ECE-C301 – Advanced Programming for Engineers

Contact

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Office Hours: 3 – 4 pm (Wednesday)

Course Website: http://learn.dcollege.net

Textbook (1st half of course)

Think Python
by Allen Downey
O'Reilly Press, 2015
ISBN-13: 978-1449330729
(Freely available in PDF format, check course website)



Grading

(subject to change)

- 30% In-lab Programming Assignments
- 30% Take-Home Programming Assignments
- 40% Programming Projects

Course Structure

1st Half

Advanced Python

2nd Half

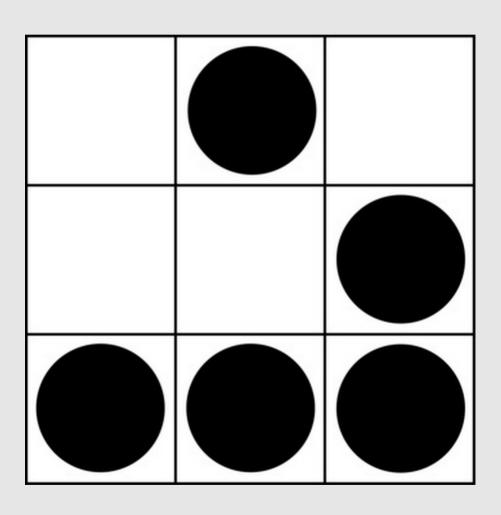
Introduction to C

Used in:

- Microcontrollers
- Embedded Systems
- System Programming

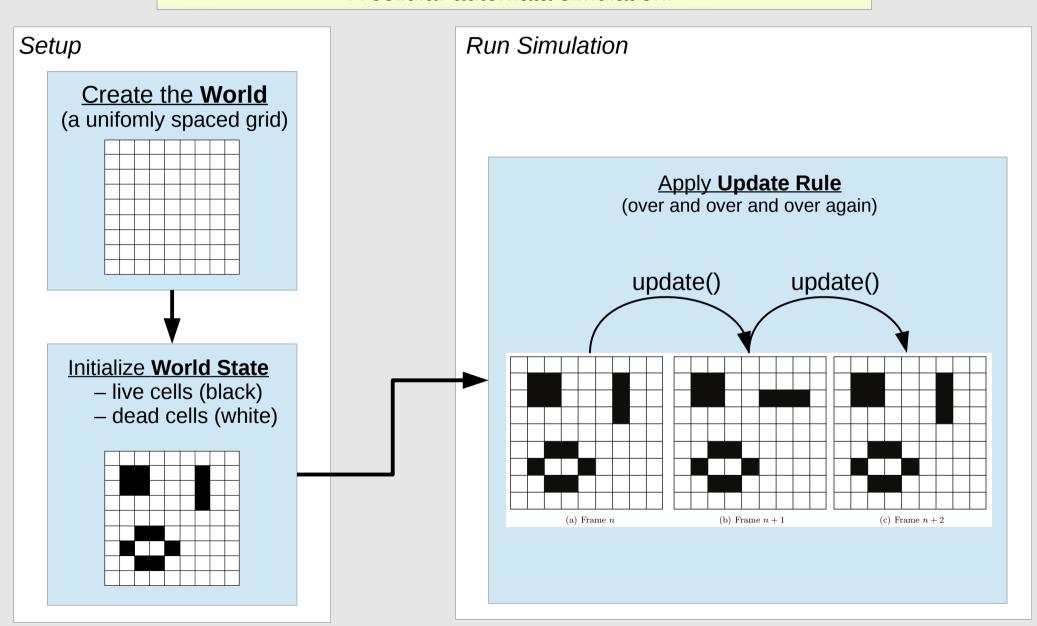
Conway's Game of Life

An introduction to programming simulations



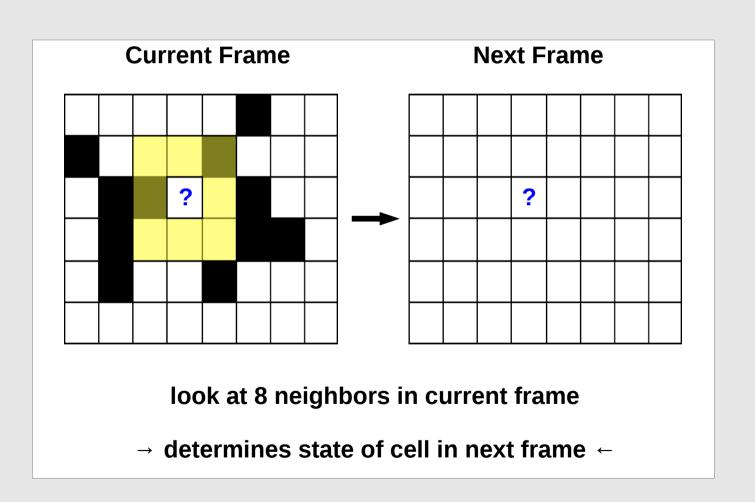
What is it?

A cellular automata simulation.



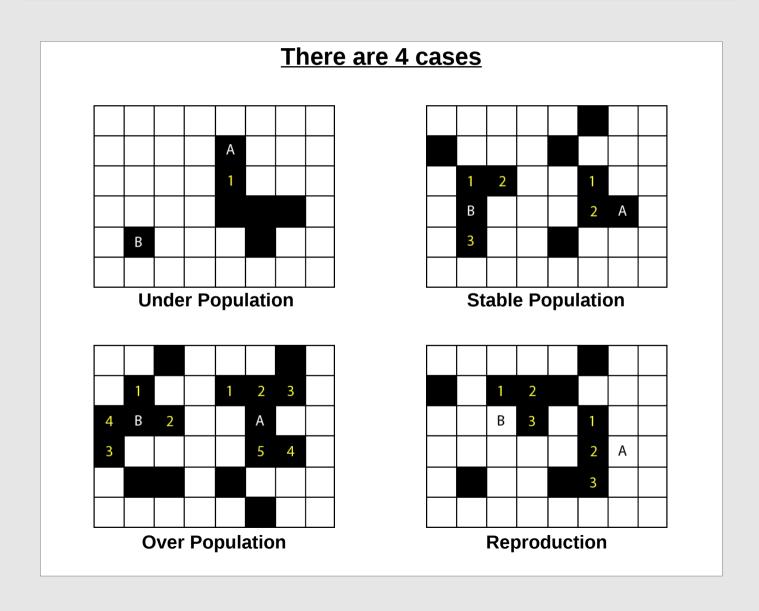
Update Rule?

Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**



Update Rule?

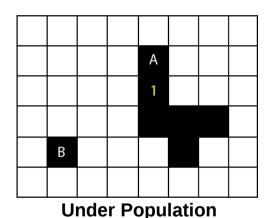
Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**



Update Rule?

Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**

There are 4 cases



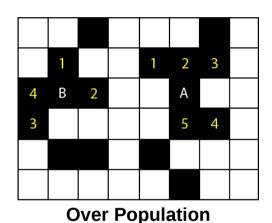
- **★** Applies to living cells
- ★ Dies if living neighbors < 2

- Cell A: Has 1 neighbor → DEAD in next frame
- Cell B: Has 0 neighbors → DEAD in next frame

Update Rule?

Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**

There are 4 cases



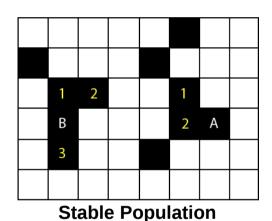
- **★** Applies to living cells
- ★ Dies if living neighbors > 3

- Cell A: Has 5 neighbors → DEAD in next frame
- Cell B: Has 4 neighbors → DEAD in next frame

Update Rule?

Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**

There are 4 cases



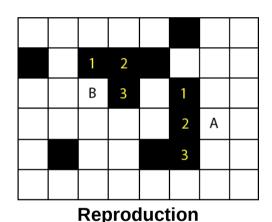
- **★** Applies to living cells
- ★ Lives if living neighbors = 2 or = 3

- Cell A: Has 2 neighbors → ALIVE in next frame
- Cell B: Has 3 neighbors → ALIVE in next frame

Update Rule?

Determines if a **cell** in the **next frame** should be **black** or **white** based on the **state** of its **neighbors**

There are 4 cases



- **★** Applies to DEAD cells
- ★ Lives if living neighbors EXACTLY = 3

- Cell A: Has 3 neighbors → ALIVE in next frame
- Cell B: Has 3 neighbors → ALIVE in next frame

ONLY WAY FOR A DEAD CELL TO COME BACK TO LIFE

Program Specifications

```
tshack@xavier:~/src/gameoflife/assignment$ ./gameoflife.py --help
usage: gameoflife.py [-h] [-r ROWS] [-c COLS] [-w WORLD_TYPE] [-d FRAMEDELAY]
optional arguments:
             show this help message and exit
 -h, --help
  -r ROWS, --rows ROWS set # of rows in the world
  -c COLS, --columns COLS
                        set # of columns in the world
  -w WORLD_TYPE, --world WORLD_TYPE
                       type of world to generate
  -d FRAMEDELAY, --framedelay FRAMEDELAY
                        time (in milliseconds) between frames
                          From command prompt:
                           ★ can specify world size
```

★ can set world type

empty

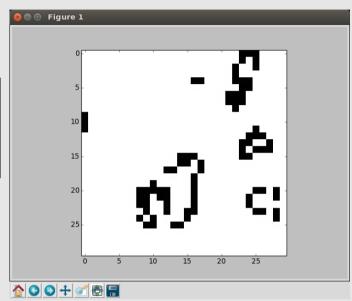
– random (10% alive)

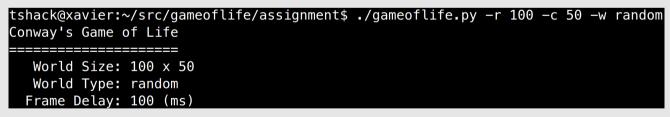
Program Specifications

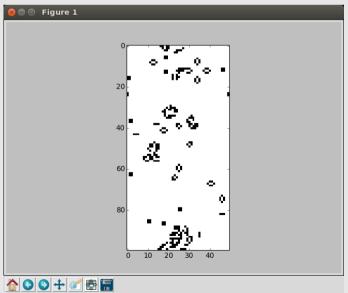
From command prompt:

- ★ can specify world size
- ★ can set world type
 - random (10% alive)
 - empty

Program Specifications







```
def main():
188
189
       The main function —— everything starts here!
190
191
     \longrightarrow opts = get_commandline_options() <\!\!\!-
192
        world = generate_world(opts)
        report_options(opts)
193
194
        blit(world, patterns.glider, 20, 20)
195
196
        run_simulation(opts, world)
197
198
199
main()
201
```

```
139 def get_commandline_options():
        parser = argparse.ArgumentParser()
140
141
142
        parser.add_argument('-r', '--rows',
143
                             help='set # of rows in the world',
144
                             action='store',
145
                             type=int.
                             dest='rows',
146
147
                             default=50)
148
149
        parser.add_argument('-c', '--columns',
                             help='set # of columns in the world',
150
151
                             action='store',
152
                             type=int,
153
                             dest='cols'.
                             default=50)
154
155
156
        parser.add argument('-w', '--world',
                             help='type of world to generate'.
157
158
                             action='store',
159
                             type=str,
160
                             dest='world_type',
161
                             default='empty')
162
163
        parser.add_argument('-d', '--framedelay',
                             help='time (in milliseconds) between frames',
164
165
                             action='store',
166
                             type=int,
167
                             dest='framedelay',
                             default=100)
168
169
170
        opts = parser.parse args()
171
172
        return opts
```

```
def main():
188
189
       The main function —— everything starts here!
190
       opts = get_commandline_options()
191
192
       world = generate_world(opts)
    report_options(opts) <-----</pre>
193
194
       blit(world, patterns.glider, 20, 20)
195
196
       run_simulation(opts, world)
197
198
199
main()
201
```

