## CPSVerification

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July 4, 2019

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begin

### Chapter 1

# Hybrid Systems Preliminaries

This chapter contains preliminary lemmas for verification of Hybrid Systems.

#### 1.1 Miscellaneous

#### 1.1.1 Functions

#### 1.1.2 Orders

```
lemma cSup-eq-linorder:
 {\bf fixes} \ c::'a::conditionally\text{-}complete\text{-}linorder
 assumes X \neq \{\} and \forall x \in X. x \leq c
   and bdd-above X and \forall y < c. \exists x \in X. y < x
 shows Sup X = c
 apply(rule\ order-antisym)
 using assms apply(simp add: cSup-least)
 using assms by (subst le-cSup-iff)
lemma cSup-eq:
  \mathbf{fixes}\ c{::}'a{::}conditionally{-}complete{-}lattice
 \textbf{assumes} \ \forall \, x \in X. \ x \leq c \ \textbf{and} \ \exists \, x \in X. \ c \leq x
 shows Sup X = c
 apply(rule order-antisym)
  apply(rule\ cSup\ -least)
  using assms apply(blast, blast)
  using assms(2) apply safe
```

```
apply(subgoal-tac\ x \leq Sup\ X,\ simp)
 by (metis\ assms(1)\ cSup-eq-maximum\ eq-iff)
\mathbf{lemma}\ bdd-above-ltimes:
 fixes c::'a::linordered-ring-strict
 assumes c > \theta and bdd-above X
 shows bdd-above \{c * x | x. x \in X\}
 using assms unfolding bdd-above-def apply clarsimp
 apply(rule-tac \ x=c*M \ in \ exI, \ clarsimp)
 using mult-left-mono by blast
lemma finite-nat-minimal-witness:
 fixes P :: ('a::finite) \Rightarrow nat \Rightarrow bool
 assumes \forall i. \exists N :: nat. \forall n \geq N. P i n
 shows \exists N. \ \forall i. \ \forall n \geq N. \ P \ i \ n
proof-
 let ?bound i = (LEAST\ N.\ \forall\ n \geq N.\ P\ i\ n)
 let ?N = Max \{?bound \ i \mid i.i \in UNIV\}
 {fix n::nat and i::'a
   obtain M where \forall n \geq M. P i n
     using assms by blast
   hence obs: \forall m \geq ?bound i. P i m
     using LeastI[of \lambda N. \forall n \geq N. P(i, n] by blast
   assume n \geq ?N
   have finite \{?bound\ i\ | i.\ i\in UNIV\}
     using finite-Atleast-Atmost-nat by fastforce
   hence ?N \ge ?bound i
     using Max-ge by blast
   hence n > ?bound i
     using \langle n \geq ?N \rangle by linarith
   hence P i n
     using obs by blast}
 thus \exists N. \ \forall i \ n. \ N \leq n \longrightarrow P \ i \ n
   by blast
qed
1.1.3
          Real Numbers
lemma sqrt-le-itself: 1 \le x \Longrightarrow sqrt \ x \le x
 by (metis basic-trans-rules (23) monoid-mult-class.power2-eq-square more-arith-simps (6)
     mult-left-mono real-sqrt-le-iff 'zero-le-one)
lemma sqrt-real-nat-le:sqrt (real n) \le real n
 by (metis (full-types) abs-of-nat le-square of-nat-mono of-nat-mult real-sqrt-abs2
real-sqrt-le-iff)
lemma sq-le-cancel:
```

**shows**  $(a::real) \ge 0 \Longrightarrow b \ge 0 \Longrightarrow a^2 \le b * a \Longrightarrow a \le b$ 

1.2. CALCULUS 7

```
and (a::real) \ge 0 \Longrightarrow b \ge 0 \Longrightarrow a^2 \le a * b \Longrightarrow a \le b
    apply(metis\ less-eq\ real-def\ mult.commute\ mult-le-cancel-left\ semiring-normalization-rules (29))
    by (metis less-eq-real-def mult-le-cancel-left semiring-normalization-rules (29))
named-theorems triq-simps simplification rules for trigonometric identities
\textbf{lemmas} \ trig-identities = sin-squared-eq[\textit{THEN} \ sym] \ cos-squared-eq[\textit{symmetric}] \ cos-diff[\textit{symmetric}]
cos-double
declare sin-minus [trig-simps]
        and cos-minus [trig-simps]
        and trig-identities (1,2) [trig-simps]
        and sin-cos-squared-add [trig-simps]
        and sin-cos-squared-add2 [trig-simps]
        and sin-cos-squared-add3 [trig-simps]
        and trig-identities(3) [trig-simps]
lemma sin-cos-squared-add4 [trig-simps]:
    fixes x :: 'a :: \{banach, real-normed-field\}
    shows x * (sin t)^2 + x * (cos t)^2 = x
   by (metis mult.right-neutral semiring-normalization-rules (34) sin-cos-squared-add)
lemma [trig-simps, simp]:
    fixes x :: 'a :: \{banach, real-normed-field\}
    shows (x * cos t - y * sin t)^2 + (x * sin t + y * cos t)^2 = x^2 + y^2
proof-
    have (x * cos t - y * sin t)^2 = x^2 * (cos t)^2 + y^2 * (sin t)^2 - 2 * (x * cos t)
*(y*sin t)
        by(simp add: power2-diff power-mult-distrib)
    also have (x * \sin t + y * \cos t)^2 = y^2 * (\cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (\sin t)^2 + 2 * (x * \cos t)^2 + x^2 * (x
cos\ t)*(y*sin\ t)
        \mathbf{by}(simp~add:~power2\text{-}sum~power\text{-}mult\text{-}distrib)
    ultimately show (x * cos t - y * sin t)^2 + (x * sin t + y * cos t)^2 = x^2 + y^2
     by (simp\ add:\ Groups.mult-ac(2)\ Groups.mult-ac(3)\ right-diff-distrib\ sin-squared-eq)
qed
```

#### 1.2 Calculus

thm trig-simps

#### 1.2.1 Single variable Derivatives

```
notation has-derivative ((1(D - \mapsto (-))/ -) [65,65] 61) notation has-vderiv-on ((1 D - = (-)/ on -) [65,65] 61) notation norm ((1||-||) [65] 61)
```

 $\mathbf{lemma}\ \mathit{closed\text{-}segment\text{-}mvt}\colon$ 

```
fixes f :: real \Rightarrow real
 assumes ( \land r. \ r \in \{a - b\} \Longrightarrow (D \ f \mapsto (f' \ r) \ (at \ r \ within \ \{a - b\}))) and a \le b
 shows \exists r \in \{a - -b\}. f b - f a = f' r (b - a)
 using assms closed-segment-eq-real-ivl mvt-very-simple by auto
lemma exp-scaleR-has-derivative-right[derivative-intros]:
 fixes f::real \Rightarrow real
 assumes D f \mapsto f' at x within s and (\lambda h. f' h *_R (exp (f x *_R A) * A)) = g'
 shows D(\lambda x. exp(fx *_R A)) \mapsto g' at x within s
proof -
 from assms have bounded-linear f' by auto
 with real-bounded-linear obtain m where f': f' = (\lambda h. h * m) by blast
 show ?thesis
   \mathbf{using}\ vector\ diff\ chain\ within\ OF\ -\ exp\ -scale\ R\ -has\ -vector\ -derivative\ -right,\ of\ f
m \ x \ s \ A] \ assms \ f'
   by (auto simp: has-vector-derivative-def o-def)
qed
named-theorems poly-derivatives compilation of derivatives for kinematics and
polynomials.
declare has-vderiv-on-const [poly-derivatives]
lemma has-vector-derivative-mult-const: ((*) a has-vector-derivative a) (at x within
T
 by (auto intro: derivative-eq-intros)
lemma has-derivative-mult-const: D (*) a \mapsto (\lambda x. x *_{B} a) at x within T
  using has-vector-derivative-mult-const unfolding has-vector-derivative-def by
simp
lemma has-derivative-quadratic-monomial:
 fixes a :: real
 shows D(\lambda t. \ a * t^2) \mapsto (\lambda t. \ a * (2 * x * t)) \ at \ x \ within \ T
 apply(rule-tac g'1=\lambda t. 2 * x * t in derivative-eq-intros(6))
  apply(rule-tac f'1=\lambda t. t in derivative-eq-intros(15))
 by (auto intro: derivative-eq-intros)
lemma has-derivative-quadratic-monomial-halfed:
 fixes a :: real
 shows D(\lambda t. \ a * t^2 / 2) \mapsto (*) (a * x) \ at \ x \ within \ T
 apply(rule-tac f'1=\lambda t. a*(2*x*t) and g'1=\lambda x. 0 in derivative-eq-intros(18))
 using has-derivative-quadratic-monomial by auto
lemma [poly-derivatives]: D(\lambda t. \ a * t^2 / 2) = (*) \ a \ on \ T
 apply(simp add: has-vderiv-on-def has-vector-derivative-def, clarify)
 using has-derivative-quadratic-monomial-halfed by (simp add: mult-commute-abs)
```

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```
lemma [poly-derivatives]: D(\lambda t. \ a * t^2 / 2 + v * t + x) = (\lambda t. \ a * t + v) \ on \ T
 apply(rule-tac f'=\lambda x. a*x+v and g'1=\lambda x. \theta in derivative-intros(191))
   apply(rule-tac f'1=\lambda x. \ a*x \ and \ g'1=\lambda x. \ v \ in \ derivative-intros(191))
 using poly-derivatives(2) by(auto intro: derivative-intros)
lemma [poly-derivatives]: D(\lambda r. a * r + v) = (\lambda t. a) on T
 apply(rule-tac f'1=\lambda x. a and g'1=\lambda x. 0 in derivative-intros(191))
 unfolding has-vderiv-on-def by(auto intro: derivative-eq-intros)
lemma [poly-derivatives]: D(\lambda t. v * t - a * t^2 / 2 + x) = (\lambda x. v - a * x) on T
 apply(subgoal-tac D (\lambda t. -a * t^2 / 2 + v * t + x) = (\lambda x. -a * x + v) on T,
simp)
 \mathbf{by}(rule\ poly\text{-}derivatives)
lemma [poly-derivatives]: D(\lambda t. v - a * t) = (\lambda x. - a) on T
 apply(subgoal-tac D (\lambda t. - a * t + v) = (\lambda x. - a) on T, simp)
 \mathbf{by}(rule\ poly\text{-}derivatives)
declare has-derivative-mult-const [poly-derivatives]
   and has-derivative-quadratic-monomial [poly-derivatives]
   and has-derivative-quadratic-monomial-halfed [poly-derivatives]
lemma [poly-derivatives]:
 assumes t \in T
 shows D(\lambda \tau. \ a * \tau^2 / 2 + v * \tau + x) \mapsto (\lambda x. \ x *_R (a * t + v)) at t within T
 using assms poly-derivatives unfolding has-vderiv-on-def has-vector-derivative-def
by simp
```

thm poly-derivatives

#### 1.2.2 Multivariable Derivatives

```
lemma eventually-all-finite2:
 fixes P :: ('a::finite) \Rightarrow 'b \Rightarrow bool
 assumes h: \forall i. eventually (P i) F
 shows eventually (\lambda x. \ \forall i. \ P \ i \ x) \ F
proof(unfold eventually-def)
 let ?F = Rep\text{-filter } F
 have obs: \forall i. ?F(P i)
    using h by auto
 have ?F(\lambda x. \forall i \in UNIV. P i x)
    apply(rule finite-induct)
    by(auto intro: eventually-conj simp: obs h)
  thus ?F(\lambda x. \forall i. P i x)
    by simp
\mathbf{qed}
lemma eventually-all-finite-mono:
  fixes P :: ('a::finite) \Rightarrow 'b \Rightarrow bool
```

```
assumes h1: \forall i. eventually (P i) F
      and h2: \forall x. (\forall i. (P i x)) \longrightarrow Q x
  shows eventually Q F
proof-
  have eventually (\lambda x. \ \forall i. \ P \ i \ x) \ F
    using h1 eventually-all-finite2 by blast
  thus eventually Q F
    unfolding eventually-def
    using h2 eventually-mono by auto
qed
lemma frechet-vec-lambda:
  fixes f::real \Rightarrow ('a::banach) \hat{\ } ('m::finite) and x::real and T::real set
  defines x_0 \equiv netlimit (at x within T) and <math>m \equiv real \ CARD('m)
  assumes \forall i. ((\lambda y. (f y \$ i - f x_0 \$ i - (y - x_0) *_R f' x \$ i) /_R (||y - x_0||))
    \rightarrow \theta) (at x within T)
  shows ((\lambda y. (f y - f x_0 - (y - x_0) *_R f' x) /_R (||y - x_0||)) \longrightarrow \theta) (at x
within T
proof(simp add: tendsto-iff, clarify)
  fix \varepsilon::real assume 0 < \varepsilon
  let ?\Delta = \lambda y. y - x_0 and ?\Delta f = \lambda y. f y - f x_0
 let P = \lambda i \ e \ y. inverse \ |?\Delta \ y| * (||f \ y \ \$ \ i - f \ x_0 \ \$ \ i - ?\Delta \ y *_R f' \ x \ \$ \ i||) < e
    and ?Q = \lambda y. inverse |?\Delta y| * (||?\Delta f y - ?\Delta y *_R f' x||) < \varepsilon
  have 0 < \varepsilon / sqrt m
    using \langle \theta < \varepsilon \rangle by (auto simp: assms)
  hence \forall i. eventually (\lambda y. ?P \ i \ (\varepsilon \ / \ sqrt \ m) \ y) \ (at \ x \ within \ T)
    using assms unfolding tendsto-iff by simp
  thus eventually ?Q (at x within T)
 proof(rule eventually-all-finite-mono, simp add: norm-vec-def L2-set-def, clarify)
    \mathbf{fix} \ t :: real
    let ?c = inverse |t - x_0| and ?u t = \lambda i. ft \$ i - fx_0 \$ i - ?\Delta t *_R f' x \$ i
    assume hyp: \forall i. ?c * (\|?u \ t \ i\|) < \varepsilon / sqrt \ m
    hence \forall i. (?c *_R (||?u \ t \ i||))^2 < (\varepsilon \ / \ sqrt \ m)^2
      \mathbf{by}\ (simp\ add\colon power\text{-}strict\text{-}mono)
    hence \forall i. ?c^2 * ((\|?u \ t \ i\|))^2 < \varepsilon^2 \ / \ m
      by (simp add: power-mult-distrib power-divide assms)
    hence \forall i. ?c^2 * ((\|?u \ t \ i\|))^2 < \varepsilon^2 / m
      by (auto simp: assms)
    also have (\{\}::'m\ set) \neq UNIV \land finite\ (UNIV :: 'm\ set)
    ultimately have (\sum i \in UNIV. ?c^2 * ((||?u t i||))^2) < (\sum (i::'m) \in UNIV. \varepsilon^2 / (||?u t i||))^2)
m)
      by (metis (lifting) sum-strict-mono)
    moreover have ?c^2 * (\sum i \in UNIV. (||?u \ t \ i||)^2) = (\sum i \in UNIV. ?c^2 * (||?u \ t
|i||)^2
      \mathbf{using} \ \mathit{sum-distrib-left} \ \mathbf{by} \ \mathit{blast}
    ultimately have ?c^2 * (\sum i \in UNIV. (||?u \ t \ i||)^2) < \varepsilon^2
      by (simp add: assms)
    hence sqrt \ (?c^2 * (\sum i \in UNIV. (||?u \ t \ i||)^2)) < sqrt \ (\varepsilon^2)
```

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```
using real-sqrt-less-iff by blast
    also have ... = \varepsilon
      using \langle \theta < \varepsilon \rangle by auto
   moreover have ?c * sqrt (\sum i \in UNIV. (||?u \ t \ i||)^2) = sqrt (?c^2 * (\sum i \in UNIV.
(\|?u\ t\ i\|)^2)
      by (simp add: real-sqrt-mult)
    ultimately show ?c * sqrt (\sum i \in UNIV. (||?u t i||)^2) < \varepsilon
  qed
qed
lemma has-derivative-vec-lambda:
  fixes f::real \Rightarrow ('a::banach) \hat{\ } ('m::finite)
  assumes \forall i. D (\lambda t. f t \$ i) \mapsto (\lambda h. h *_R f' x \$ i) (at x within T)
  shows D f \mapsto (\lambda h. h *_R f' x) at x within T
  apply(unfold has-derivative-def, safe)
  apply(force simp: bounded-linear-def bounded-linear-axioms-def)
  using assms frechet-vec-lambda of x T unfolding has-derivative-def by auto
{f lemma}\ has	ext{-}vderiv	ext{-}on	ext{-}vec	ext{-}lambda:
  fixes f::(('a::banach) \hat{\ } ('n::finite)) \Rightarrow ('a \hat{\ }'n)
  assumes \forall i. D (\lambda t. x t \$ i) = (\lambda t. f (x t) \$ i) \text{ on } T
  shows D x = (\lambda t. f(x t)) on T
 using assms unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp
  \mathbf{by}(rule\ has\text{-}derivative\text{-}vec\text{-}lambda,\ simp)
lemma frechet-vec-nth:
  fixes f::real \Rightarrow ('a::real-normed-vector) `'m and x::real and T::real set
  defines x_0 \equiv netlimit (at x within T)
  assumes ((\lambda y. (f y - f x_0 - (y - x_0) *_R f' x) /_R (||y - x_0||)) \longrightarrow 0) (at x
within T)
  shows ((\lambda y. (f y \$ i - f x_0 \$ i - (y - x_0) *_R f' x \$ i) /_R (||y - x_0||)) \longrightarrow
\theta) (at x within T)
proof(unfold tendsto-iff dist-norm, clarify)
  let ?\Delta = \lambda y. y - x_0 and ?\Delta f = \lambda y. f y - f x_0
  fix \varepsilon::real assume \theta < \varepsilon
  let P = \lambda y. \|(P \Delta f y - P \Delta y *_R f' x)/_R (\|P \Delta y\|) - \theta\| < \varepsilon
  and ?Q = \lambda y. ||(fy \$ i - fx_0 \$ i - ?\Delta y *_R f'x \$ i) /_R (||?\Delta y||) - \theta|| < \varepsilon
  have eventually ?P (at x within T)
    using \langle \theta < \varepsilon \rangle assms unfolding tendsto-iff by auto
  thus eventually ?Q (at x within T)
  \mathbf{proof}(rule\text{-}tac\ P=?P\ \mathbf{in}\ eventually\text{-}mono,\ simp\text{-}all)
    let ?u \ y \ i = f \ y \ \$ \ i - f \ x_0 \ \$ \ i - ?\Delta \ y \ *_R f' \ x \ \$ \ i
    \mathbf{fix}\ y\ \mathbf{assume}\ hyp:inverse\ |?\Delta\ y|*(\|?\Delta f\ y\ -\ ?\Delta\ y*_R\ f'\ x\|)<\varepsilon
    have \|(?\Delta f y - ?\Delta y *_R f' x) \$ i\| \le \|?\Delta f y - ?\Delta y *_R f' x\|
      \mathbf{using} \ \mathit{Finite-Cartesian-Product.norm-nth-le} \ \mathbf{by} \ \mathit{blast}
    also have \|?u\ y\ i\| = \|(?\Delta f\ y - ?\Delta\ y *_R f'\ x) \ \ i\|
    ultimately have \|?u\ y\ i\| \leq \|?\Delta f\ y - ?\Delta\ y *_R f'\ x\|
```

```
by linarith
   hence inverse |?\Delta y| * (||?u y i||) \le inverse |?\Delta y| * (||?\Delta f y - ?\Delta y *_R f')
x \parallel
     by (simp add: mult-left-mono)
   thus inverse |?\Delta y|*(||fy \$i-fx_0 \$i-?\Delta y*_R f'x \$i||) < \varepsilon
     using hyp by linarith
 aed
qed
lemma has-derivative-vec-nth:
 assumes D f \mapsto (\lambda h. \ h *_R f' x) at x within T
 shows D (\lambda t. f t \$ i) \mapsto (\lambda h. h *_R f' x \$ i) at x within T
 apply(unfold\ has\text{-}derivative\text{-}def,\ safe)
  apply(force simp: bounded-linear-def bounded-linear-axioms-def)
 using frechet-vec-nth[of x T f] assms unfolding has-derivative-def by auto
lemma has-vderiv-on-vec-nth:
 fixes f::(('a::banach) \hat{\ } ('n::finite)) \Rightarrow ('a\hat{\ }'n)
 assumes D x = (\lambda t. f(x t)) on T
 shows D(\lambda t. x t \$ i) = (\lambda t. f(x t) \$ i) on T
 using assms unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp
 by(rule has-derivative-vec-nth, simp)
```

#### 1.3 Ordinary Differential Equations

#### 1.3.1 Picard-Lindeloef

 ${\bf named-theorems}\ ubc\text{-}definitions\ definitions\ used\ in\ the\ locale\ unique\text{-}on\text{-}bounded\text{-}closed$ 

```
declare unique-on-bounded-closed-def [ubc-definitions]
   and unique-on-bounded-closed-axioms-def [ubc-definitions]
   and unique-on-closed-def [ubc-definitions]
   and compact-interval-def [ubc-definitions]
   and compact-interval-axioms-def [ubc-definitions]
   and self-mapping-def [ubc-definitions]
   and self-mapping-axioms-def [ubc-definitions]
   and continuous-rhs-def [ubc-definitions]
   and closed-domain-def [ubc-definitions]
   and global-lipschitz-def [ubc-definitions]
   and interval-def [ubc-definitions]
   and nonempty-set-def [ubc-definitions]
\mathbf{lemma(in}\ unique-on-bounded\text{-}closed)\ unique-on-bounded\text{-}closed\text{-}on-compact\text{-}subset:
  assumes t\theta \in T' and x\theta \in X and T' \subseteq T and compact-interval T'
  shows unique-on-bounded-closed to T' x0 f X L
  apply(unfold-locales)
  \textbf{using} \ \langle compact\text{-}interval \ T' \rangle \ \textbf{unfolding} \ ubc\text{-}definitions \ \textbf{apply} \ simp +
  using \langle t\theta \in T' \rangle apply simp
  using \langle x\theta \in X \rangle apply simp
```

```
\begin{array}{l} \textbf{using} \ \langle T' \subseteq T \rangle \ self\text{-}mapping \ \textbf{apply} \ blast \\ \textbf{using} \ \langle T' \subseteq T \rangle \ continuous \ \textbf{apply} (meson \ Sigma\text{-}mono \ continuous\text{-}on\text{-}subset \ subset} I) \\ \textbf{using} \ \langle T' \subseteq T \rangle \ lipschitz \ \textbf{apply} \ blast \\ \textbf{using} \ \langle T' \subseteq T \rangle \ lipschitz\text{-}bound \ \textbf{by} \ blast \end{array}
```

The next locale makes explicit the conditions for applying the Picard-Lindeloef theorem. This guarantees a unique solution for every initial value problem represented with a vector field f and an initial time  $t_0$ . It is mostly a simplified reformulation of the approach taken by the people who created the Ordinary Differential Equations entry in the AFP.

```
locale picard-lindeloef =
  fixes f::real \Rightarrow ('a::banach) \Rightarrow 'a and T::real \ set and L \ t_0::real
 assumes init-time: t_0 \in T
   and cont-vec-field: continuous-on (T \times UNIV) (\lambda(t, x), f(t, x))
   and lipschitz-vec-field: \bigwedge t. \ t \in T \Longrightarrow L-lipschitz-on UNIV (\lambda x. \ f \ t \ x)
   and nonempty-time: T \neq \{\}
   and interval-time: is-interval T
   and compact-time: compact T
   and lipschitz-bound: \bigwedge s \ t. \ s \in T \Longrightarrow t \in T \Longrightarrow abs \ (s-t) * L < 1
begin
{\bf sublocale}\ continuous\text{-}rhs\ T\ UNIV
 using cont-vec-field unfolding continuous-rhs-def by simp
{f sublocale}\ global	ext{-lipschitz}\ T\ UNIV
  using lipschitz-vec-field unfolding global-lipschitz-def by simp
sublocale closed-domain UNIV
  unfolding closed-domain-def by simp
sublocale compact-interval
  using interval-time nonempty-time compact-time by (unfold-locales, auto)
lemma is-ubc:
 shows unique-on-bounded-closed t_0 T s f UNIV L
 using nonempty-time unfolding ubc-definitions apply safe
 by(auto simp: compact-time interval-time init-time
     lipschitz-vec-field lipschitz-bound cont-vec-field)
lemma min-max-interval:
 obtains m M where T = \{m ... M\}
 using T-def by blast
lemma subinterval:
 assumes t \in T
 obtains t1 where \{t ... t1\} \subseteq T
 using assms interval-subset-is-interval interval-time by fastforce
```

```
lemma subsegment:
 assumes t1 \in T and t2 \in T
 shows \{t1 -- t2\} \subseteq T
 using assms closed-segment-subset-domain by blast
lemma unique-solution:
 assumes D x = (\lambda t. f t (x t)) on T and x t_0 = s
   and D y = (\lambda t. f t (y t)) on T and y t_0 = s and t \in T
 shows x t = y t
 apply(rule unique-on-bounded-closed.unique-solution)
 using is-ubc[of s] apply blast
 using assms unfolding solves-ode-def by auto
abbreviation phi t s \equiv (apply-bcontfun (unique-on-bounded-closed.fixed-point <math>t_0
T \ s \ f \ UNIV)) \ t
lemma fixpoint-solves-ivp:
 shows D(\lambda t. phi t s) = (\lambda t. f t (phi t s)) on T and phi t<sub>0</sub> s = s
 using is-ubc[of s] unique-on-bounded-closed.fixed-point-solution[of t_0 T s f UNIV
   unique-on-bounded-closed.fixed-point-iv[of t_0 T s f UNIV L]
 unfolding solves-ode-def by auto
lemma fixpoint-usolves-ivp:
 assumes D x = (\lambda t. f t (x t)) on T and x t_0 = s and t \in T
 shows x t = phi t s
 using unique-solution [OF assms(1,2)] fixpoint-solves-ivp assms by blast
```

#### 1.3.2 Flows for ODEs

end

This locale is a particular case of the previous one. It makes the unique solution for initial value problems explicit, it restricts the vector field to reflect autonomous systems (those that do not depend explicitly on time), and it sets the initial time equal to 0. This is the first step towards formalizing the flow of a differential equation, i.e. the function that maps every point to the unique trajectory tangent to the vector field.

```
locale local-flow = picard-lindeloef (\lambda t. f) T L 0 for f::('a::banach) \Rightarrow 'a and T L + fixes \varphi :: real \Rightarrow 'a \Rightarrow 'a assumes ivp: D (\lambdat. \varphi t s) = (\lambdat. f (\varphi t s)) on T \varphi 0 s = s begin lemma is-fixpoint: assumes t \in T shows \varphi t s = phi t s apply(rule fixpoint-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolves-usolve
```

```
using ivp assms init-time by simp-all
lemma solves-ode:
 shows ((\lambda \ t. \ \varphi \ t \ s) \ solves-ode \ (\lambda \ t. \ f)) T \ UNIV
 unfolding solves-ode-def using ivp(1) by auto
lemma usolves-ivp:
 assumes D x = (\lambda t. f(x t)) on T and x \theta = s and t \in T
 shows x t = \varphi t s
proof-
 have x t = phi t s
   using assms fixpoint-usolves-ivp by blast
 also have ... = \varphi t s
   using assms is-fixpoint by force
 finally show ?thesis.
qed
lemma usolves-on-compact-subset:
 assumes T' \subseteq T and compact-interval T' and \theta \in T' and t \in T'
      and x-solves: (x \text{ solves-ode } (\lambda t. f)) T' UNIV
 shows \varphi t (x \theta) = x t
proof-
  have obs:((\lambda \ \tau. \ \varphi \ \tau \ (x \ \theta)) \ solves-ode \ (\lambda \ \tau. \ f))T' \ UNIV
   using \langle T' \subseteq T \rangle solves-ode-on-subset solves-ode by (metis subset-eq)
 have unique-on-bounded-closed 0 T (x \ 0) \ (\lambda \ \tau. \ f) UNIV L
   using is-ubc by blast
 hence unique-on-bounded-closed 0 T'(x \ 0) \ (\lambda \ \tau. \ f) UNIV L
   {\bf using} \ unique-on-bounded-closed.unique-on-bounded-closed-on-compact-subset
   \langle \theta \in T' \rangle \langle T' \subseteq T \rangle and \langle compact\text{-}interval \ T' \rangle by blast
  moreover have \varphi \ \theta \ (x \ \theta) = x \ \theta
   using ivp by blast
  ultimately show \varphi t (x \theta) = x t
   using unique-on-bounded-closed unique-solution obs x-solves \langle t \in T' \rangle by blast
qed
end
lemma flow-on-compact-subset:
 assumes flow-on-big: local-flow f T' L \varphi and T \subseteq T'
   and compact-interval T and \theta \in T
 shows local-flow f T L \varphi
proof(unfold local-flow-def local-flow-axioms-def, safe)
  \mathbf{fix} \ s \ \mathbf{show} \ \varphi \ \theta \ s = s
   using local-flow.ivp(2) flow-on-big by blast
 show D(\lambda t. \varphi t s) = (\lambda t. f(\varphi t s)) on T
    using assms solves-ode-on-subset[where T=T and S=T' and x=\lambda t. \varphi t s
and X = UNIV
   unfolding local-flow-def local-flow-axioms-def solves-ode-def by force
next
```

```
show picard-lindeloef (\lambda t. f) T L 0
using assms apply(unfold local-flow-def local-flow-axioms-def)
apply(unfold picard-lindeloef-def ubc-definitions)
apply(meson Sigma-mono continuous-on-subset subsetI)
by(simp-all add: subset-eq)
qed
```

Finally, the flow exists when the unique solution from the last locale is defined in all of  $\mathbb{R}$ . Here we prove that it is a dyanmical system, i.e. a group action on the additive group of the real numbers.

```
locale global-flow = local-flow f UNIV L \varphi for f L \varphi
begin
lemma add-flow-solves: D(\lambda \tau. \varphi(\tau + t) s) = (\lambda \tau. f(\varphi(\tau + t) s)) on UNIV
  \mathbf{apply}(subgoal\text{-}tac\ D\ ((\lambda\tau.\ \varphi\ \tau\ s)\circ(\lambda\tau.\ \tau\ +\ t)) =
   (\lambda x. (\lambda \tau. 1) x *_R (\lambda t. f (\varphi t s)) ((\lambda \tau. \tau + t) x)) on UNIV, simp add: comp-def)
  apply(rule has-vderiv-on-compose)
  using solves-ode min-max-interval unfolding solves-ode-def apply force
  apply(rule-tac f'1=\lambda x. 1 and g'1=\lambda x. 0 in derivative-intros(191))
  \mathbf{by}(rule\ derivative\text{-}intros,\ simp) +\ simp\text{-}all
lemma is-group-action:
  shows \varphi \ \theta \ s = s
    and \varphi (t1 + t2) s = \varphi t1 (\varphi t2 s)
proof-
  \mathbf{show} \ \varphi \ \theta \ s = s
    using ivp by simp
  have \varphi (\theta + t2) s = \varphi t2 s
    bv simp
  moreover have D(\lambda \tau. \varphi(\tau + t2) s) = (\lambda \tau. f(\varphi(\tau + t2) s)) on UNIV
    using add-flow-solves by simp
  moreover have \varphi \ \theta \ (\varphi \ t2 \ s) = \varphi \ t2 \ s
    using ivp by simp
  ultimately have \bigwedge t. \varphi(t + t2) s = \varphi t (\varphi t2 s)
    using usolves-ivp by blast
  thus \varphi (t1 + t2) s = \varphi t1 (\varphi t2 s)
    by simp
\mathbf{qed}
end
\mathbf{lemma}\ \mathit{localize}\text{-}\mathit{global}\text{-}\mathit{flow}\text{:}
  assumes global-flow f L \varphi and compact-interval T
  shows local-flow f T L \varphi
 using assms unfolding global-flow-def local-flow-def picard-lindeloef-def by simp
```

#### Example

```
Below there is an example showing the general methodology to introduce pairs of vector fields and their respective flows using the previous locales.
```

```
lemma picard-lindeloef-constant: 0 \le t \Longrightarrow picard-lindeloef (\lambda t \ s. \ c) {0..t} (1 / (t + 1)) 0 unfolding picard-lindeloef-def by(simp add: nonempty-set-def lipschitz-on-def, clarsimp, simp)

lemma line-vderiv-constant: D (\lambda \tau. \ x + \tau *_R c) = (\lambda t. \ c) on {0..t} apply(rule-tac f'1 = \lambda \ x. \ 0 and g'1 = \lambda \ x. \ c in derivative-intros(191)) apply(rule derivative-intros, simp)+ by simp-all

lemma line-is-local-flow: fixes c::'a::banach assumes 0 \le t shows local-flow (\lambda s. \ c) {0..t} (1/(t + 1)) (\lambda t \ x. \ x + t *_R c) unfolding local-flow-def local-flow-axioms-def apply safe using assms picard-lindeloef-constant apply blast using line-vderiv-constant by auto
```

end
theory hs-prelims-matrices
imports hs-prelims

begin

### Chapter 2

# Linear Algebra for Hybrid Systems

Linear systems of ordinary differential equations (ODEs) are those whose vector fields are a linear operator. That is, there is a matrix A such that the system x't = f(xt) can be rewritten as x't = A \*v x t. The end goal of this section is to prove that every linear system of ODEs has a unique solution, and to obtain a characterization of said solution. For that we start by formalising various properties of vector spaces.

### 2.1 Vector operations

```
fixes q::('a::semiring-\theta)
  shows (\sum j \in UNIV. \ f \ j * axis \ i \ q \ \$ \ j) = f \ i * q
   and (\sum j \in UNIV. \ axis \ i \ q \ \$ \ j * f \ j) = q * f \ i
  \mathbf{unfolding} \ \mathit{axis-def} \ \mathbf{by}(\mathit{auto} \ \mathit{simp} \colon \mathit{vec\text{-}eq\text{-}iff})
lemma sum-scalar-nth-axis: sum (\lambda i. (x \$ i) *s e i) UNIV = x for x :: ('a::semiring-1) ^{\prime}n
  unfolding vec-eq-iff axis-def by simp
lemma scalar-eq-scaleR[simp]: c *s x = c *_R x for c :: real
  unfolding vec-eq-iff by simp
lemma matrix-add-rdistrib: ((B + C) ** A) = (B ** A) + (C ** A)
  by (vector matrix-matrix-mult-def sum.distrib[symmetric] field-simps)
lemma vec-mult-inner: (A * v v) \cdot w = v \cdot (transpose \ A * v w) for A::real ^\prime n ^\prime n
  unfolding matrix-vector-mult-def transpose-def inner-vec-def
  apply(simp add: sum-distrib-right sum-distrib-left)
  apply(subst sum.swap)
 \mathbf{apply}(\mathit{subgoal\text{-}tac} \ \forall \ i \ j. \ A \ \$ \ i \ \$ \ j \ast v \ \$ \ j \ast w \ \$ \ i = v \ \$ \ j \ast (A \ \$ \ i \ \$ \ j \ast w \ \$ \ i))
  by presburger (simp)
lemma norm-axis-eq[simp]: ||axis\ i\ k|| = ||k||
proof(simp add: axis-def norm-vec-def L2-set-def)
 have (\sum j \in UNIV. (\|(\delta_K j i k)\|)^2) = (\sum j \in \{i\}. (\|(\delta_K j i k)\|)^2) + (\sum j \in (UNIV - \{i\}).
(\|(\delta_K \ j \ i \ k)\|)^2)
   using finite-sum-univ-singleton by blast
  also have ... = (\|k\|)^2 by simp
 finally show sqrt (\sum j \in UNIV. (norm (if j = i then k else \theta))^2) = norm k by
simp
\mathbf{qed}
lemma matrix-axis-\theta:
  fixes A :: ('a::idom) \hat{\ }'n \hat{\ }'m
  assumes k \neq 0 and h: \forall i. (A *v (axis i k)) = 0
  shows A = \theta
proof-
  \{fix i::'n
   have \theta = (\sum j \in UNIV. (axis\ i\ k) \ \ j \ *s\ column\ j\ A)
      using h matrix-mult-sum[of A axis i k] by simp
   also have ... = k *s column i A
    by (simp add: axis-def vector-scalar-mult-def column-def vec-eq-iff mult.commute)
   finally have k *s column i A = 0
      unfolding axis-def by simp
   hence column \ i \ A = 0
      using vector-mul-eq-0 \langle k \neq 0 \rangle by blast
  thus A = \theta
   unfolding column-def vec-eq-iff by simp
qed
```

```
lemma scaleR-norm-sgn-eq: (||x||) *_R sgn x = x
 by (metis divideR-right norm-eq-zero scale-eq-0-iff sgn-div-norm)
lemma vector\text{-}scaleR\text{-}commute : A*v c*_R x = c*_R (A*v x) \text{ for } x :: ('a::real\text{-}normed\text{-}algebra\text{-}1) ^'n
 unfolding scaleR-vec-def matrix-vector-mult-def by (auto simp: vec-eq-iff scaleR-right.sum)
lemma scaleR-vector-assoc: c *_R (A * v x) = (c *_R A) *_V x  for x :: ('a :: real-normed - algebra - 1) ^'n
 unfolding matrix-vector-mult-def by(auto simp: vec-eq-iff scaleR-right.sum)
lemma mult-norm-matrix-sqn-eq:
 fixes x :: ('a::real-normed-algebra-1) ^'n
 shows (||A * v sgn x||) * (||x||) = ||A * v x||
proof-
 have ||A * v x|| = ||A * v ((||x||) *_R sgn x)||
   by(simp add: scaleR-norm-sgn-eq)
 also have ... = (||A * v sgn x||) * (||x||)
   \mathbf{by}(simp\ add:\ vector\text{-}scaleR\text{-}commute)
 finally show ?thesis ..
qed
```

#### 2.2 Matrix norms

Here we develop the foundations for obtaining the Lipschitz constant for every linear system of ODEs x' t = A \*v x t. For that we derive some properties of two matrix norms.

#### 2.2.1 Matrix operator norm

```
abbreviation op-norm (A::('a::real-normed-algebra-1) \hat{\ \ }'n \hat{\ \ }'m) \equiv Sup \{ ||A*vx|| \}
| x. ||x|| = 1
notation op-norm ((1||-||_{op}) [65] 61)
lemma norm-matrix-bound:
  fixes A::('a::real-normed-algebra-1) ^'n ^'m
 \mathbf{shows} \ \|x\| = 1 \Longrightarrow \|A * v \ x\| \le \|(\chi \ i \ j. \ \|A \ \$ \ i \ \$ \ j\|) * v \ 1\|
  fix x:('a, 'n) vec assume ||x|| = 1
 hence xi-le1: \land i. ||x \$ i|| \le 1
    by (metis Finite-Cartesian-Product.norm-nth-le)
  \{ \mathbf{fix} \ j :: 'm \}
    have \|(\sum i \in UNIV. \ A \ \$ \ j \ \$ \ i * x \ \$ \ i)\| \le (\sum i \in UNIV. \ \|A \ \$ \ j \ \$ \ i * x \ \$ \ i\|)\|
      \mathbf{using}\ norm\text{-}sum\ \mathbf{by}\ blast
    also have ... \leq (\sum i \in UNIV. (||A \$ j \$ i||) * (||x \$ i||))
      by (simp add: norm-mult-ineq sum-mono)
    also have ... \leq (\sum i \in UNIV. (||A \$ j \$ i||) * 1)
      using xi-le1 by (simp add: sum-mono mult-left-le)
```

```
finally have \|(\sum i \in UNIV. A \ \ j \ \ \ i * x \ \ \ i)\| \le (\sum i \in UNIV. (\|A \ \ \ j \ \ \ i\|)\|
* 1) by simp}
 from this have \[ \] | (A *v x) \$ j \| \le ((\chi i1 i2. \|A \$ i1 \$ i2\|) *v 1) \$ j \| 
   \mathbf{unfolding}\ \mathit{matrix}\text{-}\mathit{vector}\text{-}\mathit{mult}\text{-}\mathit{def}\ \mathbf{by}\ \mathit{simp}
 hence (\sum j \in UNIV. (\|(A * v x) \$ j\|)^2) \le (\sum j \in UNIV. (\|((\chi i1 i2. \|A \$ i1 \$ i1 \$ j))^2))
i2||)*v1)$||j||)^2
  by (metis (mono-tags, lifting) norm-qe-zero power2-abs power-mono real-norm-def
sum-mono)
 thus ||A *v x|| \le ||(\chi i j. ||A \$ i \$ j||) *v 1||
   unfolding norm-vec-def L2-set-def by simp
qed
lemma op-norm-set-proptys:
 fixes A::('a::real-normed-algebra-1) ^'n ^'m
 shows bounded \{||A * v x|| | x. ||x|| = 1\}
   and bdd-above {||A * v x|| | x. ||x|| = 1}
   and \{||A * v x|| \mid x. ||x|| = 1\} \neq \{\}
 unfolding bounded-def bdd-above-def apply safe
   apply(rule-tac x=0 in exI, rule-tac x=\|(\chi \ i \ j. \|A \ i \ j\|) *v \ 1\| in exI)
   apply(force simp: norm-matrix-bound dist-real-def)
 apply(rule-tac x=||(\chi ij.||A \$ i \$ j||)*v1|| in exI, force simp: norm-matrix-bound)
 using ex-norm-eq-1 by blast
lemma norm-matrix-le-op-norm: ||x|| = 1 \Longrightarrow ||A * v x|| \le ||A||_{op}
 by(rule cSup-upper, auto simp: op-norm-set-proptys)
lemma norm-matrix-le-op-norm-ge-\theta: \theta \leq ||A||_{op}
 using ex-norm-eq-1 norm-qe-zero norm-matrix-le-op-norm basic-trans-rules (23)
by blast
lemma norm-sgn-le-op-norm: ||A * v   sgn   x|| \le ||A||_{op}
 \mathbf{by}(cases\ x=0,\ simp-all\ add:\ norm-sgn\ norm-matrix-le-op-norm\ norm-matrix-le-op-norm-ge-0)
lemma norm-matrix-le-mult-op-norm: ||A * v x|| \le (||A||_{op}) * (||x||) for A :: real^{\prime} n^{\prime} m
proof-
 have ||A * v x|| = (||A * v sgn x||) * (||x||)
   by(simp add: mult-norm-matrix-sqn-eq)
 also have ... \leq (\|A\|_{op}) * (\|x\|)
   using norm-sgn-le-op-norm[of A] by (simp add: mult-mono')
 finally show ?thesis by simp
qed
lemma ltimes-op-norm:
Sup \{|c| * (||A *v x||) |x. ||x|| = 1\} = |c| * (||A||_{op}) \text{ (is } Sup ?cA = |c| * (||A||_{op}) \text{)}
proof(cases c = 0, simp add: ex-norm-eq-1)
 let ?S = \{(\|A * v x\|) | x. \|x\| = 1\}
 note op\text{-}norm\text{-}set\text{-}proptys(2)[of A]
 also have ?cA = \{|c| * x | x. x \in ?S\}
   by force
```

```
ultimately have bdd-cA:bdd-above ?cA
   using bdd-above-ltimes[of |c| ?S] by simp
 assume c \neq 0
 show Sup ?cA = |c| * (||A||_{op})
 proof(rule\ cSup-eq-linorder)
   show nempty-cA:?cA \neq \{\}
     using op\text{-}norm\text{-}set\text{-}proptys(3)[of\ A] by blast
   show bdd-above ?cA
     using bdd-cA by blast
    \{ \mathbf{fix} \ m \ \mathbf{assume} \ m \in ?cA \}
     then obtain x where x-def:||x|| = 1 \land m = |c| * (||A *v x||)
       by blast
     hence (\|A * v x\|) \le (\|A\|_{op})
       using norm-matrix-le-op-norm by force
     hence m \le |c| * (||A||_{op})
       using x-def by (simp add: mult-left-mono)}
   thus \forall x \in ?cA. \ x \leq |c| * (||A||_{op})
     by blast
 next
   show \forall y < |c| * (||A||_{op}). \exists x \in ?cA. y < x
   \mathbf{proof}(\mathit{clarify})
     fix m assume m < |c| * (||A||_{op})
     hence (m / |c|) < (||A||_{op})
       using pos-divide-less-eq[of |c| m (||A||_{op})] \langle c \neq 0 \rangle
           semiring-normalization-rules(7)[of |c|] by auto
     then obtain x where ||x|| = 1 \wedge (m / |c|) < (||A *v x||)
       using less-cSup-iff [of ?Sm / |c|] op-norm-set-proptys by force
     hence ||x|| = 1 \land m < |c| * (||A *v x||)
       using \langle c \neq 0 \rangle pos-divide-less-eq[of - m -] by (simp add: mult.commute)
     thus \exists n \in ?cA. m < n by blast
   qed
 qed
qed
lemma op-norm-le-sum-column:
 ||A||_{op} \leq (\sum i \in UNIV. ||column \ i \ A||) for A::real^{n}
  using op\text{-}norm\text{-}set\text{-}proptys(3) proof(rule\ cSup\text{-}least)
 fix m assume m \in \{ ||A * v x|| \mid x. ||x|| = 1 \}
   then obtain x where x-def:||x|| = 1 \land m = (||A * v x||) by blast
   hence x-hyp:\bigwedge i. norm (x \$ i) \le 1
     by (simp add: norm-bound-component-le-cart)
   have (||A *v x||) = norm (\sum i \in UNIV. (x \$ i *s column i A))
     \mathbf{by}(subst\ matrix-mult-sum[of\ A],\ simp)
   also have \dots \le (\sum i \in UNIV. norm (x \ \$ \ i *s \ column \ i \ A))
     by (simp add: sum-norm-le)
   also have ... = (\sum i \in UNIV. norm (x \$ i) * norm (column i A))
     by (simp add: mult-norm-matrix-sgn-eq)
   also have ... \leq (\sum i \in UNIV. \ norm \ (column \ i \ A))
     using x-hyp by (simp add: mult-left-le-one-le sum-mono)
```

```
finally show m \leq (\sum i \in UNIV. \ norm \ (column \ i \ A))
     using x-def by linarith
qed
lemma op-norm-zero-iff: (\|A\|_{op} = 0) = (A = 0) for A::('a::real-normed-field) ^'n 'm
  assume A = \theta thus ||A||_{op} = \theta
   \mathbf{by}(simp\ add:\ ex\text{-}norm\text{-}eq\text{-}1)
next
  assume ||A||_{op} = 0
  note cSup\text{-}upper[of - {||A * v x|| | x. ||x|| = 1}]
  hence \bigwedge r. \ r \in \{ \|A * v x\| \mid x. \|x\| = 1 \} \Longrightarrow r \le (\|A\|_{op})
   using op\text{-}norm\text{-}set\text{-}proptys(2) by force
  also have \bigwedge r. r \in (\{\|A * v x\| \mid x \cdot \|x\| = 1\}) \Longrightarrow 0 \le r
   using norm-ge-zero by blast
  ultimately have \bigwedge r. r \in (\{\|A * v x\| \mid x \cdot \|x\| = 1\}) \Longrightarrow r = 0
   using \langle ||A||_{op} = 0 \rangle by fastforce
  hence \bigwedge x. ||x|| = 1 \Longrightarrow x \neq 0 \land (||A * v x||) = 0
   by force
  hence \bigwedge i. norm (A * v e i) = 0
   by simp
  from this show A = \theta
   using matrix-axis-0 [of 1 A] norm-eq-zero by simp
qed
lemma op-norm-triangle:
  fixes A::('a::real-normed-algebra-1) ^'n ^'m
  shows ||A + B||_{op} \le (||A||_{op}) + (||B||_{op})
  using op-norm-set-proptys(3)[of A + B] proof(rule cSup-least)
  fix m assume m \in \{ \|(A + B) * v x\| \mid x. \|x\| = 1 \}
   then obtain x::'a^n where ||x|| = 1 and m = ||(A + B) *v x||
     by blast
   have ||(A + B) *v x|| \le (||A *v x||) + (||B *v x||)
     by (simp add: matrix-vector-mult-add-rdistrib norm-triangle-ineq)
   also have ... \leq (\|A\|_{op}) + (\|B\|_{op})
     by (simp\ add: \langle ||x|| = 1 \rangle\ add\text{-}mono\ norm\text{-}matrix\text{-}le\text{-}op\text{-}norm)
   finally show m \le (\|A\|_{op}) + (\|B\|_{op})
      using \langle m = ||(A + B) *v x|| \rangle by blast
qed
lemma op-norm-scaleR: ||c *_R A||_{op} = |c| * (||A||_{op})
proof-
  let ?N = \{ |c| * (||A *v x||) |x. ||x|| = 1 \}
  have \{\|(c *_R A) *_V x\| \mid x. \|x\| = 1\} = ?N
   by (metis (no-types, hide-lams) norm-scaleR scaleR-vector-assoc)
  also have Sup ?N = |c| * (||A||_{op})
   using ltimes-op-norm[of\ c\ A] by blast
  ultimately show op-norm (c *_R A) = |c| * (||A||_{op})
   by auto
```

