

# Information Transfer, using Ultrasound Waves

## Application

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Team Code:



# What We Are Going To Do



## Ultrasonic Data Transfer

Our project uses ultrasonic waves for data transfer, leveraging their ability to propagate through liquids and be contained by solid barriers.



## Cross-Platform Network

A many-to-many ultrasonic data transfer network for Android and iOS, with advanced collision avoidance.

# Why Ultrasound?

## RF Challenges

- Crowded frequency spectrums.
- Susceptible to electromagnetic interference.
- Signal congestion and "snooping" risks.
- Poor propagation through conductive media (e.g., water, human body).

## Ultrasound Advantages

- Propagates well through liquids and tissue.
- Naturally contained by solid barriers, enhancing security.
- Avoids crowded radio spectrums.
- Ideal for environments where RF fails (e.g., operating rooms, underwater).

## Why Is The Project Not Trivial?

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- **From PoC to Network Layer:** Transitioning from a basic one-to-one physical link to a robust, scalable **many-to-many** communication protocol.
- **Cross-Platform Interoperability:** Achieving seamless data exchange between heterogeneous mobile operating systems (**Android vs. iOS**) with unique audio chipsets and hardware constraints.
- **Physical and Algorithmic Constraints:** Managing severe acoustic challenges like **Multipath Propagation** (echoes) and **Self-Interference** on non-real-time mobile hardware.

# Project Objectives



## Bridging the Gap

From basic acoustic links to a robust, scalable, and secure network layer.



## Secure Multi-User Network

Establish a secure, multi-user ultrasonic network for non-RF applications.



## Advanced Arbitration

Implement CSMA/CA for sophisticated channel arbitration.



## Cross-Platform Compatibility

Ensure seamless operation between Android and iOS devices.

# Algorithmic challenges and solutions:

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## Mitigating Acoustic Interference and Noise

- **Challenge:** Indoor environments suffer from severe **Multipath Propagation**, where sound echoes overlap and cause Inter-Symbol Interference (ISI).
- **Solution:** Implementing a conservative **0.5ms bit duration** to allow signal echoes to decay and utilizing **Frequency-Shift Keying (FSK)** for robust signal modulation.

## Decentralized Channel Arbitration

- **Challenge:** Managing many-to-many communication without a central server or global clock.
- **Solution:** Developing a **CSMA/CA-based protocol** using unique, **prime-number-based backoff timers** to minimize collision probability.

## Overcoming the Hidden Node Problem

- **Challenge:** Undetectable collisions occurring when two transmitters, out of range of each other, simultaneously signal a central receiver.
- **Solution:** Utilizing a synchronized **RTS/CTS (Request to Send / Clear to Send) handshake** to logically reserve the medium at the receiver's end.

## Ensuring Data Integrity in Noisy Channels

- **Challenge:** Environmental noise can easily flip bits in a 160-bit frame.
- **Solution:** Implementing a robust **16-bit CRC checksum** and an **ACK/NACK feedback loop** to verify and retransmit corrupted packets.

# Building on Prior Work

Our project advances previous research in ultrasonic data transfer.

1

## Foundational PoC

Previous teams established a one-to-one ultrasonic communication channel between two Android devices.

2

## Physical Layer

Utilized Frequency-Shift Keying (FSK) for acoustic data transfer.

3

## Frequency Selection

Determined 18-19 kHz as optimal for inaudible mobile communication.

4

## Data Processing

Implemented Fast Fourier Transform (FFT) for decoding binary data.

# Hardware Equipment

## Heterogeneous Mobile Nodes (Receivers/Transmitters):

- We require at least **three concurrent devices** to validate the many-to-many network topology and collision avoidance.
- Testing must include a variety of models—specifically **two Android devices and one iPhone**—to account for different audio chipsets and microphone placements.

## Cross-Platform Development and Compilation:

- An **Apple Mac** is an essential requirement for utilizing the iOS development environment and compiling code for the iPhone Operating System.
- Development relies on standard Android and iOS APIs, specifically **AudioTrack/AudioRecord** for Android and **AVAudioEngine** for iOS.

