

The design and construction of the MICE Electron-Muon Ranger

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Abstract

The Electron-Muon Ranger (EMR) is a fully-active tracking-calorimeter installed in the beam line of the Muon Ionization Cooling Experiment (MICE). The experiment will demonstrate ionization cooling, an essential technology needed for the realization of a Neutrino Factory and/or a Muon Collider. The EMR is designed to measure the properties of low energy beams composed of muons, electrons and pions, and perform the identification particle-by-particle. The detector consists of 48 orthogonal layers of 59 triangular scintillator bars. The readout is based on FPGA custom made electronics and commercially available modules. This article describes the construction of the detector from its design up to its commissioning with cosmic data.

1 Introduction

1.1 Ionization cooling

The Neutrino Factory [1, 2] based on a high-energy muon storage-ring is the ultimate tool to study the neutrino mixing matrix and is established as the best facility to discover, and study the possible leptonic CP violation. It will produce the most intense, pure and focused neutrino beam ever achieved and is also the first step towards a $\mu^+\mu^-$ collider [3, 4]. The Neutrino Factory accelerator design uses muons as a neutrino source. A proton beam bombards a target to produce pions. These pions are captured and focused in a high-field solenoid channel and decay to muons, creating a low energy muon beam with very large emittance. The emittance of the muons needs to be reduced, i.e. the muon beam must be “cooled”, so that the beam can be accelerated efficiently.



Figure 1: Ionization cooling chronology: (1) energy loss by ionization (dE/dx reduces p_L and p_T), (2) heating through multiple scattering and (3) p_L restored by RF cavities.

Ionization cooling [5], summarised in figure 1, provides the only practical solution to muon cooling, because it is fast enough to cool the beam within the short muon lifetime ($\tau_\mu \sim 2.2 \mu\text{s}$). The emittance reduction is achieved by passing muons through a low-Z material (absorber), in which they lose energy via ionization, reducing both their longitudinal and transverse momentum. The longitudinal component is restored by accelerating cavities, providing a net reduction of the beam emittance. To maximize cooling, the absorber must be placed at a position where the transverse momentum p_T has a maximum, i.e. at a minimum of the transverse betatron function, β_\perp .

30 1.2 MICE

The international Muon Ionization Cooling Experiment (MICE) [6] is under development at the Rutherford Appleton Laboratory (UK). The goal of the experiment is to build a section of a cooling channel that can demonstrate the principle of ionization cooling.

Since energy loss and multiple Coulomb scattering are momentum dependent, so is the ionization cooling effect. MICE uses variety of muon beams of limited intensity and central momenta in the range 140–240 MeV/ c with a spread of ~ 20 MeV/ c . These muon beams are generated using a titanium target [7] dipped into the ISIS proton beam [8]. Secondary and tertiary particles are captured, momentum-selected and transported to the cooling section by a system of magnets: a 5 T superconducting decay solenoid, two dipoles, nine quadrupoles and a mechanism for inflation of the initial emittance, the diffuser.

The cooling section of MICE is similar to the one of the International Design Study for the Neutrino Factory and is schematically represented in figure 2. It consists of one primary lithium-hydride (LiH) absorber, two secondary absorbers, two focus coils and two 201 MHz RF cavities. The two superconducting focus-coil modules provide strong focusing at the absorber, ensuring that the transverse betatron function is minimised at this position and enhancing the cooling effect. Each particle is detected individually by two identical Scintillating fibre trackers in 4 T solenoids, situated upstream and downstream of the cooling section. The beam emittance is reconstructed by measuring the position and momentum (x, y, p_x, p_y, p_z) of each muon.

