

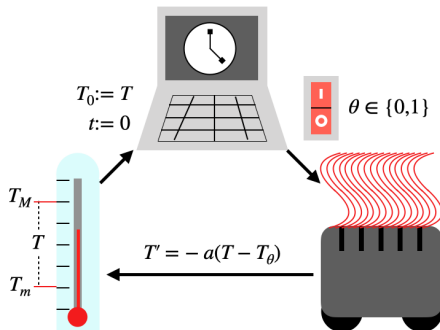
Differential Hoare Logics and Refinement Calculi for Hybrid Systems with Isabelle/HOL

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Verification of Hybrid Systems



dynamics = $T' = -a(T - T_\theta)$

pre = $T_m \leq T \leq T_M$

pos = $T_m \leq T \leq T_M$

control = $t := 0 ; T_0 := T ; \dots$

therm = (control ; dynamics)*

{pre} therm {pos}

hybrid program

correctness spec

Previous Work

- Isabelle/HOL verification components for hybrid programs that
 - benefit from huge libraries of topology, analysis, and ODEs;
 - based on [MKA](#);
 - work with weakest liberal preconditions;
 - support various verification procedures for systems of ODEs, and
 - are correct by construction.
- Yet, program verification requires simpler methods:
 - Hoare logic serves for program verification, and
 - Morgan's refinement calculus is closely related.

Can we obtain simpler Hoare logic and refinement calculus to do hybrid program verification?

Main Contributions

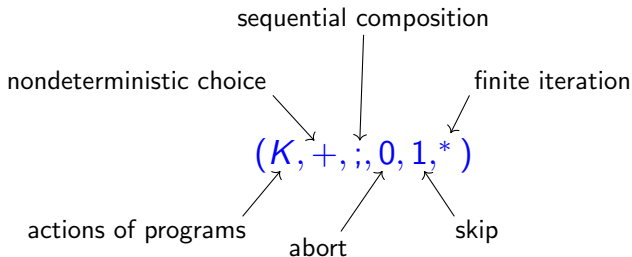
Development of minimal proof systems for verification of hybrid systems:

1. rules of differential Hoare logic $d\mathcal{H}$;
2. laws of differential refinement calculus $d\mathcal{R}$;
3. based on KAT s and $rKAT$ s respectively;
4. integration of lenses as the store model;
5. support reasoning in the style of differential dynamic logic $d\mathcal{L}$, and
6. tactics for automated verification condition generation.

<https://github.com/yonoteam/CPSVerification>

Kleene Algebras with Tests

Kleene Algebra



Tests

- $(B, +, ;, 0, 1, \neg)$ is a boolean algebra,
- use $\alpha, \beta \in K$ and $p, q \in B$ where $B \subseteq K$,
- **if** p **then** α **else** $\beta = p ; \alpha + \neg p ; \beta$, and
- $\{p\} \alpha \{q\} \leftrightarrow p ; \alpha \leq \beta ; q$

State Transformer Model

Programs are functions $S \rightarrow \mathcal{P} S$:

$$(\alpha + \beta) s = \alpha s \cup \beta s,$$

$$(\alpha ; \beta) s = (\alpha \circ_K \beta) s = \bigcup \{ \beta s' \mid s' \in \alpha s \},$$

$$0 s = \emptyset,$$

$$1 s = \{s\},$$

$$(\neg p) s = \begin{cases} \{s\}, & \text{if } p s = \emptyset, \\ \emptyset, & \text{otherwise,} \end{cases}$$

$$\alpha^* s = \bigcup_{n \geq 0} \alpha^n s,$$

where $\alpha^0 s = 1 s$ and $\alpha^{n+1} = \alpha^n \circ_K \alpha$.

$$\{p\} \alpha \{q\} \leftrightarrow (\forall s_1. p s_1 \rightarrow (\forall s_2. s_2 \in \alpha s_1 \rightarrow q s_2))$$

What about Assignments?

Lenses

- Variables are lenses $x = (A, S, get_x, put_x)$ where

$$get_x : S \rightarrow A \text{ and } put_x : S \rightarrow A \rightarrow S$$

- A provides values of variable while S is the state space
- They satisfy the axioms

$$\begin{aligned} get_x (put_x s v) &= v \\ put_x (put_x s u) v &= put_x s v, \\ put_x s (get_x s) &= s. \end{aligned}$$