## Testing Environment Tools:

- Access to standard physical obstacles (e.g., solid barriers and walls) is necessary to verify the **signal containment** and security properties of ultrasonic waves .
- Professional audio analysis software (e.g., **Audacity**) is required to verify that bit durations precisely meet the **0.5ms timing requirement** .



# Addressing Previous Limitations

## Past Challenges

- **Lack of Network Protocol:** Limited to one-to-one connections, unable to handle multiple devices simultaneously. Collisions occurred with three or more devices.
- **Single Platform Restriction:** Exclusively Android, limiting real-world application with heterogeneous devices (Android and iOS).



## Our Improvements

- **Many-to-Many Communication:** Introducing CSMA/CA for sophisticated channel arbitration.
- **Cross-Platform Compatibility:** Ensuring seamless operation between Android and iOS.

# What Is Our Approach? FSK algorithm

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## Protocol Overview & Parameters

- We utilize a multi-layered acoustic communication protocol designed for secure, many-to-many data transfer in non-RF environments.
- **Physical Layer:** Frequency-Shift Keying (FSK) modulation utilizing high-frequency carrier waves (18–20 kHz) to ensure inaudibility.
- **Data Link Layer:** A decentralized CSMA/CA arbitration mechanism with an RTS/CTS handshake to mitigate the Hidden Node Problem.
- **Protocol Inputs:**
  - **UserID** — 40-bit unique sender identifier.
  - **Sequence Number** — 8-bit packet order identifier.
  - **Payload** — 88-bit user message data.
- **Protocol Output:**
  - **Modulated Waveform** — FSK-encoded ultrasonic audio stream.

Algorithm (pseudo code)

```
Function TransmitSignal(bitStream):  
  track = InitAudioTrack(SAMPLE_RATE) for each bit in  
  bitStream:  
    if bit == 0  
      then targetFreq = 18000 HZ  
      else targetFreq = 20000  
    end if  
    buffer = GenerateSineWave(targetFreq, phase)  
    ApplyAmplitudeRamp(buffer)  
  track.write(buffer) end for track.stop() End Function
```

# What Is Our Approach? (CSMA/CA Protocol)

- **Mechanism:** We implement a decentralized, asynchronous "Listen-Before-Talk" principle to manage many-to-many communication without a central server.
- **Collision Avoidance:** Utilizing an RTS/CTS (Request to Send / Clear to Send) handshake to logically reserve the acoustic medium and solve the Hidden Node Problem.
- **Backoff Strategy:** We use unique prime-number-based timers to minimize the probability of simultaneous retransmissions.

## Protocol Inputs:

- **RBWP** — Regular Base Waiting Period (high prime number).
- **MBWP** — Minimal Base Waiting Period (low prime number fallback).
- **Channel State** — Real-time detection of 18–20 kHz activity.

## Protocol Outputs:

- **RTS/CTS Frames** — 56-bit control signals for medium reservation.
- **ACK/NACK** — Confirmation or error signals for frame integrity.

Function ExecuteCSMA(payload):

while True:

wait for RBWP\_Timer to expire

if ChannellIdle(18-20kHz)

then Transmit(RTS\_Frame)

wait for CTS\_Frame (Timeout = 2s)

if CTS\_Received

then Transmit(Data\_Frame)

wait for ACK

return Success

else

wait MBWP (Random Backoff)

end if

else

wait MBWP until idle

end if

end while

End Function

# Why CSMA/CA Works

## Collision Avoidance

CSMA/CA verifies channel availability before transmission, preventing signal collisions and packet loss.

## Cross-Platform Compatibility

Robust frameworks exist for standardized Digital Signal Processing (DSP) and uniform hardware access.

## Resilience to Dynamic Topology

Decentralized and asynchronous, allowing devices to join or leave instantly without network stalls.

## Asynchronous Operation

"Listen-Before-Talk" principle is robust for devices with varying OS delays, unlike strict time synchronization.

## Hidden Node Solution (RTS/CTS)

Explicitly reserves the medium at the receiver's end, ensuring all nodes know the channel is busy.