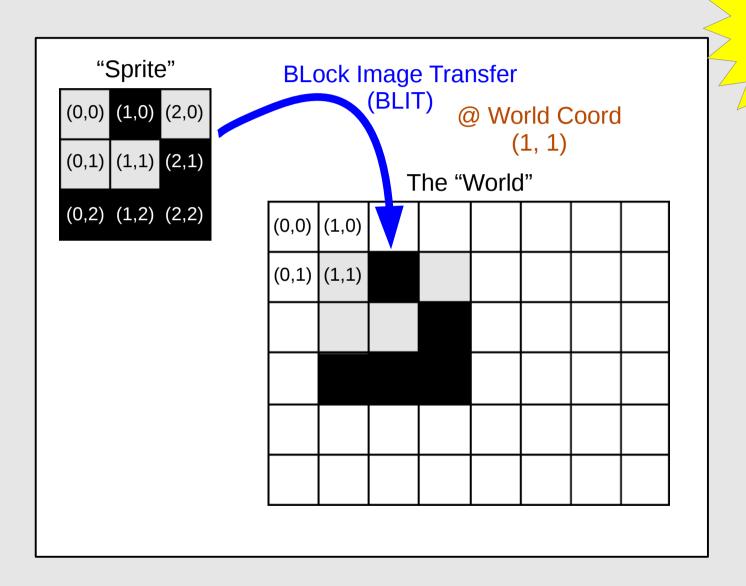
```
122 def report_options(opts):
123
124
        Accepts: opts -- a populated command line options class instance
125
        Returns: (Nothing)
126
127
128
        Descrption: This function simply prints the parameters used to
129
                    start the 'Game of Life' simulation.
        1111111
130
131
132
        print "Conway's Game of Life"
        print "===========================
133
134
        print " World Size: %i x %i" % (opts.rows, opts.cols)
135
        print " World Type: %s" % (opts.world_type)
        print " Frame Delay: %i (ms)" % (opts.framedelay)
136
```

```
def main():
188
189
       The main function —— everything starts here!
190
       opts = get_commandline_options()
191
     🔷 world = generate_world(opts) 🚤
192
                                             TASK 1
       report_options(opts)
193
194
       blit(world, patterns.glider, 20, 20)
195
196
       run_simulation(opts, world)
197
198
199
main()
201
```

```
def generate_world(opts):
16
17
       Accepts: opts -- parsed command line options
       Returns: world -- a list of lists that forms a 2D pixel buffer
18
19
       Description: This function generates a 2D pixel buffer with dimensions
20
21
                    opts.cols x opts.rows (in pixels). The initial contents
                     of the generated world is determined by the value provided
22
                     by opts.world_type: either 'random' or 'empty' A 'random'
23
                    world has 10% 'living' pixels and 90% 'dead' pixels.
24
                     'empty' world has 100% 'dead' pixels.
25
       1111111
26
27
       world = []
28
29
30
31
                              YOUR CODE GOES HERE 1
32
33
34
35
       return world
```

```
def main():
188
189
        The main function —— everything starts here!
190
        opts = get_commandline_options()
191
192
        world = generate_world(opts)
                                                   TASK 2
        report_options(opts)
193
194
        blit(world, patterns.glider, 20, 20)
195
196
        run_simulation(opts, world)
197
198
199
200 if __name__ == '__main__':
        main()
201
```

