CPSVerification

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Chapter 1

Hybrid Systems Preliminaries

This chapter contains preliminary lemmas for verification of Hybrid Systems.

1.1 Miscellaneous

1.1.1 Functions

1.1.2 Orders

```
lemma cSup-eq-linorder:
 {\bf fixes} \ c{::'a}{::} conditionally{-}complete{-}linorder
 assumes X \neq \{\} and \forall x \in X. x \leq c
   and bdd-above X and \forall y < c. \exists x \in X. y < x
 shows Sup X = c
 apply(rule\ order-antisym)
 using assms apply(simp add: cSup-least)
 using assms by (subst le-cSup-iff)
lemma cSup-eq:
  \mathbf{fixes}\ c{::}'a{::}conditionally{-}complete{-}lattice
 \textbf{assumes} \ \forall \, x \in X. \ x \leq c \ \textbf{and} \ \exists \, x \in X. \ c \leq x
 shows Sup X = c
 apply(rule order-antisym)
  apply(rule\ cSup\ -least)
  using assms apply(blast, blast)
  using assms(2) apply safe
```

```
apply(subgoal-tac\ x \leq Sup\ X,\ simp)
 by (metis\ assms(1)\ cSup-eq-maximum\ eq-iff)
\mathbf{lemma}\ bdd-above-ltimes:
 fixes c::'a::linordered-ring-strict
 assumes c > \theta and bdd-above X
 shows bdd-above \{c * x | x. x \in X\}
 using assms unfolding bdd-above-def apply clarsimp
 apply(rule-tac \ x=c*M \ in \ exI, \ clarsimp)
 using mult-left-mono by blast
lemma finite-nat-minimal-witness:
 fixes P :: ('a::finite) \Rightarrow nat \Rightarrow bool
 assumes \forall i. \exists N :: nat. \forall n \geq N. P i n
 shows \exists N. \ \forall i. \ \forall n \geq N. \ P \ i \ n
proof-
 let ?bound i = (LEAST \ N. \ \forall \ n \geq N. \ P \ i \ n)
 let ?N = Max \{?bound \ i \mid i.i \in UNIV\}
 {fix n::nat and i::'a
   obtain M where \forall n \geq M. P i n
     using assms by blast
   hence obs: \forall m \geq ?bound i. P i m
     using LeastI[of \lambda N. \forall n \geq N. P(i, n] by blast
   assume n \geq ?N
   have finite \{?bound\ i\ | i.\ i\in UNIV\}
     using finite-Atleast-Atmost-nat by fastforce
   hence ?N \ge ?bound i
     using Max-ge by blast
   hence n > ?bound i
     using \langle n \geq ?N \rangle by linarith
   hence P i n
     using obs by blast}
 thus \exists N. \ \forall i \ n. \ N \leq n \longrightarrow P \ i \ n
   by blast
qed
1.1.3
          Real Numbers
lemma sqrt-le-itself: 1 \le x \Longrightarrow sqrt \ x \le x
 by (metis basic-trans-rules (23) monoid-mult-class.power2-eq-square more-arith-simps (6)
     mult-left-mono real-sqrt-le-iff 'zero-le-one)
lemma sqrt-real-nat-le:sqrt (real n) \le real n
 by (metis (full-types) abs-of-nat le-square of-nat-mono of-nat-mult real-sqrt-abs2
real-sqrt-le-iff)
lemma sq-le-cancel:
```

shows $(a::real) \ge 0 \Longrightarrow b \ge 0 \Longrightarrow a^2 \le b * a \Longrightarrow a \le b$

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```
and (a::real) \ge 0 \Longrightarrow b \ge 0 \Longrightarrow a^2 \le a * b \Longrightarrow a \le b
     apply(metis\ less-eq\ real-def\ mult.commute\ mult-le-cancel-left\ semiring-normalization-rules (29))
    by (metis less-eq-real-def mult-le-cancel-left semiring-normalization-rules (29))
named-theorems triq-simps simplification rules for trigonometric identities
\mathbf{lemmas}\ trig-identities = sin\text{-}squared\text{-}eq[\mathit{THEN}\ sym]\ cos\text{-}squared\text{-}eq[\mathit{symmetric}]\ cos\text{-}diff[\mathit{symmetric}]
cos-double
declare sin-minus [trig-simps]
        and cos-minus [trig-simps]
        and trig-identities (1,2) [trig-simps]
        and sin-cos-squared-add [trig-simps]
        and sin-cos-squared-add2 [trig-simps]
        and sin-cos-squared-add3 [trig-simps]
        and trig-identities(3) [trig-simps]
lemma sin-cos-squared-add4 [trig-simps]:
     fixes x :: 'a :: \{banach, real-normed-field\}
    shows x * (sin t)^2 + x * (cos t)^2 = x
   by (metis mult.right-neutral semiring-normalization-rules (34) sin-cos-squared-add)
lemma [trig-simps, simp]:
    fixes x :: 'a :: \{banach, real-normed-field\}
    shows (x * cos t - y * sin t)^2 + (x * sin t + y * cos t)^2 = x^2 + y^2
proof-
    have (x * cos t - y * sin t)^2 = x^2 * (cos t)^2 + y^2 * (sin t)^2 - 2 * (x * cos t)
*(y*sin t)
        by(simp add: power2-diff power-mult-distrib)
    also have (x * \sin t + y * \cos t)^2 = y^2 * (\cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (x *
cos\ t)*(y*sin\ t)
        \mathbf{by}(simp~add:~power2\text{-}sum~power\text{-}mult\text{-}distrib)
    ultimately show (x * cos t - y * sin t)^2 + (x * sin t + y * cos t)^2 = x^2 + y^2
     by (simp\ add:\ Groups.mult-ac(2)\ Groups.mult-ac(3)\ right-diff-distrib\ sin-squared-eq)
```

1.2 Calculus

thm trig-simps

qed

1.2.1 Single variable Derivatives

```
notation has-derivative ((1(D - \mapsto (-))/ -) [65,65] 61) notation has-vderiv-on ((1 D - = (-)/ on -) [65,65] 61) notation norm ((1||-||) [65] 61)
```

 $\mathbf{lemma}\ exp\text{-}scaleR\text{-}has\text{-}derivative\text{-}right[derivative\text{-}intros]:}$

```
fixes f::real \Rightarrow real
 assumes D f \mapsto f' at x within s and (\lambda h. f' h *_R (exp (f x *_R A) *_A)) = g'
  shows D(\lambda x. exp(fx *_R A)) \mapsto g' at x within s
proof -
  from assms have bounded-linear f' by auto
  with real-bounded-linear obtain m where f': f' = (\lambda h. h * m) by blast
 show ?thesis
   using vector-diff-chain-within[OF - exp-scaleR-has-vector-derivative-right, of f
m \ x \ s \ A] assms f'
   by (auto simp: has-vector-derivative-def o-def)
qed
named-theorems poly-derivatives compilation of derivatives for kinematics and
polynomials.
declare has-vderiv-on-const [poly-derivatives]
   and has-vderiv-on-id [poly-derivatives]
   and derivative-intros(191) [poly-derivatives]
   and derivative-intros(192) [poly-derivatives]
   and derivative-intros(194) [poly-derivatives]
lemma has-vector-derivative-mult-const [derivative-intros]:
  ((*) a has-vector-derivative a) F
  by (auto intro: derivative-eq-intros)
lemma has-derivative-mult-const [derivative-intros]: D (*) a \mapsto (\lambda x. \ x *_R \ a) \ F
  using has-vector-derivative-mult-const unfolding has-vector-derivative-def by
simp
lemma has-vderiv-on-mult-const [derivative-intros]: D (*) a = (\lambda x. \ a) on T
  using has-vector-derivative-mult-const unfolding has-vderiv-on-def by auto
lemma has-vderiv-on-power2 [derivative-intros]: D power2 = (*) 2 on T
  unfolding has-vderiv-on-def has-vector-derivative-def apply clarify
  by (rule-tac\ f'1=\lambda\ t.\ t\ in\ derivative-eq-intros(15))\ auto
lemma has-vderiv-on-divide-cnst [derivative-intros]: a \neq 0 \Longrightarrow D(\lambda t. t/a) = (\lambda t.
1/a) on T
  unfolding has-vderiv-on-def has-vector-derivative-def apply clarify
  apply(rule-tac f'1=\lambda t. t and g'1=\lambda x. 0 in derivative-eq-intros(18))
 by(auto intro: derivative-eq-intros)
\mathbf{lemma} \ [\mathit{poly-derivatives}] \colon g = (*) \ \mathcal{2} \Longrightarrow D \ \mathit{power2} = g \ \mathit{on} \ T
  using has-vderiv-on-power2 by auto
lemma [poly-derivatives]: D f = f' on T \Longrightarrow g = (\lambda t. - f' t) \Longrightarrow D (\lambda t. - f t)
= g \ on \ T
  using has-vderiv-on-uminus by auto
```

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```
lemma [poly-derivatives]: a \neq 0 \Longrightarrow g = (\lambda t. 1/a) \Longrightarrow D (\lambda t. t/a) = g \text{ on } T
 using has-vderiv-on-divide-cnst by auto
\mathbf{lemma}\ \mathit{has-vderiv-on-compose-eq}\colon
 assumes D f = f' on g ' T
   and D g = g' on T
   and h = (\lambda x. g' x *_R f' (g x))
 shows D(\lambda t. f(g t)) = h \ on \ T
 apply(subst\ ssubst[of\ h],\ simp)
 using assms has-vderiv-on-compose by auto
lemma [poly-derivatives]:
 assumes (a::real) \neq 0 and D f = f' on T and g = (\lambda t. (f' t)/a)
 shows D(\lambda t. (f t)/a) = g \ on \ T
 apply(rule\ has-vderiv-on-compose-eq[of\ \lambda t.\ t/a\ \lambda t.\ 1/a])
 using assms by (auto intro: poly-derivatives)
lemma [poly-derivatives]:
 fixes f::real \Rightarrow real
 assumes D f = f' on T and g = (\lambda t. 2 *_R (f t) * (f' t))
 shows D(\lambda t. (f t)^2) = g \ on \ T
 apply(rule has-vderiv-on-compose-eq[of \lambda t. t^2])
 using assms by (auto intro!: poly-derivatives)
lemma has-vderiv-on-cos: D f = f' on T \Longrightarrow D (\lambda t. \cos (f t)) = (\lambda t. - \sin (f t))
*_R (f't)) on T
 apply(rule\ has-vderiv-on-compose-eq[of\ \lambda t.\ cos\ t])
 unfolding has-vderiv-on-def has-vector-derivative-def apply clarify
 by(auto intro!: derivative-eq-intros simp: fun-eq-iff)
lemma has-vderiv-on-sin: D f = f' on T \Longrightarrow D (\lambda t. \sin (f t)) = (\lambda t. \cos (f t))
*_R (f't)) on T
 apply(rule\ has-vderiv-on-compose-eq[of\ \lambda t.\ sin\ t])
 unfolding has-vderiv-on-def has-vector-derivative-def apply clarify
 by(auto intro!: derivative-eq-intros simp: fun-eq-iff)
lemma [poly-derivatives]:
 assumes D f = f' on T and g = (\lambda t. - sin (f t) *_R (f' t))
 shows D(\lambda t. cos(f t)) = g on T
 using assms and has-vderiv-on-cos by auto
lemma [poly-derivatives]:
 assumes D f = f' on T and g = (\lambda t. \cos (f t) *_R (f' t))
 shows D(\lambda t. \sin(f t)) = g \text{ on } T
 using assms and has-vderiv-on-sin by auto
lemma D(\lambda t. \ a * t^2 / 2) = (*) \ a \ on \ T
 by(auto intro!: poly-derivatives)
```

```
lemma D (\lambda t. a*t^2 / 2 + v*t + x) = (\lambda t. a*t + v) on T by (auto intro!: poly-derivatives)

lemma D (\lambda r. a*r + v) = (\lambda t. a) on T by (auto intro!: poly-derivatives)

lemma D (\lambda t. v*t - a*t^2 / 2 + x) = (\lambda x. v - a*x) on T by (auto intro!: poly-derivatives)

lemma D (\lambda t. v - a*t) = (\lambda x. -a) on T by (auto intro!: poly-derivatives)
```

1.2.2 Multivariable Derivatives

```
\mathbf{lemma}\ eventually \text{-} all \text{-} finite 2 \colon
  fixes P :: ('a::finite) \Rightarrow 'b \Rightarrow bool
  assumes h: \forall i. eventually (P i) F
  shows eventually (\lambda x. \ \forall i. \ P \ i \ x) \ F
proof(unfold eventually-def)
  let ?F = Rep\text{-filter } F
  have obs: \forall i. ?F (P i)
    using h by auto
  have ?F(\lambda x. \forall i \in UNIV. P i x)
    \mathbf{apply}(\mathit{rule\ finite-induct})
    \mathbf{by}(auto\ intro:\ eventually\text{-}conj\ simp:\ obs\ h)
  thus ?F(\lambda x. \forall i. P i x)
    by simp
\mathbf{qed}
lemma eventually-all-finite-mono:
  fixes P :: ('a::finite) \Rightarrow 'b \Rightarrow bool
  assumes h1: \forall i. eventually (P i) F
      and h2: \forall x. (\forall i. (P i x)) \longrightarrow Q x
  shows eventually Q F
proof-
  have eventually (\lambda x. \ \forall i. \ P \ i \ x) \ F
    using h1 eventually-all-finite2 by blast
  thus eventually Q F
    unfolding eventually-def
    using h2 eventually-mono by auto
qed
lemma frechet-vec-lambda:
  fixes f::real \Rightarrow ('a::banach) \hat{\ } ('m::finite) and x::real and T::real set
  defines x_0 \equiv netlimit (at x within T) and <math>m \equiv real \ CARD('m)
  assumes \forall i. ((\lambda y. (f y \$ i - f x_0 \$ i - (y - x_0) *_R f' x \$ i) /_R (||y - x_0||))
   \longrightarrow \theta) (at x within T)
```

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```
shows ((\lambda y. (f y - f x_0 - (y - x_0) *_R f' x) /_R (||y - x_0||)) \longrightarrow \theta) (at x
proof(simp add: tendsto-iff, clarify)
  fix \varepsilon::real assume 0 < \varepsilon
  let ?\Delta = \lambda y. y - x_0 and ?\Delta f = \lambda y. f y - f x_0
 let P = \lambda i \ e \ y. inverse |P| \Delta y| * (||fy  i - fx_0  i - P \Delta y *_R f'x  i|) < e
    and ?Q = \lambda y. inverse |?\Delta y| * (||?\Delta f y - ?\Delta y *_R f' x||) < \varepsilon
  have 0 < \varepsilon / sqrt m
    using \langle \theta < \varepsilon \rangle by (auto simp: assms)
  hence \forall i. eventually (\lambda y. ?P \ i \ (\varepsilon \ / \ sqrt \ m) \ y) \ (at \ x \ within \ T)
    using assms unfolding tendsto-iff by simp
  thus eventually ?Q (at x within T)
 proof(rule eventually-all-finite-mono, simp add: norm-vec-def L2-set-def, clarify)
    \mathbf{fix} \ t :: real
    let ?c = inverse |t - x_0| and ?u t = \lambda i. ft \$ i - fx_0 \$ i - ?\Delta t *_R f' x \$ i
    assume hyp: \forall i. ?c * (||?u t i||) < \varepsilon / sqrt m
    hence \forall i. (?c *_R (||?u \ t \ i||))^2 < (\varepsilon / sqrt \ m)^2
      \mathbf{by}\ (simp\ add\colon power\text{-}strict\text{-}mono)
    hence \forall i. ?c^2 * ((\|?u \ t \ i\|))^2 < \varepsilon^2 / m
      by (simp add: power-mult-distrib power-divide assms)
    hence \forall i. ?c^2 * ((\|?u \ t \ i\|))^2 < \varepsilon^2 / m
      by (auto simp: assms)
    also have (\{\}::'m\ set) \neq UNIV \land finite\ (UNIV :: 'm\ set)
      by simp
    ultimately have (\sum i \in UNIV. ?c^2 * ((||?u \ t \ i||))^2) < (\sum (i::'m) \in UNIV. \varepsilon^2 / (||?u \ t \ i||))^2)
m)
      by (metis (lifting) sum-strict-mono)
    moreover have ?c^2 * (\sum i \in UNIV. (||?u \ t \ i||)^2) = (\sum i \in UNIV. ?c^2 * (||?u \ t
i||)^2
      using sum-distrib-left by blast
    ultimately have ?c^2*(\sum i{\in}\textit{UNIV}.~(\|\,?u~t~i\|)^2)<\varepsilon^2
      by (simp add: assms)
    hence sqrt\ (?c^2 * (\sum i \in UNIV.\ (\|?u\ t\ i\|)^2)) < sqrt\ (\varepsilon^2)
      using real-sqrt-less-iff by blast
    also have \dots = \varepsilon
      using \langle \theta < \varepsilon \rangle by auto
   moreover have ?c * sqrt (\sum i \in UNIV. (||?u \ t \ i||)^2) = sqrt (?c^2 * (\sum i \in UNIV.
(\|?u\ t\ i\|)^2)
      by (simp add: real-sqrt-mult)
    ultimately show ?c * sqrt (\sum i \in UNIV. (||?u t i||)^2) < \varepsilon
      by simp
  qed
qed
lemma has-derivative-vec-lambda:
  fixes f::real \Rightarrow ('a::banach) \hat{\ } ('m::finite)
  assumes \forall i. D (\lambda t. f t \$ i) \mapsto (\lambda h. h *_R f' x \$ i) (at x within T)
  shows D f \mapsto (\lambda h. h *_R f' x) at x within T
  apply(unfold has-derivative-def, safe)
```

```
apply(force simp: bounded-linear-def bounded-linear-axioms-def)
  using assms frechet-vec-lambda of x T unfolding has-derivative-def by auto
\mathbf{lemma}\ \mathit{has-vderiv-on-vec-lambda}\colon
  fixes f::(('a::banach) \hat{\ } ('n::finite)) \Rightarrow ('a\hat{\ }'n)
  assumes \forall i. D (\lambda t. x t \$ i) = (\lambda t. f (x t) \$ i) on T
 shows D x = (\lambda t. f(x t)) on T
 using assms unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp
 \mathbf{by}(\mathit{rule\ has-derivative-vec-lambda},\ \mathit{simp})
lemma frechet-vec-nth:
  fixes f::real \Rightarrow ('a::real-normed-vector) \ 'm and x::real and T::real set
  defines x_0 \equiv netlimit (at x within T)
  assumes ((\lambda y. (f y - f x_0 - (y - x_0) *_R f' x) /_R (||y - x_0||)) \longrightarrow \theta) (at x
within T
  shows ((\lambda y. (f y \$ i - f x_0 \$ i - (y - x_0) *_R f' x \$ i) /_R (||y - x_0||)) \longrightarrow
\theta) (at x within T)
proof(unfold tendsto-iff dist-norm, clarify)
  let ?\Delta = \lambda y. y - x_0 and ?\Delta f = \lambda y. f y - f x_0
  fix \varepsilon::real assume 0 < \varepsilon
  let P = \lambda y. \|(P \Delta f y - P \Delta y *_R f' x)/_R (\|P \Delta y\|) - \theta\| < \varepsilon
  and Q = \lambda y. \|(fy \ \ i - fx_0 \ \ i - \ \ \Delta \ \ y *_R f'x \ \ i) /_R (\|\ \ \Delta \ \ y\|) - \theta\| < \varepsilon
  have eventually ?P (at x within T)
    using \langle \theta < \varepsilon \rangle assms unfolding tendsto-iff by auto
  thus eventually ?Q (at x within T)
  \mathbf{proof}(rule\text{-}tac\ P=?P\ \mathbf{in}\ eventually\text{-}mono,\ simp\text{-}all)
   let ?u \ y \ i = f \ y \ \$ \ i - f \ x_0 \ \$ \ i - ?\Delta \ y \ *_R f' \ x \ \$ \ i
   fix y assume hyp:inverse |?\Delta y| * (||?\Delta f y - ?\Delta y *_R f' x||) < \varepsilon
   have \|(?\Delta f y - ?\Delta y *_R f' x) \$ i\| \le \|?\Delta f y - ?\Delta y *_R f' x\|
      \mathbf{using} \ \mathit{Finite-Cartesian-Product.norm-nth-le} \ \mathbf{by} \ \mathit{blast}
    also have \|?u\ y\ i\| = \|(?\Delta f\ y - ?\Delta\ y *_R f'\ x) \ \
      by simp
    ultimately have \|?u\ y\ i\| \leq \|?\Delta f\ y - ?\Delta\ y *_R f'\ x\|
      by linarith
   \mathbf{hence}\ \mathit{inverse}\ |?\Delta\ y|*(\|?u\ y\ i\|) \leq \mathit{inverse}\ |?\Delta\ y|*(\|?\Delta f\ y\ -\ ?\Delta\ y*_R\ f\ ')
      by (simp add: mult-left-mono)
    thus inverse |?\Delta y| * (||fy \$ i - fx_0 \$ i - ?\Delta y *_R f'x \$ i||) < \varepsilon
      using hyp by linarith
  qed
qed
lemma has-derivative-vec-nth:
  assumes D f \mapsto (\lambda h. \ h *_R f' x) at x within T
  shows D (\lambda t. f t \$ i) \mapsto (\lambda h. h *_R f' x \$ i) at x within T
  apply(unfold\ has-derivative-def,\ safe)
  apply(force simp: bounded-linear-def bounded-linear-axioms-def)
  using frechet-vec-nth[of x T f] assms unfolding has-derivative-def by auto
```

```
lemma has-vderiv-on-vec-nth:

fixes f::(('a::banach) \hat{\ } ('n::finite)) \Rightarrow ('a\hat{\ }'n)

assumes D \ x = (\lambda t. \ f \ (x \ t)) \ on \ T

shows D \ (\lambda t. \ x \ t \ s) = (\lambda t. \ f \ (x \ t) \ s) \ on \ T

using assms unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp

by (rule has-derivative-vec-nth, simp)
```

1.3 Ordinary Differential Equations

declare unique-on-bounded-closed-def [ubc-definitions]

1.3.1 Picard-Lindeloef

named-theorems ubc-definitions definitions used in the locale unique-on-bounded-closed

```
and unique-on-bounded-closed-axioms-def [ubc-definitions]
   and unique-on-closed-def [ubc-definitions]
   and compact-interval-def [ubc-definitions]
   and compact-interval-axioms-def [ubc-definitions]
   and self-mapping-def [ubc-definitions]
   and self-mapping-axioms-def [ubc-definitions]
   and continuous-rhs-def [ubc-definitions]
   and closed-domain-def [ubc-definitions]
   and global-lipschitz-def [ubc-definitions]
   and interval-def [ubc-definitions]
   and nonempty-set-def [ubc-definitions]
lemma(in unique-on-bounded-closed) unique-on-bounded-closed-on-compact-subset:
 assumes t\theta \in T' and x\theta \in X and T' \subseteq T and compact-interval T'
 shows unique-on-bounded-closed to T' x0 f X L
 apply(unfold-locales)
 using \langle compact\text{-}interval\ T' \rangle unfolding ubc\text{-}definitions\ apply\ simp+
 using \langle t\theta \in T' \rangle apply simp
 using \langle x\theta \in X \rangle apply simp
 using \langle T' \subseteq T \rangle self-mapping apply blast
 using \langle T' \subseteq T \rangle continuous apply(meson Sigma-mono continuous-on-subset sub-
  using \langle T' \subseteq T \rangle lipschitz apply blast
 using \langle T' \subseteq T \rangle lipschitz-bound by blast
```

The next locale makes explicit the conditions for applying the Picard-Lindeloef theorem. This guarantees a unique solution for every initial value problem represented with a vector field f and an initial time t_0 . It is mostly a simplified reformulation of the approach taken by the people who created the Ordinary Differential Equations entry in the AFP.

```
\begin{array}{l} \textbf{locale} \ \textit{picard-lindeloef-closed-ivl} = \\ \textbf{fixes} \ \textit{f::real} \Rightarrow (\textit{'a::banach}) \Rightarrow \textit{'a} \ \textbf{and} \ \textit{T::real set} \ \textbf{and} \ \textit{L} \ \textit{t_0::real} \\ \textbf{assumes} \ \textit{init-time:} \ \textit{t_0} \in \textit{T} \\ \textbf{and} \ \textit{cont-vec-field:} \ \textit{continuous-on} \ (\textit{T} \times \textit{UNIV}) \ (\lambda(t, \, x). \ \textit{f} \ t \ x) \end{array}
```

```
and lipschitz-vec-field: \bigwedge t. t \in T \Longrightarrow L-lipschitz-on UNIV (\lambda x. f t x)
   and nonempty-time: T \neq \{\}
   and interval-time: is-interval T
   and compact-time: compact T
   and lipschitz-bound: \bigwedge s\ t.\ s\in T \Longrightarrow t\in T \Longrightarrow abs\ (s-t)*L < 1
begin
sublocale continuous-rhs T UNIV
 using cont-vec-field unfolding continuous-rhs-def by simp
{f sublocale}\ global	ext{-}lipschitz\ T\ UNIV
 using lipschitz-vec-field unfolding global-lipschitz-def by simp
{f sublocale}\ closed	ext{-}domain\ UNIV
 unfolding closed-domain-def by simp
sublocale compact-interval
 using interval-time nonempty-time compact-time by (unfold-locales, auto)
lemma is-ubc:
 shows unique-on-bounded-closed t_0 T s f UNIV L
 using nonempty-time unfolding ubc-definitions apply safe
 by (auto simp: compact-time interval-time init-time
     lipschitz-vec-field lipschitz-bound cont-vec-field)
\mathbf{lemma}\ min	ext{-}max	ext{-}interval:
 obtains m M where T = \{m ... M\}
 using T-def by blast
lemma subinterval:
 assumes t \in T
 obtains t1 where \{t ... t1\} \subseteq T
 using assms interval-subset-is-interval interval-time by fastforce
lemma subsegment:
 assumes t1 \in T and t2 \in T
 shows \{t1 -- t2\} \subseteq T
 using assms closed-segment-subset-domain by blast
lemma unique-solution:
 assumes D x = (\lambda t. f t (x t)) on T and x t_0 = s
   and D y = (\lambda t. f t (y t)) on T and y t_0 = s and t \in T
 shows x t = y t
 apply(rule\ unique-on-bounded-closed.unique-solution)
 using is-ubc[of s] apply blast
 using assms unfolding solves-ode-def by auto
abbreviation phi t s \equiv (apply-bcontfun (unique-on-bounded-closed.fixed-point <math>t_0
T \ s \ f \ UNIV)) \ t
```

```
lemma fixpoint-solves-ivp: shows D (\lambda t. phi t s) = (\lambda t. f t (phi t s)) on T and phi t_0 s = s using is-ubc[of s] unique-on-bounded-closed.fixed-point-solution[of t_0 T s f UNIV L] unique-on-bounded-closed.fixed-point-iv[of t_0 T s f UNIV L] unfolding solves-ode-def by auto lemma fixpoint-usolves-ivp: assumes D x = (\lambda t. f t (x t)) on T and x t_0 = s and t \in T shows x t = phi t s using unique-solution[OF assms(1,2)] fixpoint-solves-ivp assms by blast
```

1.3.2 Flows for ODEs

end

This locale is a particular case of the previous one. It makes the unique solution for initial value problems explicit, it restricts the vector field to reflect autonomous systems (those that do not depend explicitly on time), and it sets the initial time equal to 0. This is the first step towards formalizing the flow of a differential equation, i.e. the function that maps every point to the unique trajectory tangent to the vector field.

```
locale local-flow = picard-lindeloef-closed-ivl (\lambda t. f) T L 0
  for f:('a::banach) \Rightarrow 'a and TL +
 fixes \varphi :: real \Rightarrow 'a \Rightarrow 'a
  assumes ivp: D(\lambda t. \varphi t s) = (\lambda t. f(\varphi t s)) on T \varphi \theta s = s
begin
lemma is-fixpoint:
  assumes t \in T
 shows \varphi t s = phi t s
 using fixpoint-usolves-ivp[OF ivp assms] by simp
lemma solves-ode:
  shows ((\lambda \ t. \ \varphi \ t \ s) \ solves-ode \ (\lambda \ t. \ f)) T \ UNIV
  unfolding solves-ode-def using ivp(1) by auto
lemma usolves-ivp:
  assumes D x = (\lambda t. f(x t)) on T and x \theta = s and t \in T
 shows x t = \varphi t s
  using fixpoint-usolves-ivp[OF\ assms]\ is-fixpoint[OF\ assms(3)]\ by simp
lemma usolves-on-compact-subset:
  assumes T' \subseteq T and compact-interval T' and \theta \in T'
     and x-solves: D x = (f \circ x) on T' and t \in T'
 shows \varphi t (x \theta) = x t
proof-
```

```
have obs1:D (\lambda \tau. \varphi \tau (x \theta)) = (\lambda \tau. f (\varphi \tau (x \theta))) on T'
    using \langle T' \subseteq T \rangle has-vderiv-on-subset ivp by blast
  have unique-on-bounded-closed 0 T (x 0) (\lambda \tau. f) UNIV L
    using is-ubc by blast
  hence obs2:unique-on-bounded-closed 0 T'(x \theta)(\lambda \tau. f) UNIV L
    using unique-on-bounded-closed.unique-on-bounded-closed-on-compact-subset
    \langle \theta \in T' \rangle \langle T' \subseteq T \rangle and \langle compact\text{-}interval \ T' \rangle by blast
  moreover have \varphi \ \theta \ (x \ \theta) = x \ \theta
    using ivp by blast
  show \varphi t (x \theta) = x t
    apply(rule unique-on-bounded-closed.unique-solution[OF obs2])
    unfolding solves-ode-def using x-solves apply(simp-all add: ivp \langle t \in T' \rangle)
    using has-vderiv-on-subset [OF ivp(1) \langle T' \subseteq T \rangle] by blast
qed
lemma add-solves:
  assumes D(\lambda t. \varphi t s) = (\lambda t. f(\varphi t s)) on(\lambda \tau. \tau + t) 'T
  shows D(\lambda \tau, \varphi(\tau + t) s) = (\lambda \tau, f(\varphi(\tau + t) s)) on T
  \mathbf{apply}(\mathit{subgoal-tac}\ D\ ((\lambda\tau.\ \varphi\ \tau\ s)\ \circ\ (\lambda\tau.\ \tau\ +\ t)) = (\lambda x.\ 1\ *_R f\ (\varphi\ (x\ +\ t)\ s))
on T)
  apply(simp add: comp-def, rule has-vderiv-on-compose)
  using assms apply blast
  apply(rule-tac f'1=\lambda x. 1 and g'1=\lambda x. 0 in derivative-intros(191))
  \mathbf{by}(rule\ derivative\text{-}intros,\ simp) +\ simp\text{-}all
lemma is-group-action:
  assumes D(\lambda t. \varphi t s) = (\lambda t. f(\varphi t s)) \text{ on } (\lambda t. t + t2) \text{ '} T \text{ and } t1 \in T
  shows \varphi \ \theta \ s = s
    and \varphi (t1 + t2) s = \varphi t1 (\varphi t2 s)
proof-
  \mathbf{show} \ \varphi \ \theta \ s = s
    using ivp by simp
  have \varphi (\theta + t2) s = \varphi t2 s
    by simp
  thus \varphi (t1 + t2) s = \varphi t1 (\varphi t2 s)
    using usolves-ivp[OF\ add-solves[OF\ assms(1)]]\ assms(2) by blast
qed
end
lemma flow-on-compact-subset:
  assumes flow-on-big: local-flow f T' L \varphi and T \subseteq T'
    and compact-interval T and \theta \in T
  shows local-flow f T L \varphi
\mathbf{proof}(\mathit{unfold\ local-flow-def\ local-flow-axioms-def},\ \mathit{safe})
  \mathbf{fix} \ s \ \mathbf{show} \ \varphi \ \theta \ s = s
    using local-flow.ivp(2) flow-on-big by blast
  show D(\lambda t. \varphi t s) = (\lambda t. f(\varphi t s)) on T
```

```
using assms solves-ode-on-subset[where T=T and S=T' and x=\lambda t. \varphi t s and X=UNIV]
unfolding local-flow-def local-flow-axioms-def solves-ode-def by force
next
show picard-lindeloef-closed-ivl (\lambda t.\ f) T L 0
using assms apply(unfold local-flow-def local-flow-axioms-def)
apply(unfold picard-lindeloef-closed-ivl-def ubc-definitions)
apply(meson Sigma-mono continuous-on-subset subsetI)
by(simp-all add: subset-eq)
qed
```

Finally, the flow exists when the unique solution is defined in all of \mathbb{R} . However, this is not viable in the current formalization as the compactness assumption cannot be applied to UNIV.

```
\begin{array}{l} \textbf{locale} \ global\text{-}flow = \textit{local-}flow \textit{f} \ \textit{UNIV} \ \textit{L} \ \varphi \ \textbf{for} \ \textit{f} \ \textit{L} \ \varphi \\ \textbf{begin} \\ \\ \textbf{lemma} \ \textit{contradiction:} \ \textit{False} \\ \textbf{using} \ \textit{compact-time} \ \textbf{and} \ \textit{not-compact-UNIV} \ \textbf{by} \ \textit{simp} \\ \end{array}
```

end

Example

Below there is an example showing the general methodolog to introduce pairs of vector fields and their respective flows using the previous locales.

```
\mathbf{lemma}\ \mathit{picard-lindeloef-closed-ivl-constant}\colon
  0 \le t \Longrightarrow picard-lindeloef-closed-ivl (\lambda t s. c) \{0..t\} (1 / (t + 1)) 0
  unfolding picard-lindeloef-closed-ivl-def
  by(simp add: nonempty-set-def lipschitz-on-def, clarsimp, simp)
lemma line-vderiv-constant: D(\lambda \tau. s + \tau *_R c) = (\lambda t. c) on \{0..t\}
  apply(rule-tac f'1=\lambda x. \ \theta and g'1=\lambda x. \ c in derivative-intros(191))
 apply(rule\ derivative-intros,\ simp)+
 by simp-all
\mathbf{lemma}\ \mathit{line-is-local-flow}\colon
 fixes c::'a::banach
 assumes \theta < t
 shows local-flow (\lambda \ t. \ c) \{0..t\} (1/(t+1)) (\lambda \ t. s. \ s+t*_R c)
 unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-closed-ivl-constant apply blast
  using line-vderiv-constant by auto
end
theory hs-prelims-matrices
 imports hs-prelims
```

begin

Chapter 2

Linear Algebra for Hybrid Systems

Linear systems of ordinary differential equations (ODEs) are those whose vector fields are a linear operator. That is, there is a matrix A such that the system x't = f(xt) can be rewritten as x't = A *v x t. The end goal of this section is to prove that every linear system of ODEs has a unique solution, and to obtain a characterization of said solution. For that we start by formalising various properties of vector spaces.

2.1 Vector operations

```
fixes q::('a::semiring-\theta)
 shows (\sum j \in UNIV. \ fj * axis i \ q \ \$ \ j) = fi * q
   and (\sum j \in UNIV. \ axis \ i \ q \ \$ \ j * f \ j) = q * f \ i
 unfolding axis-def by(auto simp: vec-eq-iff)
lemma sum-scalar-nth-axis: sum (\lambda i. (x \$ i) *s e i) UNIV = x for x :: ('a::semiring-1) ^{\prime}n
 unfolding vec-eq-iff axis-def by simp
lemma scalar-eq-scaleR[simp]: c *s x = c *_R x for c :: real
 unfolding vec-eq-iff by simp
lemma matrix-add-rdistrib: ((B + C) ** A) = (B ** A) + (C ** A)
 by (vector matrix-matrix-mult-def sum.distrib[symmetric] field-simps)
lemma vec-mult-inner: (A * v v) \cdot w = v \cdot (transpose \ A * v w) for A::real ^\prime n ^\prime n
 unfolding matrix-vector-mult-def transpose-def inner-vec-def
 apply(simp add: sum-distrib-right sum-distrib-left)
 apply(subst sum.swap)
 \mathbf{apply}(\mathit{subgoal\text{-}tac} \ \forall \ i \ j. \ A \ \$ \ i \ \$ \ j \ast v \ \$ \ j \ast w \ \$ \ i = v \ \$ \ j \ast (A \ \$ \ i \ \$ \ j \ast w \ \$ \ i))
 by presburger (simp)
lemma uminus-axis-eq[simp]: - axis i k = axis i (-k) for k::'a::ring
 unfolding axis-def by(simp add: vec-eq-iff)
lemma norm-axis-eq[simp]: ||axis\ i\ k|| = ||k||
proof(simp add: axis-def norm-vec-def L2-set-def)
 have (\sum j \in UNIV. (\|(\delta_K \ j \ i \ k)\|)^2) = (\sum j \in \{i\}. (\|(\delta_K \ j \ i \ k)\|)^2) + (\sum j \in (UNIV - \{i\}).
(\|(\delta_K \ j \ i \ k)\|)^2)
   using finite-sum-univ-singleton by blast
 also have ... = (\|k\|)^2 by simp
 finally show sqrt (\sum j \in UNIV. (norm (if j = i then k else 0))^2) = norm k by
qed
lemma matrix-axis-\theta:
 fixes A :: ('a::idom) \hat{\ }'n \hat{\ }'m
 assumes k \neq 0 and h: \forall i. (A *v (axis i k)) = 0
 shows A = \theta
proof-
 {fix i::'n
   have 0 = (\sum j \in UNIV. (axis\ i\ k) \ \ j *s\ column\ j\ A)
     using h matrix-mult-sum[of A axis i k] by simp
   also have \dots = k *s column i A
   by (simp add: axis-def vector-scalar-mult-def column-def vec-eq-iff mult.commute)
   finally have k *s column i A = 0
     unfolding axis-def by simp
   hence column \ i \ A = 0
     using vector-mul-eq-0 \langle k \neq 0 \rangle by blast
 thus A = \theta
```

```
unfolding column-def vec-eq-iff by simp
qed
lemma scaleR-norm-sgn-eq: (||x||) *_R sgn x = x
 \mathbf{by}\ (\mathit{metis}\ \mathit{divideR-right}\ \mathit{norm-eq-zero}\ \mathit{scale-eq-0-iff}\ \mathit{sgn-div-norm})
lemma vector-scaleR-commute: A *v c *_R x = c *_R (A *v x) for x :: ('a::real-normed-algebra-1) ^'n
 unfolding scaleR-vec-def matrix-vector-mult-def by(auto simp: vec-eq-iff scaleR-right.sum)
lemma scaleR-vector-assoc: c *_R (A * v x) = (c *_R A) *_V x \text{ for } x :: ('a::real-normed-algebra-1) ^'n
  unfolding matrix-vector-mult-def by(auto simp: vec-eq-iff scaleR-right.sum)
lemma mult-norm-matrix-sgn-eq:
 fixes x :: ('a::real-normed-algebra-1) ^'n
 shows (||A * v sgn x||) * (||x||) = ||A * v x||
proof-
 have ||A * v x|| = ||A * v ((||x||) *_R sgn x)||
   by(simp add: scaleR-norm-sqn-eq)
 also have ... = (||A * v sgn x||) * (||x||)
   \mathbf{by}(simp\ add:\ vector\text{-}scaleR\text{-}commute)
 finally show ?thesis ...
qed
```

2.2 Matrix norms

Here we develop the foundations for obtaining the Lipschitz constant for every linear system of ODEs x' t = A *v x t. For that we derive some properties of two matrix norms.

2.2.1 Matrix operator norm

```
abbreviation op-norm (A::('a::real-normed-algebra-1) \hat{\ }'n\hat{\ }'m) \equiv Sup \ \{\|A*vx\| | x. \|x\| = 1\}
notation op-norm ((1\|\cdot\|_{op}) [65] 61)
lemma norm-matrix-bound:
fixes A::('a::real-normed-algebra-1) \hat{\ }'n\hat{\ }'m
shows \|x\| = 1 \Longrightarrow \|A*vx\| \le \|(\chi i j. \|A\$ i \$ j\|) *v 1\|
proof—
fix x::('a, 'n) vec assume \|x\| = 1
hence xi\text{-}le1: \land i. \|x\$ i\| \le 1
by (metis\ Finite-Cartesian-Product.norm-nth-le)
\{\text{fix } j::'m
have \|(\sum i \in UNIV.\ A\$ j\$ i*x\$ i)\| \le (\sum i \in UNIV.\ \|A\$ j\$ i*x\$ i\|)
using norm\text{-}sum by blast
also have ... \le (\sum i \in UNIV.\ (\|A\$ j\$ i\|) * (\|x\$ i\|))
by (simp\ add:\ norm\text{-}mult\text{-}ineq\ sum\text{-}mono)
```

```
also have ... \leq (\sum i \in UNIV. (||A \$ j \$ i||) * 1)
     using xi-le1 by (simp add: sum-mono mult-left-le)
   * 1) by simp}
 from this have \bigwedge j. \|(A * v x) \$ j\| \le ((\chi i1 i2. \|A \$ i1 \$ i2\|) * v 1) \$ j
   unfolding matrix-vector-mult-def by simp
 hence (\sum j \in UNIV. (\|(A * v x) \$ j\|)^2) \le (\sum j \in UNIV. (\|((\chi i1 i2. \|A \$ i1 \$ i1 \$ j))^2))
i2||)*v1)$j||)^2
  by (metis (mono-tags, lifting) norm-ge-zero power2-abs power-mono real-norm-def
sum-mono)
 thus ||A *v x|| \le ||(\chi i j. ||A \$ i \$ j||) *v 1||
   unfolding norm-vec-def L2-set-def by simp
qed
lemma op-norm-set-proptys:
 fixes A::('a::real-normed-algebra-1) ^'n ^'m
 shows bounded {||A * v x|| | x. ||x|| = 1}
   and bdd-above {||A * v x|| | x. ||x|| = 1}
   and {||A * v x|| | x. ||x|| = 1} \neq {\}}
 unfolding bounded-def bdd-above-def apply safe
   apply(rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=\|(\chi \ i \ j. \ \|A \ \$ \ i \ \$ \ j\|) *v \ 1\| \ in \ exI)
   apply(force simp: norm-matrix-bound dist-real-def)
 apply(rule-tac\ x=\|(\chi\ i\ j.\ \|A\ \$\ i\ \$\ j\|)*v\ 1\|\ in\ exI,\ force\ simp:\ norm-matrix-bound)
 using ex-norm-eq-1 by blast
lemma norm-matrix-le-op-norm: ||x|| = 1 \Longrightarrow ||A * v x|| \le ||A||_{op}
 by(rule cSup-upper, auto simp: op-norm-set-proptys)
lemma norm-matrix-le-op-norm-ge-0: 0 \le ||A||_{op}
 using ex-norm-eq-1 norm-qe-zero norm-matrix-le-op-norm basic-trans-rules (23)
by blast
lemma norm-sgn-le-op-norm: ||A * v   sgn   x|| \le ||A||_{op}
 by(cases x=0, simp-all \ add: norm-sqn \ norm-matrix-le-op-norm \ norm-matrix-le-op-norm-qe-0)
lemma norm-matrix-le-mult-op-norm: ||A * v x|| \le (||A||_{op}) * (||x||) for A :: real^{\prime} n^{\prime} m
proof-
 have ||A * v x|| = (||A * v sgn x||) * (||x||)
   \mathbf{by}(simp\ add\colon mult\text{-}norm\text{-}matrix\text{-}sgn\text{-}eq)
 also have ... \leq (\|A\|_{op}) * (\|x\|)
   using norm-sgn-le-op-norm[of A] by (simp add: mult-mono')
 finally show ?thesis by simp
qed
lemma ltimes-op-norm:
 Sup \{|c| * (||A *v x||) | x. ||x|| = 1\} = |c| * (||A||_{op}) \text{ (is } Sup ?cA = |c| * (||A||_{op})
proof(cases c = 0, simp add: ex-norm-eq-1)
 let ?S = \{(\|A * v x\|) | x. \|x\| = 1\}
```

