

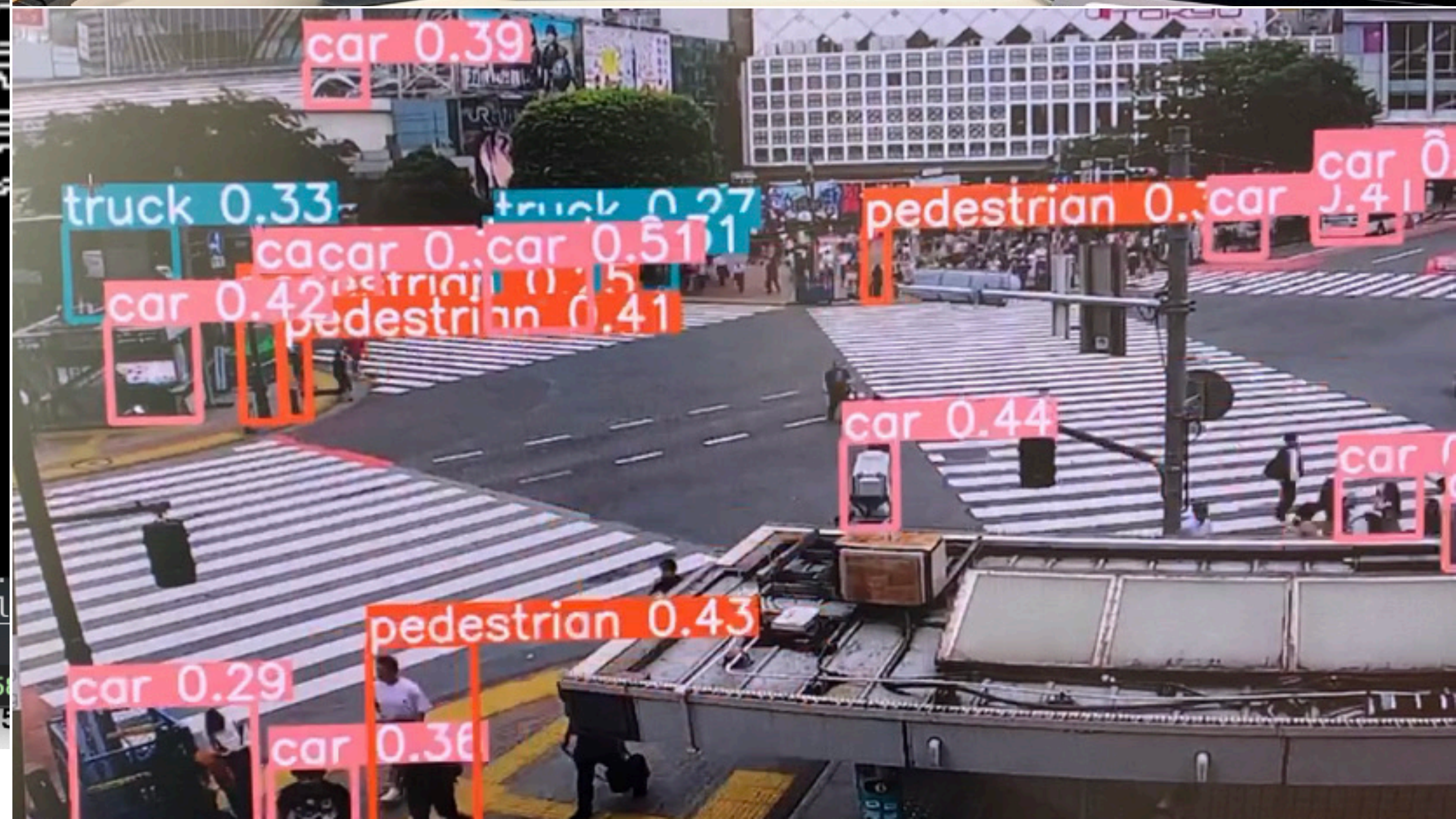


```
test_image.jpg')
(image)
lane_image, cv2.COLOR_RGB2GRAY)
blur(gray, (5, 5), 0)
ur, 50, 150)
blur)
```



python3

10/08 16:12



Motor Control
Object Detection
Lane Detection
Socket Server
Live Streaming
GUI
CNN, GAN, LSTM
...