qed

```
lemma op-norm-matrix-matrix-mult-le: ||A| ** B||_{op} \le (||A||_{op}) * (||B||_{op}) for
A::real ^n 'n ^m
using op\text{-}norm\text{-}set\text{-}proptys(3)[of\ A\ **\ B]
proof(rule cSup-least)
 have 0 \le (\|A\|_{op}) using norm-matrix-le-op-norm-ge-0 by force
 then obtain x where x\text{-}def: n = ||A ** B *v x|| \land ||x|| = 1 by blast
   have ||A ** B *v x|| = ||A *v (B *v x)||
     by (simp add: matrix-vector-mul-assoc)
   also have ... \leq (\|A\|_{op}) * (\|B * v x\|)
     by (simp add: norm-matrix-le-mult-op-norm[of - B *v x])
   also have ... \leq (\|A\|_{op}) * ((\|B\|_{op}) * (\|x\|))
     using norm-matrix-le-mult-op-norm[of B x] \langle 0 \leq (\|A\|_{op}) \rangle mult-left-mono by
blast
   also have ... = (\|A\|_{op}) * (\|B\|_{op}) using x-def by simp
   finally show n \leq (\|A\|_{op}) * (\|B\|_{op}) using x-def by blast
qed
lemma norm-matrix-vec-mult-le-transpose:
||x|| = 1 \Longrightarrow (||A *v x||) \le sqrt (||transpose A ** A||_{op}) * (||x||)  for A::real^{a}
proof-
 assume ||x|| = 1
 have (\|A * v x\|)^2 = (A * v x) \cdot (A * v x)
   using dot-square-norm[of (A * v x)] by simp
 also have ... = x \cdot (transpose \ A *v \ (A *v \ x))
   using vec-mult-inner by blast
 also have ... \leq (\|x\|) * (\|transpose A * v (A * v x)\|)
   using norm-cauchy-schwarz by blast
 also have ... \leq (\|transpose\ A ** A\|_{op}) * (\|x\|)^2
    \mathbf{apply}(\mathit{subst\ matrix-vector-mul-assoc})\ \mathbf{using\ norm-matrix-le-mult-op-norm}[\mathit{of}\ 
transpose \ A ** A x
   by (simp\ add: \langle ||x|| = 1 \rangle)
 finally have ((\|A * v x\|)) \hat{2} \leq (\|transpose A * A\|_{op}) * (\|x\|) \hat{2}
 thus (||A *v x||) \leq sqrt ((||transpose A ** A||_{op})) * (||x||)
   by (simp add: \langle ||x|| = 1 \rangle real-le-rsqrt)
qed
2.2.2
          Matrix maximum norm
abbreviation max-norm (A::real^{\hat{}}'n^{\hat{}}'m) \equiv Max \ (abs \ `(entries \ A))
notation max-norm ((1||-||_{max}) [65] 61)
lemma max-norm-def: ||A||_{max} = Max \{|A \$ i \$ j||i j. i \in UNIV \land j \in UNIV\}
 \mathbf{by}(simp\ add:\ image-def,\ rule\ arg-cong[of--Max],\ blast)
```

```
lemma max-norm-set-proptys:
 fixes A::real^('n::finite)^('m::finite)
 shows finite {|A \ \ i \ \ j| \ |i \ j. \ i \in UNIV \land j \in UNIV} (is finite ?X)
proof-
 have \bigwedge i. finite \{|A \ \ i \ \ j| \mid j. j \in UNIV\}
   using finite-Atleast-Atmost-nat by fastforce
 hence finite (\bigcup i \in UNIV. {|A \ \ i \ \ j| \ | \ j. \ j \in UNIV}) (is finite ?Y)
   using finite-class.finite-UNIV by blast
 also have ?X \subseteq ?Y by auto
 ultimately show ?thesis
   using finite-subset by blast
qed
lemma max-norm-ge-\theta: \theta \leq ||A||_{max}
proof-
 have \bigwedge i j. |A \$ i \$ j| \ge 0 by simp
 also have \bigwedge i j. |A \$ i \$ j| \le ||A||_{max}
    unfolding max-norm-def using max-norm-set-proptys Max-ge max-norm-def
by blast
 finally show 0 \leq ||A||_{max}.
qed
{f lemma} op-norm-le-max-norm:
 fixes A::real^('n::finite)^('m::finite)
 shows ||A||_{op} \le real \ CARD('n) * real \ CARD('m) * (||A||_{max}) (is ||A||_{op} \le ?n *
?m*(\|A\|_{max}))
proof(rule cSup-least)
 show \{||A * v x|| ||x|| ||x|| = 1\} \neq \{\}
   using op\text{-}norm\text{-}set\text{-}proptys(3) by blast
 {fix n assume n \in \{ ||A * v x|| ||x|| = 1 \}
   then obtain x :: (real, \ 'n) \ vec \ \text{where} \ n \text{-} def : \|x\| = 1 \ \land \ \|A * v \ x\| = n
     by blast
   hence comp-le-1:\forall i::'n. |x \$ i| \le 1
     by (simp add: norm-bound-component-le-cart)
   have A *v x = (\sum i \in UNIV. x \$ i *s column i A)
     using matrix-mult-sum by blast
   hence ||A *v x|| \le (\sum i \in UNIV. ||x \$ i *s column i A||)
     by (simp \ add: sum-norm-le)
   also have ... = (\sum i \in UNIV. |x \$ i| * (||column i A||))
   also have ... \leq (\sum i \in UNIV. \|column\ i\ A\|)
   by (metis (no-types, lifting) Groups.mult-ac(2) comp-le-1 mult-left-le norm-ge-zero
sum-mono)
   also have ... \leq (\sum (i::'n) \in UNIV. ?m * (||A||_{max}))
   proof(unfold norm-vec-def L2-set-def real-norm-def)
     have \bigwedge i j. |column \ i \ A \ \$ \ j| \le ||A||_{max}
        using max-norm-set-proptys Max-ge unfolding column-def max-norm-def
\mathbf{by}(simp, blast)
     hence \bigwedge i j. |column\ i\ A\ \$\ j|^2 \le (\|A\|_{max})^2
```

```
by (metis (no-types, lifting) One-nat-def abs-ge-zero numerals(2) order-trans-rules(23)
            power2-abs power2-le-iff-abs-le)
         then have \bigwedge i. (\sum j \in UNIV. | column \ i \ A \ \$ \ j|^2) \le (\sum (j::'m) \in UNIV.
(\|A\|_{max})^2
        by (meson sum-mono)
      also have (\sum (j::'m) \in UNIV. (||A||_{max})^2) = ?m * (||A||_{max})^2 by simp
     ultimately have \bigwedge i. (\sum j \in UNIV. |column \ i \ A \ \$ \ j|^2) \le ?m * (||A||_{max})^2 by
force
      hence \bigwedge i. sqrt (\sum j \in UNIV. | column \ i \ A \ \ \ \ j|^2) \le sqrt \ (?m * (||A||_{max})^2)
        \mathbf{by}(simp\ add:\ real\text{-}sqrt\text{-}le\text{-}mono)
      also have sqrt \ (?m * (||A||_{max})^2) \le sqrt \ ?m * (||A||_{max})
        using max-norm-ge-0 real-sqrt-mult by auto
      also have ... \leq ?m * (||A||_{max})
        \mathbf{using} \ \mathit{sqrt-real-nat-le} \ \mathit{max-norm-ge-0} \ \mathit{mult-right-mono} \ \mathbf{by} \ \mathit{blast}
    finally show (\sum i \in UNIV. \ sqrt \ (\sum j \in UNIV. \ | \ column \ i \ A \ \$ \ j|^2)) \le (\sum (i::'n) \in UNIV.
?m * (||A||_{max}))
        by (meson sum-mono)
    qed
    also have (\sum (i::'n) \in UNIV. (||A||_{max})) = ?n * (||A||_{max})
      using sum-constant-scale by auto
    ultimately have n \leq ?n * ?m * (||A||_{max})
      by (simp \ add: \ n\text{-}def)
  thus \[ \] n \in \{ \|A * v x\| | x \| \|x\| = 1 \} \implies n \le ?n * ?m * (\|A\|_{max}) \]
    by blast
qed
```

#### 2.3 Picard Lindeloef for linear systems

Now we prove our first objective. First we obtain the Lipschitz constant for linear systems of ODEs, and then we prove that IVPs arising from these satisfy the conditions for Picard-Lindeloef theorem (hence, they have a unique solution).

```
lemma matrix-lipschitz-constant: fixes A::real \ ('n::finite) \ 'n shows dist \ (A*vx) \ (A*vy) \le (real\ CARD('n))^2 * (\|A\|_{max}) * dist\ x\ y unfolding dist-norm matrix-vector-mult-diff-distrib[symmetric] proof(subst mult-norm-matrix-sgn-eq[symmetric]) have \|A\|_{op} \le (\|A\|_{max}) * (real\ CARD('n) * real\ CARD('n)) by (metis\ (no-types)\ Groups.mult-ac(2)\ op-norm-le-max-norm) then have (\|A\|_{op}) * (\|x-y\|) \le (real\ CARD('n))^2 * (\|A\|_{max}) * (\|x-y\|) by (simp\ add:\ cross3-simps(11)\ mult-left-mono\ semiring-normalization-rules(29)) also have (\|A*v\ sgn\ (x-y)\|) * (\|x-y\|) \le (\|A\|_{op}) * (\|x-y\|) by (simp\ add:\ norm-sgn-le-op-norm\ cross3-simps(11)\ mult-left-mono) ultimately show (\|A*v\ sgn\ (x-y)\|) * (\|x-y\|) \le (real\ CARD('n))^2 * (\|A\|_{max}) * (\|x-y\|) using order-trans-rules(23) by blast qed
```

```
lemma picard-lindeloef-linear-system: fixes A::real \ ('n::finite) \ 'n assumes 0 < ((real\ CARD('n))^2 * (\|A\|_{max})) (is 0 < ?L) assumes 0 \le t and t < 1/?L shows picard-lindeloef (\lambda\ t\ s.\ A*v\ s)\ \{0..t\}\ ?L\ 0 apply unfold-locales apply(simp add: (0 \le t)) subgoal by(simp, metis continuous-on-compose2 continuous-on-cong continuous-on-id continuous-on-snd matrix-vector-mult-linear-continuous-on top-greatest) subgoal using matrix-lipschitz-constant max-norm-ge-0 zero-compare-simps(4,12) unfolding lipschitz-on-def by blast apply(simp-all\ add:\ assms) subgoal for r\ s\ apply(subgoal-tac\ |r-s|<1/?L) apply(subst (asm)\ pos-less-divide-eq[of\ ?L\ |r-s|\ 1]) using assms\ by\ auto\ done
```

### 2.4 Matrix Exponential

The general solution for linear systems of ODEs is an exponential function. Unfortunately, this operation is only available in Isabelle for Banach spaces which are formalised as a class. Hence we need to prove that a specific type is an instance of this class. We define the type and build towards this instantiation in this section.

#### 2.4.1 Squared matrices operations

```
is \lambda i X. column i (to-vec X).
lift-definition vec\text{-}sq\text{-}mtx\text{-}prod::(real \hat{\ }'m) \Rightarrow 'm \ sqrd\text{-}matrix \Rightarrow (real \hat{\ }'m) \text{ is } vector\text{-}matrix\text{-}mult
lift-definition sq\text{-}mtx\text{-}diag::real \Rightarrow ('m::finite) sqrd\text{-}matrix (diag) is mat.
lift-definition sq\text{-}mtx\text{-}transpose::('m::finite) sqrd\text{-}matrix <math>\Rightarrow 'm sqrd\text{-}matrix (-^{\dagger}) is
transpose.
lift-definition sq\text{-}mtx\text{-}row::'m \Rightarrow ('m::finite) sqrd\text{-}matrix \Rightarrow real^{'}m \text{ (row)} is row
lift-definition sq\text{-}mtx\text{-}col::'m \Rightarrow ('m::finite) sqrd\text{-}matrix \Rightarrow real^{'}m \text{ (col)} is col
umn .
lift-definition sq\text{-}mtx\text{-}rows::('m::finite) sqrd\text{-}matrix <math>\Rightarrow (real \ 'm) set is rows.
lift-definition sq\text{-}mtx\text{-}cols::('m::finite) \ sqrd\text{-}matrix \Rightarrow (real \hat{\ }'m) \ set \ \mathbf{is} \ columns .
lemma sq-mtx-eq-iff:
  shows (\land i. A \$\$ i = B \$\$ i) \Longrightarrow A = B
    and (\bigwedge i j. A \$\$ i \$ j = B \$\$ i \$ j) \Longrightarrow A = B
  \mathbf{by}(\mathit{transfer}, \mathit{simp} \; \mathit{add} \colon \mathit{vec}\text{-}\mathit{eq}\text{-}\mathit{iff}) +
lemma sq\text{-}mtx\text{-}vec\text{-}prod\text{-}eq: m *_V x = (\chi i. sum (\lambda j. ((m\$\$i)\$j) * (x\$j)) UNIV)
  by(transfer, simp add: matrix-vector-mult-def)
lemma sq\text{-}mtx\text{-}transpose\text{-}transpose[simp]:}(A^{\dagger})^{\dagger} = A
  \mathbf{by}(transfer, simp)
lemma transpose-mult-vec-canon-row[simp]:(A^{\dagger}) *_{V} (e \ i) = \text{row } i \ A
  by transfer (simp add: row-def transpose-def axis-def matrix-vector-mult-def)
lemma row-ith[simp]:row i A = A $$ i
  by transfer (simp add: row-def)
lemma mtx-vec-prod-canon:A *_V (e i) = col i A
  by (transfer, simp add: matrix-vector-mult-basis)
```

#### 2.4.2 Squared matrices form Banach space

```
 \begin{array}{ll} \textbf{instantiation} \ \textit{sqrd-matrix} :: (\textit{finite}) \ \textit{ring} \\ \textbf{begin} \end{array}
```

**lift-definition** plus-sqrd-matrix :: 'a sqrd-matrix  $\Rightarrow$  'a sqrd-matrix  $\Rightarrow$  'a sqrd-matrix is (+) .

lift-definition zero-sqrd-matrix :: 'a sqrd-matrix is  $\theta$  .

```
lift-definition uminus-sqrd-matrix ::'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix is uminus.
lift-definition minus-sqrd-matrix :: 'a sqrd-matrix \Rightarrow 'a sqrd-matrix
is (-).
lift-definition times-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix \Rightarrow 'a sqrd-matrix
is (**) .
declare plus-sqrd-matrix.rep-eq [simp]
   and minus-sqrd-matrix.rep-eq [simp]
instance apply intro-classes
 \mathbf{by}(transfer, simp\ add: algebra-simps\ matrix-mul-assoc\ matrix-add-rdistrib\ matrix-add-ldistrib) +
end
lemma sq\text{-}mtx\text{-}plus\text{-}ith[simp]:(A + B) \$\$ i = A \$\$ i + B \$\$ i
 \mathbf{by}(unfold\ plus\text{-}sqrd\text{-}matrix\text{-}def,\ transfer,\ simp)
lemma sq\text{-}mtx\text{-}minus\text{-}ith[simp]:(A - B) \$\$ i = A \$\$ i - B \$\$ i
  \mathbf{by}(unfold\ minus-sqrd-matrix-def,\ transfer,\ simp)
lemma mtx-vec-prod-add-rdistr:(A + B) *_V x = A *_V x + B *_V x
  unfolding plus-sqrd-matrix-def apply(transfer)
  by (simp add: matrix-vector-mult-add-rdistrib)
lemma mtx-vec-prod-minus-rdistrib:(A - B) *_{V} x = A *_{V} x - B *_{V} x
 unfolding minus-sqrd-matrix-def by(transfer, simp add: matrix-vector-mult-diff-rdistrib)
lemma sq\text{-}mtx\text{-}times\text{-}vec\text{-}assoc: (A * B) *_V x0 = A *_V (B *_V x0)
  by (transfer, simp add: matrix-vector-mul-assoc)
lemma sq\text{-}mtx\text{-}vec\text{-}mult\text{-}sum\text{-}cols\text{:}A *_{V} x = sum \ (\lambda i. \ x \$ \ i *_{R} \operatorname{col} \ i \ A) \ UNIV
  by(transfer) (simp add: matrix-mult-sum scalar-mult-eq-scaleR)
instantiation sqrd-matrix :: (finite) real-normed-vector
begin
definition norm-sqrd-matrix :: 'a sqrd-matrix \Rightarrow real where ||A|| = ||to\text{-vec }A||_{op}
lift-definition scaleR-sqrd-matrix::real \Rightarrow 'a \ sqrd-matrix \Rightarrow 'a \ sqrd-matrix is scaleR
definition sgn\text{-}sqrd\text{-}matrix :: 'a sqrd\text{-}matrix <math>\Rightarrow 'a sqrd\text{-}matrix
  where sgn\text{-}sqrd\text{-}matrix\ A = (inverse\ (\|A\|)) *_R A
definition dist-sqrd-matrix :: 'a sqrd-matrix <math>\Rightarrow 'a sqrd-matrix <math>\Rightarrow real
  where dist-sqrd-matrix A B = ||A - B||
```

```
definition uniformity-sqrd-matrix :: ('a sqrd-matrix \times 'a sqrd-matrix) filter
    where uniformity-sqrd-matrix = (INF e: \{0 < ...\}). principal \{(x, y). dist x < e
definition open-sqrd-matrix :: 'a sqrd-matrix set \Rightarrow bool
   where open-sqrd-matrix U = (\forall x \in U. \forall x \in U. \forall x \in U. \forall x \in V. 
 U
instance apply intro-classes
   unfolding sqn-sqrd-matrix-def open-sqrd-matrix-def dist-sqrd-matrix-def uniformity-sqrd-matrix-def
    prefer 10 apply(transfer, simp add: norm-sqrd-matrix-def op-norm-triangle)
   prefer 9 apply(simp-all add: norm-sqrd-matrix-def zero-sqrd-matrix-def op-norm-zero-iff)
    by(transfer, simp add: norm-sqrd-matrix-def op-norm-scaleR algebra-simps)+
end
lemma sq\text{-}mtx\text{-}scaleR\text{-}ith[simp]: (c *_R A) $$ i = (c *_R (A $$ i))
    by(unfold scaleR-sqrd-matrix-def, transfer, simp)
lemma le-mtx-norm: m \in \{ ||A *_V x|| ||x|| ||x||| = 1 \} \Longrightarrow m \leq ||A||
    using cSup\text{-}upper[of - \{ ||(to\text{-}vec\ A) *v\ x|| \mid x. ||x|| = 1 \}]
   by (simp\ add:\ op-norm-set-proptys(2)\ norm-sqrd-matrix-def\ sq-mtx-vec-prod.rep-eq)
lemma norm-vec-mult-le: ||A *_V x|| \le (||A||) * (||x||)
   by (simp add: norm-matrix-le-mult-op-norm norm-sqrd-matrix-def sq-mtx-vec-prod.rep-eq)
lemma sq\text{-}mtx\text{-}norm\text{-}le\text{-}sum\text{-}col: ||A|| \leq (\sum i \in UNIV. ||col| i| A||)
   using op-norm-le-sum-column[of to-vec A] apply(simp add: norm-sqrd-matrix-def)
    by(transfer, simp add: op-norm-le-sum-column)
lemma norm-le-transpose: ||A|| \le ||A^{\dagger}||
    \mathbf{apply}(simp\ add:\ norm\text{-}sqrd\text{-}matrix\text{-}def,\ transfer,\ simp\ add:\ transpose\text{-}def)
    using op\text{-}norm\text{-}set\text{-}proptys(3) apply(rule\ cSup\text{-}least)
proof(clarsimp)
    fix A::real^{a} and a::real^{a} assume ||x|| = 1
    have obs: \forall x. \|x\| = 1 \longrightarrow (\|A * v x\|) \leq sqrt ((\|transpose A * * A\|_{op})) * (\|x\|)
        using norm-matrix-vec-mult-le-transpose by blast
    have (\|A\|_{op}) \leq sqrt ((\|transpose\ A ** A\|_{op}))
         using op\text{-}norm\text{-}set\text{-}proptys(3) apply(rule\ cSup\text{-}least) using obs\ by\ clarsimp
     then have ((\|A\|_{op}))^2 \leq (\|transpose\ A ** A\|_{op})
         using power-mono[of (||A||_{op}) - 2] norm-matrix-le-op-norm-ge-0 by force
    also have ... \leq (\|transpose\ A\|_{op}) * (\|A\|_{op})
        using op-norm-matrix-matrix-mult-le by blast
    finally have ((\|A\|_{op}))^2 \leq (\|transpose\ A\|_{op}) * (\|A\|_{op}) by linarith
    hence (\|A\|_{op}) \leq (\|transpose\ A\|_{op})
        using sq-le-cancel [of (||A||_{op})] norm-matrix-le-op-norm-ge-0 by blast
     thus (\|A * v x\|) \leq op\text{-}norm \ (\chi \ i \ j. \ A \$ \ j \$ \ i)
        unfolding transpose-def using \langle ||x|| = 1 \rangle order-trans norm-matrix-le-op-norm
by blast
```

```
qed
lemma norm-eq-norm-transpose[simp]: ||A^{\dagger}|| = ||A||
 using norm-le-transpose [of A] and norm-le-transpose [of A^{\dagger}] by simp
lemma norm-column-le-norm: ||A \$\$ i|| < ||A||
  using norm-vec-mult-le [of A^{\dagger} e i] by simp
instantiation sqrd-matrix :: (finite) real-normed-algebra-1
begin
lift-definition one-sqrd-matrix :: 'a sqrd-matrix is sq-mtx-chi (mat 1).
lemma sq\text{-}mtx\text{-}one\text{-}idty: 1*A=AA*1=A for A::'a sqrd\text{-}matrix
 by (transfer, transfer, unfold mat-def matrix-matrix-mult-def, simp add: vec-eq-iff)+
lemma sq\text{-}mtx\text{-}norm\text{-}1: ||(1::'a \ sqrd\text{-}matrix)|| = 1
  unfolding one-sqrd-matrix-def norm-sqrd-matrix-def apply simp
  apply(subst\ cSup-eq[of-1])
  using ex-norm-eq-1 by auto
lemma sq\text{-}mtx\text{-}norm\text{-}times: ||A * B|| \le (||A||) * (||B||) for A::'a \ sqrd\text{-}matrix
 \mathbf{unfolding}\ norm\text{-}sqrd\text{-}matrix\text{-}def\ times\text{-}sqrd\text{-}matrix\text{-}def\ \mathbf{by}(simp\ add:\ op\text{-}norm\text{-}matrix\text{-}matrix\text{-}mult\text{-}le)
instance apply intro-classes
  apply(simp-all add: sq-mtx-one-idty sq-mtx-norm-1 sq-mtx-norm-times)
 apply(simp-all add: sq-mtx-chi-inject vec-eq-iff one-sqrd-matrix-def zero-sqrd-matrix-def
  by(transfer, simp add: scalar-matrix-assoc matrix-scalar-ac)+
end
lemma sq\text{-}mtx\text{-}one\text{-}vec: 1 *_V s = s
 by (auto simp: sq-mtx-vec-prod-def one-sqrd-matrix-def
     mat-def vec-eq-iff matrix-vector-mult-def)
lemma Cauchy-cols:
  fixes X :: nat \Rightarrow ('a::finite) \ sqrd-matrix
  assumes Cauchy X
  shows Cauchy (\lambda n. \text{ col } i (X n))
proof(unfold Cauchy-def dist-norm, clarsimp)
  fix \varepsilon::real assume \varepsilon > 0
  from this obtain M where M-def: \forall m \geq M. \forall n \geq M. ||X m - X n|| < \varepsilon
    using \langle Cauchy X \rangle unfolding Cauchy-def by (simp\ add:\ dist-sqrd-matrix-def)
blast
  \{ \text{fix } m \text{ } n \text{ assume } m \geq M \text{ and } n \geq M \}
   hence \varepsilon > \|X m - X n\|
     using M-def by blast
```

```
moreover have ||X m - X n|| \ge ||(X m - X n) *_{V} e i||
      \mathbf{by}(rule\ le\text{-}mtx\text{-}norm[of\ -\ X\ m\ -\ X\ n],\ force)
    moreover have \|(X\ m\ -\ X\ n)\ *_{V}\ \mathrm{e}\ i\| = \|X\ m\ *_{V}\ \mathrm{e}\ i\ -\ X\ n\ *_{V}\ \mathrm{e}\ i\|
      \mathbf{by}\ (simp\ add\colon mtx\text{-}vec\text{-}prod\text{-}minus\text{-}rdistrib)
    moreover have ... = \|\operatorname{col} i(X m) - \operatorname{col} i(X n)\|
      by (simp add: mtx-vec-prod-minus-rdistrib mtx-vec-prod-canon)
    ultimately have \|\operatorname{col} i(X m) - \operatorname{col} i(X n)\| < \varepsilon
      by linarith}
  thus \exists M. \ \forall m \geq M. \ \forall n \geq M. \ \|\text{col}\ i\ (X\ m) - \text{col}\ i\ (X\ n)\| < \varepsilon
    by blast
\mathbf{qed}
lemma col-convergent:
  assumes \forall i. (\lambda n. \text{ col } i (X n)) \longrightarrow L \$ i
  shows convergent X
  unfolding convergent-def proof(rule-tac x=sq-mtx-chi (transpose L) in exI)
  let ?L = sq\text{-}mtx\text{-}chi \ (transpose \ L)
  show X \longrightarrow ?L
  proof(unfold LIMSEQ-def dist-norm, clarsimp)
    fix \varepsilon::real assume \varepsilon > 0
    let ?a = CARD('a) fix \varepsilon::real assume \varepsilon > 0
    hence \varepsilon / ?a > 0
      \mathbf{by} \ simp
    from this and assms have \forall i. \exists N. \forall n \geq N. \| \text{col } i (X n) - L \$ i \| < \varepsilon / ?a
      unfolding LIMSEQ-def dist-norm convergent-def by blast
    then obtain N where \forall i. \forall n \geq N. \|\text{col } i \ (X \ n) - L \ \|i\| < \varepsilon / ?a
      using finite-nat-minimal-witness[of \lambda i n. \|\text{col } i(X n) - L \$ i\| < \varepsilon/?a] by
blast
    also have \bigwedge i \ n \cdot (\operatorname{col} \ i \ (X \ n) - L \ \ i) = (\operatorname{col} \ i \ (X \ n - \ ?L))
    unfolding minus-sqrd-matrix-def by (transfer, simp add: transpose-def vec-eq-iff
column-def)
    ultimately have N-def:\forall i. \forall n \geq N. \|\text{col } i \ (X \ n - ?L)\| < \varepsilon / ?a
      by auto
    have \forall n \geq N. ||X n - ?L|| < \varepsilon
    proof(rule allI, rule impI)
      fix n::nat assume N \leq n
      hence \forall i. \| \text{col } i (X n - ?L) \| < \varepsilon / ?a
         using N-def by blast
      hence (\sum i \in UNIV. \|\text{col } i \ (X \ n - ?L)\|) < (\sum (i::'a) \in UNIV. \varepsilon / ?a)
         using sum-strict-mono[of - \lambda i. \|\operatorname{col} i(X n - ?L)\|] by force
      moreover have ||X n - ?L|| \le (\sum i \in UNIV. ||col i (X n - ?L)||)
         using sq\text{-}mtx\text{-}norm\text{-}le\text{-}sum\text{-}col by blast
      moreover have (\sum (i::'a) \in UNIV. \varepsilon/?a) = \varepsilon
         by force
      ultimately show ||X n - ?L|| < \varepsilon
         by linarith
    qed
    thus \exists no. \forall n > no. ||X n - ?L|| < \varepsilon
      by blast
```

```
qed
qed
instance \ sqrd-matrix :: (finite) \ banach
proof(standard)
  \mathbf{fix} \ X :: nat \Rightarrow 'a \ sqrd-matrix
  assume Cauchy X
  have \bigwedge i. Cauchy (\lambda n. \text{ col } i (X n))
    using \langle Cauchy X \rangle Cauchy-cols by blast
  hence obs: \forall i. \exists ! L. (\lambda n. \operatorname{col} i (X n)) \longrightarrow L
    using Cauchy-convergent convergent-def LIMSEQ-unique by fastforce
  define L where L = (\chi i. lim (\lambda n. col i (X n)))
     om this and obs have \forall i. (\lambda n. \text{ col } i (X n)) \longrightarrow L \$ i
using the I-unique [of \lambda L. (\lambda n. \text{ col } - (X n)) \longrightarrow L L \$ -] by (simp add:
  from this and obs have \forall i. (\lambda n. \text{ col } i (X n)) —
lim-def)
  thus convergent X
    using col-convergent by blast
qed
```

#### 2.5 Flow for squared matrix systems

Finally, we can use the *exp* operation to characterize the general solutions for linear systems of ODEs. After this, we show that IVPs with these systems have a unique solution (using the Picard Lindeloef locale) and explicitly write it via the local flow locale.

```
\mathbf{lemma}\ mtx\text{-}vec\text{-}prod\text{-}has\text{-}derivative\text{-}mtx\text{-}vec\text{-}prod\text{:}
  assumes \bigwedge i j. D (\lambda t. (A t) \$\$ i \$ j) \mapsto (\lambda \tau. \tau *_R (A't) \$\$ i \$ j) (at t within
s)
    and (\lambda \tau. \ \tau *_R (A' \ t) *_V x) = g'
  shows D(\lambda t. A t *_{V} x) \mapsto g' at t within s
  using assms(2) apply safe apply(rule\ ssubst[of\ g'\ (\lambda\tau.\ \tau\ *_R\ (A'\ t)\ *_V\ x)],
simp)
  unfolding sq\text{-}mtx\text{-}vec\text{-}mult\text{-}sum\text{-}cols
 \operatorname{apply}(\operatorname{rule-tac} f'1 = \lambda i \ \tau. \ \tau *_R \ (x \ \$ \ i *_R \operatorname{col} \ i \ (A' \ t)) \ \operatorname{in} \ \operatorname{derivative-eq-intros}(9))
   apply(simp-all\ add:\ scaleR-right.sum)
 apply(rule-tac g'1 = \lambda \tau. \tau *_R \operatorname{col} i (A't) in derivative-eq-intros(4), simp-all add:
mult.commute)
  using assms unfolding sq-mtx-col-def column-def apply(transfer, simp)
  apply(rule has-derivative-vec-lambda)
  \mathbf{by}(simp\ add:\ scaleR\text{-}vec\text{-}def)
lemma has-derivative-mtx-ith:
  assumes D A \mapsto (\lambda h. h *_R A' x) at x within s
  shows D(\lambda t. A t \$\$ i) \mapsto (\lambda h. h *_R A' x \$\$ i) at x within s
  unfolding has-derivative-def tendsto-iff dist-norm apply safe
   apply(force simp: bounded-linear-def bounded-linear-axioms-def)
proof(clarsimp)
  fix \varepsilon::real assume \theta < \varepsilon
```

```
let ?x = net limit (at x within s) let ?\Delta y = y - ?x and ?\Delta A y = A y - A ?x
 let ?P \ e = \lambda y. inverse \ |?\Delta \ y| * (||?\Delta A \ y - ?\Delta \ y *_R A' \ x||) < e
 let ?Q = \lambda y. inverse |?\Delta y| * (||A y \$\$ i - A ?x \$\$ i - ?\Delta y *_R A' x \$\$ i||)
  from assms have \forall e > 0. eventually (?P e) (at x within s)
   unfolding has-derivative-def tendsto-iff by auto
 hence eventually (?P \varepsilon) (at x within s)
   using \langle \theta < \varepsilon \rangle by blast
  thus eventually ?Q (at x within s)
  \operatorname{proof}(rule\text{-}tac\ P=?P\ \varepsilon\ \mathbf{in}\ eventually\text{-}mono,\ simp\text{-}all)
   let ?u\ y\ i = A\ y\$$ i-A\ ?x\$$ i-?\Delta\ y*_R\ A'\ x\$$ i
   fix y assume hyp: inverse |?\Delta y| * (||?\Delta A y - ?\Delta y *_R A' x||) < \varepsilon
   have \|?u\ y\ i\| = \|(?\Delta A\ y - ?\Delta\ y *_R A'\ x) \$\$\ i\|
     by simp
   also have ... \leq (\|?\Delta A y - ?\Delta y *_R A' x\|)
     using norm-column-le-norm by blast
   ultimately have \|?u\ y\ i\| \leq \|?\Delta A\ y - ?\Delta\ y *_R A'\ x\|
     by linarith
    hence inverse |?\Delta y| * (||?u y i||) \le inverse |?\Delta y| * (||?\Delta A y - ?\Delta y *_R)
A'x\|
     by (simp add: mult-left-mono)
   thus inverse |?\Delta y| * (||?u y i||) < \varepsilon
     using hyp by linarith
  qed
qed
lemma exp-has-vderiv-on-linear:
  fixes A::(('a::finite) \ sqrd-matrix)
 shows D(\lambda t. exp((t-t\theta)*_R A)*_V x\theta) = (\lambda t. A*_V (exp((t-t\theta)*_R A)*_V
x\theta)) on T
  unfolding has-vderiv-on-def has-vector-derivative-def apply clarsimp
 apply(rule-tac\ A'=\lambda t.\ A*exp\ ((t-t\theta)*_RA)\ in\ mtx-vec-prod-has-derivative-mtx-vec-prod)
  apply(rule has-derivative-vec-nth)
  apply(rule has-derivative-mtx-ith)
  apply(rule-tac\ f'=id\ in\ exp-scaleR-has-derivative-right)
   apply(rule-tac f'1=id and g'1=\lambda x. 0 in derivative-eq-intros(11))
     apply(rule derivative-eq-intros)
  \mathbf{by}(simp\text{-}all\ add:\ fun\text{-}eq\text{-}iff\ exp\text{-}times\text{-}scaleR\text{-}commute\ sq\text{-}mtx\text{-}times\text{-}vec\text{-}assoc})
lemma picard-lindeloef-sq-mtx:
  fixes A::('n::finite) sqrd-matrix
  assumes \theta < ((real\ CARD('n))^2 * (\|to\text{-}vec\ A\|_{max})) (is \theta < ?L)
  assumes 0 \le t and t < 1/?L
 shows picard-lindeloef (\lambda t s. A *_{V} s) {0..t} ?L 0
  apply unfold-locales apply(simp add: \langle 0 \leq t \rangle)
  subgoal by (transfer, simp, metis continuous-on-compose2 continuous-on-cong
continuous-on-id
        continuous-on-snd matrix-vector-mult-linear-continuous-on top-greatest)
 subgoal apply transfer using matrix-lipschitz-constant max-norm-qe-0 zero-compare-simps (4,12)
```

```
unfolding lipschitz-on-def by blast
 apply(simp-all add: assms)
 subgoal for r \ s \ apply(subgoal-tac \ |r-s| < 1/?L)
    apply(subst\ (asm)\ pos-less-divide-eq[of\ ?L\ |r-s|\ 1])
   using assms by auto
 done
lemma local-flow-exp:
 fixes A::('n::finite) sqrd-matrix
 assumes \theta < ((real\ CARD('n))^2 * (\|to\text{-}vec\ A\|_{max})) (is \theta < ?L)
 assumes 0 \le t and t < 1/?L
 shows local-flow (\lambda s.\ A*_{V}s) {0..t} ((real CARD('n))^2* (\|to\text{-}vec\ A\|_{max})) ((\lambda t
s. exp (t *_R A) *_V s))
 {\bf unfolding} \ local \hbox{-} {\it flow-def local-flow-axioms-def } \ {\bf apply} \ safe
 using picard-lindeloef-sq-mtx assms apply blast
 using exp-has-vderiv-on-linear[of \theta] apply force
 \mathbf{by}(auto\ simp:\ sq-mtx-one-vec)
end
theory cat2funcset
 \mathbf{imports}\ ../hs\text{-}prelims\ Transformer\text{-}Semantics.Kleisli\text{-}Quantale
begin
```

# Chapter 3

# **Hybrid System Verification**

— We start by deleting some conflicting notation and introducing some new. **type-synonym** ' $a \ pred = 'a \Rightarrow bool$ 

# 3.1 Verification of regular programs

```
First we add lemmas for computation of weakest liberal preconditions (wlps).
```

```
lemma ffb-eta[simp]:fb_{\mathcal{F}} \eta X = X
  unfolding ffb-def by(simp add: kop-def klift-def map-dual-def)
lemma ffb-eq:fb<sub>F</sub> F X = \{s. \forall y. y \in F s \longrightarrow y \in X\}
  unfolding ffb-def apply(simp add: kop-def klift-def map-dual-def)
  unfolding dual-set-def f2r-def r2f-def by auto
lemma ffb-eq-univD:fb<sub>F</sub> F P = UNIV \Longrightarrow (\forall y. y \in (F x) \longrightarrow y \in P)
proof
  fix y assume fb_{\mathcal{F}} FP = UNIV
  hence UNIV = \{s. \ \forall y. \ y \in (F \ s) \longrightarrow y \in P\}
    \mathbf{by}(subst\ ffb\text{-}eq[THEN\ sym],\ simp)
  hence \bigwedge x. \{x\} = \{s. \ s = x \land (\forall y. \ y \in (F \ s) \longrightarrow y \in P)\}
    by auto
  then show s2p (F x) y \longrightarrow y \in P
    by auto
qed
Next, we introduce assignments and their wlps.
abbreviation vec-upd :: ('a^{\dot{}}b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a^{\dot{}}b \ (-(2[-:==-])[70, 65] 61)
  where x[i :== a] \equiv (\chi j. (if j = i then a else (x \$ j)))
abbreviation assign :: 'b \Rightarrow ('a^{\hat{}}b \Rightarrow 'a) \Rightarrow ('a^{\hat{}}b) \Rightarrow ('a^{\hat{}}b) set ((2[-::==-])
[70, 65] 61)
  where [x ::== expr] \equiv (\lambda s. \{s[x :== expr s]\})
\mathbf{lemma} \ \mathit{ffb-assign}[\mathit{simp}] \colon \mathit{fb}_{\mathcal{F}} \ ([x ::== \mathit{expr}]) \ \mathit{Q} = \{\mathit{s}. \ (\mathit{s}[x :== \mathit{expr} \ \mathit{s}]) \in \mathit{Q}\}
```

```
\mathbf{by}(subst\ ffb\text{-}eq,\ simp)
The wlp of a (kleisli) composition is just the composition of the wlps.
lemma ffb-kcomp:fb<sub>F</sub> (G \circ_K F) P = fb_F G (fb_F F P)
  unfolding ffb-def apply(simp add: kop-def klift-def map-dual-def)
  unfolding dual-set-def f2r-def r2f-def by(auto simp: kcomp-def)
We also have an implementation of the conditional operator and its wlp.
definition if then else :: 'a pred \Rightarrow ('a \Rightarrow 'b set) \Rightarrow ('a \Rightarrow 'b set) \Rightarrow ('a \Rightarrow 'b set)
  (IF - THEN - ELSE - FI [64,64,64] 63) where
  IF P THEN X ELSE Y FI \equiv (\lambda x. if P x then X x else Y x)
lemma ffb-if-then-else:
  assumes P \cap \{s. \ T \ s\} \leq fb_{\mathcal{F}} \ X \ Q
   and P \cap \{s. \neg T s\} \leq fb_{\mathcal{F}} Y Q
  shows P \leq fb_{\mathcal{F}} (IF T THEN X ELSE Y FI) Q
  using assms apply(subst\ ffb-eq)
  apply(subst (asm) ffb-eq)+
  unfolding ifthenelse-def by auto
lemma ffb-if-then-elseD:
  assumes T x \longrightarrow x \in fb_{\mathcal{F}} X Q
   \mathbf{and}\, \neg \,\, T\, x\, \longrightarrow x \in \mathit{fb}_{\mathcal{F}} \,\, Y\, Q
  shows x \in fb_{\mathcal{F}} (IF T THEN X ELSE Y FI) Q
  using assms apply(subst ffb-eq)
  apply(subst (asm) ffb-eq)+
  unfolding ifthenelse-def by auto
The final wlp we add is that of the finite iteration.
lemma kstar-inv:I \leq \{s. \ \forall y. \ y \in F \ s \longrightarrow y \in I\} \Longrightarrow I \leq \{s. \ \forall y. \ y \in (kpower)\}
F \ n \ s) \longrightarrow y \in I
 apply(induct \ n, \ simp)
  \mathbf{by}(auto\ simp:\ kcomp-prop)
lemma ffb-star-induct-self:I \leq fb_{\mathcal{F}} \ F \ I \Longrightarrow I \subseteq fb_{\mathcal{F}} \ (kstar \ F) \ I
  \mathbf{apply}(\mathit{subst\ ffb-eq},\ \mathit{subst\ }(\mathit{asm})\ \mathit{ffb-eq})
  unfolding kstar-def apply clarsimp
  using kstar-inv by blast
lemma ffb-starI:
assumes P \leq I and I \leq fb_F F I and I \leq Q
shows P \leq fb_{\mathcal{F}} (kstar F) Q
proof-
  from assms(2) have I \subseteq fb_{\mathcal{F}} (kstar F) I
    using ffb-star-induct-self by blast
  then have P \leq fb_{\mathcal{F}} (kstar F) I
    using assms(1) by auto
  from this and assms(3) show ?thesis
   by(subst ffb-eq, subst (asm) ffb-eq, auto)
```

qed

# 3.2 Verification of hybrid programs

# 3.2.1 Verification by providing solutions

```
abbreviation guards :: ('a \Rightarrow bool) \Rightarrow (real \Rightarrow 'a) \Rightarrow (real set) \Rightarrow bool (- \triangleright - -
[70, 65] 61)
  where G \triangleright x \ T \equiv \forall \ r \in T. \ G \ (x \ r)
definition ivp-sols f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp-solsI:
 assumes D x = (f \circ x) on T x t_0 = s t_0 \in T
 shows x \in ivp\text{-}sols f T t_0 s
 using assms unfolding ivp-sols-def by blast
lemma ivp-solsD:
 assumes x \in ivp\text{-}sols f T t_0 s
 shows D x = (f \circ x) on T
    and x t_0 = s and t_0 \in T
  using assms unfolding ivp-sols-def by auto
We use closed segments instead of closed intervals for the following definition
due to the following property.
lemma (t::real) \in \{\theta--t\}
 by (rule\ ends-in-segment(2))
lemma (t::real) \in \{0..t\}
  apply auto
 oops
definition g-orbital f \ T \ t_0 \ G \ s = \bigcup \{ \{x \ t | t. \ t \in T \land G \rhd x \ \{t_0 - -t\} \} | x. \ x \in T \land G \rhd x \} \}
ivp-sols f T t_0 s}
lemma g-orbital-eq: g-orbital f T t_0 G s =
 \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0 - -t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t \in T \land G \rhd x\}
\{t_0 - -t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
abbreviation q-evol ::(('a::banach)\Rightarrow'a) \Rightarrow real set \Rightarrow 'a pred \Rightarrow 'a \Rightarrow 'a set
((1[x'=-]-\&-))
  where [x'=f]T \& G \equiv (\lambda \ s. \ g\text{-}orbital \ f \ T \ 0 \ G \ s)
lemmas g-evol-def = g-orbital-eq[where t_0=\theta]
```

```
lemma g-evolI:
 assumes D x = (f \circ x) on T x \theta = s
   and \theta \in T \ t \in T \ \text{and} \ G \rhd x \ \{\theta - -t\}
 shows x \ t \in ([x'=f]T \& G) \ s
  using assms unfolding q-orbital-def ivp-sols-def by blast
lemma q-evolD:
  assumes s' \in ([x'=f]T \& G) s
  obtains x and t where x \in ivp\text{-}sols f T \theta s
 and D x = (f \circ x) on T x \theta = s
 and x t = s' and \theta \in T t \in T and G \rhd x \{\theta - -t\}
  using assms unfolding g-orbital-def ivp-sols-def by blast
context local-flow
begin
lemma in-ivp-sols: (\lambda t. \varphi t s) \in ivp-sols f T \theta s
 by(auto intro: ivp-solsI simp: ivp init-time)
definition orbit s = g-orbital f T \theta (\lambda s. True) s
lemma orbit-eq[simp]: orbit s = \{ \varphi \ t \ s | \ t. \ t \in T \}
  unfolding orbit-def g-evol-def
 by(auto intro: usolves-ivp intro!: ivp simp: init-time)
\mathbf{lemma}\ g-evol-collapses:
  shows ([x'=f]T \& G) s = \{\varphi t s | t. t \in T \land G \rhd (\lambda r. \varphi r s) \{\theta--t\}\} (is -
= ?qorbit)
proof(rule subset-antisym, simp-all only: subset-eq)
  {fix s' assume s' \in ([x'=f]T \& G) s
   then obtain x and t where x-ivp:D x = (f \circ x) on T
      x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \triangleright x \{\theta - -t\}
      unfolding g-orbital-eq by blast
   hence obs: \forall \tau \in \{\theta - -t\}. \ x \ \tau = \varphi \ \tau \ s
      using usolves-ivp[of\ x\ s]\ closed-segment-subset-domain I\ in it-time\ comp-def
      by (metis (mono-tags, lifting) has-vderiv-eq)
   hence G \triangleright (\lambda r. \varphi r s) \{\theta - -t\}
      using guard by simp
   hence s' \in ?gorbit
      using \langle x | t = s' \rangle \langle t \in T \rangle \ obs \ by \ blast
  thus \forall s' \in ([x'=f]T \& G) \ s. \ s' \in ?gorbit
   by blast
next
  \{ \text{fix } s' \text{ assume } s' \in ?gorbit \}
   then obtain t where G \triangleright (\lambda r. \varphi r s) \{\theta - -t\} and t \in T and \varphi t s = s'
     \mathbf{by} blast
   hence s' \in ([x'=f]T \& G) s
      by(auto intro: q-evolI simp: ivp init-time)}
  thus \forall s' \in ?gorbit. \ s' \in ([x'=f]T \& G) \ s
```

```
by blast qed  \begin{aligned} & \text{lemma } \textit{ffb-orbit: } \textit{fb}_{\mathcal{F}} \; (\textit{orbit}) \; Q = \{s. \; \forall \; t \in T. \; \varphi \; t \; s \in Q\} \\ & \text{unfolding } \textit{orbit-eq } \textit{ffb-eq } \textbf{by } \textit{auto} \end{aligned}   \begin{aligned} & \text{lemma } \textit{ffb-g-orbit: } \textit{fb}_{\mathcal{F}} \; ([x'=f] \; T \; \& \; G) \; Q = \{s. \; \forall \; t \in T. \; (G \rhd (\lambda r. \; \varphi \; r \; s) \; \{\theta--t\}) \\ & \longrightarrow \; (\varphi \; t \; s) \in \; Q\} \\ & \text{unfolding } \textit{g-evol-collapses } \textit{ffb-eq } \textbf{by } \textit{auto} \end{aligned}   \begin{aligned} & \text{end} \end{aligned}   \begin{aligned} & \text{lemma } \; (\textbf{in } \textit{global-flow}) \; \textit{ivp-sols-collapse}[\textit{simp}] \colon \textit{ivp-sols } \textit{f } \textit{UNIV } \theta \; s = \{(\lambda t. \; \varphi \; t \; s)\} \\ & \text{by}(\textit{auto intro: usolves-ivp simp: ivp-sols-def ivp)} \end{aligned}
```

The previous lemma allows us to compute wlps for known systems of ODEs. We can also implement a version of it as an inference rule. A simple computation of a wlp is shown immmediately after.

```
{f lemma} dSolution:
```

```
assumes local-flow f T L \varphi and \forall s.\ s \in P \longrightarrow (\forall \ t \in T.\ (G \rhd (\lambda r.\ \varphi \ r.s)\ \{\theta..t\}) \longrightarrow (\varphi \ t.s) \in Q) shows P \leq fb_{\mathcal{F}}\ ([x'=f]T\ \&\ G)\ Q using assms apply(subst local-flow.ffb-g-orbit) by (auto simp: Starlike.closed-segment-eq-real-ivl)
```

```
lemma ffb-line: 0 \le t \Longrightarrow fb_{\mathcal{F}}([x'=\lambda t.\ c]\{0..t\}\ \&\ G)\ Q = \{x.\ \forall\ \tau \in \{0..t\}.\ (G \rhd (\lambda r.\ x+r*_R\ c)\ \{0..\tau\}) \longrightarrow (x+\tau*_R\ c) \in Q\} apply(subst local-flow.ffb-g-orbit[of \lambda t. c - 1/(t+1)\ (\lambda\ t.\ x.\ x+t*_R\ c)]) by(auto\ simp:\ line-is-local-flow\ closed-segment-eq-real-ivl)
```

# 3.2.2 Verification with differential invariants

We derive domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in our verification proofs.