```
note op\text{-}norm\text{-}set\text{-}proptys(2)[of A]
 also have ?cA = \{|c| * x | x. x \in ?S\}
   by force
 ultimately have bdd-cA:bdd-above ?cA
   using bdd-above-ltimes[of |c| ?S] by simp
 assume c \neq 0
 show Sup ?cA = |c| * (||A||_{op})
 proof(rule\ cSup-eq-linorder)
   show nempty-cA:?cA \neq \{\}
     using op\text{-}norm\text{-}set\text{-}proptys(3)[of A] by blast
   show bdd-above ?cA
     using bdd-cA by blast
    \{ \text{fix } m \text{ assume } m \in ?cA \}
     then obtain x where x-def:||x|| = 1 \land m = |c| * (||A *v x||)
       by blast
     hence (\|A * v x\|) \le (\|A\|_{op})
       using norm-matrix-le-op-norm by force
     hence m \leq |c| * (||A||_{op})
       using x-def by (simp add: mult-left-mono)}
   thus \forall x \in ?cA. \ x \le |c| * (||A||_{op})
     by blast
 next
   show \forall y < |c| * (||A||_{op}). \exists x \in ?cA. y < x
   proof(clarify)
     fix m assume m < |c| * (||A||_{op})
     hence (m / |c|) < (||A||_{op})
       using pos-divide-less-eq[of |c| m (||A||_{op})] \langle c \neq 0 \rangle
           semiring-normalization-rules (7) [of |c|] by auto
     then obtain x where ||x|| = 1 \wedge (m / |c|) < (||A *v x||)
       using less-cSup-iff [of ?S m / |c|] op-norm-set-proptys by force
     hence ||x|| = 1 \land m < |c| * (||A *v x||)
       using \langle c \neq 0 \rangle pos-divide-less-eq[of - m -] by (simp add: mult.commute)
     thus \exists n \in ?cA. m < n by blast
   qed
 qed
qed
lemma op-norm-le-sum-column:
 ||A||_{op} \leq (\sum i \in UNIV. ||column \ i \ A||) for A::real^n n'm
 using op\text{-}norm\text{-}set\text{-}proptys(3) proof(rule\ cSup\text{-}least)
 fix m assume m \in \{ ||A * v x|| \mid x. ||x|| = 1 \}
   then obtain x where x-def:||x|| = 1 \land m = (||A * v x||) by blast
   hence x-hyp:\bigwedge i. norm (x \$ i) \le 1
     by (simp add: norm-bound-component-le-cart)
   have (||A *v x||) = norm (\sum i \in UNIV. (x \$ i *s column i A))
     \mathbf{by}(\mathit{subst\ matrix-mult-sum}[\mathit{of}\ A],\ \mathit{simp})
   also have ... \leq (\sum i \in UNIV. norm (x \$ i *s column i A))
     by (simp add: sum-norm-le)
   also have ... = (\sum i \in UNIV. norm (x \$ i) * norm (column i A))
```

```
by (simp add: mult-norm-matrix-sgn-eq)
   also have ... \leq (\sum i \in UNIV. \ norm \ (column \ i \ A))
     using x-hyp by (simp add: mult-left-le-one-le sum-mono)
   finally show m \leq (\sum i \in UNIV. norm (column \ i \ A))
     using x-def by linarith
qed
lemma op-norm-zero-iff: (\|A\|_{op} = 0) = (A = 0) for A::('a::real-normed-field) ^'n 'm
  assume A = \theta thus ||A||_{op} = \theta
   \mathbf{by}(simp\ add:\ ex\text{-}norm\text{-}eq\text{-}1)
\mathbf{next}
  assume ||A||_{op} = \theta
  note cSup\text{-}upper[of - {||A * v x|| | x. ||x|| = 1}]
  hence \bigwedge r. \ r \in \{ \|A * v x\| \mid x. \|x\| = 1 \} \Longrightarrow r \le (\|A\|_{op})
   using op\text{-}norm\text{-}set\text{-}proptys(2) by force
  also have \bigwedge r. r \in (\{\|A * v x\| \mid x \cdot \|x\| = 1\}) \Longrightarrow 0 \le r
   using norm-ge-zero by blast
  ultimately have \bigwedge r. r \in (\{\|A * v x\| \mid x \cdot \|x\| = 1\}) \Longrightarrow r = 0
   using \langle ||A||_{op} = \theta \rangle by fastforce
  hence \bigwedge x. ||x|| = 1 \Longrightarrow x \neq 0 \land (||A * v x||) = 0
   by force
  hence \bigwedge i. norm (A * v e i) = 0
   by simp
  from this show A = 0
    using matrix-axis-0[of 1 A] norm-eq-zero by simp
qed
lemma op-norm-triangle:
  fixes A::('a::real-normed-algebra-1) ^'n ^'m
  shows ||A + B||_{op} \le (||A||_{op}) + (||B||_{op})
  using op-norm-set-proptys(3)[of A + B] proof(rule cSup-least)
  fix m assume m \in \{ \|(A+B) * v x\| \mid x. \|x\| = 1 \}
   then obtain x::'a^*n where ||x|| = 1 and m = ||(A + B) *v x||
     by blast
   have ||(A + B) *v x|| \le (||A *v x||) + (||B *v x||)
     by (simp add: matrix-vector-mult-add-rdistrib norm-triangle-ineq)
   also have ... \leq (\|A\|_{op}) + (\|B\|_{op})
     by (simp add: \langle ||x|| = 1 \rangle add-mono norm-matrix-le-op-norm)
   finally show m \leq (\|A\|_{op}) + (\|B\|_{op})
     using \langle m = ||(A + B) *v x|| \rangle by blast
qed
lemma op-norm-scaleR: ||c|*_R A||_{op} = |c|*(||A||_{op})
  let ?N = \{|c| * (||A *v x||) |x. ||x|| = 1\}
  have \{\|(c *_R A) *_V x\| \mid x. \|x\| = 1\} = ?N
   by (metis (no-types, hide-lams) norm-scaleR scaleR-vector-assoc)
  also have Sup ?N = |c| * (||A||_{op})
```

```
using ltimes-op-norm[of\ c\ A] by blast
 ultimately show op-norm (c *_R A) = |c| * (||A||_{op})
   by auto
qed
lemma op-norm-matrix-matrix-mult-le: ||A| ** B||_{op} \leq (||A||_{op}) * (||B||_{op}) for
A::real^n 'n^m
using op\text{-}norm\text{-}set\text{-}proptys(3)[of\ A\ **\ B]
proof(rule cSup-least)
 have 0 \le (\|A\|_{op}) using norm-matrix-le-op-norm-ge-0 by force
 fix n assume n \in \{ \| (A ** B) *v x \| \mid x. \| x \| = 1 \}
   then obtain x where x-def:n = ||A| ** B *v x|| \land ||x|| = 1 by blast
   have ||A ** B *v x|| = ||A *v (B *v x)||
     by (simp add: matrix-vector-mul-assoc)
   also have ... \leq (\|A\|_{op}) * (\|B *v x\|)
     \mathbf{by} \ (simp \ add: \ norm-matrix-le-mult-op-norm[of - \ B \ *v \ x])
   also have ... \leq (\|A\|_{op}) * ((\|B\|_{op}) * (\|x\|))
     using norm-matrix-le-mult-op-norm[of B x] \langle 0 \leq (\|A\|_{op}) \rangle mult-left-mono by
blast
   also have ... = (\|A\|_{op}) * (\|B\|_{op}) using x-def by simp
   finally show n \leq (\|A\|_{op}) * (\|B\|_{op}) using x-def by blast
qed
\mathbf{lemma}\ norm\text{-}matrix\text{-}vec\text{-}mult\text{-}le\text{-}transpose\text{:}
||x|| = 1 \Longrightarrow (||A *v x||) \le sqrt (||transpose A ** A||_{op}) * (||x||) for A::real^'a^'a
proof-
 assume ||x|| = 1
 have (\|A * v x\|)^2 = (A * v x) \cdot (A * v x)
   using dot-square-norm[of (A * v x)] by simp
 also have ... = x \cdot (transpose \ A * v \ (A * v \ x))
   using vec-mult-inner by blast
 also have ... \leq (\|x\|) * (\|transpose A * v (A * v x)\|)
   using norm-cauchy-schwarz by blast
 also have ... \leq (\|transpose\ A ** A\|_{op}) * (\|x\|)^2
    apply(subst\ matrix-vector-mul-assoc)\ using\ norm-matrix-le-mult-op-norm[of]
transpose \ A ** A x
   by (simp add: \langle ||x|| = 1 \rangle)
 finally have ((\|A * v x\|)) \hat{2} \leq (\|transpose A * A\|_{op}) * (\|x\|) \hat{2}
   by linarith
 thus (||A *v x||) \leq sqrt ((||transpose A ** A||_{op})) * (||x||)
   by (simp add: \langle ||x|| = 1 \rangle real-le-rsqrt)
qed
2.2.2
          Matrix maximum norm
abbreviation max-norm (A::real^n n^m) \equiv Max (abs `(entries A))
notation max-norm ((1||-||_{max}) [65] 61)
```

```
lemma max-norm-def: ||A||_{max} = Max \{|A \$ i \$ j|| i j. i \in UNIV \land j \in UNIV\}
 \mathbf{by}(simp\ add:\ image-def,\ rule\ arg-cong[of--Max],\ blast)
lemma max-norm-set-proptys:
 fixes A::real^('n::finite)^('m::finite)
 shows finite \{|A \ \ i \ \ j| \ | i \ j. \ i \in UNIV \land j \in UNIV \} (is finite ?X)
proof-
 using finite-Atleast-Atmost-nat by fastforce
 hence finite (\bigcup i \in UNIV. {|A \$ i \$ j| | j. j \in UNIV}) (is finite ?Y)
   using finite-class.finite-UNIV by blast
 also have ?X \subseteq ?Y by auto
 ultimately show ?thesis
   using finite-subset by blast
qed
lemma max-norm-ge-\theta: \theta \leq ||A||_{max}
proof-
 have \bigwedge i j. |A \$ i \$ j| \ge \theta by simp
 also have \bigwedge i j. |A \$ i \$ j| \le ||A||_{max}
    unfolding max-norm-def using max-norm-set-proptys Max-ge max-norm-def
by blast
 finally show 0 \le ||A||_{max}.
qed
lemma op-norm-le-max-norm:
 fixes A::real^('n::finite)^('m::finite)
 shows ||A||_{op} \le real \ CARD('n) * real \ CARD('m) * (||A||_{max}) (is ||A||_{op} \le ?n *
?m * (||A||_{max}))
proof(rule cSup-least)
 show \{ ||A * v x|| ||x|| ||x|| = 1 \} \neq \{ \}
   using op\text{-}norm\text{-}set\text{-}proptys(3) by blast
 {fix n assume n \in \{ ||A * v x|| ||x|| = 1 \}
   then obtain x::(real, 'n) vec where n\text{-}def:||x|| = 1 \land ||A*vx|| = n
     by blast
   hence comp-le-1: \forall i::'n. |x \$ i| \le 1
     by (simp add: norm-bound-component-le-cart)
   have A *v x = (\sum i \in UNIV. x \$ i *s column i A)
     using matrix-mult-sum by blast
   hence ||A *v x|| \le (\sum i \in UNIV. ||x \$ i *s column i A||)
     by (simp add: sum-norm-le)
   also have ... = (\sum i \in UNIV. |x \$ i| * (||column i A||))
     by simp
   also have ... \leq (\sum i \in UNIV. \|column \ i \ A\|)
   \mathbf{by}\ (\mathit{metis}\ (\mathit{no-types}, \mathit{lifting})\ \mathit{Groups.mult-ac}(2)\ \mathit{comp-le-1}\ \mathit{mult-left-le}\ \mathit{norm-ge-zero}
sum-mono)
   also have ... \leq (\sum (i::'n) \in UNIV. ?m * (||A||_{max}))
   proof(unfold norm-vec-def L2-set-def real-norm-def)
     have \bigwedge i j. |column \ i \ A \ \$ \ j| \le ||A||_{max}
```

```
using max-norm-set-proptys Max-qe unfolding column-def max-norm-def
\mathbf{by}(simp, blast)
     hence \bigwedge i \ j. |column \ i \ A \ \$ \ j|^2 \le (\|A\|_{max})^2
     by (metis (no-types, lifting) One-nat-def abs-ge-zero numerals(2) order-trans-rules(23)
           power2-abs power2-le-iff-abs-le)
        then have \bigwedge i. (\sum j \in UNIV. |column \ i \ A \ \$ \ j|^2) \le (\sum (j::'m) \in UNIV.
(\|A\|_{max})^2
       by (meson sum-mono)
     also have (\sum (j::'m) \in UNIV. (||A||_{max})^2) = ?m * (||A||_{max})^2 by simp
     ultimately have \bigwedge i. (\sum j \in UNIV. |column \ i \ A \ \$ \ j|^2) \le ?m * (||A||_{max})^2 by
     hence \bigwedge i. sqrt (\sum j \in UNIV. | column \ i \ A \ \ \ j|^2) \le sqrt \ (?m * (||A||_{max})^2)
       by(simp add: real-sqrt-le-mono)
     also have sqrt \ (?m * (||A||_{max})^2) \le sqrt \ ?m * (||A||_{max})
       using max-norm-ge-0 real-sqrt-mult by auto
     also have ... \leq ?m * (||A||_{max})
       using sqrt-real-nat-le max-norm-ge-0 mult-right-mono by blast
    finally show (\sum i \in UNIV. \ sqrt \ (\sum j \in UNIV. \ | \ column \ i \ A \ \$ \ j|^2)) \le (\sum (i::'n) \in UNIV.
?m * (||A||_{max}))
       by (meson sum-mono)
   also have (\sum (i::'n) \in UNIV. (||A||_{max})) = ?n * (||A||_{max})
     using sum-constant-scale by auto
   ultimately have n \leq ?n * ?m * (||A||_{max})
     by (simp\ add:\ n\text{-}def)
  thus \bigwedge n. n \in \{ \|A * v x\| | x \| \|x\| = 1 \} \implies n \leq ?n * ?m * (\|A\|_{max}) 
   by blast
qed
```

2.3 Picard Lindeloef for linear systems

Now we prove our first objective. First we obtain the Lipschitz constant for linear systems of ODEs, and then we prove that IVPs arising from these satisfy the conditions for Picard-Lindeloef theorem (hence, they have a unique solution).

```
lemma matrix-lipschitz-constant: fixes A::real \ ('n::finite) \ 'n shows dist \ (A*vx) \ (A*vy) \le (real\ CARD('n))^2 * (\|A\|_{max}) * dist\ x\ y unfolding dist-norm matrix-vector-mult-diff-distrib[symmetric] proof (subst mult-norm-matrix-sgn-eq[symmetric]) have \|A\|_{op} \le (\|A\|_{max}) * (real\ CARD('n) * real\ CARD('n)) by (metis (no-types) Groups.mult-ac(2) op-norm-le-max-norm) then have (\|A\|_{op}) * (\|x-y\|) \le (real\ CARD('n))^2 * (\|A\|_{max}) * (\|x-y\|) by (simp add: cross3-simps(11) mult-left-mono semiring-normalization-rules(29)) also have (\|A*vsgn(x-y)\|) * (\|x-y\|) \le (\|A\|_{op}) * (\|x-y\|) by (simp add: norm-sgn-le-op-norm cross3-simps(11) mult-left-mono) ultimately show (\|A*vsgn(x-y)\|) * (\|x-y\|) \le (real\ CARD('n))^2 *
```

```
(||A||_{max}) * (||x - y||)
   using order-trans-rules (23) by blast
qed
lemma picard-lindeloef-linear-system:
 fixes A::real^'n^'n
 assumes \theta < ((real\ CARD('n))^2 * (||A||_{max})) (is \theta < ?L)
 assumes 0 \le t and t \le 1/?L
 shows picard-lindeloef-closed-ivl (\lambda t s. A *v s) {0..t} ?L 0
 apply unfold-locales apply(simp add: \langle \theta < t \rangle)
 subgoal by (simp, metis continuous-on-compose2 continuous-on-cong continuous-on-id
       continuous-on-snd matrix-vector-mult-linear-continuous-on top-greatest)
 subgoal using matrix-lipschitz-constant max-norm-qe-0 zero-compare-simps (4,12)
   unfolding lipschitz-on-def by blast
 apply(simp-all\ add:\ assms)
 subgoal for r \ s \ apply(subgoal-tac \ |r-s| < 1/?L)
    apply(subst\ (asm)\ pos-less-divide-eq[of\ ?L\ |r-s|\ 1])
   using assms by auto
 done
```

2.4 Matrix Exponential

The general solution for linear systems of ODEs is an exponential function. Unfortunately, this operation is only available in Isabelle for Banach spaces which are formalised as a class. Hence we need to prove that a specific type is an instance of this class. We define the type and build towards this instantiation in this section.

2.4.1 Squared matrices operations

```
is matrix-vector-mult.
lift-definition sq\text{-}mtx\text{-}column::'m \Rightarrow 'm \ sqrd\text{-}matrix \Rightarrow (real^{'}m)
 is \lambda i X. column i (to-vec X).
lift-definition vec\text{-}sq\text{-}mtx\text{-}prod::(real \ \ 'm) \Rightarrow \ 'm \ sqrd\text{-}matrix \Rightarrow (real \ \ \ 'm) is vector\text{-}matrix\text{-}mult
lift-definition sq\text{-}mtx\text{-}diag::real \Rightarrow ('m::finite) sqrd\text{-}matrix (diag) is mat.
lift-definition sq\text{-}mtx\text{-}transpose::('m::finite) \ sqrd\text{-}matrix \Rightarrow 'm \ sqrd\text{-}matrix \ (-^{\dagger}) \ is
transpose .
lift-definition sq\text{-}mtx\text{-}row:'m \Rightarrow ('m::finite) sqrd\text{-}matrix \Rightarrow real^'m \text{ (row)} is row
lift-definition sq\text{-}mtx\text{-}col::'m \Rightarrow ('m::finite) sqrd\text{-}matrix \Rightarrow real^{'}m \text{ (col)} is col
umn .
lift-definition sq\text{-}mtx\text{-}rows::('m::finite) \ sqrd\text{-}matrix \Rightarrow (real `'m) \ set \ is \ rows.
lift-definition sq\text{-}mtx\text{-}cols::('m::finite) \ sqrd\text{-}matrix \Rightarrow (real^{\prime}m) \ set \ is \ columns.
lemma sq-mtx-eq-iff:
  shows (\bigwedge i. A \$\$ i = B \$\$ i) \Longrightarrow A = B
    and (\land i j. A \$\$ i \$ j = B \$\$ i \$ j) \Longrightarrow A = B
  by(transfer, simp add: vec-eq-iff)+
lemma sq-mtx-vec-prod-eq: m *_V x = (\chi i. sum (\lambda j. ((m\$\$i)\$j) * (x\$j)) UNIV)
  by(transfer, simp add: matrix-vector-mult-def)
lemma sq\text{-}mtx\text{-}transpose\text{-}transpose[simp]:}(A^{\dagger})^{\dagger} = A
  \mathbf{by}(transfer, simp)
lemma transpose-mult-vec-canon-row[simp]:(A^{\dagger}) *_{V} (e \ i) = \text{row } i \ A
  by transfer (simp add: row-def transpose-def axis-def matrix-vector-mult-def)
lemma row-ith[simp]:row i A = A $$ i
  by transfer (simp add: row-def)
lemma mtx-vec-prod-canon: A *_V (e i) = col i A
```

2.4.2 Squared matrices form Banach space

by (transfer, simp add: matrix-vector-mult-basis)

 ${\bf instantiation} \ sqrd\text{-}matrix :: (finite) \ ring \\ {\bf begin}$

lift-definition plus-sqrd-matrix :: 'a sqrd-matrix \Rightarrow 'a sqrd-matrix \Rightarrow 'a sqrd-matrix

```
is (+) .
lift-definition zero-sqrd-matrix :: 'a sqrd-matrix is \theta.
lift-definition uminus-sqrd-matrix ::'a sqrd-matrix \Rightarrow 'a sqrd-matrix is uminus.
lift-definition minus-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix
is (-).
lift-definition times-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix \Rightarrow 'a sqrd-matrix
is (**).
declare plus-sqrd-matrix.rep-eq [simp]
   and minus-sqrd-matrix.rep-eq [simp]
instance apply intro-classes
 by(transfer, simp \ add: algebra-simps \ matrix-mul-assoc \ matrix-add-rdistrib \ matrix-add-ldistrib)+
\mathbf{end}
lemma sq\text{-}mtx\text{-}plus\text{-}ith[simp]:(A + B) \$\$ i = A \$\$ i + B \$\$ i
  \mathbf{by}(unfold\ plus\text{-}sqrd\text{-}matrix\text{-}def,\ transfer,\ simp)
lemma sq\text{-}mtx\text{-}minus\text{-}ith[simp]:(A - B) \$\$ i = A \$\$ i - B \$\$ i
  by(unfold minus-sqrd-matrix-def, transfer, simp)
lemma mtx-vec-prod-add-rdistr:(A + B) *_{V} x = A *_{V} x + B *_{V} x
  unfolding plus-sqrd-matrix-def apply(transfer)
  by (simp add: matrix-vector-mult-add-rdistrib)
lemma mtx-vec-prod-minus-rdistrib:(A - B) *_V x = A *_V x - B *_V x
 unfolding minus-sqrd-matrix-def by(transfer, simp add: matrix-vector-mult-diff-rdistrib)
lemma sq\text{-}mtx\text{-}times\text{-}vec\text{-}assoc: (A * B) *_V x0 = A *_V (B *_V x0)
  by (transfer, simp add: matrix-vector-mul-assoc)
lemma sq\text{-}mtx\text{-}vec\text{-}mult\text{-}sum\text{-}cols:A *_{V} x = sum (\lambda i. x \$ i *_{R} col i A) UNIV
  by(transfer) (simp add: matrix-mult-sum scalar-mult-eq-scaleR)
instantiation sqrd-matrix :: (finite) real-normed-vector
begin
definition norm-sqrd-matrix :: 'a sqrd-matrix \Rightarrow real where ||A|| = ||to\text{-vec }A||_{op}
lift-definition scaleR-sqrd-matrix::real \Rightarrow 'a \ sqrd-matrix \Rightarrow 'a \ sqrd-matrix is scaleR
definition sqn-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix
  where sgn-sgrd-matrix <math>A = (inverse (||A||)) *_R A
```

```
definition dist-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix <math>\Rightarrow real
  where dist-sqrd-matrix A B = ||A - B||
definition uniformity-sqrd-matrix :: ('a sqrd-matrix \times 'a sqrd-matrix) filter
 where uniformity-sqrd-matrix = (INF e: \{0 < ...\}), principal \{(x, y), dist x y < e\})
definition open-sqrd-matrix :: 'a sqrd-matrix set \Rightarrow bool
 where open-sqrd-matrix U = (\forall x \in U. \forall_F (x', y) \text{ in uniformity. } x' = x \longrightarrow y \in
U
{\bf instance\ apply\ \it intro-classes}
 unfolding sgn-sqrd-matrix-def open-sqrd-matrix-def dist-sqrd-matrix-def uniformity-sqrd-matrix-def
 prefer 10 apply(transfer, simp add: norm-sqrd-matrix-def op-norm-triangle)
 prefer 9 apply(simp-all add: norm-sqrd-matrix-def zero-sqrd-matrix-def op-norm-zero-iff)
 by(transfer, simp add: norm-sqrd-matrix-def op-norm-scaleR algebra-simps)+
end
lemma sq\text{-}mtx\text{-}scaleR\text{-}ith[simp]: (c *_R A) \$\$ i = (c *_R (A \$\$ i))
 \mathbf{by}(unfold\ scaleR\text{-}sqrd\text{-}matrix\text{-}def,\ transfer,\ simp)
lemma le\text{-}mtx\text{-}norm: m \in \{\|A *_V x\| | x. \|x\| = 1\} \Longrightarrow m \leq \|A\|
  using cSup\text{-}upper[of - \{\|(to\text{-}vec\ A) *v\ x\| \mid x.\ \|x\| = 1\}]
 by (simp\ add:\ op-norm-set-proptys(2)\ norm-sqrd-matrix-def\ sq-mtx-vec-prod.rep-eq)
lemma norm-vec-mult-le: ||A *_V x|| \le (||A||) * (||x||)
 by (simp add: norm-matrix-le-mult-op-norm norm-sqrd-matrix-def sq-mtx-vec-prod.rep-eq)
lemma sq-mtx-norm-le-sum-col: ||A|| \leq (\sum i \in UNIV. ||col| i| A||)
 using op-norm-le-sum-column[of to-vec A] apply(simp add: norm-sqrd-matrix-def)
 by(transfer, simp add: op-norm-le-sum-column)
lemma norm-le-transpose: ||A|| \leq ||A^{\dagger}||
  apply(simp add: norm-sqrd-matrix-def, transfer, simp add: transpose-def)
  using op\text{-}norm\text{-}set\text{-}proptys(3) apply(rule\ cSup\text{-}least)
proof(clarsimp)
  fix A::real^{\prime}a^{\prime}a and x::real^{\prime}a assume ||x||=1
 have obs: \forall x. ||x|| = 1 \longrightarrow (||A * v x||) \leq sqrt ((||transpose A * * A||_{op})) * (||x||)
   using norm-matrix-vec-mult-le-transpose by blast
  have (\|A\|_{op}) \leq sqrt ((\|transpose\ A ** A\|_{op}))
    \textbf{using} \ \textit{op-norm-set-proptys}(3) \ \textbf{apply}(\textit{rule} \ \textit{cSup-least}) \ \textbf{using} \ \textit{obs} \ \textbf{by} \ \textit{clarsimp}
  then have ((\|A\|_{op}))^2 \leq (\|transpose\ A ** A\|_{op})
   using power-mono[of (||A||_{op}) - 2] norm-matrix-le-op-norm-ge-0 by force
  also have ... \leq (\|transpose\ A\|_{op}) * (\|A\|_{op})
   \mathbf{using}\ op\text{-}norm\text{-}matrix\text{-}matrix\text{-}mult\text{-}le\ \mathbf{by}\ blast
  finally have ((\|A\|_{op}))^2 \leq (\|transpose\ A\|_{op}) * (\|A\|_{op}) by linarith
  hence (\|A\|_{op}) \leq (\|transpose\ A\|_{op})
   using sq-le-cancel [of (||A||_{op})] norm-matrix-le-op-norm-ge-0 by blast
```

```
thus (||A *v x||) \leq op\text{-}norm (\chi i j. A \$ j \$ i)
        unfolding transpose-def using \langle ||x|| = 1 \rangle order-trans norm-matrix-le-op-norm
by blast
qed
lemma norm-eq-norm-transpose[simp]: ||A^{\dagger}|| = ||A||
    using norm-le-transpose [of A] and norm-le-transpose [of A^{\dagger}] by simp
lemma norm-column-le-norm: ||A \$\$ i|| \le ||A||
    using norm-vec-mult-le [of A^{\dagger} e i] by simp
instantiation sqrd-matrix :: (finite) real-normed-algebra-1
begin
lift-definition one-sqrd-matrix :: 'a sqrd-matrix is sq-mtx-chi (mat 1).
lemma sq\text{-}mtx\text{-}one\text{-}idty: 1*A = A A * 1 = A \text{ for } A::'a sqrd\text{-}matrix
  \mathbf{by}(\mathit{transfer}, \mathit{transfer}, \mathit{unfold} \; \mathit{mat-def} \; \mathit{matrix-matrix-mult-def}, \mathit{simp} \; \mathit{add} \colon \mathit{vec-eq-iff}) + \\
lemma sq\text{-}mtx\text{-}norm\text{-}1: ||(1::'a \ sqrd\text{-}matrix)|| = 1
    unfolding one-sqrd-matrix-def norm-sqrd-matrix-def apply simp
    apply(subst\ cSup-eq[of-1])
    using ex-norm-eq-1 by auto
lemma sq\text{-}mtx\text{-}norm\text{-}times: ||A * B|| \le (||A||) * (||B||) for A::'a \ sqrd\text{-}matrix
   unfolding norm-sqrd-matrix-def times-sqrd-matrix-def by(simp add: op-norm-matrix-matrix-mult-le)
instance apply intro-classes
    apply(simp-all add: sq-mtx-one-idty sq-mtx-norm-1 sq-mtx-norm-times)
  \mathbf{apply}(simp\text{-}all\ add\colon sq\text{-}mtx\text{-}chi\text{-}inject\ vec\text{-}eq\text{-}iff\ one\text{-}sqrd\text{-}matrix\text{-}def\ zero\text{-}sqrd\text{-}matrix\text{-}def\ zero\text{-}sqrd\text{-}matrix\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}sqrd\text{-}s
mat-def)
    by(transfer, simp add: scalar-matrix-assoc matrix-scalar-ac)+
\mathbf{end}
lemma sq\text{-}mtx\text{-}one\text{-}vec: 1 *_V s = s
    by (auto simp: sq-mtx-vec-prod-def one-sqrd-matrix-def
             mat-def vec-eq-iff matrix-vector-mult-def)
lemma Cauchy-cols:
    fixes X :: nat \Rightarrow ('a::finite) \ sqrd-matrix
    assumes Cauchy X
    shows Cauchy (\lambda n. \text{ col } i (X n))
proof(unfold Cauchy-def dist-norm, clarsimp)
    fix \varepsilon::real assume \varepsilon > 0
    from this obtain M where M-def: \forall m \geq M. \forall n \geq M. ||X m - X n|| < \varepsilon
          using (Cauchy X) unfolding Cauchy-def by (simp add: dist-sqrd-matrix-def)
blast
```

```
\{ \text{fix } m \text{ } n \text{ assume } m \geq M \text{ and } n \geq M \}
    hence \varepsilon > \|X m - X n\|
      using M-def by blast
    moreover have ||X m - X n|| \ge ||(X m - X n) *_{V} e i||
      \mathbf{by}(rule\ le\text{-}mtx\text{-}norm[of\ -\ X\ m\ -\ X\ n],\ force)
    moreover have ||(X m - X n) *_{V} e i|| = ||X m *_{V} e i - X n *_{V} e i||
      by (simp add: mtx-vec-prod-minus-rdistrib)
    moreover have ... = \|\operatorname{col} i(X m) - \operatorname{col} i(X n)\|
      by (simp add: mtx-vec-prod-minus-rdistrib mtx-vec-prod-canon)
    ultimately have \|\operatorname{col} i(X m) - \operatorname{col} i(X n)\| < \varepsilon
      by linarith}
  thus \exists M. \ \forall \ m \geq M. \ \forall \ n \geq M. \ \| \operatorname{col} \ i \ (X \ m) - \operatorname{col} \ i \ (X \ n) \| < \varepsilon
    by blast
qed
lemma col-convergent:
  assumes \forall i. (\lambda n. \text{ col } i (X n)) \longrightarrow L \$ i
  shows convergent X
  unfolding convergent-def proof(rule-tac x=sq-mtx-chi (transpose L) in exI)
  let ?L = sq\text{-}mtx\text{-}chi \ (transpose \ L)
  show X \longrightarrow ?L
  proof(unfold LIMSEQ-def dist-norm, clarsimp)
    fix \varepsilon::real assume \varepsilon > 0
    let ?a = CARD('a) fix \varepsilon::real assume \varepsilon > 0
    hence \varepsilon / ?a > 0
      by simp
    from this and assms have \forall i. \exists N. \forall n \geq N. \| \text{col } i (X n) - L \$ i \| < \varepsilon / ?a
      unfolding LIMSEQ-def dist-norm convergent-def by blast
    then obtain N where \forall i. \forall n \geq N. \| \text{col } i \ (X \ n) - L \ $\ i \| < \varepsilon / ?a
      using finite-nat-minimal-witness[of \lambda i n. \|\cot i (X n) - L \$ i\| < \varepsilon / ?a] by
blast
    also have \bigwedge i \ n \cdot (\operatorname{col} \ i \ (X \ n) - L \ \ i) = (\operatorname{col} \ i \ (X \ n - ?L))
    unfolding minus-sqrd-matrix-def by (transfer, simp add: transpose-def vec-eq-iff
column-def)
    ultimately have N-def: \forall i. \forall n \geq N. \| \text{col } i \ (X \ n - ?L) \| < \varepsilon / ?a
      by auto
    have \forall n \geq N. ||X n - ?L|| < \varepsilon
    proof(rule allI, rule impI)
      fix n::nat assume N \leq n
      hence \forall i. \| \text{col } i (X n - ?L) \| < \varepsilon / ?a
        using N-def by blast
      hence (\sum i \in UNIV. \|\text{col } i \ (X \ n - ?L)\|) < (\sum (i::'a) \in UNIV. \varepsilon /?a)
        using sum-strict-mono[of - \lambda i. \|\cot i (X n - ?L)\|] by force
      moreover have ||X n - ?L|| \le (\sum i \in UNIV. ||col i (X n - ?L)||)
        using sq\text{-}mtx\text{-}norm\text{-}le\text{-}sum\text{-}col by blast
      moreover have (\sum (i::'a) \in UNIV. \ \varepsilon/?a) = \varepsilon
        by force
      ultimately show ||X n - ?L|| < \varepsilon
        by linarith
```

```
thus \exists no. \forall n \geq no. ||X n - ?L|| < \varepsilon
      \mathbf{by} blast
 qed
qed
instance sqrd-matrix :: (finite) banach
proof(standard)
  \mathbf{fix} \ X :: nat \Rightarrow 'a \ sqrd-matrix
  assume Cauchy X
  have \bigwedge i. Cauchy (\lambda n. \text{ col } i (X n))
    using \langle Cauchy X \rangle Cauchy-cols by blast
  hence obs: \forall i. \exists ! L. (\lambda n. col i (X n)) \longrightarrow L
   using Cauchy-convergent convergent-def LIMSEQ-unique by fastforce
  define L where L = (\chi i. lim (\lambda n. col i (X n)))
  from this and obs have \forall i. (\lambda n. \text{ col } i (X n)) -
     using the I-unique [of \lambda L. (\lambda n. \text{ col - } (X n)) \longrightarrow L L \$ -] by (simp add:
lim-def
  thus convergent X
    using col-convergent by blast
```

2.5 Flow for squared matrix systems

Finally, we can use the *exp* operation to characterize the general solutions for linear systems of ODEs. After this, we show that IVPs with these systems have a unique solution (using the Picard Lindeloef locale) and explicitly write it via the local flow locale.

```
\mathbf{lemma}\ mtx\text{-}vec\text{-}prod\text{-}has\text{-}derivative\text{-}mtx\text{-}vec\text{-}prod\text{:}
  assumes \bigwedge i j. D (\lambda t. (A \ t) $$ i $ j) \mapsto (\lambda \tau. \tau *_R (A' \ t) $$ i $ j) (at \ t \ within
s)
    and (\lambda \tau. \ \tau *_R (A' \ t) *_V x) = g'
  shows D(\lambda t. A t *_{V} x) \mapsto g' at t within s
  using assms(2) apply safe apply(rule\ ssubst[of\ g'\ (\lambda\tau.\ \tau\ *_R\ (A'\ t)\ *_V\ x)],
simp)
  \mathbf{unfolding}\ sq\text{-}mtx\text{-}vec\text{-}mult\text{-}sum\text{-}cols
 \operatorname{apply}(\operatorname{rule-tac} f'1 = \lambda i \ \tau \cdot \tau *_R \ (x \ \ i \ *_R \ \operatorname{col} \ i \ (A' \ t)) \ \operatorname{in} \ \operatorname{derivative-eq-intros}(9))
   apply(simp-all add: scaleR-right.sum)
 apply(rule-tac\ g'1=\lambda\tau.\ \tau*_R\ col\ i\ (A'\ t)\ in\ derivative-eq-intros(4),\ simp-all\ add:
mult.commute)
  using assms unfolding sq-mtx-col-def column-def apply(transfer, simp)
  apply(rule\ has-derivative-vec-lambda)
  \mathbf{by}(simp\ add:\ scaleR\text{-}vec\text{-}def)
lemma has-derivative-mtx-ith:
  assumes D A \mapsto (\lambda h. h *_R A' x) at x within s
  shows D(\lambda t. A t \$\$ i) \mapsto (\lambda h. h *_R A' x \$\$ i) at x within s
  unfolding has-derivative-def tendsto-iff dist-norm apply safe
```

```
apply(force simp: bounded-linear-def bounded-linear-axioms-def)
\mathbf{proof}(clarsimp)
  fix \varepsilon::real assume \theta < \varepsilon
 let ?x = net limit (at x within s) let ?\Delta y = y - ?x and ?\Delta A y = A y - A ?x
 let P = \lambda y. inverse |P \Delta y| * (||P \Delta A y - P \Delta y *_R A' x||) < e
 let Q = \lambda y. inverse |Q = \lambda y| * (||A y \$\$ i - A ?x \$\$ i - Q \Delta y *_R A' x \$\$ i||)
< \varepsilon
  from assms have \forall e > 0. eventually (?P e) (at x within s)
    unfolding has-derivative-def tendsto-iff by auto
 hence eventually (?P \varepsilon) (at x within s)
    using \langle \theta < \varepsilon \rangle by blast
  thus eventually ?Q (at x within s)
  \mathbf{proof}(rule\text{-}tac\ P=?P\ \varepsilon\ \mathbf{in}\ eventually\text{-}mono,\ simp\text{-}all)
    let ?u \ y \ i = A \ y \ \$\$ \ i - A \ ?x \ \$\$ \ i - ?\Delta \ y \ast_R A' x \ \$\$ \ i
    fix y assume hyp: inverse |?\Delta y| * (||?\Delta A y - ?\Delta y *_R A' x||) < \varepsilon
    have \|?u \ y \ i\| = \|(?\Delta A \ y - ?\Delta \ y *_R A' \ x) \$\$ \ i\|
      by simp
    also have ... \leq (\|?\Delta A y - ?\Delta y *_R A' x\|)
      \mathbf{using}\ norm\text{-}column\text{-}le\text{-}norm\ \mathbf{by}\ blast
    ultimately have \|?u\ y\ i\| \le \|?\Delta A\ y - ?\Delta\ y *_R A'\ x\|
    hence inverse |?\Delta y| * (||?u y i||) \le inverse |?\Delta y| * (||?\Delta A y - ?\Delta y *_R
A'x\|
      by (simp add: mult-left-mono)
    thus inverse |?\Delta y| * (||?u y i||) < \varepsilon
      using hyp by linarith
  qed
qed
\mathbf{lemma}\ exp\text{-}has\text{-}vderiv\text{-}on\text{-}linear:
  fixes A::(('a::finite) sqrd-matrix)
 shows D(\lambda t. exp((t-t\theta) *_R A) *_V x\theta) = (\lambda t. A *_V (exp((t-t\theta) *_R A) *_V x\theta))
x\theta)) on T
  unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp
 apply(rule-tac A'=\lambda t. A*exp((t-t\theta)*_R A) in mtx-vec-prod-has-derivative-mtx-vec-prod)
   apply(rule has-derivative-vec-nth)
   apply(rule has-derivative-mtx-ith)
   apply(rule-tac\ f'=id\ in\ exp-scaleR-has-derivative-right)
    apply(rule-tac f'1=id and g'1=\lambda x. 0 in derivative-eq-intros(11))
      apply(rule derivative-eq-intros)
  \mathbf{by}(simp\text{-}all\ add:\ fun\text{-}eq\text{-}iff\ exp\text{-}times\text{-}scaleR\text{-}commute\ sq\text{-}mtx\text{-}times\text{-}vec\text{-}assoc})
lemma picard-lindeloef-sq-mtx:
  fixes A::('n::finite) sqrd-matrix
  assumes \theta < ((real\ CARD('n))^2 * (\|to\text{-}vec\ A\|_{max})) (is \theta < ?L)
  assumes 0 \le t and t < 1/?L
 shows picard-lindeloef-closed-ivl (\lambda t s. A *_{V} s) {0..t} ?L 0
  apply unfold-locales apply(simp add: \langle 0 < t \rangle)
  subgoal by (transfer, simp, metis continuous-on-compose2 continuous-on-conq
```

```
continuous-on-id
       continuous-on-snd matrix-vector-mult-linear-continuous-on top-greatest)
 subgoal apply transfer using matrix-lipschitz-constant max-norm-ge-0 zero-compare-simps (4,12)
   unfolding lipschitz-on-def by blast
 apply(simp-all add: assms)
 subgoal for r s apply(subgoal-tac |r - s| < 1/?L)
    apply(subst\ (asm)\ pos-less-divide-eq[of\ ?L\ |r-s|\ 1])
   using assms by auto
 done
lemma local-flow-exp:
 fixes A::('n::finite) sqrd-matrix
 assumes \theta < ((real\ CARD('n))^2 * (\|to\text{-}vec\ A\|_{max})) \text{ (is } \theta < ?L)
 assumes 0 \le t and t < 1/?L
 shows local-flow ((*_V) \ A) \ \{0..t\} \ ?L \ (\lambda t \ s. \ exp \ (t *_R \ A) *_V \ s)
 unfolding local-flow-def local-flow-axioms-def apply safe
 using picard-lindeloef-sq-mtx assms apply blast
 using exp-has-vderiv-on-linear [of \theta] apply force
 by(auto simp: sq-mtx-one-vec)
end
theory cat2funcset
 \mathbf{imports}\ ../hs\text{-}prelims\ Transformer\text{-}Semantics.Kleisli\text{-}Quantale
begin
```

Chapter 3

Hybrid System Verification

— We start by deleting some conflicting notation and introducing some new. **type-synonym** ' $a \ pred = 'a \Rightarrow bool$

3.1 Verification of regular programs

```
First we add lemmas for computation of weakest liberal preconditions (wlps).
```

```
lemma ffb-eta[simp]: fb_{\mathcal{F}} \eta X = X
  unfolding ffb-def by(simp add: kop-def klift-def map-dual-def)
lemma ffb-eq: fb_{\mathcal{F}} F X = \{s. \forall y. y \in F s \longrightarrow y \in X\}
  unfolding ffb-def apply(simp add: kop-def klift-def map-dual-def)
  unfolding dual-set-def f2r-def r2f-def by auto
lemma ffb-eq-univD: fb_{\mathcal{F}} FP = UNIV \Longrightarrow (\forall y. y \in (Fx) \longrightarrow y \in P)
proof
  fix y assume fb_{\mathcal{F}} FP = UNIV
  hence UNIV = \{s. \ \forall \ y. \ y \in (F \ s) \longrightarrow y \in P\}
    \mathbf{by}(subst\ ffb\text{-}eq[symmetric],\ simp)
  hence \bigwedge x. \{x\} = \{s. \ s = x \land (\forall y. \ y \in (F \ s) \longrightarrow y \in P)\}
    by auto
  then show s2p (F x) y \longrightarrow y \in P
    by auto
qed
Next, we introduce assignments and their wlps.
abbreviation vec\text{-}upd :: ('a^{\hat{}}b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a^{\hat{}}b
  where vec-upd x i a \equiv vec-lambda ((vec-nth x)(i := a))
abbreviation assign :: b \Rightarrow (a^b \Rightarrow a) \Rightarrow (a^b \Rightarrow a) \Rightarrow (a^b \Rightarrow a) \Rightarrow (a^b \Rightarrow a) set (2 = -)
65 61
  where (x := e) \equiv (\lambda s. \{vec\text{-}upd \ s \ x \ (e \ s)\})
lemma ffb-assign[simp]: fb_{\mathcal{F}} (x := e) Q = \{s. (vec\text{-upd } s \ x \ (e \ s)) \in Q\}
```