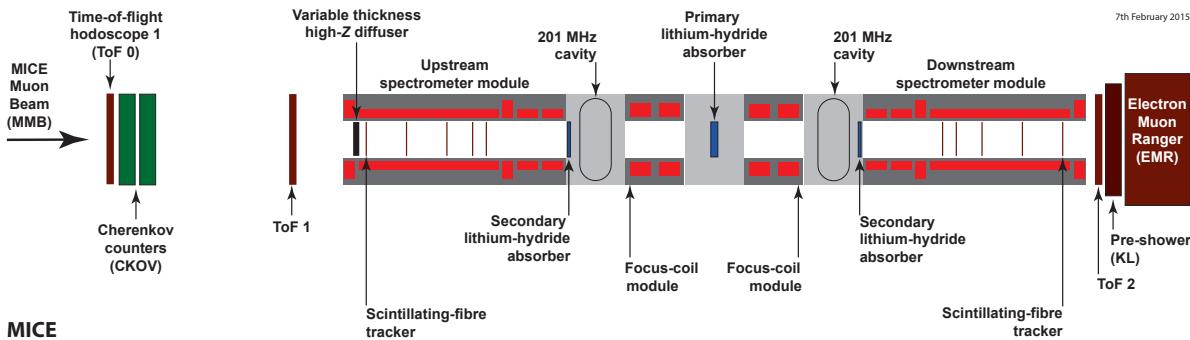


Figure 2: Schematic view of the MICE experiment.

The particle content of the beam is measured by a dedicated system of detectors situated upstream and downstream of the cooling channel and designed to provide precise muon, pion and electron identification. The upstream part includes two time-of-flight hodoscopes (TOF0 and TOF1 [9]) and a Cherenkov detectors (Ckov [10]). The downstream part combines another time-of-flight hodoscope (TOF2 [11]) with a calorimeter system. The calorimeter system consists of the KLOE-Light (KL [10]) lead-scintillator sampling calorimeter, operating as a preshower for the totally-active Electron-Muon Ranger (EMR [12]), placed behind it.

MICE will measure the normalised transverse emittance ϵ_N with a precision of $\sigma_{\epsilon_N}/\epsilon_N \sim 0.1\%$ and is expected to witness a $\sim 6\%$ cooling for a muon beam with a nominal momentum of 200 MeV/ c and a 4D input normalised emittance of $\epsilon_N = 5.8\pi \cdot \text{mm} \cdot \text{rad}$.

1.3 Electron-Muon Ranger (EMR)

The EMR is a fully-active scintillator detector. It can be classified as tracking-calorimeter as its granularity allows for track reconstruction. The primary purpose of the detector is to distinguish muons from their decay products, rejecting events in which the muon decayed in-flight in the cooling

section. This allows for the selection of a muon beam with contamination below 1 %. The range of the muon track can be measured, providing an estimate of the momentum of the muon.

The construction of the detector started in the early 2011 and in October 2013 the detector was fully commissioned with beam during one month of dedicated data-taking at RAL. The detector was upgraded in October 2014, including the replacement of the single-anode photo-multiplier tubes and the installation of a new high-voltage power supply.

2 Design

The EMR is built of triangular scintillator bars arranged in planes. One plane contains 59 bars and covers an area of 1.27 m^2 . Each even bar is rotated by 180 degrees with respect to the odd one. A cross-section of bars and their arrangement in a plane is shown in figure 3. This configuration there does not leave dead area for particles crossing a plane with angles less than 45 degrees with respect to the beam axis.