Semantics $S \rightarrow \mathcal{P} S$ for assignments are

$$(x := e) s = \{put_x s (e s)\}$$

Verification Rules

- Traditional Hoare logic:

$$\begin{aligned}p_1 \leq p_2 \wedge \{p_2\} \alpha \{q_2\} \wedge q_2 \leq q_1 &\rightarrow \{p_1\} \alpha \{q_1\} \\ \{p\} \alpha \{r\} \wedge \{r\} \beta \{q\} &\rightarrow \{p\} \alpha ; \beta \{q\}, \\ \{r ; p\} \alpha \{q\} \wedge \{\neg r ; p\} \beta \{q\} &\rightarrow \{p\} \textbf{if } r \textbf{ then } \alpha \textbf{ else } \beta \{q\}, \\ \{r ; p\} \alpha \{p\} &\rightarrow \{p\} \textbf{while } r \textbf{ do } \alpha \{\neg r ; p\}, \\ &\{ \lambda s. q (put_x s (e s)) \} x := e \{q\}.\end{aligned}$$

- Extended to regular programs

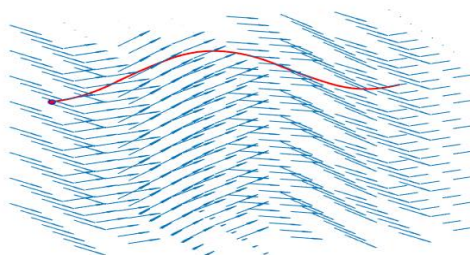
$$\begin{aligned}&\{p\} \textbf{skip} \{p\}, \\ &\{p\} \textbf{abort} \{q\}, \\ &\{p\} \alpha \{q\} \wedge \{p\} \beta \{q\} \rightarrow \{p\} \alpha + \beta \{q\}, \\ &\{p\} \alpha \{p\} \rightarrow \{p\} \textbf{loop} \alpha \{p\},\end{aligned}$$

where **loop** $\alpha = \alpha^*$, **skip** = 1, and **abort** = 0.

What about ODEs?

Vector Field

$$X'(t) = f(t, X(t))$$



where

$$X : T \subseteq \mathbb{R} \rightarrow S \quad f : T \rightarrow S \rightarrow S \quad X(0) = s$$

$$\text{orbit} : s \mapsto \{X(t) \mid t \in T\}$$

Semantics for ODEs

- Solutions to initial value problems (IVPs)

$$\text{Sols } f \ T \ s = \{X : T \rightarrow S \mid (\forall t \in T. X' \ t = f \ t \ (X \ t) \wedge X \ 0 = s)\}$$

- Guarded orbit

$$\text{orbit}_G^X \ s = \{X \ t \mid t \in T \wedge (\forall \tau \in [0, t]. G \ (X \ \tau))\}$$

- Semantics $S \rightarrow \mathcal{P} S$ for assignments are

$$(x' = f \ \& \ G) \ s = \bigcup \{\text{orbit}_G^X \ s \mid X \in \text{Sols } f \ T \ s\}$$

- The corresponding rule of inference is

$$\{\lambda s. \forall t \in T. (\forall \tau \in [0, t]. G \ (X \ \tau)) \rightarrow Q \ (X \ t)\} \ (x' = f \ \& \ G) \ \{Q\}$$

easy to obtain if there is a unique solution $X : T \rightarrow S$ to the IVPs associated to each s and the vector field f

Invariants in $d\mathcal{H}$

- I is an invariant for f iff $\{I\} x' = f \ \& \ G \ \{I\}$, or equivalently

$$\bigcup (\mathcal{P} (x' = f \ \& \ G) I) \subseteq I,$$

- We obtain the following rules

$$p \leq i \wedge \{i\} \alpha \{i\} \wedge i \leq q \rightarrow \{p\} \alpha \textbf{inv } i \{q\},$$

$$\{i\} \alpha \{i\} \wedge \{j\} \alpha \{j\} \rightarrow \{i; j\} \alpha \{i; j\},$$

$$\{i\} \alpha \{i\} \wedge \{j\} \alpha \{j\} \rightarrow \{i + j\} \alpha \{i + j\},$$

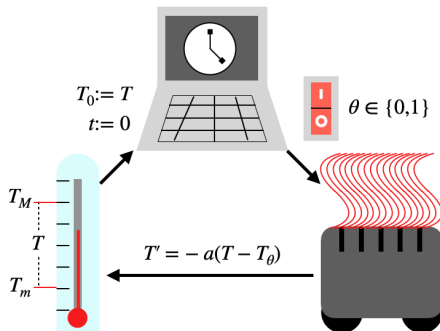
$$p \leq i \wedge \{i; t\} \alpha \{i\} \wedge \neg r; i \leq q \rightarrow \{p\} \textbf{while } r \textbf{ do } \alpha \textbf{inv } i \{q\},$$

$$p \leq i \wedge \{i\} \alpha \{i\} \wedge i \leq q \rightarrow \{p\} \textbf{loop } \alpha \textbf{inv } i \{q\},$$

$$p \leq i \wedge i \text{ is inv. for } f \wedge (G; i) \leq q \rightarrow \{p\} x' = f \ \& \ G \textbf{inv } i \{q\}.$$

where operationally $\alpha \textbf{inv } i = \alpha$.