```
\mathbf{by}(subst\ ffb\text{-}eq)\ simp
The wlp of a (kleisli) composition is just the composition of the wlps.
lemma ffb-kcomp: fb_{\mathcal{F}} (G \circ_K F) P = fb_{\mathcal{F}} G (fb_{\mathcal{F}} F P)
  unfolding ffb-def apply(simp add: kop-def klift-def map-dual-def)
  unfolding dual-set-def f2r-def r2f-def by(auto simp: kcomp-def)
We also have an implementation of the conditional operator and its wlp.
definition if then else :: 'a pred \Rightarrow ('a \Rightarrow 'b set) \Rightarrow ('a \Rightarrow 'b set) \Rightarrow ('a \Rightarrow 'b set)
  (IF - THEN - ELSE - FI [64,64,64] 63) where
  IF P THEN X ELSE Y FI \equiv (\lambda x. if P x then X x else Y x)
lemma ffb-if-then-else:
  assumes P \cap \{s. \ T \ s\} \leq fb_{\mathcal{F}} \ X \ Q
   and P \cap \{s. \neg T s\} \leq fb_{\mathcal{F}} Y Q
  shows P \leq fb_{\mathcal{F}} (IF T THEN X ELSE Y FI) Q
  using assms apply(subst\ ffb-eq)
  apply(subst (asm) ffb-eq)+
  unfolding ifthenelse-def by auto
lemma ffb-if-then-elseD:
  assumes T x \longrightarrow x \in fb_{\mathcal{F}} X Q
   \mathbf{and}\, \neg \,\, T\, x\, \longrightarrow x \in \mathit{fb}_{\mathcal{F}} \,\, Y\, Q
  shows x \in fb_{\mathcal{F}} (IF T THEN X ELSE Y FI) Q
  using assms apply(subst ffb-eq)
  apply(subst (asm) ffb-eq)+
  unfolding ifthenelse-def by auto
The final wlp we add is that of the finite iteration.
lemma kstar-inv: I \leq \{s. \ \forall y. \ y \in F \ s \longrightarrow y \in I\} \Longrightarrow I \leq \{s. \ \forall y. \ y \in (kpower)\}
F \ n \ s) \longrightarrow y \in I
 apply(induct \ n, \ simp)
  \mathbf{by}(auto\ simp:\ kcomp-prop)
lemma ffb-star-induct-self: I \leq fb_{\mathcal{F}} \ F \ I \Longrightarrow I \subseteq fb_{\mathcal{F}} \ (kstar \ F) \ I
  \mathbf{apply}(\mathit{subst\ ffb-eq},\ \mathit{subst\ }(\mathit{asm})\ \mathit{ffb-eq})
  unfolding kstar-def apply clarsimp
  using kstar-inv by blast
lemma ffb-starI:
  assumes P \leq I and I \leq fb_{\mathcal{F}} F I and I \leq Q
  shows P \leq fb_{\mathcal{F}} (kstar F) Q
proof-
  have I \subseteq fb_{\mathcal{F}} (kstar F) I
    using assms(2) ffb-star-induct-self by blast
  hence P \leq fb_{\mathcal{F}} (kstar \ F) \ I
    using assms(1) by auto
  thus ?thesis
    using assms(3) by(subst\ ffb\text{-}eq,\ subst\ (asm)\ ffb\text{-}eq,\ auto)
```

qed

3.2 Verification of hybrid programs

3.2.1 Verification by providing solutions

```
abbreviation guards :: ('a \Rightarrow bool) \Rightarrow (real \Rightarrow 'a) \Rightarrow (real set) \Rightarrow bool (- \triangleright - -
[70, 65] 61)
 where G > x T \equiv \forall r \in T. G(xr)
definition ivp-sols f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp-solsI:
  assumes D x = (f \circ x) on T x t_0 = s t_0 \in T
 shows x \in ivp\text{-}sols f T t_0 s
 using assms unfolding ivp-sols-def by blast
lemma ivp-solsD:
  assumes x \in ivp\text{-}sols f T t_0 s
 shows D x = (f \circ x) on T
    and x t_0 = s and t_0 \in T
 using assms unfolding ivp-sols-def by auto
definition g-orbital f T t_0 G s = \bigcup \{\{x \ t | t. \ t \in T \land G \rhd x \ \{t_0..t\}\}\} | x. \ x \in T
ivp-sols f T t_0 s
lemma g-orbital-eq: g-orbital f T t_0 G s=
  \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0..t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t \in T \land G \triangleright x\}
\{t_0..t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
abbreviation g-evol ::(('a::banach)\Rightarrow'a) \Rightarrow real set \Rightarrow 'a pred \Rightarrow 'a set
((1[x'=-]-\&-))
  where [x'=f]T \& G \equiv (\lambda \ s. \ g\text{-}orbital \ f \ T \ 0 \ G \ s)
lemmas g-evol-def = g-orbital-eq[where t_0=0]
lemma q-evolI:
 assumes D x = (f \circ x) on T x \theta = s
    and \theta \in T \ t \in T and G \rhd x \{\theta..t\}
 shows x \ t \in ([x'=f] T \& G) \ s
 using assms unfolding g-orbital-def ivp-sols-def by blast
lemma g-evolD:
 assumes s' \in ([x'=f]T \& G) s
 obtains x and t where x \in ivp\text{-}sols f T \theta s
```

```
and D x = (f \circ x) on T x \theta = s
 and x t = s' and \theta \in T t \in T and G \triangleright x \{\theta..t\}
  using assms unfolding g-orbital-def ivp-sols-def by blast
context local-flow
begin
lemma in-ivp-sols: (\lambda t. \varphi t s) \in ivp-sols f T \theta s
 by(auto intro: ivp-solsI simp: ivp init-time)
definition orbit s = g-orbital f T \theta (\lambda s. True) s
lemma orbit-eq[simp]: orbit s = \{ \varphi \ t \ s | \ t . \ t \in T \}
  unfolding orbit-def g-evol-def
  by(auto intro: usolves-ivp intro!: ivp simp: init-time)
lemma g-evol-collapses:
  shows ([x'=f]T \& G) s = \{\varphi \ t \ s | \ t. \ t \in T \land G \rhd (\lambda r. \varphi \ r \ s) \ \{0..t\}\}  (is - =
?qorbit)
proof(rule subset-antisym, simp-all only: subset-eq)
  \{fix s' assume s' \in ([x'=f]T \& G) s
   then obtain x and t where x-ivp:D x = (\lambda t. f(x t)) on T
      x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \triangleright x \{\theta..t\}
      unfolding g-orbital-eq by auto
    hence obs: \forall \tau \in \{0..t\}. \ x \ \tau = \varphi \ \tau \ s
      using usolves-ivp[OF x-ivp] init-time
      by (meson atLeastAtMost-iff interval-time mem-is-interval-1-I)
   hence G \triangleright (\lambda r. \varphi r s) \{\theta..t\}
      using quard by simp
   also have \varphi t s = x t
      using usolves-ivp[OF x-ivp \langle t \in T \rangle] by simp
    ultimately have s' \in ?gorbit
      using \langle x | t = s' \rangle \langle t \in T \rangle by auto
  thus \forall s' \in ([x'=f]T \& G) \ s. \ s' \in ?gorbit
   by blast
next
  \{ \text{fix } s' \text{ assume } s' \in ?gorbit \}
    then obtain t where G \triangleright (\lambda r. \varphi r s) \{0..t\} and t \in T and \varphi t s = s'
      by blast
   hence s' \in ([x'=f]T \& G) s
      by(auto intro: g-evolI simp: ivp init-time)}
  thus \forall s' \in ?gorbit. \ s' \in ([x'=f]T \& G) \ s
    by blast
qed
lemma ffb-orbit: fb_{\mathcal{F}} (orbit) Q = \{s. \forall t \in T. \varphi \ t \ s \in Q\}
  unfolding orbit-eq ffb-eq by auto
lemma ffb-g-orbit: fb_{\mathcal{F}} ([x'=f]T \& G) Q = \{s. \forall t \in T. (G \triangleright (\lambda r. \varphi r s) \{0..t\})\}
```

apply(rule unique-solution, simp-all add: ivp)

```
unfolding g-evol-collapses ffb-eq by auto
end
lemma (in local-flow) ivp-sols-collapse: ivp-sols f \ T \ 0 \ s = \{(\lambda t. \ \varphi \ t \ s)\}
apply(auto simp: ivp-sols-def ivp init-time fun-eq-iff)
```

The previous lemma allows us to compute wlps for known systems of ODEs. We can also implement a version of it as an inference rule. A simple computation of a wlp is shown immmediately after.

```
lemma dSolution:
```

oops

 $\longrightarrow (\varphi \ t \ s) \in Q$

```
assumes local-flow f T L \varphi and \forall s. s \in P \longrightarrow (\forall t \in T. (G \rhd (\lambda r. \varphi r s) \{0..t\}) \longrightarrow (\varphi t s) \in Q) shows P \leq fb_{\mathcal{F}} ([x'=f]T \& G) Q using assms by(subst local-flow.ffb-g-orbit) auto
```

```
lemma ffb-line: 0 \le t \Longrightarrow fb_{\mathcal{F}}([x'=\lambda t.\ c]\{0..t\}\ \&\ G)\ Q = \{x.\ \forall\ \tau \in \{0..t\}.\ (G\rhd(\lambda r.\ x+r*_R\ c)\ \{0..\tau\})\longrightarrow (x+\tau*_R\ c)\in Q\} apply(subst local-flow.ffb-g-orbit[of \lambda t. c - 1/(t+1)\ (\lambda\ t\ x.\ x+t*_R\ c)]) by(auto\ simp:\ line-is-local-flow)
```

3.2.2 Verification with differential invariants

We derive domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in our verification proofs.

Differential Weakening

```
\begin{array}{l} \mathbf{lemma}\ DW\colon fb_{\mathcal{F}}\ ([x'=f]\{0..t\}\ \&\ G)\ Q=fb_{\mathcal{F}}\ ([x'=f]\{0..t\}\ \&\ G)\ \{s.\ G\ s\longrightarrow s\in Q\}\\ \mathbf{by}(auto\ intro:\ g\text{-}evolD\ simp:\ ffb\text{-}eq) \\ \\ \mathbf{lemma}\ dWeakening:\\ \mathbf{assumes}\ \{s.\ G\ s\}\le Q\\ \mathbf{shows}\ P\le fb_{\mathcal{F}}\ ([x'=f]\{0..t\}\ \&\ G)\ Q\\ \mathbf{using}\ assms\ \mathbf{by}(auto\ intro:\ g\text{-}evolD\ simp:\ le\text{-}fun\text{-}def\ g\text{-}evol\text{-}def\ ffb\text{-}eq}) \end{array}
```

Differential Cut

```
lemma ffb-g-orbit-eq-univD:

assumes fb<sub>F</sub> ([x'=f]T & G) {s. C s} = UNIV

and \forall r \in \{0..t\}. x r \in ([x'=f]T \& G) s
```

```
shows \forall r \in \{0..t\}. C(x r)
proof
  fix r assume r \in \{\theta..t\}
  then have x r \in ([x'=f]T \& G) s
    using assms(2) by blast
  also have \forall y. y \in ([x'=f]T \& G) s \longrightarrow C y
    using assms(1) ffb-eq-univD by fastforce
  ultimately show C(x r) by blast
qed
lemma DC:
  assumes interval T and fb_{\mathcal{F}} ([x'=f]T \& G) \{s. C s\} = UNIV
  shows fb_{\mathcal{F}} ([x'=f]T \& G) Q = fb_{\mathcal{F}} ([x'=f]T \& (\lambda s. G s \land C s)) Q
\operatorname{\mathbf{proof}}(rule\text{-}tac\ f = \lambda\ x.\ fb_{\mathcal{F}}\ x\ Q\ \mathbf{in}\ HOL.arg\text{-}cong,\ rule\ ext,\ rule\ subset\text{-}antisym)
  \mathbf{fix} \ s
  {fix s' assume s' \in ([x'=f]T \& G) s
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
      and guard-x:G \triangleright x \{0..t\} and s' = x t and \theta \in T t \in T
      using g-evolD[of s' f T G s] by (metis (full-types))
    from guard-x have \forall r \in \{0..t\}. \forall \tau \in \{0..r\}. G(x \tau)
      by auto
    also have \forall \tau \in \{0..t\}. \tau \in T
        by (meson \ \langle \theta \in T \rangle \ \langle t \in T \rangle \ assms(1) \ atLeastAtMost-iff interval.interval
mem-is-interval-1-I)
    ultimately have \forall \tau \in \{0..t\}. x \tau \in ([x'=f]T \& G) s
      using g-evolI[OF x-ivp \langle \theta \in T \rangle] by blast
    hence C \triangleright x \{\theta..t\}
      using ffb-g-orbit-eq-univD assms(2) by blast
    hence s' \in ([x'=f]T \& (\lambda s. G s \land C s)) s
      using g-evolf[OF x-ivp \langle 0 \in T \rangle \langle t \in T \rangle] guard-x \langle s' = x t \rangle by fastforce}
  thus ([x'=f]T \& G) s \subseteq ([x'=f]T \& (\lambda s. G s \land C s)) s
    by blast
next show \bigwedge s. ([x'=f]T \& (\lambda s. G s \land C s)) s \subseteq ([x'=f]T \& G) s
    by (auto simp: g-evol-def)
qed
lemma dCut:
  assumes ffb-C:P \le fb_{\mathcal{F}} ([x'=f] \{ \theta ...t \} \& G) \{ s. C s \}
    and ffb-Q:P \le fb_{\mathcal{F}} ([x'=f]\{\theta..t\} \& (\lambda s. G s \land C s)) Q
  shows P \leq fb_{\mathcal{F}} ([x'=f] \{ \theta ... t \} \& G) Q
proof(subst ffb-eq, subst g-evol-def, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a assume (x \ \theta) \in P and \theta \leq \tau and \tau \leq t
    and x-solves: D = (\lambda t. f(x t)) on \{0...t\} and guard-x: (\forall r \in \{0...\tau\}). G(x \in \{0...\tau\})
r))
  hence \forall r \in \{0..\tau\}. \forall \tau \in \{0..r\}. G(x \tau)
    by auto
  hence \forall r \in \{0..\tau\}. \ x \ r \in ([x'=f]\{0..t\} \& G) \ (x \ 0)
    using q-evol x-solves \langle 0 < \tau \rangle \langle \tau < t \rangle by fastforce
  hence \forall r \in \{0..\tau\}. C(x r)
```

```
\begin{array}{l} \textbf{using} \ \textit{ffb-C} \ ((x \ \theta) \in P) \ \textbf{by}(\textit{subst} \ (\textit{asm}) \ \textit{ffb-eq}, \ \textit{auto}) \\ \textbf{hence} \ x \ \tau \in ([x'=f]\{\theta..t\} \ \& \ (\lambda \ s. \ G \ s \ \land \ C \ s)) \ (x \ \theta) \\ \textbf{using} \ g\text{-}evolI \ x\text{-}solves \ \textit{guard-}x \ (\theta \le \tau) \ (\tau \le t) \ \textbf{by} \ \textit{fastforce} \\ \textbf{from} \ \textit{this} \ ((x \ \theta) \in P) \ \textbf{and} \ \textit{ffb-Q} \ \textbf{show} \ (x \ \tau) \in Q \\ \textbf{by}(\textit{subst} \ (\textit{asm}) \ \textit{ffb-eq}) \ \textit{auto} \\ \textbf{qed} \end{array}
```

Differential Invariant

```
lemma DI-sufficiency:
  assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
  shows fb_{\mathcal{F}} ([x'=f]T \& G) Q \leq fb_{\mathcal{F}} (\lambda x. \{s. s = x \land G s\}) Q
  using assms apply(subst ffb-eq, subst ffb-eq, clarsimp)
  apply(rename-tac\ s,\ erule-tac\ x=s\ in\ all E,\ erule\ impE)
  apply(simp add: g-evol-def ivp-sols-def)
  apply(erule-tac \ x=s \ in \ all E, \ clarify)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
  shows fb_{\mathcal{F}} (\lambda x. \{s. s = x \land G s\}) Q \leq fb_{\mathcal{F}} ([x'=f]T \& G) Q
  unfolding ffb-g-orbit apply(subst ffb-eq, clarsimp, safe)
   apply(erule-tac \ x=0 \ in \ ballE)
    apply(simp add: ivp, simp)
  oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
\Rightarrow bool
((-)/ is'-diff'-invariant'-of (-)/ along (-) [70,65]61)
where I is-diff-invariant-of f along T \equiv
  (\forall s. \ I \ s \longrightarrow (\forall \ x. \ x \in ivp\text{-sols} \ f \ T \ 0 \ s \longrightarrow (\forall \ t \in T. \ I \ (x \ t))))
lemma invariant-to-set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s. \ Is \longrightarrow (g\text{-}orbital \ f \ T \ 0 \ (\lambda s.
True(s) \subseteq \{s. \ I \ s\}
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
   apply(erule-tac \ x=xa \ \theta \ in \ all E)
   apply(drule mp, simp-all)
  apply(erule-tac x=xa \ \theta \ in \ all E)
  apply(drule mp, simp-all add: subset-eq)
  apply(erule-tac \ x=xa \ t \ in \ all E)
  \mathbf{by}(drule\ mp,\ auto)
context local-flow
begin
\mathbf{lemma} \ \textit{diff-invariant-eq-invariant-set} \colon
  (\textit{I is-diff-invariant-of f along } T) = (\forall \textit{s}. \ \forall \textit{t} \in \textit{T}. \ \textit{I s} \longrightarrow \textit{I} \ (\varphi \ \textit{t s}))
  \mathbf{by}(subst\ invariant\text{-}to\text{-}set,\ auto\ simp:\ g\text{-}evol\text{-}collapses)
```

```
lemma invariant-set-eq-dl-invariant:
  shows (\forall s. \forall t \in T. I s \longrightarrow I (\varphi t s)) = (\{s. I s\} = fb_{\mathcal{F}} (orbit) \{s. I s\})
  apply(safe, simp-all add: ffb-orbit)
  apply(erule-tac \ x=0 \ in \ ballE)
  by(auto simp: ivp(2) init-time)
end
lemma dInvariant:
  assumes I is-diff-invariant-of f along T
  shows \{s. \ I \ s\} \le fb_{\mathcal{F}} ([x'=f] \ T \ \& \ G) \{s. \ I \ s\}
  using assms by(auto simp: diff-invariant-def ivp-sols-def ffb-eq g-orbital-eq)
\mathbf{lemma}\ dInvariant\text{-}converse:
  assumes \{s.\ I\ s\} \leq fb_{\mathcal{F}}\ ([x'=f]\ T\ \&\ (\lambda s.\ True))\ \{s.\ I\ s\}
  shows I is-diff-invariant-of f along T
  using assms unfolding invariant-to-set ffb-eq by auto
lemma ffb-g-evol-le-requires:
  assumes \forall s. \exists x. x \in (ivp\text{-}sols f \ T \ 0 \ s) \land G \ s
   shows fb_{\mathcal{F}} ([x'=f]T \& G) \{s. \ I \ s\} \le \{s. \ I \ s\}
  apply(simp add: ffb-eq g-orbital-eq, clarify)
  apply(erule-tac \ x=x \ in \ all E, \ erule \ impE, \ simp-all)
  using assms ivp-solsD(1) by(fastforce simp: ivp-sols-def)
lemma dI:
assumes I is-diff-invariant-of f along \{0..t\}
    and P \leq \{s. \ I \ s\} and \{s. \ I \ s\} \leq Q
  shows P \leq fb_{\mathcal{F}} ([x'=f] \{0..t\} \& G) Q
  apply(rule-tac\ C=I\ in\ dCut)
  using dInvariant assms apply blast
  \mathbf{apply}(\mathit{rule}\ \mathit{dWeakening})
  using assms by auto
```

Finally, we obtain some conditions to prove specific instances of differential invariants.

named-theorems diff-invariant-rules compilation of rules for differential invariants.

```
lemma [diff-invariant-rules]: fixes \vartheta::'a::banach \Rightarrow real assumes \forall x. (D \ x = (\lambda \tau. \ f \ (x \ \tau)) \ on \ \{\theta..t\}) \longrightarrow (\forall \tau \in \{\theta..t\}. \ (D \ (\lambda \tau. \ \vartheta \ (x \ \tau) - \nu \ (x \ \tau)) = ((*_R) \ \theta) \ on \ \{\theta..\tau\})) shows (\lambda s. \ \vartheta \ s = \nu \ s) is-diff-invariant-of f along \{\theta..t\} proof(simp add: diff-invariant-def ivp-sols-def, clarsimp) fix x \ \tau assume tHyp: \theta \le \tau \ \tau \le t and x\text{-ivp}: D \ x = (\lambda \tau. \ f \ (x \ \tau)) \ on \ \{\theta..t\} \ \vartheta \ (x \ \theta) = \nu \ (x \ \theta) hence \forall \ t \in \{\theta..\tau\}. \ D \ (\lambda \tau. \ \vartheta \ (x \ \tau) - \nu \ (x \ \tau)) \mapsto (\lambda \tau. \ \tau *_R \ \theta) \ at \ t \ within \ \{\theta..\tau\}
```

```
using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists t \in \{0..\tau\}. \vartheta(x\tau) - \nu(x\tau) - (\vartheta(x\theta) - \nu(x\theta)) = (\tau - \theta) \cdot \theta
    by(rule-tac mvt-very-simple) (auto simp: tHyp)
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
qed
lemma [diff-invariant-rules]:
  fixes \vartheta::'a::banach \Rightarrow real
  assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \vartheta'(x \tau) \geq \nu'
  (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
  shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) \leq \vartheta(x \theta)
  hence primed: \forall r \in \{0..\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x \tau)))
-\nu'(xr))
  at r within \{0..\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
    using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists r \in \{0..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
  then obtain r where r \in \{\theta..\tau\}
    and \vartheta (x \tau) - \nu (x \tau) = (\tau - \theta) *_R (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
    by force
  also have ... > 0
    using tHyp(1) x-ivp(2) primed calculation(1) by auto
  ultimately show \nu (x \tau) < \vartheta (x \tau)
    by simp
\mathbf{qed}
lemma [diff-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{\theta..t\}) \longrightarrow (\forall \tau \in \{\theta..t\}. \vartheta'(x \tau) \geq \nu'(x \tau))
  (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp: D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) < \vartheta(x \theta)
  hence primed: \forall r \in \{0..\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) has-derivative
(\lambda \tau. \ \tau *_R \ (\vartheta'(x r) - \nu'(x r)))) \ (at \ r \ within \ \{0..\tau\}) \land \vartheta'(x r) \ge \nu'(x r)
    using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists r \in \{0..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    by(rule-tac mvt-very-simple) (auto simp: tHyp)
  then obtain r where r \in \{\theta..\tau\} and
    \vartheta(x\tau) - \nu(x\tau) = (\tau - \theta) *_R (\vartheta'(xr) - \nu'(xr)) + (\vartheta(x\theta) - \nu(x\theta))
```

```
by force
 also have ... > \theta
  using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
      calculation(1) diff-gt-0-iff-gt ge-iff-diff-ge-0 less-eq-real-def zero-le-scaleR-iff)
 ultimately show \nu (x \tau) < \vartheta (x \tau)
   by simp
qed
lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
   and I_2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. I_1 \ s \wedge I_2 \ s) is-diff-invariant-of f along \{0..t\}
 using assms unfolding diff-invariant-def by auto
lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
   and I_2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. I_1 \ s \lor I_2 \ s) is-diff-invariant-of f along \{0..t\}
 using assms unfolding diff-invariant-def by auto
end
theory cat2funcset-examples
 imports ../hs-prelims-matrices cat2funcset
begin
```

3.2.3 Examples

The examples in this subsection show different approaches for the verification of hybrid systems. however, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n) $vec \Rightarrow ('a, 'n)$ vec to model the dynamics of our system. Then we show a partial correctness specification involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.

- 3. We define a local flow (φ_K) and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = \{''x'', ''v''\}
 morphisms to-str to-var
 apply(rule-tac \ x=''x'' \ in \ exI)
 by simp
notation to-var (\upharpoonright_V)
lemma number-of-program-vars: CARD(program-vars) = 2
 using type-definition.card type-definition-program-vars by fastforce
instance program-vars::finite
 apply(standard, subst bij-betw-finite[of to-str UNIV {"x","v"}])
  apply(rule bij-betwI')
    apply (simp add: to-str-inject)
 using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
 by simp
lemma program-vars-univD:(UNIV::program-vars\ set) = \{ \upharpoonright_V "x", \upharpoonright_V "v" \}
 apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:x = \upharpoonright_V "x" \lor x = \upharpoonright_V "v"
 using program-vars-univD by auto
abbreviation constant-acceleration-kinematics g s \equiv
 (\chi i. if i=()_V "x") then s \$ ()_V "v") else g)
notation constant-acceleration-kinematics (K)
lemma cnst-acc-continuous:
 fixes X::(real \hat{p}rogram-vars) set
 shows continuous-on X (K g)
 apply(rule\ continuous-on-vec-lambda)
 unfolding continuous-on-def apply clarsimp
 \mathbf{by}(intro\ tendsto-intros)
lemma picard-lindeloef-cnst-acc:
 fixes g::real assumes 0 \le t and t < 1
 shows picard-lindeloef-closed-ivl (\lambda t. K g) {0..t} 1 0
 unfolding picard-lindeloef-closed-ivl-def apply(simp add: lipschitz-on-def assms,
safe)
 apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
 apply(simp-all add: cnst-acc-continuous continuous-on-snd)
```

```
apply(simp add: dist-vec-def L2-set-def dist-real-def)
   apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
   apply(simp-all add: to-var-inject)
  using assms by linarith
abbreviation constant-acceleration-kinematics-flow q t s \equiv
  (\chi \ i. \ if \ i=(\upharpoonright_V \ ''x'') \ then \ g \cdot t \ \widehat{\ } 2/2 \ + \ s \ \$ \ (\upharpoonright_V \ ''v'') \cdot t \ + \ s \ \$ \ (\upharpoonright_V \ ''x'')
        else g \cdot t + s \$ (\upharpoonright_V "v"))
notation constant-acceleration-kinematics-flow (\varphi_K)
term D(\lambda t. \varphi_K g t s) = (\lambda t. K g (\varphi_K g t s)) on \{0..t\}
lemma local-flow-cnst-acc:
  assumes 0 \le t and t < 1
  shows local-flow (K g) \{0..t\} 1 (\varphi_K g)
  unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-cnst-acc apply blast
   apply(rule has-vderiv-on-vec-lambda, clarify)
   \mathbf{apply}(\mathit{case\text{-}tac}\ i = \upharpoonright_V "x")
  using program-vars-exhaust
  by(auto intro!: poly-derivatives simp: to-var-inject vec-eq-iff)
lemma single-evolution-ball:
  fixes h::real assumes 0 \le t and t < 1 and g < 0 and h \ge 0
  shows \{s. \ s \ (\upharpoonright_V "x") = h \land s \ (\upharpoonright_V "v") = \theta\}
  \leq fb_{\mathcal{F}} ([x'=K \ g] \{\theta..t\} \& (\lambda \ s. \ s \ \$ (\upharpoonright_V "x") \geq \theta))
  \{s. \ 0 \leq s \ \$ \ (\upharpoonright_V "x") \land s \ \$ \ (\upharpoonright_V "x") \leq h\}
  apply(subst local-flow.ffb-q-orbit[OF local-flow-cnst-acc])
  using assms by (auto simp: mult-nonpos-nonneg)
no-notation to-var (\upharpoonright_V)
no-notation constant-acceleration-kinematics (K)
no-notation constant-acceleration-kinematics-flow (\varphi_K)
```

Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a 3×3 matrix (named K) to denote the linear operator that models the constantly accelerated motion.
- 3. We define a local flow (φ_K) and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

term x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. however, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

lemma exhaust-5: — The analogs for 1, 2 and 3 have already been proven in Analysis.

```
fixes x::5 shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5 proof (induct \, x) case (of\text{-}int \, z) then have 0 \le z and z < 5 by simp\text{-}all then have z = 0 \lor z = 1 \lor z = 2 \lor z = 3 \lor z = 4 by arith then show ?case by auto qed lemma UNIV\text{-}3:(UNIV::3 \, set) = \{0, 1, 2\} apply safe using exhaust\text{-}3 three-eq-zero by (blast, auto) lemma sum\text{-}axis\text{-}UNIV\text{-}3[simp]:(\sum j\in (UNIV::3 \, set). \, axis \, i \, 1 \, \$ \, j \cdot f \, j) = (f::3 \Rightarrow real) \, i unfolding axis\text{-}def \, UNIV\text{-}3 apply simp using exhaust\text{-}3 by force
```

We can rewrite the original constant acceleration kinematics as a linear operator applied to a 3-dimensional vector. For that we take advantage of the following fact:

```
lemma e 1 = (\chi \ j :: 3. \ if \ j = 0 \ then \ 0 \ else \ if \ j = 1 \ then \ 1 \ else \ 0) unfolding axis-def by(rule Cart-lambda-cong, simp)
```

```
abbreviation constant-acceleration-kinematics-matrix \equiv (\chi i::3. if i=0 then e 1 else if i=1 then e 2 else (0::real^3))
```

```
abbreviation constant-acceleration-kinematics-matrix-flow t s \equiv (\chi i::3. if i=0 then s \$ 2 \cdot t ^2/2 + s \$ 1 \cdot t + s \$ 0 else if i=1 then s \$ 2 \cdot t + s \$ 1 else s \$ 2)
```

notation constant-acceleration-kinematics-matrix (A)

```
notation constant-acceleration-kinematics-matrix-flow (\varphi_A)
```

With these 2 definitions and the proof that linear systems of ODEs are Picard-Lindeloef, we can show that they form a pair of vector-field and its flow.

```
lemma entries-cnst-acc-matrix: entries A = \{0, 1\}
```

```
apply (simp-all\ add:\ axis-def,\ safe) by (rule-tac\ x=1\ in\ exI,\ simp)+ lemma local-flow-cnst-acc-matrix: assumes 0 \le t and t < 1/9 shows local-flow ((*v)\ A)\ \{0..t\}\ ((real\ CARD(3))^2\cdot (\|A\|_{max}))\ \varphi_A unfolding local-flow-def local-flow-axioms-def apply safe apply (rule\ picard-lindeloef-linear-system[where A=A and t=t]) using entries-cnst-acc-matrix assms apply (force,\ simp,\ force) apply (rule\ has-vderiv-on-vec-lambda) apply (auto\ intro!:\ poly-derivatives simp:\ matrix-vector-mult-def vec-eq-iff) using exhaust-3 by force
```

Finally, we compute the wlp and use it to verify the single-evolution ball again.

 $\mathbf{lemma} \ single-evolution\text{-}ball\text{-}matrix:$

```
assumes 0 \le t and t < 1/9

shows \{s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2\}

\le fb_{\mathcal{F}}\left([x'=(*v) \ A]\{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0)\right)

\{s. \ 0 \le s \$ \ 0 \land s \$ \ 0 \le h\}

apply(subst local-flow.ffb-g-orbit[of (*v) \ A - 9 \cdot (\|A\|_{max}) \varphi_A])

using local-flow-cnst-acc-matrix and assms apply force

using assms by(auto simp: mult-nonneg-nonpos2)
```

Circular Motion

The characteristics that distinguish this example are:

- 1. We employ an existing finite type of size 2 to model program variables.
- 2. We define a 2×2 matrix (named C) to denote the linear operator that models circular motion.
- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow (φ_C) and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two\text{-}eq\text{-}zero: (2::2) = 0
by simp
lemma [simp]: i \neq (0::2) \longrightarrow i = 1
using exhaust\text{-}2 by fastforce
```

```
lemma UNIV-2: (UNIV::2 \ set) = \{0, 1\}
 apply safe using exhaust-2 two-eq-zero by auto
abbreviation circular-motion-matrix :: real^2^2
 where circular-motion-matrix \equiv (\chi i. if i=0 then - e 1 else e 0)
notation circular-motion-matrix (C)
lemma circle-invariant:
 shows (\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2) is-diff-invariant-of (*v) C along \{\theta...t\}
 apply(rule-tac diff-invariant-rules, clarsimp)
 apply(frule-tac\ i=0\ in\ has-vderiv-on-vec-nth,\ drule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
 apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
 by(auto intro!: poly-derivatives simp: matrix-vector-mult-def)
\mathbf{lemma}\ \mathit{circular-motion-invariants}\colon
 shows \{s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2\} \le
 fb_{\mathcal{F}}([x'=(*v)\ C]\{\theta..t\}\ \&\ (\lambda\ s.\ True))
\{s.\ r^2=(s\ \$\ \theta)^2+(s\ \$\ 1)^2\}
 apply(rule-tac I=\lambda s. r^2=(s \$ \theta)^2+(s \$ 1)^2 in dInvariant)
 using circle-invariant by blast
— Proof of the same specification by providing solutions:
lemma entries-circ-mtx: entries C = \{0, -1, 1\}
 apply (simp-all add: axis-def, safe)
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 by (rule-tac \ x=1 \ in \ exI, \ simp)+
abbreviation circular-motion-matrix-flow t s \equiv
  (\chi i. if i = (0::2) then s 0 \cdot cos t - s 1 \cdot sin t else s 0 \cdot sin t + s 1 \cdot cos t)
notation circular-motion-matrix-flow (\varphi_C)
\mathbf{lemma}\ \mathit{local-flow-circ-mtx}\colon
 assumes 0 \le t and t < 1/4
 shows local-flow ((*v) C) \{\theta..t\} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \varphi_C
 unfolding local-flow-def local-flow-axioms-def apply safe
   apply(rule picard-lindeloef-linear-system)
 unfolding entries-circ-mtx using assms apply(simp-all)
  apply(rule has-vderiv-on-vec-lambda)
 apply(force intro!: poly-derivatives simp: matrix-vector-mult-def)
 using exhaust-2 two-eq-zero by(force simp: vec-eq-iff)
lemma circular-motion:
 assumes 0 \le t and t < 1/4 and (r::real) > 0
 shows \{s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2\} \le
 fb_{\mathcal{F}}([x'=(*v)\ C]\{0..t\}\ \&\ (\lambda\ s.\ s\ \$\ 0\geq 0))
```

```
\{s.\ r^2=(s\ \$\ 0)^2+(s\ \$\ 1)^2\}
apply(subst local-flow.ffb-g-orbit[OF local-flow-circ-mtx])
using assms by auto

no-notation circular-motion-matrix (C)

no-notation circular-motion-matrix-flow (\varphi_G)
```

Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynamics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb-real-arith]: 0 \le x \Longrightarrow 0 > g \Longrightarrow 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v \Longrightarrow
(x::real) \leq h
proof-
  assume 0 \le x and 0 > g and 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
  then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot h \wedge \theta > g by auto
  hence *:v \cdot v = 2 \cdot g \cdot (x - h) \land 0 > g \land v \cdot v \ge 0
    using left-diff-distrib mult.commute by (metis zero-le-square)
  from this have (v \cdot v)/(2 \cdot g) = (x - h) by auto
  also from * have (v \cdot v)/(2 \cdot g) \leq \theta
    using divide-nonneg-neg by fastforce
  ultimately have h - x \ge 0 by linarith
  thus ?thesis by auto
qed
lemma [bb-real-arith]:
  assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
   and pos: g \cdot \tau^2 / 2 + v \cdot \tau + (x::real) = 0
  shows 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    and 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
  from pos have q \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot x = 0
   by (metis (mono-tags, hide-lams) Groups.mult-ac(1,3) mult-zero-right
        monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + v^2 + 2 \cdot g \cdot h = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(g \cdot \tau + v)^2 + 2 \cdot g \cdot h = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide\text{-}lams)\ Groups.add\text{-}ac(2,3)
        Groups.mult-ac(2, 3) monoid-mult-class.power2-eq-square nat-distrib(2))
```

```
hence 2 \cdot g \cdot h + (-((g \cdot \tau) + v))^2 = 0
    by (metis\ Groups.add-ac(2)\ power2-minus)
  thus 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
 from * show 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
qed
lemma [bb-real-arith]:
 assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
shows 2 \cdot g \cdot (g \cdot \tau^2 / 2 + v \cdot \tau + (x::real)) =
  2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
  have ?lhs = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x
      apply(subst\ Rat.sign-simps(18))+
      \mathbf{by}(auto\ simp:\ semiring-normalization-rules(29))
    also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot h + v \cdot v (is ... = ?middle)
      \mathbf{bv}(subst\ invar,\ simp)
    finally have ?lhs = ?middle.
  moreover
  {have ?rhs = g \cdot g \cdot (\tau \cdot \tau) + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot h + v \cdot v
    by (simp add: Groups.mult-ac(2,3) semiring-class.distrib-left)
  also have \dots = ?middle
    by (simp add: semiring-normalization-rules(29))
 finally have ?rhs = ?middle.}
  ultimately show ?thesis by auto
qed
lemma bouncing-ball:
 assumes 0 \le t and t < 1/9
 shows \{s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 = h \land s \ \$ \ 1 = 0 \land 0 > s \ \$ \ 2\} \le fb_{\mathcal{F}}
  (kstar\ (([x'=(*v)\ A]\{0..t\}\ \&\ (\lambda\ s.\ s\ \$\ 0\geq 0))\circ_{K}
  (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s. - s \$ 1)) ELSE \eta FI)))
  \{s. \ 0 \le s \$ \ 0 \land s \$ \ 0 \le h\}
 apply(rule ffb-starI[of - {s. 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot h
+ (s\$1 \cdot s\$1)\}])
  apply(clarsimp, simp only: ffb-kcomp)
   apply(subst local-flow.ffb-g-orbit[OF local-flow-cnst-acc-matrix])
  using assms apply(simp, simp, clarsimp)
   apply(rule ffb-if-then-elseD)
  by(auto simp: bb-real-arith)
```

Bouncing Ball with invariants

We prove again the bouncing ball but this time with differential invariants.

```
lemma gravity-invariant: (\lambda s. s. s. 2 < 0) is-diff-invariant-of (*v) A along \{0..t\} apply(rule-tac \vartheta'=\lambda s. \theta and \nu'=\lambda s. \theta in diff-invariant-rules(3), clarsimp) apply(drule-tac i=2 in has-vderiv-on-vec-nth) apply(rule-tac S=\{0..t\} in has-vderiv-on-subset)
```

```
by (auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
lemma energy-conservation-invariant:
  (\lambda s. \ 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0) is-diff-invariant-of (*v) A
along \{0..t\}
  apply(rule diff-invariant-rules, clarify)
  apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
  apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
  apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
  apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
  by (auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
lemma bouncing-ball-invariants:
  shows \{s. \ 0 \leq s \ \ 0 \land s \ \ 0 = h \land s \ \ 1 = 0 \land 0 > s \ \ 2\} \leq fb_{\mathcal{F}}
  (kstar\ (([x'=(*v)\ A]\{0..t\}\ \&\ (\lambda\ s.\ s\ \$\ 0\geq 0))\circ_{K}
  (IF (\lambda s. s \$ 0 = 0) THEN (1 := (\lambda s. - s \$ 1)) ELSE \eta FI)))
  \{s. \ 0 \leq s \ \ \theta \land s \ \ \theta \leq h\}
 \mathbf{apply}(\textit{rule-tac }I = \{s. \ 0 \leq s\$0 \ \land \ 0 > s\$2 \ \land \ 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot h + (s\$1) \}
\cdot s$1)} in ffb-starI)
   apply(clarsimp, simp only: ffb-kcomp)
  apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
   apply(rule-tac I=\lambda s. s \$ 2 < 0 \text{ in } dI)
  using gravity-invariant apply(blast, force, force)
  apply(rule-tac C=\lambda s. 2 · s$2 · s$0 - 2 · s$2 · h - s$1 · s$1 = 0 in dCut)
   apply(rule-tac I=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0 in dI)
  using energy-conservation-invariant apply(blast, force, force)
  apply(rule dWeakening)
  apply(rule ffb-if-then-else)
  by(auto simp: bb-real-arith le-fun-def)
no-notation constant-acceleration-kinematics-matrix (A)
```

no-notation constant-acceleration-kinematics-matrix-flow (φ_A)

Bouncing Ball with exponential solution

In our final example, we prove again the bouncing ball specification but this time we do it with the general solution for linear systems.

```
lemma ffb-sq-mtx: fixes A::('n::finite) sqrd-matrix assumes 0 < ((real\ CARD('n))^2 * (\|to\text{-}vec\ A\|_{max})) (is 0 < ?L) assumes 0 \le t and t < 1/?L shows fb_{\mathcal{F}}([x'=(*_V)\ A]\{0..t\}\ \&\ G)\ Q = \{s.\ \forall\ \tau\in\{0..t\}.\ (G\rhd(\lambda t.\ exp\ (t*_R\ A)*_V\ s)\ \{0..\tau\}) \longrightarrow (exp\ (\tau*_R\ A)*_V\ s) \in\ Q\} apply(subst local-flow.ffb-g-orbit) using local-flow-exp[OF\ assms]\ by\ auto
```

 $\textbf{abbreviation}\ constant\text{-}acceleration\text{-}kinematics\text{-}sq\text{-}mtx \equiv sq\text{-}mtx\text{-}chi\ constant\text{-}acceleration\text{-}kinematics\text{-}median second se$

```
notation constant-acceleration-kinematics-sq-mtx (K)
lemma max-norm-cnst-acc-sq-mtx: \|to\text{-vec }K\|_{max}=1
proof-
 have \{to\text{-}vec\ K\ \$\ i\ \$\ j\ | i\ j.\ i\in UNIV\ \land\ j\in UNIV\}=\{0,\ 1\}
   apply (simp-all add: axis-def, safe)
   \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
  thus ?thesis
   by auto
qed
lemma ffb-cnst-acc-sq-mtx:
 assumes 0 \le t and t < 1/9
 shows fb_{\mathcal{F}} ([x' = (*_V) K]{\theta ...t} & G) Q =
    \{s. \ \forall \tau \in \{0..t\}. \ (G \rhd (\lambda r. \ (exp\ (r *_R K)) *_V s) \ \{0..\tau\}) \longrightarrow ((exp\ (\tau *_R K))
*_V s) \in Q
 apply(subst local-flow.ffb-g-orbit[of (*_V) K - ((real CARD(3))^2 \cdot (||to-vec K||_{max})))
(\lambda t \ x. \ (exp \ (t *_R K)) *_V x)])
  apply(rule local-flow-exp)
  using max-norm-cnst-acc-sq-mtx assms by auto
lemma exp-cnst-acc-sq-mtx-simps:
 exp (\tau *_R K) \$\$ 0 \$ 0 = 1 exp (\tau *_R K) \$\$ 0 \$ 1 = \tau exp (\tau *_R K) \$\$ 0 \$ 2
= \tau^2/2
 exp \ (\tau *_R K) \$\$ \ 1 \$ \ 0 = 0 \ exp \ (\tau *_R K) \$\$ \ 1 \$ \ 1 = 1 \ exp \ (\tau *_R K) \$\$ \ 1 \$ \ 2
 exp \ (\tau *_R K) \$\$ \ 2 \$ \ 0 = 0 \ exp \ (\tau *_R K) \$\$ \ 2 \$ \ 1 = 0 \ exp \ (\tau *_R K) \$\$ \ 2 \$ \ 2
= 1
 sorry
lemma bouncing-ball-K:
  assumes 0 \le t and t < 1/9
 shows \{s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 = h \land s \ \$ \ 1 = 0 \land 0 > s \ \$ \ 2\} \le fb_{\mathcal{F}}
  (kstar\ (([x'=(*_V)\ K]\{0..t\}\ \&\ (\lambda\ s.\ s\ \$\ 0\geq 0))\circ_K
  (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s. - s \$ 1)) ELSE \eta FI)))
  \{s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 \le h\}
  apply(rule ffb-starI[of - {s. 0 \le s \$ (0::3) \land 0 > s \$ 2 \land
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot h + (s \$ 1 \cdot s \$ 1)\}]
   apply(clarsimp, simp only: ffb-kcomp)
 apply(subst\ ffb-sq-mtx)
  using max-norm-cnst-acc-sq-mtx assms
     apply(force, simp, force, clarify)
  apply(rule ffb-if-then-elseD, clarsimp)
  apply(simp-all add: sq-mtx-vec-prod-eq)
  unfolding UNIV-3 apply(simp-all add: exp-cnst-acc-sq-mtx-simps)
  subgoal for x using bb-real-arith(3)[of x \ \ 2]
   by (simp add: add.commute mult.commute)
```

