of 60GHz wireless technology opens a door for the deployment of flexible data centers. It provides a good choice of adding capacity to data centers with under-provisioning capacity design. However, this will lead to new problems such as topology control and capacity scheduling, apart from the wireless propagation and link adaption in wireless networks. The PHY and MAC standardization of 60GHz networks is still ongoing (WirelessHD and IEEE 802.11ad/WiGig), its application in data centers should be further explored for the specific feature of topology and services.
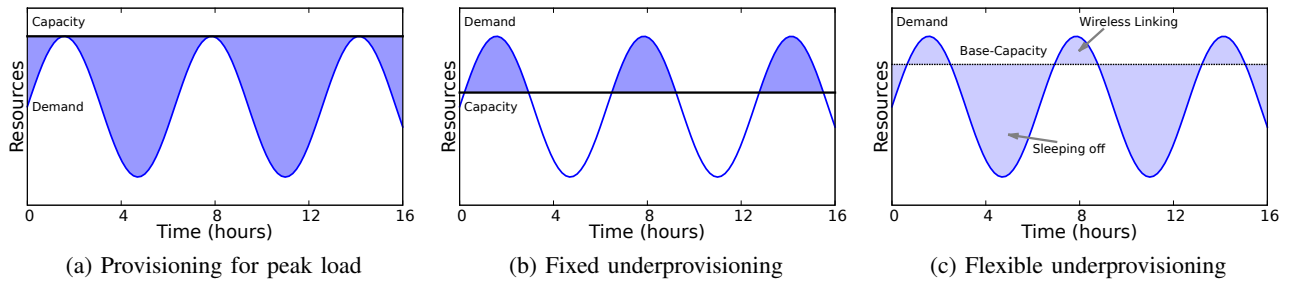

Fig. 1. Capacity provisioning based on traffic loads

Generally, the capacity of data centers is designed for peak loads, as shown in Figure 1a, but the resources will be wasted during non-peak times [Armbrust et al., 2010]. On the other hand, if the capacity is designed in under-provisioning case as shown in Figure 1b, the peak requirements can not be satisfied, leading to potential revenue sacrifice or over-occupied errors. To address these problems, we can employ flexible capacity and dynamic demand response, i.e., 60GHz wireless linking to add capacity for peak loads and sleeping mechanism to improve performance/cost efficiency, as shown in Figure 1c.

The wireless-flexible data centers are generally composed of:

1) Topology and Addressing:
    a) Conflict Graph: Propagation table (wireless), capacity matrix (wired/wireless) and traffic loads table (wired/wireless)
    b) Topology Graph: Physical-specific ID Addresses (PAs), Logical-specific IP Addresses (LAs) and Application-specific IP Addresses (AAs)
        i) PAs: providing distance information for 3D Beamforming
        ii) LAs: providing topology information for Capacity Adaption
        iii) AAs: providing traffic information for Demand Response
2) Routing and Scheduling:
    a) 3D Beamforming: adding additional capacity to neighbor ToRs according to PAs
    b) Demand Response: traffic estimation according to AAs
    c) Capacity Adaption: capacity scheduling according to LAs

II. METHODOLOGY

The problems of topology control, addressing, routing, and scheduling also exit in traditional data centers, but it brings new challenges when wireless links are introduced. For instance, the topology graph is changing due to wireless links and on-demand response. Also, the capacity matrix and conflict graph of wireless links are closely related to the relative locations of servers, e.g., capacity of 6G for neighbor servers and 1/2G for non-neighbor servers. Furthermore, the measurement and mapping of topology graph, conflict graph and traffic loads is challenging for large scale data centers.
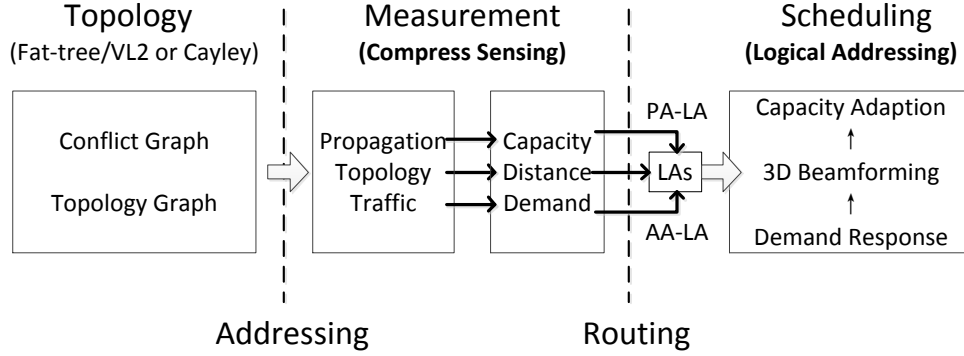