### Differential Weakening

```
lemma DW:
   shows fb_{\mathcal{F}} ([x'=f]T \& G) Q = fb_{\mathcal{F}} ([x'=f]T \& G) \{s. \ G \ s \longrightarrow s \in Q\}
   by(auto intro: g-evolD simp: ffb-eq)

lemma dWeakening:
   assumes \{s. \ G \ s\} \leq Q
   shows P \leq fb_{\mathcal{F}} ([x'=f]T \& G) Q
```

**using** assms **by**(auto intro: g-evolD simp: le-fun-def g-evol-def ffb-eq)

# Differential Cut

```
\mathbf{lemma}\ \mathit{ffb-g-orbit-eq-univD}:
  assumes fb_{\mathcal{F}}([x'=f]T \& G) \{s. Cs\} = UNIV
    and \forall r \in \{0--t\}. \ x \ r \in ([x'=f] \ T \ \& \ G) \ s
  shows \forall r \in \{0--t\}. C(x r)
proof
  fix r assume r \in \{\theta - -t\}
  then have x r \in ([x'=f]T \& G) s
    using assms(2) by blast
  also have \forall y. y \in ([x'=f]T \& G) s \longrightarrow C y
    using assms(1) ffb-eq-univD by fastforce
  ultimately show C(x r) by blast
qed
lemma DC:
  assumes interval T and fb_{\mathcal{F}} ([x'=f]T \& G) \{s. C s\} = UNIV
 shows fb_{\mathcal{F}} ([x'=f]T \& G) Q = fb_{\mathcal{F}} ([x'=f]T \& (\lambda s. G s \land C s)) Q
\operatorname{proof}(\operatorname{rule-tac} f = \lambda \ x. \ \operatorname{fb}_{\mathcal{F}} \ x \ Q \ \operatorname{in} \ HOL. \operatorname{arg-cong}, \ \operatorname{rule} \ \operatorname{ext}, \ \operatorname{rule} \ \operatorname{subset-antisym})
  {fix s' assume s' \in ([x'=f]T \& G) s
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
      and guard-x: G \triangleright x \{0--t\} and s' = x t and \theta \in T t \in T
      using g-evolD[of s' f T G s] by (metis (full-types))
    from guard-x have \forall r \in \{0--t\}. \forall \tau \in \{0--r\}. G(x\tau)
      by (metis\ contra-subset D\ ends-in-segment(1)\ subset-segment(1))
    also have \forall \tau \in \{0--t\}. \ \tau \in T
      by blast
    ultimately have \forall \tau \in \{0--t\}. x \tau \in ([x'=f]T \& G) s
      using g-evolI[OF x-ivp \langle \theta \in T \rangle] by blast
    hence C > x \{\theta - -t\}
      using ffb-g-orbit-eq-univD assms(2) by blast
    hence s' \in ([x'=f]T \& (\lambda s. G s \land C s)) s
      using g-evolI[OF x-ivp \langle 0 \in T \rangle \langle t \in T \rangle] guard-x \langle s' = x t \rangle by fastforce}
  thus ([x'=f]T \& G) \ s \subseteq ([x'=f]T \& (\lambda s. \ G \ s \land C \ s)) \ s
    by blast
next show \bigwedge s. ([x'=f]T \& (\lambda s. G s \land C s)) s \subseteq ([x'=f]T \& G) s
    by (auto simp: q-evol-def)
\mathbf{qed}
lemma dCut:
  assumes ffb-C:P \le fb_{\mathcal{F}} ([x'=f]\{0..t\} \& G) \{s. C s\}
    and ffb-Q:P \le fb_{\mathcal{F}} ([x'=f]\{0..t\} \& (\lambda s. G s \land C s)) Q
  shows P \leq fb_{\mathcal{F}} ([x'=f]\{\theta..t\} \& G) Q
proof(subst ffb-eq, subst g-evol-def, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a assume (x \ \theta) \in P and \theta \leq \tau and \tau \leq t
```

```
and x-solves: D = (\lambda t. f(x t)) on \{0...t\} and guard-x: (\forall r \in \{0--\tau\}). G(x)
r))
  hence \forall r \in \{0 - -\tau\}. \forall \tau \in \{0 - -r\}. G(x \tau)
    using closed-segment-closed-segment-subset by blast
  hence \forall r \in \{0 - -\tau\}. \ x \ r \in ([x'=f]\{0..t\} \& G) \ (x \ 0)
    using g-evol x-solves \langle 0 < \tau \rangle \langle \tau < t \rangle closed-segment-eg-real-ivl by fastforce
  hence \forall r \in \{\theta - -\tau\}. C(x r)
    using ffb-C \langle (x \ \theta) \in P \rangle by(subst (asm) ffb-eq, auto)
  hence x \tau \in ([x'=f] \{ \theta ... t \} \& (\lambda s. G s \wedge C s)) (x \theta)
    using g-evolI x-solves guard-x \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  from this \langle (x \ \theta) \in P \rangle and ffb-Q show (x \ \tau) \in Q
    by(subst (asm) ffb-eq, auto simp: closed-segment-eq-real-ivl)
qed
Differential Invariant
lemma DI-sufficiency:
  assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
  shows fb_{\mathcal{F}} ([x'=f]T \& G) Q \leq fb_{\mathcal{F}} (\lambda x. \{s. s = x \land G s\}) Q
  using assms apply(subst ffb-eq, subst ffb-eq, clarsimp)
  apply(rename-tac\ s,\ erule-tac\ x=s\ in\ all E,\ erule\ impE)
  apply(simp add: g-evol-def ivp-sols-def)
  apply(erule-tac \ x=s \ in \ all E, \ clarify)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
  shows fb_{\mathcal{F}} (\lambda x. \{s. s = x \land G s\}) Q \leq fb_{\mathcal{F}} ([x'=f]T \& G) Q
  unfolding ffb-g-orbit apply(subst ffb-eq, clarsimp, safe)
   apply(erule-tac \ x=0 \ in \ ballE)
    apply(simp add: ivp, simp)
  oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
\Rightarrow bool
((-)/is'-diff'-invariant'-of(-)/along(-)[70,65]61)
where I is-diff-invariant-of f along T \equiv
  (\forall s. \ I \ s \longrightarrow (\forall \ x. \ x \in ivp\text{-sols} \ f \ T \ 0 \ s \longrightarrow (\forall \ t \in T. \ I \ (x \ t))))
\mathbf{lemma}\ invariant\text{-}to\text{-}set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s.\ Is \longrightarrow (q\text{-}orbital\ f\ T\ 0\ (\lambda s.
True(s) \subseteq \{s, Is\}
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
   apply(erule-tac \ x=xa \ 0 \ in \ all E)
   apply(drule mp, simp-all)
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
  \mathbf{apply}(\mathit{drule}\ \mathit{mp},\,\mathit{simp-all}\ \mathit{add}\colon\mathit{subset-eq})
```

 $apply(erule-tac \ x=xa \ t \ in \ all E)$ 

 $\mathbf{by}(drule\ mp,\ auto)$ 

```
context local-flow
begin
\mathbf{lemma} \ \textit{diff-invariant-eq-invariant-set} \colon
  (I \text{ is-diff-invariant-of } f \text{ along } T) = (\forall s. \forall t \in T. I s \longrightarrow I (\varphi t s))
 by(subst invariant-to-set, auto simp: q-evol-collapses)
\mathbf{lemma}\ invariant\text{-}set\text{-}eq\text{-}dl\text{-}invariant:
  shows (\forall s. \forall t \in T. I s \longrightarrow I (\varphi t s)) = (\{s. I s\} = fb_{\mathcal{F}} (orbit) \{s. I s\})
 apply(safe, simp-all add: ffb-orbit)
  apply(erule-tac \ x=0 \ in \ ballE)
  by(auto\ simp:\ ivp(2)\ init-time)
end
lemma dInvariant:
  assumes I is-diff-invariant-of f along T
 shows \{s. \ I \ s\} \le fb_{\mathcal{F}} ([x'=f] \ T \ \& \ G) \{s. \ I \ s\}
  using assms by (auto simp: diff-invariant-def ivp-sols-def ffb-eq g-orbital-eq)
lemma dInvariant-converse:
  assumes \{s. \ I \ s\} \leq fb_{\mathcal{F}} ([x'=f] \ T \ \& (\lambda s. \ True)) \{s. \ I \ s\}
 shows I is-diff-invariant-of f along T
  using assms unfolding invariant-to-set ffb-eq by auto
lemma ffb-g-evol-le-requires:
  assumes \forall s. \exists x. x \in (ivp\text{-}sols f \ T \ 0 \ s) \land G \ s
   shows fb_{\mathcal{F}} ([x'=f]T \& G) \{s. \ I \ s\} \le \{s. \ I \ s\}
  apply(simp add: ffb-eq q-orbital-eq, clarify)
  apply(erule-tac \ x=x \ in \ all E, \ erule \ impE, \ simp-all)
  using assms\ ivp\text{-}solsD(1) by (fastforce\ simp:\ ivp\text{-}sols\text{-}def)
lemma dI:
assumes I is-diff-invariant-of f along \{0..t\}
   and P \leq \{s. \ I \ s\} and \{s. \ I \ s\} \leq Q
  shows P \leq fb_{\mathcal{F}} ([x'=f]\{\theta..t\} \& G) Q
  apply(rule-tac\ C=I\ in\ dCut)
  using dInvariant assms apply blast
 apply(rule dWeakening)
  using assms by auto
```

Finally, we obtain some conditions to prove specific instances of differential invariants.

**named-theorems** ode-invariant-rules compilation of rules for differential invariants.

```
lemma [ode-invariant-rules]: fixes \vartheta::'a::banach \Rightarrow real assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0--\tau\}.
```

```
((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \text{ has-derivative } (\lambda \tau. \tau *_R \theta)) \text{ (at } r \text{ within } \{\theta - -\tau\}))
shows (\lambda s. \ \vartheta \ s = \nu \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 < \tau \tau < t
    and x-ivp: D x = (\lambda \tau. f(x \tau)) on \{0..t\} \vartheta(x \theta) = \nu(x \theta)
  hence \forall r \in \{\theta - \tau\}. D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R \theta) at r within
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) = (\lambda \tau. \tau *_R \theta)
(\tau - \theta)
    \mathbf{by}(rule\text{-}tac\ closed\text{-}segment\text{-}mvt,\ auto\ simp:\ tHyp)
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0..-\tau\}.
\vartheta'(x r) \ge \nu'(x r)
\wedge (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x r) - \nu'(x r))) at r within
\{0--\tau\})
shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) \leq \vartheta(x \theta)
  hence primed: \forall r \in \{0--\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x \tau)))
r) - \nu'(x r))
  at r within \{\theta - -\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta' (x \ r) - \nu' (x \ r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\}
    and \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_R (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
\theta))
    by force
  also have \dots \geq \theta
    using tHyp(1) x-ivp(2) primed by (simp add: calculation(1))
  ultimately show \nu (x \tau) \leq \vartheta (x \tau)
    by simp
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0..-\tau\}.
\vartheta'(x r) \ge \nu'(x r)
\wedge (D (\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta' (x r) - \nu' (x r))) at r within
\{0--\tau\})
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{0..t\}
```

```
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) < \vartheta(x \theta)
  hence primed: \forall r \in \{0--\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) has-derivative
(\lambda \tau. \ \tau *_R \ (\vartheta'(x r) - \nu'(x r)))) \ (at \ r \ within \ \{0 - - \tau\}) \land \vartheta'(x r) \ge \nu'(x r)
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta (x \tau) - \nu (x \tau)) - (\vartheta (x \theta) - \nu (x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\} and
    \vartheta\left(x\;\tau\right)-\nu\left(x\;\tau\right)=\left(\tau\;-\;\theta\right)*_{R}\left(\vartheta'\left(x\;r\right)-\;\nu'\left(x\;r\right)\right)+\left(\vartheta\left(x\;\theta\right)-\nu\left(x\;\theta\right)\right)
    by force
  also have ... > \theta
  using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
       calculation(1) diff-qt-0-iff-qt ge-iff-diff-ge-0 less-eq-real-def zero-le-scaleR-iff)
  ultimately show \nu (x \tau) < \vartheta (x \tau)
    by simp
\mathbf{qed}
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes I1 is-diff-invariant-of f along \{0..t\}
    and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. \ I1 \ s \land I2 \ s) is-diff-invariant-of f along \{0..t\}
  using assms unfolding diff-invariant-def by auto
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes I1 is-diff-invariant-of f along \{0..t\}
    and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. \ I1 \ s \lor I2 \ s) is-diff-invariant-of f along \{0..t\}
  using assms unfolding diff-invariant-def by auto
end
theory cat2funcset-examples
  imports ../hs-prelims-matrices cat2funcset
begin
```

### 3.2.3 Examples

The examples in this subsection show different approaches for the verification of hybrid systems. However, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n)  $vec \Rightarrow ('a, 'n)$  vec to model the dynamics of our system. Then we show a partial correctness specification

involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

# Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.
- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = \{''y'', ''v''\}
 morphisms to-str to-var
 apply(rule-tac x="y" in exI)
 by simp
notation to-var (\upharpoonright_V)
lemma number-of-program-vars: CARD(program-vars) = 2
 using type-definition.card type-definition-program-vars by fastforce
instance program-vars::finite
 apply(standard, subst bij-betw-finite[of to-str UNIV {"y","v"}])
  apply(rule bij-betwI')
    apply (simp add: to-str-inject)
 using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
 by simp
lemma program-vars-univD:(UNIV::program-vars\ set) = \{ \upharpoonright_V "y", \upharpoonright_V "v" \}
 apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:\forall x::program-vars. x = \lceil_V "y" \lor x = \lceil_V "v"
 using program-vars-univD by auto
abbreviation constant-acceleration-kinematics g s \equiv
 (\chi i. if i=(\upharpoonright_V "y") then s \$ (\upharpoonright_V "v") else g)
notation constant-acceleration-kinematics (K)
```

```
lemma cnst-acc-continuous:
  fixes X::(real \hat{p}rogram-vars) set
  shows continuous-on X (K g)
 apply(rule continuous-on-vec-lambda)
  unfolding continuous-on-def apply clarsimp
  by(intro tendsto-intros)
lemma picard-lindeloef-cnst-acc:
  fixes g::real assumes 0 \le t and t < 1
  shows picard-lindeloef (\lambda t. K g) {0..t} 1 0
  unfolding picard-lindeloef-def apply(simp add: lipschitz-on-def assms, safe)
  apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
  apply(simp-all add: cnst-acc-continuous continuous-on-snd)
  apply(simp add: dist-vec-def L2-set-def dist-real-def)
  apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
  apply(simp-all add: to-var-inject)
  using assms by linarith
abbreviation constant-acceleration-kinematics-flow g t s \equiv
  (\chi i. if i=(\upharpoonright_V "y") then g \cdot t \hat{2}/2 + s \$ (\upharpoonright_V "v") \cdot t + s \$ (\upharpoonright_V "y")
        else g \cdot t + s \$ (\upharpoonright_V "v")
notation constant-acceleration-kinematics-flow (\varphi_K)
lemma local-flow-cnst-acc:
  assumes 0 \le t and t \le 1
  shows local-flow (K g) \{0..t\} 1 (\varphi_K g)
  unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-cnst-acc apply blast
  apply(rule has-vderiv-on-vec-lambda)
  using poly-derivatives (3,4) program-vars-exhaust
  apply(simp-all\ add:\ to-var-inject\ vec-eq-iff\ has-vderiv-on-def\ has-vector-derivative-def)
  using program-vars-exhaust by blast
\mathbf{lemma}\ \mathit{ffb-cnst-acc}:
  assumes 0 \le t and t < 1
  shows fb_{\mathcal{F}} ([x'=K \ g]\{0..t\} \ \& \ G) Q = \{s. \ \forall \tau \in \{0..t\}. \ (G \rhd (\lambda r. \ \varphi_K \ g \ r
s)\{\theta--\tau\}) \longrightarrow (\varphi_K \ g \ \tau \ s) \in Q\}
  apply(subst\ local-flow.ffb-g-orbit[of\ K\ g-1\ (\lambda\ t\ x.\ \varphi_K\ g\ t\ x)])
  using local-flow-cnst-acc and assms by auto
\mathbf{lemma}\ single\text{-}evolution\text{-}ball:
  fixes H::real assumes \theta \le t and t < 1 and g < \theta
  shows \{s. \ \theta \leq s \ \$ \ (\upharpoonright_V "y") \land s \ \$ \ (\upharpoonright_V "y") = H \land s \ \$ \ (\upharpoonright_V "v") = \theta \}
  \leq fb_{\mathcal{F}} \; ([x' = K \; g] \{ \theta ..t \} \; \& \; (\lambda \; s. \; s \; \$ \; (\upharpoonright_V \; ''y'') \geq \theta))
  \{s. \ 0 \le s \ \$ \ (\upharpoonright_V "y") \land s \ \$ \ (\upharpoonright_V "y") \le H\}
  apply(subst ffb-cnst-acc)
  using assms by (auto simp: mult-nonpos-nonneg)
```

```
no-notation to-var (\upharpoonright_V)
no-notation constant-acceleration-kinematics (K)
no-notation constant-acceleration-kinematics-flow (\varphi_K)
```

# Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a  $3 \times 3$  matrix (named K) to denote the linear operator that models the constantly accelerated motion.
- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

**term** x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. However, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

**lemma** exhaust-5: — The analogs for 1, 2 and 3 have already been proven in Analysis.

```
fixes x::5 shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5 proof (induct \, x) case (of\text{-}int \, z) then have 0 \le z and z < 5 by simp\text{-}all then have z=0 \lor z=1 \lor z=2 \lor z=3 \lor z=4 by arith then show ?case by auto qed lemma UNIV\text{-}3:(UNIV::3 \, set) = \{0, 1, 2\} apply safe using exhaust\text{-}3 three-eq-zero by (blast, auto) lemma sum\text{-}axis\text{-}UNIV\text{-}3[simp]:(\sum j\in (UNIV::3 \, set). \, axis \, i \, 1 \, \$ \, j \cdot f \, j) = (f::3 \Rightarrow real) \, i unfolding axis\text{-}def \, UNIV\text{-}3 apply simp using exhaust\text{-}3 by force
```

We can rewrite the original constant acceleration kinematics as a linear operator applied to a 3-dimensional vector. For that we take advantage of the following fact:

```
lemma e 1 = (\chi j :: 3. if j = 0 then 0 else if j = 1 then 1 else 0)
 unfolding axis-def by(rule Cart-lambda-cong, simp)
abbreviation constant-acceleration-kinematics-matrix \equiv
 (\chi i. if i= (0::3) then axis (1::3) (1::real) else if i= 1 then axis 2 1 else 0)
abbreviation constant-acceleration-kinematics-matrix-flow t s \equiv
 (\chi \ i. \ if \ i=(0::3) \ then \ s \ 2 \cdot t \ 2/2 + s \ 1 \cdot t + s \ 0
  notation constant-acceleration-kinematics-matrix (K)
notation constant-acceleration-kinematics-matrix-flow (\varphi_K)
With these 2 definitions and the proof that linear systems of ODEs are
Picard-Lindeloef, we can show that they form a pair of vector-field and its
flow.
lemma entries-cnst-acc-matrix: entries K = \{0, 1\}
 apply (simp-all add: axis-def, safe)
 \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
lemma picard-lindeloef-cnst-acc-matrix:
 assumes 0 \le t and t \le 1/9
 shows picard-lindeloef (\lambda t s. K *v s) {0..t} ((real CARD(3))^2 · (\|K\|_{max})) 0
 apply(rule\ picard-lindeloef-linear-system)
 unfolding entries-cnst-acc-matrix using assms by auto
lemma local-flow-cnst-acc-matrix:
 assumes 0 \le t and t < 1/9
 shows local-flow ((*v) K) \{0..t\} ((real CARD(3))<sup>2</sup> · (\|K\|_{max})) \varphi_K
 unfolding local-flow-def local-flow-axioms-def apply safe
 using picard-lindeloef-cnst-acc-matrix[OF assms] apply blast
  apply(rule has-vderiv-on-vec-lambda)
 using poly-derivatives(1,3,4)
  apply(force simp: matrix-vector-mult-def)
 using exhaust-3 by(force simp: matrix-vector-mult-def vec-eq-iff)
Finally, we compute the wlp and use it to verify the single-evolution ball
again.
lemma ffb-cnst-acc-mtx:
 assumes 0 \le t and t \le 1/9
  shows fb_{\mathcal{F}} ([x'=(*v) \ K] \{0..t\} \& G) Q = \{s. \ \forall \tau \in \{0..t\}. \ (G \rhd (\lambda r. \varphi_K \ r. \varphi_K)\} \}
s)\{\theta--\tau\}) \longrightarrow (\varphi_K \ \tau \ s) \in Q\}
  apply(subst\ local-flow.ffb-g-orbit[of\ (*v)\ K-((real\ CARD(3))^2\cdot (||K||_{max}))
\varphi_K|)
 using local-flow-cnst-acc-matrix and assms by auto
{f lemma}\ single-evolution-ball-matrix:
 assumes 0 \le t and t < 1/9
```

```
shows \{s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = H \land s \$ \ 1 = 0 \land 0 > s \$ \ 2\}

\le fb_{\mathcal{F}}([x'=(*v) \ K]\{0..t\} \& (\lambda s. s \$ \ 0 \ge 0))

\{s. \ 0 \le s \$ \ 0 \land s \$ \ 0 \le H\}

apply(subst ffb-cnst-acc-mtx)

using assms by(auto simp: mult-nonneg-nonpos2)
```

#### Circular Motion

The characteristics that distinguish this example are:

- 1. We employ an existing finite type of size 2 to model program variables.
- 2. We define a  $2 \times 2$  matrix (named C) to denote the linear operator that models circular motion.
- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow  $(\varphi_C)$  and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two-eq-zero: (2::2) = 0
 by simp
lemma [simp]: i \neq (0::2) \longrightarrow i = 1
 using exhaust-2 by fastforce
lemma UNIV-2:(UNIV::2 \ set) = \{0, 1\}
 apply safe using exhaust-2 two-eq-zero by auto
abbreviation circular-motion-matrix \equiv
  (\chi i. if i= (0::2) then axis (1::2) (-1::real) else axis (0.1)
notation circular-motion-matrix (C)
lemma circle-invariant:
 assumes \theta < R
 shows (\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2) is-diff-invariant-of (*v) C along \{\theta...t\}
 apply(rule-tac ode-invariant-rules, clarsimp)
 apply(frule-tac i=0 in has-vderiv-on-vec-nth, drule-tac i=1 in has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def, clarsimp)
 apply(erule-tac x=r in ballE)+
   apply(simp add: matrix-vector-mult-def has-vderiv-on-vec-lambda)
 subgoal for x \tau r apply(rule-tac f'1 = \lambda t. \theta and g'1 = \lambda t. \theta in derivative-eq-intros(11),
simp-all)
```

```
\mathbf{apply}(rule\text{-}tac\ f'1 = \lambda t. - 2 \cdot (x\ r\ \$\ \theta) \cdot (t \cdot x\ r\ \$\ 1)
       and g'1 = \lambda t. 2 · (x r \$ 1) \cdot t \cdot x r \$ 0 in derivative-eq-intros(8), simp-all)
      apply(rule-tac f'1 = \lambda t. - (t \cdot x \ r \ \$ \ 1) in derivative-eq-intros(15))
       apply(rule-tac\ t=\{\theta--\tau\}\ and\ s=\{\theta..t\}\ in\ has-derivative-within-subset)
        apply(simp, simp add: closed-segment-eq-real-ivl, force)
      apply(rule-tac f'1 = \lambda t. (t \cdot x \ r \ \$ \ \theta) in derivative-eq-intros(15))
       apply(rule-tac\ t=\{\theta--\tau\}\ and\ s=\{\theta..t\}\ in\ has-derivative-within-subset)
   by(simp, simp add: closed-segment-eq-real-ivl, force)
  by(auto simp: closed-segment-eq-real-ivl)
lemma circular-motion-invariants:
  assumes (R::real) > 0
  shows\{s. R^2 = (s \$ (0::2))^2 + (s \$ 1)^2\}
  \leq fb_{\mathcal{F}} ([x'=(*v) \ C]\{0..t\} \& (\lambda \ s. \ s \ \$ \ \theta \geq \theta))
  {s. R^2 = (s \$ (0::2))^2 + (s \$ 1)^2}
  using assms apply(rule-tac C = \lambda s. R^2 = (s \$ (0::2))^2 + (s \$ 1)^2 in dCut)
  apply(rule-tac I=\lambda s. R^2=(s \$ (0::2))^2+(s \$ 1)^2 in dInvariant)
  using circle-invariant apply blast
  \mathbf{by}(rule\ dWeakening,\ auto)
— Proof of the same specification by providing solutions:
lemma entries-circ-mtx:entries C = \{0, -1, 1\}
  apply (simp-all add: axis-def, safe)
  subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
  subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
  \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
lemma picard-lindeloef-circ-mtx:
  assumes 0 \le t and t < 1/4
  shows picard-lindeloef (\lambda t. (*v) C) {\theta..t} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \theta
  apply(rule picard-lindeloef-linear-system)
  unfolding entries-circ-mtx using assms by auto
abbreviation circular-motion-matrix-flow t s \equiv (\chi i. if i = (0::2) then
s\$0 \cdot cos \ t - s\$1 \cdot sin \ t \ else \ s\$0 \cdot sin \ t + s\$1 \cdot cos \ t)
notation circular-motion-matrix-flow (\varphi_C)
lemma local-flow-circ-mtx:
  assumes 0 \le t and t \le 1/4
  shows local-flow ((*v) C) \{0..t\} ((real CARD(2))<sup>2</sup> · (||C||_{max})) \varphi_C
  unfolding local-flow-def local-flow-axioms-def apply safe
  using picard-lindeloef-circ-mtx assms apply blast
  apply(rule has-vderiv-on-vec-lambda)
  apply(simp add: matrix-vector-mult-def has-vderiv-on-def has-vector-derivative-def,
safe)
  subgoal for s i x
    apply(rule-tac f'1=\lambda t. - s\$0 \cdot (t \cdot \sin x) and g'1=\lambda t. s\$1 \cdot (t \cdot \cos x)in
```

```
derivative-eq-intros(11))
      apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule derivative-eq-intros(6)[of sin (\lambda xa. (xa \cdot cos x))])
     apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
      apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp\ add: Groups.mult-ac(3)\ Rings.ring-distribs(4))
 subgoal for s i x
    apply(rule-tac f'1=\lambda t. s$0 · (t · cos x) and g'1=\lambda t. -s$1 · (t · sin x)in
derivative-eq-intros(8)
      \mathbf{apply}(\mathit{rule\ derivative-eq\text{-}intros}(6)[\mathit{of\ sin\ }(\lambda xa.\ xa\ \cdot\ \cos\ x)])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
      apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp add: Groups.mult-ac(3) Rings.ring-distribs(4))
  using exhaust-2 two-eq-zero by(force simp: vec-eq-iff)
lemma ffb-circ-mtx:
 assumes 0 \le t and t < 1/4
 shows fb_{\mathcal{F}} ([x'=\lambda s. \ C *v \ s]\{\theta..t\} \& G) Q =
   \{x. \ \forall \ \tau \in \{0..t\}. \ (\forall r \in \{0--\tau\}. \ G \ (\varphi_C \ r \ x)) \longrightarrow (\varphi_C \ \tau \ x) \in Q\}
 apply(subst local-flow.ffb-g-orbit[of \lambda s. \ C *v \ s - ((real\ CARD(2))^2 \cdot (||C||_{max}))
(\lambda t x. \varphi_C t x)])
  using local-flow-circ-mtx and assms by auto
lemma circular-motion:
  assumes 0 \le t and t < 1/4 and (R::real) > 0
 shows \{s. R^2 = (s \$ (0::2))^2 + (s \$ 1)^2\} \le fb_{\mathcal{F}}
  ([x'=\lambda s. \ C *v \ s] \{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0))
  \{s. R^2 = (s \$ (0:2))^2 + (s \$ 1)^2\}
  apply(subst\ ffb-circ-mtx)
  using assms by auto
no-notation circular-motion-matrix (C)
no-notation circular-motion-matrix-flow (\varphi_C)
```

# Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynamics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb-real-arith]: 0 < x \Longrightarrow 0 > q \Longrightarrow 2 \cdot q \cdot x = 2 \cdot q \cdot H + v \cdot v \Longrightarrow
(x::real) \leq H
proof-
  assume 0 \le x and 0 > q and 2 \cdot q \cdot x = 2 \cdot q \cdot H + v \cdot v
  then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot H \wedge 0 > g by auto
  hence *: v \cdot v = 2 \cdot g \cdot (x - H) \wedge 0 > g \wedge v \cdot v \geq 0
    using left-diff-distrib mult.commute by (metis zero-le-square)
  from this have (v \cdot v)/(2 \cdot q) = (x - H) by auto
  also from * have (v \cdot v)/(2 \cdot g) \leq \theta
    using divide-nonneg-neg by fastforce
  ultimately have H - x \ge \theta by linarith
  thus ?thesis by auto
qed
lemma [bb-real-arith]:
  assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v
    and pos: g \cdot \tau^2 / \tilde{2} + v \cdot \tau + (x::real) = 0
  shows 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    and 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
proof-
  from pos have g \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x = 0
    by (metis (mono-tags, hide-lams) Groups.mult-ac(1,3) mult-zero-right
        monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + v^2 + 2 \cdot g \cdot H = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(q \cdot \tau + v)^2 + 2 \cdot q \cdot H = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide\text{-}lams)\ Groups.add\text{-}ac(2,3)
        Groups.mult-ac(2, 3) monoid-mult-class.power2-eq-square nat-distrib(2))
  hence 2 \cdot g \cdot H + (-((g \cdot \tau) + v))^2 = 0
    by (metis\ Groups.add-ac(2)\ power2-minus)
  thus 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
  from * show 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
\mathbf{qed}
lemma [bb-real-arith]:
  \mathbf{assumes} \ invar: 2 \, \cdot \, g \, \cdot \, x \, = \, 2 \, \cdot \, g \, \cdot \, H \, + \, v \, \cdot \, v
  \mathbf{shows} \ \mathcal{2} \ \cdot \ g \ \cdot \ (g \ \cdot \ \tau^2 \ / \ \mathcal{2} \ + \ v \ \cdot \ \tau \ + \ (x::real)) =
  2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
  have ?lhs = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x
      apply(subst\ Rat.sign-simps(18))+
      \mathbf{by}(auto\ simp:\ semiring-normalization-rules(29))
    also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v (is ... = ?middle)
```

```
\mathbf{by}(subst\ invar,\ simp)
   finally have ?lhs = ?middle.
  moreover
  {have ?rhs = g \cdot g \cdot (\tau \cdot \tau) + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v
   by (simp add: Groups.mult-ac(2,3) semiring-class.distrib-left)
  also have \dots = ?middle
   by (simp add: semiring-normalization-rules(29))
 finally have ?rhs = ?middle.}
  ultimately show ?thesis by auto
qed
lemma bouncing-ball:
 assumes 0 \le t and t < 1/9
 shows \{s. (0::real) \le s \$ (0::3) \land s \$ 0 = H \land s \$ 1 = 0 \land 0 > s \$ 2\} \le fb_{\mathcal{F}}
  (kstar\ (([x'=\lambda s.\ K\ *v\ s]\{\theta..t\}\ \&\ (\lambda\ s.\ s\ \$\ \theta \ge \theta)))\circ_K
  (IF (\lambda s. s \$ \theta = \theta) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE \eta FI)))
  \{s. \ 0 \le s \ \ \theta \land s \ \ \theta \le H\}
 apply(rule ffb-starI[of - {s. 0 \le s \$ (0::3) \land 0 > s \$ 2 \land
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot H + (s \$ 1 \cdot s \$ 1)\}]
 apply(clarsimp, simp only: ffb-kcomp)
   apply(subst\ ffb-cnst-acc-mtx)
  using assms apply(simp, simp, clarsimp)
   apply(rule ffb-if-then-elseD)
  by(auto simp: bb-real-arith)
Bouncing Ball with invariants
We prove again the bouncing ball but this time with differential invariants.
lemma gravity-invariant: (\lambda s. s \$ 2 < 0) is-diff-invariant-of (*v) K along \{0...t\}
  apply(rule-tac \vartheta' = \lambda s. \theta and \nu' = \lambda s. \theta in ode-invariant-rules(3), clarsimp)
 apply(drule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def)
 apply(erule-tac \ x=r \ in \ ball E, \ simp \ add: \ matrix-vector-mult-def)
  apply(rule-tac f'1=\lambda s. \theta in derivative-eq-intros(1\theta))
  by(auto simp: closed-segment-eq-real-ivl has-derivative-within-subset)
lemma energy-conservation-invariant:
(\lambda s. \ 2 \cdot s \ \$ \ 2 \cdot s \ \$ \ 0 - 2 \cdot s \ \$ \ 2 \cdot H - s \ \$ \ 1 \cdot s \ \$ \ 1 = 0) is-diff-invariant-of
(*v) K along \{0..t\}
 apply(rule ode-invariant-rules, clarify)
 apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
 apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def)
 apply(erule-tac \ x=r \ in \ ball E, simp-all \ add: matrix-vector-mult-def)+
    apply(rule-tac f'1 = \lambda t. 2 · x r $ 2 · (t · x r $ 1)
     and g'1 = \lambda t. 2 · (t \cdot (x r \$ 1 \cdot x r \$ 2)) in derivative-eq-intros(11))
       apply(rule-tac f'1=\lambda t. 2 · x r $ 2 · (t · x r $ 1) and g'1=\lambda t. 0 in
```

derivative-eq-intros(11))

```
apply(rule-tac f'1=\lambda t. 0 and g'1=(\lambda xa. xa \cdot xr \$ 1) in derivative-eq-intros(12))
    apply(rule-tac g'1 = \lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset closed-segment-eq-real-ivl)
    apply(rule-tac g'1 = \lambda t. 0 in derivative-eq-intros(7))
   apply(rule-tac g'1 = \lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset)
   apply(rule-tac f'1=(\lambda xa. xa \cdot x r \$ 2) and g'1=(\lambda xa. xa \cdot x r \$ 2) in
derivative-eq-intros(12)
  \mathbf{by}(simp-all\ add:\ has-derivative-within-subset)
lemma bouncing-ball-invariants:
  shows \{s. (0::real) \le s \ (0::3) \land s \ \ 0 = H \land s \ \ 1 = 0 \land 0 > s \ \ 2\} \le fb_{\mathcal{F}}
  (kstar (([x'=\lambda s. K *v s] \{0..t\} \& (\lambda s. s \$ 0 \ge 0)) \circ_K)
  (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE \eta FI)))
  \{s. \ 0 \le s \ \ 0 \land s \ \ 0 \le H\}
 apply(rule-tac I = \{s. \ 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot H + (s\$1)\}
\cdot s$1)} in ffb-starI)
   apply(clarsimp, simp only: ffb-kcomp)
   apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
   apply(rule-tac I=\lambda s. s \$ 2 < 0 \text{ in } dI)
  using gravity-invariant apply(blast, force, force)
  apply(rule-tac C=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot H - s\$1 \cdot s\$1 = 0 in dCut)
   apply(rule-tac I=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot H - s\$1 \cdot s\$1 = 0 in dI)
  using energy-conservation-invariant apply(blast, force, force)
  apply(rule\ dWeakening)
  apply(rule ffb-if-then-else)
  by(auto simp: bb-real-arith le-fun-def)
no-notation constant-acceleration-kinematics-matrix (K)
```

## Bouncing Ball with exponential solution

**no-notation** constant-acceleration-kinematics-matrix-flow  $(\varphi_K)$ 

In our final example, we prove again the bouncing ball specification but this time we do it with the general solution for linear systems.

 $\textbf{abbreviation}\ constant\text{-}acceleration\text{-}kinematics\text{-}sq\text{-}mtx \equiv sq\text{-}mtx\text{-}chi\ constant\text{-}acceleration\text{-}kinematics\text{-}mediant = sq\text{-}mtx\text{-}chi\ constant\text{-}acceleration\text{-}kinematics\text{-}acceleration\text{-}kinematics\text{-}acceleration\text{-$ 

 ${f notation}$  constant-acceleration-kinematics-sq-mtx (K)

```
lemma max-norm-cnst-acc-sq-mtx: ||to\text{-}vec\ K||_{max} = 1 proof — have \{to\text{-}vec\ K\ \$\ i\ \$\ j\ | i\ j.\ s2p\ UNIV\ i\ \land\ s2p\ UNIV\ j\} = \{0,\ 1\} apply (simp\text{-}all\ add:\ axis\text{-}def,\ safe}) by (rule\text{-}tac\ x=1\ \text{in}\ exI,\ simp})+ thus ?thesis by auto qed
```

```
lemma ffb-cnst-acc-sq-mtx:
 assumes 0 \le t and t < 1/9
 shows fb_{\mathcal{F}} ([x'=(*_{V}) \ K] \{ \theta..t \} \& G) \ Q =
    \{x. \ \forall \ \tau \in \{0..t\}. \ (\forall r \in \{0--\tau\}. \ G \ ((exp \ (r *_R K)) *_V x)) \longrightarrow ((exp \ (\tau *_R K)) *_V x)) \longrightarrow ((exp \ (\tau *_R K)) *_V x)) \longrightarrow ((exp \ (\tau *_R K)) *_V x))
(K) *_{V} x) \in Q
 apply(subst local-flow.ffb-q-orbit[of (*_V) K - ((real CARD(3))^2 \cdot (||to-vec K||_{max})))
(\lambda t \ x. \ (exp \ (t *_R K)) *_V x)])
  apply(rule local-flow-exp)
  using max-norm-cnst-acc-sq-mtx assms by auto
lemma exp-cnst-acc-sq-mtx-simps:
 exp \ (\tau *_R K) \$\$ \ 0 \$ \ 0 = 1 \ exp \ (\tau *_R K) \$\$ \ 0 \$ \ 1 = \tau \ exp \ (\tau *_R K) \$\$ \ 0 \$ \ 2
 exp \ (\tau *_R K) \$\$ \ 1 \$ \ 0 = 0 \ exp \ (\tau *_R K) \$\$ \ 1 \$ \ 1 = 1 \ exp \ (\tau *_R K) \$\$ \ 1 \$ \ 2
 exp \ (\tau *_R K) \$\$ \ 2 \$ \ 0 = 0 \ exp \ (\tau *_R K) \$\$ \ 2 \$ \ 1 = 0 \ exp \ (\tau *_R K) \$\$ \ 2 \$ \ 2
= 1
 sorry
lemma bouncing-ball-sq-mtx:
 assumes 0 \le t and t < 1/9
 shows \{s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 = H \land s \ \$ \ 1 = 0 \land 0 > s \ \$ \ 2\} \le fb_{\mathcal{F}}
  (kstar\ (([x'=(*_V)\ K]\{0..t\}\ \&\ (\lambda\ s.\ s\ \$\ 0 \ge 0))\circ_K
  (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE \eta FI)))
  \{s. \ 0 \le s \ \ 0 \land s \ \ 0 \le H\}
  apply(rule ffb-starI[of - {s. 0 \le s \$ (0::3) \land 0 > s \$ 2 \land
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot H + (s \$ 1 \cdot s \$ 1)\}]
   apply(clarsimp, simp only: ffb-kcomp)
  apply(subst\ ffb-cnst-acc-sq-mtx)
  using assms apply(simp, simp, clarify)
  apply(rule ffb-if-then-elseD, clarsimp)
  apply(simp-all add: sq-mtx-vec-prod-eq)
  unfolding UNIV-3 apply(simp-all add: exp-cnst-acc-sq-mtx-simps)
  subgoal for x using bb-real-arith(3)[of x \  2]
    by (simp add: add.commute mult.commute)
 subgoal for x \tau using bb-real-arith(4)[where g=x \$ 2 and v=x \$ 1]
    by(simp add: add.commute mult.commute)
  by (force simp: bb-real-arith)
end
theory cat2rel
 imports
 ../hs-prelims-matrices
 ../../afpModified/VC-KAD
```

begin

# Chapter 4

# Hybrid System Verification with relations

```
— We start by deleting some conflicting notation.

no-notation Archimedean-Field.ceiling ([-])

and Archimedean-Field.floor-ceiling-class.floor ([-])

and Range-Semiring.antirange-semiring-class.ars-r (r)

and Relation.Domain (r2s)
```

# 4.1 Verification of regular programs

Below we explore the behavior of the forward box operator from the antidomain kleene algebra with the lifting ( $\lceil - \rceil^*$ ) operator from predicates to relations  $\lceil P \rceil = \{(s, s) \mid s. P s\}$  and its dropping counterpart  $\lfloor R \rfloor = (\lambda x. x \in Domain R)$ .