 \mathbf{begin}

```
subgoal for x \tau using bb-real-arith(4)[where g=x \$ 2 and v=x \$ 1] by(simp\ add: add.commute\ mult.commute) by (force\ simp: bb-real-arith)

no-notation constant-acceleration-kinematics-sq-mtx (K)

end
theory cat2rel
imports
../hs-prelims-matrices
.../hs-prelims-matrices
.../hs-prelims-matrices
```

Chapter 4

Hybrid System Verification with relations

```
— We start by deleting some conflicting notation. 

no-notation Archimedean-Field.ceiling (\lceil - \rceil)

and Archimedean-Field.floor-ceiling-class.floor (\lfloor - \rfloor)

and Range-Semiring.antirange-semiring-class.ars-r (r)

and Relation.Domain (r2s)

and VC-KAD.gets (-::= - \lceil 70, 65 \rceil 61)
```

4.1 Verification of regular programs

Below we explore the behavior of the forward box operator from the antidomain kleene algebra with the lifting ($\lceil - \rceil^*$) operator from predicates to relations $\lceil P \rceil = \{(s, s) \mid s. P \mid s\}$ and its dropping counterpart $\lfloor R \rfloor = (\lambda x. x \in Domain R)$.

```
lemma wp\text{-}rel: wp \ R \ [P] = [\lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y] proof—
have [wp \ R \ [P]] = [[\lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y]] by (simp \ add: \ wp\text{-}trafo \ pointfree\text{-}idE) thus wp \ R \ [P] = [\lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y] by (metis \ (no\text{-}types, \ lifting) \ wp\text{-}simp \ d\text{-}p2r \ pointfree\text{-}idE \ prp) qed

lemma p2r\text{-}r2p\text{-}wp: [[wp \ R \ P]] = wp \ R \ P apply (subst \ d\text{-}p2r[symmetric]) using wp\text{-}simp[symmetric, \ of \ R \ P] by blast

Next, we introduce assignments and compute their wp.

abbreviation vec\text{-}upd :: ('a^{'}b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a^{'}b where vec\text{-}upd \ xi \ a \equiv vec\text{-}lambda \ ((vec\text{-}nth \ x)(i := a))

abbreviation assign :: 'b \Rightarrow ('a^{'}b \Rightarrow 'a) \Rightarrow ('a^{'}b) \ rel \ ((2\text{-}::= \text{-}) \ [70, 65] \ 61)
```

```
where (x := e) \equiv \{(s, vec\text{-}upd \ s \ x \ (e \ s)) | \ s. \ True\}
lemma wp-assign [simp]: wp (x := e) [Q] = [\lambda s. \ Q \ (vec\text{-upd} \ s \ x \ (e \ s))]
 \mathbf{by}(auto\ simp:\ rel-antidomain-kleene-algebra.fbox-def\ rel-ad-def\ p2r-def)
lemma wp-assign-var \lceil simp \rceil: | wp (x := e) \lceil Q \rceil | = (\lambda s. \ Q (vec-upd \ s \ x (e \ s)))
 \mathbf{by}(subst\ wp\text{-}assign,\ simp\ add:\ pointfree\text{-}idE)
The wp of the composition was already obtained in KAD. Antidomain_Semiring:
|x \cdot y| z = |x| |y| z.
There is also already an implementation of the conditional operator if p then
x \text{ else } y \text{ fi} = d p \cdot x + ad p \cdot y \text{ and its } wp: | \text{if } p \text{ then } x \text{ else } y \text{ fi} | q = d p \cdot y
|x| q + ad p \cdot |y| q.
Finally, we add a wp-rule for a simple finite iteration.
lemma (in antidomain-kleene-algebra) fbox-starI:
  assumes d p \leq d i and d i \leq |x| i and d i \leq d q
 shows d p \leq |x^*| q
proof-
  have d i \leq |x| (d i)
   using \langle d | i \leq |x| | i \rangle local.fbox-simp by auto
  hence |1| p \leq |x^{\star}| i
   using \langle d | p \leq d \rangle by (metis\ (no-types)\ dual-order.trans)
       fbox-one fbox-simp fbox-star-induct-var)
  thus ?thesis
   using \langle d | i \leq d | q \rangle by (metis (full-types) fbox-mult
       fbox-one fbox-seq-var fbox-simp)
qed
lemma rel-ad-mka-starI:
  \mathbf{assumes}\ P\subseteq I\ \mathbf{and}\ I\subseteq wp\ R\ I\ \mathbf{and}\ I\subseteq Q
 shows P \subseteq wp(R^*) Q
proof-
  have wp R I \subseteq Id
  by (simp add: rel-antidomain-kleene-algebra.a-subid rel-antidomain-kleene-algebra.fbox-def)
  hence P \subseteq Id
   using assms(1,2) by blast
  hence rdom P = P
   by (metis d-p2r p2r-surj)
  also have rdom P \subseteq wp (R^*) Q
  by (metis \langle wp\ R\ I\subseteq Id\rangle assms d-p2r p2r-surj rel-antidomain-kleene-algebra.dka.dom-iso
        rel-antidomain-kleene-algebra.fbox-starI)
  ultimately show ?thesis
   by blast
qed
```

4.2 Verification of hybrid programs

4.2.1 Verification by providing solutions

```
abbreviation guards :: ('a \Rightarrow bool) \Rightarrow (real \Rightarrow 'a) \Rightarrow (real set) \Rightarrow bool (- \triangleright - -
[70, 65] 61)
  where G > x T \equiv \forall r \in T. G(x r)
definition ivp-sols f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp-solsI:
 assumes D x = (f \circ x) on T x t_0 = s t_0 \in T
 shows x \in ivp\text{-}sols f T t_0 s
 using assms unfolding ivp-sols-def by blast
lemma ivp-solsD:
  assumes x \in ivp\text{-}sols f T t_0 s
 shows D x = (f \circ x) on T
    and x t_0 = s and t_0 \in T
 using assms unfolding ivp-sols-def by auto
definition g-orbital f T t_0 G s = \bigcup \{\{x \ t | t. \ t \in T \land G \rhd x \ \{t_0..t\}\}\} | x. \ x \in T
ivp-sols f T t_0 s
lemma g-orbital-eq: g-orbital f T t_0 G s =
 \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0..t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t \in T \land G \triangleright x\}
\{t_0..t\}\}
  unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbitalI:
  assumes D x = (f \circ x) on T x t_0 = s
    and t_0 \in T t \in T and G \rhd x \{t_0..t\}
 shows x \ t \in g-orbital f \ T \ t_0 \ G \ s
 using assms unfolding g-orbital-def ivp-sols-def by blast
lemma g-orbitalD:
 assumes s' \in g-orbital f T t_0 G s
 obtains x and t where x \in ivp\text{-}sols \ f \ T \ t_0 \ s
 and D x = (f \circ x) on T x t_0 = s
 and x t = s' and t_0 \in T t \in T and G \triangleright x \{t_0..t\}
 using assms unfolding g-orbital-def ivp-sols-def by blast
abbreviation g\text{-}evol :: (('a::banach) \Rightarrow 'a) \Rightarrow real \ set \Rightarrow 'a \ pred \Rightarrow 'a \ rel \ ((['a::banach'] \times -] -
& -))
  where [x'=f]T \& G \equiv \{(s,s'), s' \in g\text{-}orbital \ f \ T \ 0 \ G \ s\}
lemmas g-evol-def = g-orbital-eq[where t_0=\theta]
```

```
context local-flow
begin
lemma in-ivp-sols: (\lambda t. \varphi t s) \in ivp-sols f T \theta s
  by(auto intro: ivp-solsI simp: ivp init-time)
definition orbit s = g-orbital f T \theta (\lambda s. True) s
lemma orbit-eq[simp]: orbit s = \{ \varphi \ t \ s | \ t. \ t \in T \}
  unfolding orbit-def g-evol-def
  by(auto intro: usolves-ivp intro!: ivp simp: init-time)
lemma g-orbital-collapses:
  shows g-orbital f \ T \ \theta \ G \ s = \{ \varphi \ t \ s \mid t. \ t \in T \land G \rhd (\lambda r. \ \varphi \ r \ s) \ \{ \theta..t \} \} (is -
= ?gorbit)
proof(rule subset-antisym, simp-all only: subset-eq)
  \{fix s' assume s' \in g-orbital f T \cap G s
    then obtain x and t where x-ivp:D x = (\lambda t. f(x t)) on T
      x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \rhd x \{\theta..t\}
      unfolding g-orbital-eq by auto
    hence obs: \forall \tau \in \{0..t\}. \ x \ \tau = \varphi \ \tau \ s
      using usolves-ivp[OF x-ivp]
      by (meson atLeastAtMost-iff init-time interval mem-is-interval-1-I)
    hence G \triangleright (\lambda r. \varphi r s) \{\theta..t\}
      using guard by simp
    also have \varphi t s = x t
      using usolves-ivp \ x-ivp \ \langle t \in T \rangle by simp
    ultimately have s' \in ?qorbit
      using \langle x | t = s' \rangle \langle t \in T \rangle by auto
  thus \forall s' \in g-orbital f \ T \ \theta \ G \ s. \ s' \in ?gorbit
    by blast
next
  \{ \text{fix } s' \text{ assume } s' \in ?gorbit \}
    then obtain t where G \triangleright (\lambda r. \varphi r s) \{\theta..t\} and t \in T and \varphi t s = s'
      by blast
    hence s' \in g-orbital f T \cap G s
      by(auto intro: g-orbitalI simp: ivp init-time)}
  thus \forall s' \in ?gorbit. \ s' \in g\text{-}orbital \ f \ T \ 0 \ G \ s
    \mathbf{by} blast
qed
lemma g-evol-collapses:
  shows ([x'=f]T \& G) = \{(s, \varphi \ t \ s) \mid t \ s. \ t \in T \land G \rhd (\lambda r. \varphi \ r \ s) \mid \theta...t\}\}
  unfolding g-orbital-collapses by auto
lemma wp-orbit: wp (\{(s,s') \mid s \ s'. \ s' \in orbit \ s\}) \lceil Q \rceil = \lceil \lambda \ s. \ \forall \ t \in T. \ Q \ (\varphi \ t) \rceil
  unfolding orbit-eq wp-rel by auto
```

```
lemma wp-g-orbit: wp ([x'=f]T & G) \lceil Q \rceil = \lceil \lambda \ s. \ \forall \ t \in T. \ (G \rhd (\lambda r. \ \varphi \ r \ s) \ \{\theta..t\}) \longrightarrow Q \ (\varphi \ t \ s) \rceil unfolding g-evol-collapses <math>wp-rel by auto
```

```
lemma (in local-flow) ivp-sols-collapse: ivp-sols f T 0 s = \{(\lambda t. \varphi t s)\} apply(auto simp: ivp-sols-def ivp init-time fun-eq-iff) apply(rule unique-solution, simp-all add: ivp) oops
```

The previous theorem allows us to compute wlps for known systems of ODEs. We can also implement a version of it as an inference rule. A simple computation of a wlp is shown immmediately after.

```
lemma dSolution:
```

```
assumes local-flow f T L \varphi and \forall s. P s \longrightarrow (\forall t \in T. (G \rhd (\lambda r. \varphi rs) \{\theta..t\}) \longrightarrow Q (\varphi ts)) shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \lceil Q \rceil using assms by (subst local-flow.wp-g-orbit, auto)

lemma line-DS: 0 \leq t \Longrightarrow wp \ (\lceil x' = \lambda s. \ c \rceil \{\theta..t\} \& G) \lceil Q \rceil = \lceil \lambda \ x. \ \forall \tau \in \{\theta..t\}. \ (G \rhd (\lambda t. \ x + t *_R c) \{\theta..\tau\}) \longrightarrow Q \ (x + \tau *_R c) \rceil apply (subst local-flow.wp-g-orbit [of \lambda s. \ c - 1/(t+1) \ (\lambda t \ x. \ x + t *_R c) ])
```

4.2.2 Verification with differential invariants

by(auto simp: line-is-local-flow closed-segment-eq-real-ivl)

We derive the domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in verification proofs.

Differential Weakening

```
lemma DW: wp ([x'=f]\{0..t\} & G) \lceil Q \rceil = wp ([x'=f]\{0..t\} & G) \lceil \lambda s. G s \longrightarrow Q s \rceil by (auto intro: g-orbitalD simp: wp-rel)

lemma dWeakening:
assumes \lceil G \rceil \leq \lceil Q \rceil
shows \lceil P \rceil \leq wp ([x'=f]\{0..t\} & G) \lceil Q \rceil
using assms apply(subst wp-rel)
by(auto simp: g-evol-def)
```

Differential Cut

```
lemma wp-q-orbit-IdD:
 assumes wp ([x'=f]T \& G) [C] = Id \text{ and } \forall r \in \{0..t\}. (s, xr) \in ([x'=f]T \& G)
G
 shows \forall r \in \{0..t\}. C(x r)
proof
  fix r assume r \in \{0..t\}
  then have x r \in g-orbital f T \theta G s
    using assms(2) by blast
  also have \forall y. y \in (g\text{-}orbital\ f\ T\ 0\ G\ s) \longrightarrow C\ y
    using assms(1) unfolding wp\text{-}rel by (auto\ simp:\ p2r\text{-}def)
  ultimately show C(x r) by blast
qed
theorem DC:
  assumes interval T and wp ([x'=f]T \& G) [C] = Id
  shows wp([x'=f]T \& G)[Q] = wp([x'=f]T \& (\lambda s. G s \land C s))[Q]
\operatorname{proof}(\operatorname{rule-tac} f = \lambda \ x. \ \operatorname{wp} \ x \ [Q] \ \operatorname{in} \ HOL. \operatorname{arg-cong}, \ \operatorname{rule} \ \operatorname{subset-antisym}, \ \operatorname{safe})
  {fix s and s' assume s' \in g-orbital f T 0 G s
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
       and guard-x:G \triangleright x \{0..t\} and s' = x t and \theta \in T t \in T
       \mathbf{using}\ g\text{-}orbitalD[of\ s'\ f\ T\ 0\ G\ s]\ \mathbf{by}\ (metis\ (\mathit{full-types}))
    from guard-x have \forall r \in \{0..t\}. \forall \tau \in \{0..r\}. G(x \tau)
       by auto
    also have \forall \tau \in \{0..t\}. \tau \in T
         \textbf{by} \ (\textit{meson} \ \lor \textit{0} \ \in \ \textit{T} \lor \ \lor t \ \in \ \textit{T} \lor \ \textit{assms(1)} \ \ \textit{atLeastAtMost-iff interval.interval}
mem-is-interval-1-I)
    ultimately have \forall \tau \in \{0..t\}. x \tau \in g-orbital f T \theta G s
       using q-orbitalI[OF x-ivp \langle \theta \in T \rangle] by blast
    hence \forall \tau \in \{0..t\}. (s, x \tau) \in [x'=f]T \& G
       unfolding wp-rel by(auto simp: p2r-def)
    hence C \triangleright x \{\theta..t\}
       using wp-g-orbit-IdD[OF\ assms(2)] by blast
    hence s' \in g-orbital f T \theta (\lambda s. G s \wedge C s) s
      using g-orbitalI[OF x-ivp \langle 0 \in T \rangle \langle t \in T \rangle] guard-x \langle s' = x t \rangle by fastforce}
  thus \bigwedge s \ s'. \ s' \in g-orbital f \ T \ 0 \ G \ s \Longrightarrow s' \in g-orbital f \ T \ 0 \ (\lambda s. \ G \ s \land C \ s) \ s
next show \bigwedge s \ s'. \ s' \in g-orbital f \ T \ 0 \ (\lambda s. \ G \ s \land C \ s) \ s \Longrightarrow s' \in g-orbital f \ T \ 0
    by (auto simp: q-evol-def)
qed
theorem dCut:
  assumes wp-C:[P] \le wp ([x'=f] \{ \theta ..t \} \& G) [C]
    and wp-Q:[P] \subseteq wp ([x'=f]\{0..t\} \& (\lambda s. G s \land C s)) [Q]
  \mathbf{shows} \ \lceil P \rceil \subseteq \mathit{wp} \ ([x' = \!\! f] \{ \mathit{0}..t \} \ \& \ \mathit{G}) \ \lceil Q \rceil
proof(subst wp-rel, simp add: g-orbital-eq p2r-def, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a
  assume guard-x:(\forall r \in \{0..\tau\}, G(xr)) and 0 \le \tau and \tau \le t
```

```
and x-solves:D x = (\lambda t. f(x t)) on \{0..t\} and P(x \theta)
  hence \forall r \in \{0..\tau\}. \forall \tau \in \{0..r\}. G(x \tau)
    by auto
  hence \forall r \in \{0..\tau\}. x r \in g-orbital f \{0..t\} \ 0 \ G (x \ 0)
    using g-orbital x-solves \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  hence \forall r \in \{\theta ... \tau\}. C(x r)
    using wp-C \langle P(x \theta) \rangle by(subst (asm) wp-rel, auto)
  hence x \tau \in g-orbital f \{0...t\} \theta (\lambda s. G s \wedge G s) (x \theta)
    using g-orbitalI x-solves guard-x \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  from this \langle P(x \theta) \rangle and wp-Q show Q(x \tau)
    by(subst (asm) wp-rel, auto)
\mathbf{qed}
Differential Invariant
```

```
lemma DI-sufficiency:
 assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
 shows wp ([x'=f]T \& G) [Q] \le wp [G] [Q]
 apply(subst wp-rel, subst wp-rel, simp add: p2r-def, clarsimp)
  using assms apply(simp add: g-evol-def ivp-sols-def)
 apply(erule-tac \ x=s \ in \ all E)+
  apply(erule\ exE,\ erule\ impE)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
  shows wp \lceil G \rceil \lceil Q \rceil \le wp (\lceil x' = f \rceil T \& G) \lceil Q \rceil
  unfolding wp-g-orbit apply(subst wp-rel, simp add: p2r-def, clarsimp)
  apply(erule-tac \ x=0 \ in \ ballE)
    apply(simp-all add: ivp)
 oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
  ((-)/is'-diff'-invariant'-of(-)/along(-)[70,65]61)
 where I is-diff-invariant-of f along T \equiv
  (\forall s. \ I \ s \longrightarrow (\forall \ x. \ x \in ivp\text{-sols} \ f \ T \ 0 \ s \longrightarrow (\forall \ t \in T. \ I \ (x \ t))))
\mathbf{lemma}\ invariant\text{-}to\text{-}set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s. \ Is \longrightarrow (g\text{-}orbital \ f \ T \ 0 \ (\lambda s.
True(s) \subseteq \{s, Is\}
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
  apply(drule mp, simp-all)
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
 apply(drule mp, simp-all add: subset-eq)
 apply(erule-tac \ x=xa \ t \ in \ all E)
  \mathbf{by}(drule\ mp,\ auto)
```

lemma dInvariant:

```
assumes I is-diff-invariant-of f along T shows \lceil I \rceil \leq wp (\lceil x' = f \rceil T \& G \rangle \lceil I \rceil using assms unfolding diff-invariant-def by(auto simp: wp-rel g-evol-def ivp-sols-def)

lemma dI:
assumes I is-diff-invariant-of f along \{0..t\}
and \lceil P \rceil \leq \lceil I \rceil and \lceil I \rceil \leq \lceil Q \rceil
shows \lceil P \rceil \leq wp (\lceil x' = f \rceil \rbrace \lbrace 0..t \rbrace \& G \rbrace \lceil Q \rceil using assms(1) apply(rule-tac C = I in dCut) apply(drule-tac G = G in dInvariant)
using assms(2) dual-order.trans apply blast apply(rule d Weakening)
using assms by auto
```

Finally, we obtain some conditions to prove specific instances of differential invariants.

named-theorems diff-invariant-rules compilation of rules for differential invariants.

```
lemma [diff-invariant-rules]:
  \mathbf{fixes}\ \vartheta {::} 'a {::} banach \Rightarrow real
  assumes \forall x. (D \ x = (\lambda \tau. \ f \ (x \ \tau)) \ on \ \{\theta..t\}) \longrightarrow
  (\forall \tau \in \{0..t\}. (D (\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) = ((*_R) \theta) \text{ on } \{0..\tau\}))
  shows (\lambda s. \vartheta s = \nu s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
     and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0...t\} \vartheta(x \theta) = \nu(x \theta)
  hence \forall t \in \{0..\tau\}. D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R \theta) at t within \{0..\tau\}
     using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists t \in \{0..\tau\}. \vartheta(x\tau) - \nu(x\tau) - (\vartheta(x\theta) - \nu(x\theta)) = (\tau - \theta) \cdot \theta
     \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
qed
lemma [diff-invariant-rules]:
  fixes \vartheta::'a::banach \Rightarrow real
  assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \vartheta'(x \tau) \geq \nu'
  (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
  shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
\mathbf{proof}(\mathit{simp}\ \mathit{add}\colon \mathit{diff-invariant-def}\ \mathit{ivp-sols-def},\ \mathit{clarsimp})
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
     and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) \leq \vartheta(x \theta)
  hence primed: \forall r \in \{0..\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x r)))
-\nu'(xr))
  at r within \{0..\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
     using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
```

```
hence \exists r \in \{0..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
      (\lambda \tau. \ \tau *_R (\vartheta' (x \ r) - \nu' (x \ r))) (\tau - \theta)
            \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
       then obtain r where r \in \{\theta..\tau\}
            and \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_R (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
 \theta))
            by force
     also have \dots \ge \theta
            using tHyp(1) x-ivp(2) primed calculation(1) by auto
      ultimately show \nu (x \tau) \leq \vartheta (x \tau)
            by simp
qed
lemma [diff-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \vartheta'(x \tau) \geq \nu'(x \tau) \leq \vartheta'(x \tau)
      (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{\theta..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
      fix x \tau assume tHyp: 0 \le \tau \tau \le t
            and x-ivp: D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) < \vartheta(x \theta)
      hence primed: \forall r \in \{0..\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) has-derivative
(\lambda \tau. \tau *_R (\vartheta'(x r) - \nu'(x r)))) (at r within \{\theta..\tau\}) \wedge \vartheta'(x r) \geq \nu'(x r)
            using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
      hence \exists r \in \{0..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
       (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
            \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
      then obtain r where r \in \{\theta..\tau\} and
            \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_{R} (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
            by force
      also have ... > \theta
        using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
                      calculation(1) \ diff-gt-0-iff-gt \ ge-iff-diff-ge-0 \ less-eq-real-def \ zero-le-scale R-iff)
      ultimately show \nu (x \tau) < \vartheta (x \tau)
            by simp
qed
lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
            and I_2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. I_1 s \wedge I_2 s) is-diff-invariant-of f along \{0..t\}
     using assms unfolding diff-invariant-def by auto
lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
            and I_2 is-diff-invariant-of f along \{0...t\}
```

```
shows (\lambda s.\ I_1\ s\ \lor\ I_2\ s) is-diff-invariant-of f along \{0..t\} using assms unfolding diff-invariant-def by auto end theory cat2rel-examples imports cat2rel
```

4.2.3 Examples

begin

The examples in this subsection show different approaches for the verification of hybrid systems. however, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n) $vec \Rightarrow ('a, 'n)$ vec to model the dynamics of our system. Then we show a partial correctness specification involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.
- 3. We define a local flow (φ_K) and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = {"x","v"} morphisms to-str to-var apply(rule-tac x="x" in exI) by simp

notation to-var (\lceil_V)

lemma number-of-program-vars: CARD(program-vars) = 2 using type-definition.card type-definition-program-vars by fastforce instance program-vars::finite apply(standard, subst bij-betw-finite[of to-str UNIV {"x","v"}]) apply(rule bij-betwI')
```

```
apply (simp add: to-str-inject)
 using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
 by simp
lemma program-vars-univD:(UNIV::program-vars\ set)=\{\restriction_V "x", \restriction_V "v"\}
 apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:x = \upharpoonright_V "x" \lor x = \upharpoonright_V "v"
 using program-vars-univD by auto
abbreviation constant-acceleration-kinematics g s \equiv
 (\chi i. if i=(\upharpoonright_V "x") then s \$ (\upharpoonright_V "v") else g)
notation constant-acceleration-kinematics (K)
lemma cnst-acc-continuous:
 fixes X::(real \hat{p}rogram-vars) set
 shows continuous-on X (K g)
 apply(rule\ continuous-on-vec-lambda)
 unfolding continuous-on-def apply clarsimp
 by(intro tendsto-intros)
lemma picard-lindeloef-cnst-acc:
 fixes g::real assumes 0 \le t and t < 1
 shows picard-lindeloef-closed-ivl (\lambda t. K g) {0..t} 1 0
 unfolding picard-lindeloef-closed-ivl-def apply(simp add: lipschitz-on-def assms,
safe)
 apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
 apply(simp-all add: cnst-acc-continuous continuous-on-snd)
  apply(simp add: dist-vec-def L2-set-def dist-real-def)
  apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
  apply(simp-all add: to-var-inject)
  using assms by linarith
abbreviation constant-acceleration-kinematics-flow g\ t\ s \equiv
 (\chi i. if i=(\upharpoonright_V "x") then g \cdot t \hat{\ } 2/2 + s \$ (\upharpoonright_V "v") \cdot t + s \$ (\upharpoonright_V "x")
       else g \cdot t + s \$ (\upharpoonright_V "v")
notation constant-acceleration-kinematics-flow (\varphi_K)
term D(\lambda t. \varphi_K g t s) = (\lambda t. K g (\varphi_K g t s)) on \{0..t\}
lemma local-flow-cnst-acc:
 assumes 0 \le t and t \le 1
 shows local-flow (K g) \{0..t\} 1 (\varphi_K g)
 unfolding local-flow-def local-flow-axioms-def apply safe
 using assms picard-lindeloef-cnst-acc apply blast
  apply(rule has-vderiv-on-vec-lambda, clarify)
```

```
 \begin{array}{l} \mathbf{apply}(case\text{-}tac\ i = \upharpoonright_V \ ''x'') \\ \mathbf{using}\ program\text{-}vars\text{-}exhaust \\ \mathbf{by}(auto\ intro!:\ poly\text{-}derivatives\ simp:\ to\text{-}var\text{-}inject\ vec\text{-}eq\text{-}iff) \\ \\ \mathbf{lemma}\ single\text{-}evolution\text{-}ball: \\ \mathbf{fixes}\ h\text{::}real\ \mathbf{assumes}\ 0 \leq t\ \mathbf{and}\ t < 1\ \mathbf{and}\ g < 0 \\ \mathbf{shows}\ \lceil \lambda s.\ 0 \leq s\ \$\ (\upharpoonright_V \ ''y'') \wedge s\ \$\ (\upharpoonright_V \ ''y'') = h \wedge s\ \$\ (\upharpoonright_V \ ''v'') = 0 \rceil \\ \leq wp\ ([x'=K\ g]\{\theta..t\}\ \&\ (\lambda\ s.\ s\ \$\ (\upharpoonright_V \ ''y'') \geq 0)) \\ \lceil \lambda s.\ 0 \leq s\ \$\ (\upharpoonright_V \ ''y'') \wedge s\ \$\ (\upharpoonright_V \ ''y'') \leq h \rceil \\ \mathbf{apply}(subst\ local\text{-}flow.wp\text{-}g\text{-}orbit[OF\ local\text{-}flow\text{-}cnst\text{-}acc]) \\ \mathbf{using}\ assms\ \mathbf{by}\ (auto\ simp:\ mult\text{-}nonneg\text{-}nonpos2) \\ (metis\ (full\text{-}types)\ less\text{-}eq\text{-}real\text{-}def\ program\text{-}vars\text{-}exhaust\ split\text{-}mult\text{-}neg\text{-}le) \\ \mathbf{no\text{-}notation}\ to\text{-}var\ (\upharpoonright_V) \\ \mathbf{no\text{-}notation}\ constant\text{-}acceleration\text{-}kinematics\ (K) \\ \mathbf{no\text{-}notation}\ constant\text{-}acceleration\text{-}kinematics\text{-}flow\ } (\varphi_K) \\ \end{array}
```

Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a 3×3 matrix (named K) to denote the linear operator that models the constantly accelerated motion.
- 3. We define a local flow (φ_K) and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

term x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. however, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

lemma exhaust-5: — The analogs for 1, 2 and 3 have already been proven in Analysis.

```
fixes x::5

shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5

proof (induct\ x)

case (of\text{-}int\ z)

then have 0 \le z and z < 5 by simp\text{-}all

then have z=0 \lor z=1 \lor z=2 \lor z=3 \lor z=4 by arith
```

```
then show ?case by auto
lemma UNIV-3:(UNIV::3 \ set) = \{0, 1, 2\}
 apply safe using exhaust-3 three-eq-zero by(blast, auto)
lemma sum-axis-UNIV-3[simp]:(\sum j \in (UNIV::3 \text{ set}). \text{ axis } i \text{ 1 } \text{\$ } j \cdot fj) = (f::3 \Rightarrow i \text{ 1})
real) i
 unfolding axis-def UNIV-3 apply simp
 using exhaust-3 by force
We can rewrite the original constant acceleration kinematics as a linear
operator applied to a 3-dimensional vector. For that we take advantage of
the following fact:
lemma e 1 = (\chi j :: 3. if j = 0 then 0 else if j = 1 then 1 else 0)
 unfolding axis-def by(rule Cart-lambda-cong, simp)
abbreviation constant-acceleration-kinematics-matrix \equiv
 (\chi i::3. if i=0 then e 1 else if i=1 then e 2 else (0::real^3))
abbreviation constant-acceleration-kinematics-matrix-flow t s \equiv
 (\chi i::3. if i=0 then s \$ 2 \cdot t ^2/2 + s \$ 1 \cdot t + s \$ 0
  notation constant-acceleration-kinematics-matrix (A)
notation constant-acceleration-kinematics-matrix-flow (\varphi_A)
With these 2 definitions and the proof that linear systems of ODEs are
Picard-Lindeloef, we can show that they form a pair of vector-field and its
flow.
lemma entries-cnst-acc-matrix: entries A = \{0, 1\}
 apply (simp-all add: axis-def, safe)
 by (rule-tac \ x=1 \ in \ exI, \ simp)+
lemma local-flow-cnst-acc-matrix:
 assumes 0 \le t and t \le 1/9
 shows local-flow ((*v) A) \{\theta..t\} ((real CARD(3))<sup>2</sup> · (\|A\|_{max})) \varphi_A
 unfolding local-flow-def local-flow-axioms-def apply safe
   apply(rule\ picard-lindeloef-linear-system[where\ A=A\ and\ t=t])
 using entries-cnst-acc-matrix assms apply(force, simp, force)
  apply(rule has-vderiv-on-vec-lambda)
  apply(auto intro!: poly-derivatives simp: matrix-vector-mult-def vec-eq-iff)
 using exhaust-3 by force
```

Finally, we compute the wlp of this example and use it to verify the single-evolution ball again.

 $\mathbf{lemma}\ single\text{-}evolution\text{-}ball\text{-}K$:

```
assumes 0 \le t and t < 1/9

shows \lceil \lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2 \rceil

\le wp (\lceil x' = (*v) \ A \rceil \{0..t\} \& (\lambda s. \ s \$ \ 0 \ge 0))

\lceil \lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 \le h \rceil

apply(subst local-flow.wp-g-orbit[of - - 9 \cdot (\|A\|_{max}) \varphi_A])

using local-flow-cnst-acc-matrix and assms apply force

using assms by(auto simp: mult-nonneq-nonpos2)
```

Circular Motion

The characteristics that distinguish this example are:

- 1. We employ an existing finite type of size 2 to model program variables.
- 2. We define a 2×2 matrix (named C) to denote the linear operator that models circular motion.
- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow (φ_C) and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two-eq-zero: (2::2) = 0
by simp
lemma [simp]: i \neq (0::2) \longrightarrow i = 1
using exhaust-2 by fastforce
lemma UNIV-2: (UNIV::2\ set) = \{0,\ 1\}
apply safe using exhaust-2\ two-eq-zero by auto
abbreviation circular-motion-matrix :: real^22
where circular-motion-matrix \equiv (\chi\ i.\ if\ i=0\ then\ - e\ 1\ else\ e\ 0)
notation circular-motion-matrix\ (C)
lemma circle-invariant: shows\ (\lambda s.\ r^2 = (s\ \$\ 0)^2 + (s\ \$\ 1)^2)\ is-diff-invariant-of\ (*v)\ C\ along\ \{0..t\} apply (rule-tac\ diff-invariant-rules,\ clarsimp) apply (frule-tac\ i=0\ in\ has-vderiv-on-vec-nth, drule-tac\ i=1\ in\ has-vderiv-on-vec-nth) apply (rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset) by (auto\ intro!:\ poly-derivatives\ simp:\ matrix-vector-mult-def)
```

lemma circular-motion-invariants:

```
shows [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le
  wp ([x'=(*v) \ C] \{0..t\} \& G)
  \begin{bmatrix} \lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2 \end{bmatrix}
  apply(rule-tac C=\lambda s. \ r^2=(s \$ \theta)^2+(s \$ 1)^2 in dCut)
  apply(rule-tac I = \lambda s. r^2 = (s \$ 0)^2 + (s \$ 1)^2 in dI)
  using circle-invariant apply(blast, force, force)
  \mathbf{by}(rule\ dWeakening,\ auto)
— Proof of the same specification by providing solutions:
lemma entries-circ-matrix:entries C = \{0, -1, 1\}
  apply (simp-all add: axis-def, safe)
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
  \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
abbreviation circular-motion-matrix-flow t s \equiv
  (\chi i::2. if i=0 then s\$0 \cdot cos t - s\$1 \cdot sin t else s\$0 \cdot sin t + s\$1 \cdot cos t)
notation circular-motion-matrix-flow (\varphi_C)
lemma local-flow-circ-mtx:
  assumes 0 \le t and t < 1/4
 shows local-flow ((*v) C) \{\theta..t\} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \varphi_C
  unfolding local-flow-def local-flow-axioms-def apply safe
   apply(rule picard-lindeloef-linear-system)
  {\bf unfolding} \ entries-circ-matrix \ {\bf using} \ assms \ {\bf apply} (simp-all)
  apply(rule has-vderiv-on-vec-lambda)
  apply(force intro!: poly-derivatives simp: matrix-vector-mult-def)
  using exhaust-2 two-eq-zero by (force simp: vec-eq-iff)
lemma circular-motion:
  assumes 0 \le t and t < 1/4
 shows \lceil \lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2 \rceil \le
  wp ([x'=(*v) C] \{0..t\} \& G)
  [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2]
  apply(subst local-flow.wp-g-orbit[OF local-flow-circ-mtx])
  using assms by simp-all
no-notation circular-motion-matrix (C)
no-notation circular-motion-matrix-flow (\varphi_C)
```

Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynam-

ics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb-real-arith]: 0 \le x \Longrightarrow 0 > q \Longrightarrow 2 \cdot q \cdot x = 2 \cdot q \cdot h + v \cdot v \Longrightarrow
(x::real) \leq h
proof-
  assume 0 \le x and 0 > g and 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
  then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot h \wedge 0 > g by auto
  hence *:v \cdot v = 2 \cdot g \cdot (x - h) \wedge 0 > g \wedge v \cdot v \geq 0
    using left-diff-distrib mult.commute by (metis zero-le-square)
  from this have (v \cdot v)/(2 \cdot g) = (x - h) by auto
  also from * have (v \cdot v)/(2 \cdot g) \leq \theta
    using divide-nonneg-neg by fastforce
  ultimately have h - x \ge \theta by linarith
  thus ?thesis by auto
qed
lemma [bb\text{-}real\text{-}arith]:
  assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
    and pos: g \cdot \tau^2 / 2 + v \cdot \tau + (x::real) = 0
  shows 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
and 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
proof-
  from pos have g \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x = 0
    by (metis\ (mono-tags,\ hide-lams)\ Groups.mult-ac(1,3)\ mult-zero-right
         monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + v^2 + 2 \cdot q \cdot h = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(g \cdot \tau + v)^2 + 2 \cdot g \cdot h = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide\text{-}lams)\ Groups.add\text{-}ac(2,3)
         Groups.mult-ac(2, 3) monoid-mult-class.power2-eq-square nat-distrib(2))
  hence 2 \cdot g \cdot h + (-((g \cdot \tau) + v))^2 = 0
    by (metis\ Groups.add-ac(2)\ power2-minus)
  thus 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    \mathbf{by}\ (simp\ add\colon monoid\text{-}mult\text{-}class.power2\text{-}eq\text{-}square)
  from * show 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
qed
lemma [bb-real-arith]:
 assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
shows 2 \cdot g \cdot (g \cdot \tau^2 / 2 + v \cdot \tau + (x::real)) =
  2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
  have ?lhs = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x
    \mathbf{apply}(\mathit{subst}\ \mathit{Rat.sign\text{-}simps}(18)) +
```

```
\mathbf{by}(auto\ simp:\ semiring-normalization-rules(29))
  also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot h + v \cdot v (is ... = ?middle)
   \mathbf{by}(subst\ invar,\ simp)
  finally have ?lhs = ?middle.
  moreover
  {have ?rhs = q \cdot q \cdot (\tau \cdot \tau) + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot h + v \cdot v
     by (simp add: Groups.mult-ac(2,3) semiring-class.distrib-left)
   also have ... = ?middle
     by (simp add: semiring-normalization-rules (29))
   finally have ?rhs = ?middle.}
  ultimately show ?thesis by auto
qed
lemma bouncing-ball:
  assumes 0 \le t and t < 1/9
  shows [\lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \subseteq wp
  ((([x'=\lambda s. \ A * v \ s] \{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0));
  (IF \ (\lambda \ s. \ s \ \$ \ 0 = 0) \ THEN \ (1 ::= (\lambda s. - s \ \$ \ 1)) \ ELSE \ Id \ FI))^*)
  [\lambda s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 \le h]
  apply(rule rel-ad-mka-starI [of - \lceil \lambda s. \ 0 \le s \$ \ (0::3) \land 0 > s \$ 2 \land
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot h + (s \$ 1 \cdot s \$ 1)]])
   apply(simp, simp only: rel-antidomain-kleene-algebra.fbox-seq)
   apply(subst p2r-r2p-wp[symmetric, of (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s.
-s \$ 1) ELSE Id FI)
  apply(subst\ local-flow.wp-g-orbit[of - - 9 \cdot (||A||_{max}) \varphi_A])
  using local-flow-cnst-acc-matrix[OF assms] apply force
  apply(subst wp-trafo)
  {\bf unfolding} \ rel-antidomain-kleene-algebra. cond-def \ rel-antidomain-kleene-algebra. ads-d-def
  by(auto simp: p2r-def rel-ad-def bb-real-arith)
Bouncing Ball with invariants
We prove again the bouncing ball but this time with differential invariants.
```

```
apply(rule-tac \vartheta'=\lambda s. \theta and \nu'=\lambda s. \theta in diff-invariant-rules(3), clarsimp)
 apply(drule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 \mathbf{apply}(\mathit{rule\text{-}tac}\ S{=}\{\theta..t\}\ \mathbf{in}\ \mathit{has\text{-}vderiv\text{-}on\text{-}subset})
  by(auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
lemma energy-conservation-invariant:
  (\lambda s. \ 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0) is-diff-invariant-of (*v) A
along \{0..t\}
  apply(rule diff-invariant-rules, clarify)
 apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
  apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
  apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
  apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
  by(auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
```

lemma gravity-invariant: ($\lambda s. s \ 2 < 0$) is-diff-invariant-of (*v) A along $\{0..t\}$

```
lemma bouncing-ball-invariants:
  [\lambda s. \ 0 \leq s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \subseteq wp
  ((([x'=\lambda s. \ A *v \ s]\{\theta..t\} \& (\lambda \ s. \ s \$ \ \theta \ge \theta));
  (IF (\lambda s. s \$ \theta = \theta) THEN (1 := (\lambda s. - s \$ 1)) ELSE Id FI))*)
  [\lambda s. \ 0 < s \ \ 0 \land s \ \ 0 < h]
  apply(rule-tac I = [\lambda s. \ 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot h +
(s\$1 \cdot s\$1) in rel-ad-mka-starI)
   apply(simp, simp only: rel-antidomain-kleene-algebra.fbox-seq)
  apply(subst p2r-r2p-wp[symmetric, of (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s.
-s \$ 1) ELSE Id FI)
  apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
   apply(rule-tac I=\lambda s. s \$ 2 < 0 \text{ in } dI)
  using gravity-invariant apply blast
    apply(force simp: p2r-def, force simp: p2r-def)
  apply(rule-tac C=\lambda s. 2 · s$2 · s$0 - 2 · s$2 · h - s$1 · s$1 = 0 in dCut)
   apply(rule-tac I=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0 in dI)
  using energy-conservation-invariant apply(blast)
    apply(force simp: p2r-def, force simp: p2r-def)
  apply(rule\ dWeakening,\ subst\ p2r-r2p-wp)
  apply(simp add: rel-antidomain-kleene-algebra.fbox-def)
  unfolding rel-antidomain-kleene-algebra.cond-def p2r-def
  by(auto simp: bb-real-arith rel-ad-def rel-antidomain-kleene-algebra.ads-d-def)
no-notation constant-acceleration-kinematics-matrix (A)
no-notation constant-acceleration-kinematics-matrix-flow (\varphi_A)
end
theory cat2ndfun
 \mathbf{imports}../hs\text{-}prelims\text{-}matrices\ Transformer\text{-}Semantics.Kleisli\text{-}Quantale\ KAD.Modal\text{-}Kleene\text{-}Algebra
begin
```

Chapter 5

Hybrid System Verification with nondeterministic functions

```
— We start by deleting some conflicting notation and introducing some new.

no-notation Archimedean-Field.ceiling ([-])

and Archimedean-Field.floor-ceiling-class.floor ([-])

and Range-Semiring.antirange-semiring-class.ars-r (r)

and Isotone-Transformers.bqtran ([-])

type-synonym 'a pred = 'a ⇒ bool

notation Abs-nd-fun (-• [101] 100) and Rep-nd-fun (-• [101] 100)
```

5.1 Nondeterministic Functions

Our semantics correspond now to nondeterministic functions 'a nd-fun. Below we prove some auxiliary lemmas for them and show that they form an antidomain kleene algebra. The proof just extends the results on the Transformer_Semantics.Kleisli_Quantale theory.