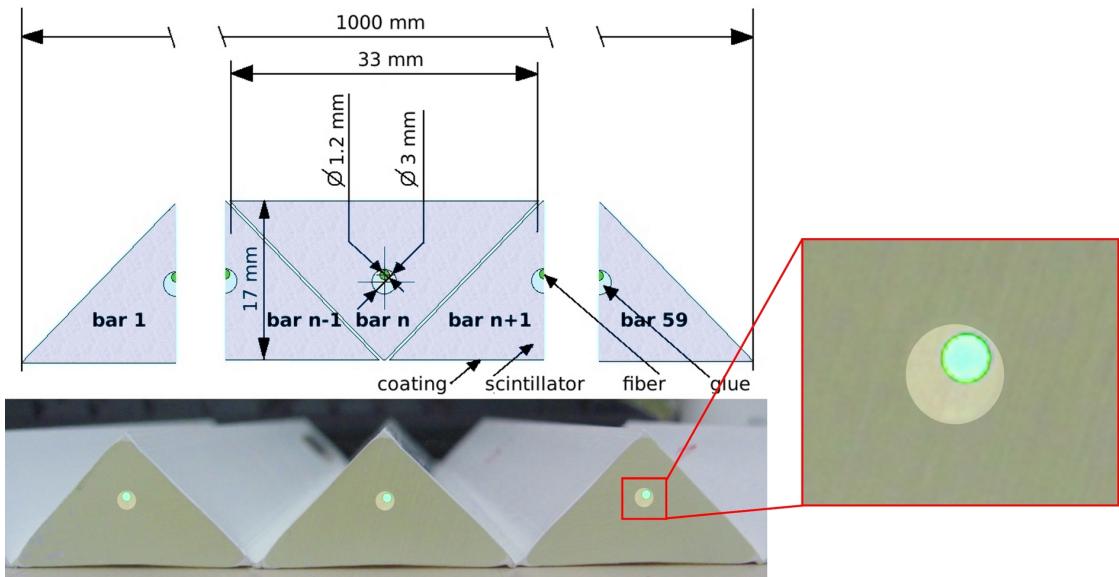


Figure 3: EMR bar cross-section and their arrangement in a plane.

The light, produced when a particle crosses a bar, is collected by a wave-length shifting (WLS) fibre glued inside the bar. At both ends, the WLS fibre is coupled to clear fibres that transport the light to a photo-multiplier (PMT). The clear fibres are protected with rubber sleeves and packed in aluminium fibre boxes as drawn in figure 4. In order to increase the bending radius, which affects light attenuation, each fibre has an individual length. The two bunches of clear fibres coming from the two sides of a plane are glued into different types of connectors 5. One is designed to match a multi-anode PMT and the other a single-anode PMT.

Two planes attached to each other via aluminum profiles form a rigid structure called module (figure 6). The full detector contains 24 modules as shown in figure 7. Panels cover all sides of the detector in order to insure a light-tightness. The signals coming from a multi-anode PMT are read out and processed by a dedicated front-end board attached directly to the fibre box as shown in figure 6. The single anode PMTs are equipped with a voltage divider and the analog signal is sent outside the detector for digitization.

A calibration system was installed inside the enclosure of the detector in order to monitor the