Formalisation of the Thermostat



Lenses $\Pi[n] = (\mathbb{R}, \mathbb{R}^{\{0,1,2,3\}}, \lambda s. s\ n, \lambda s\ t. s[n \mapsto t])$ give us variables

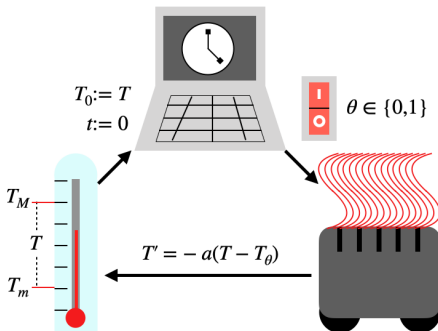
abbreviation $T :: \text{real} \Rightarrow \text{real}^4$ where $T \equiv \Pi[0]$

abbreviation $t :: \text{real} \Rightarrow \text{real}^4$ where $t \equiv \Pi[1]$

abbreviation $T_0 :: \text{real} \Rightarrow \text{real}^4$ where $T_0 \equiv \Pi[2]$

abbreviation $\vartheta :: \text{real} \Rightarrow \text{real}^4$ where $\vartheta \equiv \Pi[3]$

Formalisation of the Thermostat



Provide vector field and unique solution

abbreviation $f a c \equiv [T \mapsto_s - (a * (T - c)), T_0 \mapsto_s 0, \vartheta \mapsto_s 0, t \mapsto_s 1]$

abbreviation $\varphi a c \tau \equiv [T \mapsto_s - \exp(-a * \tau) * (c - T) + c,$
 $T_0 \mapsto_s T_0, \vartheta \mapsto_s \vartheta, t \mapsto_s \tau + t]$

Verification of the Thermostat

abbreviation $G T_m T_M a L \equiv$

$\mathbf{U}(t \leq -(\ln((L - (\text{if } L=0 \text{ then } T_m \text{ else } T_M)) / (L - T_0))) / a)$

abbreviation $I T_m T_M \equiv \mathbf{U}(T_m \leq T \wedge T \leq T_M \wedge (\vartheta = 0 \vee \vartheta = 1))$

abbreviation $ctrl T_m T_M \equiv$

$(t ::= 0); (T_0 ::= T);$

$(\text{IF } (\vartheta = 0 \wedge T_0 \leq T_m + 1) \text{ THEN } (\vartheta ::= 1) \text{ ELSE}$

$\text{IF } (\vartheta = 1 \wedge T_0 \geq T_h - 1) \text{ THEN } (\vartheta ::= 0) \text{ ELSE skip})$

abbreviation $dyn T_m T_M a T_u \tau \equiv$

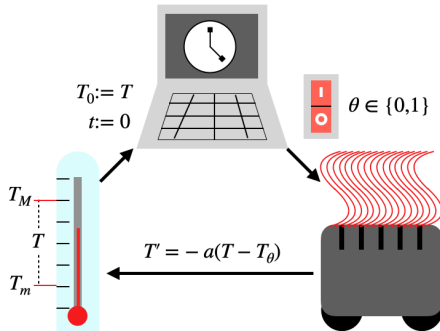
$\text{IF } (\vartheta = 0) \text{ THEN } x' = f a 0 \ \& \ G T_m T_M a 0 \text{ on } \{0..\tau\} \text{ UNIV @ } 0$

$\text{ELSE } x' = f a T_u \ \& \ G T_m T_M a T_u \text{ on } \{0..\tau\} \text{ UNIV @ } 0$

abbreviation $therm T_m T_M a L \tau \equiv$

$\text{LOOP } (ctrl T_m T_M ; dyn T_m T_M a L \tau) \text{ INV } (I T_m T_M)$

Verification of the Thermostat



lemma thermostat-flow:

assumes $0 < a$ and $0 \leq \tau$ and $0 < T_m$ and $T_M < T_u$

shows $\{I \ T_m \ T_M\} \text{ therm } T_m \ T_M \ a \ T_u \ \tau \ \{I \ T_m \ T_M\}$

apply (hyb-hoare $\mathbf{U}(I \ T_m \ T_M \wedge t=0 \wedge T_0 = T)$)

prefer 4 prefer 8 using local-flow-therm assms apply force+

using assms therm-dyn-up therm-dyn-down by rel-auto'