```
declare Abs-nd-fun-inverse [simp]
```

```
— Analog of already existing (f = g) = (\forall x. f x = g x). lemma nd-fun-ext: (\bigwedge x. (f_{\bullet}) x = (g_{\bullet}) x) \Longrightarrow f = g apply(subgoal-tac Rep-nd-fun f = \text{Rep-nd-fun } g) using Rep-nd-fun-inject apply blast by(rule ext, simp)
```

 $\begin{tabular}{ll} \textbf{instantiation} & \textit{nd-fun} :: (type) & \textit{antidomain-kleene-algebra} \\ \textbf{begin} \\ \end{tabular}$

lift-definition antidomain-op-nd-fun :: 'a nd- $fun \Rightarrow 'a nd$ -fun

```
is \lambda f. (\lambda x. if ((f_{\bullet}) x = \{\}) then \{x\} else \{\})^{\bullet}.
lift-definition zero-nd-fun :: 'a nd-fun
 is \zeta^{\bullet}.
lift-definition star-nd-fun :: 'a nd-fun \Rightarrow 'a nd-fun
 is \lambda(f::'a \ nd\text{-}fun). qstar f.
lift-definition plus-nd-fun :: 'a nd-fun \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun
 is \lambda f g.((f_{\bullet}) \sqcup (g_{\bullet}))^{\bullet}.
named-theorems nd-fun-aka antidomain kleene algebra properties for nondeter-
ministic functions.
lemma nd-fun-assoc[nd-fun-aka]: (a::'a nd-fun) + b + c = a + (b + c)
 by(transfer, simp add: ksup-assoc)
lemma nd-fun-comm[nd-fun-aka]: (a::'a nd-fun) + b = b + a
 \mathbf{by}(\mathit{transfer}, \mathit{simp add: ksup-comm})
lemma nd-fun-distr[nd-fun-aka]: ((x::'a nd-fun) + y) \cdot z = x \cdot z + y \cdot z
 and nd-fun-distl[nd-fun-aka]: x \cdot (y + z) = x \cdot y + x \cdot z
 by(transfer, simp add: kcomp-distr, transfer, simp add: kcomp-distl)
lemma nd-fun-zero-sum[nd-fun-aka]: <math>0 + (x::'a \ nd-fun) = x
 and nd-fun-zero-dot[nd-fun-aka]: 0 \cdot x = 0
 by(transfer, simp, transfer, auto)
lemma nd-fun-leq[nd-fun-aka]: ((x::'a nd-fun) <math>\leq y) = (x + y = y)
 and nd-fun-leq-add[nd-fun-aka]: z \cdot x \leq z \cdot (x + y)
  apply(transfer)
 apply(metis (no-types, lifting) less-eq-nd-fun.transfer sup.absorb-iff2 sup-nd-fun.transfer)
 by(transfer, simp add: kcomp-isol)
lemma nd-fun-ad-zero[nd-fun-aka]: ad(x::'a nd-fun) · <math>x = 0
 and nd-fun-ad[nd-fun-aka]: ad(x \cdot y) + ad(x \cdot ad(ady)) = ad(x \cdot ad(ady))
 and nd-fun-ad-one [nd-fun-aka]: ad(adx) + adx = 1
  apply(transfer, rule nd-fun-ext, simp add: kcomp-def)
  apply(transfer, rule nd-fun-ext, simp, simp add: kcomp-def)
 by(transfer, simp, rule nd-fun-ext, simp add: kcomp-def)
lemma nd-star-one[nd-fun-aka]: 1 + (x::'a nd-fun) \cdot x^* \leq x^*
 and nd-star-unfoldl[nd-fun-aka]: z + x \cdot y \leq y \Longrightarrow x^* \cdot z \leq y
 and nd-star-unfoldr[nd-fun-aka]: z + y \cdot x \leq y \Longrightarrow z \cdot x^* \leq y
  apply(transfer, metis Abs-nd-fun-inverse Rep-comp-hom UNIV-I fun-star-unfoldr
     le-sup-iff less-eq-nd-fun.abs-eq mem-Collect-eq one-nd-fun.abs-eq qstar-comm)
  apply(transfer, metis (no-types, lifting) Abs-comp-hom Rep-nd-fun-inverse
     fun-star-inductl less-eq-nd-fun.transfer sup-nd-fun.transfer)
```

```
by(transfer, metis qstar-inductr Rep-comp-hom Rep-nd-fun-inverse less-eq-nd-fun.abs-eq sup-nd-fun.transfer)
```

instance

```
apply intro-classes apply auto
using nd-fun-aka apply simp-all
by(transfer; auto)+
```

end

Now that we know that nondeterministic functions form an Antidomain Kleene Algebra, we give a lifting operation from predicates to 'a nd-fun and prove some useful results for them. Then we add an operation that does the opposite and prove the relationship between both of these.

```
abbreviation p2ndf :: 'a \ pred \Rightarrow 'a \ nd\text{-}fun \ ((1 \lceil - \rceil))
  where [Q] \equiv (\lambda x :: 'a. \{s :: 'a. s = x \land Q s\})^{\bullet}
lemma le\text{-p2ndf-iff}[simp]: \lceil P \rceil \leq \lceil Q \rceil = (\forall s. \ P \ s \longrightarrow Q \ s)
  by(transfer, auto simp: le-fun-def)
lemma p2ndf-le-eta[simp]: \lceil P \rceil \leq \eta^{\bullet}
  by(transfer, simp add: le-fun-def, clarify)
lemma ads-d-p2ndf[simp]: d <math>\lceil P \rceil = \lceil P \rceil
  unfolding ads-d-def antidomain-op-nd-fun-def by(rule nd-fun-ext, auto)
lemma ad-p2ndf[simp]: ad [P] = [\lambda s. \neg P s]
  unfolding antidomain-op-nd-fun-def by(rule nd-fun-ext, auto)
abbreviation ndf2p :: 'a \ nd\text{-}fun \Rightarrow 'a \Rightarrow bool \ ((1 | -|))
  where |f| \equiv (\lambda x. \ x \in Domain \ (\mathcal{R} \ (f_{\bullet})))
lemma p2ndf-ndf2p-id: F \leq \eta^{\bullet} \Longrightarrow \lceil |F| \rceil = F
  unfolding f2r-def apply(rule nd-fun-ext)
  \mathbf{apply}(subgoal\text{-}tac \ \forall \ x.\ (F_{\bullet})\ x \subseteq \{x\},\ simp)
  \mathbf{by}(\mathit{blast}, \mathit{simp} \; \mathit{add} \colon \mathit{le-fun-def} \; \mathit{less-eq-nd-fun.rep-eq})
```

5.2 Verification of regular programs

As expected, the weakest precondition is just the forward box operator from the KAD. Below we explore its behavior with the previously defined lifting $(\lceil - \rceil^*)$ and dropping $(\lfloor - \rfloor^*)$ operators

```
abbreviation wp \ f \equiv fbox \ (f::'a \ nd\text{-}fun)

lemma wp\text{-}eta[simp]: \ wp \ (\eta^{\bullet}) \ \lceil P \rceil = \lceil P \rceil

apply(simp \ add: \ fbox\text{-}def, \ transfer, \ simp)

by(rule \ nd\text{-}fun\text{-}ext, \ auto \ simp: \ kcomp\text{-}def)
```

```
lemma wp-nd-fun: wp (F^{\bullet}) [P] = [\lambda \ x. \ \forall \ y. \ y \in (F \ x) \longrightarrow P \ y]
  apply(simp add: fbox-def, transfer, simp)
  by(rule nd-fun-ext, auto simp: kcomp-def)
lemma wp-nd-fun2: wp F[P] = [\lambda x. \forall y. y \in ((F_{\bullet}) x) \longrightarrow Py]
  apply(simp add: fbox-def antidomain-op-nd-fun-def)
 by(rule nd-fun-ext, auto simp: Rep-comp-hom kcomp-prop)
lemma wp-nd-fun-etaD: wp (F^{\bullet}) [P] = \eta^{\bullet} \Longrightarrow (\forall y. y \in (Fx) \longrightarrow Py)
proof
  fix y assume wp (F^{\bullet}) [P] = (\eta^{\bullet})
  from this have \eta^{\bullet} = [\lambda s. \ \forall y. \ s2p \ (F \ s) \ y \longrightarrow P \ y]
   \mathbf{by}(subst\ wp\text{-}nd\text{-}fun[THEN\ sym],\ simp)
  hence \bigwedge x. \{x\} = \{s. \ s = x \land (\forall y. \ s2p \ (F \ s) \ y \longrightarrow P \ y)\}
   apply(subst (asm) Abs-nd-fun-inject, simp-all)
   by (drule-tac \ x=x \ in \ fun-cong, \ simp)
  then show s2p (F x) y \longrightarrow P y by auto
qed
lemma p2ndf-ndf2p-wp: \lceil |wp R P| \rceil = wp R P
  apply(rule p2ndf-ndf2p-id)
 by (simp add: a-subid fbox-def one-nd-fun.transfer)
lemma ndf2p\text{-}wpD: |wp F [Q]| s = (\forall s'. s' \in (F_{\bullet}) s \longrightarrow Q s')
  apply(subgoal-tac\ F = (F_{\bullet})^{\bullet})
  apply(rule\ ssubst[of\ F\ (F_{\bullet})^{\bullet}],\ simp)
  apply(subst wp-nd-fun)
  by(simp-all add: f2r-def)
We can verify that our introduction of wp coincides with another definition
of the forward box operator fb_{\mathcal{F}} = \partial_F \circ bd_{\mathcal{F}} \circ op_K with the following
characterization lemmas.
lemma ffb-is-wp: fb_{\mathcal{F}}(F_{\bullet})\{x.\ P\ x\} = \{s.\ |wp\ F\ [P]|\ s\}
  unfolding ffb-def unfolding map-dual-def klift-def kop-def fbox-def
  unfolding r2f-def f2r-def apply clarsimp
  unfolding antidomain-op-nd-fun-def unfolding dual-set-def
  unfolding times-nd-fun-def kcomp-def by force
lemma wp-is-ffb: wp FP = (\lambda x. \{x\} \cap fb_{\mathcal{F}} (F_{\bullet}) \{s. |P| s\})^{\bullet}
  apply(rule nd-fun-ext, simp)
  unfolding ffb-def unfolding map-dual-def klift-def kop-def fbox-def
  unfolding r2f-def f2r-def apply clarsimp
  unfolding antidomain-op-nd-fun-def unfolding dual-set-def
  unfolding times-nd-fun-def apply auto
  unfolding kcomp-prop by auto
Next, we introduce assignments and compute their wp.
abbreviation vec\text{-}upd :: ('a^*b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a^*b
```

```
where vec-upd x i a \equiv vec-lambda ((vec-nth x)(i := a))
abbreviation assign :: 'b \Rightarrow ('a^'b \Rightarrow 'a) \Rightarrow ('a^'b) nd-fun ((2- ::= -) [70, 65]
 where (x := e) \equiv (\lambda s. \{vec\text{-}upd\ s\ x\ (e\ s)\})^{\bullet}
lemma wp-assign[simp]: wp (x := e) [Q] = [\lambda s. \ Q \ (vec\text{-upd} \ s \ x \ (e \ s))]
 by(subst wp-nd-fun, rule nd-fun-ext, simp)
The wp of the composition was already obtained in KAD. Antidomain_Semiring:
|x \cdot y| z = |x| |y| z.
We also have an implementation of the conditional operator and its wp.
definition (in antidomain-kleene-algebra) cond :: 'a \Rightarrow 'a \Rightarrow 'a \Rightarrow 'a
 (if - then - else - fi [64,64,64] 63) where if p then x else y fi = d p · x + ad p
· y
abbreviation cond-sugar :: 'a pred \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun
  (IF - THEN - ELSE - FI [64,64,64] 63) where IF P THEN X ELSE Y FI \equiv
cond [P] X Y
lemma wp-if-then-else:
 assumes [\lambda s. P s \wedge T s] < wp X [Q]
   and [\lambda s. P s \land \neg T s] < wp Y [Q]
 \mathbf{shows} \ \lceil P \rceil \leq \mathit{wp} \ (\mathit{IF} \ \mathit{T} \ \mathit{THEN} \ \mathit{X} \ \mathit{ELSE} \ \mathit{Y} \ \mathit{FI}) \ \lceil \mathit{Q} \rceil
  using assms apply(subst wp-nd-fun2)
 apply(subst (asm) wp-nd-fun2)+
  unfolding cond-def apply(clarsimp, transfer)
  \mathbf{by}(auto\ simp:\ kcomp-prop)
Finally we also deal with finite iteration.
lemma (in antidomain-kleene-algebra) fbox-starI:
 assumes d p \leq d i and d i \leq |x| i and d i \leq d q
 shows d p \leq |x^{\star}| q
 by (meson assms local.dual-order.trans local.fbox-iso local.fbox-star-induct-var)
lemma ads-d-mono: x \le y \Longrightarrow d \ x \le d \ y
 by (metis ads-d-def fbox-antitone-var fbox-dom)
lemma nd-fun-top-ads-d:(x::'a <math>nd-fun) < 1 \implies d x = x
 apply(simp add: ads-d-def, transfer, simp)
 apply(rule nd-fun-ext, simp)
 apply(subst (asm) le-fun-def)
 by auto
lemma wp-starI:
  assumes P \leq I and I \leq wp \ F \ I and I \leq Q
 shows P \leq wp \ (qstar \ F) \ Q
proof-
```

```
have P \leq 1 using assms(1,2) by (metis\ a\text{-subid\ basic-trans-rules}(23)\ fbox-def) hence d\ P = P using nd\text{-}fun\text{-}top\text{-}ads\text{-}d by blast have \bigwedge\ x\ y.\ d\ (wp\ x\ y) = wp\ x\ y by (metis\ ds.ddual.mult\text{-}oner\ fbox\text{-}mult\ fbox\text{-}one) hence d\ P \leq d\ I \wedge d\ I \leq wp\ F\ I \wedge d\ I \leq d\ Q using assms by (metis\ (no\text{-}types)\ ads\text{-}d\text{-}mono\ assms) hence d\ P \leq wp\ (F^*)\ Q by (simp\ add:\ fbox\text{-}starI[of\ -\ I]) thus P \leq wp\ (qstar\ F)\ Q using (d\ P = P) by (transfer,\ simp) qed
```

5.3 Verification of hybrid programs

5.3.1 Verification by providing solutions

```
[70, 65] 61)
 where G \triangleright x \ T \equiv \forall \ r \in T. \ G \ (x \ r)
definition ivp-sols f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp-solsI:
 assumes D x = (f \circ x) on T x t_0 = s t_0 \in T
 shows x \in ivp\text{-}sols f T t_0 s
 using assms unfolding ivp-sols-def by blast
lemma ivp-solsD:
 assumes x \in ivp\text{-}sols f T t_0 s
 shows D x = (f \circ x) on T
   and x t_0 = s and t_0 \in T
 using assms unfolding ivp-sols-def by auto
definition g-orbital f T t_0 G s = \bigcup \{\{x \ t | t. \ t \in T \land G \rhd x \ \{t_0..t\}\}\} | x. \ x \in T
ivp-sols f T t_0 s
lemma g-orbital-eq: g-orbital f T t_0 G s =
 \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0..t\}\}
 unfolding q-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t \in T \land G \rhd x\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbitalI:
 assumes D x = (f \circ x) on T x t_0 = s
   and t_0 \in T t \in T and G \triangleright x \{t_0..t\}
 shows x \ t \in g-orbital f \ T \ t_0 \ G \ s
```

using assms unfolding g-orbital-def ivp-sols-def by blast **lemma** *q-orbitalD*: assumes $s' \in g$ -orbital $f T t_0 G s$ obtains x and t where $x \in ivp\text{-}sols f T t_0 s$ and $D x = (f \circ x)$ on $T x t_0 = s$ and x t = s' and $t_0 \in T t \in T$ and $G \triangleright x \{t_0..t\}$ using assms unfolding g-orbital-def ivp-sols-def by blast **abbreviation** $g\text{-}evol ::(('a::banach) \Rightarrow 'a) \Rightarrow real set \Rightarrow 'a pred \Rightarrow 'a nd\text{-}fun ((1[x'=-]-$ & -)) where $[x'=f]T \& G \equiv (\lambda \ s. \ g\text{-}orbital \ f \ T \ 0 \ G \ s)^{\bullet}$ lemmas g-evol-def = g-orbital-eq[where $t_0 = \theta]$ context local-flow begin lemma in-ivp-sols: $(\lambda t. \varphi t s) \in ivp$ -sols $f T \theta s$ **by**(auto intro: ivp-solsI simp: ivp init-time) **definition** orbit s = g-orbital $f T \theta (\lambda s. True) s$ **lemma** orbit-eq[simp]: orbit $s = \{ \varphi \ t \ s | \ t . \ t \in T \}$ unfolding orbit-def g-evol-def **by**(auto intro: usolves-ivp intro!: ivp simp: init-time) lemma g-evol-collapses: shows $([x'=f]T \& G) = (\lambda s. \{\varphi \ t \ s | \ t. \ t \in T \land G \rhd (\lambda r. \ \varphi \ r \ s) \{0..t\}\})^{\bullet}$ **proof**(rule nd-fun-ext, rule subset-antisym, simp-all add: subset-eq) $\mathbf{fix} \ s$ let $?P \ s \ s' = \exists \ t. \ s' = \varphi \ t \ s \land s2p \ T \ t \land (\forall \ r \in \{0..t\}. \ G \ (\varphi \ r \ s))$ $\{ \text{fix } s' \text{ assume } s' \in g\text{-}orbital \ f \ T \ \theta \ G \ s \}$ then obtain x and t where x-ivp:D $x = (\lambda t. f(x t))$ on T $x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \triangleright x \{\theta..t\}$ **unfolding** g-orbital-eq by auto hence $obs: \forall \tau \in \{0..t\}. \ x \ \tau = \varphi \ \tau \ s$ **using** usolves-ivp[OF x-ivp] by (meson atLeastAtMost-iff init-time interval mem-is-interval-1-I) hence $G \triangleright (\lambda r. \varphi r s) \{\theta..t\}$ using guard by simp also have φ t s = x tusing $usolves-ivp \ x-ivp \ \langle t \in T \rangle$ by simpultimately have $\exists t. \ s' = \varphi \ t \ s \land s2p \ T \ t \land (\forall r \in \{0..t\}. \ G \ (\varphi \ r \ s))$ using $\langle x | t = s' \rangle \langle t \in T \rangle$ by autothus $\forall s' \in g$ -orbital $f \ T \ 0 \ G \ s$. $?P \ s \ s'$ **by** blast

{fix s' **assume** $\exists t. s' = \varphi t s \land s2p T t \land (\forall r \in \{0..t\}. G (\varphi r s))$

then obtain t where $G \triangleright (\lambda r. \varphi r s) \{\theta..t\}$ and $t \in T$ and $\varphi t s = s'$

```
by blast
   hence s' \in g-orbital f T \cap G s
      by(auto intro: g-orbitalI simp: ivp init-time)}
  thus \forall s'. ?P \ s \ s' \longrightarrow s' \in (g\text{-}orbital \ f \ T \ 0 \ G \ s)
   by blast
qed
lemma wp-orbit: wp ((\lambda \ s. \ orbit \ s)^{\bullet}) \ [Q] = [\lambda \ s. \ \forall \ t \in T. \ Q \ (\varphi \ t \ s)]
  unfolding orbit-eq wp-nd-fun apply(rule nd-fun-ext) by auto
lemma wp-g-orbit: wp ([x'=f]T \& G) [Q] = [\lambda \ s. \ \forall \ t \in T. \ (G \rhd (\lambda r. \varphi \ r \ s))]
\{0..t\}) \longrightarrow Q (\varphi t s)
  unfolding g-evol-collapses wp-nd-fun apply(rule nd-fun-ext) by auto
end
lemma (in local-flow) ivp-sols-collapse: ivp-sols f T \theta s = \{(\lambda t. \varphi t s)\}
  apply(auto simp: ivp-sols-def ivp init-time fun-eq-iff)
 apply(rule unique-solution, simp-all add: ivp)
  oops
```

The previous lemma allows us to compute wlps for known systems of ODEs. We can also implement a version of it as an inference rule. A simple computation of a wlp is shown immmediately after.

```
\mathbf{lemma}\ dSolution:
```

```
assumes local-flow f T L \varphi and \forall s. P s \longrightarrow (\forall t \in T. (G \rhd (\lambda r. \varphi rs) \{\theta..t\}) \longrightarrow Q (\varphi ts)) shows \lceil P \rceil \leq wp \ ([x'=f]T \& G) \lceil Q \rceil using assms by(subst local-flow.wp-g-orbit, auto)

lemma line-DS: 0 \leq t \Longrightarrow wp \ ([x'=\lambda s. \ c]\{\theta..t\} \& G) \lceil Q \rceil = [\lambda \ x. \ \forall \ \tau \in \{\theta..t\}. \ (G \rhd (\lambda r. \ x + r *_R c) \{\theta..\tau\}) \longrightarrow Q \ (x + \tau *_R c) \rceil apply(subst local-flow.wp-g-orbit[of \lambda s. \ c - 1/(t+1) \ (\lambda t \ x. \ x + t *_R c)]) by(auto simp: line-is-local-flow closed-segment-eq-real-ivl)
```

5.3.2 Verification with differential invariants

We derive the domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in verification proofs.

Differential Weakening

```
lemma DW: wp ([x'=f]\{0..t\} & G) \lceil Q \rceil = wp ([x'=f]\{0..t\} & G) \lceil \lambda s. G s \longrightarrow Q s \rceil apply(rule nd-fun-ext)
```

```
by (auto intro: g-orbitalD simp: wp-nd-fun)
lemma dWeakening:
  assumes \lceil G \rceil \leq \lceil Q \rceil
  shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil \{ \theta ...t \} \& G) \lceil Q \rceil
  using assms apply(subst wp-nd-fun)
  \mathbf{by}(auto\ simp:\ g\text{-}evol\text{-}def)
Differential Cut
lemma wp-g-orbit-etaD:
  assumes wp ([x'=f]T \& G) [C] = \eta^{\bullet} \text{ and } \forall r \in \{0..t\}. \ x r \in g\text{-}orbital f T 0 G
  shows \forall r \in \{\theta ...t\}. C(x r)
proof
  fix r assume r \in \{0..t\}
  then have x r \in g-orbital f T \theta G s
    using assms(2) by blast
  also have \forall y. y \in (g\text{-}orbital\ f\ T\ 0\ G\ s) \longrightarrow C\ y
    using assms(1) wp-nd-fun-etaD by fastforce
  ultimately show C(x r) by blast
qed
lemma DC:
  assumes interval T and wp ([x'=f]T \& G) [C] = \eta^{\bullet}
  shows wp ([x'=f]T \& G) [Q] = wp ([x'=f]T \& (\lambda s. G s \land C s)) [Q]
\mathbf{proof}(\mathit{rule-tac}\,f = \lambda \; x. \; \mathit{wp} \; x \; \lceil Q \rceil \; \mathbf{in} \; \mathit{HOL.arg-cong}, \; \mathit{rule} \; \mathit{nd-fun-ext}, \; \mathit{rule} \; \mathit{subset-antisym},
simp-all)
  \mathbf{fix} \ s
  \{fix s' assume s' \in g-orbital f T \in G 
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
      and guard-x: G \triangleright x \{0..t\} and s' = x t and \theta \in T t \in T
      using g-orbitalD[of s' f T 0 G s] by (metis (full-types))
    from guard-x have \forall r \in \{0..t\}. \forall \tau \in \{0..r\}. G(x \tau)
      by auto
    also have \forall \tau \in \{0..t\}. \tau \in T
        by (meson \ (0 \in T) \ (t \in T) \ assms(1) \ atLeastAtMost-iff interval.interval
mem-is-interval-1-I)
    ultimately have \forall \tau \in \{0..t\}. x \tau \in g-orbital f T \theta G s
      using q-orbitalI[OF x-ivp \langle \theta \in T \rangle] by blast
    hence C \triangleright x \{0..t\}
      using wp-g-orbit-etaD assms(2) by blast
    hence s' \in g-orbital f T \theta (\lambda s. G s \wedge C s) s
      using g-orbital [OF x-ivp \langle 0 \in T \rangle \langle t \in T \rangle] guard-x \langle s' = x t \rangle by fastforce
  thus g-orbital f T \theta G s \subseteq g-orbital f T \theta (\lambda s. G s \wedge C s) s
    by blast
next show \bigwedge s. g-orbital f \ T \ \theta \ (\lambda s. \ G \ s \land C \ s) \ s \subseteq g-orbital f \ T \ \theta \ G \ s
    by (auto simp: g-evol-def)
qed
```

```
lemma dCut:
  assumes wp-C:[P] \le wp ([x'=f]\{0..t\} \& G) [C]
    and wp-Q:[P] \le wp ([x'=f]\{0..t\} \& (\lambda s. G s \land C s)) [Q]
  shows \lceil P \rceil \leq wp \ ([x'=f] \{ \theta ..t \} \& G) \ \lceil Q \rceil
proof(simp add: wp-nd-fun q-orbital-eq, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a assume P(x \theta) and \theta \leq \tau and \tau \leq t
    and x-solves:D x = (\lambda t. f(x t)) on \{0...t\} and guard-x:(\forall r \in \{0...\tau\}). G (x \in \{0...\tau\})
r))
  hence \forall r \in \{0..\tau\}. \forall \tau \in \{0..r\}. G(x \tau)
    by auto
  hence \forall r \in \{0..\tau\}. x r \in g-orbital f \{0..t\} \ \theta \ G \ (x \ \theta)
    using g-orbital x-solves \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle closed-segment-eq-real-iv by fastforce
  hence \forall r \in \{0..\tau\}. C(x r)
    using wp-C \langle P (x \theta) \rangle by(subst (asm) wp-nd-fun, auto)
  hence x \tau \in g-orbital f \{0..t\} \theta (\lambda s. G s \wedge C s) (x \theta)
    using g-orbital x-solves guard-x \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  from this \langle P(x \theta) \rangle and wp-Q show Q(x \tau)
    by(subst (asm) wp-nd-fun, auto simp: closed-segment-eq-real-ivl)
qed
Differential Invariant
lemma DI-sufficiency:
  assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
  shows wp ([x'=f]T \& G) [Q] \le wp [G] [Q]
  using assms apply(subst wp-nd-fun, subst wp-nd-fun, clarsimp)
  apply(rename-tac\ s,\ erule-tac\ x=s\ in\ all E,\ erule\ impE)
  apply(simp add: g-evol-def ivp-sols-def)
  apply(erule-tac \ x=s \ in \ all E, \ clarify)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
  shows wp \lceil G \rceil \lceil Q \rceil \le wp ([x'=f]T \& G) \lceil Q \rceil
  unfolding wp-g-orbit apply(subst wp-nd-fun, clarsimp, safe)
   apply(erule-tac \ x=0 \ in \ ballE)
    apply(simp \ add: ivp, simp)
  oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
  ((-)/is'-diff'-invariant'-of(-)/along(-)[70,65]61)
  where I is-diff-invariant-of f along T \equiv
  (\forall\, s.\ I\ s \longrightarrow (\forall\ x.\ x \in \mathit{ivp\text{-}sols}\ f\ T\ 0\ s \longrightarrow (\forall\ t \in T.\ I\ (x\ t))))
lemma invariant-to-set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s.\ Is \longrightarrow (g\text{-}orbital\ f\ T\ 0\ (\lambda s.
True(s) \subseteq \{s. \ I \ s\}
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
```

 $apply(erule-tac \ x=xa \ 0 \ in \ all E)$ $apply(drule \ mp, \ simp-all)$

```
apply(erule-tac \ x=xa \ \theta \ in \ all E)
  \mathbf{apply}(\mathit{drule}\ \mathit{mp},\ \mathit{simp-all}\ \mathit{add}\colon \mathit{subset-eq})
  apply(erule-tac \ x=xa \ t \ in \ all E)
  \mathbf{by}(drule\ mp,\ auto)
lemma dInvariant:
  assumes I is-diff-invariant-of f along T
  shows [I] \leq wp ([x'=f]T \& G) [I]
  \mathbf{using} \ assms \ \mathbf{unfolding} \ diff\text{-}invariant\text{-}def \ \mathbf{apply}(subst \ wp\text{-}nd\text{-}fun)
  apply(subst\ le-p2ndf-iff,\ clarify)
  apply(erule-tac \ x=s \ in \ all E)
  unfolding g-orbital-def by auto
lemma dI:
  assumes I is-diff-invariant-of f along \{0..t\}
    and \lceil P \rceil \leq \lceil I \rceil and \lceil I \rceil \leq \lceil Q \rceil
  shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil \mid \{0..t\} \& G) \ \lceil Q \rceil
  using assms(1) apply(rule-tac\ C=I\ in\ dCut)
   apply(drule-tac\ G=G\ in\ dInvariant)
  using assms(2) dual-order.trans apply blast
  apply(rule dWeakening)
  using assms by auto
Finally, we obtain some conditions to prove specific instances of differential
invariants.
named-theorems diff-invariant-rules compilation of rules for differential invari-
ants.
lemma [diff-invariant-rules]:
  fixes \vartheta::'a::banach \Rightarrow real
  assumes \forall x. (D \ x = (\lambda \tau. f \ (x \ \tau)) \ on \ \{0..t\}) \longrightarrow
  (\forall \tau \in \{0..t\}. (D (\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) = ((*_R) \vartheta) on \{0..\tau\}))
  shows (\lambda s. \ \theta \ s = \nu \ s) is-diff-invariant-of f along \{\theta...t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \vartheta(x \theta) = \nu(x \theta)
 hence \forall t \in \{0..\tau\}. D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R \theta) at t within \{0..\tau\}
    using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists t \in \{0..\tau\}. \vartheta(x\tau) - \nu(x\tau) - (\vartheta(x\theta) - \nu(x\theta)) = (\tau - \theta) \cdot \theta
    \mathbf{by}(\mathit{rule-tac\ mvt-very-simple})\ (\mathit{auto\ simp}:\ \mathit{tHyp})
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
qed
lemma [diff-invariant-rules]:
  fixes \vartheta::'a::banach \Rightarrow real
  assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \vartheta'(x \tau) \geq \nu'
```

```
(x \ \tau) \land
  (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
  shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 < \tau \tau < t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0...t\} \nu(x \theta) < \theta(x \theta)
  hence primed: \forall r \in \{0..\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x \tau)))
-\nu'(xr))
  at r within \{0..\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
    using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists r \in \{\theta..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
  then obtain r where r \in \{0..\tau\}
    and \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_R (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
\theta))
    by force
  also have \dots \geq \theta
    using tHyp(1) x-ivp(2) primed calculation(1) by auto
  ultimately show \nu (x \tau) \leq \vartheta (x \tau)
    by simp
qed
lemma [diff-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \vartheta'(x \tau) \geq \nu'(x \tau))
\tau) \wedge
  (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) = (\lambda r. \vartheta'(x r) - \nu'(x r)) \text{ on } \{0..\tau\}))
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) < \vartheta(x \theta)
  hence primed: \forall r \in \{0..\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) has-derivative
(\lambda \tau. \tau *_R (\vartheta'(x r) - \nu'(x r)))) (at r within \{\theta..\tau\}) \wedge \vartheta'(x r) \geq \nu'(x r)
    using assms by (auto simp: has-vderiv-on-def has-vector-derivative-def)
  hence \exists r \in \{0..\tau\}. (\vartheta(x\tau) - \nu(x\tau)) - (\vartheta(x\theta) - \nu(x\theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    \mathbf{by}(rule\text{-}tac\ mvt\text{-}very\text{-}simple)\ (auto\ simp:\ tHyp)
  then obtain r where r \in \{\theta..\tau\} and
    \vartheta\left(x\;\tau\right)-\nu\left(x\;\tau\right)=\left(\tau\;-\;\theta\right)\ast_{R}^{\cdot}\left(\vartheta'\left(x\;r\right)\;-\;\nu'\left(x\;r\right)\right)+\left(\vartheta\;\left(x\;\theta\right)\;-\;\nu\;\left(x\;\theta\right)\right)
    by force
  also have \dots > \theta
   using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
        calculation(1) diff-qt-0-iff-qt qe-iff-diff-qe-0 less-eq-real-def zero-le-scaleR-iff)
  ultimately show \nu (x \tau) < \vartheta (x \tau)
    by simp
ged
```

```
lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
and I_2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s.\ I_1\ s \land I_2\ s) is-diff-invariant-of f along \{0..t\}
using assms unfolding diff-invariant-def by auto

lemma [diff-invariant-rules]:
assumes I_1 is-diff-invariant-of f along \{0..t\}
and I_2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s.\ I_1\ s \lor I_2\ s) is-diff-invariant-of f along \{0..t\}
using assms unfolding diff-invariant-def by auto

end
theory cat2ndfun-examples
imports cat2ndfun
```

5.3.3 Examples

The examples in this subsection show different approaches for the verification of hybrid systems. however, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n) $vec \Rightarrow ('a, 'n)$ vec to model the dynamics of our system. Then we show a partial correctness specification involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.
- 3. We define a local flow (φ_K) and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = \{''x'', ''v''\}
morphisms to-str to-var
apply(rule-tac x=''x'' in exI)
```

```
by simp
notation to-var (\upharpoonright_V)
lemma number-of-program-vars: CARD(program-vars) = 2
 using type-definition.card type-definition-program-vars by fastforce
instance program-vars::finite
  \mathbf{apply}(\mathit{standard}, \, \mathit{subst} \, \, \mathit{bij-betw-finite}[\mathit{of} \, \mathit{to-str} \, \, \mathit{UNIV} \, \, \{ ''x'', ''v'' \}])
  apply(rule bij-betwI')
    apply (simp add: to-str-inject)
  using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
  by simp
\mathbf{lemma}\ program\text{-}vars\text{-}univD\text{:}(\textit{UNIV}\text{::}program\text{-}vars\ set}) = \{\restriction_{V} \ ''x'', \restriction_{V} \ ''v''\}
  apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:x = \upharpoonright_V "x" \lor x = \upharpoonright_V "v"
  using program-vars-univD by auto
abbreviation constant-acceleration-kinematics g s \equiv
  (\chi i. if i=()_V "x") then s \$ ()_V "v") else g)
notation constant-acceleration-kinematics (K)
lemma cnst-acc-continuous:
  fixes X::(real \hat{p}rogram-vars) set
  shows continuous-on X (K q)
  apply(rule\ continuous-on-vec-lambda)
  unfolding continuous-on-def apply clarsimp
  \mathbf{by}(intro\ tendsto-intros)
lemma picard-lindeloef-cnst-acc:
  fixes g::real assumes 0 \le t and t < 1
 shows picard-lindeloef-closed-ivl (\lambda t. K g) {0..t} 1 0
 unfolding picard-lindeloef-closed-ivl-def apply(simp add: lipschitz-on-def assms,
safe)
  apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
  apply(simp-all add: cnst-acc-continuous continuous-on-snd)
  apply(simp add: dist-vec-def L2-set-def dist-real-def)
  apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
  apply(simp-all add: to-var-inject)
  using assms by linarith
\textbf{abbreviation} \ \textit{constant-acceleration-kinematics-flow} \ \textit{g} \ t \ s \equiv
  (\chi i. if i = (\upharpoonright_V "x") then g \cdot t \hat{} 2/2 + s \$ (\upharpoonright_V "v") \cdot t + s \$ (\upharpoonright_V "x")
        else g \cdot t + s \$ (\upharpoonright_V "v")
```

```
notation constant-acceleration-kinematics-flow (\varphi_K)
term D(\lambda t. \varphi_K g t s) = (\lambda t. K g (\varphi_K g t s)) on \{0..t\}
lemma local-flow-cnst-acc:
  assumes 0 \le t and t \le 1
  shows local-flow (K g) \{0..t\} 1 (\varphi_K g)
  unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-cnst-acc apply blast
   apply(rule has-vderiv-on-vec-lambda, clarify)
   apply(case-tac\ i = \upharpoonright_V "x")
  using program-vars-exhaust
  by(auto intro!: poly-derivatives simp: to-var-inject vec-eq-iff)
\mathbf{lemma}\ single\text{-}evolution\text{-}ball:
  fixes h::real assumes 0 \le t and t < 1 and g < 0
 shows \lceil \lambda s. \ 0 \le s \$ (\upharpoonright_V "y") \land s \$ (\upharpoonright_V "y") = h \land s \$ (\upharpoonright_V "v") = 0 \rceil

\le wp ([x'=K g] \{0..t\} \& (\lambda s. s \$ (\upharpoonright_V "y") \ge 0))

\lceil \lambda s. \ 0 \le s \$ (\upharpoonright_V "y") \land s \$ (\upharpoonright_V "y") \le h \rceil
  apply(subst local-flow.wp-g-orbit[OF local-flow-cnst-acc])
  using assms by(auto simp: mult-nonpos-nonneg)
    (metis (full-types) less-eq-real-def program-vars-exhaust split-mult-neq-le)
no-notation to-var (\upharpoonright_V)
no-notation constant-acceleration-kinematics (K)
no-notation constant-acceleration-kinematics-flow (\varphi_K)
```

Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a 3×3 matrix (named K) to denote the linear operator that models the constantly accelerated motion.
- 3. We define a local flow (φ_K) and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

term x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. however, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

```
lemma exhaust-5: — The analogs for 1,2 and 3 have already been proven in Analysis.
```

```
fixes x::5 shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5 proof (induct\ x) case (of\text{-}int\ z) then have 0 \le z and z < 5 by simp\text{-}all then have z=0 \lor z=1 \lor z=2 \lor z=3 \lor z=4 by arith then show ?case by auto qed lemma UNIV\text{-}3:(UNIV::3\ set)=\{0,1,2\} apply safe using exhaust\text{-}3 three-eq-zero by (blast,\ auto) lemma sum\text{-}axis\text{-}UNIV\text{-}3[simp]:(\sum j\in (UNIV::3\ set).\ axis\ i\ 1\ \$\ j\cdot f\ j)=(f::3\Rightarrow real)\ i unfolding axis\text{-}def\ UNIV\text{-}3 apply simp using exhaust\text{-}3 by force
```

We can rewrite the original constant acceleration kinematics as a linear operator applied to a 3-dimensional vector. For that we take advantage of the following fact:

```
lemma e 1 = (\chi j :: 3. if j = 0 then 0 else if j = 1 then 1 else 0) unfolding axis-def by(rule Cart-lambda-cong, simp)
```

```
abbreviation constant-acceleration-kinematics-matrix \equiv (\chi i::3. if i=0 then e 1 else if i=1 then e 2 else (0::real^3))
```

```
abbreviation constant-acceleration-kinematics-matrix-flow t s \equiv (\chi i::3. if i=0 then s \$ 2 \cdot t ^2/2 + s \$ 1 \cdot t + s \$ 0 else if i=1 then s \$ 2 \cdot t + s \$ 1 else s \$ 2)
```

notation constant-acceleration-kinematics-matrix (A)

notation constant-acceleration-kinematics-matrix-flow (φ_A)

With these 2 definitions and the proof that linear systems of ODEs are Picard-Lindeloef, we can show that they form a pair of vector-field and its flow

```
lemma entries-cnst-acc-matrix: entries A = \{0, 1\} apply (simp-all\ add:\ axis-def,\ safe) by (rule-tac\ x=1\ \mathbf{in}\ exI,\ simp)+ lemma local-flow-cnst-acc-matrix: assumes 0 \le t and t < 1/9
```

```
shows local-flow ((*v) A) \{0..t\} ((real CARD(3))<sup>2</sup> · (\|A\|_{max})) \varphi_A unfolding local-flow-def local-flow-axioms-def apply safe apply(rule picard-lindeloef-linear-system[where A=A and t=t]) using entries-cnst-acc-matrix assms apply(force, simp, force) apply(rule has-vderiv-on-vec-lambda) apply(auto intro!: poly-derivatives simp: matrix-vector-mult-def vec-eq-iff) using exhaust-3 by force
```

Finally, we compute the wlp of this example and use it to verify the single-evolution ball again.

```
lemma single-evolution-ball-K:

assumes 0 \le t and t < 1/9

shows \lceil \lambda s. \ 0 \le s \$ \ 0 \wedge s \$ \ 0 = h \wedge s \$ \ 1 = 0 \wedge 0 > s \$ \ 2 \rceil

\le wp ([x'=(*v) \ A] \{0..t\} \& (\lambda s. \ s \$ \ 0 \ge 0))

\lceil \lambda s. \ 0 \le s \$ \ 0 \wedge s \$ \ 0 \le h \rceil

apply(subst local-flow.wp-g-orbit[OF local-flow-cnst-acc-matrix])

using assms by(auto simp: mult-nonneg-nonpos2)
```

Circular Motion

The characteristics that distinguish this example are:

- 1. We employ an existing finite type of size 2 to model program variables.
- 2. We define a 2×2 matrix (named C) to denote the linear operator that models circular motion.
- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow (φ_C) and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two\text{-}eq\text{-}zero\text{:}\ (2\text{::}2) = 0
by simp
lemma [simp]\text{:}\ i \neq (0\text{::}2) \longrightarrow i = 1
using exhaust\text{-}2 by fastforce
lemma UNIV\text{-}2\text{:}\ (UNIV\text{::}2\ set) = \{0, 1\}
apply safe using exhaust\text{-}2\ two\text{-}eq\text{-}zero by auto
abbreviation circular\text{-}motion\text{-}matrix :: real^2 2
where circular\text{-}motion\text{-}matrix \equiv (\chi\ i.\ if\ i=0\ then\ -\ e\ 1\ else\ e\ 0)
```

```
notation circular-motion-matrix (C)
lemma circle-invariant:
 shows (\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2) is-diff-invariant-of (*v) C along \{\theta...t\}
 apply(rule-tac diff-invariant-rules, clarsimp)
 apply(frule-tac i=0 in has-vderiv-on-vec-nth, drule-tac i=1 in has-vderiv-on-vec-nth)
 apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
 by(auto intro!: poly-derivatives simp: matrix-vector-mult-def)
lemma circular-motion-invariants:
 shows [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le
 wp ([x'=(*v) \ C]\{\theta..t\} \& G)
 [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2]
 apply(rule-tac C=\lambda s. r^2=(s \$ \theta)^2+(s \$ 1)^2 in dCut)
  apply(rule-tac I=\lambda s. \ r^2=(s \$ \theta)^2+(s \$ 1)^2 \ \text{in} \ dI)
 \mathbf{using}\ \mathit{circle-invariant}\ \mathbf{apply}(\mathit{blast},\mathit{force},\mathit{force})
 \mathbf{by}(rule\ dWeakening,\ auto)
— Proof of the same specification by providing solutions:
lemma entries-circ-matrix:entries C = \{0, -1, 1\}
 apply (simp-all add: axis-def, safe)
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 by (rule-tac \ x=1 \ in \ exI, \ simp)+
abbreviation circular-motion-matrix-flow t s \equiv
 (\chi i::2. if i=0 then s\$0 \cdot cos t - s\$1 \cdot sin t else s\$0 \cdot sin t + s\$1 \cdot cos t)
notation circular-motion-matrix-flow (\varphi_C)
lemma local-flow-circ-mtx:
 assumes 0 \le t and t < 1/4
 shows local-flow ((*v) C) \{0..t\} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \varphi_C
 unfolding local-flow-def local-flow-axioms-def apply safe
   apply(rule picard-lindeloef-linear-system)
 unfolding entries-circ-matrix using assms apply(simp-all)
  apply(rule has-vderiv-on-vec-lambda)
 \mathbf{apply}(force\ intro!:\ poly-derivatives\ simp:\ matrix-vector-mult-def)
 using exhaust-2 two-eq-zero by(force simp: vec-eq-iff)
lemma circular-motion:
 assumes 0 \le t and t < 1/4
 shows [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le
  wp ([x'=(*v) \ C]\{0..t\} \& G)
 [\lambda s. \ r^2 = (s \$ \theta)^2 + (s \$ 1)^2]
 apply(subst\ local-flow.wp-g-orbit[of\ (*v)\ C-(4\cdot (||C||_{max}))\ \varphi_C])
 using local-flow-circ-mtx and assms by auto
```