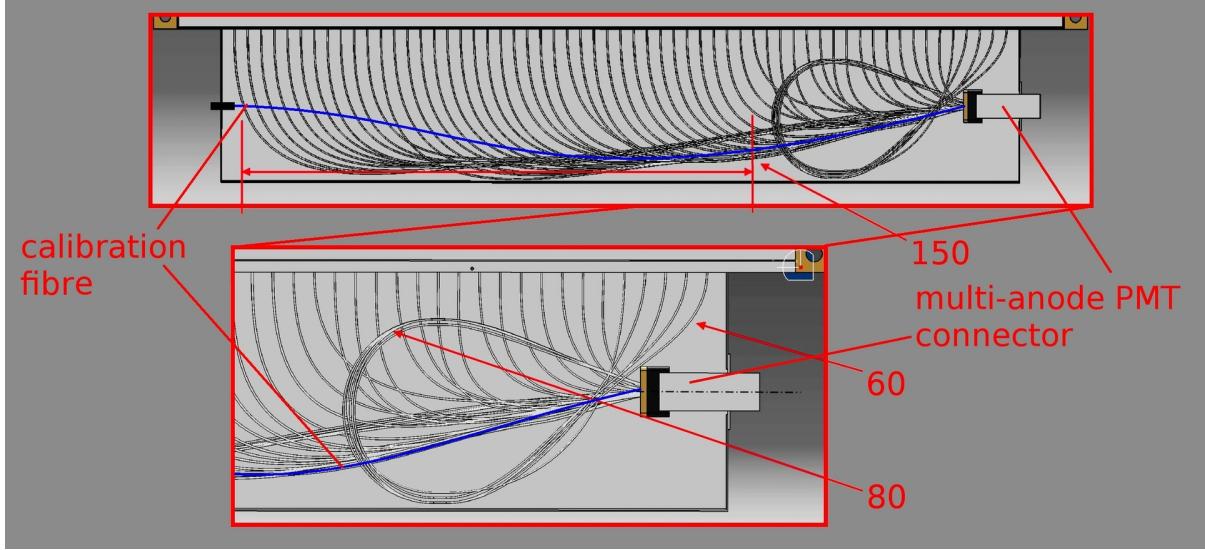


Figure 4: Clear fibre arrangement in a fibre box on the multi-anode PMT side. The bending radii of a selected few fibres are indicated in red.

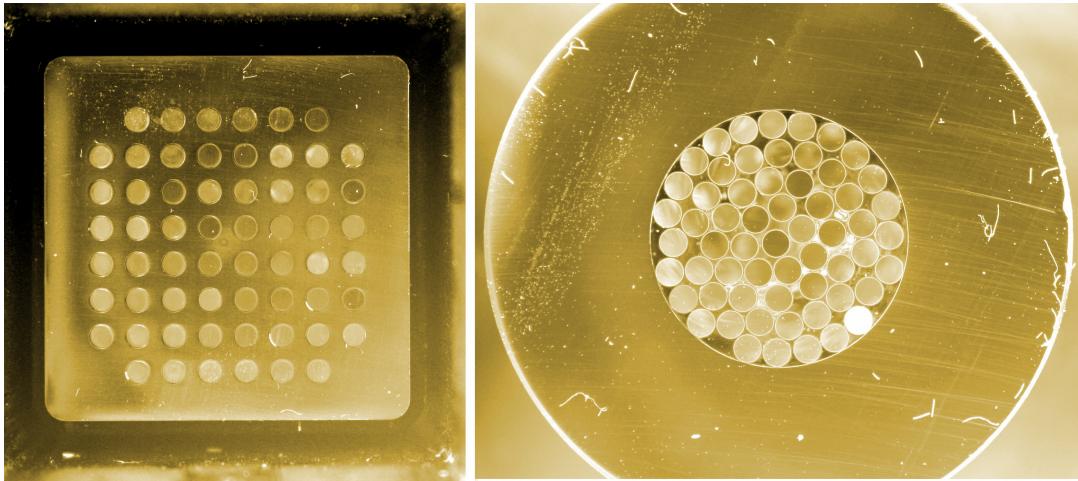


Figure 5: Multi-anode PMT connector (left) and single-anode PMT connector (right).

drift of the gain and the quantum efficiency of the PMTs. This system is made of a LED driver distributing light homogeneously to 100 fibre. Each fibre box is connected to one of the calibration fibres through a connector. Inside a fibre box a clear fibre connects the calibration fibre to the PMT (see figure 4).

All the cables inside the detector are fed through four patch-panels. There are 96 high-voltage, 6 low-voltage, 48 analog, 48 digital, and three configuration cables in total. A support frame is designed to withhold the full weight of the sensitive volume (~ 1 tonne) with its readout system. In order to protect the front-end electronics from the magnetic field of the spectrometer solenoid, a shielding plate is mounted on the side of the detector that faces the beam. The total weight of the detector is almost 2.5 tonnes.

