



# **GPS & GLONASS Antenna Module YIC51513PGMGG-33**

**Datasheet** 

# YIC5 Series



#### 1. Product Information

#### 1.1 Product Description

YIC51513PGMGG-33 is a complete standalone GPS/GNSS antenna module. It can simultaneously acquire and track multiple satellite constellations that include GPS, GLONASS, GALILEO, QZSS and SBAS. It features low power and small form factor.

YIC51513PGMGG-33 is suitable for the following applications

- Wearable and portable devices
- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

#### 1.2 Product Features

- Very small size with antenna module
- MediaTek high sensitivity solution
- Support 99-channel (33 Tracking, 99 Acquisition)
- Very low power consumption
- Fast TTFF at low signal level
- Built-in 12 multi-tone active interference canceller
- Free hybrid ephemeris prediction to achieve faster cold start
- Built-in data logger
- Built-in DC/DC converter to save power
- Up to 10 Hz update rate
- ±11ns high accuracy time pulse (1PPS)
- Capable of SBAS (WAAS, EGNOS, MSAS, GAGAN)
- Support Japan QZSS
- Indoor and outdoor multi-path detection and compensation



# **1.3 Product Specifications**

| GNSS Receiver           |  |  |  |  |
|-------------------------|--|--|--|--|
| Chip                    | MediaTek   |  |  |  |
| Frequency               |  | GPS, GALILEO, QZSS: L1 1575.42MHz, C/A code GLONASS: L1 1598.0625MHz ~ 1605.375MHz, C/A code |  |  |
| Channels                |  | Tracking, 99 Acquisition)  |  |  |
| Update rate             | 1Hz default, up to 10Hz  |  |  |  |
|                         | Tracking   | -161dBm, up to -165dBm (with external LNA)   |  |  |
| Sensitivity             | Cold start   | -142.5dBm, up to -148dBm (with external LNA)   |  |  |
|                         | Hot start (Open Sky)   | < 1s   |  |  |
| Acquisition Time        | Cold Short (On on Shr)   | < 38s  |  |  |
|                         | Cold Start (Open Sky)  | < 18s with AGPS  |  |  |
| Position                | Autonomous   | 5m (2D RMS).   |  |  |
| Accuracy                | SBAS   | 2.5m (depends on accuracy of correction data).   |  |  |
| Max. Altitude           | < 18,000 m, up to 50,000m by request   |  |  |  |
| Max. Velocity           | Velocity < 515 m/s   |  |  |  |
| Protocol Support        | 9600 bps, 8 data bits, no parity, 1 stop bits (default) 1Hz: GGA, GLL, GSA, GSV, RMC, V7 |  |  |  |
| Physical Characteristic |  |  |  |  |
| Dimensions              | 15.0.0mm * 13.0 mm * 6.8mm ±0.2mm  |  |  |  |

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#### 1.4 DC Electrical Characteristics

| Parameter                    | Symbol | Conditions                                   | Min. | Тур.                           | Max.               | Unit<br>s            |
|------------------------------|--------|--|------|--------------------------------|--------------------|----------------------|
| Input Voltage                | VCC    |  | 3.0  | 3.3                            | 4.3                | V                    |
| Input Backup Battery Voltage | V_BCKP |  | 2.0  |                                | 4.3                | V                    |
| Supply Current               | Iss    | VCC = 3.3V Peak Acquisition Tracking Standby |      | 31<br>24 <sup>(2)</sup><br>600 | 150 <sup>(1)</sup> | mA<br>mA<br>mA<br>uA |
| Backup Battery Current       | Ibat   | VCC = 0V                                     |      | 7                              |                    | uA                   |
| High Level Input Voltage     | VIH    |  | 2.0  |                                | 3.6                | V                    |
| Low Level Input Voltage      | VIL    |  | -0.3 |                                | 0.8                | V                    |
| High Level Input Current     | IIH    | no pull-up or down                           | -1   |                                | 1                  | uA                   |
| Low Level Input Current      | IIL    | no pull-up or down                           | -1   |                                | 1                  | uA                   |
| High Level Output<br>Voltage | VOH    |  | 2.4  |                                | 3.3                | V                    |
| Low Level Output<br>Voltage  | VOL    |  |      |                                | 0.4                | V                    |
| High Level Output Current    | ЮН     |  |      | 2                              |                    | mA                   |
| Low Level Output<br>Current  | IOL    |  |      | 2                              |                    | mA                   |

Note 1: This happens when downloading AGPS data to module.