```
no-notation circular-motion-matrix (C)
no-notation circular-motion-matrix-flow (\varphi_C)
```

Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynamics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb-real-arith]: 0 \le x \Longrightarrow 0 > g \Longrightarrow 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v \Longrightarrow
(x::real) \leq h
proof-
  assume 0 \le x and 0 > g and 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
 then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot h \wedge 0 > g by auto
 hence *:v \cdot v = 2 \cdot g \cdot (x - h) \wedge 0 > g \wedge v \cdot v \geq 0
    using left-diff-distrib mult.commute by (metis zero-le-square)
  from this have (v \cdot v)/(2 \cdot g) = (x - h) by auto
 also from * have (v \cdot v)/(2 \cdot g) \leq \theta
    using divide-nonneg-neg by fastforce
  ultimately have h - x \ge \theta by linarith
  thus ?thesis by auto
qed
lemma [bb-real-arith]:
 assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot h + v \cdot v
    and pos: g \cdot \tau^2 / 2 + v \cdot \tau + (x::real) = 0
 shows 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
and 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
proof-
  from pos have g \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x = 0
    by (metis (mono-tags, hide-lams) Groups.mult-ac(1,3) mult-zero-right
        monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + v^2 + 2 \cdot q \cdot h = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(g \cdot \tau + v)^2 + 2 \cdot g \cdot h = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide\text{-}lams)\ Groups.add\text{-}ac(2,3)
        Groups.mult-ac(2, 3) monoid-mult-class.power2-eq-square nat-distrib(2))
  hence 2 \cdot g \cdot h + (-((g \cdot \tau) + v))^2 = 0
    by (metis\ Groups.add-ac(2)\ power2-minus)
  thus 2 \cdot g \cdot h + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
```

```
from * show 2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
   by (simp add: monoid-mult-class.power2-eq-square)
qed
lemma [bb-real-arith]:
 assumes invar: 2 \cdot q \cdot x = 2 \cdot q \cdot h + v \cdot v
 shows 2 \cdot g \cdot (g \cdot \tau^2 / 2 + v \cdot \tau + (x::real)) =
  2 \cdot g \cdot h + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
  have ?lhs = q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot x
      apply(subst\ Rat.sign-simps(18))+
      \mathbf{by}(\textit{auto simp: semiring-normalization-rules}(\textit{29}))
    also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot h + v \cdot v (is ... = ?middle)
      \mathbf{by}(subst\ invar,\ simp)
    finally have ?lhs = ?middle.
  moreover
  {have ?rhs = g \cdot g \cdot (\tau \cdot \tau) + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot h + v \cdot v
   by (simp\ add:\ Groups.mult-ac(2,3)\ semiring-class.distrib-left)
  also have \dots = ?middle
   by (simp\ add:\ semiring-normalization-rules(29))
  finally have ?rhs = ?middle.}
  ultimately show ?thesis by auto
\mathbf{qed}
lemma bouncing-ball:
  assumes 0 \le t and t < 1/9
  shows [\lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \le wp
  ((([x'=(*v) A]\{0..t\} \& (\lambda s. s \$ 0 \ge 0)) \cdot
  (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s. - s \$ 1)) ELSE \eta^{\bullet} FI))^{\star})
  [\lambda s. \ 0 \le s \ \ 0 \land s \ \ 0 \le h]
  apply(subst\ star-nd-fun.abs-eq)
  apply(rule wp-starI[of - \lceil \lambda s. \ 0 \le s \$ \ 0 \land 0 > s \$ \ 2 \land
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot h + (s \$ 1 \cdot s \$ 1)]])
   apply(simp, simp only: fbox-mult)
   apply(subst p2ndf-ndf2p-wp[symmetric, of (IF (\lambda s. s \$ \theta = \theta) THEN (1 ::=
(\lambda s. - s \$ 1) ELSE \eta^{\bullet} FI)
   apply(subst\ local-flow.wp-g-orbit[of - - 9 \cdot (||A||_{max}) \varphi_A])
  using local-flow-cnst-acc-matrix[OF assms] apply force
   apply(subst\ ndf2p-wpD)
  unfolding cond-def apply clarsimp
   apply(transfer, simp add: kcomp-def)
  by(auto simp: bb-real-arith)
```

Bouncing Ball with invariants

We prove again the bouncing ball but this time with differential invariants.

```
lemma gravity-invariant: (\lambda s. s. s. 2 < 0) is-diff-invariant-of (*v) A along \{0..t\} apply(rule-tac \vartheta' = \lambda s. \ 0 and \nu' = \lambda s. \ 0 in diff-invariant-rules(3), clarsimp) apply(drule-tac i = 2 in has-vderiv-on-vec-nth)
```

begin

```
apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
 by(auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
{\bf lemma}\ energy-conservation-invariant:
  (\lambda s. \ 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0) is-diff-invariant-of (*v) A
along \{0..t\}
  apply(rule diff-invariant-rules, clarify)
 apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
 apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
 apply(rule-tac\ S=\{0..t\}\ in\ has-vderiv-on-subset)
  by(auto intro!: poly-derivatives simp: vec-eq-iff matrix-vector-mult-def)
lemma bouncing-ball-invariants:
  [\lambda s. \ 0 \leq s \$ \ 0 \land s \$ \ 0 = h \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \leq
  wp ((([x'=(*v) A]\{0..t\} \& (\lambda s. s \$ 0 \ge 0)) \cdot
  (IF (\lambda s. s \$ 0 = 0) THEN (1 ::= (\lambda s. - s \$ 1)) ELSE \eta^{\bullet} FI))^{\star})
  [\lambda s. \ 0 \le s \ \ 0 \land s \ \ 0 \le h]
  apply(subst\ star-nd-fun.abs-eq)
  apply(rule-tac I = [\lambda s. \ 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot h + s\$2 \cdot s\$0
(s\$1 \cdot s\$1) in wp-starI)
    apply(simp, simp only: fbox-mult)
   \mathbf{apply}(\mathit{subst\ p2ndf-ndf2p-wp}[\mathit{symmetric},\ \mathit{of}\ (\mathit{IF}\ (\lambda s.\ s\ \$\ \theta\ =\ \theta)\ \mathit{THEN}\ (1::=
(\lambda s. - s \$ 1) ELSE \eta^{\bullet} FI)])
  apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
    apply(rule-tac I=\lambda s. s \$ 2 < 0 in dI)
  using gravity-invariant apply(blast, force, force)
  apply(rule-tac C=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot h - s\$1 \cdot s\$1 = 0 in dCut)
    \operatorname{apply}(rule-tac\ I=\lambda\ s.\ 2\cdot s\$2\cdot s\$0-2\cdot s\$2\cdot h-s\$1\cdot s\$1=0\ \mathbf{in}\ dI)
  using energy-conservation-invariant apply(blast, force, force)
  apply(rule dWeakening, subst p2ndf-ndf2p-wp)
  apply(rule wp-if-then-else)
  \mathbf{by}(auto\ simp:\ bb\text{-}real\text{-}arith\ le\text{-}fun\text{-}def)
no-notation constant-acceleration-kinematics-matrix (A)
no-notation constant-acceleration-kinematics-matrix-flow (\varphi_A)
end
          VC_diffKAD
5.4
theory VC-diffKAD-auxiliarities
imports
Main
../afpModified/VC	ext{-}KAD
Ordinary	ext{-}Differential	ext{-}Equations. ODE	ext{-}Analysis
```

5.4.1 Stack Theories Preliminaries: VC_KAD and ODEs

To make our notation less code-like and more mathematical we declare:

```
no-notation Archimedean-Field.ceiling ([-])
     and Archimedean-Field.floor (|-|)
     and Set.image ( ')
     and Range-Semiring.antirange-semiring-class.ars-r(r)
notation p2r([-])
     and r2p(|-|)
     and Set.image (-(|-|))
     and Product-Type.prod.fst (\pi_1)
     and Product-Type.prod.snd (\pi_2)
     and List.zip (infix1 \otimes 63)
     and rel-ad (\Delta^c_1)
This and more notation is explained by the following lemmata.
lemma shows \lceil P \rceil = \{(s, s) \mid s. P s\}
   and |R| = (\lambda x. \ x \in r2s \ R)
   and r2s R = \{x \mid x. \exists y. (x,y) \in R\}
   and \pi_1(x,y) = x \wedge \pi_2(x,y) = y
   and \Delta^{c_1} R = \{(x, x) | x. \not\exists y. (x, y) \in R\}
   and wp \ R \ Q = \Delta^{c_1} \ (R \ ; \Delta^{c_1} \ Q)
    and [x1,x2,x3,x4] \otimes [y1,y2] = [(x1,y1),(x2,y2)]
   and \{a..b\} = \{x. \ a \le x \land x \le b\}
   and \{a < ... < b\} = \{x. \ a < x \land x < b\}
   and (x \text{ solves-ode } f) \{0..t\} R = ((x \text{ has-vderiv-on } (\lambda t. f t (x t))) \{0..t\} \land x \in A
\{\theta..t\} \to R
   and f \in A \to B = (f \in \{f. \ \forall \ x. \ x \in A \longrightarrow (f \ x) \in B\})
   and (x has-vderiv-on x')\{0..t\} =
      (\forall r \in \{0..t\}. (x \text{ has-vector-derivative } x'r) (\text{at } r \text{ within } \{0..t\}))
    and (x \text{ has-vector-derivative } x' r) (at r \text{ within } \{0..t\}) =
      (x \text{ has-derivative } (\lambda x. \ x *_R x' r)) \ (at \ r \ within \{0..t\})
\mathbf{apply}(simp\text{-}all\ add\colon p2r\text{-}def\ r2p\text{-}def\ rel\text{-}ad\text{-}def\ rel\text{-}antidomain\text{-}kleene\text{-}algebra.fbox-}def
  solves-ode-def has-vderiv-on-def)
apply(blast, fastforce, fastforce)
using has-vector-derivative-def by auto
Observe also, the following consequences and facts:
proposition \pi_1(|R|) = r2s R
by (simp add: fst-eq-Domain)
proposition \Delta^{c_1} R = Id - \{(s, s) \mid s. s \in (\pi_1(R))\}
by(simp add: image-def rel-ad-def, fastforce)
proposition P \subseteq Q \Longrightarrow wp \ R \ P \subseteq wp \ R \ Q
by(simp\ add:\ rel-antidomain-kleene-algebra.dka.dom-iso\ rel-antidomain-kleene-algebra.fbox-iso)
```

```
proposition boxProgrPred-IsProp: wp R \lceil P \rceil \subseteq Id
\mathbf{by}(simp\ add:\ rel-antidomain-kleene-algebra\ .a-subid'\ rel-antidomain-kleene-algebra\ .addual\ .bbox-def)
proposition rdom-p2r-contents:(a, b) \in rdom \lceil P \rceil = ((a = b) \land P \ a)
proof-
have (a, b) \in rdom \lceil P \rceil = ((a = b) \land (a, a) \in rdom \lceil P \rceil) using p2r-subid by
fast force
also have ... = ((a = b) \land (a, a) \in [P]) by simp
also have ... = ((a = b) \land P \ a) by (simp \ add: p2r-def)
ultimately show ?thesis by simp
qed
//.SNGYJJd/ndot/b/JJd/Ndese/dom/g/le/nde/dt/rJJde//s/t/ø/sim/g//.
proposition rel-ad-rule1: (x,x) \notin \Delta^{c_1} [P] \Longrightarrow P x
by(auto simp: rel-ad-def p2r-subid p2r-def)
proposition rel-ad-rule2: (x,x) \in \Delta^{c_1} [P] \Longrightarrow \neg P x
by (metis ComplD VC-KAD.p2r-neg-hom rel-ad-rule1 empty-iff mem-Collect-eq p2s-neg-hom
rel-antidomain-kleene-algebra.a-one\ rel-antidomain-kleene-algebra.am1\ relcomp.relcompI)
proposition rel-ad-rule3: R \subseteq Id \Longrightarrow (x,x) \notin R \Longrightarrow (x,x) \in \Delta^{c_1} R
by (metis IdI Un-iff d-p2r rel-antidomain-kleene-algebra.addual.ars3
rel-antidomain-kleene-algebra.addual.ars-r-def rpr)
proposition rel-ad-rule4: (x,x) \in R \Longrightarrow (x,x) \notin \Delta^{c_1} R
\mathbf{by}(\textit{metis empty-iff rel-antidomain-kleene-algebra}. \textit{addual.ars1 relcomp.relcompI})
proposition boxProgrPred-chrctrztn:(x,x) \in wp \ R \ [P] = (\forall \ y. \ (x,y) \in R \longrightarrow P
by (metis boxProgrPred-IsProp rel-ad-rule1 rel-ad-rule2 rel-ad-rule3
rel-ad-rule4 d-p2r wp-simp wp-trafo)
lemma (in antidomain-kleene-algebra) fbox-starI:
assumes d p \leq d i and d i \leq |x| i and d i \leq d q
shows d p \leq |x^*| q
proof-
from \langle d | i \leq |x| | i \rangle have d | i \leq |x| (d | i)
  using local.fbox-simp by auto
hence |1| p \le |x^*| i using \langle d p \le d i \rangle by (metis (no-types))
  local.dual-order.trans local.fbox-one local.fbox-simp local.fbox-star-induct-var)
thus ?thesis using \langle d | i \leq d | q \rangle by (metis (full-types)
  local.fbox-mult local.fbox-one local.fbox-seq-var local.fbox-simp)
qed
proposition cons-eq-zipE:
(x, y) \# tail = xList \otimes yList \Longrightarrow \exists xTail \ yTail. \ x \# xTail = xList \wedge y \# yTail
= yList
by(induction xList, simp-all, induction yList, simp-all)
```

```
proposition set\text{-}zip\text{-}left\text{-}rightD: (x, y) \in set \ (xList \otimes yList) \Longrightarrow x \in set \ xList \land y \in set \ yList apply(rule \ conjI) apply(rule\text{-}tac \ y=y \ and \ ys=yList \ in \ set\text{-}zip\text{-}leftD, \ simp) apply(rule\text{-}tac \ x=x \ and \ xs=xList \ in \ set\text{-}zip\text{-}rightD, \ simp) done
\mathbf{declare} \ zip\text{-}map\text{-}fst\text{-}snd \ [simp]
```

5.4.2 VC_diffKAD Preliminaries

In dL, the set of possible program variables is split in two, the set of variables V and their primed counterparts V'. To implement this, we use Isabelle's string-type and define a function that primes a given string. We then define the set of primed-strings based on it.

```
definition vdiff :: string \Rightarrow string (\partial - [55] 70) where
(\partial x) = "d["@x@"]"
definition varDiffs :: string set where
varDiffs = \{y. \exists x. y = \partial x\}
proposition vdiff-inj:(\partial x) = (\partial y) \Longrightarrow x = y
\mathbf{by}(simp\ add:\ vdiff\text{-}def)
proposition vdiff-noFixPoints: x \neq (\partial x)
by(simp add: vdiff-def)
lemma varDiffsI: x = (\partial z) \Longrightarrow x \in varDiffs
by(simp add: varDiffs-def vdiff-def)
lemma varDiffsE:
assumes x \in varDiffs
obtains y where x = "d["@y@"]"
using assms unfolding varDiffs-def vdiff-def by auto
proposition vdiff-invarDiffs:(\partial x) \in varDiffs
by (simp add: varDiffsI)
```

(primed) dSolve preliminaries

This subsubsection is to define a function that takes a system of ODEs (expressed as a list xfList), a presumed solution $uInput = [u_1, \ldots, u_n]$, a state s and a time t, and outputs the induced flow $sols[xfList \leftarrow uInput]t$.

```
abbreviation varDiffs-to-zero ::real store \Rightarrow real store (sol) where sol a \equiv (override-on a \ (\lambda \ x. \ 0) \ varDiffs)
```

```
proposition varDiffs-to-zero-vdiff[simp]: (sol s) (\partial x) = 0
apply(simp add: override-on-def varDiffs-def)
by auto
proposition varDiffs-to-zero-beginning[simp]: take 2 \ x \neq "d" \Longrightarrow (sol \ s) \ x = s
apply(simp add: varDiffs-def override-on-def vdiff-def)
by fastforce
— Next, for each entry of the input-list, we update the state using said entry.
definition vderiv-of f S = (SOME f'. (f has-vderiv-on f') S)
primrec state-list-upd :: ((real \Rightarrow real \ store \Rightarrow real) \times string \times (real \ store \Rightarrow real) \times string \times (real \ store \Rightarrow real)
real)) list \Rightarrow
real \Rightarrow real \ store \Rightarrow real \ store \ \mathbf{where}
state-list-upd [] t s = s[
state-list-upd (uxf \# tail) \ t \ s = (state-list-upd tail \ t \ s)
     (\pi_1 \ (\pi_2 \ uxf)) := (\pi_1 \ uxf) \ t \ s,
    \partial (\pi_1 (\pi_2 uxf)) := (if t = 0 then (\pi_2 (\pi_2 uxf)) s
else vderiv-of (\lambda r. (\pi_1 uxf) rs) \{0 < .. < (2 *_R t)\} t)
abbreviation state-list-cross-upd ::real store \Rightarrow (string \times (real store \Rightarrow real)) list
(real \Rightarrow real \ store \Rightarrow real) \ list \Rightarrow real \Rightarrow (char \ list \Rightarrow real) \ (-[-\leftarrow -] - [64, 64, 64])
63) where
s[xfList \leftarrow uInput] \ t \equiv state-list-upd \ (uInput \otimes xfList) \ t \ s
proposition state-list-cross-upd-empty[simp]: (s[[] \leftarrow list] \ t) = s
\mathbf{by}(induction\ list,\ simp-all)
lemma inductive-state-list-cross-upd-its-vars:
assumes distHyp:distinct\ (map\ \pi_1\ ((y,\ g)\ \#\ xftail))
and varHyp: \forall xf \in set((y, g) \# xftail). \pi_1 xf \notin varDiffs
and indHyp:(u, x, f) \in set \ (utail \otimes xftail) \Longrightarrow (s[xftail \leftarrow utail] \ t) \ x = u \ t \ s
and disjHyp:(u, x, f) = (v, y, g) \lor (u, x, f) \in set (utail \otimes xftail)
shows (s[(y, g) \# xftail \leftarrow v \# utail] t) x = u t s
using disjHyp proof
 assume (u, x, f) = (v, y, g)
 hence (s[(y, g) \# xftail \leftarrow v \# utail] t) x = ((s[xftail \leftarrow utail] t)(x := u t s,
  \partial x := if \ t = 0 \ then \ f \ s \ else \ vderiv-of \ (\lambda \ r. \ u \ r. s) \ \{0 < .. < (2 *_R t)\} \ t)) \ x \ by
  also have ... = u t s by (simp add: vdiff-def)
  ultimately show ?thesis by simp
next
  assume yTailHyp:(u, x, f) \in set (utail \otimes xftail)
 from this and indHyp have 3:(s[xftail\leftarrow utail]\ t)\ x=u\ t\ s\ by\ fastforce
  from yTailHyp and distHyp have 2:y \neq x using set-zip-left-rightD by force
  from yTailHyp and varHyp have 1:x \neq \partial y
```

```
using set-zip-left-rightD vdiff-invarDiffs by fastforce
  from 1 and 2 have (s[(y, g) \# xftail \leftarrow v \# utail] t) x = (s[xftail \leftarrow utail] t) x
by simp
 thus ?thesis using 3 by simp
qed
theorem state-list-cross-upd-its-vars:
assumes distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and its-var: (u,x,f) \in set (uInput \otimes xfList)
shows (s[xfList \leftarrow uInput] \ t) \ x = u \ t \ s
using assms apply(induct xfList uInput arbitrary: x rule: list-induct2', simp,
simp, simp)
\mathbf{by}(\mathit{clarify}, \mathit{rule inductive-state-list-cross-upd-its-vars}, \mathit{simp-all})
lemma override-on-upd:x \in X \Longrightarrow (override-on f \ q \ X)(x := z) = (override-on f \ q \ X)(x := z)
(q(x := z)) X)
by (rule ext, simp add: override-on-def)
lemma inductive-state-list-cross-upd-its-dvars:
assumes \exists g. (s[xfTail \leftarrow uTail] \ \theta) = override-on \ s \ g \ varDiffs
and \forall xf \in set (xf \# xfTail). \pi_1 xf \notin varDiffs
and \forall uxf \in set (u \# uTail \otimes xf \# xfTail). \pi_1 uxf 0 s = s (\pi_1 (\pi_2 uxf))
shows \exists g. (s[xf \# xfTail \leftarrow u \# uTail] \theta) = override-on s g varDiffs
proof-
let ?gLHS = (s[(xf \# xfTail) \leftarrow (u \# uTail)] \theta)
have observ: \partial (\pi_1 \ xf) \in varDiffs by (auto simp: varDiffs-def)
from assms(1) obtain q where (s[xfTail \leftarrow uTail] \theta) = override-on s q varDiffs
by force
then have ?gLHS = (\textit{override-on } s \textit{ g varDiffs})(\pi_1 \textit{ xf } := \textit{u } \theta \textit{ s}, \ \partial \ (\pi_1 \textit{ xf}) := \pi_2
xf s) by simp
also have ... = (override-on \ s \ g \ varDiffs)(\partial \ (\pi_1 \ xf) := \pi_2 \ xf \ s)
using override-on-def varDiffs-def assms by auto
also have ... = (override-on s (g(\partial (\pi_1 xf) := \pi_2 xf s)) varDiffs)
using observ and override-on-upd by force
ultimately show ?thesis by auto
qed
theorem state-list-cross-upd-its-dvars:
assumes lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ 0 \ s = s \ (\pi_1 \ (\pi_2 \ uxf))
shows \exists g. (s[xfList \leftarrow uInput] \theta) = (override-on \ s \ g \ varDiffs)
using assms proof(induct xfList uInput rule: list-induct2')
case 1
  have (s[[] \leftarrow []] \ \theta) = override - on \ s \ varDiffs
  unfolding override-on-def by simp
  thus ?case by metis
```

```
next
 case (2 xf xfTail)
 have (s[(xf \# xfTail) \leftarrow []] \ \theta) = override-on \ s \ varDiffs
 unfolding override-on-def by simp
  thus ?case by metis
next
  case (3 u utail)
 have (s[[]\leftarrow utail] \ \theta) = override-on \ s \ varDiffs
 unfolding override-on-def by simp
  thus ?case by force
next
  case (4 xf xfTail u uTail)
  then have \exists g. (s[xfTail \leftarrow uTail] \ \theta) = override-on \ s \ g \ varDiffs \ by \ simp
  thus ?case using inductive-state-list-cross-upd-its-dvars 4.prems by blast
qed
lemma vderiv-unique-within-open-interval:
assumes (f has-vderiv-on f') \{0 < ... < t\} and t > 0
   and (f \text{ has-vderiv-on } f'') \{ \theta < ... < t \} and tauHyp: \tau \in \{ \theta < ... < t \}
shows f' \tau = f'' \tau
using assms apply(simp add: has-vderiv-on-def has-vector-derivative-def)
using frechet-derivative-unique-within-open-interval by (metis box-real(1) scaleR-one
tauHyp)
lemma has-vderiv-on-cong-open-interval:
assumes gHyp: \forall \tau > 0. f \tau = g \tau and tHyp: t>0
and fHyp:(f has-vderiv-on f') \{0 < .. < t\}
shows (g \text{ has-vderiv-on } f') \{0 < .. < t\}
from gHyp have \land \tau. \tau \in \{0 < ... < t\} \implies f \tau = g \tau using tHyp by force
hence eqDs:(f has-vderiv-on f') \{0 < ... < t\} = (g has-vderiv-on f') \{0 < ... < t\}
apply(rule-tac has-vderiv-on-cong) by auto
thus (g \text{ has-vderiv-on } f') \{0 < ... < t\} \text{ using } eqDs \text{ } fHyp \text{ by } simp
qed
\mathbf{lemma}\ closed\text{-}vderiv\text{-}on\text{-}cong\text{-}to\text{-}open\text{-}vderiv\text{:}
assumes gHyp: \forall \tau > 0. f \tau = g \tau
and fHyp: \forall t \geq 0. (f has-vderiv-on f') \{0..t\}
and tHyp: t>0 and cHyp: c>1
shows vderiv-of g {\theta < ... < (c *_R t)} t = f' t
proof-
have ctHyp:c \cdot t > 0 using tHyp and cHyp by auto
from fHyp have (f has-vderiv-on f') \{0 < ... < c \cdot t\} using has-vderiv-on-subset
by (metis\ greaterThanLessThan-subseteq-atLeastAtMost-iff\ less-eq-real-def)
then have derivHyp:(g has-vderiv-on f') \{0 < ... < c \cdot t\}
using gHyp ctHyp and has-vderiv-on-cong-open-interval by blast
hence f'Hyp: \forall f''. (g \text{ has-vderiv-on } f'') \{0 < ... < c \cdot t\} \longrightarrow (\forall \tau \in \{0 < ... < c \cdot t\}.
f' \tau = f'' \tau
using vderiv-unique-within-open-interval ctHyp by blast
```

```
also have (g \text{ has-vderiv-on } (vderiv\text{-of } g \{\theta < ... < (c *_R t)\})) \{\theta < ... < c \cdot t\}
by(simp add: vderiv-of-def, metis derivHyp someI-ex)
ultimately show vderiv-of g {0 < ... < c *_R t} t = f' t using tHyp cHyp by force
qed
lemma vderiv-of-to-sol-its-vars:
assumes distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp2: \forall t \geq 0. ((\lambda \tau. (sol s[xfList \leftarrow uInput] \tau) x)
has-vderiv-on (\lambda \tau. f (sol s[xfList \leftarrow uInput] \tau))) \{0..t\}
and tHyp: t>0 and uxfHyp:(u, x, f) \in set (uInput \otimes xfList)
shows vderiv - of(\lambda \tau. \ u \ \tau \ (sol \ s)) \{0 < .. < (2 *_R t)\} \ t = f(sol \ s[xfList \leftarrow uInput]
apply(rule-tac\ f = (\lambda \tau.\ (sol\ s[xfList \leftarrow uInput]\ \tau)\ x) in closed-vderiv-on-cong-to-open-vderiv)
subgoal using assms and state-list-cross-upd-its-vars by metis
by(simp-all add: solHyp2 tHyp)
\mathbf{lemma}\ inductive-to\text{-}sol\text{-}zero\text{-}its\text{-}dvars:
assumes eqFuncs: \forall s. \forall g. \forall xf \in set((x, f) \# xfs). \pi_2 xf (override-on s g varDiffs)
and eqLengths:length ((x, f) \# xfs) = length (u \# us)
and \textit{distinct:distinct} \ (\textit{map} \ \pi_1 \ ((x, f) \ \# \ \textit{xfs}))
and vars: \forall xf \in set ((x, f) \# xfs). \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set ((u \# us) \otimes ((x, f) \# xfs)). \pi_1 uxf \theta (sol s) = sol s (\pi_1)
(\pi_2 \ uxf)
and disjHyp:(y, g) = (x, f) \lor (y, g) \in set xfs
and indHyp:(y, g) \in set \ xfs \Longrightarrow (sol \ s[xfs \leftarrow us] \ \theta) \ (\partial \ y) = g \ (sol \ s[xfs \leftarrow us] \ \theta)
shows (sol\ s[(x,f) \# xfs \leftarrow u \# us]\ \theta)\ (\partial\ y) = g\ (sol\ s[(x,f) \# xfs \leftarrow u \# us]\ \theta)
proof-
from assms obtain h1 where h1Def:(sol s[((x, f) # xfs)\leftarrow(u # us)] 0) =
(\textit{override-on} \; (\textit{sol} \; s) \; \textit{h1} \; \textit{varDiffs}) \; \textbf{using} \; \textit{state-list-cross-upd-its-dvars} \; \textbf{by} \; \textit{blast}
from disjHyp show (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us]\ 0)\ (\partial\ y)=g\ (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us])
xfs \leftarrow u \# us \mid \theta)
proof
  assume eqHeads:(y, g) = (x, f)
  then have g(sol\ s[(x, f) \# xfs \leftarrow u \# us]\ \theta) = f(sol\ s) using h1Def eqFuncs
  also have ... = (sol\ s[(x, f) \# xfs \leftarrow u \# us]\ \theta)\ (\partial\ y) using eqHeads by auto
  ultimately show ?thesis by linarith
next
  assume tailHyp:(y, g) \in set xfs
  then have y \neq x using distinct set-zip-left-rightD by force
  hence \partial x \neq \partial y by (simp add: vdiff-def)
  have x \neq \partial y using vars vdiff-invarDiffs by auto
  obtain h2 where h2Def:(sol\ s[xfs\leftarrow us]\ 0) = override-on\ (sol\ s)\ h2\ varDiffs
  using state-list-cross-upd-its-dvars eqLengths distinct vars and solHyp1 by force
  have (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us]\ \theta)\ (\partial\ y)=q\ (sol\ s[xfs\leftarrow us]\ \theta)
  using tailHyp \ indHyp \ \langle x \neq \partial \ y \rangle and \langle \partial \ x \neq \partial \ y \rangle by simp
```

```
also have ... = q (override-on (sol s) h2 varDiffs) using h2Def by simp
    also have ... = g (sol s) using eqFuncs and tailHyp by force
    also have ... = g (sol s[(x, f) \# xfs \leftarrow u \# us] \theta)
     using eqFuncs h1Def tailHyp and eq-snd-iff by fastforce
    ultimately show ?thesis by simp
    qed
qed
lemma to-sol-zero-its-dvars:
assumes funcsHyp:\forall s. \forall g. \forall xf \in set xfList. \pi_2 xf (override-on s g varDiffs)
=\pi_2 xf s
and distinctHyp:distinct (map \pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf)) = (sol s) (\pi_2 uxf) = (sol s) (\pi_2
uxf)
and ygHyp:(y, g) \in set xfList
shows (sol\ s[xfList \leftarrow uInput]\ \theta)(\partial\ y) = g\ (sol\ s[xfList \leftarrow uInput]\ \theta)
\mathbf{using}\ assms\ \mathbf{apply} (induct\ xfList\ uInput\ rule:\ list-induct2',\ simp,\ simp,\ simp,\ clar-list uInput\ rule:\ list-induct2',\ simp,\ simp
ify)
by(rule inductive-to-sol-zero-its-dvars, simp-all)
\mathbf{lemma}\ inductive-to-sol-greater-than-zero-its-dvars:
assumes lengthHyp:length((y, g) \# xfs) = length(v \# vs)
and distHyp:distinct (map \pi_1 ((y, g) \# xfs))
and varHyp: \forall xf \in set ((y, g) \# xfs). \pi_1 xf \notin varDiffs
and indHyp:(u,x,f) \in set\ (vs \otimes xfs) \Longrightarrow (s[xfs \leftarrow vs]t)(\partial\ x) = vderiv - of\ (\lambda r.\ u\ r
s) \{0 < ... < 2 *_{R} t\} t
and disjHyp:(v, y, g) = (u, x, f) \lor (u, x, f) \in set (vs \otimes xfs) and tHyp:t > 0
shows (s[(y, g) \# xfs \leftarrow v \# vs] t) (\partial x) = vderiv-of (\lambda r. u r s) \{0 < ... < 2 *_R t\} t
proof-
let ?lhs = ((s[xfs \leftarrow vs]\ t)(y := v\ t\ s,\ \partial\ y := vderiv\text{-}of\ (\lambda\ r.\ v\ r\ s)\ \{\theta < .. < (2\ \cdot\ t)\}
t)) (\partial x)
let ?rhs = vderiv-of (\lambda r. u r s) \{0 < .. < (2 \cdot t)\} t
have (s[(y, g) \# xfs \leftarrow v \# vs] t) (\partial x) = ?lhs using tHyp by simp
also have vderiv-of (\lambda r. u r s) \{0 < ... < 2 *_R t\} t = ?rhs by simp
ultimately have obs:?thesis = (?lhs = ?rhs) by simp
from disjHyp have ?lhs = ?rhs
proof
     assume uxfEq:(v, y, g) = (u, x, f)
     then have ?lhs = vderiv - of (\lambda r. u r s) \{0 < .. < (2 \cdot t)\} t by simp
    also have vderiv-of (\lambda r. u rs) \{ \theta < ... < (2 \cdot t) \} t = ?rhs using uxfEq by simp
     ultimately show ?lhs = ?rhs by simp
     assume sygTail:(u, x, f) \in set (vs \otimes xfs)
    from this have y \neq x using distHyp set-zip-left-rightD by force
    hence \partial x \neq \partial y by (simp add: vdiff-def)
    have y \neq \partial x using varHyp using vdiff-invarDiffs by auto
    then have ?lhs = (s[xfs \leftarrow vs] \ t) \ (\partial x) using \langle y \neq \partial x \rangle and \langle \partial x \neq \partial y \rangle by simp
```

```
also have (s[xfs \leftarrow vs] \ t) \ (\partial \ x) = ?rhs  using indHyp \ sygTail by simp
  ultimately show ?lhs = ?rhs by simp
qed
from this and obs show ?thesis by simp
qed
lemma to-sol-greater-than-zero-its-dvars:
assumes distinctHyp:distinct (map \pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and uxfHyp:(u, x, f) \in set (uInput \otimes xfList) and tHyp:t > 0
shows (s[xfList \leftarrow uInput] \ t) \ (\partial \ x) = vderiv-of \ (\lambda \ r. \ u \ r. s) \ \{0 < .. < (2 *_R t)\} \ t
using assms apply(induct xfList uInput rule: list-induct2', simp, simp, simp, clar-
\mathbf{by}(rule\text{-}tac\ f=f\ \mathbf{in}\ inductive\text{-}to\text{-}sol\text{-}greater\text{-}than\text{-}zero\text{-}its\text{-}dvars},\ auto)
dInv preliminaries
Here, we introduce syntactic notation to talk about differential invariants.
no-notation Antidomain-Semiring.antidomain-left-monoid-class.am-add-op (infix)
no-notation Dioid.times-class.opp-mult (infixl \odot 70)
no-notation Lattices.inf-class.inf (infixl \sqcap 70)
no-notation Lattices.sup-class.sup (infixl \sqcup 65)
datatype trms = Const \ real \ (t_C - [54] \ 70) \ | \ Var \ string \ (t_V - [54] \ 70) \ |
                     Mns trms (\ominus - [54] 65) | Sum trms trms (infixl \oplus 65) |
                     Mult trms trms (infixl ⊙ 68)
primrec tval ::trms \Rightarrow (real \ store \Rightarrow real) \ ((1 \llbracket - \rrbracket_t)) \ \mathbf{where}
[t_C \ r]_t = (\lambda \ s. \ r)
[t_V \ x]_t = (\lambda \ s. \ s. \ x)
\llbracket \ominus \vartheta \rrbracket_t = (\lambda \ s. - (\llbracket \vartheta \rrbracket_t) \ s) |
\llbracket \vartheta \oplus \eta \rrbracket_t = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s + (\llbracket \eta \rrbracket_t) \ s)|
\llbracket \vartheta \odot \eta \rrbracket_t = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s \cdot (\llbracket \eta \rrbracket_t) \ s)
datatype props = Eq \ trms \ trms \ (infixr = 60) \mid Less \ trms \ trms \ (infixr < 62) \mid
                      Leq trms trms (infixr \leq 61) | And props props (infixl \sqcap 63) |
                      Or props props (infixl \sqcup 64)
primrec pval :: props \Rightarrow (real \ store \Rightarrow bool) ((1 \llbracket - \rrbracket_P)) where
\llbracket \vartheta \doteq \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s = (\llbracket \eta \rrbracket_t) \ s) |
\llbracket \vartheta \prec \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s < (\llbracket \eta \rrbracket_t) \ s) 
\llbracket \vartheta \preceq \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s \leq (\llbracket \eta \rrbracket_t) \ s)|
\llbracket \varphi \sqcap \psi \rrbracket_P = (\lambda \ s. \ (\llbracket \varphi \rrbracket_P) \ s \wedge (\llbracket \psi \rrbracket_P) \ s) |
\llbracket \varphi \sqcup \psi \rrbracket_P = (\lambda \ s. \ (\llbracket \varphi \rrbracket_P) \ s \lor (\llbracket \psi \rrbracket_P) \ s)
primrec tdiff :: trms \Rightarrow trms (\partial_t - [54] 70) where
(\partial_t t_C r) = t_C \theta
```

```
(\partial_t t_V x) = t_V (\partial x)
(\partial_t \ominus \vartheta) = \ominus (\partial_t \vartheta)
(\partial_t \ (\vartheta \oplus \eta)) = (\partial_t \ \vartheta) \oplus (\partial_t \ \eta)
(\partial_t (\vartheta \odot \eta)) = ((\partial_t \vartheta) \odot \eta) \oplus (\vartheta \odot (\partial_t \eta))
primrec pdiff :: props \Rightarrow props (\partial_P - [54] 70) where
(\partial_P (\vartheta \doteq \eta)) = ((\partial_t \vartheta) \doteq (\partial_t \eta))|
(\partial_P (\vartheta \prec \eta)) = ((\partial_t \vartheta) \preceq (\partial_t \eta))|
(\partial_P (\vartheta \leq \eta)) = ((\partial_t \vartheta) \leq (\partial_t \eta))|
(\partial_P (\varphi \sqcap \psi)) = (\partial_P \varphi) \sqcap (\partial_P \psi)
(\partial_P (\varphi \sqcup \psi)) = (\partial_P \varphi) \sqcap (\partial_P \psi)
primrec trmVars :: trms \Rightarrow string set where
trmVars\ (t_C\ r) = \{\}
trmVars\ (t_V\ x) = \{x\}
trm Vars \ (\ominus \ \vartheta) = trm Vars \ \vartheta
trm Vars (\vartheta \oplus \eta) = trm Vars \vartheta \cup trm Vars \eta
trm Vars (\vartheta \odot \eta) = trm Vars \vartheta \cup trm Vars \eta
fun substList :: (string \times trms) \ list \Rightarrow trms \Rightarrow trms \ (-\langle - \rangle \ [54] \ 80) where
xtList\langle t_C \ r \rangle = t_C \ r
\left| \left| \left\langle t_V \ x \right\rangle \right| = t_V \ x \right|
((y,\xi) \# xtTail)\langle Var x \rangle = (if x = y then \xi else xtTail\langle Var x \rangle)|
xtList\langle \ominus \vartheta \rangle = \ominus (xtList\langle \vartheta \rangle)
xtList\langle\vartheta\oplus\eta\rangle = (xtList\langle\vartheta\rangle) \oplus (xtList\langle\eta\rangle)
xtList\langle\vartheta\odot\eta\rangle = (xtList\langle\vartheta\rangle)\odot(xtList\langle\eta\rangle)
\textbf{proposition} \ \textit{substList-on-compl-of-varDiffs}:
assumes trmVars \eta \subset (UNIV - varDiffs)
and set (map \ \pi_1 \ xtList) \subseteq varDiffs
shows xtList\langle \eta \rangle = \eta
using assms apply(induction \eta, simp-all add: varDiffs-def)
\mathbf{by}(induction\ xtList,\ auto)
lemma substList-help1:set (map <math>\pi_1 ((map (vdiff \circ \pi_1) xfList) \otimes uInput)) \subseteq
varDiffs
apply(induct xfList uInput rule: list-induct2', simp-all add: varDiffs-def)
by auto
lemma substList-help2:
assumes trmVars \eta \subseteq (UNIV - varDiffs)
shows ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput)\langle \eta \rangle = \eta
using assms substList-help1 substList-on-compl-of-varDiffs by blast
\mathbf{lemma}\ substList-cross-vdiff-on-non-ocurring-var:
assumes x \notin set\ list1
shows ((map \ vdiff \ list1) \otimes list2)\langle t_V \ (\partial \ x)\rangle = t_V \ (\partial \ x)
using assms apply(induct list1 list2 rule: list-induct2', simp, simp, clarsimp)
\mathbf{by}(simp\ add:\ vdiff\text{-}def)
```

```
primrec prop Vars :: props \Rightarrow string set where prop Vars (\vartheta \doteq \eta) = trm Vars \vartheta \cup trm Vars \eta| prop Vars (\vartheta \prec \eta) = trm Vars \vartheta \cup trm Vars \eta| prop Vars (\vartheta \prec \eta) = trm Vars \vartheta \cup trm Vars \eta| prop Vars (\vartheta \preceq \eta) = trm Vars \vartheta \cup trm Vars \eta| prop Vars (\varphi \sqcap \psi) = prop Vars \varphi \cup prop Vars \psi| prop Vars (\varphi \sqcup \psi) = prop Vars \varphi \cup prop Vars \psi

primrec subspList :: (string \times trms) \ list \Rightarrow props \Rightarrow props (-\uparrow-\uparrow [54] 80) where xtList \upharpoonright \vartheta \doteq \eta \upharpoonright = ((xtList \langle \vartheta \rangle) \doteq (xtList \langle \eta \rangle)) \upharpoonright xtList \upharpoonright \vartheta \preceq \eta \upharpoonright = ((xtList \langle \vartheta \rangle) \preceq (xtList \langle \eta \rangle)) \upharpoonright xtList \upharpoonright \varphi \sqcap \psi \upharpoonright = ((xtList \langle \vartheta \rangle) \sqcup (xtList \langle \psi \upharpoonright)) \upharpoonright xtList \upharpoonright \varphi \sqcup \psi \upharpoonright = ((xtList \langle \varphi \upharpoonright) \sqcup (xtList \langle \psi \upharpoonright)) \upharpoonright xtList \upharpoonright \varphi \sqcup \psi \upharpoonright = ((xtList \langle \varphi \urcorner) \sqcup (xtList \langle \psi \urcorner)) \upharpoonright xtList \upharpoonright \varphi \sqcup \psi \upharpoonright = ((xtList \langle \varphi \urcorner) \sqcup (xtList \langle \psi \urcorner))
```

ODE Extras

For exemplification purposes, we compile some concrete derivatives used commonly in classical mechanics. A more general approach should be taken that generates this theorems as instantiations.

named-theorems ubc-definitions definitions used in the locale unique-on-bounded-closed

```
declare unique-on-bounded-closed-def [ubc-definitions]
and unique-on-bounded-closed-axioms-def [ubc-definitions]
and unique-on-closed-def [ubc-definitions]
and compact-interval-def [ubc-definitions]
and compact-interval-axioms-def [ubc-definitions]
and self-mapping-def [ubc-definitions]
and self-mapping-axioms-def [ubc-definitions]
and continuous-rhs-def [ubc-definitions]
and closed-domain-def [ubc-definitions]
and global-lipschitz-def [ubc-definitions]
and interval-def [ubc-definitions]
and nonempty-set-def [ubc-definitions]
and lipschitz-on-def [ubc-definitions]
```

 ${\bf named-theorems}\ poly-deriv\ temporal\ compilation\ of\ derivatives\ representing\ galilean\ transformations$

 ${\bf named-theorems} \ galilean-transform \ temporal \ compilation \ of \ vderivs \ representing \ galilean \ transformations$