```
lemma p2r\text{-}IdD: \lceil P \rceil = Id \Longrightarrow P \ s by (metis \ (full\text{-}types) \ UNIV\text{-}I \ impl\text{-}prop \ p2r\text{-}subid \ top\text{-}empty\text{-}eq}) lemma wp\text{-}rel:wp \ R \ \lceil P \rceil = \lceil \lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y \rceil proof—
have \lfloor wp \ R \ \lceil P \rceil \rfloor = \lfloor \lceil \lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y \rceil \rfloor by (simp \ add: \ wp\text{-}trafo \ pointfree\text{-}idE) thus wp \ R \ \lceil P \rceil = \lceil \lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y \rceil by (metis \ (no\text{-}types, \ lifting) \ wp\text{-}simp \ d\text{-}p2r \ pointfree\text{-}idE \ prp) qed

corollary wp\text{-}relD:(x,x) \in wp \ R \ \lceil P \rceil \Longrightarrow \forall \ y. \ (x,y) \in R \longrightarrow P \ y proof—
assume (x,x) \in wp \ R \ \lceil P \rceil
hence (x,x) \in \lceil \lambda \ x. \ \forall \ y. \ (x,y) \in R \longrightarrow P \ y \rceil using wp\text{-}rel by auto thus \forall \ y. \ (x,y) \in R \longrightarrow P \ y by (simp \ add: \ p2r\text{-}def) qed
```

```
lemma p2r-r2p-wp-sym:wp R P = \lceil |wp R P| \rceil
 using d-p2r wp-simp by blast
lemma p2r-r2p-wp:\lceil \lfloor wp \ R \ P \rfloor \rceil = wp \ R \ P
 by (rule\ sym,\ subst\ p2r-r2p-wp-sym,\ simp)
Next, we introduce assignments and compute their wp.
abbreviation vec-upd :: ('a^{\hat{}}b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a^{\hat{}}b (-(2[-:==-]) [70, 65] 61)
where
x[i :== a] \equiv (\chi j. (if j = i then a else (x \$ j)))
abbreviation assign :: b \Rightarrow (a^b \Rightarrow a) \Rightarrow (a^b \Rightarrow b) rel ((2[- ::== -]) [70, 65]
61) where
[x ::== expr] \equiv \{(s, s[x :== expr s]) | s. True\}
lemma wp-assign [simp]: wp ([x ::== expr]) [Q] = [\lambda s. \ Q \ (s[x :== expr \ s])]
 by(auto simp: rel-antidomain-kleene-algebra.fbox-def rel-ad-def p2r-def)
lemma wp-assign-var [simp]: |wp|([x ::== expr])|[Q]| = (\lambda s. Q (s[x :== expr])|[Q]|
s]))
 \mathbf{by}(subst\ wp\text{-}assign,\ simp\ add:\ pointfree\text{-}idE)
The wp of the composition was already obtained in KAD. Antidomain_Semiring:
|x \cdot y| z = |x| |y| z.
There is also already an implementation of the conditional operator if p then
x \text{ else } y \text{ fi} = d p \cdot x + ad p \cdot y \text{ and its } wp: | \text{if } p \text{ then } x \text{ else } y \text{ fi} | q = d p \cdot y
|x| q + ad p \cdot |y| q.
Finally, we add a wp-rule for a simple finite iteration.
lemma (in antidomain-kleene-algebra) fbox-starI:
assumes d p \leq d i and d i \leq |x| i and d i \leq d q
shows d p \leq |x^*| q
proof-
from \langle d | i \leq |x| | i \rangle have d | i \leq |x| | (d | i)
  using local.fbox-simp by auto
hence |1| p \le |x^*| i using \langle d | p \le d \rangle by (metis (no-types)
  local.dual - order.trans\ local.fbox-one\ local.fbox-simp\ local.fbox-star-induct-var)
thus ?thesis using \langle d | i \leq d | q \rangle by (metis (full-types)
  local.fbox-mult local.fbox-one local.fbox-seg-var local.fbox-simp)
qed
lemma rel-ad-mka-starI:
assumes P \subseteq I and I \subseteq wp \ R \ I and I \subseteq Q
shows P \subseteq wp(R^*) Q
proof-
  have wp R I \subseteq Id
  by (simp add: rel-antidomain-kleene-algebra.a-subid rel-antidomain-kleene-algebra.fbox-def)
  hence P \subseteq Id using assms(1,2) by blast
```

```
from this have rdom\ P=P by (metis\ d-p2r\ p2r-surj) also have rdom\ P\subseteq wp\ (R^*)\ Q by (metis\ \langle wp\ R\ I\subseteq Id\rangle\ assms\ d-p2r\ p2r-surj rel-antidomain-kleene-algebra.dka.dom-iso\ rel-antidomain-kleene-algebra.fbox-starI) ultimately show ?thesis by blast qed
```

# 4.2 Verification of hybrid programs

# 4.2.1 Verification by providing solutions

```
abbreviation guards :: ('a \Rightarrow bool) \Rightarrow (real \Rightarrow 'a) \Rightarrow (real set) \Rightarrow bool (- \triangleright - -
  where G \triangleright x \ T \equiv \forall \ r \in T. \ G \ (x \ r)
definition ivp-sols f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp-solsI:
 assumes D x = (f \circ x) on T x t_0 = s t_0 \in T
 shows x \in ivp\text{-}sols f T t_0 s
 using assms unfolding ivp-sols-def by blast
lemma ivp-solsD:
 assumes x \in ivp\text{-}sols f T t_0 s
 shows D x = (f \circ x) on T
    and x t_0 = s and t_0 \in T
  using assms unfolding ivp-sols-def by auto
lemma (t::real) \in \{\theta--t\}
 by (rule ends-in-segment(2))
lemma (t::real) \in \{0..t\}
 apply auto
 \mathbf{oops}
definition g-orbital f T t_0 G s = \bigcup \{\{x \ t | t. \ t \in T \land G \rhd x \ \{t_0 - -t\}\} \} | x. \ x \in T
ivp-sols f T t_0 s}
lemma g-orbital-eq: g-orbital f T t_0 G s =
 \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0 - -t\}\}\
 unfolding q-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t \in T \land G \rhd x\}
\{t_0--t\}\}
  unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbitalI:
 assumes D x = (f \circ x) on T x t_0 = s
    and t_0 \in T t \in T and G \triangleright x \{t_0 - -t\}
```

```
shows x \ t \in g-orbital f \ T \ t_0 \ G \ s
 using assms unfolding g-orbital-def ivp-sols-def by blast
lemma g-orbitalD:
  assumes s' \in g-orbital f \ T \ t_0 \ G \ s
  obtains x and t where x \in ivp\text{-}sols f T t_0 s
  and D x = (f \circ x) on T x t_0 = s
 and x t = s' and t_0 \in T t \in T and G \triangleright x \{t_0 - -t\}
  using assms unfolding g-orbital-def ivp-sols-def by blast
abbreviation g\text{-}evol :: (('a::banach) \Rightarrow 'a) \Rightarrow real \ set \Rightarrow 'a \ pred \Rightarrow 'a \ rel \ (([x'=]-
& -))
  where [x'=f]T \& G \equiv \{(s,s'). s' \in g\text{-}orbital f T 0 G s\}
lemmas g-evol-def = g-orbital-eq[where t_0 = 0]
context local-flow
begin
lemma in-ivp-sols: (\lambda t. \varphi t s) \in ivp-sols f T \theta s
 by(auto intro: ivp-solsI simp: ivp init-time)
definition orbit s = g-orbital f T \theta (\lambda s. True) s
lemma orbit-eq[simp]: orbit s = \{ \varphi \ t \ s | \ t . \ t \in T \}
  unfolding orbit-def g-evol-def
  by(auto intro: usolves-ivp intro!: ivp simp: init-time)
lemma q-orbital-collapses:
 shows g-orbital f T \theta G s = \{ \varphi \ t \ s \mid t. \ t \in T \land G \rhd (\lambda r. \ \varphi \ r \ s) \ \{ \theta - - t \} \} (is -
= ?gorbit)
proof(rule subset-antisym, simp-all only: subset-eq)
  \{fix s' assume s' \in g-orbital f T \cap G s
    then obtain x and t where x-ivp:D x = (f \circ x) on T
      x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \triangleright x \{\theta - -t\}
      unfolding g-orbital-eq by blast
   hence obs: \forall \tau \in \{0--t\}. \ x \ \tau = \varphi \ \tau \ s
      using usolves-ivp[of\ x\ s] closed-segment-subset-domainI init-time\ comp-def
      by (metis (mono-tags, lifting) has-vderiv-eq)
   hence G \triangleright (\lambda r. \varphi r s) \{\theta - -t\}
      using guard by simp
   hence s' \in ?gorbit
      using \langle x | t = s' \rangle \langle t \in T \rangle \ obs \ by \ blast
  thus \forall s' \in g\text{-}orbital \ f \ T \ 0 \ G \ s. \ s' \in ?gorbit
   by blast
next
  \{ \text{fix } s' \text{ assume } s' \in ?gorbit \}
    then obtain t where G \triangleright (\lambda r. \varphi rs) \{\theta - t\} and t \in T and \varphi ts = s'
      \mathbf{bv} blast
```

```
hence s' \in g-orbital f T \circ G s
      by(auto intro: g-orbitalI simp: ivp init-time)}
  thus \forall s' \in ?gorbit. \ s' \in g\text{-}orbital \ f \ T \ 0 \ G \ s
    \mathbf{by} blast
qed
lemma q-evol-collapses:
  shows ([x'=f]T \& G) = \{(s, \varphi t s) \mid t s. t \in T \land G \rhd (\lambda r. \varphi r s) \{0--t\}\}
  unfolding g-orbital-collapses by auto
lemma wp-orbit: wp (\{(s,s') \mid s \ s'. \ s' \in orbit \ s\}) \lceil Q \rceil = \lceil \lambda \ s. \ \forall \ t \in T. \ Q \ (\varphi \ t) \rceil
s)
  unfolding orbit-eq wp-rel by auto
lemma wp-g-orbit: wp ([x'=f]T \& G) [Q] = [\lambda \ s. \ \forall \ t \in T. \ (G \rhd (\lambda r. \varphi \ r \ s))]
\{0--t\}\longrightarrow Q\ (\varphi\ t\ s)
  unfolding g-evol-collapses wp-rel by auto
end
lemma (in global-flow) ivp-sols-collapse[simp]: ivp-sols f UNIV 0 s = \{(\lambda t. \varphi t)\}
s)
  by(auto intro: usolves-ivp simp: ivp-sols-def ivp)
```

The previous theorem allows us to compute wlps for known systems of ODEs. We can also implement a version of it as an inference rule. A simple computation of a wlp is shown immmediately after.

```
lemma dSolution:
```

```
assumes local-flow f T L \varphi and \forall s. P s \longrightarrow (\forall t \in T. (G \rhd (\lambda r. \varphi rs) \{0..t\}) \longrightarrow Q (\varphi ts)) shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \ \lceil Q \rceil using assms apply(subst local-flow.wp-g-orbit, auto) by (simp add: Starlike.closed-segment-eq-real-ivl)

lemma line-DS: 0 \leq t \Longrightarrow wp \ (\lceil x' = \lambda s. \ c \rceil \{0..t\} \& G) \ \lceil Q \rceil = [\lambda x. \forall \tau \in \{0..t\}. (G \rhd (\lambda r. x + r *_R c) \{0..\tau\}) \longrightarrow Q \ (x + \tau *_R c) \rceil apply(subst local-flow.wp-g-orbit[of \lambda s. \ c - 1/(t+1) \ (\lambda t x. x + t *_R c) \rceil)
```

#### 4.2.2 Verification with differential invariants

**by**(auto simp: line-is-local-flow closed-segment-eq-real-ivl)

We derive the domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in verification proofs.

# Differential Weakening

by blast

```
lemma DW: wp ([x'=f]T \& G) [Q] = wp ([x'=f]T \& G) [\lambda s. Gs \longrightarrow Qs]
  apply(subst wp-rel)+
 \mathbf{by}(auto\ simp:\ g\text{-}orbital\text{-}eq)
lemma dWeakening:
  assumes \lceil G \rceil \leq \lceil Q \rceil
 shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \lceil Q \rceil
  using assms apply(subst wp-rel)
  \mathbf{by}(auto\ simp:\ g\text{-}orbital\text{-}eq)
Differential Cut
lemma wp-g-orbit-IdD:
  assumes wp ([x'=f]T \& G) [C] = Id \text{ and } \forall r \in \{0--t\}. (s, xr) \in ([x'=f]T)
\& G
  shows \forall r \in \{0--t\}. C(x r)
proof
  fix r assume r \in \{\theta - -t\}
  then have x r \in g-orbital f T \theta G s
    using assms(2) by blast
  also have \forall y. y \in (g\text{-}orbital\ f\ T\ 0\ G\ s) \longrightarrow C\ y
   using assms(1) unfolding wp\text{-rel} by (auto simp: p2r\text{-}def)
  ultimately show C(x r) by blast
qed
theorem DC:
  assumes interval T and wp ([x'=f]T \& G) [C] = Id
  shows wp ([x'=f]T \& G) [Q] = wp ([x'=f]T \& (\lambda s. G s \land C s)) [Q]
proof(rule-tac f = \lambda x. wp x \lceil Q \rceil in HOL.arg-cong, rule subset-antisym, safe)
  {fix s and s' assume s' \in g-orbital f T \cap G s
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
      and guard-x: G \triangleright x \{\theta--t\} and s'=x t and \theta \in T t \in T
     using g-orbitalD[of s' f T \theta G s] by (metis\ (full-types))
   from guard-x have \forall r \in \{0--t\}. \forall \tau \in \{0--r\}. G(x\tau)
      \mathbf{by}\ (\mathit{metis}\ \mathit{contra-subsetD}\ \mathit{ends-in-segment}(1)\ \mathit{subset-segment}(1))
   also have \forall \tau \in \{0--t\}. \ \tau \in T
      using interval.closed-segment-subset-domain [OF assms(1) \land 0 \in T \land \langle t \in T \rangle]
by blast
    ultimately have \forall \tau \in \{0--t\}. x \tau \in q-orbital f T \theta G s
      using q-orbitalI[OF x-ivp \langle \theta \in T \rangle] by blast
   hence \forall \tau \in \{0--t\}. (s, x \tau) \in [x'=f]T \& G
      unfolding wp-rel by(auto simp: p2r-def)
    hence C > x \{\theta - -t\}
      using wp-g-orbit-IdD[OF\ assms(2)] by blast
   hence s' \in g-orbital f T \theta (\lambda s. G s \wedge C s) s
```

using g-orbitalI[OF x-ivp  $\langle 0 \in T \rangle \langle t \in T \rangle$ ] guard-x  $\langle s' = x \ t \rangle$  by fastforce} thus  $\bigwedge s \ s' \in g$ -orbital  $f \ T \ 0 \ G \ s \Longrightarrow s' \in g$ -orbital  $f \ T \ 0 \ (\lambda s. \ G \ s \land C \ s) \ s$ 

```
next show \bigwedge s \ s'. \ s' \in g\text{-}orbital \ f \ T \ \theta \ (\lambda s. \ G \ s \land C \ s) \ s \Longrightarrow s' \in g\text{-}orbital \ f \ T \ \theta
    by (auto simp: g-evol-def)
qed
theorem dCut:
  assumes wp-C:[P] \le wp ([x'=f]\{0..t\} \& G) [C]
    and wp-Q:[P] \subseteq wp ([x'=f]\{0..t\} \& (\lambda s. G s \land C s)) [Q]
  shows \lceil P \rceil \subseteq wp \ (\lceil x' = f \rceil \mid \{0..t\} \& G) \lceil Q \rceil
proof(subst wp-rel, simp add: g-orbital-eq p2r-def, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a assume P(x \theta) and \theta \leq \tau and \tau \leq t
    and x-solves: D = (\lambda t. f(x t)) on \{0...t\} and guard-x: (\forall r \in \{0--\tau\}). G(x)
r))
  hence \forall r \in \{0 - -\tau\}. \forall \tau \in \{0 - -r\}. G(x \tau)
    using closed-segment-closed-segment-subset by blast
  hence \forall r \in \{0 - \tau\}. x r \in g-orbital f \in \{0 . . t\} \theta \in G(x \theta)
    using g-orbital x-solves \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle closed-segment-eq-real-iv by fastforce
  hence \forall r \in \{0 - -\tau\}. C(x r)
    using wp-C \langle P (x \theta) \rangle by(subst (asm) wp-rel, auto)
  hence x \tau \in g-orbital f \{0...t\} \theta (\lambda s. G s \wedge G s) (x \theta)
    using g-orbitalI x-solves guard-x \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  from this \langle P(x \theta) \rangle and wp-Q show Q(x \tau)
    by(subst (asm) wp-rel, auto simp: closed-segment-eq-real-ivl)
qed
```

### Differential Invariant

```
lemma DI-sufficiency:
 assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
 shows wp ([x'=f]T \& G) [Q] \le wp [G] [Q]
 apply(subst wp-rel, subst wp-rel, simp add: p2r-def, clarsimp)
  using assms apply(simp add: g-evol-def ivp-sols-def)
  apply(erule-tac \ x=s \ in \ all E)+
  apply(erule\ exE,\ erule\ impE)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
 shows wp [G] [Q] \le wp ([x'=f]T \& G) [Q]
  unfolding wp-g-orbit apply(subst wp-rel, simp add: p2r-def, clarsimp)
  apply(erule-tac \ x=0 \ in \ ballE)
   apply(simp-all add: ivp)
 oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
((-)/is'-diff'-invariant'-of(-)/along(-)[70,65]61)
where I is-diff-invariant-of f along T \equiv
 (\forall s. \ I \ s \longrightarrow (\forall \ x. \ x \in ivp\text{-sols} \ f \ T \ 0 \ s \longrightarrow (\forall \ t \in T. \ I \ (x \ t))))
```

```
lemma invariant-to-set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s.\ Is \longrightarrow (g\text{-}orbital\ f\ T\ 0\ (\lambda s.
True(s) \subseteq \{s. \ I \ s\}
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
   apply(drule mp, simp-all)
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
  apply(drule mp, simp-all add: subset-eq)
  apply(erule-tac \ x=xa \ t \ in \ all E)
  \mathbf{by}(drule\ mp,\ auto)
lemma dInvariant:
  assumes I is-diff-invariant-of f along T
  shows \lceil I \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \ \lceil I \rceil
  using assms unfolding diff-invariant-def
  by(auto simp: wp-rel g-evol-def ivp-sols-def)
lemma dI:
  assumes I is-diff-invariant-of f along \{0..t\}
    and \lceil P \rceil \leq \lceil I \rceil and \lceil I \rceil \leq \lceil Q \rceil
  shows [P] \leq wp ([x'=f]\{0..t\} \& G) [Q]
  using assms(1) apply(rule-tac\ C=I\ in\ dCut)
  apply(drule-tac\ G=G\ in\ dInvariant)
  using assms(2) dual-order.trans apply blast
  apply(rule\ dWeakening)
  using assms by auto
Finally, we obtain some conditions to prove specific instances of differential
invariants.
named-theorems ode-invariant-rules compilation of rules for differential invari-
ants.
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0--\tau\}.
  ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \text{ has-derivative } (\lambda \tau. \tau *_R \theta)) \text{ (at } r \text{ within } \{\theta - -\tau\}))
shows (\lambda s. \ \vartheta \ s = \nu \ s) is-diff-invariant-of f along \{\theta..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 < \tau \tau < t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0...t\} \vartheta(x \theta) = \nu(x \theta)
  hence \forall r \in \{0-\tau\}. D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R \theta) at r within
\{\theta--\tau\}
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) = (\lambda \tau. \tau *_R \theta)
(\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: tHyp)
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
```

qed

```
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
\textbf{assumes} \ \forall \ x. \ (D \ x = (\lambda \tau. \ f \ (x \ \tau)) \ on \ \{\theta..t\}) \longrightarrow (\forall \ \tau \in \{\theta..t\}. \ \forall \ r \in \{\theta--\tau\}.
\vartheta'(x r) > \nu'(x r)
\wedge (D (\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta' (x r) - \nu' (x r))) \text{ at } r \text{ within}
\{0--\tau\})
shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) \leq \vartheta(x \theta)
  hence primed: \forall r \in \{0--\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x \tau) - \nu(x \tau))))
r) - \nu'(x r))
  at r within \{\theta - -\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\}
    and \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_R (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
\theta))
    by force
  also have \dots \geq \theta
    using tHyp(1) x-ivp(2) primed by (simp add: calculation(1))
  ultimately show \nu (x \tau) \leq \vartheta (x \tau)
    by simp
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0--\tau\}.
\vartheta'(x r) \geq \nu'(x r)
\wedge (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta'(x r) - \nu'(x r))) \text{ at } r \text{ within}
\{0--\tau\}))
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) < \vartheta(x \theta)
  hence primed: \forall r \in \{0--\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) has-derivative
(\lambda \tau. \ \tau *_R \ (\vartheta'(x r) - \nu'(x r)))) \ (at \ r \ within \ \{\theta - -\tau\}) \land \vartheta'(x r) \ge \nu'(x r)
    using assms by auto
  hence \exists r \in \{\theta - \tau\}. (\vartheta (x \tau) - \nu (x \tau)) - (\vartheta (x \theta) - \nu (x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta' (x r) - \nu' (x r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\} and
    \vartheta(x\tau) - \nu(x\tau) = (\tau - \theta) *_R (\vartheta'(xr) - \nu'(xr)) + (\vartheta(x\theta) - \nu(x\theta))
    by force
  also have ... > 0
```

```
using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
      calculation(1) diff-gt-0-iff-gt ge-iff-diff-ge-0 less-eq-real-def zero-le-scaleR-iff)
 ultimately show \nu (x \tau) < \vartheta (x \tau)
   by simp
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes I1 is-diff-invariant-of f along \{0..t\}
   and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. \ I1 \ s \land I2 \ s) is-diff-invariant-of f along \{0..t\}
 using assms unfolding diff-invariant-def by auto
lemma [ode-invariant-rules]:
\mathbf{fixes}\ \vartheta{::}{'a}{::}banach\ \Rightarrow\ real
assumes I1 is-diff-invariant-of f along \{0..t\}
   and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. \ I1 \ s \lor I2 \ s) is-diff-invariant-of f along \{0..t\}
 using assms unfolding diff-invariant-def by auto
end
theory cat2rel-examples
 imports cat2rel
begin
```

### 4.2.3 Examples

The examples in this subsection show different approaches for the verification of hybrid systems. However, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n)  $vec \Rightarrow ('a, 'n)$  vec to model the dynamics of our system. Then we show a partial correctness specification involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

### Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.

- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = \{"y", "v"\}
 morphisms to-str to-var
 apply(rule-tac \ x="y" \ in \ exI)
 by simp
notation to-var (\upharpoonright_V)
lemma number-of-program-vars: CARD(program-vars) = 2
 using type-definition.card type-definition-program-vars by fastforce
instance program-vars::finite
 apply(standard, subst bij-betw-finite[of to-str UNIV {"y","v"}])
  apply(rule bij-betwI')
    apply (simp add: to-str-inject)
 using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
 by simp
lemma program-vars-univD:(UNIV::program-vars\ set) = \{ \upharpoonright_V "y", \upharpoonright_V "v" \}
 apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:\forall x::program-vars. x = \upharpoonright_V "y" \lor x = \upharpoonright_V "v"
 using program-vars-univD by auto
abbreviation constant-acceleration-kinematics g s \equiv
 (\chi i. if i=()_V "y") then s \$ ()_V "v") else g)
notation constant-acceleration-kinematics (K)
lemma cnst-acc-continuous:
 fixes X::(real \hat{p}rogram-vars) set
 shows continuous-on X (K g)
 apply(rule\ continuous-on-vec-lambda)
 unfolding continuous-on-def apply clarsimp
 by(intro tendsto-intros)
lemma picard-lindeloef-cnst-acc:
 fixes g::real assumes 0 \le t and t < 1
 shows picard-lindeloef (\lambda t. K g) {\theta ...t} 1 \theta
 unfolding picard-lindeloef-def apply(simp add: lipschitz-on-def assms, safe)
 apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
 apply(simp-all add: cnst-acc-continuous continuous-on-snd)
  apply(simp add: dist-vec-def L2-set-def dist-real-def)
```

```
apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
   apply(simp-all add: to-var-inject)
  using assms by linarith
abbreviation constant-acceleration-kinematics-flow g t s \equiv
 (\chi i. if i=(\upharpoonright_V "y") then g \cdot t \hat{2}/2 + s \$ (\upharpoonright_V "v") \cdot t + s \$ (\upharpoonright_V "y")
        else q \cdot t + s \$ (\upharpoonright_V "v")
notation constant-acceleration-kinematics-flow (\varphi_K)
lemma local-flow-cnst-acc:
  assumes 0 \le t and t < 1
  shows local-flow (K g) \{0..t\} 1 (\varphi_K g)
  unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-cnst-acc apply blast
  apply(rule has-vderiv-on-vec-lambda)
  using poly-derivatives (3,4) program-vars-exhaust
  apply(simp-all add: to-var-inject vec-eq-iff has-vderiv-on-def has-vector-derivative-def)
  using program-vars-exhaust by blast
lemma wp-cnst-acc:
  assumes 0 \le t and t \le 1
  shows wp ([x'=K g] \{ \theta ... t \} \& G) [Q] =
    \lceil \lambda \ s. \ \forall \ \tau \in \{\theta..t\}. \ (G \rhd (\lambda r. \ \varphi_K \ g \ r \ s) \{\theta - - \tau\}) \longrightarrow Q \ (\varphi_K \ g \ \tau \ s) \rceil
  apply(subst\ local-flow.wp-g-orbit[of\ K\ g-1\ (\lambda\ t\ x.\ \varphi_K\ g\ t\ x)])
  using local-flow-cnst-acc and assms by (auto simp: p2r-def)
\mathbf{lemma}\ single\text{-}evolution\text{-}ball:
  fixes H::real assumes 0 \le t and t \le 1 and q \le 0
  shows \lceil \lambda s. \ \theta \leq s \$ (\lceil_V "y") \land s \$ (\lceil_V "y") = H \land s \$ (\lceil_V "v") = \theta \rceil
  \leq wp \ ([x'=K \ g]\{0..t\} \ \& \ (\lambda \ s. \ s \ \$ \ (\upharpoonright_V \ ''y'') \geq 0))
  [\lambda s. \ 0 \le s \ \$ \ (\upharpoonright_V "y") \land s \ \$ \ (\upharpoonright_V "y") \le H]
  apply(subst\ wp\text{-}cnst\text{-}acc)
  using assms by (auto simp: mult-nonpos-nonneg)
no-notation to-var (\upharpoonright_V)
no-notation constant-acceleration-kinematics (K)
no-notation constant-acceleration-kinematics-flow (\varphi_K)
```

### Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a  $3 \times 3$  matrix (named K) to denote the linear operator that models the constantly accelerated motion.

- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

**term** x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. However, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

**lemma** exhaust-5: — The analogs for 1, 2 and 3 have already been proven in Analysis.

```
fixes x::5 shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5 proof (induct \, x) case (of\text{-}int \, z) then have 0 \le z and z < 5 by simp\text{-}all then have z=0 \lor z=1 \lor z=2 \lor z=3 \lor z=4 by arith then show ?case by auto qed lemma UNIV\text{-}3:(UNIV::3\ set)=\{0,1,2\} apply safe using exhaust\text{-}3 three-eq-zero by (blast, auto) lemma sum\text{-}axis\text{-}UNIV\text{-}3[simp]:(\sum j\in (UNIV::3\ set).\ axis\ i\ 1\ $j\cdot fj)=(f::3\Rightarrow real)\ i unfolding axis\text{-}def\ UNIV\text{-}3 apply simp using exhaust\text{-}3 by force
```

We can rewrite the original constant acceleration kinematics as a linear operator applied to a 3-dimensional vector. For that we take advantage of the following fact:

```
lemma e 1=(\chi\ j::3.\ if\ j=0\ then\ 0\ else\ if\ j=1\ then\ 1\ else\ 0) unfolding axis-def by(rule Cart-lambda-cong, simp)

abbreviation constant-acceleration-kinematics-matrix \equiv (\chi\ i.\ if\ i=(0::3)\ then\ axis\ (1::3)\ (1::real)\ else\ if\ i=1\ then\ axis\ 2\ 1\ else\ 0)

abbreviation constant-acceleration-kinematics-matrix-flow t\ s\equiv (\chi\ i.\ if\ i=(0::3)\ then\ s\ \$\ 2\cdot t\ ^2/2+s\ \$\ 1\cdot t+s\ \$\ 0 else if i=1\ then\ s\ \$\ 2\cdot t+s\ \$\ 1\ else\ s\ \$\ 2)

notation constant-acceleration-kinematics-matrix (K)
```

**notation** constant-acceleration-kinematics-matrix-flow  $(\varphi_K)$ 

With these 2 definitions and the proof that linear systems of ODEs are Picard-Lindeloef, we can show that they form a pair of vector-field and its flow.

**lemma** entries-cnst-acc-matrix: entries  $K = \{0, 1\}$ 

```
apply (simp-all add: axis-def, safe)
      \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
lemma picard-lindeloef-cnst-acc-matrix:
      assumes 0 \le t and t \le 1/9
      shows picard-lindeloef (\lambda \ t \ s. \ K * v \ s) \{0..t\} \ ((real \ CARD(3))^2 \cdot (\|K\|_{max})) \ \theta
      apply(rule picard-lindeloef-linear-system)
      unfolding entries-cnst-acc-matrix using assms by auto
lemma local-flow-cnst-acc-matrix:
      assumes 0 \le t and t < 1/9
      shows local-flow ((*v) K) \{0..t\} ((real CARD(3))<sup>2</sup> · (\|K\|_{max})) \varphi_K
      unfolding local-flow-def local-flow-axioms-def apply safe
      using picard-lindeloef-cnst-acc-matrix[OF assms] apply blast
         apply(rule has-vderiv-on-vec-lambda)
      using poly-derivatives (1,3,4)
         apply(force simp: matrix-vector-mult-def)
      using exhaust-3 by(force simp: matrix-vector-mult-def vec-eq-iff)
Finally, we compute the wlp of this example and use it to verify the single-
evolution ball again.
\mathbf{lemma}\ wp\text{-}cnst\text{-}acc\text{-}matrix:
      assumes 0 \le t and t \le 1/9
      shows wp ([x'=(*v) K]\{\theta..t\} \& G) [Q] = [\lambda s. \forall \tau \in \{\theta..t\}. (G \rhd (\lambda r. \varphi_K r. 
s)\{\theta--\tau\}) \longrightarrow Q (\varphi_K \tau s)
        apply(subst\ local-flow.wp-g-orbit[of\ (*v)\ K-((real\ CARD(3))^2\cdot (||K||_{max}))
      using local-flow-cnst-acc-matrix and assms by auto
\mathbf{lemma}\ single\text{-}evolution\text{-}ball\text{-}K:
      assumes 0 \le t and t \le 1/9
      shows [\lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = H \land s \$ \ 1 = 0 \land 0 > s \$ \ 2]
```

### Circular Motion

 $apply(subst\ wp\text{-}cnst\text{-}acc\text{-}matrix)$ 

The characteristics that distinguish this example are:

using assms by (auto simp: mult-nonneg-nonpos2)

1. We employ an existing finite type of size 2 to model program variables.

 $\leq wp \ ([x'=(*v) \ K]\{\theta..t\} \ \& \ (\lambda s. \ s \ \$ \ \theta \geq \theta)) \ \lceil \lambda s. \ \theta \leq s \ \$ \ \theta \wedge s \ \$ \ \theta \leq H \rceil$ 

2. We define a  $2 \times 2$  matrix (named C) to denote the linear operator that models circular motion.

- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow  $(\varphi_C)$  and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two-eq-zero: (2::2) = 0
 by simp
lemma [simp]: i \neq (0::2) \longrightarrow i = 1
 using exhaust-2 by fastforce
lemma UNIV-2:(UNIV::2\ set)=\{0,\ 1\}
 apply safe using exhaust-2 two-eq-zero by auto
abbreviation circular-motion-matrix \equiv
  (\chi i. if i= (0::2) then axis (1::2) (-1::real) else axis (0.1)
notation circular-motion-matrix (C)
lemma circle-invariant:
 assumes \theta < R
 shows (\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2) is-diff-invariant-of (*v) C along \{\theta...t\}
 apply(rule-tac ode-invariant-rules, clarsimp)
 apply(frule-tac i=0 in has-vderiv-on-vec-nth, drule-tac i=1 in has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def, clarsimp)
 apply(erule-tac x=r in ballE)+
   apply(simp add: matrix-vector-mult-def has-vderiv-on-vec-lambda)
 subgoal for x \tau r apply(rule-tac f'1 = \lambda t. \theta and g'1 = \lambda t. \theta in derivative-eq-intros(11),
simp-all)
    apply(rule-tac f'1 = \lambda t. -2 \cdot (x r \$ \theta) \cdot (t \cdot x r \$ 1)
       and g'1 = \lambda t. 2 · (x r \$ 1) · t · x r \$ 0 in derivative-eq-intros(8), simp-all)
      apply(rule-tac f'1 = \lambda t. - (t \cdot x \ r \ \$ \ 1) in derivative-eq-intros(15))
       apply(rule-tac\ t=\{\theta--\tau\}\ and\ s=\{\theta..t\}\ in\ has-derivative-within-subset)
        apply(simp, simp add: closed-segment-eq-real-ivl, force)
      apply(rule-tac f'1=\lambda t. (t \cdot x \ r \ \$ \ \theta) in derivative-eq-intros(15))
       apply(rule-tac t = \{0 - \tau\} and s = \{0 ... t\} in has-derivative-within-subset)
   \mathbf{by}(simp, simp \ add: \ closed-segment-eq-real-ivl, \ force)
 \mathbf{by}(auto\ simp:\ closed\text{-}segment\text{-}eq\text{-}real\text{-}ivl)
lemma circular-motion-invariants:
 assumes (R::real) > 0
 shows [\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le wp ([x'=(*v) C] \{\theta..t\} \& G) [\lambda s. R^2]
= (s \$ \theta)^2 + (s \$ 1)^2
 using assms(1) apply(rule-tac\ C=\lambda s.\ R^2=(s\ \$\ 0)^2+(s\ \$\ 1)^2 in dCut)
```

```
apply(rule-tac I = \lambda s. R^2 = (s \$ 0)^2 + (s \$ 1)^2 in dI)
 using circle-invariant \langle R > 0 \rangle apply(blast, force, force)
 \mathbf{by}(rule\ dWeakening,\ auto)
— Proof of the same specification by providing solutions:
lemma entries-circ-matrix:entries C = \{0, -1, 1\}
 apply (simp-all add: axis-def, safe)
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
 \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
lemma picard-lindeloef-circ-matrix:
 assumes 0 \le t and t < 1/4
 shows picard-lindeloef (\lambda t. (*v) C) {\theta..t} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \theta
 apply(rule picard-lindeloef-linear-system)
 unfolding entries-circ-matrix using assms by auto
abbreviation circular-motion-matrix-flow t s \equiv (\chi i. if i = (0::2) then
s\$0 \cdot cos \ t - s\$1 \cdot sin \ t \ else \ s\$0 \cdot sin \ t + s\$1 \cdot cos \ t)
notation circular-motion-matrix-flow (\varphi_C)
lemma local-flow-circ-mtx:
 assumes 0 \le t and t < 1/4
 shows local-flow ((*v) C) \{0..t\} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \varphi_C
 unfolding local-flow-def local-flow-axioms-def apply safe
 using picard-lindeloef-circ-matrix assms apply blast
  apply(rule has-vderiv-on-vec-lambda)
 apply(simp add: matrix-vector-mult-def has-vderiv-on-def has-vector-derivative-def,
safe)
 subgoal for s i x
    apply(rule-tac f'1=\lambda t. -s\$0 \cdot (t \cdot \sin x) and g'1=\lambda t. s\$1 \cdot (t \cdot \cos x)in
derivative-eq-intros(11)
     apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule\ derivative-eq-intros(6)[of\ sin\ (\lambda xa.\ (xa\cdot cos\ x))])
     apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
      apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp add: Groups.mult-ac(3) Rings.ring-distribs(4))
 subgoal for s i x
    apply(rule-tac f'1=\lambda t. s\$0 \cdot (t \cdot cos x) and g'1=\lambda t. -s\$1 \cdot (t \cdot sin x)in
derivative-eq-intros(8)
     apply(rule\ derivative-eq-intros(6)[of\ sin\ (\lambda xa.\ xa\cdot cos\ x)])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
     apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
```

```
apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp\ add:\ Groups.mult-ac(3)\ Rings.ring-distribs(4))
  using exhaust-2 two-eq-zero by(force simp: vec-eq-iff)
lemma flow-for-Circ-DS:
 assumes 0 \le t and t \le 1/4
 shows wp ([x'=(*v) C] \{0..t\} \& G) [Q] =
   [\lambda \ x. \ \forall \ \tau \in \{0..t\}. \ (\forall \ r \in \{0--\tau\}. \ G \ (\varphi_C \ r \ x)) \longrightarrow Q \ (\varphi_C \ \tau \ x)]
  apply(subst local-flow.wp-g-orbit|of (*v) C - ((real CARD(2))<sup>2</sup> · (||C||_{max}))
  using local-flow-circ-mtx and assms by auto
lemma circular-motion:
 assumes 0 \le t and t < 1/4 and R > 0
 shows \lceil \lambda s. \ R^2 = (s \ \$ \ \theta)^2 + (s \ \$ \ 1)^2 \rceil \le wp \ ([x'=(*v) \ C] \{\theta..t\} \ \& \ G) \ \lceil \lambda s. \ R^2 \rceil
= (s \$ \theta)^2 + (s \$ 1)^2
 apply(subst flow-for-Circ-DS)
  using assms by simp-all
no-notation circular-motion-matrix (C)
no-notation circular-motion-matrix-flow (\varphi_C)
```

### Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynamics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb\text{-}real\text{-}arith]: 0 \le x \Longrightarrow 0 > g \Longrightarrow 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v \Longrightarrow (x::real) \le H

proof—

assume 0 \le x and 0 > g and 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v

then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot H \wedge 0 > g by auto

hence *:v \cdot v = 2 \cdot g \cdot (x - H) \wedge 0 > g \wedge v \cdot v \ge 0

using left\text{-}diff\text{-}distrib mult.commute by (metis\ zero-le\text{-}square)

from this have (v \cdot v)/(2 \cdot g) = (x - H) by auto

also from * have (v \cdot v)/(2 \cdot g) \le 0

using divide\text{-}nonneg\text{-}neg by fastforce

ultimately have H - x \ge 0 by linarith

thus ?thesis by auto

qed
```

```
assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v
   and pos: g \cdot \tau^2 / 2 + v \cdot \tau + (x::real) = 0
  shows 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
and 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
proof-
  from pos have q \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot x = 0
   by (metis (mono-tags, hide-lams) Groups.mult-ac(1,3) mult-zero-right
        monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + v^2 + 2 \cdot q \cdot H = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(g \cdot \tau + v)^2 + 2 \cdot g \cdot H = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide\text{-}lams)\ Groups.add\text{-}ac(2,3)
        Groups.mult-ac(2, 3) monoid-mult-class.power2-eq-square nat-distrib(2))
  hence 2 \cdot g \cdot H + (-((g \cdot \tau) + v))^2 = 0
   by (metis\ Groups.add-ac(2)\ power2-minus)
  thus 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
   by (simp add: monoid-mult-class.power2-eq-square)
  from * show 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
   by (simp add: monoid-mult-class.power2-eq-square)
qed
lemma [bb-real-arith]:
  assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v
 shows 2 \cdot g \cdot (g \cdot \tau^2 / 2 + v \cdot \tau + (x::real)) =
  2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
  have ?lhs = q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot x
   apply(subst\ Rat.sign-simps(18))+
   \mathbf{by}(auto\ simp:\ semiring-normalization-rules(29))
  also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v (is ... = ?middle)
   \mathbf{by}(subst\ invar,\ simp)
  finally have ?lhs = ?middle.
  moreover
  {have ?rhs = g \cdot g \cdot (\tau \cdot \tau) + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v
      by (simp\ add:\ Groups.mult-ac(2,3)\ semiring-class.distrib-left)
    also have \dots = ?middle
      \mathbf{by}\ (simp\ add\colon semiring\text{-}normalization\text{-}rules(29))
    finally have ?rhs = ?middle.}
  ultimately show ?thesis by auto
qed
lemma bouncing-ball:
  assumes 0 \le t and t \le 1/9
 shows [\lambda s. (0::real) \leq s \$ (0::3) \land s \$ 0 = H \land s \$ 1 = 0 \land 0 > s \$ 2] \subseteq wp
  ((([x'=\lambda s. \ K *v \ s] \{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0));
  (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE Id FI))^*)
  [\lambda s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 \le H]
```

```
apply(rule rel-ad-mka-starI [of - [\lambda s. \ 0 \le s \ \$ \ (0::3) \land 0 > s \ \$ \ 2 \land ]
  2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot H + (s \$ 1 \cdot s \$ 1)]])
   apply(simp, simp only: rel-antidomain-kleene-algebra.fbox-seq)
   apply(subst p2r-r2p-wp-sym[of (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s
$ 1)]) ELSE Id FI)])
   apply(subst\ wp\text{-}cnst\text{-}acc\text{-}matrix)\ using\ assms\ apply(simp,\ simp)\ apply(subst
wp-trafo)
  {\bf unfolding} \ rel-antidomain-kleene-algebra. cond-def \ rel-antidomain-kleene-algebra. ads-d-def
  by(auto simp: p2r-def rel-ad-def bb-real-arith)
Bouncing Ball with invariants
We prove again the bouncing ball but this time with differential invariants.
lemma gravity-invariant: (\lambda s. s \ 2 < 0) is-diff-invariant-of (*v) K along \{0..t\}
  apply(rule-tac \vartheta' = \lambda s. \theta and \nu' = \lambda s. \theta in ode-invariant-rules(3), clarsimp)
  apply(drule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
  apply(unfold has-vderiv-on-def has-vector-derivative-def)
  apply(erule-tac \ x=r \ in \ ball E, simp \ add: matrix-vector-mult-def)
  apply(rule-tac f'1=\lambda s. 0 in derivative-eq-intros(10))
  by(auto simp: closed-segment-eq-real-ivl has-derivative-within-subset)
lemma energy-conservation-invariant:
(\lambda s. \ 2 \cdot s \ \$ \ 2 \cdot s \ \$ \ 0 - 2 \cdot s \ \$ \ 2 \cdot H - s \ \$ \ 1 \cdot s \ \$ \ 1 = 0) is-diff-invariant-of
(*v) K along \{0..t\}
  apply(rule ode-invariant-rules, clarify)
 apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
 apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
  apply(unfold has-vderiv-on-def has-vector-derivative-def)
 apply(erule-tac \ x=r \ in \ ball E, simp-all \ add: matrix-vector-mult-def)+
    apply(rule-tac f'1 = \lambda t. 2 · x r $ 2 · (t · x r $ 1)
     and g'1 = \lambda t. 2 · (t \cdot (x r \$ 1 \cdot x r \$ 2)) in derivative-eq-intros(11))
       apply(rule-tac f'1=\lambda t. 2 · x r $ 2 · (t · x r $ 1) and g'1=\lambda t. 0 in
derivative-eq-intros(11)
   apply(rule-tac f'1=\lambda t. 0 and g'1=(\lambda xa.\ xa.\ xr \$ 1) in derivative-eq-intros(12))
    apply(rule-tac g'1=\lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset closed-segment-eq-real-ivl)
    apply(rule-tac g'1 = \lambda t. 0 in derivative-eq-intros(7))
   apply(rule-tac q'1 = \lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset)
   apply(rule-tac f'1=(\lambda xa. xa \cdot x r \$ 2) and g'1=(\lambda xa. xa \cdot x r \$ 2) in
derivative-eq-intros(12))
  \mathbf{by}(simp-all\ add:\ has-derivative-within-subset)
lemma bouncing-ball-invariants:
  \lceil \lambda s. \ (0::real) \leq s \ \$ \ (0::3) \ \land \ s \ \$ \ 0 = H \ \land \ s \ \$ \ 1 = 0 \ \land \ 0 > s \ \$ \ 2 \rceil \subseteq wp
  ((([x'=\lambda s. \ K *v \ s]\{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0));
```

 $(IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE Id FI))^*)$ 

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begin

```
\lceil \lambda s. \ \theta \leq s \$ \ \theta \wedge s \$ \ \theta \leq H \rceil
       apply(rule-tac I = \lceil \lambda s. \ 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot H + s\$2 \cdot S\$2 
(s\$1 \cdot s\$1) in rel-ad-mka-starI)
              \mathbf{apply}(simp, simp\ only:\ rel-antidomain-kleene-algebra.fbox-seq)
           apply(subst p2r-r2p-wp-sym[of (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s
$ 1)]) ELSE Id FI)])
           apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
              apply(rule-tac I=\lambda s. s \$ 2 < 0 \text{ in } dI)
       using gravity-invariant apply(blast, force simp: p2r-def, force simp: p2r-def)
          \mathbf{apply}(\mathit{rule-tac}\ C = \lambda\ s.\ 2\ \cdot\ s\$2\ \cdot\ s\$0\ -\ 2\ \cdot\ s\$2\ \cdot\ H\ -\ s\$1\ \cdot\ s\$1\ =\ 0\ \mathbf{in}\ dCut)
              \mathbf{apply}(\mathit{rule-tac}\ I = \lambda\ s.\ 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot H - s\$1 \cdot s\$1 = 0\ \mathbf{in}\ dI)
     using energy-conservation-invariant apply (blast, force simp: p2r-def, force simp:
p2r-def)
           apply(rule dWeakening, subst p2r-r2p-wp)
       apply(simp add: rel-antidomain-kleene-algebra.fbox-def)
       unfolding rel-antidomain-kleene-algebra.cond-def p2r-def
       by(auto simp: bb-real-arith rel-ad-def rel-antidomain-kleene-algebra.ads-d-def)
\mathbf{end}
theory cat2ndfun
   \mathbf{imports}../hs\text{-}prelims\text{-}matrices\ Transformer\text{-}Semantics.Kleisli\text{-}Quantale\ KAD.Modal\text{-}Kleene\text{-}Algebra
```

# Chapter 5

# Hybrid System Verification with nondeterministic functions

```
— We start by deleting some conflicting notation and introducing some new.

no-notation Archimedean-Field.ceiling ([-])

and Archimedean-Field.floor-ceiling-class.floor ([-])

and Range-Semiring.antirange-semiring-class.ars-r (r)

and Isotone-Transformers.bqtran ([-])

type-synonym 'a pred = 'a ⇒ bool

notation Abs-nd-fun (-• [101] 100) and Rep-nd-fun (-• [101] 100)
```

### 5.1 Nondeterministic Functions

Our semantics correspond now to nondeterministic functions 'a nd-fun. Below we prove some auxiliary lemmas for them and show that they form an antidomain kleene algebra. The proof just extends the results on the Transformer\_Semantics.Kleisli\_Quantale theory.

```
— Analog of already existing (x<sub>•</sub>)<sup>•</sup> = x.
lemma Abs-nd-fun-inverse2 [simp]:(f<sup>•</sup>)<sub>•</sub> = f
by(simp add: Abs-nd-fun-inverse)
— Analog of already existing (x<sub>•</sub>)<sup>•</sup> = x.
lemma nd-fun-ext:(∧x. (f<sub>•</sub>) x = (g<sub>•</sub>) x) ⇒ f = g
apply(subgoal-tac Rep-nd-fun f = Rep-nd-fun g)
using Rep-nd-fun-inject apply blast
by(rule ext, simp)
instantiation nd-fun :: (type) antidomain-kleene-algebra
begin
```

```
lift-definition antidomain-op-nd-fun :: 'a nd-fun \Rightarrow 'a nd-fun
 is \lambda f. (\lambda x. if ((f_{\bullet}) x = \{\}) then \{x\} else \{\})^{\bullet}.
lift-definition zero-nd-fun :: 'a nd-fun
 is \zeta^{\bullet}.
lift-definition star-nd-fun :: 'a nd-fun \Rightarrow 'a nd-fun
 is \lambda(f::'a \ nd\text{-}fun).gstar \ f.
lift-definition plus-nd-fun :: 'a nd-fun \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun
 is \lambda f g.((f_{\bullet}) \sqcup (g_{\bullet}))^{\bullet}.
named-theorems nd-fun-aka antidomain kleene algebra properties for nondeter-
ministic functions.
lemma nd-fun-assoc[nd-fun-aka]:(a::'a nd-fun) + b + c = a + (b + c)
 \mathbf{by}(transfer, simp \ add: ksup-assoc)
lemma nd-fun-comm[nd-fun-aka]:(a::'a nd-fun) + b = b + a
 by(transfer, simp add: ksup-comm)
lemma nd-fun-distr[nd-fun-aka]:((x::'a nd-fun) + y) \cdot z = x \cdot z + y \cdot z
 and nd-fun-distl[nd-fun-aka]:x \cdot (y + z) = x \cdot y + x \cdot z
 by(transfer, simp add: kcomp-distr, transfer, simp add: kcomp-distl)
lemma nd-fun-zero-sum[nd-fun-aka]: 0 + (x::'a nd-fun) = x
 and nd-fun-zero-dot[nd-fun-aka]:0 \cdot x = 0
 \mathbf{by}(transfer, simp, transfer, auto)
lemma nd-fun-leq[nd-fun-aka]:((x::'a nd-fun) <math>\leq y) = (x + y = y)
 and nd-fun-leq-add[nd-fun-aka]: z \cdot x \leq z \cdot (x + y)
  apply(transfer, metis Abs-nd-fun-inverse2 Rep-nd-fun-inverse le-iff-sup)
 \mathbf{by}(transfer, simp \ add: kcomp-isol)
lemma nd-fun-ad-zero[nd-fun-aka]: ad(x::'a nd-fun) \cdot x = 0
 and nd-fun-ad[nd-fun-aka]: ad(x \cdot y) + ad(x \cdot ad(ady)) = ad(x \cdot ad(ady))
 and nd-fun-ad-one [nd-fun-aka]: ad (ad x) + ad x = 1
  apply(transfer, rule nd-fun-ext, simp add: kcomp-def)
  apply(transfer, rule nd-fun-ext, simp, simp add: kcomp-def)
 by(transfer, simp, rule nd-fun-ext, simp add: kcomp-def)
lemma nd-star-one[nd-fun-aka]:1 + (x::'a nd-fun) \cdot x^* \leq x^*
 and nd-star-unfoldl[nd-fun-aka]:z + x \cdot y \leq y \Longrightarrow x^* \cdot z \leq y
 and nd-star-unfoldr[nd-fun-aka]:z + y \cdot x \leq y \Longrightarrow z \cdot x^* \leq y
  apply(transfer, metis Abs-nd-fun-inverse Rep-comp-hom UNIV-I fun-star-unfoldr
     le-sup-iff less-eq-nd-fun.abs-eq mem-Collect-eq one-nd-fun.abs-eq qstar-comm)
  apply(transfer, metis (no-types, lifting) Abs-comp-hom Rep-nd-fun-inverse
     fun-star-inductl less-eq-nd-fun.transfer sup-nd-fun.transfer)
 by (transfer, metis gstar-inductr Rep-comp-hom Rep-nd-fun-inverse
     less-eq-nd-fun.abs-eq sup-nd-fun.transfer)
```

```
instance
  apply intro-classes apply auto
  using nd-fun-aka apply simp-all
  by(transfer; auto)+
end
```