**Note 2:** Measured when position fix (1Hz) is available, input voltage is 3.3V and the function of self-generated ephemeris prediction is inactive.

## Temperature characteristics

| Parameter                | Symbol | Min. | Тур. | Max. | Units  |
|--------------------------|--------|------|------|------|--|
| Operating<br>Temperature | Topr   | -40  | 25   | 85   | $^{\circ}\!\mathbb{C}$   |
| Storage Temperature      | Tstg   | -40  | 25   | 85   | $^{\circ}\!$ |

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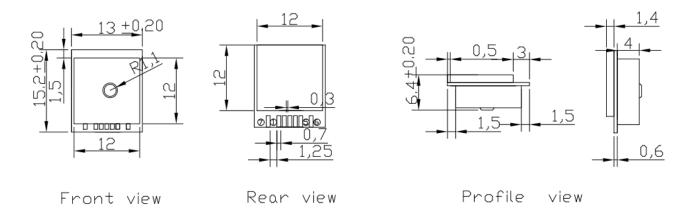
# 2. Technical Information

# 2.1 Module Pin Assignment



| Pin NO. | Pin Name | I/O | Remark  |  |
|---------|----------|-----|---|--|
| 1.      | VBAT     | ı   | RTC Battery Input                                       |  |
| 2.      | TXD      | 0   | UART/TTL Serial Data Output ,Pull up (75KΩ) if not used |  |
| 3.      | RXD      | ı   | UART/TTL Serial Data Input, Pull up (75KΩ) if not used. |  |
| 4.      | VCC      | ı   | Module Power Supply                                     |  |
| 5       | GND      | G   | Ground  |  |
| 6       | PPS      | 0   | Time Pulse(1PPS)  |  |
| 7       | GPIO1    | I/O | General purpose I/O                                     |  |

#### 2.2 Dimensions

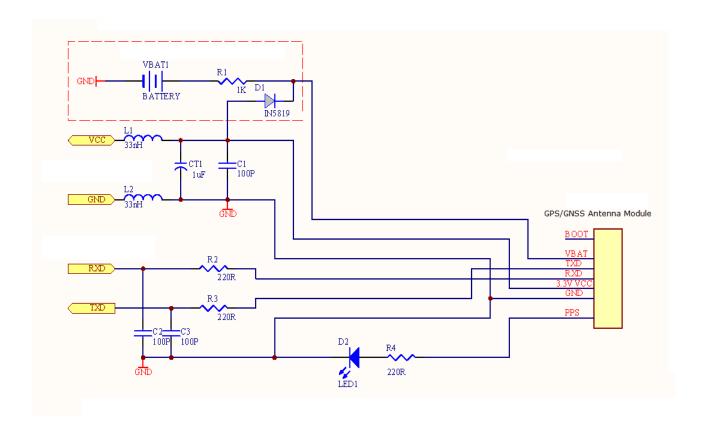


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# 3. Application Circuit : (Example)



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## 4. Software Protocol

# NMEA output message

Table 4.1 NMEA output message

| NMEA | Description                              |  |
|------|--|--|
| GGA  | Global positioning system fixed data     |  |
| GLL  | Geographic position - latitude/longitude |  |
| GSA  | GNSS DOP and active satellites           |  |
| GSV  | GNSS satellites in view                  |  |
| RMC  | Recommended minimum specific GNSS data   |  |
| VTG  | Course over ground and ground speed      |  |

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# GGA--- Global Positioning System Fixed Data

Table 4.2 contains the values for the following example:

\$GPGGA,060406.000,2503.7148,N,12138.7451,E,2,17,0.71,116.7,M,15.3,M,0000,0000\*6D

Table4. 2 GGA Data Format

| Name                   | Example    | Units  | Description                       |
|------------------------|------------|--------|-----------------------------------|
| Message ID             | \$GPGGA    |        | GGA protocol header               |
| UTC Time               | 060406.000 |        | hhmmss.sss                        |
| Latitude               | 2503.7148  |        | ddmm.mmmm                         |
| N/S indicator          | N          |        | N=north or S=south                |
| Longitude              | 12138.7451 |        | dddmm.mmmm                        |
| E/W Indicator          | Е          |        | E=east or W=west                  |
| Position Fix Indicator | 2          |        | See Table 4.3                     |
| Satellites Used        | 17         |        | Range 0 to 33                     |
| HDOP                   | 0.71       |        | Horizontal Dilution of Precision  |
| MSL Altitude           | 116.7      | mters  |                                   |
| Units                  | M          | mters  |                                   |
| Geoid Separation       | 15.3       | mters  |                                   |
| Units                  | М          | mters  |                                   |
| Age of Diff. Corr.     | 0000       | second | Null fields when DGPS is not used |
| Diff. Ref. Station ID  | 0000       |        |                                   |
| Checksum               | *6D        |        |                                   |
| <cr> <lf></lf></cr>    |            |        | End of message termination        |