Fig. 2. framework

Considering the scale of topology (conflict/topology graph and different addresses) and multi-layer scheduling (physical topology, capacity matrix and traffic patterns), we can employ **Compress Sensing** and **Logical Addressing** to address these problems.

Topology: multi-layer tree topology such as Fat-tree and VL2 (or cylindrical racks housing pie-shaped servers [Shin et al., 2012]) with ToRs.

Addressing: changing according to topology, PAs and AAs should be mapped to LAs to make 3D beamforming, demand response and capacity scheduling.

Scheduling: when the capacity matrix and traffic demands are mapped to LAs, we can determine the scheduling strategy including 3D beamforming and routing paths.

A. Compress Sensing

The conflict graph can be classified into the topology graph, since it represents the wireless connections which provide additional 1/2/6G capacity for different ToRs. It is challenging to measure such a large scale topology graph (PAs and AAs) which usually requires all-to-all communications. Since both conflict graph [Halperin et al., 2011] and topology graph [Chen et al., 2010] are sparse, we can utilize Compress Sensing to reduce overhead, just as the famous example that using only 3 out of 10 words can reconstruct the whole account password. In this way, we can use small number of samples to get the topology so that all-to-all communications are not necessary.

The requirements and reasons for Compress Sensing are:

1) topology graphs are **large**, and so comes the requirement to reduce measuring and mapping overhead
2) wireless propagation and traffic demand have **dynamic** furthers, so the measurement is challenging
3) topology graphs are **sparse**, which is the prior condition for compress sensing
4) topology graphs only have **local changes** (errors, on-off or wireless) in real-time operating

If the adjacency matrix of a given topology graph $G = (V, E)$ is $A^{N \times N}$, it can be represented by N vertex A_i. Then the estimated matrix $\hat{y} \in \mathbf{R}^n$ can be calculated through the measure matrix $\Phi \in \mathbf{R}^{n \times N}(n \ll N)$ as follows:

$$y = \Phi A_i \tag{1}$$

If the measured data is recovered through $\hat{A}_i = f(y) = \Psi y = \Psi \Phi A_i$, the estimated results can be obtained by optimization

$$min \parallel A_i - f(y) \parallel_{l_x} \tag{2}$$

$$s.t. \quad \Phi A_i = y \tag{3}$$

where $l_x(x = 0, 1, 2)$ is the . Then y can be easily measured and A can be reconstructed through y if the measure and reconstruct matrix (Φ and Ψ) are suitably designed. Therefore, all-to-all communications are not required which can help to reduce the measurement overhead. The topology graph can be estimated by Compress Sensing due to its large-scale and sparse feature. Furthermore, the propagation table and traffic loads can be measured in this way according to the measurement results in [Halperin et al., 2011] and [Greenberg et al., 2009].

The topology that should be measured includes:

- Propagation table → Capacity matrix: the curve is quite certain for high frequency at near distance (do not consider PHY and MAC settings) [Zhou et al., 2012], [Halperin et al., 2011]
- PAs → LAs
- Traffic loads → Demands: the distribution of traffic loads has location differences across AAs and ToRs [Halperin et al., 2011], [Greenberg et al., 2009]

Topology changes due to:

- Errors: nodes, links, miswiring
- wireless linking (links)
- Sleeping on-off (nodes)

B. Logical Addressing

Wireless links make data centers flexible, i.e., using topology control and capacity scheduling to make resource allocation responding to traffic patterns and requirements. So the problem is how to allocate wireless links to deal with the problem of demand response when topology graphs are changing.