Differential Refinement Calculus $d\mathcal{R}$

Extend KAT with refinement operation $[-, -] : B \times B \rightarrow K$ such that

$$\{p\} \alpha \{q\} \leftrightarrow \alpha \leq [p, q].$$

Obtain traditional Morgan Style Refinement laws:

$$\begin{aligned} \text{skip} &\leq [p, p], \\ \text{abort} &\leq [p, q], \\ [p', q'] &\leq [p, q], & \text{if } p \leq p' \text{ and } q' \leq q, \\ [p, r] ; [r, q] &\leq [p, q], \\ [p, q] + [p, q] &\leq [p, q], \\ \text{if } t \text{ then } [t ; p, q] \text{ else } [\neg t ; p, q] &\leq [p, q], \\ \text{while } t \text{ do } [t ; p, p] &\leq [p, \neg t ; p], \\ \text{loop } [p, p] &\leq [p, p]. \end{aligned}$$

Refinement of the Thermostat

abbreviation $\text{dyn } T_m \ T_M \ a \ T_u \ \tau \equiv$

$\text{IF } (\vartheta = 0) \ \text{THEN } x' = f \ a \ 0 \ \& \ G \ T_m \ T_M \ a \ 0 \ \text{on } \{0..\tau\} \ \text{UNIV} @ 0$
 $\text{ELSE } x' = f \ a \ T_u \ \& \ G \ T_m \ T_M \ a \ T_u \ \text{on } \{0..\tau\} \ \text{UNIV} @ 0$

lemma *R-therm-down*:

assumes $a > 0$ **and** $0 \leq \tau$ **and** $0 < T_m$ **and** $T_M < T_u$

shows $[\vartheta = 0 \wedge I \ T_m \ T_M \wedge t = 0 \wedge T_0 = T, I \ T_m \ T_M] \geq$

$(x' = f \ a \ 0 \ \& \ G \ T_m \ T_M \ a \ 0 \ \text{on } \{0..\tau\} \ \text{UNIV} @ 0)$

apply(*rule local-flow.R-g-ode-ivl*[*OF local-flow-therm*])

using *therm-dyn-down*[*OF assms*(1,3), *of* - T_M] *assms by rel-auto'*

lemma *R-therm-up*:

assumes $a > 0$ **and** $0 \leq \tau$ **and** $0 < T_m$ **and** $T_M < T_u$

shows $[\neg \vartheta = 0 \wedge I \ T_m \ T_M \wedge t = 0 \wedge T_0 = T, I \ T_m \ T_M] \geq$

$(x' = f \ a \ T_u \ \& \ G \ T_m \ T_M \ a \ T_u \ \text{on } \{0..\tau\} \ \text{UNIV} @ 0)$

apply(*rule local-flow.R-g-ode-ivl*[*OF local-flow-therm*])

using *therm-dyn-up*[*OF assms*(1) - - *assms*(4), *of* T_m] *assms by rel-auto'*

Refinement of the Thermostat

abbreviation $ctrl\ T_m\ T_M \equiv$

$(t ::= 0); (T_0 ::= T);$
 $(IF\ (\vartheta = 0 \wedge T_0 \leq T_m + 1)\ THEN\ (\vartheta ::= 1)\ ELSE$
 $IF\ (\vartheta = 1 \wedge T_0 \geq T_h - 1)\ THEN\ (\vartheta ::= 0)\ ELSE\ skip)$

lemma *R-therm-time*: $[I\ T_m\ T_M, I\ T_m\ T_M \wedge t = 0] \geq (t ::= 0)$
by (rule *R-assign-law*, *pred-simp*)

lemma *R-therm-temp*:

$[I\ T_m\ T_M \wedge t = 0, I\ T_m\ T_M \wedge t = 0 \wedge T_0 = T] \geq (T_0 ::= T)$
by (rule *R-assign-law*, *pred-simp*)

lemma *R-thermostat-flow*:

assumes $a > 0$ and $0 \leq \tau$ and $0 < T_m$ and $T_M < T_u$

shows $[I\ T_m\ T_M, I\ T_m\ T_M] \geq therm\ T_m\ T_M\ a\ T_u\ \tau$

by (refinement;(rule *R-therm-time*)?,(rule *R-therm-temp*)?,
(rule *R-assign-law*)?, (rule *R-therm-up*[OF *assms*])?,
(rule *R-therm-down*[OF *assms*])?) *rel-auto'*

Conclusions

- Used modular semantic framework in Isabelle/HOL to
 - derive a minimal logic $d\mathcal{H}$ for verification of hybrid programs,
 - obtain refinement components via the laws of $d\mathcal{R}$,
- Added lenses for better parsing and alternative program stores
- Future work:
 - Explore total correctness,
 - Adversarial dynamics like in differential game logic,
 - Code generation of verified executable code,
 - Integrate with a CAS that supplies solutions and invariants, leaving the certification work to Isabelle.

<https://github.com/yonoteam/CPSVerification>