Explain abbreviation in the title not in the text

# Implementation: Data Encoding (FSK)

## Frequency-Shift Keying (FSK)

Our application uses FSK to encode binary data onto ultrasonic sound waves. This digital modulation technique changes the frequency of a carrier signal to transmit information.

- **Binary FSK (BFSK):** Carrier shifts between two discrete frequencies for binary (0s and 1s) information.
- **Frequency Selection:** 18 kHz for '0' and 20 kHz for '1', inaudible to humans.
- **Bit Duration:** Optimal 0.5 milliseconds per bit, allowing for signal stability and receiver sampling.

# Implementation: Connection Establishment (RTS/CTS)

1

## RTS (Request to Send)

Transmitter sends a short control frame indicating intent to transmit and occupy the medium.

2

## Wait (SIFS)

Transmitter listens for a predefined window (Timeout).

3

## CTS (Clear to Send)

If the receiver is idle, it responds with a CTS frame, informing other participants the channel is busy.

4

## Data Transmission

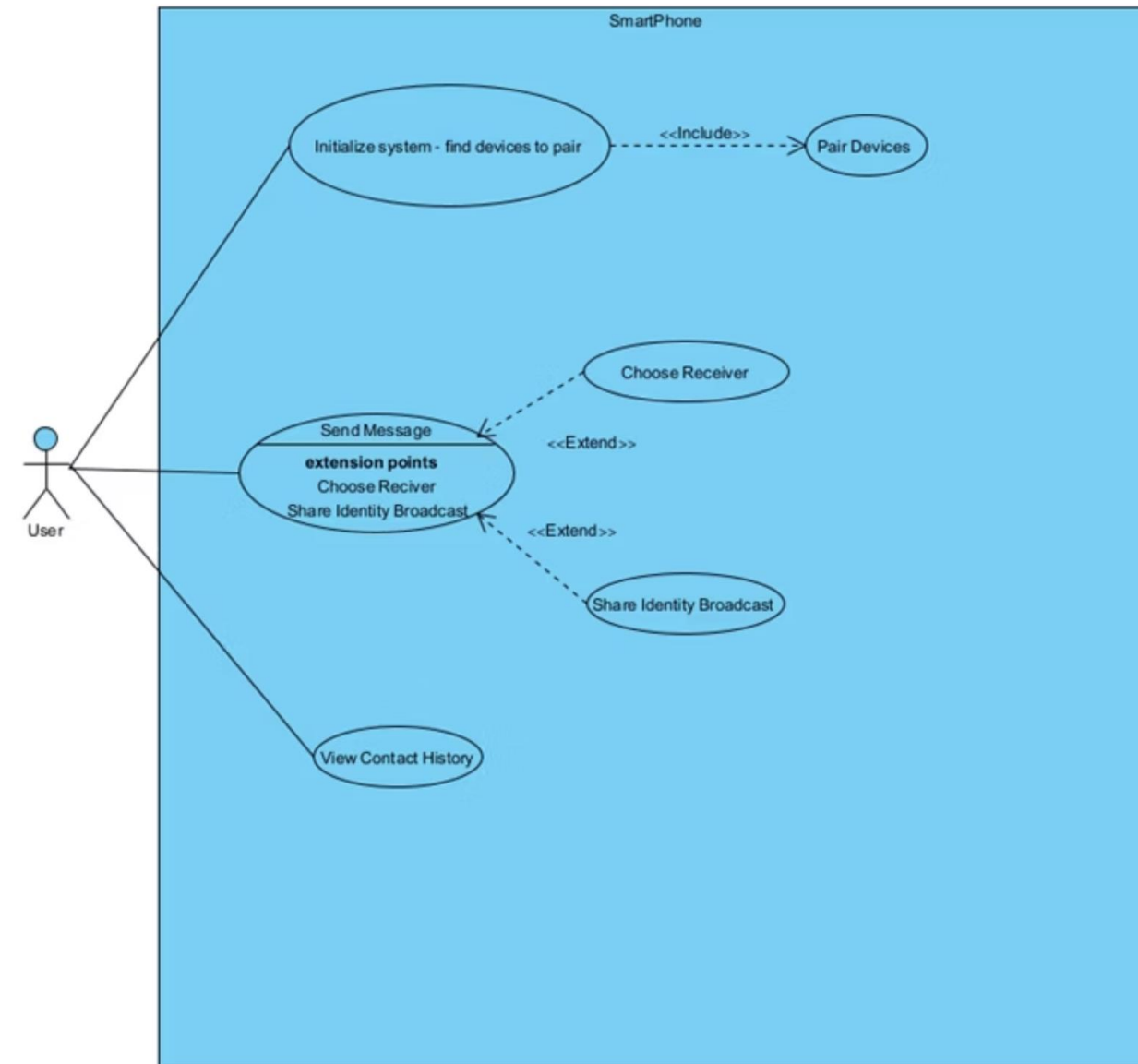
Upon receiving CTS, the transmitter sends the full data packet.