The capacity matrix is composed of wired and wireless links (direct links between neighbor nodes or 3D beamforming for remote nodes), which can be obtained by PAs:

- wired 10G
- wireless direct 6G
- wireless indirect 1/2G

Then the PAs (conflict and topology graphs) and demands estimation (AAs) can be mapped to LAs:

- PA to LA for 3D Beamforming
- AA to LA for Traffic estimation

When the topology graph and traffic demands are mapped to LAs, the capacity scheduling can be made responding to dynamic traffic loads. First, we can get the whole capacity matrix according to propagation table and topology graph. Second, greedy choice of flyways can be made according to capacity matrix an traffic demands. Finally, we can make wireless linking by direct or indirect beamforming if necessary, and make routing and scheduling further.

III. Literature Review

Data Center Networks:

- Static-electrical:
  - Server-centric:
    * DCell [Guo et al., 2008]
    * BCube [Guo et al., 2009]
  - Multi-level tree:
    * Fat-tree [Al-Fares et al., 2008]
    * VL2 [Greenberg et al., 2009]
- Flexible:
  - Optical:
    * c-Through [Wang et al., 2010]
    * Helios [Farrington et al., 2010]
    * OSA [Chen et al., 2012]
  - Wireless:
    * Wireless flyways [Halperin et al., 2011]
    * 3D beamforming [Zhou et al., 2012]
    * Cylindrical racks with pie-shaped servers [Shin et al., 2012]

These papers mainly discussed the issues of:

- topology [Al-Fares et al., 2008], [Greenberg et al., 2009], [Guo et al., 2008], [Guo et al., 2009]
- addressing [Al-Fares et al., 2008], [Greenberg et al., 2009]
- mapping [Chen et al., 2010], [Greenberg et al., 2009]
- routing [Guo et al., 2008], [Guo et al., 2009]
- scheduling [Al-Fares et al., 2008], [Halperin et al., 2011]

"Generic and Automatic Address Configuration for Data Center Networks", SIGCOMM 2010

Basic Procedures:

1) O2 Mapping
   a) Candidate selection via SPLD: **select** candidate with the same SPLD.
   b) Candidate filtering via orbit: **skip** candidate with the same orbit, then $Decomposition()$.
   c) Selective splitting $Refinement^*()$: **split** cells that really connect to the including cell.
2) Malfunction Detection
   a) Anchor pair selection:
   b) Malfunction detection:

Problems:

1) Initial selection of vertex $\nu \in \pi_p^i$
2) Whether it can be resolved by Compress Sensing?
   a) the topology graphs are sparse.
   b) only certain parts are changing in real-time operating (considering certain servers can be turned down for energy-efficiency and demand response).

"OSA: An Optical Switching Architecture for Data Center Networks with Unprecedented Flexibility", NSDI 2012

Architecture

"A Scalable, Commodity Data Center Network Architecture", SIGCOMM 2008

Topology: k pods, two layers of k/2 switches, each k-port switch connected to k/2 hosts, each remaining k/2 ports connected to k/2 of the k ports in the aggregation layer of the hierarchy. Max $48 \cdot \frac{48}{2} \cdot \frac{48}{2} = 27648$ hosts for 48-port GigE switches.

Addressing: Pod: 10.pod.switch.1, core: 10.k.j.i, host: 10.pod.switch.ID

"DCell: A Scalable and Fault-Tolerant Network Structure for Data Centers", SIGCOMM 2008

Large-scale, server-centric data centers

Topology: n servers connected to a mini-switch within $DCell_0$, then $DCell_k$ is recursively generated by $t_{k-1}+1$ $DCell_{k-1}$s. The number of servers scales doubly exponentially as the node degree increases.