Now that we know that nondeterministic functions form an Antidomain Kleene Algebra, we give a lifting operation from predicates to 'a nd-fun and prove some useful results for them. Then we add an operation that does the opposite and prove the relationship between both of these.

```
abbreviation p2ndf :: 'a \ pred \Rightarrow 'a \ nd\text{-}fun \ ((1 \lceil - \rceil))
  where [Q] \equiv (\lambda x :: 'a. \{s :: 'a. s = x \land Q s\})^{\bullet}
lemma le-nd-fun-def:F^{\bullet} \leq G^{\bullet} = (\forall s. \ F \ s \subseteq G \ s)
  by(transfer, auto simp: le-fun-def)
lemma le\text{-p2ndf-iff}[simp]:[P] \leq [Q] = (\forall s. P s \longrightarrow Q s)
  by(transfer, auto simp: le-fun-def)
lemma eq-p2ndf-iff:(\lceil P \rceil = \lceil Q \rceil) = (P = Q)
\mathbf{proof}(safe)
  assume \lceil P \rceil = \lceil Q \rceil
  hence \lceil P \rceil \leq \lceil Q \rceil \land \lceil Q \rceil \leq \lceil P \rceil by simp
  then have (\forall s. P s \longrightarrow Q s) \land (\forall s. Q s \longrightarrow P s) by simp
  thus P = Q by auto
qed
lemma p2ndf-le-eta[simp]:[P] \leq \eta^{\bullet}
  by(transfer, simp add: le-fun-def, clarify)
lemma ads-d-p2ndf[simp]:d \lceil P \rceil = \lceil P \rceil
  unfolding ads-d-def antidomain-op-nd-fun-def by(rule nd-fun-ext, auto)
lemma ad-p2ndf[simp]:ad [P] = [\lambda s. \neg P s]
  unfolding antidomain-op-nd-fun-def by(rule nd-fun-ext, auto)
abbreviation ndf2p :: 'a nd-fun \Rightarrow 'a \Rightarrow bool ((1 | - |))
  where |f| \equiv (\lambda x. \ x \in Domain \ (\mathcal{R} \ (f_{\bullet})))
lemma p2ndf-ndf2p-id:F \leq \eta^{\bullet} \Longrightarrow \lceil |F| \rceil = F
  unfolding f2r-def apply(rule nd-fun-ext)
  \mathbf{apply}(\mathit{subgoal\text{-}tac} \ \forall \, x. \ (F_{\bullet}) \ x \subseteq \{x\}, \, \mathit{simp})
  \mathbf{by}(blast, simp\ add:\ le-fun-def\ less-eq-nd-fun.rep-eq)
lemma ndf2p-p2ndf-id:|\lceil P\rceil|=P
  by(simp add: f2r-def)
```

# 5.2 Verification of regular programs

As expected, the weakest precondition is just the forward box operator from the KAD. Below we explore its behavior with the previously defined lifting  $(\lceil - \rceil^*)$  and dropping  $(\lfloor - \rfloor^*)$  operators

```
abbreviation wp f \equiv fbox (f::'a nd-fun)
lemma wp-eta[simp]:wp (\eta^{\bullet}) [P] = [P]
  apply(simp add: fbox-def, transfer, simp)
  \mathbf{by}(rule\ nd\text{-}fun\text{-}ext,\ auto\ simp:\ kcomp\text{-}def)
lemma wp-nd-fun:wp (F^{\bullet}) [P] = [\lambda \ x. \ \forall \ y. \ y \in (F \ x) \longrightarrow P \ y]
  apply(simp add: fbox-def, transfer, simp)
  \mathbf{by}(rule\ nd\text{-}fun\text{-}ext,\ auto\ simp:\ kcomp\text{-}def)
lemma wp-nd-fun2:wp F[P] = [\lambda \ x. \ \forall \ y. \ y \in ((F_{\bullet}) \ x) \longrightarrow P \ y]
  apply(simp add: fbox-def antidomain-op-nd-fun-def)
  by(rule nd-fun-ext, auto simp: Rep-comp-hom kcomp-prop)
lemma wp-nd-fun-etaD:wp (F^{\bullet}) [P] = \eta^{\bullet} \Longrightarrow (\forall y. y \in (F x) \longrightarrow P y)
proof
  fix y assume wp (F^{\bullet}) \lceil P \rceil = (\eta^{\bullet})
  from this have \eta^{\bullet} = [\lambda s. \ \forall y. \ s2p \ (F \ s) \ y \longrightarrow P \ y]
    \mathbf{by}(\mathit{subst\ wp-nd-fun}[\mathit{THEN\ sym}],\ \mathit{simp})
  hence \bigwedge x. \{x\} = \{s. \ s = x \land (\forall y. \ s2p \ (F \ s) \ y \longrightarrow P \ y)\}
    apply(subst (asm) Abs-nd-fun-inject, simp-all)
    by (drule-tac \ x=x \ in \ fun-cong, \ simp)
  then show s2p (F x) y \longrightarrow P y by auto
qed
lemma p2ndf-ndf2p-wp:\lceil |wp|R|P|\rceil = wp|R|P
  apply(rule p2ndf-ndf2p-id)
  by (simp add: a-subid fbox-def one-nd-fun.transfer)
lemma p2ndf-ndf2p-wp-sym:wp R P = \lceil |wp R P| \rceil
  by(rule sym, simp add: p2ndf-ndf2p-wp)
lemma ndf2p\text{-}wpD: |wp F [Q]| s = (\forall s'. s' \in (F_{\bullet}) s \longrightarrow Q s')
  \operatorname{apply}(\operatorname{subgoal-tac} F = (F_{\bullet})^{\bullet})
  apply(rule\ ssubst[of\ F\ (F_{\bullet})^{\bullet}],\ simp)
  \mathbf{apply}(\mathit{subst\ wp-nd-fun})
  \mathbf{by}(simp\text{-}all\ add:\ f2r\text{-}def)
```

We can verify that our introduction of wp coincides with another definition of the forward box operator  $fb_{\mathcal{F}} = \partial_F \circ bd_{\mathcal{F}} \circ op_K$  with the following characterization lemmas.

```
lemma ffb-is-wp:fb<sub>F</sub> (F_{\bullet}) \{x.\ P\ x\} = \{s.\ \lfloor wp\ F\ \lceil P\rceil\rfloor\ s\} unfolding ffb-def unfolding map-dual-def klift-def kop-def fbox-def
```

```
unfolding r2f-def f2r-def apply clarsimp
 unfolding antidomain-op-nd-fun-def unfolding dual-set-def
 unfolding times-nd-fun-def kcomp-def by force
lemma wp-is-ffb:wp F P = (\lambda x. \{x\} \cap fb_{\mathcal{F}} (F_{\bullet}) \{s. |P| s\})^{\bullet}
 apply(rule nd-fun-ext, simp)
 unfolding ffb-def unfolding map-dual-def klift-def kop-def fbox-def
 unfolding r2f-def f2r-def apply clarsimp
 unfolding antidomain-op-nd-fun-def unfolding dual-set-def
 unfolding times-nd-fun-def apply auto
 unfolding kcomp-prop by auto
Next, we introduce assignments and compute their wp.
abbreviation vec-upd :: ('a \hat{\ }'b) \Rightarrow 'b \Rightarrow 'a \Rightarrow 'a \hat{\ }'b \ (-(2[-:==-])[70, 65] 61)
where
x[i :== a] \equiv (\chi j. (if j = i then a else (x \$ j)))
abbreviation assign :: b \Rightarrow (a^b \Rightarrow a) \Rightarrow (a^b \Rightarrow a) nd-fun ((2[-::== -]) [70,
65 | 61) where
[x ::== expr] \equiv (\lambda s. \{s[x :== expr s]\})^{\bullet}
lemma wp-assign[simp]: wp ([x ::== expr]) [Q] = [\lambda s. Q (s[x :== expr s])]
 by(subst wp-nd-fun, rule nd-fun-ext, simp)
The wp of the composition was already obtained in KAD. Antidomain_Semiring:
|x \cdot y| z = |x| |y| z.
We also have an implementation of the conditional operator and its wp.
definition (in antidomain-kleene-algebra) cond :: 'a \Rightarrow 'a \Rightarrow 'a \Rightarrow 'a
(if - then - else - fi [64,64,64] 63) where if p then x else y fi = d p · x + ad p · y
abbreviation cond-sugar :: 'a pred \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun \Rightarrow 'a nd-fun
(IF - THEN - ELSE - FI [64,64,64] 63) where
 IF P THEN X ELSE Y FI \equiv cond \lceil P \rceil X Y
lemma wp-if-then-else:
 assumes [\lambda s. P s \wedge T s] \leq wp X [Q]
   and [\lambda s. \ P \ s \land \neg \ T \ s] \leq wp \ Y \ [Q]
 shows \lceil P \rceil \leq wp \ (IF \ T \ THEN \ X \ ELSE \ Y \ FI) \ \lceil Q \rceil
 using assms apply(subst wp-nd-fun2)
 apply(subst (asm) wp-nd-fun2)+
 unfolding cond-def apply(clarsimp, transfer)
 \mathbf{by}(auto\ simp:\ kcomp-prop)
Finally we also deal with finite iteration.
\mathbf{lemma} \ (\mathbf{in} \ \mathit{antidomain-kleene-algebra}) \ \mathit{fbox-starI} \colon
assumes d p \leq d i and d i \leq |x| i and d i \leq d q
shows d p \leq |x^{\star}| q
 by (meson assms local.dual-order.trans local.fbox-iso local.fbox-star-induct-var)
```

```
lemma nd-fun-ads-d-ef:d (f::'a nd-fun) = (<math>\lambda x. if (f_{\bullet}) x = \{\} then \{\} else \eta x
 unfolding ads-d-def apply(rule nd-fun-ext, simp)
 apply transfer by auto
lemma ads-d-mono: x \le y \Longrightarrow d \ x \le d \ y
 by (metis ads-d-def fbox-antitone-var fbox-dom)
lemma nd-fun-top-ads-d:(x::'a <math>nd-fun) < 1 \implies d x = x
 apply(simp add: ads-d-def, transfer, simp)
 apply(rule \ nd\text{-}fun\text{-}ext, \ simp)
 apply(subst (asm) le-fun-def)
 by auto
lemma wp-starI:
assumes P \leq I and I \leq wp \ F \ I and I \leq Q
shows P \leq wp \ (qstar \ F) \ Q
proof-
 from assms(1,2) have P \leq 1
   by (metis a-subid basic-trans-rules (23) fbox-def)
 hence dP = P using nd-fun-top-ads-d by blast
 have \bigwedge x y. d(wp x y) = wp x y
   by(metis ds.ddual.mult-oner fbox-mult fbox-one)
 from this and assms have d P \leq d I \wedge d I \leq wp F I \wedge d I \leq d Q
   by (metis (no-types) ads-d-mono assms)
 hence d P \leq wp (F^*) Q
   \mathbf{by}(simp\ add:\ fbox-starI[of-I])
 then show P \leq wp \; (qstar \; F) \; Q
   using \langle d|P = P \rangle by (transfer, simp)
qed
```

# 5.3 Verification of hybrid programs

## 5.3.1 Verification by providing solutions

```
abbreviation guards :: ('a \Rightarrow bool) \Rightarrow (real \Rightarrow 'a) \Rightarrow (real set) \Rightarrow bool (- \triangleright - - [70, 65] 61)
where G \triangleright x \ T \equiv \forall \ r \in T. G \ (x \ r)
definition ivp\text{-}sols \ f \ T \ t_0 \ s = \{x \ | x. \ (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T\}
lemma ivp\text{-}sols \ I:
assumes D \ x = (f \circ x) \ on \ T \ x \ t_0 = s \ t_0 \in T
shows x \in ivp\text{-}sols \ f \ T \ t_0 \ s
using assms unfolding ivp\text{-}sols\text{-}def by blast
lemma ivp\text{-}sols \ D:
assumes x \in ivp\text{-}sols \ f \ T \ t_0 \ s
```

```
shows D x = (f \circ x) on T
   and x t_0 = s and t_0 \in T
 using assms unfolding ivp-sols-def by auto
lemma (t::real) \in \{0--t\}
 by (rule ends-in-segment(2))
lemma (t::real) \in \{0..t\}
 apply auto
 oops
definition g-orbital f T t_0 G s = \bigcup \{\{x \ t | t. \ t \in T \land G \rhd x \ \{t_0 - - t\}\}\} | x. \ x \in T
ivp-sols f T t_0 s
lemma g-orbital-eq: g-orbital f T t_0 G s =
 \{x \ t \ | t \ x. \ t \in T \land (D \ x = (f \circ x) \ on \ T) \land x \ t_0 = s \land t_0 \in T \land G \rhd x \ \{t_0 - -t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbital f T t_0 G s = (\bigcup x \in ivp\text{-sols } f T t_0 s. \{x \mid t \mid t. t \in T \land G \rhd x\}
\{t_0--t\}\}
 unfolding g-orbital-def ivp-sols-def by auto
lemma g-orbitalI:
 assumes D x = (f \circ x) on T x t_0 = s
   and t_0 \in T t \in T and G \rhd x \{t_0 - -t\}
 shows x \ t \in g-orbital f \ T \ t_0 \ G \ s
 using assms unfolding g-orbital-def ivp-sols-def by blast
lemma q-orbitalD:
  assumes s' \in g-orbital f T t_0 G s
 obtains x and t where x \in ivp\text{-}sols f T t_0 s
 and D x = (f \circ x) on T x t_0 = s
 and x t = s' and t_0 \in T t \in T and G \triangleright x \{t_0 - -t\}
  using assms unfolding g-orbital-def ivp-sols-def by blast
abbreviation g\text{-}evol ::(('a::banach) \Rightarrow 'a) \Rightarrow real \ set \Rightarrow 'a \ pred \Rightarrow 'a \ nd\text{-}fun \ ((1[x'=-]-
& -))
 where [x'=f]T \& G \equiv (\lambda \ s. \ g\text{-}orbital \ f \ T \ 0 \ G \ s)^{\bullet}
lemmas g-evol-def = g-orbital-eq[where t_0=\theta]
context local-flow
begin
lemma in-ivp-sols: (\lambda t. \varphi t s) \in ivp-sols f T \theta s
 by(auto intro: ivp-solsI simp: ivp init-time)
definition orbit s = q-orbital f T \theta (\lambda s. True) s
```

```
lemma orbit-eq[simp]: orbit s = \{ \varphi \ t \ s | \ t. \ t \in T \}
  unfolding orbit-def g-evol-def
  by(auto intro: usolves-ivp intro!: ivp simp: init-time)
lemma q-evol-collapses:
  shows ([x'=f]T \& G) = (\lambda s. \{\varphi \ t \ s| \ t. \ t \in T \land G \rhd (\lambda r. \ \varphi \ r \ s) \{\theta--t\}\})^{\bullet}
proof(rule nd-fun-ext, rule subset-antisym, simp-all add: subset-eq)
  let ?P \ s \ s' = \exists \ t. \ s' = \varphi \ t \ s \land s2p \ T \ t \land (\forall \ r \in \{0 - - t\}. \ G \ (\varphi \ r \ s))
  {fix s' assume s' \in g-orbital f T \theta G s
    then obtain x and t where x-ivp:D x = (f \circ x) on T
      x \theta = s \text{ and } x t = s' \text{ and } t \in T \text{ and } guard: G \triangleright x \{\theta - -t\}
      unfolding g-orbital-eq by blast
    hence obs: \forall \tau \in \{0--t\}. \ x \ \tau = \varphi \ \tau \ s
      using usolves-ivp[of\ x\ s]\ closed-segment-subset-domain I\ in it-time\ comp-def
      by (metis (mono-tags, lifting) has-vderiv-eq)
    hence G \triangleright (\lambda r. \varphi r s) \{\theta - -t\}
      using quard by simp
    hence \exists t. \ s' = \varphi \ t \ s \land s2p \ T \ t \land (\forall r \in \{0 - -t\}. \ G \ (\varphi \ r \ s))
      using \langle x | t = s' \rangle \langle t \in T \rangle \ obs \ by \ blast
  thus \forall s' \in g-orbital f \ T \ 0 \ G \ s. ?P \ s \ s'
    by blast
  \{\text{fix } s' \text{ assume } \exists t. \ s' = \varphi \ t \ s \land s2p \ T \ t \land (\forall r \in \{0--t\}. \ G \ (\varphi \ r \ s))\}
    then obtain t where G \rhd (\lambda r. \varphi \ r \ s) \ \{\theta - - t\} and t \in T and \varphi \ t \ s = s'
    hence s' \in g-orbital f T \theta G s
      by(auto intro: g-orbitalI simp: ivp init-time)}
  thus \forall s'. ?P \ s \ s' \longrightarrow s' \in (g\text{-}orbital \ f \ T \ 0 \ G \ s)
    by blast
\mathbf{qed}
lemma wp-orbit: wp ((\lambda \ s. \ orbit \ s)^{\bullet}) \ [Q] = [\lambda \ s. \ \forall \ t \in T. \ Q \ (\varphi \ t \ s)]
  unfolding orbit-eq wp-nd-fun apply(rule nd-fun-ext) by auto
lemma wp-g-orbit: wp ([x'=f]T \& G) [Q] = [\lambda \ s. \ \forall \ t \in T. \ (G \rhd (\lambda r. \varphi \ r \ s))]
\{\theta--t\}\longrightarrow Q\ (\varphi\ t\ s)
  unfolding g-evol-collapses wp-nd-fun apply(rule nd-fun-ext) by auto
end
lemma (in global-flow) ivp-sols-collapse[simp]: ivp-sols f UNIV 0 s = \{(\lambda t. \varphi t)\}
s)
  by(auto intro: usolves-ivp simp: ivp-sols-def ivp)
The previous lemma allows us to compute wlps for known systems of ODEs.
We can also implement a version of it as an inference rule. A simple com-
putation of a wlp is shown immediately after.
```

lemma dSolution:

assumes local-flow  $f T L \varphi$ 

```
and \forall s. \ P \ s \longrightarrow (\forall \ t \in T. \ (G \rhd (\lambda r. \varphi \ r \ s) \ \{\theta..t\}) \longrightarrow Q \ (\varphi \ t \ s))
  shows [P] \leq wp ([x'=f]T \& G) [Q]
  using assms apply(subst local-flow.wp-g-orbit, auto)
  by (simp add: Starlike.closed-segment-eq-real-ivl)
lemma line-DS: 0 \le t \Longrightarrow wp ([x'=\lambda s. c]\{0..t\} \& G) [Q] =
     [\lambda \ x. \ \forall \ \tau \in \{\theta..t\}. \ (G \rhd (\lambda r. \ x + r *_R c) \ \{\theta..\tau\}) \longrightarrow Q \ (x + \tau *_R c)]
  \mathbf{apply}(\mathit{subst\ local\text{-}flow}.\mathit{wp-g-orbit}[\mathit{of}\ \lambda \mathit{s.\ c-1/(t+1)}\ (\lambda\ t\ \mathit{x.\ x+t}\ *_{\mathit{R}}\ \mathit{c})])
  by(auto simp: line-is-local-flow closed-segment-eq-real-ivl)
```

### 5.3.2 Verification with differential invariants

We derive the domain specific rules of differential dynamic logic (dL). In each subsubsection, we first derive the dL axioms (named below with two capital letters and "D" being the first one). This is done mainly to prove that there are minimal requirements in Isabelle to get the dL calculus. Then we prove the inference rules which are used in verification proofs.

### Differential Weakening

```
lemma DW: wp ([x'=f]T \& G) [Q] = wp ([x'=f]T \& G) [\lambda s. Gs \longrightarrow Qs]
 apply(subst\ wp-nd-fun)+
 apply(rule \ nd-fun-ext)
 \mathbf{by}(auto\ simp:\ g\text{-}orbital\text{-}eq)
lemma dWeakening:
  assumes \lceil G \rceil \leq \lceil Q \rceil
 shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \lceil Q \rceil
 using assms apply(subst\ wp-nd-fun)
  by(auto simp: le-fun-def g-orbital-eq)
Differential Cut
```

```
lemma wp-q-orbit-etaD:
 assumes wp ([x'=f]T \& G) [C] = \eta^{\bullet} \text{ and } \forall r \in \{0--t\}. \ x r \in g\text{-}orbital f T 0
 shows \forall r \in \{\theta - -t\}. C(x r)
proof
 fix r assume r \in \{\theta - -t\}
 then have x r \in q-orbital f T \theta G s
   using assms(2) by blast
 also have \forall y. y \in (g\text{-}orbital\ f\ T\ 0\ G\ s) \longrightarrow C\ y
   using assms(1) wp-nd-fun-etaD by fastforce
  ultimately show C(x r) by blast
qed
lemma DC:
 assumes interval T and wp ([x'=f]T \& G) [C] = \eta^{\bullet}
 shows wp ([x'=f]T \& G) [Q] = wp ([x'=f]T \& (\lambda s. G s \land C s)) [Q]
```

```
\operatorname{proof}(\operatorname{rule-tac} f = \lambda \ x. \ wp \ x \ [Q] \ \operatorname{in} \ HOL. arg\text{-}cong, \ \operatorname{rule} \ \operatorname{nd-fun-ext}, \ \operatorname{rule} \ \operatorname{subset-antisym},
simp-all)
  \mathbf{fix} \ s
  \{ \text{fix } s' \text{ assume } s' \in g\text{-}orbital \ f \ T \ \theta \ G \ s \} 
    then obtain t::real and x where x-ivp: D x = (f \circ x) on T x \theta = s
       and quard-x: G \triangleright x \{0--t\} and s'=x t and \theta \in T t \in T
       using q-orbitalD[of s' f T 0 G s] by (metis (full-types))
    from guard-x have \forall r \in \{0--t\}. \forall \tau \in \{0--r\}. G(x\tau)
       by (metis\ contra-subset D\ ends-in-segment(1)\ subset-segment(1))
    also have \forall \tau \in \{0--t\}. \ \tau \in T
       using interval.closed-segment-subset-domain[OF assms(1) \langle 0 \in T \rangle \langle t \in T \rangle]
by blast
    ultimately have \forall \tau \in \{0--t\}. x \tau \in g-orbital f T \theta G s
       using g-orbitalI[OF x-ivp (0 \in T)] by blast
    hence C > x \{\theta - -t\}
       using wp-g-orbit-etaD assms(2) by blast
    hence s' \in g-orbital f T \theta (\lambda s. G s \wedge C s) s
       using g-orbitalI[OF x-ivp \langle 0 \in T \rangle \langle t \in T \rangle] guard-x \langle s' = x t \rangle by fastforce}
  thus g-orbital f T \theta G s \subseteq g-orbital f T \theta (\lambda s. G s \wedge C s) s
    by blast
next show \bigwedge s. g-orbital f \ T \ \theta \ (\lambda s. \ G \ s \land C \ s) \ s \subseteq g-orbital f \ T \ \theta \ G \ s
    by (auto simp: q-evol-def)
qed
lemma dCut:
  assumes wp-C:[P] \le wp ([x'=f]\{0..t\} \& G) [C]
    and wp-Q:[P] \le wp ([x'=f]\{0..t\} \& (\lambda s. G s \land C s)) [Q]
  shows \lceil P \rceil \leq wp \ (\lceil x' = f \rceil \mid \{0..t\} \& G) \ \lceil Q \rceil
proof(simp add: wp-nd-fun q-orbital-eq, clarsimp)
  fix \tau::real and x::real \Rightarrow 'a assume P(x \theta) and \theta \leq \tau and \tau \leq t
    and x-solves: D = (\lambda t. f(x t)) on \{0...t\} and guard-x: (\forall r \in \{0--\tau\}). G(x)
r))
  hence \forall r \in \{0 - -\tau\}. \forall \tau \in \{0 - -r\}. G(x \tau)
    using closed-segment-closed-segment-subset by blast
  hence \forall r \in \{0 - \tau\}. x r \in g-orbital f \{0 . t\} \ \theta \ G \ (x \ \theta)
    using g-orbital x-solves \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle closed-segment-eq-real-iv by fastforce
  hence \forall r \in \{0 - -\tau\}. C(x r)
    using wp-C \langle P(x \theta) \rangle by(subst(asm) wp-nd-fun, auto)
  hence x \tau \in g-orbital f \{0..t\} \theta (\lambda s. G s \wedge C s) (x \theta)
    using g-orbital x-solves guard-x \langle 0 \leq \tau \rangle \langle \tau \leq t \rangle by fastforce
  from this \langle P(x \theta) \rangle and wp-Q show Q(x \tau)
    by(subst (asm) wp-nd-fun, auto simp: closed-segment-eq-real-ivl)
qed
Differential Invariant
```

```
lemma DI-sufficiency:
  assumes \forall s. \exists x. x \in ivp\text{-sols } f \ T \ 0 \ s
 shows wp ([x'=f]T \& G) [Q] \le wp [G] [Q]
```

```
using assms apply(subst wp-nd-fun, subst wp-nd-fun, clarsimp)
 apply(rename-tac\ s,\ erule-tac\ x=s\ in\ all E,\ erule\ impE)
 apply(simp add: g-evol-def ivp-sols-def)
 apply(erule-tac \ x=s \ in \ all E, \ clarify)
  by (rule-tac \ x=0 \ in \ exI, \ rule-tac \ x=x \ in \ exI, \ auto)
lemma (in local-flow) DI-necessity:
  shows wp \lceil G \rceil \lceil Q \rceil \le wp (\lceil x' = f \rceil T \& G) \lceil Q \rceil
  unfolding wp-g-orbit apply(subst wp-nd-fun, clarsimp, safe)
  apply(erule-tac x=0 in ballE)
    apply(simp \ add: ivp, simp)
 oops
definition diff-invariant :: 'a pred \Rightarrow (('a::real-normed-vector) \Rightarrow 'a) \Rightarrow real set
\Rightarrow bool
((-)/is'-diff'-invariant'-of(-)/along(-)[70,65]61)
where I is-diff-invariant-of f along T \equiv
  (\forall s. \ I \ s \longrightarrow (\forall \ x. \ x \in ivp\text{-sols} \ f \ T \ 0 \ s \longrightarrow (\forall \ t \in T. \ I \ (x \ t))))
lemma invariant-to-set:
  shows (I is-diff-invariant-of f along T) \longleftrightarrow (\forall s. \ Is \longrightarrow (g\text{-}orbital \ f \ T \ 0 \ (\lambda s.
True(s) \subseteq \{s. \ I \ s\})
  unfolding diff-invariant-def ivp-sols-def g-orbital-eq apply safe
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
   apply(drule mp, simp-all)
  apply(erule-tac \ x=xa \ \theta \ in \ all E)
  apply(drule mp, simp-all add: subset-eq)
  apply(erule-tac \ x=xa \ t \ in \ all E)
  \mathbf{by}(drule\ mp,\ auto)
lemma dInvariant:
  assumes I is-diff-invariant-of f along T
 shows \lceil I \rceil \leq wp \ (\lceil x' = f \rceil T \& G) \ \lceil I \rceil
  using assms unfolding diff-invariant-def apply(subst wp-nd-fun)
 apply(subst le-p2ndf-iff, clarify)
 apply(erule-tac \ x=s \ in \ all E)
  unfolding g-orbital-def by auto
lemma dI:
  assumes I is-diff-invariant-of f along \{0..t\}
    and \lceil P \rceil \leq \lceil I \rceil and \lceil I \rceil \leq \lceil Q \rceil
 shows \lceil P \rceil \leq wp \ ([x'=f] \{ \theta ..t \} \& G) \ \lceil Q \rceil
  using assms(1) apply(rule-tac\ C=I\ in\ dCut)
  apply(drule-tac\ G=G\ in\ dInvariant)
  using assms(2) dual-order.trans apply blast
 apply(rule dWeakening)
  using assms by auto
```

Finally, we obtain some conditions to prove specific instances of differential

invariants.

named-theorems ode-invariant-rules compilation of rules for differential invariants

```
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0--\tau\}.
  ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \text{ has-derivative } (\lambda \tau. \tau *_R \theta)) \text{ (at } r \text{ within } \{\theta - -\tau\}))
shows (\lambda s. \vartheta s = \nu s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x = (\lambda \tau. f(x \tau)) on \{0..t\} \vartheta(x \theta) = \nu(x \theta)
  hence \forall r \in \{0-\tau\}. D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R \theta) at r within
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) = (\lambda \tau. \tau *_R \theta)
    by(rule-tac closed-segment-mvt, auto simp: tHyp)
  thus \vartheta (x \tau) = \nu (x \tau) by (simp \ add: x-ivp(2))
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0--\tau\}.
\vartheta'(x r) \geq \nu'(x r)
\wedge (D (\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \mapsto (\lambda \tau. \tau *_R (\vartheta' (x r) - \nu' (x r))) \text{ at } r \text{ within}
\{0--\tau\})
shows (\lambda s. \ \nu \ s \leq \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp: D x = (\lambda \tau. f(x \tau)) on \{0..t\} \nu(x \theta) \leq \vartheta(x \theta)
  hence primed: \forall r \in \{0-\tau\}. (D(\lambda \tau. \vartheta(x \tau) - \nu(x \tau)) \mapsto (\lambda \tau. \tau *_R(\vartheta'(x \tau)))
r) - \nu'(x r))
  at r within \{0--\tau\}) \wedge \nu'(x r) \leq \vartheta'(x r)
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\}
    and \vartheta(x \tau) - \nu(x \tau) = (\tau - \theta) *_{B} (\vartheta'(x r) - \nu'(x r)) + (\vartheta(x \theta) - \nu(x \theta))
\theta))
    by force
  also have \dots \geq \theta
    using tHyp(1) x-ivp(2) primed by (simp add: calculation(1))
  ultimately show \nu (x \tau) \leq \vartheta (x \tau)
    by simp
qed
```

```
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes \forall x. (D x = (\lambda \tau. f(x \tau)) \text{ on } \{0..t\}) \longrightarrow (\forall \tau \in \{0..t\}. \forall \tau \in \{0..-\tau\}.
\vartheta'(x r) \ge \nu'(x r)
\wedge (D(\lambda \tau, \vartheta(x, \tau) - \nu(x, \tau)) \mapsto (\lambda \tau, \tau *_{R}(\vartheta'(x, r) - \nu'(x, r))) at r within
\{0--\tau\})
shows (\lambda s. \ \nu \ s < \vartheta \ s) is-diff-invariant-of f along \{0..t\}
proof(simp add: diff-invariant-def ivp-sols-def, clarsimp)
  fix x \tau assume tHyp: 0 \le \tau \tau \le t
    and x-ivp:D x=(\lambda \tau.\ f\ (x\ \tau)) on \{\theta..t\}\ \nu\ (x\ \theta)<\vartheta\ (x\ \theta)
  hence primed: \forall r \in \{0--\tau\}. ((\lambda \tau. \vartheta (x \tau) - \nu (x \tau)) \text{ has-derivative }
(\lambda \tau. \ \tau *_R \ (\vartheta'(x \ r) - \ \nu'(x \ r)))) \ (at \ r \ within \ \{\theta - - \tau\}) \land \vartheta'(x \ r) \ge \nu'(x \ r)
    using assms by auto
  hence \exists r \in \{0 - \tau\}. (\vartheta(x \tau) - \nu(x \tau)) - (\vartheta(x \theta) - \nu(x \theta)) =
  (\lambda \tau. \ \tau *_R (\vartheta'(x r) - \nu'(x r))) (\tau - \theta)
    by(rule-tac closed-segment-mvt, auto simp: \langle 0 \leq \tau \rangle)
  then obtain r where r \in \{\theta - -\tau\} and
    \vartheta\left(x\;\tau\right)-\nu\left(x\;\tau\right)=\left(\tau\;-\;\theta\right)\ast_{R}\left(\vartheta'\left(x\;r\right)\;-\;\nu'\left(x\;r\right)\right)+\left(\vartheta\;\left(x\;\theta\right)\;-\;\nu\;\left(x\;\theta\right)\right)
    by force
  also have ... > \theta
   using tHyp(1) x-ivp(2) primed by (metis (no-types,hide-lams) Groups.add-ac(2)
add-sign-intros(1)
        calculation(1) diff-gt-0-iff-gt ge-iff-diff-ge-0 less-eq-real-def zero-le-scaleR-iff)
  ultimately show \nu (x \tau) < \vartheta (x \tau)
    by simp
qed
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes I1 is-diff-invariant-of f along \{0..t\}
    and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. I1 s \wedge I2 s) is-diff-invariant-of f along {0..t}
  using assms unfolding diff-invariant-def by auto
lemma [ode-invariant-rules]:
fixes \vartheta::'a::banach \Rightarrow real
assumes I1 is-diff-invariant-of f along \{0..t\}
    and I2 is-diff-invariant-of f along \{0..t\}
shows (\lambda s. \ I1 \ s \lor I2 \ s) is-diff-invariant-of f along \{0..t\}
  using assms unfolding diff-invariant-def by auto
end
theory cat2ndfun-examples
  imports cat2ndfun
begin
```

### 5.3.3 Examples

The examples in this subsection show different approaches for the verification of hybrid systems. However, the general approach can be outlined as follows: First, we select a finite type to model program variables 'n. We use this to define a vector field f of type ('a, 'n)  $vec \Rightarrow ('a, 'n)$  vec to model the dynamics of our system. Then we show a partial correctness specification involving the evolution command [x'=f]T & G either by finding a flow for the vector field or through differential invariants.

### Single constantly accelerated evolution

The main characteristics distinguishing this example from the rest are:

- 1. We define the finite type of program variables with 2 Isabelle strings which make the final verification easier to parse.
- 2. We define the vector field (named K) to model a constantly accelerated object.
- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this vector field.
- 4. The verification is only done on a single evolution command (not operated with any other hybrid program).

```
typedef program-vars = \{''y'', ''v''\}
 morphisms to-str to-var
 apply(rule-tac \ x="y" \ in \ exI)
 by simp
notation to-var (\upharpoonright_V)
lemma number-of-program-vars: CARD(program-vars) = 2
 using type-definition.card type-definition-program-vars by fastforce
instance program-vars::finite
 apply(standard, subst bij-betw-finite[of to-str UNIV {"y","v"}])
  apply(rule bij-betwI')
    apply (simp add: to-str-inject)
 using to-str apply blast
  apply (metis to-var-inverse UNIV-I)
 by simp
lemma program-vars-univD:(UNIV::program-vars\ set) = \{ \upharpoonright_V "y", \upharpoonright_V "v" \}
 apply auto by (metis to-str to-str-inverse insertE singletonD)
lemma program-vars-exhaust:\forall x::program-vars. x = \lceil_V "y" \lor x = \lceil_V "v"
```

```
using program-vars-univD by auto
abbreviation constant-acceleration-kinematics q s \equiv
  (\chi i. if i=(\upharpoonright_V "y") then s \$ (\upharpoonright_V "v") else g)
notation constant-acceleration-kinematics (K)
lemma cnst-acc-continuous:
  fixes X::(real \hat{p}rogram-vars) set
 shows continuous-on X (K q)
 apply(rule\ continuous-on-vec-lambda)
  unfolding continuous-on-def apply clarsimp
  \mathbf{by}(intro\ tendsto-intros)
\textbf{lemma} \ \textit{picard-lindeloef-cnst-acc:}
  fixes g::real assumes 0 \le t and t < 1
 shows picard-lindeloef (\lambda t. K g) {\theta ...t} 1 \theta
  unfolding picard-lindeloef-def apply(simp add: lipschitz-on-def assms, safe)
  apply(rule-tac\ t=UNIV\ and\ f=snd\ in\ continuous-on-compose2)
  apply(simp-all add: cnst-acc-continuous continuous-on-snd)
  apply(simp add: dist-vec-def L2-set-def dist-real-def)
  apply(subst\ program-vars-univD,\ subst\ program-vars-univD)
  apply(simp-all add: to-var-inject)
  using assms by linarith
abbreviation constant-acceleration-kinematics-flow g\ t\ s \equiv
  (\chi i. if i=(\upharpoonright_V "y") then g \cdot t \hat{} 2/2 + s \$ (\upharpoonright_V "v") \cdot t + s \$ (\upharpoonright_V "y")
        else g \cdot t + s \$ (\upharpoonright_V "v")
notation constant-acceleration-kinematics-flow (\varphi_K)
lemma local-flow-cnst-acc:
  assumes 0 \le t and t < 1
 shows local-flow (K g) \{\theta..t\} 1 (\varphi_K g)
  unfolding local-flow-def local-flow-axioms-def apply safe
  using assms picard-lindeloef-cnst-acc apply blast
  apply(rule has-vderiv-on-vec-lambda)
  using poly-derivatives (3,4) program-vars-exhaust
  apply(simp-all\ add:\ to-var-inject\ vec-eq-iff\ has-vderiv-on-def\ has-vector-derivative-def)
  using program-vars-exhaust by blast
lemma wp-cnst-acc:
  assumes 0 \le t and t < 1
 shows wp ([x'=K g]\{\theta..t\} \& G) \lceil Q \rceil =
   [\lambda \ s. \ \forall \ \tau \in \{0..t\}. \ (G \rhd (\lambda r. \varphi_K \ g \ r \ s)\{0--\tau\}) \longrightarrow Q \ (\varphi_K \ g \ \tau \ s)]
  \mathbf{apply}(\mathit{subst\ local-flow}.\mathit{wp-g-orbit}[\mathit{of}\ \mathit{K}\ \mathit{g}\ \text{-}\ 1\ (\lambda\ t\ \mathit{x}.\ \varphi_{\mathit{K}}\ \mathit{g}\ t\ \mathit{x})])
  using local-flow-cnst-acc and assms by(auto simp: nd-fun-ext)
```

 ${f lemma}\ single-evolution-ball:$ 

```
fixes H::real assumes 0 \le t and t < 1 and g < 0 shows \lceil \lambda s. \ 0 \le s \$ \ (\lceil_V \ ''y'') \land s \$ \ (\lceil_V \ ''y'') = H \land s \$ \ (\lceil_V \ ''v'') = 0 \rceil \le wp \ ([x'=K g]\{0..t\} \& (\lambda s. s \$ \ (\lceil_V \ ''y'') \ge 0)) \lceil \lambda s. \ 0 \le s \$ \ (\lceil_V \ ''y'') \land s \$ \ (\lceil_V \ ''y'') \le H \rceil apply(subst wp-cnst-acc) using assms by(auto simp: mult-nonpos-nonneg) no-notation to-var (\lceil_V) no-notation constant-acceleration-kinematics (K)
```

### Single evolution revisited.

We list again the characteristics that distinguish this example:

- 1. We employ an existing finite type of size 3 to model program variables.
- 2. We define a  $3 \times 3$  matrix (named K) to denote the linear operator that models the constantly accelerated motion.
- 3. We define a local flow  $(\varphi_K)$  and use it to compute the wlp for this linear operator.
- 4. The verification is done equivalently to the above example.

**term** x::2 — It turns out that there is already a 2-element type:

```
lemma CARD(program-vars) = CARD(2)
unfolding number-of-program-vars by simp
```

In fact, for each natural number n there is already a corresponding n-element type in Isabelle. However, there are still lemmas to prove about them in order to do verification of hybrid systems in n-dimensional Euclidean spaces.

**lemma** exhaust-5: — The analogs for 1, 2 and 3 have already been proven in Analysis.

```
fixes x::5

shows x=1 \lor x=2 \lor x=3 \lor x=4 \lor x=5

proof (induct\ x)

case (of\text{-}int\ z)

then have 0 \le z and z < 5 by simp\text{-}all

then have z=0 \lor z=1 \lor z=2 \lor z=3 \lor z=4 by arith

then show ?case by auto

qed

lemma UNIV\text{-}3:(UNIV::3\ set)=\{0,1,2\}

apply safe using exhaust\text{-}3 three-eq-zero by (blast,\ auto)
```

```
lemma sum-axis-UNIV-3[simp]:(\sum j \in (UNIV::3 \ set). \ axis i 1 \$ j \cdot f j) = (f::3 \Rightarrow real) i unfolding axis-def UNIV-3 apply simp using exhaust-3 by force
```

We can rewrite the original constant acceleration kinematics as a linear operator applied to a 3-dimensional vector. For that we take advantage of the following fact:

```
lemma e 1=(\chi\ j::3.\ if\ j=0\ then\ 0\ else\ if\ j=1\ then\ 1\ else\ 0) unfolding axis-def by(rule Cart-lambda-cong, simp)

abbreviation constant-acceleration-kinematics-matrix \equiv (\chi\ i.\ if\ i=(0::3)\ then\ axis\ (1::3)\ (1::real)\ else\ if\ i=1\ then\ axis\ 2\ 1\ else\ 0)

abbreviation constant-acceleration-kinematics-matrix-flow t\ s\equiv (\chi\ i.\ if\ i=(0::3)\ then\ s\ 2\cdot t\ 2/2+s\ 1\cdot t+s\ 0 else if i=1\ then\ s\ 2\cdot t+s\ 1\ else\ s\ 2)
```

**notation** constant-acceleration-kinematics-matrix (K)

**notation** constant-acceleration-kinematics-matrix-flow  $(\varphi_K)$ 

With these 2 definitions and the proof that linear systems of ODEs are Picard-Lindeloef, we can show that they form a pair of vector-field and its flow.

```
lemma entries-cnst-acc-matrix: entries K = \{0, 1\}
 apply (simp-all add: axis-def, safe)
 by (rule-tac \ x=1 \ in \ exI, \ simp)+
{\bf lemma}\ picard{-}lindeloef{-}cnst{-}acc{-}matrix:
 assumes 0 \le t and t < 1/9
 shows picard-lindeloef (\lambda \ t \ s. \ K * v \ s) \{0..t\} \ ((real \ CARD(3))^2 \cdot (\|K\|_{max})) \ \theta
 apply(rule picard-lindeloef-linear-system)
 unfolding entries-cnst-acc-matrix using assms by auto
lemma local-flow-cnst-acc-matrix:
  assumes 0 \le t and t \le 1/9
 shows local-flow ((*v) K) \{0..t\} ((real CARD(3))<sup>2</sup> · (\|K\|_{max})) \varphi_K
 unfolding local-flow-def local-flow-axioms-def apply safe
  using picard-lindeloef-cnst-acc-matrix[OF assms] apply blast
  apply(rule\ has-vderiv-on-vec-lambda)
  using poly-derivatives (1,3,4)
  apply(force\ simp:\ matrix-vector-mult-def)
 using exhaust-3 by(force simp: matrix-vector-mult-def vec-eq-iff)
```

Finally, we compute the wlp of this example and use it to verify the single-evolution ball again.