5

## Acknowledgement (ACK)

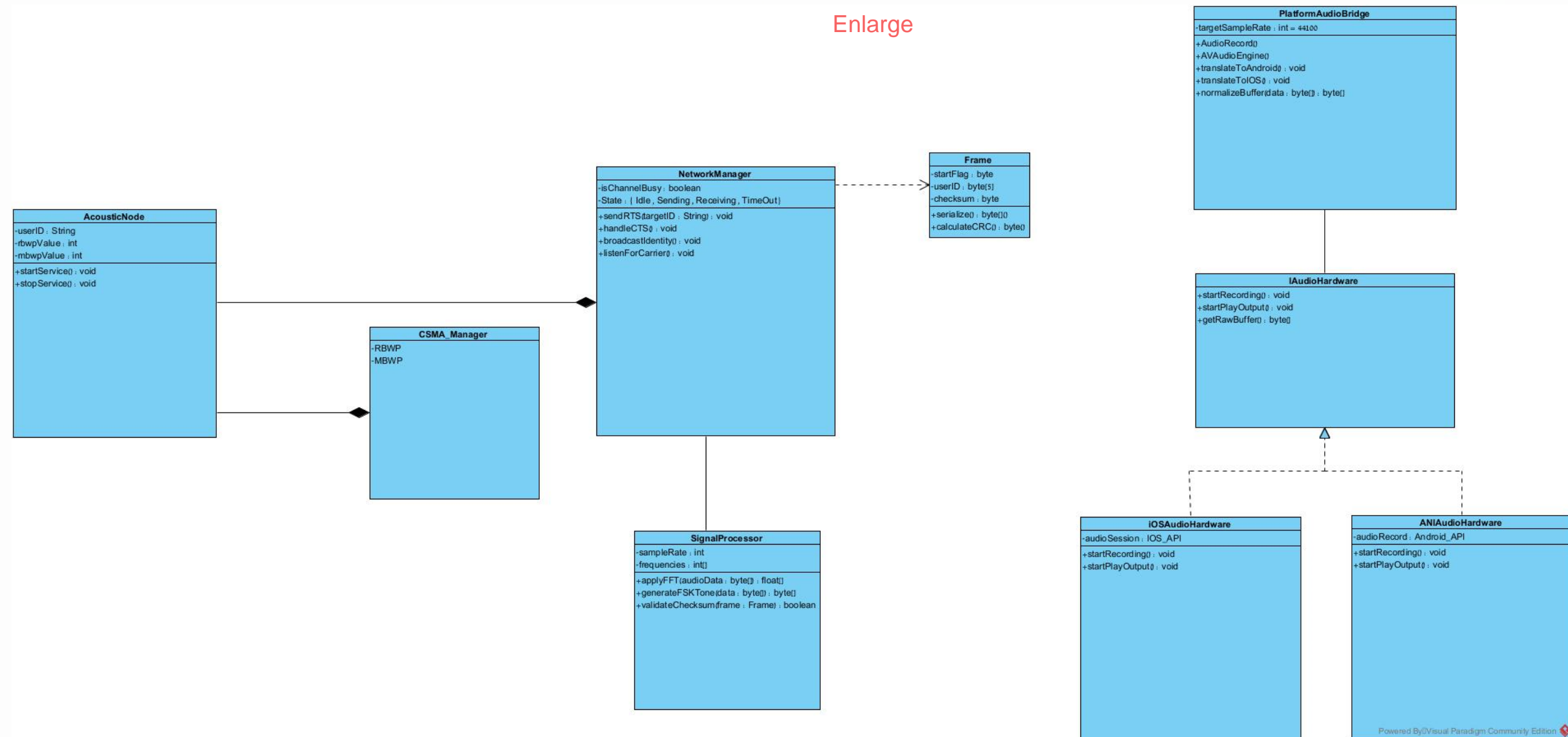
Receiver sends ACK upon correct data arrival; sender retransmits if no ACK.