Addressing: a server in $DCell_k$ is denoted by $[a_k, uid_{k-1}]$, where a_k is the $DCell_k$ this server belongs to and uid_{k-1} is the unique ID of the server inside this $DCell_{k-1}$.

Routing: find the connection (n_1, n_2) between $DCell$s, then find the paths of src to n_1 and n_2 to dst. When failures occur, choosing *proxy* to make local-reroute or jump-up (rack failure).

Problems:

- the bottleneck link locates in the low-level links and traffics are not balanced
- increment expansion requires additional ports which brings extra overhead and complexity

"BCube: A High Performance, Server-centric Network Architecture for Modular Data Centers", SIGCOMM 2009

Server-centric modular data centers

Topology: $BCube_0$ is n servers connecting to an n-port switch. $BCube_k$ is constructed from n $BCube_{k-1}$s and n^k n-port switches.

Addressing: servers: $a_k a_{k-1} \cdots a_0$ ($a_i \in [0, n-1], i \in [0, k]$); switches: $< l, s_{k-1}, s_{k-2} \cdots s_0 >$, where $l(0 \leq l \leq k)$ is the level of the switch.

Routing:

"VL2: A Scalable and Flexible Data Center Network", SIGCOMM 2009

1. Background:

- Limited server-to-server capacity: over-subscription ratio increases rapidly
- Fragmentation of resources: high turnaround time for reconfiguration
- Poor reliability and utilization: multiple paths waste at most 50% of maximum utilization

2. Measurement:

- Flow: VLB will perform well on this traffic
  - Distribution of flow sizes: majority of flows are small
  - Number of concurrent flows: 10 concurrent flows at more than 50% of the time, 80 concurrent flows at least 5% of the time
- Traffic: it is unlikely that other routing strategies will outperform VLB
  - Poor summarizability of traffic patterns
  - Instability of traffic patterns
- Failure

3. Solution: Virtual Layer 2 Networking

- Topology: D_I Int. Switches and D_A Agg. Switches

- Addressing: Location-specific IP Addresses and Application-specific IP Addresses
- Directory: lookups and updates of AA-to-LA mapping, reactive cache update

Problems:

- arrive intervals.
- application types.

Wireless

"Mirror Mirror on the Ceiling: Flexible Wireless Links for Data Centers", SIGCOMM 2012

Wireless Data Center is a new concept which should be explored further. Many issues such as interference, secluding, security, etc. should be standardized. On the other hand, the issues on cost, performance, energy-efficiency, reliability, etc. should be taken into consideration compared with electrical or optical data centers.

1) electrical
2) optical
3) wireless
   a) Link Blockage
   b) Radio Interference

Max concurrent links: Link conflicts (SINR); Greedy scheduling (graph coloring); Assigning radios.

Problems:

- Apart from the concurrent links, the efficient throughput should be explored. For instance, although the concurrent links are more with larger ceiling height h, it can decrease the throughput according to the curves of RSS (or Data Rate) vs. distance as shown in Figure 5.

"Augmenting Data Center Networks with Multi-gigabit Wireless Links", SIGCOMM 2011

"The base wired network is provisioned for the **average case** and can be oversubscribed. Each ToR switch is equipped withe one or more 60GHz wireless devices." "A central controller monitors DC **traffic patterns**, and switches the beams of the wireless devices to set up flyways between ToR switches that provide **added bandwidth** as needed." So it is ideal for **flexible and energy-efficient** data centers.

Problems:

- Conflict graph: for N racks and K antenna orientations, the input table is very **large** with the size of $(NK)^2$. On the other hand, the propagation conditions are similar, i.e., the table is **sparse**.

to be done

"FairCloud: Sharing The Network In Cloud Computing", SIGCOMM 2012

"NetPilot: Automating Datacenter Network Failure Mitigation", SIGCOMM 2012

"Towards Predictable Datacenter Networks", SIGCOMM 2011

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