The Skeleton Code



TASK 2

TASK 2

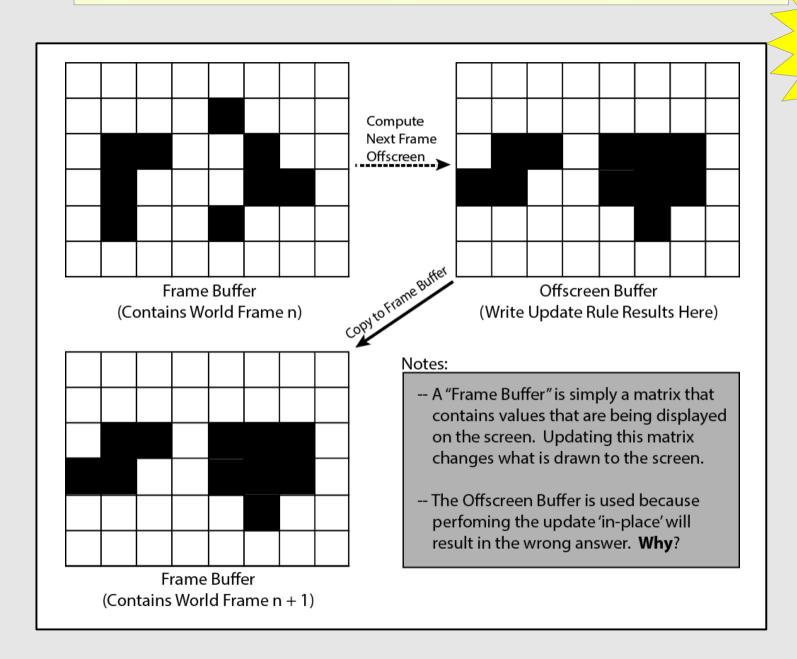
```
def blit(world, sprite, x, y):
70
       Accepts: world -- a 2D world pixel buffer generated by generate_world\)
                sprite -- a 2D matrix containing a pattern of 1s and 0s
                       -- x world coord where left edge of sprite will be placed
                       -- y world coord where top edge of sprite will be placed
76
       Returns: (Nothing)
78
       Description: Copies a 2D pixel pattern (i.e sprite) into the larger 2D
79
                            The sprite will be copied into the 2D world with
80
                     its top left corner being located at world coordinate (x,y)
       1111111
81
82
83
84
                             [ YOUR CODE GOES HERE ]
85
86
```

```
def main():
188
189
       The main function —— everything starts here!
190
       opts = get_commandline_options()
191
192
       world = generate_world(opts)
                                               TASK 3
       report_options(opts)
193
194
       blit(world, patterns.glider, 20, 20)
195
196
19<del>7</del>
     🔷 run_simulation(opts, world) 🚤
198
199
main()
201
```

```
run simulation(opts, world):
                                                                                      TASK 3
        Accepts: opts -- a populated command line options class instance
 91
 92
                 world -- a 2D world pixel buffer generated by generate world()
 93
       Returns: (Nothing)
 95
       Description: This function generates the plot that we will use as a
 97
                     rendering surfance. 'Living' cells (represented as 1s in
                     the 2D world matrix) will be rendered as black pixels and
 99
                     'dead' cells (represetned as 0s) will be rendered as
                     white pixels. The method FuncAnimation() accepts 4
101
                     parameters: the figure, the frame update function, a
                     tuple containing arguments to pass to the update function,
102
                     and the frame update interval (in milliseconds). Once the
103
                     show() method is called to display the plot, the frame
104
                     update function will be called every 'interval'
105
                     milliseconds to update the plot image (img).
106
        1111111
107
108
        if not world:
            print "The 'world' was never created. Exiting"
109
            sys.exit()
110
                                                                    world pixels are
111
                                                                      either 0 or 1
        fig = plt.figure()
112
113
        img = plt.imshow(world, interpolation='none', cmap='Greys', vmax=1, vmin=0)
        ani = animation.FuncAnimation(fig,
114
115
                                      update_frame,
                                      fargs=(opts, world, img)
116
                                      interval=opts.framedelay)
117
118
        plt.show()
```