# Use Case: Many-to-Many Interaction and Messaging Protocol



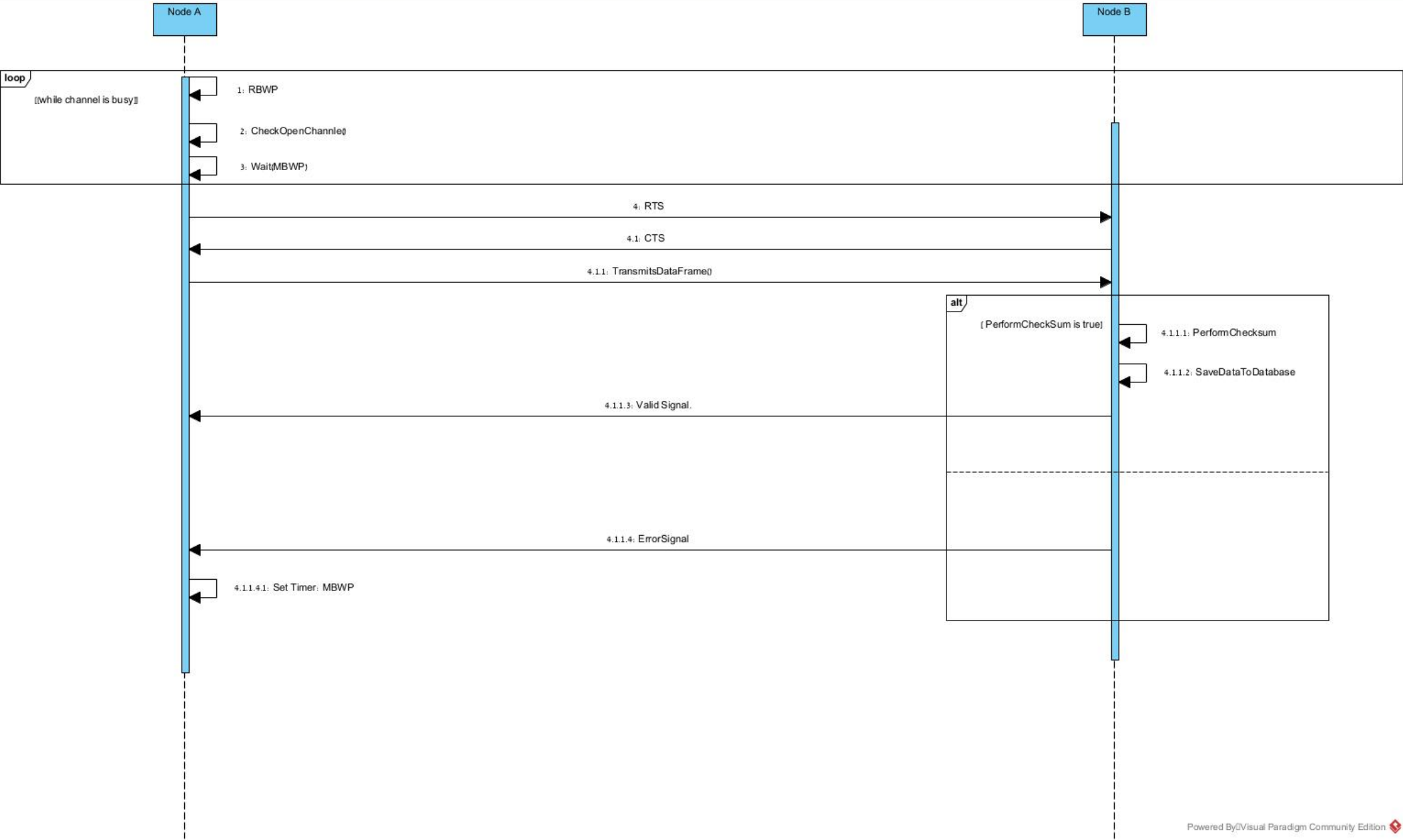
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# Class Diagram: Structural Design of the CSMA/CA and Signal Processing Layers