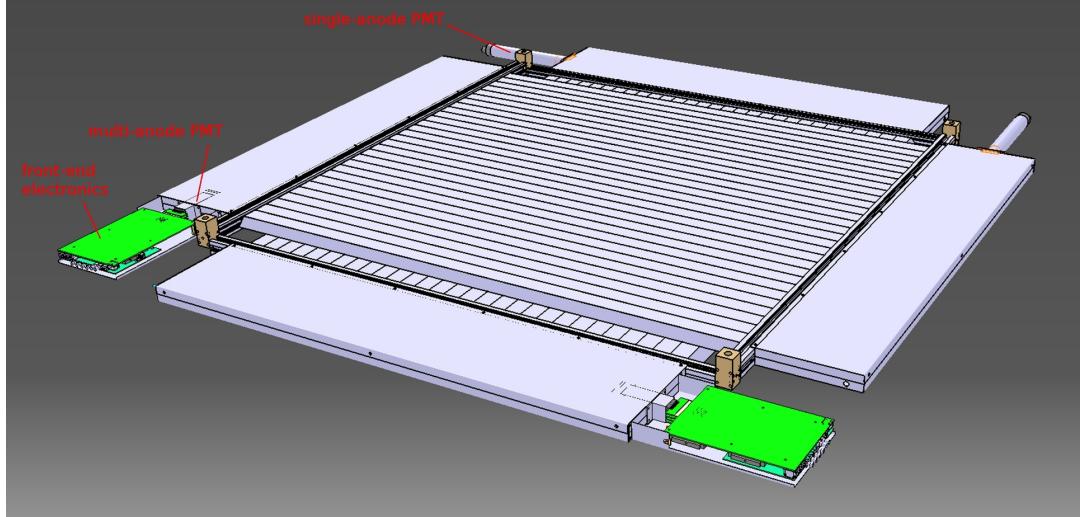


Figure 6: CAD drawing of one EMR module made of an X plane and a Y plane. There are two front-end boards and two single-anode PMTs per module.

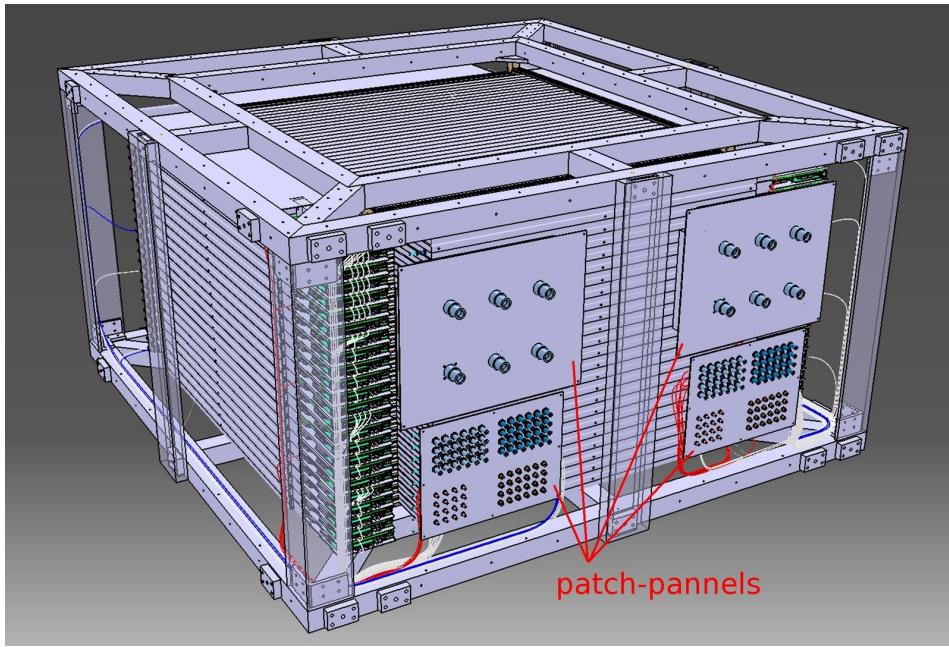


Figure 7: CAD drawing of the EMR detector. The external protective panels are not shown.

2.1 Optical Elements

The scintillator bars were manufactured at an extrusion facility at Fermilab [13]. Each bar is 110 cm long, has a triangular, 1.7 cm high, 3.3 cm wide section and is pierced with a 3 mm hole to host a wavelength shifting fibre. The scintillator is made of polystyrene pellets¹ as base, 1% PPO² as primary and 0.03% POPOP³ as secondary fluor. Each bar is coated with TiO₂ reflector in order

¹Dow Styron 663 W

²Scintillator, 2,5-diphenyloxazole, C₁₅H₁₁NO

³Wavelength shifter, 1,4-di-(5-phenyl-2-oxazolyl)-benzene, C₂₄H₁₆N₂O, spectrum peaks at 410 nm (violet)

to increase the trapping efficiency. The light output of the scintillator was measured [13] with a
105 photo-multiplier (25% quantum efficiency) and it is around 17 photo-electrons.

