Ricci Notation

M. Yoon

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1 Index Notation

1.1 Contravariance and Covariance

A p-contravariant-q-covariant component of a tensor T is denoted as $T_{\nu_1\cdots\nu_q}^{\mu_1\cdots\mu_p}$.

1.2 Einstein Summation Convention

Summation over an index appearing once each as upper and lower within a term is denoted without the sum sign. For instance,

$$x_{\mu}e^{\mu} = \sum_{\mu=0 \text{ or } 1}^{n} x_{\mu}e^{\mu}$$

Such indices are said to be dummy indices, otherwise free indices.

1.3 Rasing and Lowering Indices

For a given metric tensor q, an upper index can be lowered or vice versa:

$$\begin{cases} x_{\mu} = g_{\mu\nu} x^{\nu} \\ x^{\mu} = g^{\mu\nu} x_{\nu} \end{cases}$$

2 Symmetrisation and Antisymmetrisation

2.1 Parentheses and Square Brackets

Suppose a tensor $T_{\nu_1...\nu_q}^{\mu_1...\mu_p}$. One can symmetrise $T_{\nu_1...\nu_q}^{\mu_1...\mu_p}$ over the first r indices by summing components about permutated indices divided by r!, with σ a permutation of $\{1, \dots, r\}$, that is,

$$T_{\nu_1 \cdots \nu_q}^{(\mu_1 \cdots \mu_r)\mu_{r+1} \cdots \mu_p} = \frac{1}{r!} \sum_{\sigma} T_{\nu_1 \cdots \nu_q}^{\mu_{\sigma(1)} \cdots \mu_{\sigma(r)} \mu_{r+1} \cdots \mu_p}$$

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Symmetrisation is denoted with parentheses. Similarly, the antisymmetrised component, denoted with square brackets, is given as

$$T_{\nu_1\cdots\nu_q}^{[\mu_1\cdots\mu_r]\mu_{r+1}\cdots\mu_p} = \frac{1}{r!} \sum_{\sigma} \operatorname{sgn}(\sigma) T_{\nu_1\cdots\nu_q}^{\mu_{\sigma(1)}\cdots\mu_{\sigma(r)}\mu_{r+1}\cdots\mu_p}$$

2.2 Parcelling Indices

One can symmetrise or antisymmetrise over discrete indices, using vertical bar notation. Say,

$$T^{(\mu_1 \cdots \mu_s | \mu_{s+1} \cdots \mu_t | \mu_{t+1} \cdots \mu_r) \mu_{r+1} \cdots \mu_p}_{\nu_1 \cdots \nu_q} = \frac{1}{r!} \sum_{\sigma} T^{\mu_{\sigma(1)} \cdots \mu_{\sigma(s)} \mu_{s+1} \cdots \mu_t \mu_{\sigma(t+1)} \cdots \mu_{\sigma(r)} \mu_{r+1} \cdots \mu_p}_{\nu_1 \cdots \nu_q}$$

Where σ is a permutation of $\{1, \dots, s, t+1, \dots r\}$.

3 Kronecker Delta and Levi-Civita Symbol

3.1 The Kronecker Delta

The Kronecker delta δ^{μ}_{ν} is a type (1, 1) tensor whose component is 1 only if $\mu = \nu$, otherwise 0. The Kronecker delta behaves as an 'index reducer', say,

$$\delta^{\mu}_{\nu}x^{\nu} = x^{\mu}$$

3.2 The Anti-Symmetric Tensor Density

The anti-symmetric tensor density $\varepsilon^{\mu_1\cdots\mu_p}=\varepsilon_{\mu_1\cdots\mu_p}$ is defined as

$$\varepsilon^{\mu_1\cdots\mu_p} = \varepsilon_{\mu_1\cdots\mu_p} = \begin{cases} \operatorname{sgn}(\mu), & \mu \text{ is a permutation of } \{1,\cdots p\} \\ 0, & \text{otherwise, i.e., } \mu_i = \mu_j \text{ for some } i \neq j \end{cases}$$

3.3 The Generalised Kronecker Delta

The p-dimensional generalised Kronecker delta $\delta^{\mu_1\cdots\mu_p}_{\nu_1\cdots\nu_p}$ is an (p,p) tensor given as

$$\delta^{\mu_1\cdots\mu_p}_{\nu_1\cdots\nu_p}=\varepsilon^{\mu_1\cdots\mu_p}\varepsilon_{\nu_1\cdots\nu_p}$$

This behaves as an 'index antisymmetrizer', say,

$$\frac{1}{p!}\delta^{\mu_1\cdots\mu_p}_{\nu_1\cdots\nu_p}a^{\nu_1\cdots\nu_p} = a^{[\mu_1\cdots\mu_p]}$$

4 Differentiation

4.1 Partial Derivative

A partial derivative is denoted with ∂ .

$$\partial_{\mu} = \frac{\partial}{\partial \mu}$$

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4.2 Covariant Derivative

A covariant derivative is denoted with ∇ . The components of the covariant derivative $(\nabla_{\nu}Y)^{\mu}$ have been written as $\nabla_{\nu}Y^{\mu}$ for simplicity.

$$\nabla_{\nu} f = \partial_{\nu} f$$

$$\nabla_{\nu} Y^{\mu} = \partial_{\nu} Y^{\mu} + \Gamma^{\mu}_{\nu\rho} Y^{\rho}$$

$$\nabla_{\nu} Y_{\mu} = \partial_{\nu} Y_{\mu} + \Gamma^{\rho}_{\nu\mu} Y_{\rho}$$