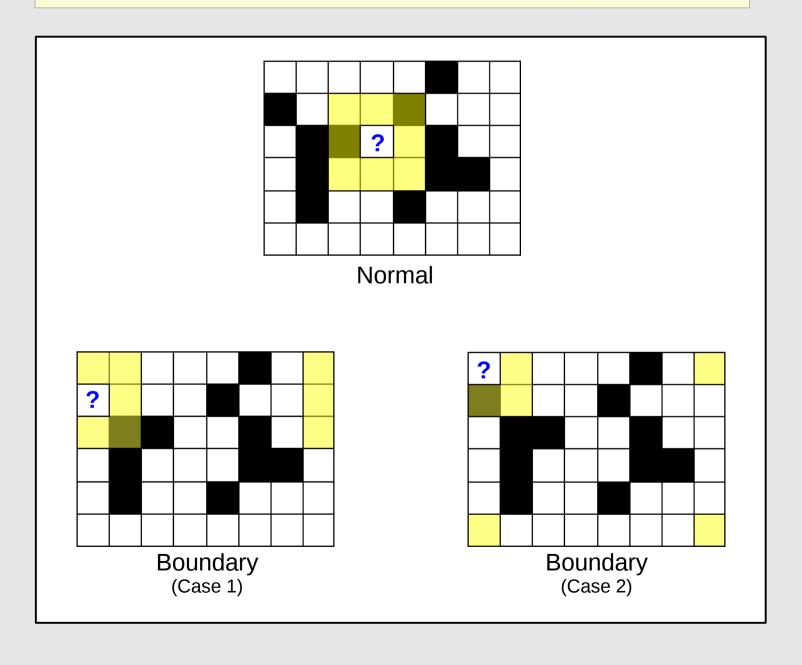
```
38 def update_frame(frame_num, opts, world, img):
                                                                                TASK 3
39
       Accepts: frame num -- (automatically passed in) current frame number
40
                opts -- a populated command line options instance
41
42
                world
                          -- the 2D world pixel buffer
43
                imq
                           -- the plot image
       1111111
44
45
47
       img.set array(world)
48
49
50
51
       # 'new world' so that we may maintain an in-tact copy of the current
52
       # 'world' at the same time.
53
       new world = []
54
       for row in world:
55
           new_world.append(row[:])
56
57
58
59
                             [ YOUR CODE GOES HERE ]
60
61
62
63
64
       # (i.e. make the future the present)
65
       world[:] = new_world[:]
66
       return img,
```