 ${f lemma}\ wp ext{-}cnst ext{-}acc ext{-}matrix:$ 

```
assumes 0 \le t and t < 1/9 shows wp \ ([x'=(*v) \ K]\{0..t\} \& G) \ [Q] = [\lambda \ s. \ \forall \tau \in \{0..t\}. \ (G \rhd (\lambda r. \ \varphi_K \ r \ s)\{0--\tau\}) \longrightarrow Q \ (\varphi_K \ \tau \ s)] apply(subst local-flow.wp-g-orbit[of (*v) \ K - ((real \ CARD(3))^2 \cdot (\|K\|_{max})) \ \varphi_K]) using local-flow-cnst-acc-matrix and assms by auto

lemma single-evolution-ball-K: assumes 0 \le t and t < 1/9 shows [\lambda s. \ 0 \le s \ s \ 0 \land s \ s \ 0 = H \land s \ s \ 1 = 0 \land 0 > s \ s \ 2] \le wp \ ([x'=(*v) \ K]\{0..t\} \& \ (\lambda s. \ s \ s \ 0 \ge 0)) \ [\lambda s. \ 0 \le s \ s \ 0 \land s \ s \ 0 \le H] apply(subst wp-cnst-acc-matrix) using assms by(auto simp: mult-nonneg-nonpos2)
```

### Circular Motion

The characteristics that distinguish this example are:

- 1. We employ an existing finite type of size 2 to model program variables.
- 2. We define a  $2 \times 2$  matrix (named C) to denote the linear operator that models circular motion.
- 3. We show that the circle equation is a differential invariant for the linear operator.
- 4. We prove the partial correctness specification corresponding to the previous point.
- 5. For completeness, we define a local flow  $(\varphi_C)$  and use it to compute the wlp for the linear operator and the specification is proven again with this flow.

```
lemma two\text{-}eq\text{-}zero: (2::2) = 0
by simp
lemma [simp]: i \neq (0::2) \longrightarrow i = 1
using exhaust\text{-}2 by fastforce
lemma UNIV\text{-}2:(UNIV::2\ set) = \{0,\ 1\}
apply safe using exhaust\text{-}2\ two\text{-}eq\text{-}zero by auto
abbreviation circular\text{-}motion\text{-}matrix \equiv
(\chi\ i.\ if\ i=(0::2)\ then\ axis\ (1::2)\ (-1::real)\ else\ axis\ 0\ 1)
notation circular\text{-}motion\text{-}matrix\ (C)
lemma circle\text{-}invariant:
assumes 0 < R
```

```
shows (\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2) is-diff-invariant-of (*v) C along \{\theta...t\}
 apply(rule-tac ode-invariant-rules, clarsimp)
 apply(frule-tac i=0 in has-vderiv-on-vec-nth, drule-tac i=1 in has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def, clarsimp)
 apply(erule-tac x=r in ballE)+
   apply(simp add: matrix-vector-mult-def has-vderiv-on-vec-lambda)
 subgoal for x \tau rapply (rule-tac f'1=\lambda t. 0 and g'1=\lambda t. 0 in derivative-eq-intros(11),
    apply(rule-tac f'1=\lambda t. -2 \cdot (x r \$ \theta) \cdot (t \cdot x r \$ 1)
       and q'1 = \lambda t. 2 · (x r \$ 1) · t · x r \$ 0 in derivative-eq-intros(8), simp-all)
       \mathbf{apply}(rule\text{-}tac\ f'1 = \lambda t. - (t \cdot x\ r\ \$\ 1)\ \mathbf{in}\ derivative\text{-}eq\text{-}intros(15))
       apply(rule-tac t = \{0 - \tau\} and s = \{0 ... t\} in has-derivative-within-subset)
        apply(simp, simp add: closed-segment-eq-real-ivl, force)
       apply(rule-tac f'1=\lambda t. (t \cdot x \ r \ \$ \ \theta) in derivative-eq-intros(15))
       apply(rule-tac t = \{0 - \tau\} and s = \{0 ... t\} in has-derivative-within-subset)
   by(simp, simp add: closed-segment-eq-real-ivl, force)
  \mathbf{by}(auto\ simp:\ closed\text{-}segment\text{-}eq\text{-}real\text{-}ivl)
\mathbf{lemma}\ \mathit{circular-motion-invariants}\colon
  assumes (R::real) > 0
 shows [\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le wp ([x'=(*v) C] \{\theta..t\} \& G) [\lambda s. R^2]
= (s \$ \theta)^2 + (s \$ 1)^2
  using assms(1) apply(rule-tac\ C=\lambda s.\ R^2=(s\ \$\ \theta)^2+(s\ \$\ 1)^2 in dCut)
  apply(rule-tac I=\lambda s. R^2=(s \$ \theta)^2+(s \$ 1)^2 in dI)
  using circle-invariant \langle R > 0 \rangle apply(blast, force, force)
  \mathbf{by}(rule\ dWeakening,\ auto)
— Proof of the same specification by providing solutions:
lemma entries-circ-matrix:entries C = \{0, -1, 1\}
  apply (simp-all add: axis-def, safe)
 subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
  subgoal by (rule-tac \ x=0 \ in \ exI, \ simp)+
  \mathbf{by}(rule\text{-}tac\ x=1\ \mathbf{in}\ exI,\ simp)+
{f lemma}\ picard{\it -lindeloef-circ-matrix}:
 assumes 0 \le t and t < 1/4
 shows picard-lindeloef (\lambda t. (*v) C) {0..t} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) 0
 apply(rule picard-lindeloef-linear-system)
  unfolding entries-circ-matrix using assms by auto
abbreviation circular-motion-matrix-flow t s \equiv (\chi i. if i = (0::2) then
s\$0 \cdot cos \ t - s\$1 \cdot sin \ t \ else \ s\$0 \cdot sin \ t + s\$1 \cdot cos \ t)
notation circular-motion-matrix-flow (\varphi_C)
lemma local-flow-circ-mtx:
 assumes \theta \le t and t < 1/4
 shows local-flow ((*v) C) \{0..t\} ((real CARD(2))<sup>2</sup> · (\|C\|_{max})) \varphi_C
```

```
unfolding local-flow-def local-flow-axioms-def apply safe
 using picard-lindeloef-circ-matrix assms apply blast
  apply(rule has-vderiv-on-vec-lambda)
 apply(simp add: matrix-vector-mult-def has-vderiv-on-def has-vector-derivative-def,
safe
 subgoal for s i x
    apply(rule-tac f'1=\lambda t. - s\$0 \cdot (t \cdot \sin x) and g'1=\lambda t. s\$1 \cdot (t \cdot \cos x)in
derivative-eq-intros(11))
     apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule\ derivative-eq-intros(6)[of\ sin\ (\lambda xa.\ (xa\cdot cos\ x))])
     apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
      apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp\ add:\ Groups.mult-ac(3)\ Rings.ring-distribs(4))
 subgoal for s i x
    apply(rule-tac f'1=\lambda t. s\$0 \cdot (t \cdot cos x) and g'1=\lambda t. -s\$1 \cdot (t \cdot sin x)in
derivative-eq-intros(8)
     apply(rule\ derivative-eq-intros(6)[of\ sin\ (\lambda xa.\ xa\cdot cos\ x)])
      apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(55))
       apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
    apply(rule\ derivative-eq-intros(6)[of\ cos\ (\lambda xa.-(xa\cdot sin\ x))])
     apply(rule-tac\ Db1=1\ in\ derivative-eq-intros(58))
      apply(rule\ ssubst[of\ (\cdot)\ 1\ id],\ force,\ simp,\ force,\ force)
   by (simp add: Groups.mult-ac(3) Rings.ring-distribs(4))
 using exhaust-2 two-eq-zero by(force simp: vec-eq-iff)
lemma flow-for-Circ-DS:
 assumes 0 \le t and t \le 1/4
 shows wp ([x'=(*v) \ C] \{0..t\} \& G) [Q] =
   [\lambda \ x. \ \forall \ \tau \in \{0..t\}. \ (\forall \ r \in \{0--\tau\}. \ G \ (\varphi_C \ r \ x)) \longrightarrow Q \ (\varphi_C \ \tau \ x)]
  apply(subst\ local-flow.wp-g-orbit[of\ (*v)\ C-((real\ CARD(2))^2\cdot (||C||_{max}))
|\varphi_C|
 using local-flow-circ-mtx and assms by auto
lemma circular-motion:
 assumes \theta \le t and t < 1/4 and R > \theta
 shows [\lambda s. R^2 = (s \$ \theta)^2 + (s \$ 1)^2] \le wp ([x'=(*v) C] \{\theta..t\} \& G) [\lambda s. R^2]
= (s \$ \theta)^2 + (s \$ 1)^2
 apply(subst flow-for-Circ-DS)
 using assms by simp-all
no-notation circular-motion-matrix (C)
no-notation circular-motion-matrix-flow (\varphi_C)
```

### Bouncing Ball with solution

We revisit the previous dynamics for a constantly accelerated object modelled with the matrix K. We compose the corresponding evolution command with an if-statement, and iterate this hybrid program to model a (completely elastic) "bouncing ball". Using the previously defined flow for this dynamics, proving a specification for this hybrid program is merely an exercise of real arithmetic.

named-theorems bb-real-arith real arithmetic properties for the bouncing ball.

```
lemma [bb-real-arith]: 0 \le x \Longrightarrow 0 > q \Longrightarrow 2 \cdot q \cdot x = 2 \cdot q \cdot H + v \cdot v \Longrightarrow
(x::real) \leq H
proof-
  assume 0 \le x and 0 > g and 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v
 then have v \cdot v = 2 \cdot g \cdot x - 2 \cdot g \cdot H \wedge 0 > g by auto
 hence *:v \cdot v = 2 \cdot g \cdot (x - H) \wedge 0 > g \wedge v \cdot v \geq 0
    using left-diff-distrib mult.commute by (metis zero-le-square)
 from this have (v \cdot v)/(2 \cdot g) = (x - H) by auto
 also from * have (v \cdot v)/(2 \cdot g) \leq \theta
    using divide-nonneq-neg by fastforce
  ultimately have H - x \ge 0 by linarith
  thus ?thesis by auto
qed
lemma [bb-real-arith]:
 assumes invar: 2 \cdot g \cdot x = 2 \cdot g \cdot H + v \cdot v
    and pos: g \cdot \tau^2 / 2 + v \cdot \tau + (x::real) = 0
 shows 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
and 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
proof-
  from pos have g \cdot \tau^2 + 2 \cdot v \cdot \tau + 2 \cdot x = 0 by auto
  then have g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot x = 0
    by (metis (mono-tags, hide-lams) Groups.mult-ac(1,3) mult-zero-right
        monoid-mult-class.power2-eq-square semiring-class.distrib-left)
  hence g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + v^2 + 2 \cdot g \cdot H = 0
    using invar by (simp add: monoid-mult-class.power2-eq-square)
  from this have *:(g \cdot \tau + v)^2 + 2 \cdot g \cdot H = 0
   apply(subst\ power2\text{-}sum)\ by\ (metis\ (no\text{-}types,\ hide-lams)\ Groups.add-ac(2,3)
        Groups.mult-ac(2, 3) \ monoid-mult-class.power2-eq-square \ nat-distrib(2))
 hence 2 \cdot g \cdot H + (-((g \cdot \tau) + v))^2 = 0
    by (metis Groups.add-ac(2) power2-minus)
  thus 2 \cdot g \cdot H + (-(g \cdot \tau) - v) \cdot (-(g \cdot \tau) - v) = 0
    by (simp add: monoid-mult-class.power2-eq-square)
  from * show 2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) = 0
    \mathbf{by}\ (simp\ add\colon monoid\text{-}mult\text{-}class.power2\text{-}eq\text{-}square)
qed
```

```
lemma [bb-real-arith]:
     \mathbf{assumes} \ invar{:} 2 \, \cdot \, g \, \cdot \, x \, = \, 2 \, \cdot \, g \, \cdot \, H \, + \, v \, \cdot \, v
     shows 2 \cdot g \cdot (g \cdot \tau^2 / 2 + v \cdot \tau + (x::real)) =
      2 \cdot g \cdot H + (g \cdot \tau \cdot (g \cdot \tau + v) + v \cdot (g \cdot \tau + v)) (is ?lhs = ?rhs)
proof-
      have ?lhs = q^2 \cdot \tau^2 + 2 \cdot q \cdot v \cdot \tau + 2 \cdot q \cdot x
                  apply(subst\ Rat.sign-simps(18))+
                  \mathbf{by}(\textit{auto simp: semiring-normalization-rules}(\textit{29}))
            also have ... = g^2 \cdot \tau^2 + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v (is ... = ?middle)
                  \mathbf{by}(subst\ invar,\ simp)
            finally have ?lhs = ?middle.
      moreover
       {have ?rhs = g \cdot g \cdot (\tau \cdot \tau) + 2 \cdot g \cdot v \cdot \tau + 2 \cdot g \cdot H + v \cdot v
            by (simp\ add:\ Groups.mult-ac(2,3)\ semiring-class.distrib-left)
      also have \dots = ?middle
           by (simp add: semiring-normalization-rules(29))
      finally have ?rhs = ?middle.}
      ultimately show ?thesis by auto
qed
lemma bouncing-ball:
      assumes \theta \le t and t < 1/9
      shows [\lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = H \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \le wp
      ((([x'=(*v) \ K]\{0..t\} \& (\lambda \ s. \ s \$ \ 0 \ge 0)) \cdot
      (IF (\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE \eta^{\bullet} FI))^{\star})
       [\lambda s. \ 0 \le s \ \$ \ 0 \land s \ \$ \ 0 \le H]
      apply(subst\ star-nd-fun.abs-eq)
      apply(rule wp-starI[of - \lceil \lambda s. \ 0 \le s \$ \ 0 \land 0 > s \$ \ 2 \land
      2 \cdot s \$ 2 \cdot s \$ 0 = 2 \cdot s \$ 2 \cdot H + (s \$ 1 \cdot s \$ 1)]])
           apply(simp, simp only: fbox-mult)
         \mathbf{apply}(\mathit{subst}\ \mathit{p2ndf-ndf2p-wp-sym}[\mathit{of}\ (\mathit{IF}\ (\lambda s.\ s\ \$\ \mathit{0}\ =\ \mathit{0})\ \mathit{THEN}\ ([1\ ::==\ (\lambda s.\ \mathsf{apply}(\mathsf{ndf-ndf2p-wp-sym}[\mathsf{of}\ (\mathsf{ndf}\ \mathsf{od}\ \mathsf{od
 -s \$ 1) ELSE \eta^{\bullet} FI)
         apply(subst\ wp\text{-}cnst\text{-}acc\text{-}matrix)
      using assms apply(simp, simp)
         apply(subst\ ndf2p\text{-}wpD)
      unfolding cond-def apply clarsimp
         apply(transfer, simp add: kcomp-def)
      by(auto simp: bb-real-arith)
```

### Bouncing Ball with invariants

We prove again the bouncing ball but this time with differential invariants.

```
lemma gravity-invariant: (\lambda s. s. s. 2 < 0) is-diff-invariant-of (*v) K along \{0..t\} apply(rule-tac. \vartheta'=\lambda s. \theta. and \nu'=\lambda s. \theta. in ode-invariant-rules(3), clarsimp) apply(drule-tac. i=2 in has-vderiv-on-vec-nth) apply(unfold. has-vderiv-on-def. has-vector-derivative-def) apply(erule-tac. x=r. in. ball. E., simp. add: matrix-vector-mult-def) apply(rule-tac. f. '1=\lambda s. \theta. in. derivative-eq-intros(10)) by (auto. simp: closed-segment-eq-real-ivl. has-derivative-within-subset)
```

```
lemma energy-conservation-invariant:
(\lambda s. \ 2 \cdot s \ \$ \ 2 \cdot s \ \$ \ 0 - 2 \cdot s \ \$ \ 2 \cdot H - s \ \$ \ 1 \cdot s \ \$ \ 1 = 0) is-diff-invariant-of
(*v) K along \{0..t\}
 apply(rule ode-invariant-rules, clarify)
 apply(frule-tac\ i=2\ in\ has-vderiv-on-vec-nth)
 apply(frule-tac\ i=1\ in\ has-vderiv-on-vec-nth)
 apply(drule-tac\ i=0\ in\ has-vderiv-on-vec-nth)
 apply(unfold has-vderiv-on-def has-vector-derivative-def)
 apply(erule-tac \ x=r \ in \ ballE, simp-all \ add: matrix-vector-mult-def)+
    apply(rule-tac f'1 = \lambda t. 2 · x r \$ 2 \cdot (t \cdot x r \$ 1)
      and g'1 = \lambda t. 2 · (t \cdot (x r \$ 1 \cdot x r \$ 2)) in derivative-eq-intros(11))
       apply(rule-tac f'1=\lambda t. 2 · x r $ 2 · (t · x r $ 1) and g'1=\lambda t. 0 in
derivative-eq-intros(11))
   apply(rule-tac f'1 = \lambda t. 0 and g'1 = (\lambda xa. xa \cdot x r \$ 1) in derivative-eq-intros(12))
    apply(rule-tac g'1=\lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset closed-segment-eq-real-ivl)
    apply(rule-tac q'1 = \lambda t. 0 in derivative-eq-intros(7))
   apply(rule-tac g'1 = \lambda t. 0 in derivative-eq-intros(6))
    apply(simp-all add: has-derivative-within-subset)
   apply(rule-tac f'1 = (\lambda xa. xa \cdot x r \$ 2) and g'1 = (\lambda xa. xa \cdot x r \$ 2) in
derivative-eq-intros(12))
  \mathbf{by}(simp-all\ add:\ has-derivative-within-subset)
lemma bouncing-ball-invariants:
  [\lambda s. \ 0 \le s \$ \ 0 \land s \$ \ 0 = H \land s \$ \ 1 = 0 \land 0 > s \$ \ 2] \le
  wp ((([x'=(\lambda s. K *v s)] \{0..t\} \& (\lambda s. s \$ 0 \ge 0)) \cdot
  (IF (\lambda s. s \$ \theta = \theta) THEN ([1 ::== (\lambda s. - s \$ 1)]) ELSE \eta^{\bullet} FI))^{\star})
  [\lambda s. \ 0 < s \$ \ 0 \land s \$ \ 0 < H]
  apply(subst\ star-nd-fun.abs-eq)
  apply(rule-tac I = [\lambda s. \ 0 \le s\$0 \land 0 > s\$2 \land 2 \cdot s\$2 \cdot s\$0 = 2 \cdot s\$2 \cdot H + s\$2 \cdot s\$0
(s\$1 \cdot s\$1) in wp-starI)
   apply(simp, simp only: fbox-mult)
   apply(subst p2ndf-ndf2p-wp-sym[of (IF (<math>\lambda s. s \$ 0 = 0) THEN ([1 ::== (\lambda s.
-s \$ 1)]) ELSE \eta^{\bullet} FI)])
  apply(rule dCut[where C=\lambda s. s \$ 2 < 0])
   apply(rule-tac I=\lambda s. s \$ 2 < 0 \text{ in } dI)
  using gravity-invariant apply(blast, force, force)
  apply(rule-tac C=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot H - s\$1 \cdot s\$1 = 0 in dCut)
   apply(rule-tac I=\lambda s. 2 \cdot s\$2 \cdot s\$0 - 2 \cdot s\$2 \cdot H - s\$1 \cdot s\$1 = 0 in dI)
  using energy-conservation-invariant apply(blast, force, force)
  apply(rule dWeakening, subst p2ndf-ndf2p-wp)
  apply(rule wp-if-then-else)
  \mathbf{by}(auto\ simp:\ bb\-real\-arith\ le\-fun\-def)
```

end

### 5.4 VC\_diffKAD

```
\begin{tabular}{l} \textbf{theory} & \textit{VC-diffKAD-auxiliarities} \\ \textbf{imports} \\ \textit{Main} \\ ../\textit{afpModified/VC-KAD} \\ \textit{Ordinary-Differential-Equations.ODE-Analysis} \\ \end{tabular}
```

begin

### 5.4.1 Stack Theories Preliminaries: VC\_KAD and ODEs

To make our notation less code-like and more mathematical we declare:

```
no-notation Archimedean-Field.ceiling (\lceil - \rceil)
and Archimedean-Field.floor (\lfloor - \rfloor)
and Set.image (')
and Range-Semiring.antirange-semiring-class.ars-r (r)

notation p2r (\lceil - \rceil)
and r2p (\lfloor - \rfloor)
and Set.image (-\lceil - \rceil)
and Product-Type.prod.fst (\pi_1)
and Product-Type.prod.snd (\pi_2)
and List.zip (infixl \otimes 63)
and rel-ad (\Delta^c_1)
```

using has-vector-derivative-def by auto

This and more notation is explained by the following lemmata.

```
lemma shows [P] = \{(s, s) | s. P s\}
               and |R| = (\lambda x. \ x \in r2s \ R)
              and r2s R = \{x \mid x. \exists y. (x,y) \in R\}
              and \pi_1(x,y) = x \wedge \pi_2(x,y) = y
              and \Delta^{c_1} R = \{(x, x) | x. \not\exists y. (x, y) \in R\}
              and wp R Q = \Delta^{c_1} (R ; \Delta^{c_1} Q)
              and [x1,x2,x3,x4] \otimes [y1,y2] = [(x1,y1),(x2,y2)]
              and \{a..b\} = \{x. \ a \le x \land x \le b\}
              and \{a < ... < b\} = \{x. \ a < x \land x < b\}
              and (x \ solves \ ode \ f) \ \{\theta..t\} \ R = ((x \ has \ vderiv \ on \ (\lambda t. \ ft \ (x \ t))) \ \{\theta..t\} \ \land \ x \in \{0, t\} \ \land \ t \in \{0, t\} \ \land \ 
\{\theta..t\} \to R
              and f \in A \to B = (f \in \{f. \ \forall \ x. \ x \in A \longrightarrow (f \ x) \in B\})
               and (x has-vderiv-on x')\{0..t\} =
                       (\forall r \in \{0..t\}. (x \text{ has-vector-derivative } x' r) (at r \text{ within } \{0..t\}))
              and (x has-vector-derivative x'r) (at r within {0..t}) =
                       (x \text{ has-derivative } (\lambda x. \ x *_R x' r)) \ (at \ r \ within \ \{0..t\})
apply(simp-all add: p2r-def r2p-def rel-ad-def rel-antidomain-kleene-algebra.fbox-def
       solves-ode-def has-vderiv-on-def)
apply(blast, fastforce, fastforce)
```

Observe also, the following consequences and facts: **proposition**  $\pi_1(|R|) = r2s R$ **by** (simp add: fst-eq-Domain) **proposition**  $\Delta^{c_1} R = Id - \{(s, s) \mid s. s \in (\pi_1(R))\}$ **by**(simp add: image-def rel-ad-def, fastforce) **proposition**  $P \subseteq Q \Longrightarrow wp R P \subseteq wp R Q$  $by(simp\ add:\ rel-antidomain-kleene-algebra.dka.dom-iso\ rel-antidomain-kleene-algebra.fbox-iso)$ **proposition** boxProgrPred-IsProp: wp  $R \lceil P \rceil \subseteq Id$  $by(simp\ add:\ rel-antidomain-kleene-algebra\ .a-subid'\ rel-antidomain-kleene-algebra\ .addual\ .bbox-def)$ **proposition** rdom-p2r- $contents:(a, b) \in rdom [P] = ((a = b) \land P \ a)$ proofhave  $(a, b) \in rdom [P] = ((a = b) \land (a, a) \in rdom [P])$  using p2r-subid by also have ... =  $((a = b) \land (a, a) \in [P])$  by simpalso have ... =  $((a = b) \land P \ a)$  by  $(simp \ add: p2r-def)$ ultimately show ?thesis by simp qed //.SVh.c/vi.ld//r/ort/c/d.d//rh/e.se//c/orr/y/Vyrra.e/ntt/r/uNe//s/V/o/s/nr/y//. **proposition** rel-ad-rule1:  $(x,x) \notin \Delta^{c_1} [P] \Longrightarrow P x$ **by**(auto simp: rel-ad-def p2r-subid p2r-def) **proposition** rel-ad-rule2:  $(x,x) \in \Delta^{c_1} \lceil P \rceil \Longrightarrow \neg P x$ by (metis ComplD VC-KAD.p2r-neg-hom rel-ad-rule1 empty-iff mem-Collect-eq p2s-neg-hom  $rel-antidomain-kleene-algebra.a-one\ rel-antidomain-kleene-algebra.am1\ relcomp.relcompI)$ **proposition** rel-ad-rule3:  $R \subseteq Id \Longrightarrow (x,x) \notin R \Longrightarrow (x,x) \in \Delta^{c_1} R$ **by**(metis IdI Un-iff d-p2r rel-antidomain-kleene-algebra.addual.ars3 rel-antidomain-kleene-algebra.addual.ars-r-def rpr) **proposition** rel-ad-rule  $4:(x,x)\in R \Longrightarrow (x,x)\notin \Delta^{c_1}R$  $\mathbf{by}(metis\ empty-iff\ rel-antidomain-kleene-algebra.addual.ars1\ relcomp.relcompI)$ **proposition** boxProgrPred-chrctrztn: $(x,x) \in wp \ R \ [P] = (\forall \ y. \ (x,y) \in R \longrightarrow P$ y)by (metis boxProgrPred-IsProp rel-ad-rule1 rel-ad-rule2 rel-ad-rule3 rel-ad-rule4 d-p2r wp-simp wp-trafo) **lemma** (in antidomain-kleene-algebra) fbox-starI: assumes  $d p \leq d i$  and  $d i \leq |x| i$  and  $d i \leq d q$ shows  $d p \leq |x^*| q$ prooffrom  $\langle d | i \leq |x| | i \rangle$  have  $d | i \leq |x| | (d | i)$ using local.fbox-simp by auto

```
hence |1| p \le |x^*| i using \langle d p \le d i \rangle by (metis (no-types))
  local.dual-order.trans local.fbox-one local.fbox-simp local.fbox-star-induct-var)
thus ?thesis using \langle d | i \leq d | q \rangle by (metis (full-types)
  local.fbox-mult local.fbox-one local.fbox-seq-var local.fbox-simp)
qed
proposition cons-eq-zipE:
(x, y) \# tail = xList \otimes yList \Longrightarrow \exists xTail \ yTail. \ x \# xTail = xList \wedge y \# yTail
= yList
by(induction xList, simp-all, induction yList, simp-all)
proposition set-zip-left-rightD:
(x, y) \in set (xList \otimes yList) \Longrightarrow x \in set xList \wedge y \in set yList
apply(rule \ conjI)
apply(rule-tac\ y=y\ and\ ys=yList\ in\ set-zip-leftD,\ simp)
apply(rule-tac \ x=x \ and \ xs=xList \ in \ set-zip-rightD, \ simp)
done
declare zip-map-fst-snd [simp]
```

### 5.4.2 VC\_diffKAD Preliminaries

In dL, the set of possible program variables is split in two, the set of variables V and their primed counterparts V'. To implement this, we use Isabelle's string-type and define a function that primes a given string. We then define the set of primed-strings based on it.

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definition vdiff::string \Rightarrow string (\partial - [55] 70) where
(\partial x) = ''d[''@x@'']''
definition varDiffs :: string set where
varDiffs = \{y. \exists x. y = \partial x\}
proposition vdiff-inj:(\partial x) = (\partial y) \Longrightarrow x = y
\mathbf{by}(simp\ add:\ vdiff\text{-}def)
proposition vdiff-noFixPoints: x \neq (\partial x)
by(simp add: vdiff-def)
lemma varDiffsI: x = (\partial z) \Longrightarrow x \in varDiffs
by(simp add: varDiffs-def vdiff-def)
lemma varDiffsE:
assumes x \in varDiffs
obtains y where x = ''d[''@y@'']''
using assms unfolding varDiffs-def vdiff-def by auto
proposition vdiff-invarDiffs:(\partial x) \in varDiffs
by (simp add: varDiffsI)
```

### (primed) dSolve preliminaries

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This subsubsection is to define a function that takes a system of ODEs
(expressed as a list xfList), a presumed solution uInput = [u_1, \ldots, u_n], a
state s and a time t, and outputs the induced flow sol s[xfList \leftarrow uInput] t.
abbreviation varDiffs-to-zero ::real store \Rightarrow real store (sol) where
sol \ a \equiv (override-on \ a \ (\lambda \ x. \ \theta) \ varDiffs)
proposition varDiffs-to-zero-vdiff[simp]: (sol s) (\partial x) = 0
apply(simp add: override-on-def varDiffs-def)
by auto
proposition varDiffs-to-zero-beginning[simp]: take 2 \ x \neq "d" \Longrightarrow (sol \ s) \ x = s
apply(simp add: varDiffs-def override-on-def vdiff-def)
by fastforce
— Next, for each entry of the input-list, we update the state using said entry.
definition vderiv-of fS = (SOME f'. (f has-vderiv-on f') S)
primrec state-list-upd :: ((real \Rightarrow real \ store \Rightarrow real) \times string \times (real \ store \Rightarrow real) \times string \times (real \ store \Rightarrow real)
real)) list \Rightarrow
real \Rightarrow real \ store \Rightarrow real \ store \ \mathbf{where}
state-list-upd [] t s = s[
state-list-upd (uxf # tail) t s = (state-list-upd tail t s)
      (\pi_1 \ (\pi_2 \ uxf)) := (\pi_1 \ uxf) \ t \ s,
    \partial (\pi_1 (\pi_2 uxf)) := (if t = 0 then (\pi_2 (\pi_2 uxf)) s
else vderiv-of (\lambda r. (\pi_1 uxf) rs) \{0 < .. < (2 *_R t)\} t)
abbreviation state-list-cross-upd ::real store \Rightarrow (string \times (real store \Rightarrow real)) list
(real \Rightarrow real \ store \Rightarrow real) \ list \Rightarrow real \Rightarrow (char \ list \Rightarrow real) \ (-[-\leftarrow-] - [64,64,64])
63) where
s[xfList \leftarrow uInput] \ t \equiv state-list-upd \ (uInput \otimes xfList) \ t \ s
proposition state-list-cross-upd-empty[simp]: (s[[] \leftarrow list] \ t) = s
by(induction list, simp-all)
lemma inductive-state-list-cross-upd-its-vars:
assumes distHyp:distinct\ (map\ \pi_1\ ((y,\ g)\ \#\ xftail))
and varHyp: \forall xf \in set((y, g) \# xftail). \pi_1 xf \notin varDiffs
and indHyp:(u, x, f) \in set \ (utail \otimes xftail) \Longrightarrow (s[xftail \leftarrow utail] \ t) \ x = u \ t \ s
and disjHyp:(u, x, f) = (v, y, g) \lor (u, x, f) \in set (utail \otimes xftail)
shows (s[(y, g) \# xftail \leftarrow v \# utail] t) x = u t s
using disjHyp proof
 assume (u, x, f) = (v, y, g)
 hence (s[(y, g) \# xftail \leftarrow v \# utail] t) x = ((s[xftail \leftarrow utail] t)(x := u t s,
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 $\partial x := if \ t = 0 \ then \ f \ s \ else \ vderiv-of \ (\lambda \ r. \ u \ r \ s) \ \{0 < .. < (2 *_R t)\} \ t)) \ x \ \mathbf{by}$ 

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simp
 also have ... = u \ t \ s by (simp \ add: vdiff-def)
 ultimately show ?thesis by simp
 assume yTailHyp:(u, x, f) \in set (utail \otimes xftail)
 from this and indHyp have 3:(s[xftail \leftarrow utail] t) x = u t s by fastforce
 from yTailHyp and distHyp have 2:y \neq x using set-zip-left-rightD by force
 from yTailHyp and varHyp have 1:x \neq \partial y
 using set-zip-left-rightD vdiff-invarDiffs by fastforce
 from 1 and 2 have (s[(y, g) \# xftail \leftarrow v \# utail] t) x = (s[xftail \leftarrow utail] t) x
by simp
 thus ?thesis using 3 by simp
qed
{\bf theorem}\ state{-list-cross-upd-its-vars}:
assumes distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and its-var: (u,x,f) \in set (uInput \otimes xfList)
shows (s[xfList \leftarrow uInput] \ t) \ x = u \ t \ s
using assms apply(induct xfList uInput arbitrary: x rule: list-induct2', simp,
simp, simp)
by(clarify, rule inductive-state-list-cross-upd-its-vars, simp-all)
lemma override-on-upd:x \in X \Longrightarrow (override-on f g X)(x := z) = (override-on f g X)(x := z)
(g(x := z)) X)
by (rule ext, simp add: override-on-def)
lemma inductive-state-list-cross-upd-its-dvars:
assumes \exists g. (s[xfTail \leftarrow uTail] \theta) = override-on s g varDiffs
and \forall xf \in set (xf \# xfTail). \pi_1 xf \notin varDiffs
and \forall uxf \in set (u \# uTail \otimes xf \# xfTail). \pi_1 uxf 0 s = s (\pi_1 (\pi_2 uxf))
shows \exists g. (s[xf \# xfTail \leftarrow u \# uTail] \theta) = override-on s g varDiffs
proof-
let ?gLHS = (s[(xf \# xfTail) \leftarrow (u \# uTail)] \theta)
have observ:\partial (\pi_1 \ xf) \in varDiffs by (auto simp: varDiffs-def)
from assms(1) obtain g where (s[xfTail \leftarrow uTail] \ \theta) = override-on \ s \ g \ varDiffs
by force
then have ?gLHS = (override-on\ s\ g\ varDiffs)(\pi_1\ xf := u\ 0\ s,\ \partial\ (\pi_1\ xf) := \pi_2
xf s) by simp
also have ... = (override-on\ s\ g\ varDiffs)(\partial\ (\pi_1\ xf):=\pi_2\ xf\ s)
using override-on-def varDiffs-def assms by auto
also have ... = (override-on s (g(\partial (\pi_1 xf) := \pi_2 xf s)) varDiffs)
using observ and override-on-upd by force
ultimately show ?thesis by auto
\mathbf{qed}
theorem state-list-cross-upd-its-dvars:
assumes lengthHyp:length xfList = length uInput
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and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \theta s = s (\pi_1 (\pi_2 uxf))
shows \exists g. (s[xfList \leftarrow uInput] \theta) = (override-on \ s \ g \ varDiffs)
using assms proof(induct xfList uInput rule: list-induct2')
case 1
 have (s[[] \leftarrow []] \ \theta) = override \text{-} on \ s \ varDiffs
 unfolding override-on-def by simp
  thus ?case by metis
next
  case (2 xf xfTail)
 have (s[(xf \# xfTail) \leftarrow []] \ \theta) = override-on \ s \ varDiffs
  \mathbf{unfolding}\ override\text{-}on\text{-}def\ \mathbf{by}\ simp
  thus ?case by metis
next
  case (3 u utail)
 have (s[[\leftarrow utail] \ \theta) = override-on \ s \ varDiffs
  unfolding override-on-def by simp
  thus ?case by force
next
  case (4 xf xfTail u uTail)
  then have \exists g. (s[xfTail \leftarrow uTail] \ \theta) = override-on \ s \ g \ varDiffs \ by \ simp
  thus ?case using inductive-state-list-cross-upd-its-dvars 4.prems by blast
qed
\mathbf{lemma}\ vderiv\text{-}unique\text{-}within\text{-}open\text{-}interval:
assumes (f has-vderiv-on f') \{0 < ... < t\} and t > 0
   and (f \text{ has-vderiv-on } f'') \{ 0 < ... < t \} and tauHyp: \tau \in \{ 0 < ... < t \}
shows f' \tau = f'' \tau
using assms apply(simp add: has-vderiv-on-def has-vector-derivative-def)
using frechet-derivative-unique-within-open-interval by (metis box-real(1) scaleR-one
tauHyp)
lemma has-vderiv-on-cong-open-interval:
assumes gHyp: \forall \tau > 0. f \tau = g \tau and tHyp: t>0
and fHyp:(f has-vderiv-on f') \{0 < .. < t\}
shows (g \text{ has-vderiv-on } f') \{0 < ... < t\}
proof-
from gHyp have \land \tau. \tau \in \{0 < ... < t\} \Longrightarrow f \ \tau = g \ \tau  using tHyp by force
hence eqDs:(f has-vderiv-on f') \{0 < ... < t\} = (g has-vderiv-on f') \{0 < ... < t\}
apply(rule-tac has-vderiv-on-cong) by auto
thus (g \text{ has-vderiv-on } f') \{0 < ... < t\} \text{ using } eqDs fHyp \text{ by } simp
qed
lemma closed-vderiv-on-cong-to-open-vderiv:
assumes gHyp: \forall \tau > 0. f \tau = g \tau
and fHyp: \forall t \geq 0. (f has-vderiv-on f') \{0..t\}
and tHyp: t>0 and cHyp: c>1
shows vderiv-of g \{ 0 < ... < (c *_R t) \} t = f' t
proof-
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have ctHyp:c \cdot t > 0 using tHyp and cHyp by auto
from fHyp have (f has-vderiv-on f') \{0 < ... < c \cdot t\} using has-vderiv-on-subset
by (metis\ greaterThanLessThan-subseteq-atLeastAtMost-iff\ less-eq-real-def)
then have derivHyp:(g\ has-vderiv-on\ f')\ \{0<...< c\cdot t\}
using qHyp ctHyp and has-vderiv-on-conq-open-interval by blast
hence f'Hyp: \forall f''. (q \text{ has-vderiv-on } f'') \{0 < ... < c \cdot t\} \longrightarrow (\forall \tau \in \{0 < ... < c \cdot t\}.
f' \tau = f'' \tau
\mathbf{using}\ \mathit{vderiv-unique-within-open-interval}\ \mathit{ctHyp}\ \mathbf{by}\ \mathit{blast}
also have (g \text{ has-vderiv-on } (v \text{deriv-of } g \{0 < .. < (c *_R t)\})) \{0 < .. < c \cdot t\}
by(simp add: vderiv-of-def, metis derivHyp someI-ex)
ultimately show vderiv-of g {0 < ... < c *_R t} t = f' t using tHyp cHyp by force
qed
lemma vderiv-of-to-sol-its-vars:
assumes distinctHyp:distinct\ (map\ \pi_1\ xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp2: \forall t \geq 0. ((\lambda \tau. (sol s[xfList \leftarrow uInput] \tau) x)
has-vderiv-on (\lambda \tau. f (sol s[xfList \leftarrow uInput] \tau))) \{0..t\}
and tHyp: t>0 and uxfHyp:(u, x, f) \in set (uInput \otimes xfList)
shows vderiv-of (\lambda \tau. \ u \ \tau \ (sol \ s)) \ \{0 < .. < (2 *_R t)\} \ t = f \ (sol \ s[xfList \leftarrow uInput]
t)
apply(rule-tac\ f = (\lambda \tau.\ (sol\ s[xfList \leftarrow uInput]\ \tau)\ x) in closed\text{-}vderiv\text{-}on\text{-}cong\text{-}to\text{-}open\text{-}vderiv})
subgoal using assms and state-list-cross-upd-its-vars by metis
by(simp-all add: solHyp2 tHyp)
lemma inductive-to-sol-zero-its-dvars:
assumes eqFuncs: \forall s. \forall g. \forall xf \in set((x, f) \# xfs). \pi_2 xf(override-on s g varDiffs)
=\pi_2 xf s
and eqLengths:length ((x, f) \# xfs) = length (u \# us)
and distinct: distinct (map \pi_1 ((x, f) # xfs))
and vars: \forall xf \in set ((x, f) \# xfs). \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set ((u \# us) \otimes ((x, f) \# xfs)). \pi_1 uxf \theta (sol s) = sol s (\pi_1)
(\pi_2 \ uxf)
and disjHyp:(y, g) = (x, f) \lor (y, g) \in set xfs
and indHyp:(y, g) \in set \ xfs \Longrightarrow (sol \ s[xfs \leftarrow us] \ \theta) \ (\partial \ y) = g \ (sol \ s[xfs \leftarrow us] \ \theta)
shows (sol\ s[(x, f) \# xfs \leftarrow u \# us]\ \theta)\ (\partial\ y) = q\ (sol\ s[(x, f) \# xfs \leftarrow u \# us]\ \theta)
from assms obtain h1 where h1Def:(sol s[((x, f) # xfs)\leftarrow(u # us)] 0) =
(override-on (sol s) h1 varDiffs) using state-list-cross-upd-its-dvars by blast
from disjHyp show (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us]\ 0)\ (\partial\ y)=g\ (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us])
xfs \leftarrow u \# us ] 0)
proof
  assume eqHeads:(y, g) = (x, f)
  then have g (sol \ s[(x, f) \# xfs \leftarrow u \# us] \ \theta) = f (sol \ s) using h1Def eqFuncs
  also have ... = (sol\ s[(x, f) \# xfs \leftarrow u \# us]\ \theta)\ (\partial\ y) using eqHeads by auto
  ultimately show ?thesis by linarith
next
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assume tailHyp:(y, g) \in set xfs
    then have y \neq x using distinct set-zip-left-right by force
    hence \partial x \neq \partial y by (simp add: vdiff-def)
    have x \neq \partial y using vars vdiff-invarDiffs by auto
   obtain h2 where h2Def:(sol\ s[xfs\leftarrow us]\ \theta) = override-on\ (sol\ s)\ h2\ varDiffs
   using state-list-cross-upd-its-dvars eqLengths distinct vars and solHyp1 by force
   have (sol\ s[(x,\ f)\ \#\ xfs\leftarrow u\ \#\ us]\ \theta)\ (\partial\ y)=q\ (sol\ s[xfs\leftarrow us]\ \theta)
    using tailHyp indHyp \langle x \neq \partial y \rangle and \langle \partial x \neq \partial y \rangle by simp
    also have ... = g (override-on (sol s) h2 varDiffs) using h2Def by simp
    also have ... = q (sol s) using eqFuncs and tailHyp by force
   also have ... = g (sol s[(x, f) \# xfs \leftarrow u \# us] \theta)
    using eqFuncs h1Def tailHyp and eq-snd-iff by fastforce
    ultimately show ?thesis by simp
   qed
qed
lemma to-sol-zero-its-dvars:
assumes funcsHyp:\forall s. \forall g. \forall xf \in set xfList. \pi_2 xf (override-on s g varDiffs)
=\pi_2 xf s
and distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ \theta (sol s) = (sol s) (\pi_1 (\pi_2 \cup sol s)) (\pi_2 (\pi_
uxf))
and ygHyp:(y, g) \in set xfList
shows (sol\ s[xfList \leftarrow uInput]\ \theta)(\partial\ y) = g\ (sol\ s[xfList \leftarrow uInput]\ \theta)
using assms apply(induct xfList uInput rule: list-induct2', simp, simp, simp, clar-
ify
by(rule inductive-to-sol-zero-its-dvars, simp-all)
\mathbf{lemma}\ inductive-to-sol-greater-than\text{-}zero\text{-}its\text{-}dvars:
assumes lengthHyp:length((y, g) \# xfs) = length(v \# vs)
and distHyp:distinct (map \pi_1 ((y, g) \# xfs))
and varHyp: \forall xf \in set ((y, g) \# xfs). \pi_1 xf \notin varDiffs
and indHyp:(u,x,f) \in set\ (vs \otimes xfs) \Longrightarrow (s[xfs \leftarrow vs]t)(\partial\ x) = vderiv - of\ (\lambda r.\ u\ r)
s) \{0 < ... < 2 *_R t\} t
and \textit{disjHyp}:(v,\ y,\ g)=(u,\ x,\ f)\ \lor\ (u,\ x,\ f)\in\textit{set}\ (\textit{vs}\ \otimes\textit{xfs}) and \textit{tHyp}:t>0
shows (s[(y, g) \# xfs \leftarrow v \# vs] t) (\partial x) = vderiv-of (\lambda r. u r s) \{0 < ... < 2 *_R t\} t
proof-
let ?lhs = ((s[xfs \leftarrow vs] \ t)(y := v \ t \ s, \partial \ y := vderiv - of \ (\lambda \ r. \ v \ r \ s) \ \{\theta < ... < (2 \cdot t)\}
t)) (\partial x)
let ?rhs = vderiv-of (\lambda r. u r s) \{0 < .. < (2 \cdot t)\} t
have (s[(y, g) \# xfs \leftarrow v \# vs] t) (\partial x) = ?lhs using tHyp by simp
also have vderiv-of (\lambda r. u r s) \{0 < ... < 2 *_R t\} t = ?rhs by simp
ultimately have obs:?thesis = (?lhs = ?rhs) by simp
from disjHyp have ?lhs = ?rhs
proof
    assume uxfEq:(v, y, q) = (u, x, f)
    then have ?lhs = vderiv - of (\lambda r. u r s) \{0 < .. < (2 \cdot t)\} t by simp
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also have vderiv-of (\lambda r. urs) \{0 < ... < (2 \cdot t)\} t = ?rhs using uxfEq by simp
  ultimately show ?lhs = ?rhs by simp
next
  assume sygTail:(u, x, f) \in set (vs \otimes xfs)
  from this have y \neq x using distHyp set-zip-left-rightD by force
  hence \partial x \neq \partial y by (simp add: vdiff-def)
  have y \neq \partial x using varHyp using vdiff-invarDiffs by auto
 then have ?lhs = (s[xfs \leftarrow vs] \ t) \ (\partial \ x) \ using \ \langle y \neq \partial \ x \rangle \ and \ \langle \partial \ x \neq \partial \ y \rangle \ by \ simp
  also have (s[xfs \leftarrow vs] \ t) \ (\partial \ x) = ?rhs using indHyp \ sygTail by simp
  ultimately show ?lhs = ?rhs by simp
qed
from this and obs show ?thesis by simp
qed
\mathbf{lemma}\ to\text{-}sol\text{-}greater\text{-}than\text{-}zero\text{-}its\text{-}dvars\text{:}
assumes distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and uxfHyp:(u, x, f) \in set (uInput \otimes xfList) and tHyp:t > 0
shows (s[xfList \leftarrow uInput] \ t) \ (\partial \ x) = vderiv-of \ (\lambda \ r. \ u \ r. s) \ \{0 < .. < (2 *_R t)\} \ t
using assms apply(induct xfList uInput rule: list-induct2', simp, simp, simp, clar-
ify
\mathbf{by}(rule\text{-}tac\ f=f\ \mathbf{in}\ inductive\text{-}to\text{-}sol\text{-}greater\text{-}than\text{-}zero\text{-}its\text{-}dvars,\ auto)
dInv preliminaries
Here, we introduce syntactic notation to talk about differential invariants.
no-notation Antidomain-Semiring.antidomain-left-monoid-class.am-add-op (infixl
\oplus 65)
no-notation Dioid.times-class.opp-mult (infixl \odot 70)
no-notation Lattices.inf-class.inf (infixl \sqcap 70)
no-notation Lattices.sup-class.sup (infixl \sqcup 65)
datatype trms = Const \ real \ (t_C - [54] \ 70) \ | \ Var \ string \ (t_V - [54] \ 70) \ |
                  Mns \ trms \ (\ominus - [54] \ 65) \mid Sum \ trms \ trms \ (\mathbf{infixl} \oplus 65) \mid
                  Mult trms trms (infixl ⊙ 68)
primrec tval :: trms \Rightarrow (real \ store \Rightarrow real) \ ((1 \llbracket - \rrbracket_t)) \ \mathbf{where}
[t_C \ r]_t = (\lambda \ s. \ r)
[t_V \ x]_t = (\lambda \ s. \ s \ x)
\llbracket \ominus \vartheta \rrbracket_t = (\lambda \ s. - (\llbracket \vartheta \rrbracket_t) \ s) |
\llbracket \vartheta \oplus \eta \rrbracket_t = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s + (\llbracket \eta \rrbracket_t) \ s)|
\llbracket \vartheta \odot \eta \rrbracket_t = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s \cdot (\llbracket \eta \rrbracket_t) \ s)
datatype props = Eq \ trms \ trms \ (infixr \doteq 60) \mid Less \ trms \ trms \ (infixr \prec 62) \mid
                    Leq trms trms (infixr \leq 61) | And props props (infixl \sqcap 63) |
                    Or props props (infixl \sqcup 64)
primrec pval :: props \Rightarrow (real \ store \Rightarrow bool) \ ((1 \llbracket - \rrbracket_P)) \ \mathbf{where}
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\llbracket \vartheta \doteq \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s = (\llbracket \eta \rrbracket_t) \ s) |
\llbracket \vartheta \prec \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s < (\llbracket \eta \rrbracket_t) \ s) |
\llbracket \vartheta \preceq \eta \rrbracket_P = (\lambda \ s. \ (\llbracket \vartheta \rrbracket_t) \ s \le (\llbracket \eta \rrbracket_t) \ s)|
\llbracket \varphi \sqcap \psi \rrbracket_P = (\lambda \ s. \ (\llbracket \varphi \rrbracket_P) \ s \wedge (\llbracket \psi \rrbracket_P) \ s) |
\llbracket \varphi \sqcup \psi \rrbracket_P = (\lambda \ s. \ (\llbracket \varphi \rrbracket_P) \ s \lor (\llbracket \psi \rrbracket_P) \ s)
primrec tdiff :: trms \Rightarrow trms (\partial_t - [54] 70) where
(\partial_t t_C r) = t_C \theta
(\partial_t t_V x) = t_V (\partial x)
(\partial_t \ominus \vartheta) = \ominus (\partial_t \vartheta)
(\partial_t \ (\vartheta \oplus \eta)) = (\partial_t \ \vartheta) \oplus (\partial_t \ \eta)
(\partial_t (\vartheta \odot \eta)) = ((\partial_t \vartheta) \odot \eta) \oplus (\vartheta \odot (\partial_t \eta))
primrec pdiff :: props \Rightarrow props (\partial_P - [54] 70) where
(\partial_P (\vartheta \doteq \eta)) = ((\partial_t \vartheta) \doteq (\partial_t \eta))
(\partial_P (\vartheta \prec \eta)) = ((\partial_t \vartheta) \preceq (\partial_t \eta))|
(\partial_P (\vartheta \leq \eta)) = ((\partial_t \vartheta) \leq (\partial_t \eta))
(\partial_P (\varphi \sqcap \psi)) = (\partial_P \varphi) \sqcap (\partial_P \psi)
(\partial_P (\varphi \sqcup \psi)) = (\partial_P \varphi) \sqcap (\partial_P \psi)
primrec trm Vars :: trms \Rightarrow string set where
trmVars\ (t_C\ r) = \{\}|
trmVars\ (t_V\ x) = \{x\}
\mathit{trm}\,\mathit{Vars}\ (\ominus\ \vartheta) = \mathit{trm}\,\mathit{Vars}\ \vartheta|
trm Vars (\vartheta \oplus \eta) = trm Vars \vartheta \cup trm Vars \eta
trm Vars (\vartheta \odot \eta) = trm Vars \vartheta \cup trm Vars \eta
fun substList :: (string \times trms) \ list \Rightarrow trms \Rightarrow trms \ (-\langle - \rangle \ [54] \ 80) where
xtList\langle t_C | r \rangle = t_C | r |
[\langle t_V | x \rangle = t_V | x |
((y,\xi) \# xtTail)\langle Var x \rangle = (if x = y then \xi else xtTail\langle Var x \rangle)|
xtList\langle \ominus \vartheta \rangle = \ominus (xtList\langle \vartheta \rangle)
xtList\langle\vartheta\oplus\eta\rangle = (xtList\langle\vartheta\rangle) \oplus (xtList\langle\eta\rangle)
xtList\langle\vartheta\odot\eta\rangle = (xtList\langle\vartheta\rangle)\odot(xtList\langle\eta\rangle)
\textbf{proposition} \ \textit{substList-on-compl-of-varDiffs}:
assumes trmVars \eta \subseteq (UNIV - varDiffs)
and set (map \ \pi_1 \ xtList) \subseteq varDiffs
shows xtList\langle \eta \rangle = \eta
using assms apply(induction \eta, simp-all add: varDiffs-def)
\mathbf{by}(induction\ xtList,\ auto)
lemma substList-help1:set (map <math>\pi_1 ((map (vdiff \circ \pi_1) xfList) \otimes uInput)) \subseteq
apply(induct xfList uInput rule: list-induct2', simp-all add: varDiffs-def)
by auto
lemma substList-help2:
assumes trmVars \eta \subseteq (UNIV - varDiffs)
```

```
shows ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput)\langle \eta \rangle = \eta
using assms substList-help1 substList-on-compl-of-varDiffs by blast
\mathbf{lemma}\ substList\text{-}cross\text{-}vdiff\text{-}on\text{-}non\text{-}ocurring\text{-}var:}
assumes x \notin set\ list1
shows ((map\ vdiff\ list1)\otimes list2)\langle t_V\ (\partial\ x)\rangle = t_V\ (\partial\ x)
using assms apply(induct list1 list2 rule: list-induct2', simp, simp, clarsimp)
\mathbf{by}(simp\ add:\ vdiff\text{-}def)
primrec prop Vars :: props \Rightarrow string set where
prop Vars \ (\vartheta \doteq \eta) = trm Vars \ \vartheta \cup trm Vars \ \eta
prop Vars (\vartheta \prec \eta) = trm Vars \vartheta \cup trm Vars \eta
prop Vars (\vartheta \leq \eta) = trm Vars \vartheta \cup trm Vars \eta
prop Vars \ (\varphi \sqcap \psi) = prop Vars \ \varphi \cup prop Vars \ \psi
prop Vars \ (\varphi \sqcup \psi) = prop Vars \ \varphi \cup prop Vars \ \psi
primrec subspList :: (string \times trms) \ list \Rightarrow props \Rightarrow props (-[-] [54] \ 80) where
xtList \upharpoonright \vartheta \doteq \eta \upharpoonright = ((xtList \langle \vartheta \rangle) \doteq (xtList \langle \eta \rangle))
xtList \upharpoonright \vartheta \prec \eta \upharpoonright = ((xtList \langle \vartheta \rangle) \prec (xtList \langle \eta \rangle))|
xtList \upharpoonright \vartheta \leq \eta \upharpoonright = ((xtList \langle \vartheta \rangle) \leq (xtList \langle \eta \rangle))
xtList \upharpoonright \varphi \sqcap \psi \upharpoonright = ((xtList \upharpoonright \varphi \upharpoonright) \sqcap (xtList \upharpoonright \psi \urcorner))
xtList \upharpoonright \varphi \sqcup \psi \upharpoonright = ((xtList \upharpoonright \varphi \upharpoonright) \sqcup (xtList \upharpoonright \psi \upharpoonright))
```