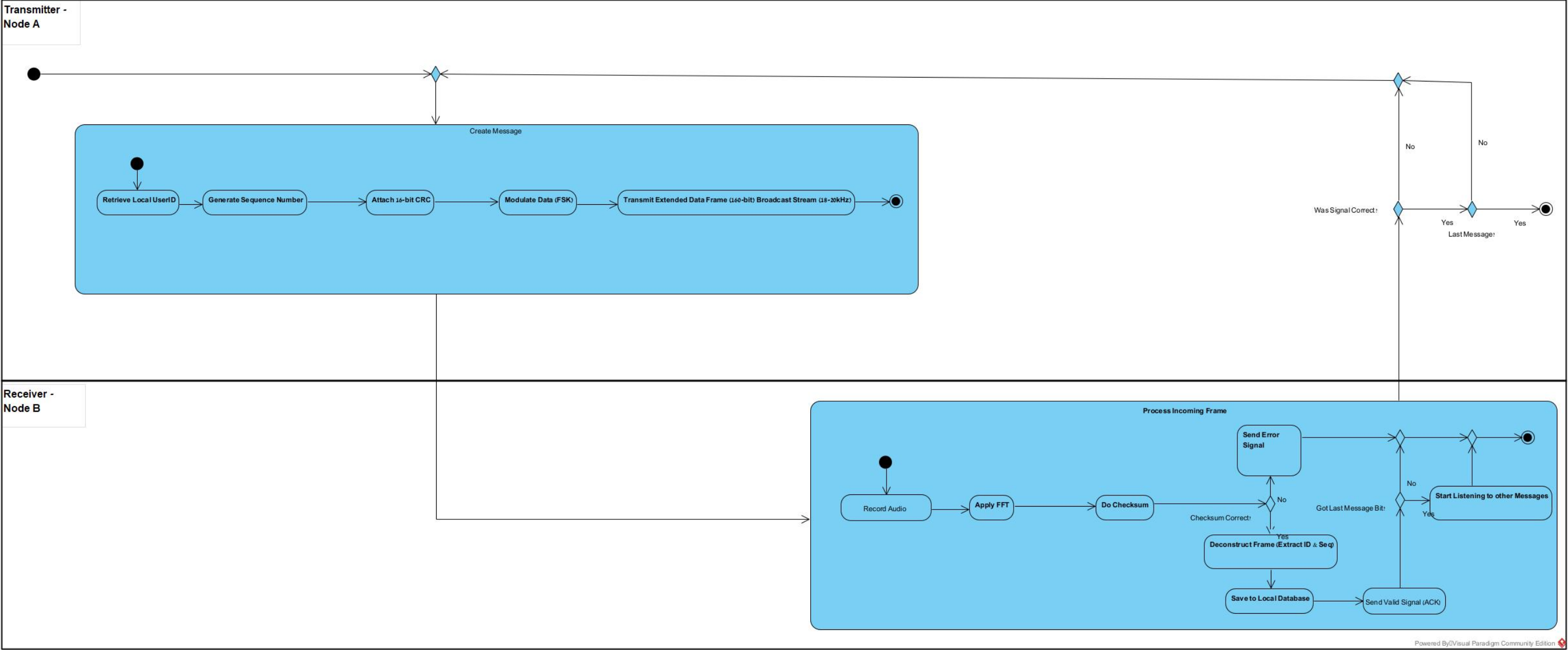
# Sequence Diagram: CSMA/CA Protocol with RTS/CTS Handshake Sequence