The Skeleton Code

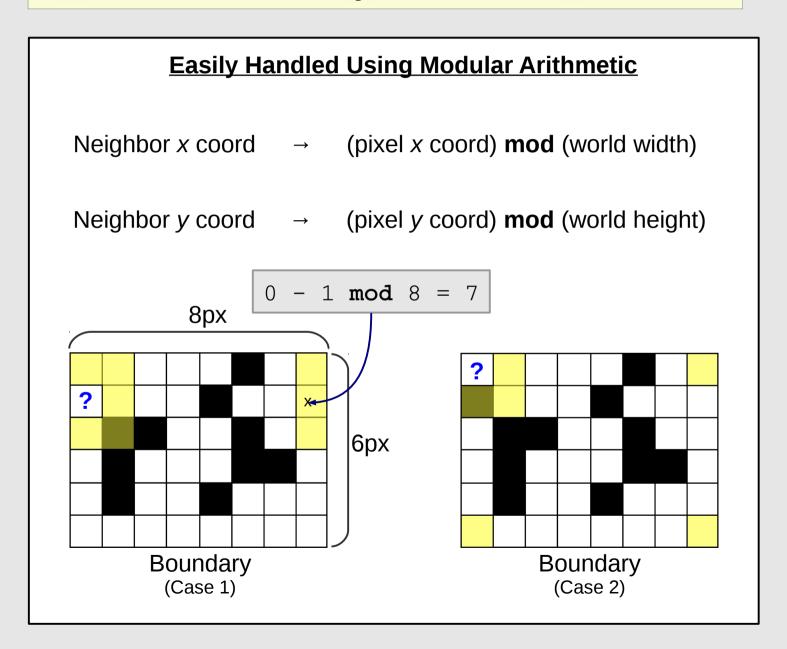


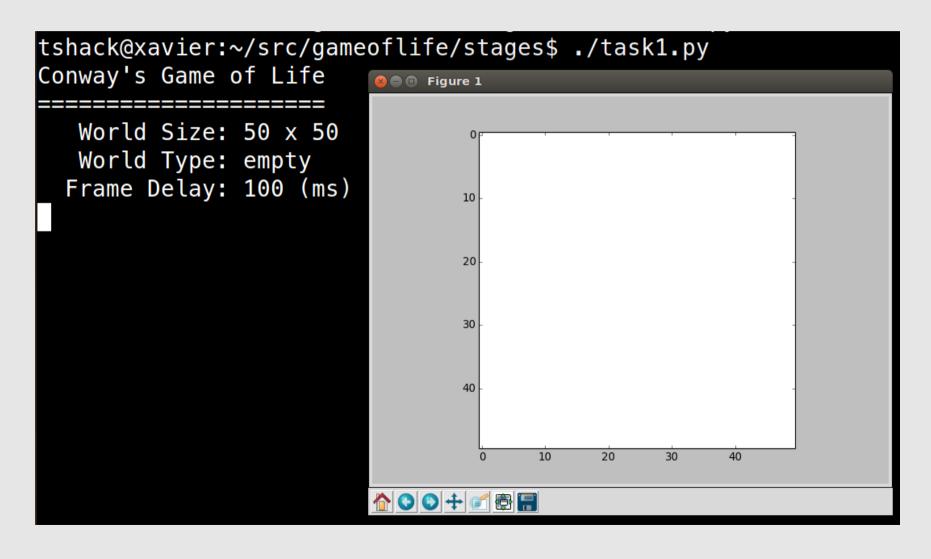
TASK 3

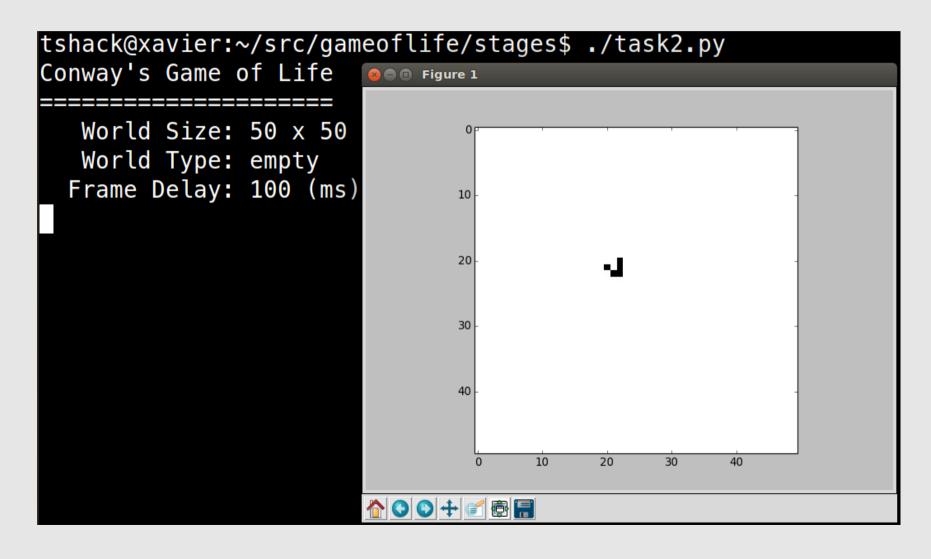
Boundary Conditions