 ${\bf named-theorems}\ galilean-transform-eq\ the\ equational\ version\ of\ galilean-transform$

```
lemma vector-derivative-line-at-origin:((\cdot) a has-vector-derivative a) (at x within T) by (auto intro: derivative-eq-intros)
```

```
lemma [poly-deriv]:((·) a has-derivative (\lambda x. x *_R a)) (at x within T) using vector-derivative-line-at-origin unfolding has-vector-derivative-def by simp
```

```
lemma quadratic-monomial-derivative:
((\lambda t :: real. \ a \cdot t^2) \ has-derivative \ (\lambda t. \ a \cdot (2 \cdot x \cdot t))) \ (at \ x \ within \ T)
apply(rule-tac g'1=\lambda t. 2 \cdot x \cdot t in derivative-eq-intros(6))
apply(rule-tac f'1=\lambda t. t in derivative-eq-intros(15))
by (auto intro: derivative-eq-intros)
\mathbf{lemma}\ quadratic-monomial-derivative 2:
((\lambda t::real.\ a\cdot t^2\ /\ 2)\ has-derivative\ (\lambda t.\ a\cdot x\cdot t))\ (at\ x\ within\ T)
apply(rule-tac f'1=\lambda t. a \cdot (2 \cdot x \cdot t) and g'1=\lambda x. 0 in derivative-eq-intros(18))
using quadratic-monomial-derivative by auto
lemma quadratic-monomial-vderiv[poly-deriv]:((\lambda t. \ a \cdot t^2 \ / \ 2) \ has-vderiv-on \ (\cdot)
a) T
apply(simp add: has-vderiv-on-def has-vector-derivative-def, clarify)
using quadratic-monomial-derivative2 by (simp add: mult-commute-abs)
lemma galilean-position[galilean-transform]:
((\lambda t. \ a \cdot t^2 \ / \ 2 + v \cdot t + x) \ has-vderiv-on \ (\lambda t. \ a \cdot t + v)) \ T
apply(rule-tac f'=\lambda x. \ a \cdot x + v and g'1=\lambda x. \ \theta in derivative-intros(191))
apply(rule-tac f'1=\lambda x. a \cdot x and g'1=\lambda x. v in derivative-intros(191))
using poly-deriv(2) by (auto intro: derivative-intros)
lemma [poly-deriv]:
t \in T \Longrightarrow ((\lambda \tau. \ a \cdot \tau^2 \ / \ 2 + v \cdot \tau + x) \ has-derivative \ (\lambda x. \ x *_R (a \cdot t + v)))
(at\ t\ within\ T)
using galilean-position unfolding has-vderiv-on-def has-vector-derivative-def by
simp
lemma [qalilean-transform-eq]:
t > 0 \Longrightarrow \textit{vderiv-of} \ (\lambda t. \ a \cdot t \ \hat{\ } 2 \ / \ 2 \ + \ v \cdot t \ + \ x) \ \{0 < .. < 2 \cdot t\} \ t = a \cdot t \ + \ v \ \}
proof-
let ?f = vderiv - of(\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\}
assume t > \theta hence t \in \{\theta < ... < \theta \cdot t\} by auto
have \exists f. ((\lambda t. \ a \cdot t^2 \ / \ 2 + v \cdot t + x) \ has-vderiv-on f) \{0 < ... < 2 \cdot t\}
\mathbf{using} \ \mathit{galilean-position} \ \mathbf{by} \ \mathit{blast}
hence ((\lambda t. \ a \cdot t^2 \ / \ 2 + v \cdot t + x) \ has-vderiv-on ?f) \ \{0 < .. < 2 \cdot t\}
unfolding vderiv-of-def by (metis (mono-tags, lifting) someI-ex)
t
using qalilean-position by simp
ultimately show (vderiv-of (\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) {0 < ... < 2 \cdot t}) t = a \cdot t
apply(rule-tac f' = ?f and \tau = t and t = 2 \cdot t in vderiv-unique-within-open-interval)
using \langle t \in \{0 < ... < 2 \cdot t\} \rangle by auto
qed
lemma t > 0 \Longrightarrow vderiv of (\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\} \ t = a \cdot t
```

```
unfolding vderiv-of-def apply(subst\ some1-equality[of - (\lambda t.\ a\cdot t + v)])
apply(rule-tac a=\lambda t. a \cdot t + v in ex11)
apply(simp-all add: galilean-position)
apply(rule\ ext,\ rename-tac\ f\ 	au)
apply(rule-tac f = \lambda t. a \cdot t^2 / 2 + v \cdot t + x and t = 2 \cdot t and f' = f in vderiv-unique-within-open-interval)
apply(simp-all add: qalilean-position)
oops
lemma galilean-velocity[galilean-transform]:((\lambda r. a \cdot r + v) has-vderiv-on (\lambda t. a))
apply(rule-tac f'1=\lambda x. a and g'1=\lambda x. 0 in derivative-intros(191))
unfolding has-vderiv-on-def by(auto intro: derivative-eq-intros)
lemma [galilean-transform-eq]:
t > 0 \Longrightarrow vderiv-of(\lambda r. \ a \cdot r + v) \{0 < ... < 2 \cdot t\} \ t = a
proof-
let ?f = vderiv - of(\lambda r. a \cdot r + v) \{0 < ... < 2 \cdot t\}
assume t > 0 hence t \in \{0 < ... < 2 \cdot t\} by auto
have \exists f. ((\lambda r. a \cdot r + v) has-vderiv-on f) \{0 < ... < 2 \cdot t\}
using galilean-velocity by blast
hence ((\lambda r. \ a \cdot r + v) \ has-vderiv-on ?f) \{0 < .. < 2 \cdot t\}
unfolding vderiv-of-def by (metis (mono-tags, lifting) some I-ex)
also have ((\lambda r. \ a \cdot r + v) \ has-vderiv-on \ (\lambda t. \ a)) \ \{0 < ... < 2 \cdot t\}
using galilean-velocity by simp
ultimately show (vderiv-of (\lambda r. \ a \cdot r + v) \{0 < ... < 2 \cdot t\}) t = a
apply(rule-tac f' = ?f and \tau = t and t = 2 \cdot t in vderiv-unique-within-open-interval)
using \langle t \in \{0 < ... < 2 \cdot t\} \rangle by auto
qed
lemma [qalilean-transform]:
((\lambda t.\ v \cdot t - a \cdot t^2 / 2 + x)\ has-vderiv-on\ (\lambda x.\ v - a \cdot x))\ \{\theta..t\}
apply(subgoal-tac ((\lambda t. - a \cdot t^2 / 2 + v \cdot t +x) has-vderiv-on (\lambda x. - a \cdot x +
v)) \{0..t\}, simp)
by(rule galilean-transform)
lemma [galilean-transform-eq]:t > 0 \implies vderiv-of \ (\lambda t. \ v \cdot t - a \cdot t^2 \ / \ 2 + x)
\{0 < ... < 2 \cdot t\} \ t = v - a \cdot t
apply(subgoal-tac vderiv-of (\lambda t. - a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\} t = -a
\cdot t + v, simp)
\mathbf{by}(rule\ galilean-transform-eq)
lemma [galilean-transform]:
((\lambda t. \ v - a \cdot t) \ has-vderiv-on \ (\lambda x. - a)) \ \{0..t\}
apply(subgoal-tac ((\lambda t. - a \cdot t + v) \text{ has-vderiv-on } (\lambda x. - a)) \{0..t\}, simp)
by(rule galilean-transform)
lemma [galilean-transform-eq]:t > 0 \implies vderiv\text{-}of (\lambda r. \ v - a \cdot r) \{0 < ... < 2 \cdot t\}
t = -a
apply(subgoal-tac vderiv-of (\lambda t. - a \cdot t + v) \{0 < ... < 2 \cdot t\} t = -a, simp)
```

 $\mathbf{by}(rule\ galilean-transform-eq)$

```
lemma [simp]:(\lambda x. \ case \ x \ of \ (t, \ x) \Rightarrow f \ t) = (\lambda \ x. \ (f \circ \pi_1) \ x)
by auto
end
theory VC-diffKAD
imports VC-diffKAD-auxiliarities
begin
5.4.3
             Phase Space Relational Semantics
definition solvesStoreIVP :: (real \Rightarrow real store) \Rightarrow (string \times (real store \Rightarrow real))
list \Rightarrow
real\ store \Rightarrow bool
((- solvesTheStoreIVP - withInitState - ) [70, 70, 70] 68) where
solvesStoreIVP \ \varphi_S \ xfList \ s \equiv
— F sends vdiffs-in-list to derivs.
(\forall t \geq 0. (\forall xf \in set xfList. \varphi_S t (\partial (\pi_1 xf)) = \pi_2 xf (\varphi_S t)) \land
— F preserves the rest of the variables and F sends derive of constants to 0.
(\forall y. (y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S \ t \ y = s \ y) \land 
       (y \notin (\pi_1(set xfList)) \longrightarrow \varphi_S \ t \ (\partial \ y) = \theta)) \land
— F solves the induced IVP.
(\forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf) (\varphi_S t))) \{0..t\}
UNIV \wedge
\varphi_S \ \theta \ (\pi_1 \ xf) = s(\pi_1 \ xf))
lemma solves-store-ivpI:
assumes \forall t \geq 0. \forall xf \in set xfList. (\varphi_S t (\partial (\pi_1 xf))) = (\pi_2 xf) (\varphi_S t)
  and \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S t y = s y
  and \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \longrightarrow \varphi_S t (\partial y) = 0
  and \forall t \geq 0. \ \forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf))
(\varphi_S t))) \{\theta..t\} UNIV
  and \forall xf \in set xfList. \varphi_S \ \theta \ (\pi_1 xf) = s(\pi_1 xf)
shows \varphi_S solvesTheStoreIVP xfList withInitState s
apply(simp add: solvesStoreIVP-def, safe)
using assms apply simp-all
\mathbf{by}(force, force, force)
named-theorems solves-store-ivpE elimination rules for solvesStoreIVP
lemma [solves-store-ivpE]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
shows \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S t y = s y
  and \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \longrightarrow \varphi_S t (\partial y) = 0
  and \forall t \geq 0. \forall xf \in set xfList. (\varphi_S t (\partial (\pi_1 xf))) = (\pi_2 xf) (\varphi_S t)
  and \forall t \geq 0. \ \forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf))
(\varphi_S t))) \{0..t\} UNIV
```

```
and \forall xf \in set xfList. \varphi_S \ \theta \ (\pi_1 xf) = s(\pi_1 xf)
using assms solvesStoreIVP-def by auto
\mathbf{lemma} \; [solves\text{-}store\text{-}ivpE] :
\mathbf{assumes}\ \varphi_S\ solves The \textit{Store IVP}\ \textit{xfList}\ \textit{with InitState}\ s
shows \forall y. y \notin varDiffs \longrightarrow \varphi_S \ 0 \ y = s \ y
proof(clarify, rename-tac x)
fix x assume x \notin varDiffs
from assms and solves-store-ivpE(5) have x \in (\pi_1(set xfList)) \Longrightarrow \varphi_S \ 0 \ x = s
x by fastforce
also have x \notin (\pi_1(set xfList)) \cup varDiffs \Longrightarrow \varphi_S \ \theta \ x = s \ x
using assms and solves-store-ivpE(1) by simp
ultimately show \varphi_S \theta x = s x using \langle x \notin varDiffs \rangle by auto
qed
{f named-theorems} solves-store-ivpD computation rules for solvesStoreIVP
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
 and y \notin (\pi_1(set xfList)) \cup varDiffs
shows \varphi_S t y = s y
using assms solves-store-ivpE(1) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
 and y \notin (\pi_1(set xfList))
shows \varphi_S t (\partial y) = 0
using assms solves-store-ivpE(2) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
 and xf \in set xfList
shows (\varphi_S \ t \ (\partial \ (\pi_1 \ xf))) = (\pi_2 \ xf) \ (\varphi_S \ t)
using assms solves-store-ivpE(3) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
  and xf \in set xfList
shows ((\lambda \ t. \ \varphi_S \ t \ (\pi_1 \ xf)) \ solves-ode \ (\lambda \ t.\lambda \ r.(\pi_2 \ xf) \ (\varphi_S \ t))) \ \{0..t\} \ UNIV
using assms solves-store-ivpE(4) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and (x,f) \in set xfList
shows \varphi_S \ \theta \ x = s \ x
```

```
using assms solves-store-ivpE(5) by fastforce
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and y \notin varDiffs
shows \varphi_S \ \theta \ y = s \ y
using assms solves-store-ivpE(6) by simp
definition guarDiffEqtn :: (string \times (real store \Rightarrow real)) list \Rightarrow (real store pred)
real store rel (ODEsystem - with - [70, 70] 61) where
ODEsystem xfList with G = \{(s, \varphi_S \ t) \mid s \ t \ \varphi_S. \ t \geq 0 \land (\forall \ r \in \{0..t\}. \ G \ (\varphi_S \ r))\}
\land solvesStoreIVP \varphi_S xfList s
          Derivation of Differential Dynamic Logic Rules
"Differential Weakening"
lemma wlp\text{-}evol\text{-}quard:Id \subseteq wp (ODEsystem xfList with G) [G]
by(simp add: rel-antidomain-kleene-algebra.fbox-def rel-ad-def guarDiffEqtn-def p2r-def,
force)
theorem dWeakening:
assumes guardImpliesPost: \lceil G \rceil \subseteq \lceil Q \rceil
shows PRE P (ODEsystem xfList with G) POST Q
using assms and wlp-evol-quard by (metis (no-types, hide-lams) d-p2r
order-trans p2r-subid rel-antidomain-kleene-algebra.fbox-iso)
theorem dW: wp (ODEsystem xfList with G) \lceil Q \rceil = wp (ODEsystem xfList with
G) [\lambda s. G s \longrightarrow Q s]
unfolding rel-antidomain-kleene-algebra.fbox-def rel-ad-def guarDiffEqtn-def
\mathbf{by}(simp\ add:\ relcomp.simps\ p2r-def,\ fastforce)
"Differential Cut"
lemma all-interval-guarDiffEqtn:
assumes solvesStoreIVP \varphi_S xfList s \land (\forall r \in \{0..t\}, G(\varphi_S r)) \land 0 \leq t
shows \forall r \in \{0..t\}. (s, \varphi_S r) \in (ODEsystem xfList with G)
{\bf unfolding} \ {\it guarDiffEqtn-def} \ {\bf using} \ {\it atLeastAtMost-iff} \ {\bf apply} \ {\it clarsimp}
apply(rule-tac x=r in exI, rule-tac x=\varphi_S in exI) using assms by simp
lemma condA fter Evol-remains Along Evol:
assumes boxDiffC:(s, s) \in wp \ (ODEsystem \ xfList \ with \ G) \ \lceil C \rceil
and FisSol:solvesStoreIVP \varphi_S xfList s \land (\forall r \in \{0..t\}. G(\varphi_S r)) \land 0 \le t
shows \forall r \in \{0..t\}. G(\varphi_S r) \land C(\varphi_S r)
proof-
from boxDiffC have \forall c. (s,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow C \ c
 by (simp add: boxProgrPred-chrctrztn)
also from FisSol have \forall r \in \{0..t\}. (s, \varphi_S r) \in (ODEsystem xfList with G)
 using all-interval-guarDiffEqtn by blast
```

```
ultimately show ?thesis
 using FisSol atLeastAtMost-iff guarDiffEqtn-def by fastforce
qed
theorem dCut:
assumes pBoxDiffCut:(PRE\ P\ (ODEsystem\ xfList\ with\ G)\ POST\ C)
assumes pBoxCutQ:(PRE\ P\ (ODEsystem\ xfList\ with\ (\lambda\ s.\ G\ s \land C\ s))\ POST\ Q)
shows PRE P (ODEsystem xfList with G) POST Q
apply(clarify, subgoal-tac\ a = b)\ defer
proof(metis\ d-p2r\ rdom-p2r-contents,\ simp,\ subst\ boxProgrPred-chrctrztn,\ clarify)
fix b y assume (b, b) \in [P] and (b, y) \in ODEsystem xfList with G
then obtain \varphi_S t where *:solvesStoreIVP \varphi_S xfList b \land (\forall r \in \{0..t\}. G (\varphi_S))
r)) \wedge \theta \leq t \wedge \varphi_S \ t = y
 using guarDiffEqtn-def by auto
hence \forall r \in \{0..t\}. (b, \varphi_S r) \in (ODEsystem xfList with G)
 using all-interval-guarDiffEqtn by blast
from this and pBoxDiffCut have \forall r \in \{0..t\}. C(\varphi_S r)
 using boxProgrPred-chrctrztn (b, b) \in [P] by (metis\ (no-types,\ lifting)\ d-p2r
subsetCE)
then have \forall r \in \{0..t\}. (b, \varphi_S r) \in (ODEsystem \ xfList \ with \ (\lambda \ s. \ G \ s \land C \ s))
 using * all-interval-guarDiffEqtn by (metis (mono-tags, lifting))
from this and pBoxCutQ have \forall r \in \{0..t\}. Q(\varphi_S r)
 using boxProgrPred-chrctrztn (b, b) \in [P] by (metis\ (no-types,\ lifting)\ d-p2r
subsetCE)
thus Q y using * by auto
qed
theorem dC:
assumes Id \subseteq wp (ODEsystem xfList with G) [C]
shows wp (ODEsystem xfList with G) [Q] = wp (ODEsystem xfList with (\lambda s.
G s \wedge C s)) [Q]
\operatorname{\mathbf{proof}}(rule\text{-}tac\ f = \lambda\ x.\ wp\ x\ [Q]\ \mathbf{in}\ HOL.arg\text{-}cong,\ safe)
 fix a b assume (a, b) \in ODEsystem xfList with G
 then obtain \varphi_S t where *:solvesStoreIVP \varphi_S xfList a \land (\forall r \in \{0..t\}. G (\varphi_S))
r)) \wedge \theta \leq t \wedge \varphi_S t = b
   using guarDiffEqtn-def by auto
 hence 1:\forall r \in \{0..t\}. (a, \varphi_S r) \in ODEsystem xfList with G
   by (meson all-interval-guarDiffEqtn)
 from this have \forall r \in \{0..t\}. C(\varphi_S r) using assms boxProgrPred-chrctrztn
   by (metis IdI boxProgrPred-IsProp subset-antisym)
 thus (a, b) \in ODEsystem xfList with (\lambda s. G s \land C s)
   using * guarDiffEqtn-def by blast
next
 fix a b assume (a, b) \in ODEsystem xfList with (\lambda s. G s \land C s)
 then show (a, b) \in ODEsystem xfList with G
 unfolding guarDiffEqtn-def by(clarsimp, rule-tac x=t in exI, rule-tac x=\varphi_S in
exI, simp)
qed
```

Solve Differential Equation

```
lemma prelim-dSolve:
assumes solHyp:(\lambda t.\ sol\ s[xfList\leftarrow uInput]\ t)\ solvesTheStoreIVP\ xfList\ withInit-
and uniqHyp: \forall X. \ solvesStoreIVP \ X \ xfList \ s \longrightarrow (\forall t \geq 0. \ (sol\ s[xfList \leftarrow uInput])
t) = X t
and diffAssgn: \forall t \geq 0. G(sol\ s[xfList \leftarrow uInput]\ t) \longrightarrow Q(sol\ s[xfList \leftarrow uInput]\ t)
shows \forall c. (s,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow Q \ c
\mathbf{proof}(clarify)
fix c assume (s,c) \in (ODEsystem \ xfList \ with \ G)
from this obtain t::real and \varphi_S::real \Rightarrow real store
where FHyp:t\geq 0 \land \varphi_S \ t = c \land solvesStoreIVP \ \varphi_S \ xfList \ s \land (\forall \ r \in \{0..t\}. \ G
using guarDiffEqtn-def by auto
from this and uniqHyp have (sol s[xfList\leftarrowuInput] t) = \varphi_S t by blast
then have cHyp:c = (sol\ s[xfList \leftarrow uInput]\ t) using FHyp by simp
from this have G (sol s[xfList \leftarrow uInput] t) using FHyp by force
then show Q c using diffAssgn FHyp cHyp by auto
qed
theorem dS:
assumes solHyp: \forall s. solvesStoreIVP (\lambda t. sol s[xfList \leftarrow uInput] t) xfList s
and uniqHyp: \forall s \ X. \ solvesStoreIVP \ X \ xfList \ s \longrightarrow (\forall t \geq 0. \ (sol\ s[xfList \leftarrow uInput]
t) = X t
shows wp (ODEsystem xfList with G) \lceil Q \rceil =
 [\lambda \ s. \ \forall \ t \geq 0. \ (\forall \ r \in \{0..t\}. \ G \ (sol \ s[xfList \leftarrow uInput] \ r)) \longrightarrow Q \ (sol \ s[xfList \leftarrow uInput] \ r)
t)
apply(simp add: p2r-def, rule subset-antisym)
unfolding quarDiffEqtn-def rel-antidomain-kleene-algebra.fbox-def rel-ad-def
using solHyp apply(simp add: relcomp.simps) apply clarify
apply(rule-tac \ x=x \ in \ exI, \ clarsimp)
apply(erule-tac \ x=sol \ x[xfList\leftarrow uInput] \ t \ in \ all E, \ erule \ disjE)
apply(erule-tac \ x=x \ in \ all E, \ erule-tac \ x=t \ in \ all E)
apply(erule\ impE,\ simp,\ erule-tac\ x=\lambda t.\ sol\ x[xfList\leftarrow uInput]\ t\ in\ allE)
apply(simp-all, clarify, rule-tac x=s in exI, simp add: relcomp.simps)
using uniqHyp by fastforce
theorem dSolve:
assumes solHyp: \forall s. \ solvesStoreIVP \ (\lambda t. \ sol \ s[xfList \leftarrow uInput] \ t) \ xfList \ s
and uniqHyp: \forall s. \forall X. solvesStoreIVP X xfList s \longrightarrow (\forall t > 0.(sol s[xfList \leftarrow uInput]
t) = X t
and diffAssgn: \forall s. \ Ps \longrightarrow (\forall t \geq 0. \ G(sols[xfList \leftarrow uInput]\ t) \longrightarrow Q(sols[xfList \leftarrow uInput]\ t)
shows PRE P (ODEsystem xfList with G) POST Q
apply(clarsimp, subgoal-tac\ a=b)
apply(clarify, subst boxProgrPred-chrctrztn)
apply(simp-all \ add: \ p2r-def)
apply(rule-tac uInput=uInput in prelim-dSolve)
apply(simp add: solHyp, simp add: uniqHyp)
```

```
by (metis (no-types, lifting) diffAssgn)
— We proceed to refine the previous rule by finding the necessary restrictions on
varFunList and uInput so that the solution to the store-IVP is guaranteed.
lemma conds4vdiffs-prelim:
assumes funcsHyp: \forall s \ g. \ \forall \ xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct\ (map\ \pi_1\ xfList)
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and lengthHyp:length xfList = length uInput
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ 0 \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf) \ solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 \ uxf) \ solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 \ uxf) \ solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 \ uxf) \ solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 \ uxf) \ solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 \ uxf) \ solHyp1: (\pi_1 \ uxf) \ solHyp1: (\pi_2 \ uxf) \ solHyp1: (\pi_2 \ uxf) \ solHyp1: (\pi_3 \ uxf) \ solHyp1: (\pi_3
uxf)
and solHyp2: \forall t \geq 0. ((\lambda \tau. (sol\ s[xfList \leftarrow uInput]\ \tau)\ x)
has-vderiv-on (\lambda \tau. f (sol s[xfList \leftarrow uInput] \tau))) \{0..t\}
and xfHyp:(x, f) \in set xfList and tHyp:t \geq 0
shows (sol\ s[xfList \leftarrow uInput]\ t)\ (\partial\ x) = f\ (sol\ s[xfList \leftarrow uInput]\ t)
proof-
from xfHyp obtain u where xfuHyp: (u,x,f) \in set (uInput \otimes xfList)
by (metis in-set-impl-in-set-zip2 lengthHyp)
show (sol\ s[xfList \leftarrow uInput]\ t)\ (\partial\ x) = f\ (sol\ s[xfList \leftarrow uInput]\ t)
    \mathbf{proof}(cases\ t=0)
    {f case}\ {\it True}
       have (sol\ s[xfList \leftarrow uInput]\ \theta)\ (\partial\ x) = f\ (sol\ s[xfList \leftarrow uInput]\ \theta)
       using assms and to-sol-zero-its-dvars by blast
        then show ?thesis using True by blast
    next
        case False
       from this have t > 0 using tHyp by simp
       hence (sol\ s[xfList \leftarrow uInput]\ t)\ (\partial\ x) = vderiv\text{-}of\ (\lambda\ r.\ u\ r\ (sol\ s))\ \{0 < .. < (2)\}
*_R t)} t
       using xfuHyp assms to-sol-greater-than-zero-its-dvars by blast
     also have vderiv-of (\lambda r.\ u\ r\ (sol\ s)) \{0<..<(2*_Rt)\}\ t=f\ (sol\ s[xfList\leftarrow uInput]
       using assms xfuHyp \langle t > 0 \rangle and vderiv-of-to-sol-its-vars by blast
        ultimately show ?thesis by simp
    qed
\mathbf{qed}
lemma conds4vdiffs:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map <math>\pi_1 xfList)
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and lengthHyp:length xfList = length uInput
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ 0 \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf) \ sol(sol \ s))
```

and $solHyp2: \forall t > 0$. $\forall xf \in set xfList. ((\lambda \tau. (sol s[xfList \leftarrow uInput] \tau) (\pi_1 xf))$

has-vderiv-on $(\lambda \tau. (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput] \ \tau))) \ \{0..t\}$

```
shows \forall t \geq 0. \forall xf \in set xfList. (sol s[xfList \leftarrow uInput] t) (\partial (\pi_1 xf)) = (\pi_2 xf)
(sol\ s[xfList\leftarrow uInput]\ t)
apply(rule allI, rule impI, rule ballI, rule conds4vdiffs-prelim)
using assms by simp-all
lemma conds4Consts:
assumes varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
shows \forall x. x \notin (\pi_1(set xfList)) \longrightarrow (sol s[xfList \leftarrow uInput] t) (\partial x) = 0
using varsHyp apply(induct xfList uInput rule: list-induct2')
apply(simp-all add: override-on-def varDiffs-def vdiff-def)
by clarsimp
lemma conds4InitState:
assumes distinctHyp:distinct\ (map\ \pi_1\ xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set \ (uInput \otimes xfList). \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_2 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_2 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_2 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_3 \ uxf) \ (sol \ s) \ (\pi_3 \ uxf) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s
uxf)
and xfHyp:(x, f) \in set xfList
shows (sol s[xfList\leftarrowuInput] 0) x = s x
proof-
from xfHyp obtain u where uxfHyp:(u, x, f) \in set (uInput \otimes xfList)
by (metis in-set-impl-in-set-zip2 lengthHyp)
from varsHyp have toZeroHyp:(sol\ s)\ x = s\ x using override-on-def\ xfHyp by
from uxfHyp and solHyp1 have u \ 0 \ (sol \ s) = (sol \ s) \ x by fastforce
also have (sol\ s[xfList \leftarrow uInput]\ \theta)\ x = u\ \theta\ (sol\ s)
using state-list-cross-upd-its-vars uxfHyp and assms by blast
ultimately show (sol s[xfList\leftarrowuInput] 0) x = s x using toZeroHyp by simp
qed
lemma conds4RestOfStrings:
assumes x \notin (\pi_1(set xfList)) \cup varDiffs
shows (sol s[xfList\leftarrowuInput] t) x = s x
using assms apply(induct xfList uInput rule: list-induct2')
by(auto simp: varDiffs-def)
lemma conds4storeIVP-on-toSol:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct\ (map\ \pi_1\ xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set \ (uInput \otimes xfList). \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol
uxf)
and solHyp2: \forall t \geq 0. \ \forall xf \in set xfList.
((\lambda t. (sol s[xfList \leftarrow uInput] t) (\pi_1 xf)) has-vderiv-on (\lambda t. \pi_2 xf (sol s[xfList \leftarrow uInput] t)))
t))) \{0...t\}
shows solvesStoreIVP (\lambda t. (sol s[xfList\leftarrowuInput] t)) xfList s
```

```
apply(rule\ solves-store-ivpI)
subgoal using conds4vdiffs assms by blast
subgoal using conds4RestOfStrings by blast
subgoal using conds4Consts varsHyp by blast
subgoal apply(rule allI, rule impI, rule ballI, rule solves-odeI)
   using solHyp2 by simp-all
subgoal using conds4InitState and assms by force
done
theorem dSolve-toSolve:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map \pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall s. \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \cup s)) \ (sol \ s) = (sol \ s) \ (so
and solHyp2: \forall s. \forall t \geq 0. \forall xf \in set xfList.
((\lambda t. (sol s[xfList \leftarrow uInput] t) (\pi_1 xf)) has-vderiv-on (\lambda t. \pi_2 xf (sol s[xfList \leftarrow uInput])))
t))) \{0..t\}
and uniqHyp: \forall s. \forall X. solvesStoreIVP X xfList s \longrightarrow (\forall t \geq 0. (sol s[xfList \leftarrow uInput]))
t) = X t
and postCondHyp: \forall s. \ P \ s \longrightarrow (\forall \ t \ge 0. \ Q \ (sol \ s[xfList \leftarrow uInput] \ t))
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac uInput=uInput in dSolve)
subgoal using assms and conds/storeIVP-on-toSol by simp
subgoal by (simp add: uniqHyp)
\mathbf{using}\ postCondHyp\ postCondHyp\ \mathbf{by}\ simp
— As before, we keep refining the rule dSolve. This time we find the necessary
restrictions to attain uniqueness.
lemma conds4UniqSol:
fixes f::real store \Rightarrow real
assumes tHyp:t \geq 0
and contHyp:continuous-on (\{0..t\} \times UNIV) (\lambda(t, (r::real)). f(\varphi_s t))
shows unique-on-bounded-closed \theta \{\theta..t\} \tau (\lambda t \ r. \ f (\varphi_s \ t)) \ UNIV (if \ t = \theta \ then
1 else 1/(t+1)
apply(simp\ add:\ ubc\text{-}definitions,\ rule\ conjI)
subgoal using contHyp continuous-rhs-def by fastforce
subgoal using assms continuous-rhs-def by fastforce
done
lemma solves-store-ivp-at-beginning-overrides:
assumes solvesStoreIVP \varphi_s xfList a
shows \varphi_s \theta = override-on a (\varphi_s \ \theta) varDiffs
apply(rule\ ext,\ subgoal-tac\ x\notin varDiffs\longrightarrow \varphi_s\ 0\ x=a\ x)
subgoal by (simp add: override-on-def)
using assms and solves-store-ivpD(6) by simp
```

```
lemma ubcStoreUniqueSol:
assumes tHyp:t > 0
assumes contHyp: \forall xf \in set xfList. continuous-on (\{0..t\} \times UNIV)
(\lambda(t, (r::real)). (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ t))
and eqDerivs: \forall xf \in set xfList. \ \forall \tau \in \{0..t\}. \ (\pi_2 xf) \ (\varphi_s \tau) = (\pi_2 xf) \ (sol
s[xfList \leftarrow uInput] \tau
and Fsolves:solvesStoreIVP \varphi_s xfList s
and solHyp:solvesStoreIVP (\lambda \tau. (sol\ s[xfList \leftarrow uInput]\ \tau)) xfList\ s
shows (sol\ s[xfList \leftarrow uInput]\ t) = \varphi_s\ t
proof
  fix x::string show (sol s[xfList\leftarrowuInput] t) x = \varphi_s t x
  \mathbf{proof}(cases\ x \in (\pi_1(set\ xfList)) \cup varDiffs)
  case False
    then have notInVars:x \notin (\pi_1(set xfList)) \cup varDiffs by simp
    from solHyp have (sol\ s[xfList \leftarrow uInput]\ t)\ x = s\ x
    using tHyp \ notInVars \ solves-store-ivpD(1) by blast
   also from Fsolves have \varphi_s t x = s x using tHyp notInVars solves-store-ivpD(1)
by blast
    ultimately show (sol s[xfList \leftarrow uInput] t) x = \varphi_s t x by simp
  next case True
    then have x \in (\pi_1(set xfList)) \lor x \in varDiffs by simp
    from this show ?thesis
    proof
      assume x \in (\pi_1(set xfList))
      from this obtain f where xfHyp:(x, f) \in set xfList by fastforce
      then have expand1: \forall xf \in set xfList.((\lambda \tau. \varphi_s \tau (\pi_1 xf)) solves-ode)
      (\lambda \tau \ r. \ (\pi_2 \ xf) \ (\varphi_s \ \tau))) \{\theta..t\} \ UNIV \land \varphi_s \ \theta \ (\pi_1 \ xf) = s \ (\pi_1 \ xf)
      using Fsolves tHyp by (simp add:solvesStoreIVP-def)
      hence expand2: \forall xf \in set xfList. \ \forall \tau \in \{0..t\}. \ ((\lambda r. \varphi_s \ r \ (\pi_1 \ xf)))
       has-vector-derivative (\lambda r. (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput]\ \tau))\ \tau) (at \tau within
\{0..t\}
      using eqDerivs by (simp add: solves-ode-def has-vderiv-on-def)
      then have \forall xf \in set xfList. ((\lambda \tau. \varphi_s \tau (\pi_1 xf)) solves-ode
       (\lambda \tau \ r. \ (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ \tau)))\{0..t\} \ UNIV \land \varphi_s \ \theta \ (\pi_1 \ xf) = s
(\pi_1 xf)
      by (simp add: has-vderiv-on-def solves-ode-def expand1 expand2)
     then have 1:((\lambda \tau. \varphi_s \tau x) \text{ solves-ode } (\lambda \tau r. f (\text{sol s}[xfList \leftarrow uInput] \tau))) \{0..t\}
UNIV \wedge
      \varphi_s \ \theta \ x = s \ x \ \text{using} \ xfHyp \ \text{by} \ fastforce
      from solHyp and xfHyp have 2:((\lambda \tau. (sol s[xfList \leftarrow uInput] \tau) x) solves-ode
      (\lambda \tau \ r. \ f \ (sol \ s[xfList \leftarrow uInput] \ \tau))) \ \{\theta..t\} \ UNIV \land (sol \ s[xfList \leftarrow uInput] \ \theta)
x = s x
      using solvesStoreIVP-def tHyp by fastforce
```

```
from tHyp and contHyp have \forall xf \in set xfList. unique-on-bounded-closed 0
\{0..t\}\ (s\ (\pi_1\ xf))
     (\lambda \tau \ r. \ (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ \tau)) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1/(t+1))
      apply(clarify) apply(rule conds4UniqSol) by(auto)
        from this have 3:unique-on-bounded-closed 0 \{0...t\} (s x) (\lambda \tau r. f (sol
s[xfList \leftarrow uInput] \tau)
      UNIV (if t = 0 then 1 else 1/(t+1)) using xfHyp by fastforce
      from 1 2 and 3 show (sol s[xfList \leftarrow uInput] t) x = \varphi_s t x
     using unique-on-bounded-closed.unique-solution using real-Icc-closed-segment
tHyp by blast
   next
      assume x \in varDiffs
      then obtain y where xDef: x = \partial y by (auto simp: varDiffs-def)
      show (sol s[xfList\leftarrowuInput] t) x = \varphi_s t x
      \operatorname{\mathbf{proof}}(cases\ y\in set\ (map\ \pi_1\ xfList))
      case True
       then obtain f where xfHyp:(y, f) \in set xfList by fastforce
       from tHyp and Fsolves have \varphi_s t x = f(\varphi_s t)
       using solves-store-ivpD(3) xfHyp xDef by force
       also have (sol\ s[xfList \leftarrow uInput]\ t)\ x = f\ (sol\ s[xfList \leftarrow uInput]\ t)
       using solves-store-ivpD(3) xfHyp xDef solHyp tHyp by force
       ultimately show ?thesis using eqDerivs xfHyp tHyp by auto
      next case False
        then have \varphi_s t x = \theta
       using xDef solves-store-ivpD(2) Fsolves tHyp by simp
       also have (sol\ s[xfList \leftarrow uInput]\ t)\ x = 0
       using False solHyp tHyp solves-store-ivpD(2) xDef by fastforce
       ultimately show ?thesis by simp
      qed
   qed
  qed
qed
theorem dSolveUBC:
assumes contHyp:\forall s. \forall t \geq 0. \forall xf \in set xfList. continuous-on (<math>\{0..t\} \times UNIV)
(\lambda(t, (r::real)). (\pi_2 xf) (sol s[xfList \leftarrow uInput] t))
and solHyp: \forall s. solvesStoreIVP (\lambda t. (sol s[xfList \leftarrow uInput] t)) xfList s
and uniqHyp: \forall s. \forall \varphi_s. \varphi_s  solvesTheStoreIVP xfList withInitState s \longrightarrow
(\forall t \geq 0. \ \forall xf \in set \ xfList. \ \forall \ r \in \{0..t\}. \ (\pi_2 \ xf) \ (\varphi_s \ r) = (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput])
r))
and diffAssgn: \forall s. \ Ps \longrightarrow (\forall t \geq 0. \ G(sols[xfList \leftarrow uInput]t) \longrightarrow Q(sols[xfList \leftarrow uInput]t)
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac\ uInput=uInput\ in\ dSolve)
prefer 2 subgoal proof(clarify)
fix s::real store and \varphi_s::real \Rightarrow real store and t::real
assume isSol:solvesStoreIVP \varphi_s xfList s and sHyp:0 \le t
```

using tHyp by fastforce

 $\{0..t\}$

```
from this and uniqHyp have \forall xf \in set xfList. \forall t \in \{0..t\}.
(\pi_2 xf) (\varphi_s t) = (\pi_2 xf) (sol s[xfList \leftarrow uInput] t) by auto
also have \forall xf \in set xfList. continuous-on (\{0..t\} \times UNIV)
(\lambda(t, (r::real)). (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ t)) using contHyp \ sHyp by blast
ultimately show (sol s[xfList \leftarrow uInput] t) = \varphi_s t
using sHyp isSol ubcStoreUniqueSol solHyp by simp
qed using assms by simp-all
theorem dSolve-toSolveUBC:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map \pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall s. \ \forall uxf \in set \ (uInput \otimes xfList). \ \pi_1 \ uxf \ 0 \ (sol \ s) = sol \ s \ (\pi_1 \ (\pi_2 \ uxf \ solHyp1: \forall s. \ \forall uxf \in set \ (uInput \ solHyp1: \ uxf \ solHyp1: \ vxfList).
uxf)
and solHyp2: \forall s. \forall t \geq 0. \forall xf \in set xfList. ((\lambda t. (sol s[xfList \leftarrow uInput] t) (\pi_1 xf))
has-vderiv-on
(\lambda t. \pi_2 \ xf \ (sol \ s[xfList \leftarrow uInput] \ t))) \{0..t\}
and contHyp: \forall s. \forall t \geq 0. \forall xf \in set xfList. continuous-on (\{0..t\} \times UNIV)
(\lambda(t, (r::real)), (\pi_2 xf) (sol s[xfList \leftarrow uInput] t))
and uniqHyp: \forall s. \ \forall \varphi_s. \ \varphi_s \ solvesTheStoreIVP \ xfList \ withInitState \ s \longrightarrow
(\forall \ t \geq 0. \ \forall \ xf \in set \ xfList. \ \forall \ r \in \{0..t\}. \ (\pi_2 \ xf) \ (\varphi_s \ r) = (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) \ (sol \ s[xfList \leftarrow uInput] \ (\pi_s \ r) = (\pi_s \ xf) 
r))
and postCondHyp: \forall s. \ P \ s \longrightarrow (\forall \ t \ge 0. \ Q \ (sol \ s[xfList \leftarrow uInput] \ t))
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac uInput=uInput in dSolveUBC)
using contHyp apply simp
apply(rule allI, rule-tac uInput=uInput in conds4storeIVP-on-toSol)
using assms by auto
"Differential Invariant."
lemma solvesStoreIVP-couldBeModified:
fixes F::real \Rightarrow real store
assumes vars: \forall t \geq 0. \ \forall xf \in set \ xfList. \ ((\lambda t. \ Ft \ (\pi_1 \ xf)) \ solves-ode \ (\lambda t \ r. \ \pi_2 \ xf \ (Ft))
t))) \{0..t\} UNIV
and dvars: \forall t \geq 0. \forall xf \in set xfList. (F t (\partial (\pi_1 xf))) = (\pi_2 xf) (F t)
shows \forall t \geq 0. \ \forall r \in \{0..t\}. \ \forall xf \in set xfList.
((\lambda \ t. \ F \ t \ (\pi_1 \ xf)) \ has-vector-derivative \ F \ r \ (\partial \ (\pi_1 \ xf))) \ (at \ r \ within \ \{0..t\})
proof(clarify, rename-tac\ t\ r\ x\ f)
fix x f and t r :: real
assume tHyp:0 \le t and xfHyp:(x, f) \in set xfList and rHyp:r \in \{0..t\}
```

from this and vars have $((\lambda t. F t x) solves-ode (\lambda t r. f (F t))) \{0..t\} UNIV$

hence *: $\forall r \in \{0..t\}$. $((\lambda t. F t x) has-vector-derivative <math>(\lambda t. f (F t)) r)$ (at r within

have $\forall t \geq 0. \ \forall r \in \{0..t\}. \ \forall xf \in set xfList. (F r (\partial (\pi_1 xf))) = (\pi_2 xf) (F r)$

by (simp add: solves-ode-def has-vderiv-on-def tHyp)

```
using assms by auto
from this rHyp and xfHyp have (F r (\partial x)) = f (F r) by force
then show ((\lambda t. \ F \ t \ (\pi_1 \ (x, f))) \ has-vector-derivative \ F \ (\partial \ (\pi_1 \ (x, f)))) \ (at \ r
within \{0..t\})
using * rHyp by auto
qed
\mathbf{lemma}\ derivation Lemma-base Case:
fixes F::real \Rightarrow real \ store
assumes solves:solvesStoreIVP F xfList a
shows \forall x \in (UNIV - varDiffs). \forall t \geq 0. \forall r \in \{0..t\}.
((\lambda \ t. \ F \ t \ x) \ has-vector-derivative \ F \ r \ (\partial \ x)) \ (at \ r \ within \ \{0..t\})
proof
\mathbf{fix} \ x
\mathbf{assume}\ x \in \mathit{UNIV} - \mathit{varDiffs}
then have notVarDiff: \forall z. x \neq \partial z using varDiffs-def by fastforce
 show \forall t \geq 0. \forall r \in \{0..t\}. ((\lambda t. F t x) has-vector-derivative F r <math>(\partial x)) (at r within
\{\theta..t\}
  \mathbf{proof}(\mathit{cases}\ x \in \mathit{set}\ (\mathit{map}\ \pi_1\ \mathit{xfList}))
    case True
    from this and solves have \forall t \geq 0. \forall r \in \{0..t\}. \forall xf \in set xfList.
    ((\lambda \ t. \ F \ t \ (\pi_1 \ xf)) \ has-vector-derivative \ F \ r \ (\partial \ (\pi_1 \ xf))) \ (at \ r \ within \ \{0..t\})
    apply(rule-tac\ solvesStoreIVP-couldBeModified)\ using\ solves\ solves-store-ivpD
by auto
    from this show ?thesis using True by auto
  next
    case False
    from this not VarDiff and solves have const: \forall t \geq 0. F t x = a x
    using solves-store-ivpD(1) by (simp add: varDiffs-def)
     have constD: \forall t \geq 0. \ \forall r \in \{0..t\}. \ ((\lambda r. \ a x) \ has-vector-derivative \ 0) \ (at \ r. \ a x) \ has-vector-derivative \ 0)
within \{0..t\})
    \mathbf{by}\ (\mathit{auto\ intro:\ derivative-eq\text{-}intros})
    \{fix t r:: real \}
      assume t \ge \theta and r \in \{\theta..t\}
      hence ((\lambda \ s. \ a \ x) \ has\text{-}vector\text{-}derivative \ \theta) (at r within \{\theta..t\}) by (simp add:
      moreover have \bigwedge s. \ s \in \{0..t\} \Longrightarrow (\lambda \ r. \ F \ r \ x) \ s = (\lambda \ r. \ a \ x) \ s
      using const by (simp add: \langle 0 \leq t \rangle)
      ultimately have ((\lambda \ s. \ F \ s \ x) \ has-vector-derivative \ \theta) \ (at \ r \ within \ \{\theta...t\})
      using has-vector-derivative-transform by (metis \langle r \in \{0..t\}\rangle)
    hence isZero: \forall t \geq 0. \forall r \in \{0..t\}. ((\lambda t. F t x) has-vector-derivative 0) (at r within
\{\theta..t\})by blast
    from False solves and notVarDiff have \forall t \geq 0. F t (\partial x) = 0
    using solves-store-ivpD(2) by simp
    then show ?thesis using isZero by simp
  qed
qed
```