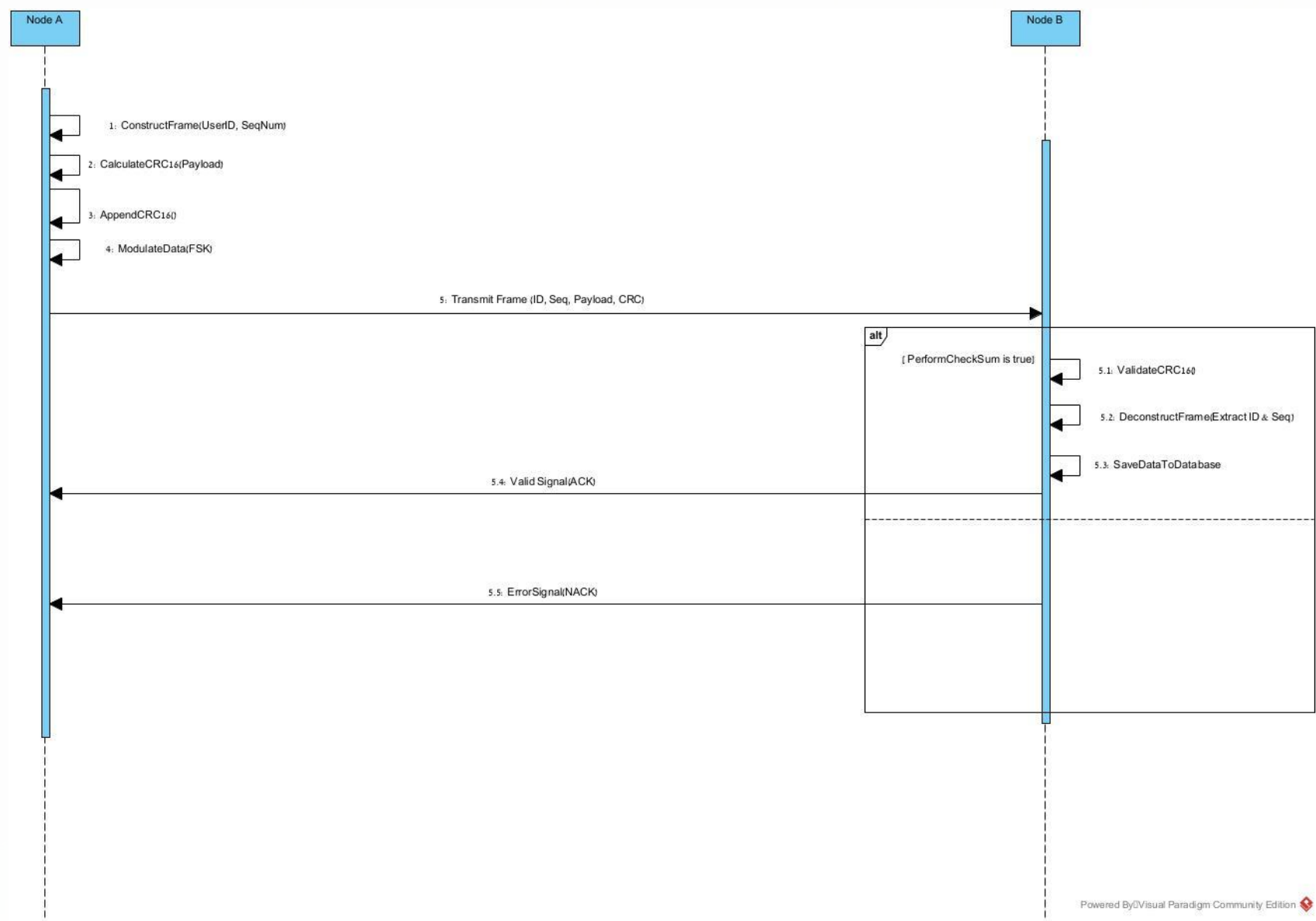
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# Activity Diagram: CSMA/CA Protocol with RTS/CTS Handshake