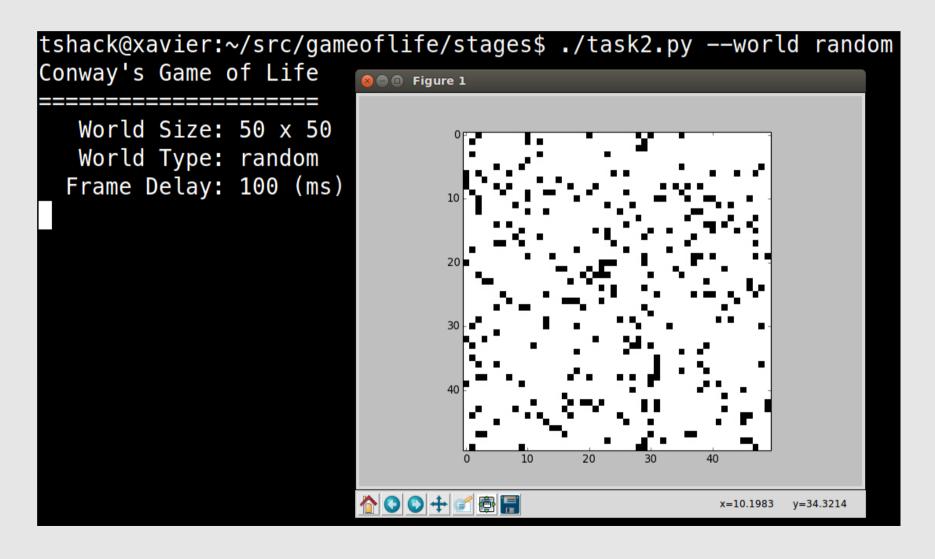


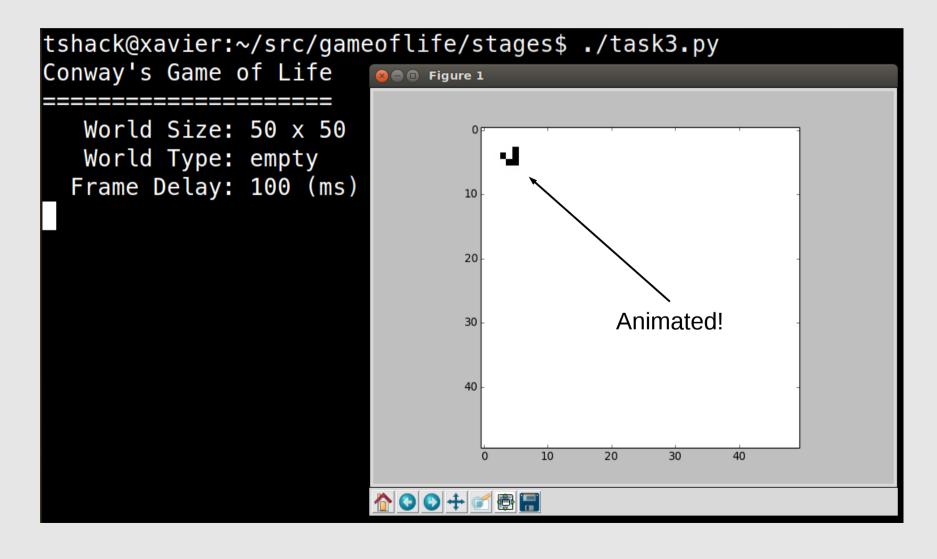
Boundary Conditions











Now Go Have Some Fun!

(check out other cool patterns in patterns.py)