lemma derivationLemma:

```
assumes solvesStoreIVP F xfList a
and tHyp:t \geq 0
and termVarsHyp: \forall x \in trmVars \ \eta. \ x \in (UNIV - varDiffs)
shows \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (Fs)) has-vector-derivative \llbracket \partial_t \eta \rrbracket_t (Fr)) (at r within
\{0..t\}
using termVarsHyp proof(induction \eta)
  case (Const r)
  then show ?case by simp
next
  case (Var y)
  then have yHyp:y \in UNIV - varDiffs by auto
  from this tHyp and assms(1) show ?case
  using derivationLemma-baseCase by auto
\mathbf{next}
  case (Mns \ \eta)
  then show ?case
  apply(clarsimp)
  \mathbf{by}(rule\ derivative\text{-}intros,\ simp)
next
  case (Sum \eta 1 \ \eta 2)
  then show ?case
  apply(clarsimp)
  \mathbf{by}(rule\ derivative\text{-}intros,\ simp\text{-}all)
next
  case (Mult \eta 1 \ \eta 2)
  then show ?case
  apply(clarsimp)
  apply(subgoal-tac ((\lambda s. \llbracket \eta 1 \rrbracket_t (F s) *_R \llbracket \eta 2 \rrbracket_t (F s)) has-vector-derivative
   [\![\partial_t \ \eta 1]\!]_t \ (F \ r) \cdot [\![\eta 2]\!]_t \ (F \ r) + [\![\eta 1]\!]_t \ (F \ r) \cdot [\![\partial_t \ \eta 2]\!]_t \ (F \ r)) \ (at \ r \ within
\{0..t\}, simp
 apply(rule-tac f'1 = [\partial_t \eta 1]_t (Fr) and g'1 = [\partial_t \eta 2]_t (Fr) in derivative-eq-intros(25))
 by (simp-all add: has-field-derivative-iff-has-vector-derivative)
qed
lemma diff-subst-prprty-4terms:
assumes solves: \forall xf \in set xfList. F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
and tHyp:(t::real) \geq 0
and listsHyp:map \pi_2 xfList = map tval uInput
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
shows [\![\partial_t \ \eta]\!]_t (F t) = [\![(map \ (vdiff \circ \pi_1) \ xfList) \otimes uInput) \langle \partial_t \ \eta \rangle]\!]_t (F t)
using termVarsHyp apply(induction \eta) apply(simp-all \ add: \ substList-help2)
using listsHyp and solves apply(induct xfList uInput rule: list-induct2', simp,
simp, simp)
\mathbf{proof}(clarify, rename\text{-}tac\ y\ g\ xfTail\ \vartheta\ trmTail\ x)
fix x y::string and \vartheta::trms and g and xfTail::((string \times (real\ store \Rightarrow real))\ list)
and trm Tail
assume IH: \Lambda x. \ x \notin varDiffs \Longrightarrow map \ \pi_2 \ xfTail = map \ tval \ trmTail \Longrightarrow
\forall xf \in set \ xfTail. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t) \Longrightarrow
F \ t \ (\partial \ x) = \llbracket (map \ (vdiff \circ \pi_1) \ xfTail \otimes trmTail) \langle t_V \ (\partial \ x) \rangle \rrbracket_t \ (F \ t)
```

```
and 1:x \notin varDiffs and 2:map \ \pi_2 \ ((y, g) \# xfTail) = map \ tval \ (\vartheta \# trmTail)
and \partial: \forall xf \in set ((y, g) \# xfTail). F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
hence *: \llbracket (map \ (vdiff \circ \pi_1) \ xfTail \otimes trmTail) \langle Var \ (\partial \ x) \rangle \rrbracket_t \ (F \ t) = F \ t \ (\partial \ x)
using tHyp by auto
show F \ t \ (\partial \ x) = \llbracket ((map \ (vdiff \circ \pi_1) \ ((y, g) \ \# \ xfTail)) \otimes (\vartheta \ \# \ trmTail)) \ \langle t_V \ \rangle
(\partial x)\|_t (F t)
  \mathbf{proof}(cases\ x \in set\ (map\ \pi_1\ ((y,\ g)\ \#\ xfTail)))
    case True
    then have x = y \lor (x \neq y \land x \in set (map \ \pi_1 \ xfTail)) by auto
    moreover
    {assume x = y
       from this have ((map\ (vdiff\ \circ\ \pi_1)\ ((y,\ g)\ \#\ xfTail))\otimes (\vartheta\ \#\ trmTail))\langle t_V
(\partial x)\rangle = \vartheta  by simp
      also from 3 tHyp have F t (\partial y) = g (F t) by simp
       moreover from 2 have [\![\vartheta]\!]_t (F\ t) = g\ (F\ t) by simp
       ultimately have ?thesis by (simp add: \langle x = y \rangle)
    moreover
    {assume x \neq y \land x \in set (map \ \pi_1 \ xfTail)}
       then have \partial x \neq \partial y using vdiff-inj by auto
       from this have ((map\ (vdiff\ \circ\ \pi_1)\ ((y,\ g)\ \#\ xfTail))\ \otimes\ (\vartheta\ \#\ trmTail))\ \langle t_V
       ((map\ (vdiff\ \circ \pi_1)\ xfTail)\ \otimes\ trmTail)\ \langle t_V\ (\partial\ x)\rangle\ by simp\ 
       hence ?thesis using * by simp}
    ultimately show ?thesis by blast
  next
    case False
    then have ((map\ (vdiff\ \circ \pi_1)\ ((y,\ g)\ \#\ xfTail))\ \otimes\ (\vartheta\ \#\ trmTail))\ \langle t_V\ (\partial\ x)\rangle
= t_V (\partial x)
   using substList-cross-vdiff-on-non-ocurring-var by(metis(no-types, lifting) List.map.compositionality)
    thus ?thesis by simp
  qed
qed
lemma eqInVars-impl-eqInTrms:
assumes term Vars Hyp:trm Vars \eta \subseteq (UNIV - varDiffs)
and initHyp: \forall x. \ x \notin varDiffs \longrightarrow b \ x = a \ x
shows [\![\eta]\!]_t \ a = [\![\eta]\!]_t \ b
using assms by (induction \eta, simp-all)
\mathbf{lemma}\ non\text{-}empty\text{-}funList\text{-}implies\text{-}non\text{-}empty\text{-}trmList\text{:}
shows \forall list.(x,f) \in set list \land map \ \pi_2 \ list = map \ tval \ tList \longrightarrow (\exists \ \vartheta. \llbracket \vartheta \rrbracket_t = f \land f )
\vartheta \in set\ tList)
\mathbf{by}(induction\ tList,\ auto)
\mathbf{lemma}\ dInvForTrms\text{-}prelim:
assumes substHyp:
\forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t \eta \rangle \rrbracket_t \ st = 0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
```

```
and listsHyp:map \pi_2 xfList = map tval uInput
shows \llbracket \eta \rrbracket_t \ a = 0 \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow \llbracket \eta \rrbracket_t \ c = 0)
proof(clarify)
fix c assume aHyp: \llbracket \eta \rrbracket_t \ a = 0 and cHyp: (a, c) \in ODEsystem xfList with G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t>0 \land F \ t=c \land solvesStoreIVP \ F \ xfList \ a \land (\forall r\in\{0..t\}, \ G \ (F \ r))
using guarDiffEqtn-def by auto
then have \forall x. \ x \notin varDiffs \longrightarrow F \ 0 \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t a = [\![\eta]\!]_t (F \ \theta) using term Vars Hyp \ eqIn Vars-impl-eqIn Trms
by blast
hence obs1: \llbracket \eta \rrbracket_t \ (F \ \theta) = \theta using aHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \eta]\!]_t (F r) (at r within \{0..t\}) using derivationLemma termVarsHyp by blast
have \forall r \in \{0..t\}. \forall xf \in set xfList. F r (\partial (\pi_1 xf)) = \pi_2 xf (F r)
using tcHyp solves-store-ivpD(3) by fastforce
hence \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (Fr) = [\![(map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput)\ \langle \partial_t \eta \rangle]\!]_t
using tcHyp diff-subst-prprty-4terms termVarsHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0..t\}. [(map\ (vdiff\ \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t
\eta \rangle |_t (F r) = 0
using solves-store-ivpD(2) tcHyp by fastforce
ultimately have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative 0) (at r within
\{\theta..t\}
using obs2 by auto
from this and tcHyp have \forall s \in \{0..t\}. ((\lambda x. \llbracket \eta \rrbracket_t (F x)) \text{ has-derivative } (\lambda x. x *_R x)
(at s within \{0...t\}) by (metis has-vector-derivative-def)
hence [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = (\lambda x. \ x *_R \theta) (t - \theta)
\mathbf{using}\ \mathit{mvt-very-simple}\ \mathbf{and}\ \mathit{tcHyp}\ \mathbf{by}\ \mathit{fastforce}
then show [\![\eta]\!]_t \ c = \theta using obs1 tcHyp by auto
qed
theorem dInvForTrms:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ st=0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and eta-f:f = [\![\eta]\!]_t
shows PRE (\lambda s. f s = 0) (ODEsystem xfList with G) POST (\lambda s. f s = 0)
using eta-f proof(clarsimp)
\mathbf{fix} \ a \ b
assume (a, b) \in [\lambda s. [\![\eta]\!]_t \ s = \theta] and f = [\![\eta]\!]_t
from this have aHyp: a = b \land [\![\eta]\!]_t \ a = 0 by (metis (full-types) \ d-p2r \ rdom-p2r-contents)
have [\![\eta]\!]_t \ a = \emptyset \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow [\![\eta]\!]_t \ c = \emptyset)
using assms dInvForTrms-prelim by metis
from this and aHyp have \forall c. (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow [\![\eta]\!]_t \ c =
0 by blast
thus (a, b) \in wp (ODEsystem xfList with G) \lceil \lambda s. \llbracket \eta \rrbracket_t \ s = 0 \rceil
```

```
using aHyp by (simp add: boxProgrPred-chrctrztn)
qed
\mathbf{lemma} \ \textit{diff-subst-prprty-4props} :
assumes solves: \forall xf \in set xfList. F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
and tHyp:t > 0
and listsHyp:map \pi_2 xfList = map tval uInput
and prop VarsHyp:prop Vars \varphi \subseteq (UNIV - varDiffs)
shows [\![\partial_P \varphi]\!]_P (F t) = [\![(map (vdiff \circ \pi_1) xfList) \otimes uInput)\!]_P (F t)
using prop VarsHyp apply(induction \varphi, simp-all)
using assms diff-subst-prprty-4terms apply fastforce
using assms diff-subst-prprty-4terms apply fastforce
using assms diff-subst-prprty-4terms by fastforce
\mathbf{lemma}\ dInvForProps\text{-}prelim:
assumes substHyp:
\forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ st \geq 0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
shows [\![\eta]\!]_t \ a > 0 \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow [\![\eta]\!]_t \ c > 0)
and [\![\eta]\!]_t a \geq 0 \longrightarrow (\forall \ c. \ (a,c) \in (\textit{ODEsystem xfList with } G) \longrightarrow [\![\eta]\!]_t c \geq 0)
\mathbf{proof}(clarify)
fix c assume aHyp: [\![\eta]\!]_t \ a > 0 and cHyp: (a, c) \in ODEsystem xfList with G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F t=c \land solvesStoreIVP F xfList a \land (\forall r \in \{0..t\}. G (F r))
using quarDiffEqtn-def by auto
then have \forall x. \ x \notin varDiffs \longrightarrow F \ \theta \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t a = [\![\eta]\!]_t (F \ \theta) using term Vars Hyp \ eq In Vars-impl-eq In Trms
by blast
hence obs1: [\![\eta]\!]_t (F \theta) > \theta using aHyp \ tcHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \ \eta]\!]_t \ (F \ r)) \ (at \ r \ within \ \{0..t\}) \ \mathbf{using} \ derivationLemma \ termVarsHyp \ \mathbf{by} \ blast
have (\forall t \ge 0. \ \forall \ xf \in set \ xfList. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t))
using tcHyp \ solves-store-ivpD(3) by blast
hence \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (Fr) = [\![(map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput)\ \langle \partial_t \eta \rangle]\!]_t
(F r)
using diff-subst-prprty-4terms term VarsHyp tcHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0...t\}. [((map\ (vdiff\ \circ \pi_1)\ xfList) \otimes uInput)\ \langle \partial_t
\eta \rangle |_t (F r) \geq 0
using solves-store-ivpD(2) tcHyp by (metis atLeastAtMost-iff)
ultimately have *:\forall r \in \{0..t\}. [\![\partial_t \ \eta]\!]_t \ (F \ r) \geq 0 by (simp)
from obs2 and tcHyp have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-derivative
(\lambda x. \ x *_R (\llbracket \partial_t \eta \rrbracket_t (Fr)))) (at \ r \ within \{0..t\})  by (simp \ add: has-vector-derivative-def)
hence \exists r \in \{0..t\}. [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = t \cdot ([\![(\partial_t \eta)]\!]_t) (F r)
using mvt-very-simple and tcHyp by fastforce
then obtain r where [\![\partial_t \ \eta]\!]_t (F r) \geq 0 \wedge 0 \leq r \wedge r \leq t \wedge [\![\partial_t \ \eta]\!]_t (F t) \geq 0
```

```
\wedge \ [\![\eta]\!]_t \ (F \ t) - [\![\eta]\!]_t \ (F \ \theta) = t \cdot ([\![\partial_t \ \eta]\!]_t \ (F \ r))
using * tcHyp by (meson atLeastAtMost-iff order-refl)
thus [\![\eta]\!]_t \ c > 0
using obs1 tcHyp by (metis cancel-comm-monoid-add-class.diff-cancel diff-ge-0-iff-ge
diff-strict-mono linorder-negE-linordered-idom linordered-field-class.sign-simps (45)
not-le)
next
show 0 \leq [\![\eta]\!]_t \ a \longrightarrow (\forall c. (a, c) \in ODE system xfList with <math>G \longrightarrow 0 \leq [\![\eta]\!]_t \ c)
\mathbf{fix}\ c\ \mathbf{assume}\ a\mathit{Hyp}: \llbracket \eta \rrbracket_t\ a \geq \theta\ \mathbf{and}\ c\mathit{Hyp}: (a,\ c) \in \mathit{ODEsystem}\ \mathit{xfList}\ \mathit{with}\ \mathit{G}
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F \ t = c \land solvesStoreIVP \ F \ xfList \ a \land (\forall r\in \{0..t\}. \ G \ (F \ r))
using guarDiffEqtn-def by auto
then have \forall x. \ x \notin varDiffs \longrightarrow F \ 0 \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t a = [\![\eta]\!]_t (F \ \theta) using termVarsHyp\ eqInVars-impl-eqInTrms
by blast
hence obs1: [\![\eta]\!]_t (F \theta) \ge \theta using aHyp \ tcHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \eta]\!]_t (F r) (at r within \{0..t\}) using derivationLemma termVarsHyp by blast
have (\forall t \geq 0. \ \forall \ xf \in set \ xfList. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t))
using tcHyp\ solves-store-ivpD(3) by blast
from this and tcHyp have \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) =
\llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t \eta \rangle \rrbracket_t (F\ r)
using diff-subst-prprty-4terms termVarsHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0..t\}. [((map\ (vdiff\ \circ \pi_1)\ xfList) \otimes uInput)\ (\partial_t
\eta \rangle \mathbb{I}_t (F r) > 0
using solves-store-ivpD(2) tcHyp by (metis atLeastAtMost-iff)
ultimately have *:\forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) \geq 0 by (simp)
from obs2 and tcHyp have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-derivative
(\lambda x. \ x *_R(\llbracket \partial_t \eta \rrbracket_t (Fr)))) (at \ r \ within \{0..t\}) by (simp \ add: has-vector-derivative-def)
hence \exists r \in \{0..t\}. [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = t \cdot ([\![\partial_t \eta]\!]_t (F r))
using mvt-very-simple and tcHyp by fastforce
then obtain r where [\![\partial_t \ \eta]\!]_t (F r) \geq 0 \wedge 0 \leq r \wedge r \leq t \wedge [\![\partial_t \ \eta]\!]_t (F t) \geq 0
\wedge \ [\![\eta]\!]_t \ (F \ t) - [\![\eta]\!]_t \ (F \ \theta) = t \cdot ([\![\partial_t \ \eta]\!]_t \ (F \ r))
using * tcHyp by (meson atLeastAtMost-iff order-refl)
thus [\![\eta]\!]_t \ c \geq \theta
using obs1 tcHyp by (metis cancel-comm-monoid-add-class.diff-cancel diff-ge-0-iff-ge
diff-strict-mono linorder-negE-linordered-idom linordered-field-class.siqn-simps(45)
not-le)
qed
qed
lemma less-pval-to-tval:
assumes \llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ (\vartheta \prec \eta) \upharpoonright \rrbracket_P\ st
shows \llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t\ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t\ st \geq 0
```

```
using assms by (auto)
lemma leq-pval-to-tval:
assumes \llbracket ((map \ (vdiff \circ \pi_1) \ xfList) \otimes uInput) \upharpoonright \partial_P \ (\vartheta \leq \eta) \upharpoonright \rrbracket_P \ st
shows \llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t\ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t\ st \geq 0
using assms by (auto)
lemma dInv-prelim:
assumes substHyp:\forall st. G st \longrightarrow (\forall str. str \notin (\pi_1(set xfList)) \longrightarrow st (\partial str) =
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and prop VarsHyp:prop Vars \varphi \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
shows \llbracket \varphi \rrbracket_P \ a \longrightarrow (\forall \ c. \ (a,c) \in (ODE system \ xfList \ with \ G) \longrightarrow \llbracket \varphi \rrbracket_P \ c)
proof(clarify)
fix c assume aHyp: \llbracket \varphi \rrbracket_P a and cHyp: (a, c) \in \mathit{ODEsystem} \ \mathit{xfList} \ \mathit{with} \ \mathit{G}
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F \ t=c \land solvesStoreIVP \ F \ xfList \ a \ using \ quarDiffEqtn-def
by auto
from aHyp prop VarsHyp and substHyp show \llbracket \varphi \rrbracket_P c
\mathbf{proof}(induction \ \varphi)
case (Eq \vartheta \eta)
hence hyp: \forall st. \ G \ st \longrightarrow \ (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ (\vartheta \doteq \eta) \upharpoonright \rrbracket_P\ st\ \mathbf{by}\ blast
then have \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList))) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\langle \partial_t\ (\vartheta\ \oplus\ (\ominus\ \eta))\rangle \rrbracket_t\ st=\ 0\ \ \mathbf{by}\ simp
also have trmVars\ (\vartheta \oplus (\ominus \eta)) \subseteq UNIV - varDiffs\ using\ Eq.prems(2) by simp
moreover have [\![\vartheta \oplus (\ominus \eta)]\!]_t a = \theta using Eq.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![\vartheta \oplus (\ominus \eta)]\!]_t \ c =
using dInvForTrms-prelim listsHyp by blast
hence [\![\vartheta \oplus (\ominus \eta)]\!]_t (F t) = \theta using tcHyp \ cHyp by simp
from this have [\![\vartheta]\!]_t (F t) = [\![\eta]\!]_t (F t) by simp
also have (\llbracket \vartheta \doteq \eta \rrbracket_P) c = (\llbracket \vartheta \rrbracket_t (F t) = \llbracket \eta \rrbracket_t (F t)) using tcHyp by simp
ultimately show ?case by simp
next
case (Less \vartheta \eta)
hence \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
0 \leq (\llbracket (\mathit{map}\ (\mathit{vdiff}\ \circ\ \pi_1)\ \mathit{xfList}\ \otimes\ \mathit{uInput}) \langle \partial_t\ (\eta\ \oplus\ (\ominus\ \vartheta)) \rangle \rrbracket_t)\ \mathit{st}
using less-pval-to-tval by metis
also from Less.prems(2) have trmVars\ (\eta \oplus (\ominus \vartheta)) \subseteq UNIV - varDiffs by simp
moreover have [\![ \eta \oplus (\ominus \vartheta) ]\!]_t \ a > \theta using Less.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![ \eta \oplus (\ominus \vartheta) ]\!]_t \ c >
using dInvForProps-prelim(1) listsHyp by blast
hence [\eta \oplus (\ominus \vartheta)]_t (F t) > \theta using tcHyp \ cHyp \ by \ simp
from this have [\![\eta]\!]_t (F t) > [\![\vartheta]\!]_t (F t) by simp
also have [\![\vartheta \prec \eta]\!]_P c = ([\![\vartheta]\!]_t (Ft) < [\![\eta]\!]_t (Ft)) using tcHyp by simp
ultimately show ?case by simp
```

```
next
case (Leq \vartheta \eta)
hence \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
0 \leq (\llbracket (map \ (vdiff \circ \pi_1) \ xfList \otimes uInput) \langle \partial_t \ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t) \ st \ using \ leq-pval-to-tval
by metis
also from Leq.prems(2) have trmVars(\eta \oplus (\ominus \vartheta)) \subseteq UNIV - varDiffs by simp
moreover have [\eta \oplus (\ominus \vartheta)]_t a \ge \theta using Leq.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![ \eta \oplus (\ominus \vartheta) ]\!]_t \ c \geq
\theta
using dInvForProps-prelim(2) listsHyp by blast
hence [\eta \oplus (\ominus \vartheta)]_t (F t) \ge \theta using tcHyp \ cHyp \ by \ simp
from this have (\llbracket \eta \rrbracket_t (F t) \geq \llbracket \vartheta \rrbracket_t (F t)) by simp
also have [\![\vartheta \preceq \eta]\!]_P c = ([\![\vartheta]\!]_t (Ft)) \leq [\![\eta]\!]_t (Ft) using tcHyp by simp
ultimately show ?case by simp
next
case (And \varphi 1 \varphi 2)
then show ?case by (simp)
next
case (Or \varphi 1 \varphi 2)
from this show ?case by auto
qed
theorem dInv:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList))) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and termVarsHyp:propVars \varphi \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and phi-p:P = [\![\varphi]\!]_P
shows PRE P (ODEsystem xfList with G) POST P
proof(clarsimp)
\mathbf{fix} \ a \ b
assume (a, b) \in [P]
from this have aHyp:a = b \land P a by (metis\ (full-types)\ d-p2r\ rdom-p2r-contents)
have P \ a \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow P \ c)
using assms dInv-prelim by metis
from this and a Hyp have \forall c. (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow P \ c by
thus (a, b) \in wp \ (ODEsystem \ xfList \ with \ G \ ) \ [P]
using aHyp by (simp add: boxProgrPred-chrctrztn)
qed
theorem dInvFinal:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and term Vars Hyp: prop Vars \varphi \subseteq (UNIV - var Diffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and impls: [P] \subseteq [F] \land [F] \subseteq [Q]
and phi-f:F = [\![\varphi]\!]_P
```

```
shows PRE P (ODEsystem xfList with G) POST Q
\operatorname{apply}(rule\text{-}tac\ C=\llbracket\varphi\rrbracket_P\ \mathbf{in}\ dCut)
apply(subgoal-tac [F] \subseteq wp (ODEsystem xfList with G) [F], simp)
using impls and phi-f apply blast
apply(subgoal-tac PRE F (ODEsystem xfList with G) POST F, simp)
apply(rule-tac \varphi = \varphi and uInput = uInput in dInv)
prefer 5 apply(subgoal-tac PRE P (ODEsystem xfList with (\lambda s. G s \wedge F s))
POST Q, simp add: phi-f)
apply(rule\ dWeakening)
using impls apply simp
using assms by simp-all
end
theory VC-diffKAD-examples
imports VC-diffKAD
begin
5.4.5
          Rules Testing
In this section we test the recently developed rules with simple dynamical
systems.
— Example of hybrid program verified with the rule dSolve and a single differential
equation: x' = v.
lemma motion-with-constant-velocity:
     PRE (\lambda s. s "y" < s "x" \wedge s "v" > 0)
     (ODE system [("x", (\lambda s. s "v"))] with (\lambda s. True))
     POST (\lambda s. (s "y" < s "x"))
apply(rule-tac uInput=[\lambda \ t \ s. \ s''v'' \cdot t + s''x''] in dSolve-toSolveUBC)
prefer 9 subgoal by(simp add: wp-trafo vdiff-def add-strict-increasing2)
apply(simp-all add: vdiff-def varDiffs-def)
prefer 2 apply(simp add: solvesStoreIVP-def vdiff-def varDiffs-def)
apply(clarify, rule-tac f'1=\lambda x. s''v'' and g'1=\lambda x. \theta in derivative-intros(191))
apply(rule-tac f'1=\lambda x.0 and g'1=\lambda x.1 in derivative-intros(194))
by(auto intro: derivative-intros)
Same hybrid program verified with dSolve and the system of ODEs: x' =
v, v' = a. The uniqueness part of the proof requires a preliminary lemma.
lemma flow-vel-is-galilean-vel:
assumes solHyp:\varphi_s solvesTheStoreIVP [(x, \lambda s.\ s\ v), (v, \lambda s.\ s\ a)] withInitState\ s
   and tHyp:r \leq t and rHyp:0 \leq r and distinct:x \neq v \land v \neq a \land x \neq a \land a \notin s
varDiffs
shows \varphi_s r v = s a \cdot r + s v
proof-
from assms have 1:((\lambda t. \varphi_s t v) solves-ode (\lambda t r. \varphi_s t a)) {0..t} UNIV \wedge \varphi_s \theta
```

by (simp add: solvesStoreIVP-def)

from assms have obs: $\forall r \in \{0..t\}$. $\varphi_s r a = s a$

```
by(auto simp: solvesStoreIVP-def varDiffs-def)
have 2:((\lambda t. \ s \ a \cdot t + s \ v) \ solves-ode \ (\lambda t \ r. \ \varphi_s \ t \ a)) \ \{0..t\} \ UNIV
  unfolding solves-ode-def apply(subgoal-tac ((\lambda x. s. a. x + s. v)) has-vderiv-on
(\lambda x. \ s \ a)) \ \{\theta..t\})
  using obs apply (simp add: has-vderiv-on-def) by(rule galilean-transform)
have 3:unique-on-bounded-closed 0 \{0..t\} (s v) (\lambda t r. \varphi_s t a) UNIV (if t = 0 then
1 else 1/(t+1)
  apply(simp add: ubc-definitions del: comp-apply, rule conjI)
   using rHyp \ tHyp \ obs \ apply(simp-all \ del: \ comp-apply)
  apply(clarify, rule continuous-intros) prefer 3 apply safe
  apply(rule\ continuous-intros)
  apply(auto intro: continuous-intros)
  by (metis continuous-on-const continuous-on-eq)
thus \varphi_s r v = s a \cdot r + s v
  \mathbf{apply}(\textit{rule-tac unique-on-bounded-closed.unique-solution}[\textit{of } 0\ \{0..t\}\ \textit{s v}
   (\lambda t \ r. \ \varphi_s \ t \ a) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1 \ / \ (t + 1)) \ (\lambda t. \ \varphi_s \ t \ v)])
   using rHyp \ tHyp \ 1 \ 2 and 3 by auto
qed
{\bf lemma}\ motion\hbox{-}with\hbox{-}constant\hbox{-}acceleration\colon
      PRE (\lambda s. s "y" < s "x" \land s "v" \ge 0 \land s "a" > 0)
      (\textit{ODEsystem}\ [("x", (\lambda\ s.\ s\ "v")), ("v", (\lambda\ s.\ s\ "a"))]\ \textit{with}\ (\lambda\ s.\ \textit{True}))
      POST \ (\lambda \ s. \ (s \ ''y'' < s \ ''x''))
apply(rule-tac uInput=[\lambda \ t \ s. \ s \ "a" \cdot t \ \hat{2}/2 + s \ "v" \cdot t + s \ "x",
  \lambda \ t \ s. \ s \ ''a'' \cdot t + s \ ''v'' in dSolve-toSolveUBC)
prefer 9 subgoal by(simp add: wp-trafo vdiff-def add-strict-increasing2)
prefer \theta subgoal
    apply(simp add: vdiff-def, clarify, rule conjI)
    by(rule qalilean-transform)+
prefer 6 subgoal
    apply(simp add: vdiff-def, safe)
    \mathbf{by}(rule\ continuous\text{-}intros)+
prefer \theta subgoal
    apply(simp add: vdiff-def, safe)
    subgoal for s \varphi_s t r apply(rule flow-vel-is-galilean-vel[of \varphi_s "x" - - - - t])
      by(simp-all add: varDiffs-def vdiff-def)
    apply(simp add: solvesStoreIVP-def vdiff-def varDiffs-def) done
by(auto simp: varDiffs-def vdiff-def)
Example of a hybrid system with two modes verified with the equality dS.
We also need to provide a previous (similar) lemma.
\mathbf{lemma}\ \mathit{flow-vel-is-galilean-vel2}\colon
assumes solHyp:\varphi_s solvesTheStoreIVP [(x, \lambda s. s. v), (v, \lambda s. - s. a)] withInitState
    and tHyp:r \leq t and rHyp:0 \leq r and distinct:x \neq v \land v \neq a \land x \neq a \land a \notin s
varDiffs
shows \varphi_s \ r \ v = s \ v - s \ a \cdot r
proof-
from assms have 1:((\lambda t. \varphi_s t v) solves-ode (\lambda t r. - \varphi_s t a)) {0..t} UNIV \wedge \varphi_s
```

```
0 \ v = s \ v
 by (simp add: solvesStoreIVP-def)
from assms have obs: \forall r \in \{0..t\}. \varphi_s r a = s a
 by(auto simp: solvesStoreIVP-def varDiffs-def)
have 2:((\lambda t. - s \ a \cdot t + s \ v) \ solves-ode \ (\lambda t \ r. - \varphi_s \ t \ a)) \ \{0..t\} \ UNIV
 unfolding solves-ode-def apply(subgoal-tac ((\lambda x. - s \ a \cdot x + s \ v)) has-vderiv-on
(\lambda x. - s \ a)) \ \{0..t\})
  using obs apply (simp add: has-vderiv-on-def) by(rule galilean-transform)
have 3:unique-on-bounded-closed 0 \{0..t\} (s\ v)\ (\lambda t\ r. - \varphi_s\ t\ a)\ UNIV\ (if\ t=0)
then 1 else 1/(t+1)
  apply(simp add: ubc-definitions del: comp-apply, rule conjI)
  using rHyp tHyp obs apply(simp-all del: comp-apply)
  apply(clarify, rule continuous-intros) prefer 3 apply safe
  apply(rule continuous-intros)+
  apply(auto intro: continuous-intros)
  by (metis continuous-on-const continuous-on-eq)
thus \varphi_s r v = s v - s a \cdot r
  apply(rule-tac\ unique-on-bounded-closed.unique-solution[of\ 0\ \{0..t\}\ s\ v
  (\lambda t \ r. - \varphi_s \ t \ a) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1 \ / \ (t + 1)) \ (\lambda t. \ \varphi_s \ t \ v)])
  using rHyp tHyp 1 2 and 3 by auto
lemma single-hop-ball:
     PRE \ (\lambda \ s. \ 0 \le s \ ''x'' \land s \ ''x'' = H \land s \ ''v'' = 0 \land s \ ''g'' > 0 \land 1 \ge c \land c
     (((ODEsystem [("x", \lambda s. s"v"), ("v", \lambda s. - s"g")] with (\lambda s. 0 \le s "x")));
     (IF (\lambda s. s "x" = 0) THEN ("v" := (\lambda s. - c \cdot s "v")) ELSE ("v" := (\lambda s. - c \cdot s "v"))
s. \ s \ ''v'')) \ FI))
     POST \ (\lambda \ s. \ 0 < s \ "x" \land s \ "x" < H)
     apply(simp, subst dS[of [\lambda t s. - s "g" · t ^{\circ} 2/2 + s "v" · t + s "x", \lambda t
s.\,-\,s\,\,^{\prime\prime}g^{\,\prime\prime}\cdot\,t\,+\,s\,\,^{\prime\prime}v^{\,\prime\prime}]])
      — Given solution is actually a solution.
    apply(simp\ add:\ vdiff-def\ varDiffs-def\ solvesStoreIVP-def\ solves-ode-def\ has-vderiv-on-singleton,
safe)
     apply(rule\ galilean-transform-eq,\ simp)+
     apply(rule\ galilean-transform)+

    Uniqueness of the flow.

     apply(rule ubcStoreUniqueSol, simp)
     apply(simp add: vdiff-def del: comp-apply)
     apply(auto intro: continuous-intros del: comp-apply)[1]
     apply(rule continuous-intros)+
     apply(simp\ add:\ vdiff-def,\ safe)
     apply(clarsimp) subgoal for s X t \tau
     \mathbf{apply}(\mathit{rule\ flow-vel-is-galilean-vel2}[\mathit{of\ X\ ''x''}])
     by(simp-all add: varDiffs-def vdiff-def)
     apply(simp add: vdiff-def varDiffs-def solvesStoreIVP-def)
     apply(simp add: vdiff-def varDiffs-def solvesStoreIVP-def solves-ode-def
       has-vderiv-on-singleton galilean-transform-eq galilean-transform)
       - Relation Between the guard and the postcondition.
```

by(auto simp: vdiff-def p2r-def)

```
— Example of hybrid program verified with differential weakening.
\mathbf{lemma}\ system\text{-}where\text{-}the\text{-}guard\text{-}implies\text{-}the\text{-}postcondition}:
      PRE (\lambda s. s''x'' = 0)
      (ODEsystem [("x",(\lambda s. s "x" + 1))] with (\lambda s. s "x" \ge 0))
      POST (\lambda s. s''x'' > 0)
using dWeakening by blast
lemma system-where-the-quard-implies-the-postcondition 2:
      PRE (\lambda s. s''x'' = 0)
      (ODEsystem [("x",(\lambda s. s "x" + 1))] with (\lambda s. s "x" \geq 0))
      POST \ (\lambda \ s. \ s \ "x" \ge 0)
apply(clarify, simp add: p2r-def)
apply(simp add: rel-ad-def rel-antidomain-kleene-algebra.addual.ars-r-def)
apply(simp add: rel-antidomain-kleene-algebra.fbox-def)
apply(simp add: relcomp-def rel-ad-def guarDiffEqtn-def solvesStoreIVP-def)
by auto
— Example of system proved with a differential invariant.
lemma circular-motion:
      PRE \ (\lambda \ s. \ (s \ ''x'') \cdot (s \ ''x'') + (s \ ''y'') \cdot (s \ ''y'') - (s \ ''r'') \cdot (s \ ''r'') = 0)
      (ODE system [("x",(\lambda s. s "y")),("y",(\lambda s. - s "x"))] with G)
      POST \ (\lambda \ s. \ (s \ ''x'') \cdot (s \ ''x'') + (s \ ''y'') \cdot (s \ ''y'') - (s \ ''r'') \cdot (s \ ''r'') = 0)
\mathbf{apply}(\textit{rule-tac}\ \eta = (t_V \ ''x'') \odot (t_V \ ''x'') \oplus (t_V \ ''y'') \odot (t_V \ ''y'') \oplus (\ominus (t_V \ ''r'') \odot (t_V \ ''y'')))
"r"))
 and uInput=[t_V "y", \ominus (t_V "x")] in dInvForTrms)
apply(simp-all add: vdiff-def varDiffs-def)
apply(clarsimp, erule-tac x=''r'' in allE)
bv simp
— Example of systems proved with differential invariants, cuts and weakenings.
declare d-p2r [simp del]
\mathbf{lemma}\ motion\text{-}with\text{-}constant\text{-}velocity\text{-}and\text{-}invariants:
      PRE (\lambda s. s "x" > s "y" \wedge s "v" > 0)
      (ODE system [("x", \lambda s. s "v")] with (\lambda s. True))
      POST (\lambda s. s "x" > s "y")
apply(rule-tac C = \lambda \ s. \ s''v'' > 0 \ in \ dCut)
apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ "v") and uInput=[t_V \ "v"]in dInvFinal)
apply(simp-all add: vdiff-def varDiffs-def, clarify, erule-tac x=''v'' in allE, simp)
\mathbf{apply}(\textit{rule-tac } C = \lambda \textit{ s. } s \textit{ "x"} > s \textit{ "y"} \mathbf{in } \textit{ dCut})
apply(rule-tac \varphi=(t_V "y") \prec (t_V "x") and uInput=[t_V "v"] and
  F = \lambda \ s. \ s \ ''x'' > s \ ''y''  in dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x=''y''\ in\ all E,\ simp)
using dWeakening by simp
{\bf lemma}\ motion\hbox{-}with\hbox{-}constant\hbox{-}acceleration\hbox{-}and\hbox{-}invariants:
      PRE \ (\lambda \ s. \ s \ ''y'' < s \ ''x'' \ \land s \ ''v'' \ge 0 \ \land s \ ''a'' > 0)
      (ODE system [("x",(\lambda s. s "v")),("v",(\lambda s. s "a"))] with (\lambda s. True))
```

```
POST (\lambda s. (s "y" < s "x"))
apply(rule-tac C = \lambda \ s. \ s \ ''a'' > 0 \ in \ dCut)
apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ ''a'') and uInput = [t_V \ ''v'', t_V \ ''a'']in dInvFinal)
\mathbf{apply}(simp\text{-}all\ add:\ vdiff\text{-}def\ varDiffs\text{-}def,\ clarify,\ erule\text{-}tac\ x=''a''\ \mathbf{in}\ allE,\ simp)
apply(rule-tac\ C = \lambda\ s.\ s\ ''v'' \ge 0\ in\ dCut)
apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ ''v'') and uInput = [t_V \ ''v'', t_V \ ''a''] in dInvFi
nal
apply(simp-all add: vdiff-def varDiffs-def)
apply(rule-tac\ C = \lambda\ s.\ s\ ''x'' > s\ ''y''\ in\ dCut)
apply(rule-tac \varphi = (t_V "y") \prec (t_V "x") and uInput = [t_V "v", t_V "a"]in dInv-
Final)
apply(simp-all\ add:\ varDiffs-def\ vdiff-def\ ,\ clarify,\ erule-tac\ x=''y''\ in\ all E\ ,\ simp)
using dWeakening by simp
— We revisit the two modes example from before, and prove it with invariants.
{f lemma}\ single-hop-ball-and-invariants:
      PRE (\lambda s. 0 < s "x" \wedge s "x" = H \wedge s "v" = 0 \wedge s "q" > 0 \wedge 1 > c \wedge c
     (((ODE system \ [(''x'', \lambda \ s. \ s \ ''v''), (''v'', \lambda \ s. - s \ ''g'')] \ with \ (\lambda \ s. \ 0 \le s \ ''x'')));
      (IF (\lambda s. s "x" = 0) THEN ("v" := (\lambda s. - c \cdot s "v")) ELSE ("v" := (\lambda s. - c \cdot s "v"))
s. s "v") FI)
      POST (\lambda s. 0 < s "x" \wedge s "x" < H)
      apply(simp add: d-p2r, subgoal-tac rdom [\lambda s. \ 0 \le s \ ''x'' \land s \ ''x'' = H \land s
"v" = 0 \land 0 < s "g" \land c \le 1 \land 0 \le c
   \subseteq wp \ (ODEsystem \ [("x", \lambda s. s "v"), ("v", \lambda s. - s "g")] \ with \ (\lambda s. \theta \leq s "x")
        [inf (sup (-(\lambda s. s "x" = 0)) (\lambda s. 0 \le s "x" \wedge s "x" \le H)) (sup (\lambda s. s = 0))
"x" = 0) (\lambda s. \ 0 < s \ "x" \wedge s \ "x" < H))])
      apply(simp add: d-p2r, rule-tac C = \lambda s. s''q'' > 0 in dCut)
      apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ ''g'') and uInput = [t_V \ ''v'', \ominus t_V \ ''g'']in
dInvFinal)
      apply(simp-all add: vdiff-def varDiffs-def, clarify, erule-tac x=''g'' in all E,
      apply(rule-tac C = \lambda \ s. \ s \ "v" \le \theta \ in \ dCut)
      apply(rule-tac \varphi = (t_V "v") \preceq (t_C \ \theta) and uInput = [t_V "v", \ominus t_V "g"] in
      apply(simp-all add: vdiff-def varDiffs-def)
      apply(rule-tac C = \lambda \ s. \ s''x'' \le H \ in \ dCut)
      apply(rule-tac \varphi = (t_V "x") \leq (t_C H) and uInput = [t_V "v", \ominus t_V "g"]in
dInvFinal)
      apply(simp-all add: varDiffs-def vdiff-def)
      using dWeakening by simp
— Finally, we add a well known example in the hybrid systems community, the
bouncing ball.
lemma bouncing-ball-invariant:0 \le x \Longrightarrow 0 < g \Longrightarrow 2 \cdot g \cdot x = 2 \cdot g \cdot H - v \cdot g \Longrightarrow 0
v \Longrightarrow (x::real) \leq H
proof-
assume 0 \le x and 0 < g and 2 \cdot g \cdot x = 2 \cdot g \cdot H - v \cdot v
```

end

```
then have v \cdot v = 2 \cdot g \cdot H - 2 \cdot g \cdot x \wedge 0 < g by auto
hence *:v \cdot v = 2 \cdot g \cdot (H - x) \wedge 0 < g \wedge v \cdot v \geq 0
  using left-diff-distrib mult.commute by (metis zero-le-square)
from this have (v \cdot v)/(2 \cdot g) = (H - x) by auto
also from * have (v \cdot v)/(2 \cdot g) \geq 0
by (meson divide-nonneq-pos linordered-field-class.siqn-simps(44) zero-less-numeral)
ultimately have H - x \ge 0 by linarith
thus ?thesis by auto
qed
lemma bouncing-ball:
PRE \ (\lambda \ s. \ 0 \le s \ ''x'' \land s \ ''x'' = H \land s \ ''v'' = 0 \land s \ ''g'' > 0)
((ODEsystem [("x", \lambda s. s "v"),("v",\lambda s. - s "g")] with (\lambda s. \theta \leq s "x"));
(IF (\lambda s. s "x" = 0) THEN ("v" ::= (\lambda s. - s "v")) ELSE (Id) FI))^*
POST \ (\lambda \ s. \ 0 \le s \ "x" \land s \ "x" \le H)
\mathbf{apply}(\textit{rule rel-antidomain-kleene-algebra.fbox-starI} | \textit{of -} \lceil \lambda s. \ \textit{0} \leq s \ \textit{"x"} \land \ \textit{0} < s
2 \cdot s ''g'' \cdot s ''x'' = 2 \cdot s ''g'' \cdot H - (s ''v'' \cdot s ''v'')]])
apply(simp, simp \ add: \ d-p2r)
apply(subgoal-tac
  rdom \ \lceil \lambda s. \ 0 \le s \ ''x'' \land 0 < s \ ''g'' \land 2 \cdot s \ ''g'' \cdot s \ ''x'' = 2 \cdot s \ ''g'' \cdot H - s
"v" \cdot s "v"
  \subseteq wp \ (ODEsystem \ [("x", \lambda s. \ s "v"), ("v", \lambda s. - s "g")] \ with \ (\lambda s. \ 0 \le s "x")
  [inf (sup (-(\lambda s. s "x" = 0)) (\lambda s. 0 \le s "x" \wedge 0 < s "g" \wedge 2 \cdot s "g" \cdot s "x"]
           2 \cdot s ''g'' \cdot H - s ''v'' \cdot s ''v''))
         (sup (\lambda s. s "x" = 0) (\lambda s. 0 < s "x" \wedge 0 < s "q" \wedge 2 \cdot s "q" \cdot s "x" =
           2 \cdot s ''q'' \cdot H - s''v'' \cdot s ''v'')
apply(simp\ add:\ d-p2r)
apply(rule-tac C = \lambda \ s. \ s \ ''g'' > \theta \ in \ dCut)
apply(rule-tac \varphi = ((t_C \ \theta) \prec (t_V \ ''g'')) and uInput = [t_V \ ''v'', \ominus t_V \ ''g'']in
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x=''g''\ in\ allE,\ simp)
\mathbf{apply}(\textit{rule-tac } C = \lambda \ \textit{s. 2} \cdot \textit{s} \ ''g'' \cdot \textit{s} \ ''x'' = 2 \cdot \textit{s} \ ''g'' \cdot \textit{H} - \textit{s} \ ''v'' \cdot \textit{s} \ ''v'' \text{ in}
dCut)
\mathbf{apply}(\textit{rule-tac}\ \varphi = (t_C\ 2)\ \odot\ (t_V\ ''g'')\ \odot\ (t_C\ H)\ \oplus\ (\ominus\ ((t_V\ ''v'')\ \odot\ (t_V\ ''v'')))
 \doteq (t_C \ 2) \odot (t_V \ ''g'') \odot (t_V \ ''x'') and uInput = [t_V \ ''v'', \ominus t_V \ ''g'']in dInvFinal)
\mathbf{apply}(simp\text{-}all\ add\colon vdiff\text{-}def\ varDiffs\text{-}def\ ,\ clarify\ ,\ erule\text{-}tac\ x=''g''\ \mathbf{in}\ all E\ ,\ simp)
apply(rule dWeakening, clarsimp)
using bouncing-ball-invariant by auto
declare d-p2r [simp]
```