### **ODE Extras**

For exemplification purposes, we compile some concrete derivatives used commonly in classical mechanics. A more general approach should be taken that generates this theorems as instantiations.

named-theorems ubc-definitions definitions used in the locale unique-on-bounded-closed

```
declare unique-on-bounded-closed-def [ubc-definitions]
and unique-on-bounded-closed-axioms-def [ubc-definitions]
and unique-on-closed-def [ubc-definitions]
and compact-interval-def [ubc-definitions]
and compact-interval-axioms-def [ubc-definitions]
and self-mapping-def [ubc-definitions]
and self-mapping-axioms-def [ubc-definitions]
and continuous-rhs-def [ubc-definitions]
and closed-domain-def [ubc-definitions]
and global-lipschitz-def [ubc-definitions]
and interval-def [ubc-definitions]
and nonempty-set-def [ubc-definitions]
and lipschitz-on-def [ubc-definitions]
```

 ${\bf named-theorems}\ poly-deriv\ temporal\ compilation\ of\ derivatives\ representing\ galilean\ transformations$ 

 ${\bf named-theorems} \ galilean-transform \ temporal \ compilation \ of \ vderivs \ representing \ galilean \ transformations$ 

 ${f named-theorems}\ galilean-transform-eq\ the\ equational\ version\ of\ galilean-transform$ 

```
lemma vector-derivative-line-at-origin: ((\cdot) a has-vector-derivative a) (at x within
by (auto intro: derivative-eq-intros)
lemma [poly-deriv]:((·) a has-derivative (\lambda x. x *_{B} a)) (at x within T)
using vector-derivative-line-at-origin unfolding has-vector-derivative-def by simp
lemma quadratic-monomial-derivative:
((\lambda t :: real. \ a \cdot t^2) \ has-derivative \ (\lambda t. \ a \cdot (2 \cdot x \cdot t))) \ (at \ x \ within \ T)
apply(rule-tac g'1=\lambda t. 2 \cdot x \cdot t in derivative-eq-intros(6))
apply(rule-tac f'1=\lambda t. t in derivative-eq-intros(15))
by (auto intro: derivative-eq-intros)
\mathbf{lemma}\ \mathit{quadratic}\text{-}\mathit{monomial}\text{-}\mathit{derivative} 2\colon
((\lambda t::real.\ a\cdot t^2\ /\ 2)\ has-derivative\ (\lambda t.\ a\cdot x\cdot t))\ (at\ x\ within\ T)
apply(rule-tac f'1=\lambda t. a \cdot (2 \cdot x \cdot t) and g'1=\lambda x. 0 in derivative-eq-intros(18))
using quadratic-monomial-derivative by auto
lemma quadratic-monomial-vderiv[poly-deriv]:((\lambda t.\ a\cdot t^2\ /\ 2) has-vderiv-on (\cdot)
a) T
apply(simp add: has-vderiv-on-def has-vector-derivative-def, clarify)
using quadratic-monomial-derivative2 by (simp add: mult-commute-abs)
lemma galilean-position[galilean-transform]:
((\lambda t. \ a \cdot t^2 \ / \ 2 + v \cdot t + x) \ has-vderiv-on \ (\lambda t. \ a \cdot t + v)) \ T
apply(rule-tac f'=\lambda x. \ a \cdot x + v and g'1=\lambda x. \ \theta in derivative-intros(191))
apply(rule-tac f'1=\lambda x. a \cdot x and g'1=\lambda x. v in derivative-intros(191))
using poly-deriv(2) by (auto intro: derivative-intros)
lemma [poly-deriv]:
t \in T \Longrightarrow ((\lambda \tau. \ a \cdot \tau^2 \ / \ 2 + v \cdot \tau + x) \ has-derivative \ (\lambda x. \ x *_R (a \cdot t + v)))
(at\ t\ within\ T)
using galilean-position unfolding has-vderiv-on-def has-vector-derivative-def by
simp
lemma [galilean-transform-eq]:
t > 0 \implies vderiv-of(\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\} \ t = a \cdot t + v
proof-
let ?f = vderiv-of(\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \{0 < .. < 2 \cdot t\}
assume t > \theta hence t \in \{\theta < ... < \theta \cdot t\} by auto
have \exists f. ((\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \ has-vderiv-on f) \{0 < ... < 2 \cdot t\}
using galilean-position by blast
hence ((\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \ has-vderiv-on ?f) \{0 < ... < 2 \cdot t\}
unfolding vderiv-of-def by (metis (mono-tags, lifting) someI-ex)
using galilean-position by simp
ultimately show (vderiv-of (\lambda t.\ a\cdot t^2 / 2 + v\cdot t + x) {0 < ... < 2 \cdot t}) t = a\cdot t
```

```
apply(rule-tac f'=?f and \tau=t and t=2 \cdot t in vderiv-unique-within-open-interval)
using \langle t \in \{0 < ... < 2 \cdot t\} \rangle by auto
qed
lemma t > 0 \Longrightarrow vderiv of (\lambda t. \ a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\} \ t = a \cdot t
unfolding vderiv-of-def apply (subst\ some 1-equality [of - (\lambda t.\ a \cdot t + v)])
apply(rule-tac a=\lambda t. \ a \cdot t + v \ in \ ex1I)
apply(simp-all add: galilean-position)
apply(rule\ ext,\ rename-tac\ f\ 	au)
apply(rule-tac f = \lambda t. \ a \cdot t^2 / 2 + v \cdot t + x \ and \ t = 2 \cdot t \ and \ f' = f \ in \ vderiv-unique-within-open-interval)
apply(simp-all add: galilean-position)
oops
lemma galilean-velocity[galilean-transform]:((\lambda r. a \cdot r + v) has-vderiv-on (\lambda t. a))
apply(rule-tac f'1=\lambda x. a and g'1=\lambda x. 0 in derivative-intros(191))
unfolding has-vderiv-on-def by(auto intro: derivative-eq-intros)
lemma [qalilean-transform-eq]:
t > 0 \Longrightarrow vderiv-of(\lambda r. \ a \cdot r + v) \{0 < .. < 2 \cdot t\} \ t = a
proof-
let ?f = vderiv - of(\lambda r. a \cdot r + v) \{0 < ... < 2 \cdot t\}
assume t > \theta hence t \in \{\theta < ... < \theta \cdot t\} by auto
have \exists f. ((\lambda r. \ a \cdot r + v) \ has-vderiv-on f) \{0 < ... < 2 \cdot t\}
using galilean-velocity by blast
hence ((\lambda r. \ a \cdot r + v) \ has-vderiv-on ?f) \{0 < .. < 2 \cdot t\}
unfolding vderiv-of-def by (metis (mono-tags, lifting) someI-ex)
also have ((\lambda r. \ a \cdot r + v) \ has-vderiv-on \ (\lambda t. \ a)) \ \{0 < .. < 2 \cdot t\}
using galilean-velocity by simp
ultimately show (vderiv-of (\lambda r. \ a \cdot r + v) \{0 < ... < 2 \cdot t\}) t = a
apply(rule-tac f' = ?f and \tau = t and t = 2 \cdot t in vderiv-unique-within-open-interval)
using \langle t \in \{0 < ... < 2 \cdot t\} \rangle by auto
qed
lemma [qalilean-transform]:
((\lambda t. \ v \cdot t - a \cdot t^2 / 2 + x) \ has-vderiv-on \ (\lambda x. \ v - a \cdot x)) \ \{0..t\}
apply(subgoal-tac ((\lambda t. - a \cdot t^2 / 2 + v \cdot t +x) has-vderiv-on (\lambda x. - a \cdot x +
v)) \{0..t\}, simp)
\mathbf{by}(rule\ galilean-transform)
lemma [galilean-transform-eq]:t > 0 \implies vderiv-of (\lambda t. \ v \cdot t - a \cdot t^2 / 2 + x)
\{0 < ... < 2 \cdot t\} \ t = v - a \cdot t
apply(subgoal-tac vderiv-of (\lambda t. - a \cdot t^2 / 2 + v \cdot t + x) \{0 < ... < 2 \cdot t\} t = -a
\cdot t + v, simp)
by(rule qalilean-transform-eq)
```

```
lemma [galilean-transform]:
((\lambda t. \ v - a \cdot t) \ has-vderiv-on \ (\lambda x. - a)) \ \{0..t\}
apply(subgoal-tac ((\lambda t. - a \cdot t + v) has-vderiv-on (\lambda x. - a)) {0..t}, simp)
by(rule galilean-transform)
lemma [qalilean-transform-eq]:t > 0 \implies vderiv-of (\lambda r. \ v - a \cdot r) \{0 < ... < 2 \cdot t\}
t = -a
apply(subgoal-tac vderiv-of (\lambda t. - a \cdot t + v) \{0 < ... < 2 \cdot t\} \ t = -a, simp)
\mathbf{by}(rule\ galilean-transform-eq)
lemma [simp]:(\lambda x. \ case \ x \ of \ (t, \ x) \Rightarrow f \ t) = (\lambda \ x. \ (f \circ \pi_1) \ x)
by auto
end
theory VC-diffKAD
imports VC-diffKAD-auxiliarities
begin
            Phase Space Relational Semantics
5.4.3
definition solvesStoreIVP :: (real \Rightarrow real store) \Rightarrow (string \times (real store \Rightarrow real))
list \Rightarrow
real\ store \Rightarrow bool
((- solvesTheStoreIVP - withInitState - ) [70, 70, 70] 68) where
solvesStoreIVP \varphi_S xfList s \equiv
— F sends vdiffs-in-list to derivs.
(\forall t \geq 0. (\forall xf \in set xfList. \varphi_S t (\partial (\pi_1 xf)) = \pi_2 xf (\varphi_S t)) \land
— F preserves the rest of the variables and F sends derive of constants to 0.
(\forall y. (y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S \ t \ y = s \ y) \land 
      (y \notin (\pi_1(set xfList)) \longrightarrow \varphi_S \ t \ (\partial \ y) = \theta)) \land
— F solves the induced IVP.
(\forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf) (\varphi_S t))) \{0..t\}
UNIV \wedge
\varphi_S \ \theta \ (\pi_1 \ xf) = s(\pi_1 \ xf))
lemma solves-store-ivpI:
assumes \forall t \geq 0. \forall xf \in set xfList. (\varphi_S t (\partial (\pi_1 xf))) = (\pi_2 xf) (\varphi_S t)
  and \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S t y = s y
  and \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \longrightarrow \varphi_S t (\partial y) = 0
  and \forall t \geq 0. \ \forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf))
(\varphi_S \ t))) \{\theta..t\} \ UNIV
  and \forall xf \in set xfList. \varphi_S \ \theta \ (\pi_1 xf) = s(\pi_1 xf)
shows \varphi_S solves The Store IVP xfList with InitState s
apply(simp add: solvesStoreIVP-def, safe)
using assms apply simp-all
\mathbf{by}(force, force, force)
```

 ${f named-theorems}$  solves-store-ivpE elimination rules for solvesStoreIVP

```
lemma [solves-store-ivpE]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
shows \forall t \geq 0. \forall y. y \notin (\pi_1(set xfList)) \cup varDiffs \longrightarrow \varphi_S t y = s y
 and \forall t \geq 0. \forall y. y \notin (\pi_1(|set xfList|)) \longrightarrow \varphi_S t (\partial y) = 0
 and \forall t \geq 0. \forall xf \in set xfList. (\varphi_S t (\partial (\pi_1 xf))) = (\pi_2 xf) (\varphi_S t)
 and \forall t \geq 0. \ \forall xf \in set xfList. ((\lambda t. \varphi_S t (\pi_1 xf)) solves-ode (\lambda t.\lambda r.(\pi_2 xf))
(\varphi_S \ t))) \{\theta..t\} \ UNIV
 and \forall xf \in set xfList. \varphi_S \ \theta \ (\pi_1 xf) = s(\pi_1 xf)
using assms solvesStoreIVP-def by auto
lemma [solves-store-ivpE]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
shows \forall y. y \notin varDiffs \longrightarrow \varphi_S \ 0 \ y = s \ y
proof(clarify, rename-tac x)
fix x assume x \notin varDiffs
from assms and solves-store-ivpE(5) have x \in (\pi_1(set xfList)) \Longrightarrow \varphi_S \ 0 \ x = s
x by fastforce
also have x \notin (\pi_1(set xfList)) \cup varDiffs \Longrightarrow \varphi_S \ \theta \ x = s \ x
using assms and solves-store-ivpE(1) by simp
ultimately show \varphi_S \theta x = s x using \langle x \notin varDiffs \rangle by auto
qed
{f named-theorems} solves-store-ivpD computation rules for solvesStoreIVP
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t > \theta
 and y \notin (\pi_1(set xfList)) \cup varDiffs
shows \varphi_S t y = s y
using assms solves-store-ivpE(1) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
 and y \notin (\pi_1(set xfList))
shows \varphi_S t (\partial y) = 0
using assms solves-store-ivpE(2) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
 and xf \in set xfList
shows (\varphi_S \ t \ (\partial \ (\pi_1 \ xf))) = (\pi_2 \ xf) \ (\varphi_S \ t)
using assms solves-store-ivpE(3) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and t \geq \theta
```

```
and xf \in set xfList
shows ((\lambda \ t. \ \varphi_S \ t \ (\pi_1 \ xf)) \ solves-ode \ (\lambda \ t.\lambda \ r.(\pi_2 \ xf) \ (\varphi_S \ t))) \ \{0..t\} \ UNIV
using assms solves-store-ivpE(4) by simp
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and (x,f) \in set xfList
shows \varphi_S \ \theta \ x = s \ x
using assms solves-store-ivpE(5) by fastforce
lemma [solves-store-ivpD]:
assumes \varphi_S solvesTheStoreIVP xfList withInitState s
 and y \notin varDiffs
shows \varphi_S \ \theta \ y = s \ y
using assms solves-store-ivpE(6) by simp
definition quarDiffEqtn :: (string \times (real store \Rightarrow real)) list \Rightarrow (real store pred)
real store rel (ODEsystem - with - [70, 70] 61) where
ODEsystem xfList with G = \{(s, \varphi_S \ t) \mid s \ t \ \varphi_S. \ t \geq 0 \ \land \ (\forall \ r \in \{\theta..t\}. \ G \ (\varphi_S \ r))\}
\land solvesStoreIVP \varphi_S xfList s
```

### 5.4.4 Derivation of Differential Dynamic Logic Rules

### "Differential Weakening"

**lemma** wlp-evol-guard:  $Id \subseteq wp$  (ODEsystem xfList with G)  $\lceil G \rceil$  **by**(simp add: rel-antidomain-kleene-algebra.fbox-def rel-ad-def guarDiffEqtn-def p2r-def, force)

```
theorem dWeakening: assumes guardImpliesPost: \lceil G \rceil \subseteq \lceil Q \rceil shows PRE\ P\ (ODEsystem\ xfList\ with\ G)\ POST\ Q using assms and wlp\text{-}evol\text{-}guard by (metis\ (no\text{-}types,\ hide\text{-}lams)\ d\text{-}p2r order\text{-}trans\ p2r\text{-}subid\ rel\text{-}antidomain\text{-}kleene\text{-}algebra.fbox\text{-}iso})
```

```
theorem dW: wp (ODEsystem xfList with G) \lceil Q \rceil = wp (ODEsystem xfList with G) \lceil \lambda s. G s \longrightarrow Q s \rceil unfolding rel-antidomain-kleene-algebra. fbox-def <math>rel-ad-def guarDiffEqtn-def by(simp add: relcomp.simps p2r-def, fastforce)
```

## "Differential Cut"

```
lemma all-interval-guarDiffEqtn: assumes solvesStoreIVP \varphi_S xfList s \land (\forall r \in \{0..t\}. \ G \ (\varphi_S \ r)) \land 0 \le t shows \forall r \in \{0..t\}. \ (s, \varphi_S \ r) \in (ODEsystem \ xfList \ with \ G) unfolding guarDiffEqtn-def using atLeastAtMost-iff apply clarsimp apply(rule-tac x=r in exI, rule-tac x=\varphi_S in exI) using assms by simp
```

 $\mathbf{lemma}\ cond A fter Evol-remains Along Evol:$ 

```
assumes boxDiffC:(s, s) \in wp \ (ODEsystem \ xfList \ with \ G) \ [C]
and FisSol:solvesStoreIVP \varphi_S xfList s \land (\forall r \in \{0..t\}, G(\varphi_S r)) \land \theta \leq t
shows \forall r \in \{0..t\}. G(\varphi_S r) \land C(\varphi_S r)
proof-
from boxDiffC have \forall c. (s,c) \in (ODEsystem xfList with G) \longrightarrow Cc
 by (simp add: boxProgrPred-chrctrztn)
also from FisSol have \forall r \in \{0..t\}. (s, \varphi_S r) \in (ODEsystem \ xfList \ with \ G)
 using all-interval-guarDiffEqtn by blast
ultimately show ?thesis
 using FisSol atLeastAtMost-iff quarDiffEqtn-def by fastforce
qed
theorem dCut:
assumes pBoxDiffCut:(PRE P (ODEsystem xfList with G) POST C)
assumes pBoxCutQ:(PRE\ P\ (ODEsystem\ xfList\ with\ (\lambda\ s.\ G\ s \land C\ s))\ POST\ Q)
shows PRE P (ODEsystem xfList with G) POST Q
apply(clarify, subgoal-tac\ a = b)\ defer
proof(metis d-p2r rdom-p2r-contents, simp, subst boxProgrPred-chrctrztn, clarify)
fix b y assume (b, b) \in [P] and (b, y) \in ODEsystem xfList with G
then obtain \varphi_S t where *:solvesStoreIVP \varphi_S xfList b \land (\forall r \in \{0..t\}. G (\varphi_S))
r)) \wedge \theta \leq t \wedge \varphi_S t = y
 using guarDiffEqtn-def by auto
hence \forall r \in \{0..t\}. (b, \varphi_S r) \in (ODE system xfList with G)
 using all-interval-guarDiffEqtn by blast
from this and pBoxDiffCut have \forall r \in \{0..t\}. C(\varphi_S r)
 using boxProgrPred-chrctrztn \langle (b, b) \in [P] \rangle by (metis (no-types, lifting) d-p2r
subsetCE)
then have \forall r \in \{0..t\}. (b, \varphi_S r) \in (ODEsystem \ xfList \ with \ (\lambda \ s. \ G \ s \land C \ s))
 using * all-interval-quarDiffEqtn by (metis (mono-tags, lifting))
from this and pBoxCutQ have \forall r \in \{0..t\}. Q (\varphi_S r)
 using boxProgrPred-chrctrztn \langle (b, b) \in [P] \rangle by (metis\ (no-types,\ lifting)\ d-p2r)
subsetCE)
thus Q y using * by auto
qed
theorem dC:
assumes Id \subseteq wp (ODEsystem xfList with G) [C]
shows wp (ODEsystem xfList with G) Q = wp (ODEsystem xfList with (\lambda s.
G s \wedge C s)) [Q]
\operatorname{proof}(rule\text{-}tac\ f = \lambda\ x.\ wp\ x\ [Q]\ \operatorname{in}\ HOL.arg\text{-}cong,\ safe)
 fix a b assume (a, b) \in ODEsystem xfList with G
 then obtain \varphi_S t where *:solvesStoreIVP \varphi_S xfList a \land (\forall r \in \{0..t\}. G (\varphi_S))
r)) \wedge 0 \leq t \wedge \varphi_S t = b
   using guarDiffEqtn-def by auto
 hence 1:\forall r \in \{0..t\}. (a, \varphi_S r) \in ODEsystem xfList with G
   by (meson all-interval-guarDiffEqtn)
 from this have \forall r \in \{0..t\}. C(\varphi_S r) using assms boxProgrPred-chrctrztn
   by (metis IdI boxProgrPred-IsProp subset-antisym)
 thus (a, b) \in ODEsystem xfList with (\lambda s. G s \wedge C s)
```

```
using * guarDiffEqtn-def by blast
next
 fix a b assume (a, b) \in ODEsystem xfList with (\lambda s. G s \land C s)
 then show (a, b) \in ODEsystem xfList with G
 unfolding quarDiffEqtn-def by (clarsimp, rule-tac x=t in exI, rule-tac x=\varphi_S in
exI, simp)
qed
Solve Differential Equation
lemma prelim-dSolve:
assumes solHyp:(\lambda t.\ sol\ s[xfList\leftarrow uInput]\ t)\ solvesTheStoreIVP\ xfList\ withInit-
State \ s
and uniqHyp: \forall X. \ solvesStoreIVP \ X \ xfList \ s \longrightarrow (\forall t \geq 0. \ (sol\ s[xfList \leftarrow uInput])
t) = X t
and diffAssgn: \forall t \geq 0. G(sol\ s[xfList \leftarrow uInput]\ t) \longrightarrow Q(sol\ s[xfList \leftarrow uInput]\ t)
shows \forall c. (s,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow Q \ c
proof(clarify)
fix c assume (s,c) \in (ODEsystem \ xfList \ with \ G)
from this obtain t::real and \varphi_S::real \Rightarrow real store
where FHyp:t\geq 0 \land \varphi_S \ t = c \land solvesStoreIVP \ \varphi_S \ xfList \ s \land (\forall \ r \in \{0..t\}. \ G
(\varphi_S r)
using guarDiffEqtn-def by auto
from this and uniqHyp have (sol\ s[xfList \leftarrow uInput]\ t) = \varphi_S\ t by blast
then have cHyp:c = (sol\ s[xfList \leftarrow uInput]\ t) using FHyp by simp
from this have G (sol s[xfList \leftarrow uInput] t) using FHyp by force
then show Q c using diffAssgn FHyp cHyp by auto
qed
theorem dS:
assumes solHyp: \forall s. solvesStoreIVP (\lambda t. sol s[xfList \leftarrow uInput] t) xfList s
and uniqHyp: \forall s \ X. \ solvesStoreIVP \ X \ xfList \ s \longrightarrow (\forall t \geq 0. \ (sol\ s[xfList \leftarrow uInput])
t) = X t
shows wp (ODEsystem xfList with G) [Q] =
 [\lambda \ s. \ \forall \ t \ge 0. \ (\forall \ r \in \{0..t\}. \ G \ (sol \ s[xfList \leftarrow uInput] \ r)) \longrightarrow Q \ (sol \ s[xfList \leftarrow uInput] 
t)
apply(simp add: p2r-def, rule subset-antisym)
unfolding guarDiffEqtn-def rel-antidomain-kleene-algebra.fbox-def rel-ad-def
using solHyp apply(simp add: relcomp.simps) apply clarify
apply(rule-tac \ x=x \ in \ exI, \ clarsimp)
apply(erule-tac \ x=sol \ x[xfList\leftarrow uInput] \ t \ in \ all E, \ erule \ disjE)
apply(erule-tac \ x=x \ in \ all E, \ erule-tac \ x=t \ in \ all E)
apply(erule\ impE,\ simp,\ erule-tac\ x=\lambda t.\ sol\ x[xfList\leftarrow uInput]\ t\ in\ allE)
apply(simp-all, clarify, rule-tac x=s in exI, simp add: relcomp.simps)
using uniqHyp by fastforce
theorem dSolve:
assumes solHyp: \forall s. \ solvesStoreIVP \ (\lambda t. \ sol \ s[xfList \leftarrow uInput] \ t) \ xfList \ s
```

and  $uniqHyp: \forall s. \forall X. solvesStoreIVP \ X xfList \ s \longrightarrow (\forall t \geq 0.(sol\ s[xfList \leftarrow uInput]))$ 

```
t) = X t
and diffAssgn: \forall s. \ Ps \longrightarrow (\forall t \geq 0. \ G(sols[xfList \leftarrow uInput] \ t) \longrightarrow Q(sols[xfList \leftarrow uInput])
shows PRE P (ODEsystem xfList with G) POST Q
apply(clarsimp, subgoal-tac\ a=b)
apply(clarify, subst boxProgrPred-chrctrztn)
apply(simp-all add: p2r-def)
apply(rule-tac uInput=uInput in prelim-dSolve)
apply(simp add: solHyp, simp add: uniqHyp)
by (metis (no-types, lifting) diffAssgn)
— We proceed to refine the previous rule by finding the necessary restrictions on
varFunList and uInput so that the solution to the store-IVP is guaranteed.
lemma conds4vdiffs-prelim:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map <math>\pi_1 xfList)
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and lengthHyp:length xfList = length uInput
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ \theta (sol s) = (sol s) (\pi_1 (\pi_2 \cup xf)) (\pi_1 \cup xf) (\pi_2 \cup xf) (\pi_2
uxf)
and solHyp2: \forall t \geq 0. ((\lambda \tau. (sol\ s[xfList \leftarrow uInput]\ \tau)\ x)
has-vderiv-on (\lambda \tau. f (sol\ s[xfList \leftarrow uInput]\ \tau))) \{0..t\}
and xfHyp:(x, f) \in set xfList and tHyp:t \geq 0
shows (sol s[xfList\leftarrowuInput] t) (\partial x) = f (sol s[xfList\leftarrowuInput] t)
proof-
from xfHyp obtain u where xfuHyp: (u,x,f) \in set (uInput \otimes xfList)
by (metis in-set-impl-in-set-zip2 lengthHyp)
show (sol\ s[xfList \leftarrow uInput]\ t)\ (\partial\ x) = f\ (sol\ s[xfList \leftarrow uInput]\ t)
    proof(cases t=0)
    case True
        have (sol\ s[xfList \leftarrow uInput]\ \theta)\ (\partial\ x) = f\ (sol\ s[xfList \leftarrow uInput]\ \theta)
        using assms and to-sol-zero-its-dvars by blast
        then show ?thesis using True by blast
    next
        {f case}\ {\it False}
        from this have t > 0 using tHyp by simp
        hence (sol\ s[xfList \leftarrow uInput]\ t)\ (\partial\ x) = vderiv - of\ (\lambda\ r.\ u\ r\ (sol\ s))\ \{0 < .. < (2)\}
        using xfuHyp assms to-sol-greater-than-zero-its-dvars by blast
      also have vderiv-of (\lambda r.\ u\ r\ (sol\ s)) \{0 < ... < (2 *_R t)\}\ t = f\ (sol\ s[xfList \leftarrow uInput]
        using assms xfuHyp \langle t > 0 \rangle and vderiv-of-to-sol-its-vars by blast
        ultimately show ?thesis by simp
    qed
qed
```

lemma conds4vdiffs:

```
assumes funcsHyp:\forall s \ g. \ \forall x f \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map <math>\pi_1 xfList)
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and lengthHyp:length xfList = length uInput
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_1 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_1 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_1 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) \theta (sol s) = (sol s) (\pi_1 (\pi_2 uxf) (\pi_2 uxf)) \theta (sol s) \theta (sol s
uxf)
and solHyp2: \forall t \geq 0. \ \forall \ xf \in set \ xfList. \ ((\lambda \tau. \ (sol \ s[xfList \leftarrow uInput] \ \tau) \ (\pi_1 \ xf))
has-vderiv-on (\lambda \tau. (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput] \ \tau))) \ \{0..t\}
shows \forall t \geq 0. \forall xf \in set xfList. (sol s[xfList \leftarrow uInput] t) (\partial (\pi_1 xf)) = (\pi_2 xf)
(sol\ s[xfList \leftarrow uInput]\ t)
apply(rule allI, rule impI, rule ballI, rule conds4vdiffs-prelim)
using assms by simp-all
lemma conds4Consts:
assumes varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
shows \forall x. x \notin (\pi_1(set xfList)) \longrightarrow (sol s[xfList \leftarrow uInput] t) (\partial x) = 0
using varsHyp apply(induct xfList uInput rule: list-induct2')
apply(simp-all add: override-on-def varDiffs-def vdiff-def)
by clarsimp
lemma conds4InitState:
assumes distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set \ (uInput \otimes xfList). \ (\pi_1 \ uxf) \ 0 \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ (sol \ s) = (sol \ s) = (sol \ s) \ (sol \ s) = 
uxf)
and xfHyp:(x, f) \in set xfList
shows (sol s[xfList\leftarrowuInput] 0) x = s x
proof-
from xfHyp obtain u where uxfHyp:(u, x, f) \in set (uInput \otimes xfList)
by (metis in-set-impl-in-set-zip2 lengthHyp)
from varsHyp have toZeroHyp:(sol\ s)\ x = s\ x using override-on-def\ xfHyp by
auto
from uxfHyp and solHyp1 have u \ 0 \ (sol \ s) = (sol \ s) \ x by fastforce
also have (sol\ s[xfList \leftarrow uInput]\ \theta)\ x = u\ \theta\ (sol\ s)
using state-list-cross-upd-its-vars uxfHyp and assms by blast
ultimately show (sol s[xfList\leftarrowuInput] 0) x = s x using toZeroHyp by simp
qed
lemma conds4RestOfStrings:
assumes x \notin (\pi_1(set xfList)) \cup varDiffs
shows (sol s[xfList\leftarrowuInput] t) x = s x
using assms apply(induct xfList uInput rule: list-induct2')
\mathbf{by}(auto\ simp:\ varDiffs-def)
\mathbf{lemma}\ conds 4 store IVP-on-to Sol:
assumes funcsHyp:\forall s \ q. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ q \ varDiffs) = \pi_2 \ xf
```

```
and distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall uxf \in set (uInput \otimes xfList). (\pi_1 uxf) \ 0 \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \cup sol \ s))
and solHyp2: \forall t > 0. \forall xf \in set xfList.
((\lambda t. (sol s[xfList \leftarrow uInput] t) (\pi_1 xf)) has-vderiv-on (\lambda t. \pi_2 xf (sol s[xfList \leftarrow uInput] t)))
t))) \{0..t\}
shows solvesStoreIVP (\lambda t. (sol s[xfList\leftarrowuInput] t)) xfList s
apply(rule\ solves-store-ivpI)
subgoal using conds4vdiffs assms by blast
subgoal using conds4RestOfStrings by blast
subgoal using conds4Consts varsHyp by blast
subgoal apply(rule allI, rule impI, rule ballI, rule solves-odeI)
   using solHyp2 by simp-all
subgoal using conds4InitState and assms by force
done
theorem dSolve-toSolve:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map \pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall s. \forall uxf \in set \ (uInput \otimes xfList). \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ (\pi_2 \ uxf)) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (\pi_2 \ uxf) \ \theta \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (\pi_1 \ uxf) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s) \ (sol \ s) \ (sol \ s) = (sol \ s)
uxf))
and solHyp2: \forall s. \forall t \geq 0. \forall xf \in set xfList.
((\lambda t. (sol s[xfList \leftarrow uInput] t) (\pi_1 xf)) has-vderiv-on (\lambda t. \pi_2 xf (sol s[xfList \leftarrow uInput] t)))
t))) \{0...t\}
and uniqHyp: \forall s. \forall X. solvesStoreIVP X xfList s \longrightarrow (\forall t \geq 0. (sol s[xfList \leftarrow uInput]
t) = X t
and postCondHyp: \forall s. \ P \ s \longrightarrow (\forall t \geq 0. \ Q \ (sol \ s[xfList \leftarrow uInput] \ t))
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac\ uInput=uInput\ in\ dSolve)
subgoal using assms and conds/storeIVP-on-toSol by simp
subgoal by (simp add: uniqHyp)
using postCondHyp postCondHyp by simp
— As before, we keep refining the rule dSolve. This time we find the necessary
restrictions to attain uniqueness.
lemma conds4UniqSol:
fixes f::real store \Rightarrow real
assumes tHyp:t \geq 0
and contHyp:continuous-on (\{0..t\} \times UNIV) (\lambda(t, (r::real)).f(\varphi_s t))
shows unique-on-bounded-closed \theta {\theta..t} \tau (\lambda t r. f (\varphi_s t)) UNIV (if t = \theta then
1 else 1/(t+1)
apply(simp add: ubc-definitions, rule conjI)
subgoal using contHyp continuous-rhs-def by fastforce
```

 $(\pi_1 xf)$ 

subgoal using assms continuous-rhs-def by fastforce  ${\bf lemma}\ solves\text{-}store\text{-}ivp\text{-}at\text{-}beginning\text{-}overrides\text{:}$ assumes  $solvesStoreIVP \varphi_s xfList a$ shows  $\varphi_s \theta = override - on \ a \ (\varphi_s \ \theta) \ varDiffs$  $apply(rule\ ext,\ subgoal\ tac\ x \notin varDiffs \longrightarrow \varphi_s\ 0\ x=a\ x)$ **subgoal by** (simp add: override-on-def) using assms and solves-store-ivpD(6) by simp  $lemma \ ubcStoreUniqueSol:$ assumes  $tHyp:t \geq 0$ **assumes**  $contHyp: \forall xf \in set xfList. continuous-on ({0..t} \times UNIV)$  $(\lambda(t, (r::real)). (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput]\ t))$ and eqDerivs:  $\forall xf \in set xfList. \ \forall \tau \in \{0..t\}. \ (\pi_2 xf) \ (\varphi_s \tau) = (\pi_2 xf) \ (sol$  $s[xfList \leftarrow uInput] \tau$ and Fsolves:solvesStoreIVP  $\varphi_s$  xfList s and solHyp:solvesStoreIVP ( $\lambda \tau.$  ( $sol s[xfList \leftarrow uInput] \tau$ )) xfList s**shows**  $(sol\ s[xfList \leftarrow uInput]\ t) = \varphi_s\ t$ proof fix x::string show (sol s[xfList $\leftarrow$ uInput] t)  $x = \varphi_s t x$  $\mathbf{proof}(\mathit{cases}\ x \in (\pi_1(\mathit{set}\ \mathit{xfList})) \cup \mathit{varDiffs})$ case False then have  $notInVars:x \notin (\pi_1(set xfList)) \cup varDiffs$  by simpfrom solHyp have (sol s[xfList $\leftarrow$ uInput] t) x = s xusing  $tHyp \ notInVars \ solves-store-ivpD(1)$  by blastalso from Fsolves have  $\varphi_s$  t x = s x using tHyp notInVars solves-store-ivpD(1) by blast ultimately show (sol s[xfList $\leftarrow$ uInput] t)  $x = \varphi_s t x$  by simp next case True then have  $x \in (\pi_1(set xfList)) \lor x \in varDiffs$  by simpfrom this show ?thesis proof assume  $x \in (\pi_1(set xfList))$ from this obtain f where  $xfHyp:(x, f) \in set xfList$  by fastforce then have expand1:  $\forall xf \in set xfList.((\lambda \tau. \varphi_s \tau (\pi_1 xf)) solves-ode)$  $(\lambda \tau \ r. \ (\pi_2 \ xf) \ (\varphi_s \ \tau)))\{\theta..t\} \ UNIV \land \varphi_s \ \theta \ (\pi_1 \ xf) = s \ (\pi_1 \ xf)$ **using** Fsolves tHyp **by** (simp add:solvesStoreIVP-def) **hence** expand2:  $\forall xf \in set xfList. \ \forall \tau \in \{0..t\}. \ ((\lambda r. \varphi_s \ r \ (\pi_1 \ xf)))$ has-vector-derivative ( $\lambda r. (\pi_2 \ xf) (sol \ s[xfList \leftarrow uInput] \ \tau)) \ \tau) (at \ \tau \ within$  $\{\theta..t\}$ **using** eqDerivs **by** (simp add: solves-ode-def has-vderiv-on-def) then have  $\forall xf \in set xfList. ((\lambda \tau. \varphi_s \tau (\pi_1 xf)) solves-ode$  $(\lambda \tau \ r. \ (\pi_2 \ xf) \ (sol \ s[xfList\leftarrow uInput] \ \tau)))\{0..t\} \ UNIV \land \varphi_s \ 0 \ (\pi_1 \ xf) = s$ 

by (simp add: has-vderiv-on-def solves-ode-def expand1 expand2)

then have  $1:((\lambda \tau. \varphi_s \tau x) \text{ solves-ode } (\lambda \tau r. f (\text{sol s}[xfList \leftarrow uInput] \tau))) \{0..t\}$ 

```
UNIV \wedge
      \varphi_s \ \theta \ x = s \ x \ \text{using} \ xfHyp \ \text{by} \ fastforce
     from solHyp and xfHyp have 2:((\lambda \tau. (sol s[xfList \leftarrow uInput] \tau) x) solves-ode
      (\lambda \tau \ r. \ f \ (sol \ s[xfList \leftarrow uInput] \ \tau))) \ \{0..t\} \ UNIV \land (sol \ s[xfList \leftarrow uInput] \ \theta)
x = s x
      using solvesStoreIVP-def tHyp by fastforce
      from tHyp and contHyp have \forall xf \in set xfList. unique-on-bounded-closed 0
\{0..t\}\ (s\ (\pi_1\ xf))
     (\lambda \tau \ r. \ (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ \tau)) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1/(t+1))
      apply(clarify) apply(rule conds4UniqSol) by(auto)
        from this have 3:unique-on-bounded-closed 0 \{0..t\} (s\ x) (\lambda \tau\ r.\ f\ (sol
s[xfList \leftarrow uInput] \tau)
      UNIV (if t = 0 then 1 else 1/(t+1)) using xfHyp by fastforce
      from 1 2 and 3 show (sol s[xfList\leftarrow uInput] t) x = \varphi_s t x
     using unique-on-bounded-closed.unique-solution using real-Icc-closed-segment
tHyp by blast
   next
      assume x \in varDiffs
      then obtain y where xDef: x = \partial y by (auto simp: varDiffs-def)
      show (sol s[xfList\leftarrowuInput] t) x = \varphi_s t x
      \mathbf{proof}(cases\ y \in set\ (map\ \pi_1\ xfList))
      case True
       then obtain f where xfHyp:(y, f) \in set xfList by fastforce
       from tHyp and Fsolves have \varphi_s t x = f(\varphi_s t)
       using solves-store-ivpD(3) xfHyp xDef by force
        \textbf{also have} \ (\textit{sol s}[\textit{xfList} \leftarrow \textit{uInput}] \ t) \ x = f \ (\textit{sol s}[\textit{xfList} \leftarrow \textit{uInput}] \ t)
        using solves-store-ivpD(3) xfHyp xDef solHyp tHyp by force
        ultimately show ?thesis using eqDerivs xfHyp tHyp by auto
      next case False
        then have \varphi_s t x = \theta
        using xDef solves-store-ivpD(2) Fsolves tHyp by simp
        also have (sol\ s[xfList \leftarrow uInput]\ t)\ x = 0
       using False solHyp tHyp solves-store-ivpD(2) xDef by fastforce
        ultimately show ?thesis by simp
      qed
    qed
  qed
qed
theorem dSolveUBC:
assumes contHyp:\forall s. \forall t \geq 0. \forall xf \in set xfList. continuous-on (<math>\{0..t\} \times UNIV)
(\lambda(t, (r::real)). (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput]\ t))
and solHyp: \forall s. solvesStoreIVP (\lambda t. (sol s[xfList \leftarrow uInput] t)) xfList s
and uniqHyp: \forall s. \ \forall \varphi_s. \ \varphi_s \ solvesTheStoreIVP \ xfList \ withInitState \ s \longrightarrow
```

```
(\forall t \geq 0. \ \forall xf \in set \ xfList. \ \forall r \in \{0..t\}. \ (\pi_2 \ xf) \ (\varphi_s \ r) = (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput]
and diffAssgn: \forall s. Ps \longrightarrow (\forall t \geq 0. G(sols[xfList \leftarrow uInput]t) \longrightarrow Q(sols[xfList \leftarrow uInput]t)
t))
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac uInput=uInput in dSolve)
prefer 2 subgoal proof(clarify)
fix s::real store and \varphi_s::real \Rightarrow real store and t::real
\mathbf{assume}\ \mathit{isSol:solvesStoreIVP}\ \varphi_s\ \mathit{xfList}\ s\ \mathbf{and}\ \mathit{sHyp}{:}\theta \leq t
from this and uniqHyp have \forall xf \in set xfList. \forall t \in \{0..t\}.
(\pi_2 \ xf) \ (\varphi_s \ t) = (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput] \ t) by auto
also have \forall xf \in set xfList. continuous-on (\{0..t\} \times UNIV)
(\lambda(t, (r::real)), (\pi_2 \ xf) \ (sol\ s[xfList \leftarrow uInput]\ t)) using contHyp sHyp by blast
ultimately show (sol s[xfList\leftarrow uInput] t) = \varphi_s t
using sHyp isSol ubcStoreUniqueSol solHyp by simp
qed using assms by simp-all
theorem dSolve-toSolveUBC:
assumes funcsHyp:\forall s \ g. \ \forall xf \in set \ xfList. \ \pi_2 \ xf \ (override-on \ s \ g \ varDiffs) = \pi_2 \ xf
and distinctHyp:distinct (map <math>\pi_1 xfList)
and lengthHyp:length xfList = length uInput
and varsHyp: \forall xf \in set xfList. \pi_1 xf \notin varDiffs
and solHyp1: \forall s. \ \forall uxf \in set \ (uInput \otimes xfList). \ \pi_1 \ uxf \ \theta \ (sol \ s) = sol \ s \ (\pi_1 \ (\pi_2 \ uxf))
uxf))
and solHyp2: \forall s. \ \forall t \geq 0. \ \forall xf \in set \ xfList. \ ((\lambda t. \ (sol \ s[xfList \leftarrow uInput] \ t) \ (\pi_1 \ xf))
has-vderiv-on
(\lambda t. \pi_2 \ xf \ (sol \ s[xfList \leftarrow uInput] \ t))) \ \{0..t\}
and contHyp: \forall s. \forall t > 0. \forall xf \in set xfList. continuous-on (\{0..t\} \times UNIV)
(\lambda(t, (r::real)). (\pi_2 xf) (sol s[xfList \leftarrow uInput] t))
and uniqHyp: \forall s. \ \forall \varphi_s. \ \varphi_s \ solvesTheStoreIVP \ xfList \ withInitState \ s \longrightarrow
(\forall \ t \geq 0. \ \forall \ xf \in set \ xfList. \ \forall \ r \in \{0..t\}. \ (\pi_2 \ xf) \ (\varphi_s \ r) = (\pi_2 \ xf) \ (sol \ s[xfList \leftarrow uInput])
r))
and postCondHyp: \forall s. \ P \ s \longrightarrow (\forall \ t \geq 0. \ Q \ (sol \ s[xfList \leftarrow uInput] \ t))
shows PRE P (ODEsystem xfList with G) POST Q
apply(rule-tac uInput=uInput in dSolveUBC)
using contHyp apply simp
apply(rule allI, rule-tac uInput=uInput in conds4storeIVP-on-toSol)
using assms by auto
"Differential Invariant."
{\bf lemma}\ solves Store IVP-could Be Modified:
fixes F::real \Rightarrow real \ store
assumes vars: \forall t \geq 0. \ \forall xf \in set \ xfList. \ ((\lambda t. \ F \ t \ (\pi_1 \ xf)) \ solves-ode \ (\lambda t \ r. \ \pi_2 \ xf \ (F \ t))
t))) \{0..t\} UNIV
and dvars: \forall t \geq 0. \forall xf \in set xfList. (F t (\partial (\pi_1 xf))) = (\pi_2 xf) (F t)
shows \forall t \geq 0. \ \forall r \in \{0..t\}. \ \forall xf \in set xfList.
```

 $((\lambda \ t. \ F \ t \ (\pi_1 \ xf)) \ has-vector-derivative \ F \ r \ (\partial \ (\pi_1 \ xf))) \ (at \ r \ within \ \{0..t\})$ 

```
\mathbf{proof}(clarify, rename\text{-}tac\ t\ r\ x\ f)
fix x f and t r :: real
assume tHyp:0 \le t and xfHyp:(x, f) \in set xfList and rHyp:r \in \{0..t\}
from this and vars have ((\lambda t. \ F \ t \ x) \ solves-ode \ (\lambda t \ r. \ f \ (F \ t))) \ \{\theta..t\} \ UNIV
using tHyp by fastforce
hence *:\forall r \in \{0..t\}. ((\lambda t. F t x) has-vector-derivative (\lambda t. f (F t)) r) (at r within
\{\theta..t\}
by (simp add: solves-ode-def has-vderiv-on-def tHyp)
have \forall t \geq 0. \ \forall r \in \{0..t\}. \ \forall xf \in set \ xfList. \ (Fr(\partial(\pi_1 xf))) = (\pi_2 xf) \ (Fr)
using assms by auto
from this rHyp and xfHyp have (F \ r \ (\partial \ x)) = f \ (F \ r) by force
then show ((\lambda t. \ F \ t \ (\pi_1 \ (x, f))) \ has-vector-derivative \ F \ r \ (\partial \ (\pi_1 \ (x, f)))) \ (at \ r
within \{0..t\})
using * rHyp by auto
qed
\mathbf{lemma} derivationLemma-base Case:
fixes F::real \Rightarrow real \ store
assumes solves:solvesStoreIVP\ F\ xfList\ a
shows \forall x \in (UNIV - varDiffs). \forall t \geq 0. \forall r \in \{0..t\}.
((\lambda \ t. \ F \ t \ x) \ has-vector-derivative \ F \ r \ (\partial \ x)) \ (at \ r \ within \ \{0..t\})
proof
\mathbf{fix} \ x
assume x \in UNIV - varDiffs
then have notVarDiff: \forall z. x \neq \partial z  using varDiffs-def by fastforce
 show \forall t \geq 0. \ \forall r \in \{0..t\}. \ ((\lambda t. \ F \ t \ x) \ has-vector-derivative \ F \ r \ (\partial \ x)) \ (at \ r \ within
\{\theta..t\}
  \mathbf{proof}(cases \ x \in set \ (map \ \pi_1 \ xfList))
    case True
    from this and solves have \forall t \geq 0. \forall r \in \{0..t\}. \forall xf \in set xfList.
    ((\lambda \ t. \ F \ t \ (\pi_1 \ xf)) \ has-vector-derivative \ F \ r \ (\partial \ (\pi_1 \ xf))) \ (at \ r \ within \ \{0..t\})
   apply(rule-tac\ solvesStoreIVP-couldBeModified)\ using\ solves\ solves-store-ivpD
by auto
    from this show ?thesis using True by auto
  next
    case False
    from this notVarDiff and solves have const: \forall t \geq 0. F t x = a x
    using solves-store-ivpD(1) by (simp \ add: varDiffs-def)
     have constD: \forall t \geq 0. \ \forall r \in \{0..t\}. \ ((\lambda r. \ a x) \ has-vector-derivative \ 0) \ (at \ r. \ a x) \ has-vector-derivative \ 0)
within \{0..t\})
    by (auto intro: derivative-eq-intros)
    \{fix t r:: real \}
      assume t \ge \theta and r \in \{\theta..t\}
      hence ((\lambda \ s. \ a \ x) \ has\text{-}vector\text{-}derivative \ \theta) (at r within \{\theta..t\}) by (simp add:
constD)
      moreover have \bigwedge s. \ s \in \{0..t\} \Longrightarrow (\lambda \ r. \ F \ r \ x) \ s = (\lambda \ r. \ a \ x) \ s
      using const by (simp add: \langle 0 \leq t \rangle)
      ultimately have ((\lambda \ s. \ F \ s \ x) \ has-vector-derivative \ \theta) (at r within \{\theta..t\})
      using has-vector-derivative-transform by (metis \langle r \in \{0..t\}\rangle)
```