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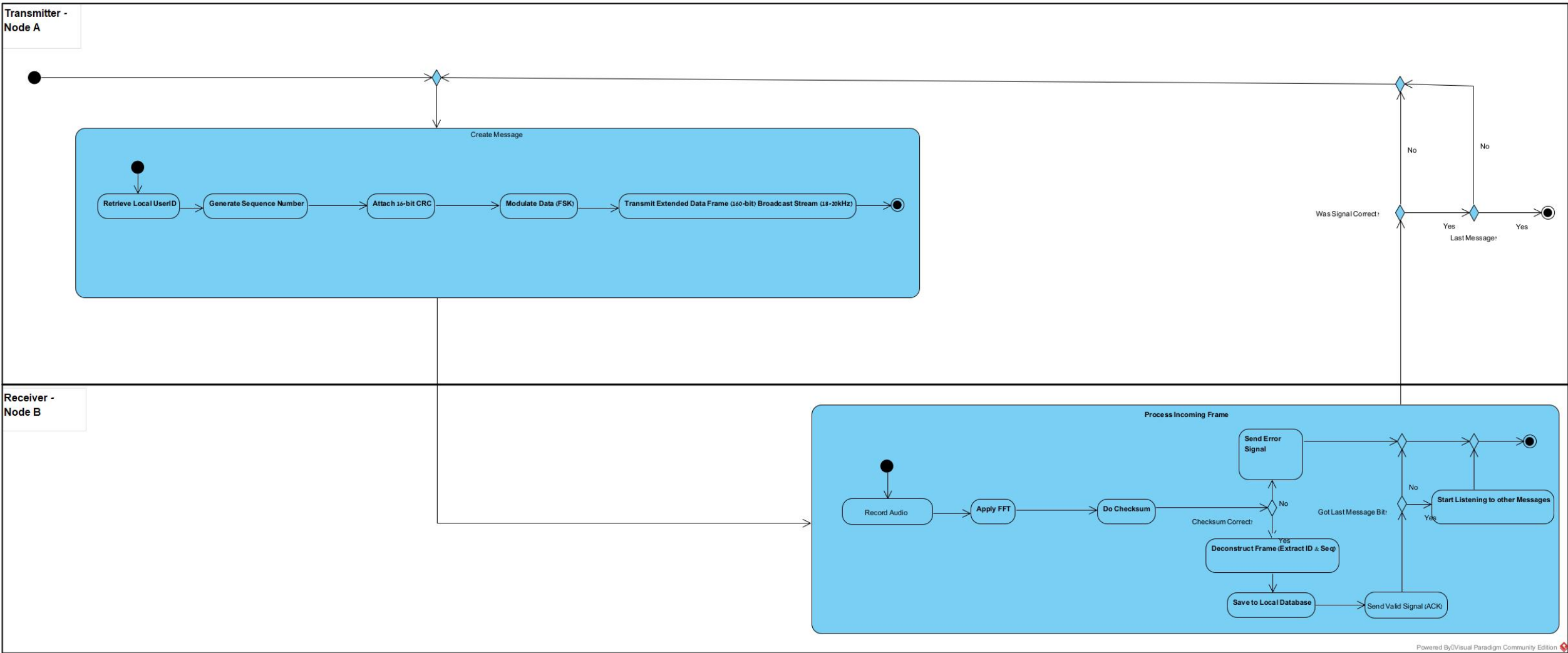
# Sequence Diagram – Data Transmission and Frame Verification Protocol



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# Activity Diagram: Data Framing and Physical Layer

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# Expected Results & Key Specifications

## Fully Functional Network

Acoustic communication network using ultrasonic waves.

## Cross-Platform

Seamless communication between Android and iOS devices.

## Reliable Protocol

Data Link Layer with RTS/CTS collision avoidance.

## Capacity & Range

Supports 3+ concurrent nodes within a 2-meter radius.

## Many-to-Many Topology

Manages data transfer from multiple emitters to multiple recipients.