

# **Yong-Sung Masuda**

ydmasuda@hawaii.edu

Honolulu, Hawaii

(614) 260-4717

## **Education**

---

### **University of Hawaii at Manoa**

M.S. Computer Science (2025)

B.S. Computer Science (2024)

- GPA: 3.95, Dean's List (6 semesters)
- Treasurer, UH Ballroom Dance Club (2022–Present)

## **Publications**

---

### **Micromachines Journal, MDPI**

Sep 2025

*High-Throughput Evaluation of Mechanical Exfoliation Using Optical Classification of Two-Dimensional Materials*

- Co-authored paper on GPU-accelerated software for classifying 2D materials from optical microscopy.
- Developed machine learning platform achieving 200x throughput improvement and 60x speed reduction.
- DOI: 10.3390/mi16101084

### **Electronics Journal, MDPI**

Jan 2025

*Accessible and Inexpensive Parameter Testing Platform for Adhesive Removal in Mechanical Exfoliation Procedures*

- Co-authored paper detailing Arduino-powered testing equipment.
- Responsible for data validation, software integration, and technical drafting.
- DOI: 10.3390/electronics14030533

## **Experience**

---

### **Computer Science Research Assistant (VNC Intern) – Naval Information Warfare Center**

May 2024 – August 2025

- Developed experimental control software integrating Arduino, stepper motor drivers, and CLI for automated actuator positioning in mechanical exfoliation procedures.
- Developed GPU-accelerated unsupervised ML model for classifying 2D material structures from optical microscopy, processing thousands of images for experimental validation.
- Co-authored two peer-reviewed publications, contributing software development and technical figure generation.

## **Projects**

---

### **Stereo Vision System for Autonomous Marine Navigation – Implementation & Comparative Analysis**

M.S. Thesis Project

- Developed end-to-end stereo vision system integrating depth estimation and semantic segmentation for obstacle detection in autonomous marine navigation, deployed as containerized FastAPI service supporting ARM and x86 architectures.
- Implemented and compared two stereo depth estimation approaches (traditional OpenCV-based stereo matching and deep learning-based FoundationStereo) across 120 experimental conditions varying camera baselines, viewing angles, target distances, and checkerboard calibrations.

### **Mosquito Larvae Detection – YOLOv8 Object Detection**

May 2023

- Developed a detection system using YOLOv8 and Python to identify larvae in lab imagery, aiding vector control research.
- Labeled datasets and tuned models via transfer learning, achieving F1 score of 0.94 with strong generalization on test data.

## **Technical Skills**

---

Python, C, C++, C#, JavaScript, Java, SQL, Bash, React, MongoDB, Meteor, Git, GNU, Docker, Arduino, PyTorch, TensorFlow

## **Military Experience**

---

### **Ground Radio Repair Technician – U.S. Marine Corps**

Nov 2016 – Aug 2021

- Performed diagnostics and corrective maintenance on VHF/UHF/SATCOM radio systems supporting ground operations.
- Led a 5-8 person maintenance team, coordinating workflows and quality control to sustain tactical network capabilities.