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```
hence isZero: \forall t \geq 0. \forall r \in \{0..t\}. ((\lambda t. F t x) has-vector-derivative 0)(at r within
\{\theta..t\})by blast
    from False solves and notVarDiff have \forall t \geq 0. F t (\partial x) = 0
    using solves-store-ivpD(2) by simp
    then show ?thesis using isZero by simp
 qed
qed
lemma derivationLemma:
assumes solvesStoreIVP F xfList a
and tHyp:t \geq 0
and termVarsHyp: \forall x \in trmVars \ \eta. \ x \in (UNIV - varDiffs)
shows \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (Fs)) has-vector-derivative \llbracket \partial_t \eta \rrbracket_t (Fr)) (at r within
\{0..t\}
using termVarsHyp proof(induction \eta)
 case (Const r)
  then show ?case by simp
next
  case (Var y)
 then have yHyp:y \in UNIV - varDiffs by auto
 from this tHyp and assms(1) show ?case
  using derivationLemma-baseCase by auto
\mathbf{next}
  case (Mns \ \eta)
 then show ?case
 apply(clarsimp)
  by(rule derivative-intros, simp)
next
 case (Sum \eta 1 \ \eta 2)
  then show ?case
 apply(clarsimp)
 \mathbf{by}(rule\ derivative\text{-}intros,\ simp\text{-}all)
next
  case (Mult \eta 1 \ \eta 2)
  then show ?case
 apply(clarsimp)
 apply(subgoal-tac ((\lambda s. \llbracket \eta 1 \rrbracket_t \ (F \ s) *_R \llbracket \eta 2 \rrbracket_t \ (F \ s)) has-vector-derivative
   [\![\partial_t \ \eta 1]\!]_t \ (F \ r) \cdot [\![\eta 2]\!]_t \ (F \ r) + [\![\eta 1]\!]_t \ (F \ r) \cdot [\![\partial_t \ \eta 2]\!]_t \ (F \ r)) \ (at \ r \ within
\{0..t\}, simp
 apply(rule-tac f'1 = [\![ \partial_t \eta 1 ]\!]_t (Fr) and g'1 = [\![ \partial_t \eta 2 ]\!]_t (Fr) in derivative-eq-intros(25))
 by (simp-all add: has-field-derivative-iff-has-vector-derivative)
qed
lemma diff-subst-prprty-4terms:
assumes solves: \forall xf \in set xfList. F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
and tHyp:(t::real) \ge \theta
and listsHyp:map \pi_2 xfList = map tval uInput
and term Vars Hyp:trm Vars \eta \subset (UNIV - var Diffs)
shows [\![\partial_t \ \eta]\!]_t (F \ t) = [\![(map \ (vdiff \circ \pi_1) \ xfList) \otimes uInput)\langle \partial_t \ \eta \rangle]\!]_t (F \ t)
```

```
using termVarsHyp apply(induction \eta) apply(simp-all \ add: \ substList-help2)
using listsHyp and solves apply(induct xfList uInput rule: list-induct2', simp,
simp, simp)
\mathbf{proof}(\mathit{clarify}, \mathit{rename-tac} \ y \ \mathit{g} \ \mathit{xfTail} \ \vartheta \ \mathit{trmTail} \ x)
fix x y :: string and \vartheta :: trms and q and xfTail :: ((string \times (real store \Rightarrow real)) list)
assume IH: \Lambda x. \ x \notin varDiffs \Longrightarrow map \ \pi_2 \ xfTail = map \ tval \ trmTail \Longrightarrow
\forall xf \in set \ xfTail. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t) \Longrightarrow
F \ t \ (\partial \ x) = \llbracket (map \ (vdiff \circ \pi_1) \ xfTail \otimes trmTail) \langle t_V \ (\partial \ x) \rangle \rrbracket_t \ (F \ t)
and 1:x \notin varDiffs and 2:map \ \pi_2 \ ((y, g) \# xfTail) = map \ tval \ (\vartheta \# trmTail)
and \partial: \forall xf \in set ((y, g) \# xfTail). F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
hence *: \llbracket (map \ (vdiff \circ \pi_1) \ xfTail \otimes trmTail) \langle Var \ (\partial \ x) \rangle \rrbracket_t \ (F \ t) = F \ t \ (\partial \ x)
using tHyp by auto
show F \ t \ (\partial \ x) = \llbracket ((map \ (vdiff \circ \pi_1) \ ((y, g) \ \# \ xfTail)) \otimes (\vartheta \ \# \ trmTail)) \ \langle t_V \ \rangle
(\partial x)\|_t (F t)
  \mathbf{proof}(cases\ x \in set\ (map\ \pi_1\ ((y,\ g)\ \#\ xfTail)))
     case True
    then have x = y \lor (x \neq y \land x \in set (map \pi_1 xfTail)) by auto
    moreover
     {assume x = y
       from this have ((map\ (vdiff\ \circ \pi_1)\ ((y,\ g)\ \#\ xfTail))\otimes (\vartheta\ \#\ trmTail))\langle t_V
(\partial x) = \vartheta  by simp
       also from 3 tHyp have F t (\partial y) = g (F t) by simp
       moreover from 2 have [\![\vartheta]\!]_t (F\ t) = g\ (F\ t) by simp
       ultimately have ?thesis by (simp add: \langle x = y \rangle)
    moreover
     {assume x \neq y \land x \in set (map \ \pi_1 \ xfTail)}
       then have \partial x \neq \partial y using vdiff-inj by auto
       from this have ((map\ (vdiff \circ \pi_1)\ ((y, g) \# xfTail)) \otimes (\vartheta \# trmTail)) \langle t_V \rangle
(\partial x) = \langle (\partial x) \rangle = \langle (\partial x) \rangle
       ((map\ (vdiff\ \circ\ \pi_1)\ xfTail)\ \otimes\ trmTail)\ \langle t_V\ (\partial\ x)\rangle\ \mathbf{by}\ simp
       hence ?thesis using * by simp}
     ultimately show ?thesis by blast
  next
    {f case}\ {\it False}
    then have ((map\ (vdiff\ \circ \pi_1)\ ((y,\ g)\ \#\ xfTail))\otimes (\vartheta\ \#\ trmTail))\ \langle t_V\ (\partial\ x)\rangle
= t_V (\partial x)
   using substList-cross-vdiff-on-non-ocurring-var by(metis(no-types, lifting) List.map.compositionality)
    thus ?thesis by simp
  qed
qed
lemma eqInVars-impl-eqInTrms:
assumes termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
\mathbf{and} \ \mathit{initHyp:} \forall \, x. \ x \not\in \mathit{varDiffs} \, \longrightarrow \, b \, \, x = \, a \, \, x
shows \llbracket \eta \rrbracket_t \ a = \llbracket \eta \rrbracket_t \ b
```

 $\mathbf{lemma}\ non\text{-}empty\text{-}funList\text{-}implies\text{-}non\text{-}empty\text{-}trmList\text{:}$ 

using assms by (induction  $\eta$ , simp-all)

```
\vartheta \in set\ tList)
\mathbf{by}(induction\ tList,\ auto)
lemma dInvForTrms-prelim:
assumes substHyp:
\forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ st = 0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
shows \llbracket \eta \rrbracket_t \ a = 0 \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow \llbracket \eta \rrbracket_t \ c = 0)
\mathbf{proof}(\mathit{clarify})
fix c assume aHyp: \llbracket \eta \rrbracket_t \ a = 0 and cHyp: (a, c) \in ODEsystem xfList with G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F t=c \land solvesStoreIVP F xfList a \land (\forall r \in \{0..t\}. G (F r))
using guarDiffEqtn-def by auto
then have \forall x. x \notin varDiffs \longrightarrow F \ \theta \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t a = [\![\eta]\!]_t (F \ \theta) using term Vars Hyp \ eqIn Vars-impl-eqIn Trms
by blast
hence obs1: [\![\eta]\!]_t (F \theta) = \theta using aHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \eta]\!]_t (F r) (at r within \{0..t\}) using derivationLemma term VarsHyp by blast
have \forall r \in \{0..t\}. \forall xf \in set xfList. F r (\partial (\pi_1 xf)) = \pi_2 xf (F r)
using tcHyp\ solves-store-ivpD(3) by fastforce
hence \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) = [\![(map (vdiff \circ \pi_1) xfList) \otimes uInput) \langle \partial_t \eta \rangle]\!]_t
using tcHyp diff-subst-prprty-4terms termVarsHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0..t\}. [(map\ (vdiff\ \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t
\eta \rangle |_t (F r) = 0
using solves-store-ivpD(2) tcHyp by fastforce
ultimately have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) \text{ has-vector-derivative } 0) (at r within
\{\theta..t\}
using obs2 by auto
from this and tcHyp have \forall s \in \{0..t\}. ((\lambda x. \llbracket \eta \rrbracket_t (F x)) \text{ has-derivative } (\lambda x. x *_R x)
(at s within \{0..t\}) by (metis has-vector-derivative-def)
hence [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = (\lambda x. \ x *_R \theta) (t - \theta)
using mvt-very-simple and tcHyp by fastforce
then show [\![\eta]\!]_t c = 0 using obs1 tcHyp by auto
qed
theorem dInvForTrms:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ st = 0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and eta-f:f = [\![\eta]\!]_t
shows PRE (\lambda s. fs = 0) (ODEsystem xfList with G) POST (\lambda s. fs = 0)
```

```
using eta-f proof(clarsimp)
\mathbf{fix} \ a \ b
assume (a, b) \in [\lambda s. [\![\eta]\!]_t \ s = \theta] and f = [\![\eta]\!]_t
from this have aHyp: a = b \wedge [\![\eta]\!]_t \ a = 0 by (metis\ (full-types)\ d-p2r\ rdom-p2r-contents)
have [\![\eta]\!]_t \ a = \emptyset \longrightarrow (\forall \ c. \ (a,c) \in (ODE system \ xfList \ with \ G) \longrightarrow [\![\eta]\!]_t \ c = \emptyset)
using assms dInvForTrms-prelim by metis
from this and aHyp have \forall c. (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow [\![\eta]\!]_t \ c =
0 by blast
thus (a, b) \in wp \ (ODEsystem \ xfList \ with \ G \ ) \ [\lambda s. \ [\![\eta]\!]_t \ s = 0]
using aHyp by (simp add: boxProgrPred-chrctrztn)
qed
lemma diff-subst-prprty-4props:
assumes solves: \forall xf \in set xfList. F t (\partial (\pi_1 xf)) = \pi_2 xf (F t)
and tHyp:t \geq 0
and listsHyp:map \pi_2 xfList = map tval uInput
and prop VarsHyp:prop Vars \varphi \subseteq (UNIV - varDiffs)
shows [\![\partial_P \varphi]\!]_P (F t) = [\![(map (vdiff \circ \pi_1) xfList) \otimes uInput)\!]\partial_P \varphi [\!]_P (F t)
using prop VarsHyp apply(induction \varphi, simp-all)
using assms diff-subst-prprty-4terms apply fastforce
using assms diff-subst-prprty-4terms apply fastforce
using assms diff-subst-prprty-4terms by fastforce
\mathbf{lemma}\ dInvForProps\text{-}prelim:
assumes substHyp:
\forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ st \geq 0
and termVarsHyp:trmVars \eta \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
shows \llbracket \eta \rrbracket_t \ a > 0 \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow \llbracket \eta \rrbracket_t \ c > 0)
and [\![\eta]\!]_t \ a \geq 0 \longrightarrow (\forall \ c. \ (a,c) \in (\textit{ODEsystem xfList with } G) \longrightarrow [\![\eta]\!]_t \ c \geq 0)
proof(clarify)
fix c assume aHyp: [\![\eta]\!]_t \ a > 0 and cHyp: (a, c) \in ODE system \ xfList \ with \ G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F t=c \land solvesStoreIVP F xfList a \land (\forall r \in \{0..t\}. G (F r))
using guarDiffEqtn-def by auto
then have \forall x. \ x \notin varDiffs \longrightarrow F \ 0 \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t a = [\![\eta]\!]_t (F \ \theta) using term Vars Hyp \ eqIn Vars-impl-eqIn Trms
hence obs1: [\![\eta]\!]_t (F \theta) > \theta using aHyp \ tcHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \ \eta]\!]_t \ (F \ r)) \ (at \ r \ within \ \{0..t\}) \ \mathbf{using} \ derivationLemma \ term VarsHyp \ \mathbf{by} \ blast
have (\forall t \geq 0. \ \forall \ xf \in set \ xfList. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t))
using tcHyp solves-store-ivpD(3) by blast
hence \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) = [\![(map (vdiff \circ \pi_1) xfList) \otimes uInput) \langle \partial_t \eta \rangle]\!]_t
(F r)
using diff-subst-prprty-4terms term VarsHyp tcHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0...t\}. [((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput)\ \langle \partial_t
```

```
\eta \rangle |_t (F r) \geq 0
using solves-store-ivpD(2) tcHyp by (metis atLeastAtMost-iff)
ultimately have *: \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) \geq 0 by (simp)
from obs2 and tcHyp have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-derivative
(\lambda x.\ x*_R(\llbracket \partial_t\ \eta \rrbracket_t\ (F\ r))))\ (at\ r\ within\ \{0..t\})\ \mathbf{by}\ (simp\ add:\ has-vector-derivative-def)
hence \exists r \in \{0..t\}. [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = t \cdot ([\![(\partial_t \eta)]\!]_t) (F r)
using mvt-very-simple and tcHyp by fastforce
then obtain r where [\![\partial_t \ \eta]\!]_t (F r) \geq 0 \wedge 0 \leq r \wedge r \leq t \wedge [\![\partial_t \ \eta]\!]_t (F t) \geq 0
\wedge [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = t \cdot ([\![\partial_t \eta]\!]_t (F r))
using * tcHyp by (meson atLeastAtMost-iff order-refl)
thus \|\eta\|_t c>0
using obs1 tcHyp by (metis cancel-comm-monoid-add-class.diff-cancel diff-ge-0-iff-ge
diff-strict-mono linorder-neqE-linordered-idom linordered-field-class.siqn-simps(45)
not-le)
next
\mathbf{show}\ \ \theta \leq \llbracket \eta \rrbracket_t\ a \longrightarrow (\forall\ c.\ (a,\ c) \in\ ODE \textit{system xfList with}\ G\ \longrightarrow \ \theta \leq \llbracket \eta \rrbracket_t\ c)
proof(clarify)
fix c assume aHyp: [\![\eta]\!]_t \ a \geq 0 and cHyp: (a, c) \in ODEsystem xfList with G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F \ t = c \land solvesStoreIVP \ F \ xfList \ a \land (\forall r\in \{0..t\}. \ G \ (F \ r))
using guarDiffEqtn-def by auto
then have \forall x. \ x \notin varDiffs \longrightarrow F \ 0 \ x = a \ x \ using \ solves-store-ivpD(6) by blast
from this have [\![\eta]\!]_t \ a = [\![\eta]\!]_t \ (F \ \theta) using termVarsHyp \ eqInVars-impl-eqInTrms
bv blast
hence obs1: [\![\eta]\!]_t (F \theta) \ge \theta using aHyp \ tcHyp by simp
from tcHyp have obs2: \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-vector-derivative
[\![\partial_t \eta]\!]_t (F r) (at r within \{0..t\}) using derivationLemma termVarsHyp by blast
have (\forall t \ge 0. \ \forall \ xf \in set \ xfList. \ F \ t \ (\partial \ (\pi_1 \ xf)) = \pi_2 \ xf \ (F \ t))
using tcHyp\ solves-store-ivpD(3) by blast
from this and tcHyp have \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) =
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\ \langle \partial_t\ \eta \rangle \rrbracket_t\ (F\ r)
using diff-subst-prprty-4terms termVarsHyp listsHyp by fastforce
also from substHyp have \forall r \in \{0..t\}. [((map\ (vdiff\ \circ \pi_1)\ xfList) \otimes uInput)\ \langle \partial_t
\eta \rangle \|_t (F r) \geq \theta
using solves-store-ivpD(2) tcHyp by (metis\ atLeastAtMost-iff)
ultimately have *: \forall r \in \{0..t\}. [\![\partial_t \eta]\!]_t (F r) \geq 0 by (simp)
from obs2 and tcHyp have \forall r \in \{0..t\}. ((\lambda s. \llbracket \eta \rrbracket_t (F s)) has-derivative
(\lambda x. \ x *_R (\llbracket \partial_t \eta \rrbracket_t (Fr)))) (at \ r \ within \{0..t\}) by (simp \ add: has-vector-derivative-def)
hence \exists r \in \{0..t\}. [\![\eta]\!]_t (F t) - [\![\eta]\!]_t (F \theta) = t \cdot ([\![\partial_t \eta]\!]_t (F r))
using mvt-very-simple and tcHyp by fastforce
then obtain r where [\![\partial_t \ \eta]\!]_t (F r) \geq 0 \wedge 0 \leq r \wedge r \leq t \wedge [\![\partial_t \ \eta]\!]_t (F t) \geq 0
\wedge \ [\![\eta]\!]_t \ (F \ t) - [\![\eta]\!]_t \ (F \ \theta) = t \cdot ([\![\partial_t \ \eta]\!]_t \ (F \ r))
using * tcHyp by (meson atLeastAtMost-iff order-refl)
thus [\![\eta]\!]_t \ c > 0
using obs1 tcHyp by (metis cancel-comm-monoid-add-class.diff-cancel diff-qe-0-iff-qe
```

```
diff-strict-mono linorder-neqE-linordered-idom linordered-field-class.sign-simps (45)
not-le)
qed
qed
lemma less-pval-to-tval:
assumes \llbracket ((map \ (vdiff \circ \pi_1) \ xfList) \otimes uInput) \upharpoonright \partial_P \ (\vartheta \prec \eta) \upharpoonright \rrbracket_P \ st
shows \llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t\ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t\ st \geq 0
using assms by (auto)
lemma leq-pval-to-tval:
assumes \llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ (\vartheta \leq \eta) \upharpoonright \rrbracket_P\ st
shows [(map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \langle \partial_t\ (\eta \oplus (\ominus \vartheta)) \rangle]_t\ st \geq 0
using assms by (auto)
lemma dInv-prelim:
assumes substHyp: \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList))) \longrightarrow st \ (\partial \ str) =
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and prop VarsHyp:prop Vars \varphi \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
shows \llbracket \varphi \rrbracket_P \ a \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow \llbracket \varphi \rrbracket_P \ c)
\mathbf{proof}(clarify)
fix c assume aHyp: \llbracket \varphi \rrbracket_P a and cHyp: (a, c) \in ODEsystem xfList with G
from this obtain t::real and F::real \Rightarrow real store
where tcHyp:t\geq 0 \land F t=c \land solvesStoreIVP F xfList a using guarDiffEqtn-def
by auto
from aHyp prop VarsHyp and substHyp show \llbracket \varphi \rrbracket_P c
\mathbf{proof}(induction \ \varphi)
case (Eq \vartheta \eta)
hence hyp: \forall st. \ G \ st \longrightarrow \ (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff \circ \pi_1)\ xfList) \otimes uInput) \upharpoonright \partial_P \ (\vartheta \doteq \eta) \upharpoonright \rrbracket_P \ st \ by \ blast
then have \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList))) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
[((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput)\langle\partial_t\ (\vartheta\oplus(\ominus\eta))\rangle]_t\ st=0\ \mathbf{by}\ simp
also have trmVars\ (\vartheta \oplus (\ominus \eta)) \subseteq UNIV - varDiffs\ using\ Eq.prems(2) by simp
moreover have [\![\vartheta \oplus (\ominus \eta)]\!]_t a = \theta using Eq.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![\vartheta \oplus (\ominus \eta)]\!]_t \ c =
\theta
using dInvForTrms-prelim listsHyp by blast
hence [\![\vartheta \oplus (\ominus \eta)]\!]_t (F t) = \theta using tcHyp \ cHyp by simp
from this have [\![\vartheta]\!]_t (F\ t) = [\![\eta]\!]_t (F\ t) by simp
also have (\llbracket \vartheta \doteq \eta \rrbracket_P) c = (\llbracket \vartheta \rrbracket_t \ (F \ t) = \llbracket \eta \rrbracket_t \ (F \ t)) using tcHyp by simp
ultimately show ?case by simp
next
case (Less \vartheta \eta)
hence \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
0 < (\llbracket (map\ (vdiff \circ \pi_1)\ xfList \otimes uInput) \langle \partial_t\ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t)\ st
using less-pval-to-tval by metis
```

```
also from Less.prems(2) have trmVars\ (\eta \oplus (\ominus \vartheta)) \subseteq UNIV - varDiffs\ by\ simp
moreover have [\eta \oplus (\ominus \vartheta)]_t a > \theta using Less.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![ \eta \oplus (\ominus \vartheta) ]\!]_t \ c >
using dInvForProps-prelim(1) listsHyp by blast
hence [\eta \oplus (\ominus \vartheta)]_t (F t) > \theta using tcHyp \ cHyp by simp
from this have [\![\eta]\!]_t (F t) > [\![\vartheta]\!]_t (F t) by simp
also have [\![\vartheta \prec \eta]\!]_P c = ([\![\vartheta]\!]_t (Ft) < [\![\eta]\!]_t (Ft)) using tcHyp by simp
ultimately show ?case by simp
next
case (Leq \vartheta \eta)
hence \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
0 \leq (\llbracket (map \ (vdiff \circ \pi_1) \ xfList \otimes uInput) \langle \partial_t \ (\eta \oplus (\ominus \vartheta)) \rangle \rrbracket_t) \ st \ using \ leq-pval-to-tval
also from Leq.prems(2) have trmVars\ (\eta \oplus (\ominus \vartheta)) \subseteq UNIV - varDiffs\ by\ simp
moreover have [\eta \oplus (\ominus \vartheta)]_t a \ge \theta using Leq.prems(1) by simp
ultimately have (\forall c. (a, c) \in ODEsystem \ xfList \ with \ G \longrightarrow [\![ \eta \oplus (\ominus \vartheta) ]\!]_t \ c \geq
using dInvForProps-prelim(2) listsHyp by blast
hence [\![ \eta \oplus (\ominus \vartheta) ]\!]_t (F t) \geq \theta using tcHyp \ cHyp by simp
from this have (\llbracket \eta \rrbracket_t (F t) \geq \llbracket \vartheta \rrbracket_t (F t)) by simp
also have [\![\vartheta \leq \eta]\!]_P c = ([\![\vartheta]\!]_t (Ft) \leq [\![\eta]\!]_t (Ft)) using tcHyp by simp
ultimately show ?case by simp
next
case (And \varphi 1 \varphi 2)
then show ?case by (simp)
\mathbf{next}
case (Or \varphi 1 \varphi 2)
from this show ?case by auto
qed
qed
theorem dInv:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and termVarsHyp:propVars \varphi \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and phi-p:P = [\![\varphi]\!]_P
shows PRE P (ODEsystem xfList with G) POST P
proof(clarsimp)
\mathbf{fix} \ a \ b
assume (a, b) \in [P]
from this have aHyp:a = b \land P a by (metis (full-types) d-p2r rdom-p2r-contents)
have P \ a \longrightarrow (\forall \ c. \ (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow P \ c)
using assms dInv-prelim by metis
from this and aHyp have \forall c. (a,c) \in (ODEsystem \ xfList \ with \ G) \longrightarrow P \ c by
blast
thus (a, b) \in wp \ (ODEsystem \ xfList \ with \ G) \ [P]
using aHyp by (simp add: boxProgrPred-chrctrztn)
```

qed

```
theorem dInvFinal:
assumes \forall st. \ G \ st \longrightarrow (\forall str. \ str \notin (\pi_1(set \ xfList)) \longrightarrow st \ (\partial \ str) = 0) \longrightarrow
\llbracket ((map\ (vdiff\ \circ\ \pi_1)\ xfList)\otimes uInput) \upharpoonright \partial_P\ \varphi \upharpoonright \rrbracket_P\ st
and termVarsHyp:propVars \varphi \subseteq (UNIV - varDiffs)
and listsHyp:map \pi_2 xfList = map tval uInput
and impls: [P] \subseteq [F] \land [F] \subseteq [Q]
and phi-f:F = [\![\varphi]\!]_P
shows PRE P (ODEsystem xfList with G) POST Q
\operatorname{apply}(rule\text{-}tac\ C=[\![\varphi]\!]_P\ \operatorname{in}\ dCut)
\mathbf{apply}(\mathit{subgoal\text{-}tac}\ \lceil F \rceil \subseteq \mathit{wp}\ (\mathit{ODEsystem}\ \mathit{xfList}\ \mathit{with}\ \mathit{G})\ \lceil F \rceil,\ \mathit{simp})
using impls and phi-f apply blast
apply(subgoal-tac PRE F (ODEsystem xfList with G) POST F, simp)
apply(rule-tac \varphi = \varphi and uInput = uInput in dInv)
prefer 5 apply(subgoal-tac PRE P (ODEsystem xfList with (\lambda s. G s \wedge F s))
POST Q, simp add: phi-f)
apply(rule dWeakening)
using impls apply simp
using assms by simp-all
end
theory VC-diffKAD-examples
imports VC-diffKAD
```

### 5.4.5 Rules Testing

begin

In this section we test the recently developed rules with simple dynamical systems.

— Example of hybrid program verified with the rule d Solve and a single differential equation: x' = v.

```
lemma motion-with-constant-velocity:

PRE \ (\lambda \ s. \ s''y'' < s \ ''x'' \ \land s''v'' > 0)
(ODE system \ [(''x'', (\lambda \ s. \ s \ ''v''))] \ with \ (\lambda \ s. \ True))
POST \ (\lambda \ s. \ (s \ ''y'' < s \ ''x''))
apply(rule-tac uInput=[\lambda \ t. s. s \ ''v'' \cdot t + s \ ''x''] \ in \ dSolve-toSolveUBC)
prefer g subgoal by(simp \ add: \ wp-trafo \ vdiff-def \ add-strict-increasing2)
apply(simp \ add: \ vdiff-def \ varDiffs-def)
prefer g apply(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
apply(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
apply(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
apply(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
apply(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
by(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
by(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def))
by(simp \ add: \ solvesStoreIVP-def \ vdiff-def \ varDiffs-def)
```

Same hybrid program verified with dSolve and the system of ODEs: x' = v, v' = a. The uniqueness part of the proof requires a preliminary lemma.

 $\mathbf{lemma}\ \mathit{flow-vel-is-galilean-vel}\colon$ 

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```
assumes solHyp:\varphi_s solvesTheStoreIVP [(x, \lambda s.\ s\ v),\ (v, \lambda s.\ s\ a)] withInitState\ s
   and tHyp:r \leq t and rHyp:0 \leq r and distinct:x \neq v \land v \neq a \land x \neq a \land a \notin s
varDiffs
shows \varphi_s \ r \ v = s \ a \cdot r + s \ v
proof-
from assms have 1:((\lambda t. \varphi_s t v) \text{ solves-ode } (\lambda t r. \varphi_s t a)) \{0..t\} UNIV \wedge \varphi_s 0
v = s v
 \mathbf{by}\ (simp\ add:\ solvesStoreIVP\text{-}def)
from assms have obs: \forall r \in \{0..t\}. \varphi_s r a = s a
  by(auto simp: solvesStoreIVP-def varDiffs-def)
have 2:((\lambda t. \ s \ a \cdot t + s \ v) \ solves-ode \ (\lambda t \ r. \ \varphi_s \ t \ a)) \ \{0..t\} \ UNIV
  unfolding solves-ode-def apply(subgoal-tac ((\lambda x. s. a. x. + s. v) has-vderiv-on
(\lambda x. \ s \ a)) \ \{\theta..t\})
  using obs apply (simp add: has-vderiv-on-def) by(rule galilean-transform)
have 3:unique-on-bounded-closed 0 \{0..t\} (s\ v) (\lambda t\ r.\ \varphi_s\ t\ a) UNIV (if\ t=0\ then
1 else 1/(t+1)
  apply(simp\ add:\ ubc\ definitions\ del:\ comp\ apply,\ rule\ conjI)
   using rHyp tHyp obs apply(simp-all\ del:\ comp-apply)
  apply(clarify, rule continuous-intros) prefer 3 apply safe
  apply(rule continuous-intros)
  apply(auto intro: continuous-intros)
   by (metis continuous-on-const continuous-on-eq)
thus \varphi_s r v = s a \cdot r + s v
  apply(rule-tac\ unique-on-bounded-closed.unique-solution[of\ 0\ \{0..t\}\ s\ v
   (\lambda t \ r. \ \varphi_s \ t \ a) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1 \ / \ (t + 1)) \ (\lambda t. \ \varphi_s \ t \ v)])
   using rHyp tHyp 1 2 and 3 by auto
\mathbf{qed}
lemma motion-with-constant-acceleration:
      PRE (\lambda s. s "y" < s "x" \land s "v" \ge 0 \land s "a" > 0)
      (ODE system [("x",(\lambda s. s "v")),("v",(\lambda s. s "a"))] with (\lambda s. True))
      POST \ (\lambda \ s. \ (s \ "y" < s \ "x"))
apply(rule-tac uInput=[\lambda t s. s ''a'' \cdot t \hat{2}/2 + s ''v'' \cdot t + s ''x'',
 \lambda \ t \ s. \ s \ ''a'' \cdot t + s \ ''v'' in dSolve-toSolveUBC)
prefer 9 subgoal by(simp add: wp-trafo vdiff-def add-strict-increasing2)
prefer 6 subgoal
   apply(simp add: vdiff-def, clarify, rule conjI)
   \mathbf{by}(rule\ galilean-transform)+
prefer \theta subgoal
   apply(simp add: vdiff-def, safe)
   \mathbf{by}(rule\ continuous\text{-}intros)+
prefer \theta subgoal
   apply(simp add: vdiff-def, safe)
   subgoal for s \varphi_s t r apply(rule flow-vel-is-galilean-vel[of \varphi_s "x" - - - - t])
      by(simp-all add: varDiffs-def vdiff-def)
   apply(simp add: solvesStoreIVP-def vdiff-def varDiffs-def) done
by(auto simp: varDiffs-def vdiff-def)
```

Example of a hybrid system with two modes verified with the equality dS.

We also need to provide a previous (similar) lemma.

```
lemma flow-vel-is-galilean-vel2:
assumes solHyp:\varphi_s solvesTheStoreIVP [(x, \lambda s. s. v), (v, \lambda s. - s. a)] withInitState
   and tHyp:r \leq t and rHyp:0 \leq r and distinct:x \neq v \land v \neq a \land x \neq a \land a \notin s
varDiffs
shows \varphi_s \ r \ v = s \ v - s \ a \cdot r
proof-
from assms have 1:((\lambda t. \varphi_s t v) solves-ode (\lambda t r. - \varphi_s t a)) {0..t} UNIV \wedge \varphi_s
\theta v = s v
 by (simp add: solvesStoreIVP-def)
from assms have obs: \forall r \in \{0..t\}. \varphi_s r a = s a
  by(auto simp: solvesStoreIVP-def varDiffs-def)
have 2:((\lambda t. - s \ a \cdot t + s \ v) \ solves-ode \ (\lambda t \ r. - \varphi_s \ t \ a)) \ \{0..t\} \ UNIV
 unfolding solves-ode-def apply(subgoal-tac ((\lambda x. - s \ a \cdot x + s \ v) has-vderiv-on
(\lambda x. - s \ a)) \ \{\theta..t\})
  using obs apply (simp add: has-vderiv-on-def) by(rule galilean-transform)
have 3:unique-on-bounded-closed 0 \{0..t\} (s\ v)\ (\lambda t\ r. - \varphi_s\ t\ a)\ UNIV\ (if\ t=0)
then 1 else 1/(t+1)
  apply(simp add: ubc-definitions del: comp-apply, rule conjI)
  using rHyp tHyp obs apply(simp-all\ del:\ comp-apply)
  apply(clarify, rule continuous-intros) prefer 3 apply safe
  apply(rule\ continuous-intros)+
  apply(auto intro: continuous-intros)
  by (metis continuous-on-const continuous-on-eq)
thus \varphi_s r v = s v - s a \cdot r
  apply(rule-tac\ unique-on-bounded-closed.unique-solution[of\ 0\ \{0..t\}\ s\ v
   (\lambda t \ r. - \varphi_s \ t \ a) \ UNIV \ (if \ t = 0 \ then \ 1 \ else \ 1 \ / \ (t + 1)) \ (\lambda t. \ \varphi_s \ t \ v)])
   using rHyp tHyp 1 2 and 3 by auto
qed
lemma single-hop-ball:
     PRE(\lambda s. 0 \le s "x" \land s "x" = H \land s "v" = 0 \land s "q" > 0 \land 1 > c \land c
     (((ODEsystem [("x", \lambda s. s "v"), ("v", \lambda s. - s "g")] with (\lambda s. 0 \le s "x")));
     (IF (\lambda s. s "x" = 0) THEN ("v" := (\lambda s. - c \cdot s "v")) ELSE ("v" := (\lambda s. - c \cdot s "v"))
s. s "v") FI)
     POST (\lambda \ s. \ 0 \le s \ "x" \land s \ "x" \le H)
     apply(simp, subst dS[of [\lambda \ t \ s. - s \ ''g'' \cdot t \ \hat{2}/2 + s \ ''v'' \cdot t + s \ ''x'', \lambda \ t
s. - s "g" \cdot t + s "v" \rangle \rangle
      — Given solution is actually a solution.
    apply(simp add: vdiff-def varDiffs-def solvesStoreIVP-def solves-ode-def has-vderiv-on-singleton,
safe)
     apply(rule\ galilean-transform-eq,\ simp)+
     apply(rule\ galilean-transform)+
      — Uniqueness of the flow.
     apply(rule\ ubcStore\ UniqueSol,\ simp)
     apply(simp add: vdiff-def del: comp-apply)
     apply(auto intro: continuous-intros del: comp-apply)[1]
```

```
apply(rule\ continuous-intros)+
      apply(simp\ add:\ vdiff-def,\ safe)
      apply(clarsimp) subgoal for s X t \tau
      apply(rule\ flow-vel-is-galilean-vel2[of\ X\ ''x''])
      by(simp-all add: varDiffs-def vdiff-def)
      apply(simp add: vdiff-def varDiffs-def solvesStoreIVP-def)
      apply(simp add: vdiff-def varDiffs-def solvesStoreIVP-def solves-ode-def
       has-vderiv-on-singleton galilean-transform-eq galilean-transform)
       — Relation Between the guard and the postcondition.
      by(auto simp: vdiff-def p2r-def)

    Example of hybrid program verified with differential weakening.

{\bf lemma}\ system-where-the-guard-implies-the-postcondition:
      PRE (\lambda s. s''x'' = 0)
      (ODEsystem [("x",(\lambda s. s"x" + 1))] with (\lambda s. s"x" > 0))
      POST \ (\lambda \ s. \ s \ "x" \ge 0)
using dWeakening by blast
\textbf{lemma} \ \textit{system-where-the-guard-implies-the-postcondition2}:
      PRE (\lambda s. s''x'' = 0)
      (ODEsystem [("x",(\lambda s. s "x" + 1))] with (\lambda s. s "x" \ge 0)
      POST \ (\lambda \ s. \ s \ ''x'' \ge \theta)
apply(clarify, simp add: p2r-def)
apply(simp add: rel-ad-def rel-antidomain-kleene-algebra.addual.ars-r-def)
apply(simp add: rel-antidomain-kleene-algebra.fbox-def)
apply(simp add: relcomp-def rel-ad-def guarDiffEqtn-def solvesStoreIVP-def)
by auto
— Example of system proved with a differential invariant.
lemma circular-motion:
      PRE(\lambda s. (s''x'') \cdot (s''x'') + (s''y'') \cdot (s''y'') - (s''r'') \cdot (s''r'') = 0)
       \begin{array}{l} (ODE system \ [(''x'', (\lambda \ s. \ s \ ''y'')), (''y'', (\lambda \ s. \ - \ s \ ''x''))] \ with \ G) \\ POST \ (\lambda \ s. \ (s \ ''x'') \cdot (s \ ''x'') + (s \ ''y'') \cdot (s \ ''y'') - (s \ ''r'') \cdot (s \ ''r'') = 0) \end{array} 
\mathbf{apply}(\textit{rule-tac}\ \eta = (t_V \ ''x'') \odot (t_V \ ''x'') \oplus (t_V \ ''y'') \odot (t_V \ ''y'') \oplus (\ominus (t_V \ ''r'') \odot (t_V \ ''y'')))
"r"))
 and uInput=[t_V "y", \ominus (t_V "x")] in dInvForTrms)
apply(simp-all add: vdiff-def varDiffs-def)
apply(clarsimp, erule-tac \ x=''r'' \ in \ all E)
by simp
— Example of systems proved with differential invariants, cuts and weakenings.
declare d-p2r [simp del]
\textbf{lemma} \ \textit{motion-with-constant-velocity-and-invariants}:
      PRE (\lambda s. s''x'' > s''y'' \wedge s''v'' > 0)
      (ODEsystem [("x", \lambda s. s "v")] with (\lambda s. True))
      POST (\lambda s. s "x"> s "y")
apply(rule-tac\ C = \lambda\ s.\ s\ ''v'' > \theta\ in\ dCut)
apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ "v") and uInput = [t_V \ "v"]in dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x="v"\ in\ all E,\ simp)
```

```
apply(rule-tac C = \lambda \ s. \ s \ ''x'' > s \ ''y'' \ in \ dCut)
apply(rule-tac \varphi = (t_V "y") \prec (t_V "x") and uInput = [t_V "v"] and
 F=\lambda \ s. \ s ''x'' > s ''y''  in dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x="y"\ in\ allE,\ simp)
using dWeakening by simp
lemma motion-with-constant-acceleration-and-invariants:
      PRE (\lambda s. s "y" < s "x" \land s "v" \ge 0 \land s "a" > 0)
      (ODE system \ [("x", (\lambda s. s "v")), ("v", (\lambda s. s "a"))] \ with \ (\lambda s. True))
      POST (\lambda \ s. \ (s \ "y" < s \ "x"))
apply(rule-tac C = \lambda \ s. \ s''a'' > 0 \ in \ dCut)
apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ ''a'') and uInput = [t_V \ ''v'', t_V \ ''a'']in dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x=''a''\ in\ all E,\ simp)
apply(rule-tac\ C = \lambda\ s.\ s\ ''v'' \ge 0\ in\ dCut)
\mathbf{apply}(\textit{rule-tac}\ \varphi = (\textit{t}_{\textit{C}}\ \textit{0}) \preceq (\textit{t}_{\textit{V}}\ ''\textit{v}'') \ \mathbf{and} \ \textit{uInput} = [\textit{t}_{\textit{V}}\ ''\textit{v}'',\ \textit{t}_{\textit{V}}\ ''\textit{a}''] \ \mathbf{in} \ \textit{dInvFi-}
nal)
apply(simp-all add: vdiff-def varDiffs-def)
apply(rule-tac C = \lambda \ s. \ s''x'' > s''y'' in dCut)
apply(rule-tac \varphi = (t_V "y") \prec (t_V "x") and uInput = [t_V "v", t_V "a"]in dInv-
Final
apply(simp-all\ add:\ varDiffs-def\ vdiff-def,\ clarify,\ erule-tac\ x="y"\ in\ all E,\ simp)
using dWeakening by simp
— We revisit the two modes example from before, and prove it with invariants.
{f lemma}\ single-hop-ball-and-invariants:
      PRE (\lambda s. 0 \le s "x" \land s "x" = H \land s "v" = 0 \land s "g" > 0 \land 1 \ge c \land c
      (((ODEsystem [("x", \lambda s. s"v"), ("v", \lambda s. - s"g")] with (\lambda s. 0 \le s "x")));
      (IF (\lambda s. s "x" = 0) THEN ("v" := (\lambda s. - c \cdot s "v")) ELSE ("v" := (\lambda s. - c \cdot s "v"))
s. s "v") FI)
      POST \ (\lambda \ s. \ 0 \le s \ "x" \land s \ "x" \le H)
      \mathbf{apply}(\mathit{simp\ add}\colon\mathit{d-p2r},\,\mathit{subgoal-tac\ rdom}\,\,\lceil \lambda s.\,\, 0\,\leq\,s\,\,{''}x{''}\,\wedge\,s\,\,{''}x{''}=\,H\,\,\wedge\,\, s
"v" = 0 \land 0 < s "g" \land c \leq 1 \land 0 \leq c
    \subseteq wp \ (ODEsystem \ [("x", \lambda s. \ s "v"), ("v", \lambda s. - s "g")] \ with \ (\lambda s. \ 0 \le s "x")
         [inf (sup\ (-(\lambda s.\ s\ ''x''=0))\ (\lambda s.\ 0 \le s\ ''x'' \land s\ ''x'' \le H))\ (sup\ (\lambda s.\ s
"x" = 0) (\lambda s. \ 0 \le s \ "x" \wedge s \ "x" \le H))))
      apply(simp add: d-p2r, rule-tac C = \lambda \ s. \ s \ ''g'' > 0 \ in \ dCut)
       apply(rule-tac \varphi = (t_C \ \theta) \prec (t_V \ ''g'') and uInput=[t_V \ ''v'', \ominus t_V \ ''g'']in
dInvFinal)
      apply(simp-all add: vdiff-def varDiffs-def, clarify, erule-tac x=''q'' in all E,
      apply(rule-tac C = \lambda \ s. \ s \ "v" \le \theta \ in \ dCut)
      apply(rule-tac \varphi = (t_V "v") \preceq (t_C \ \theta) and uInput = [t_V "v", \ominus t_V "g"] in
dInvFinal)
      apply(simp-all add: vdiff-def varDiffs-def)
      \mathbf{apply}(\textit{rule-tac } C = \lambda \textit{ s. } s \textit{ "x"} \leq \textit{ H in } dCut)
      apply(rule-tac \varphi = (t_V "x") \leq (t_C H) and uInput = [t_V "v", \ominus t_V "g"]in
dInvFinal)
```

**apply**(simp-all add: varDiffs-def vdiff-def)

```
using dWeakening by simp
— Finally, we add a well known example in the hybrid systems community, the
bouncing ball.
lemma bouncing-ball-invariant:0 < x \Longrightarrow 0 < q \Longrightarrow 2 \cdot q \cdot x = 2 \cdot q \cdot H - v
v \Longrightarrow (x::real) < H
proof-
assume 0 \le x and 0 < g and 2 \cdot g \cdot x = 2 \cdot g \cdot H - v \cdot v
then have v \cdot v = 2 \cdot g \cdot H - 2 \cdot g \cdot x \wedge 0 < g by auto
hence *:v \cdot v = 2 \cdot g \cdot (H - x) \wedge 0 < g \wedge v \cdot v \geq 0
  using left-diff-distrib mult.commute by (metis zero-le-square)
from this have (v \cdot v)/(2 \cdot g) = (H - x) by auto
also from * have (v \cdot v)/(2 \cdot g) \geq 0
by (meson divide-nonneg-pos linordered-field-class.sign-simps(44) zero-less-numeral)
ultimately have H - x \ge \theta by linarith
thus ?thesis by auto
qed
lemma bouncing-ball:
PRE \ (\lambda \ s. \ 0 \le s \ ''x'' \land s \ ''x'' = H \land s \ ''v'' = 0 \land s \ ''g'' > 0)
((ODEsystem \ [("x", \lambda s. s "v"), ("v", \lambda s. - s "g")] \ with \ (\lambda s. \theta \le s "x"));
(IF (\lambda s. s "x" = 0) THEN ("v" ::= (\lambda s. - s "v")) ELSE (Id) FI))^*
POST \ (\lambda \ s. \ 0 \le s \ "x" \land s \ "x" \le H)
apply(rule rel-antidomain-kleene-algebra.fbox-starI[of - \lceil \lambda s. \ 0 \le s \ ''x'' \land 0 < s
2 \cdot s ''g'' \cdot s ''x'' = 2 \cdot s ''g'' \cdot H - (s ''v'' \cdot s ''v'')]])
apply(simp, simp add: d-p2r)
apply(subgoal-tac
  rdom \ \lceil \lambda s. \ 0 \le s \ ''x'' \land \ 0 < s \ ''g'' \land \ 2 \cdot s \ ''g'' \cdot s \ ''x'' = 2 \cdot s \ ''g'' \cdot H - s
"v" \cdot s "v"
 \subseteq wp \ (ODEsystem \ [(''x'', \lambda s. \ s \ ''v''), \ (''v'', \lambda s. - s \ ''g'')] \ with \ (\lambda s. \ \theta \le s \ ''x'')
  \lceil \inf \left( \sup \left( - (\lambda s. \ s \ ''x'' = \theta) \right) \right) \left( \lambda s. \ \theta \le s \ ''x'' \land \theta < s \ ''g'' \land 2 \cdot s \ ''g'' \cdot s \ ''x'' \right) 
           2 \cdot s ''g'' \cdot H - s ''v'' \cdot s ''v''))
         (\sup (\lambda s.\ s.\ ''x'' = 0)\ (\lambda s.\ 0 \le s.\ ''x'' \land 0 < s.\ ''g'' \land 2 \cdot s.\ ''g'' \cdot s.\ ''x'' = 2 \cdot s.\ ''g'' \cdot H - s.\ ''v'' \cdot s.\ ''v'')])
apply(simp \ add: \ d-p2r)
apply(rule-tac C = \lambda \ s. \ s \ ''q'' > 0 \ in \ dCut)
apply(rule-tac \varphi = ((t_C \ \theta) \prec (t_V \ ''g'')) and uInput = [t_V \ ''v'', \ominus t_V \ ''g'']in
dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x=''g''\ in\ all E,\ simp)
apply(rule-tac C = \lambda \ s. \ 2 \cdot s \ ''g'' \cdot s \ ''x'' = 2 \cdot s \ ''g'' \cdot H - s \ ''v'' \cdot s \ ''v'' in
dCut
\mathbf{apply}(\textit{rule-tac}\ \varphi = (t_C\ 2)\ \odot\ (t_V\ ''g'')\ \odot\ (t_C\ H)\ \oplus\ (\ominus\ ((t_V\ ''v'')\ \odot\ (t_V\ ''v'')))
  \stackrel{.}{=} (t_C \ 2) \odot (t_V \ ''g'') \odot (t_V \ ''x'') and uInput = [t_V \ ''v'', \ominus t_V \ ''g''] in dInvFinal)
apply(simp-all\ add:\ vdiff-def\ varDiffs-def,\ clarify,\ erule-tac\ x=''g''\ in\ all E,\ simp)
```

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 $\begin{array}{l} \mathbf{apply}(\mathit{rule}\ \mathit{dWeakening},\ \mathit{clarsimp}) \\ \mathbf{using}\ \mathit{bouncing-ball-invariant}\ \mathbf{by}\ \mathit{auto} \end{array}$ 

**declare** d-p2r [simp]

 $\mathbf{end}$