Table4.3 Position Fix Indicators

| Value | Description                           |  |  |  |
|-------|---------------------------------------|--|--|--|
| 0     | Fix not available or invalid          |  |  |  |
| 1     | GPS SPS Mode, fix valid               |  |  |  |
| 2     | Differential GPS, SPS Mode, fix valid |  |  |  |
| 3-5   | Not supported                         |  |  |  |
| 6     | Dead Reckoning Mode, fix valid        |  |  |  |

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GLL--- Geographic Position – Latitude/Longitude

Table 4.4 contains the values for the following example:

\$GNGLL,2503.7148,N,12138.7451,E,060406.000,A,D\*46

Table3.4 GLL Data Format

| Name                | Example    | Units | Description  |
|---------------------|------------|-------|--|
| Message ID          | \$GNGLL    |       | GLL protocol header (GPGLL or GNGLL; GP indicates the device receives GPS satellites signal only and GN indicates the position is calculated with BEIDOU satellite signal) |
| Latitude            | 2503.7148  |       | ddmm.mmmm  |
| N/S indicator       | N          |       | N=north or S=south   |
| Longitude           | 12138.7451 |       | dddmm.mmmm   |
| E/W indicator       | E          |       | E=east or W=west   |
| UTC Time            | 060406.000 |       | hhmmss.sss   |
| Status              | А          |       | A=data valid or V=data not valid   |
| Mode                | D          |       | A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator   |
| Checksum            | *46        |       |  |
| <cr> <lf></lf></cr> |            |       | End of message termination   |

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#### **GSA---GNSS DOP and Active Satellites**

Table 4.5 contains the values for the following example:

\$GNGSA,A,3,22,21,18,12,24,25,14,15,193,,,,1.18,0.71,0.95\*2C

\$GNGSA,A,3,205,207,210,202,201,203,209,208,,,,,1.18,0.71,0.95\*1C

Table3. 5 GSA Data Format

| Name                 | Example | Units | Description                                    |
|----------------------|---------|-------|--|
|                      |         |       | GSA protocol header (GNGSA or GPGSA; GP        |
|                      |         |       | indicates the device receives GPS satellites   |
|                      |         |       | signal only and GN indicates the position is   |
| Message ID           | \$GNGSA |       | calculated with BEIDOU satellite signal).First |
|                      |         |       | row of GSA message contains GPS & QZSS         |
|                      |         |       | satellites and second row of GSA message       |
|                      |         |       | contains BEIDOU satellites.                    |
| Mode 1               | А       |       | See Table 4.6                                  |
| Mode 2               | 3       |       | See Table 4.7                                  |
| ID of satellite used | 22      |       | Sv on Channel 1                                |
| ID of satellite used | 21      |       | Sv on Channel 2                                |
|                      |         |       |  |
| ID of satellite used |         |       | Sv on Channel 12                               |
| PDOP                 | 1.18    |       | Position Dilution of Precision                 |
| HDOP                 | 0.71    |       | Horizontal Dilution of Precision               |
| VDOP                 | 0.95    |       | Vertical Dilution of Precision                 |
| Checksum             | *2C     |       |  |
| <cr> <lf></lf></cr>  |         |       | End of message termination                     |

#### Table 4.6 Mode 1

| Value | Description                                     |  |  |
|-------|---|--|--|
| M     | Manual- forced to operate in 2D or 3D mode      |  |  |
| А     | Automatic-allowed to automatically switch 2D/3D |  |  |

#### Table 4.7 Mode 2

| Value | Description       |  |  |
|-------|-------------------|--|--|
| 1     | Fix not available |  |  |
| 2     | 2D                |  |  |
| 3     | 3D                |  |  |

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#### **GSV---GNSS Satellites in View**

Table 4.8 contains the values for the following example:

\$GPGSV,6,1,21,18,78,169,36,209,72,273,36,22,63,309,38,207,63,328,38\*7B

\$GPGSV,6,2,21,203,58,205,39,25,56,138,39,201,55,141,34,206,50,168,\*45

\$GPGSV,6,3,21,210,49,282,34,12,48,076,39,204,39,118,,14,38,322,37\*77

\$GPGSV,6,4,21,193,37,180,34,202,36,246,29,24,23,041,34,31,21,244,\*71

\$GPGSV,6,5,21,21,17,198,33,205,16,258,28,15,12,092,33,208,09,169,30\*7B

\$GPGSV,6,6,21,51,,,\*7E

#### Table 4.8 GSV Data Format

| Name                      | Example | Units   | Description   |
|---------------------------|---------|---------|---|
| Message ID                | \$GPGSV |         | GSV protocol header   |
| Total number of messages1 | 6       |         | Range 1 to 6  |
| Message number1           | 1       |         | Range 1 to 6  |
| Satellites in view        | 21      |         |   |
| Satellite ID              | 18      |         | Channel 1 (Range 01 to 237), GPS Satellites ID: 01~32,SBAS Satellites ID: 33~64, QZSS Satellites ID:193~196, &BEIDOU Satellites ID: 201~214 |
| Elevation                 | 78      | degrees | Channel 1 (Range 00 to 90)  |
| Azimuth                   | 169     | degrees | Channel 1 (Range 000 to 359)  |
| SNR (C/No)                | 36      | dB-Hz   | Channel 1 (Range 00 to 99, null when not tracking)  |
| Satellite ID              | 207     |         | Channel 4 (Range 01 to 237), GPS Satellites ID: 01~32,SBAS Satellites ID: 33~64, QZSS Satellites ID:193~196, &BEIDOU Satellites ID: 201~214 |
| Elevation                 | 63      | degrees | Channel 4 (Range 00 to 90)  |
| Azimuth                   | 328     | degrees | Channel 4 (Range 000 to 359)  |
| SNR (C/No)                | 38      | dB-Hz   | Channel 4 (Range 00 to 99, null when not tracking)  |
| Checksum                  | *7B     |         |   |
| <cr> <lf></lf></cr>       |         |         | End of message termination  |

Depending on the number of satellites tracked multiple messages of GSV data may be required.



RMC---Recommended Minimum Specific GNSS Data

Table 4.9 contains the values for the following example:

\$GNRMC,060406.000,A,2503.7148,N,12138.7451,E,0.01,0.00,180313,,,D\*78

Table 4.9 RMC Data Format

| Name                | Example    | Units   | Description  |
|---------------------|------------|---------|--|
| Message ID          | \$GNRMC    |         | RMC protocol header (GNRMC or GPRMC; GP indicates the device receives GPS satellites signal only and GN indicates the position is calculated with BEIDOU satellite signal) |
| UTC Time            | 060406.000 |         | hhmmss.sss   |
| Status              | А          |         | A=data valid or V=data not valid   |
| Latitude            | 2503.7148  |         | ddmm.mmmm  |
| N/S Indicator       | N          |         | N=north or S=south   |
| Longitude           | 12138.7451 |         | dddmm.mmmm   |
| E/W Indicator       | E          |         | E=east or W=west   |
| Speed over ground   | 0.01       | knots   | True   |
| Course over ground  | 0.00       | degrees |  |
| Date                | 180313     |         | ddmmyy   |
| Magnetic variation  |            | degrees |  |
| Variation sense     |            |         | E=east or W=west (Not shown)   |
| Mode                | D          |         | A=autonomous, D=DGPS, E=DR, N=Data not valid,R=Coarse Position, S=Simulator  |
| Checksum            | *78        |         |  |
| <cr> <lf></lf></cr> |            |         | End of message termination   |

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VTG---Course Over Ground and Ground Speed

Table 4.10 contains the values for the following example:

\$GPVTG,0.00,T,,M,0.01,N,0.02,K,D\*3B

Table 4.10 VTG Data Format

| Name                | Example | Units       | Description   |
|---------------------|---------|-------------|---|
| Message ID          | \$GPVTG |             | VTG protocol header   |
| Course over ground  | 0.00    | degree<br>s | Measured heading  |
| Reference           | Т       |             | True  |
| Course over ground  |         | degree<br>s | Measured heading  |
| Reference           | М       |             | Magnetic  |
| Speed over ground   | 0.01    | knots       | Measured speed  |
| Units               | N       |             | Knots   |
| Speed over ground   | 0.02    | km/hr       | Measured speed  |
| Units               | K       |             | Kilometer per hour  |
| Mode                | D       |             | A=autonomous, D=DGPS, E=DR, N=Data not valid,R=Coarse Position, S=Simulator |
| Checksum            | *3B     |             |   |
| <cr> <lf></lf></cr> |         |             | End of message termination  |

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