The WLS fibre glued inside each bar is a double-cladding 1.2 mm fibre produced by Saint-Gobain Crystals [16]. The core material polystyrene with acrylic cladding. It has a larger numerical aperture of 0.58 compared to the 0.2–0.3 of graded-index multi-mode fibres used in data communication. Their trapping efficiency is 3.5 %. The light is absorbed in the blue part of the visible spectrum and
110 re-emitted in green.

The clear fibres, used to transfer light from the ends of scintillator bar to the PMTs, are 1.5 mm multi-cladding fibres produced by Kuraray [17] with a special structure (S-type) that allows for better flexibility. The aperture of this fibre matches the one of WLS fibre to ensure a minimal transmission loss.
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A special connector was designed to couple the clear fibre to the WLS fibre [25] and is represented in figure 8. It has a small cylindrical enlargement meant to be filled with glue to fix the fibre in the connector. This configuration avoid crimping the fibre since a sharp edge of the connector would easily damage it. The retaining clip (B) is screwed into the wavelength shifting fibre connector (A) to allow the clear fibre connector (C) to be safely attached. All these pieces are non-standard and
120 a special mold was designed to produce them.

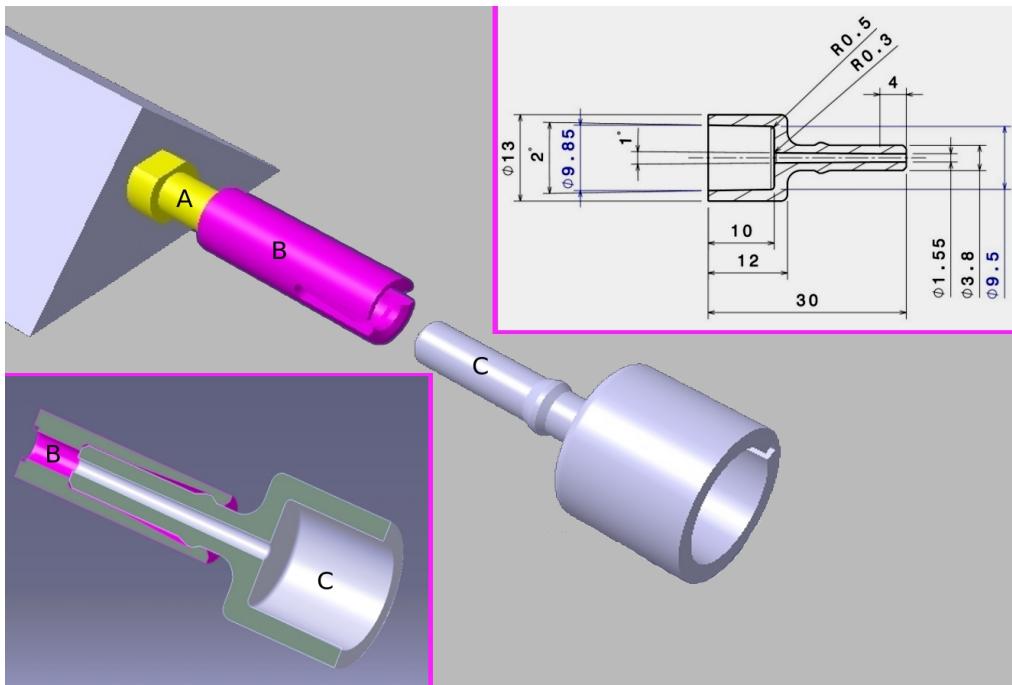


Figure 8: WLS to clear fibre coupling: a clear fibre connector (C) is attached to the wavelength shifting fibre connector (A) using a retaining clip (B).

2.2 Photo-detectors

The EMR has a dual readout. Each scintillator plane is equipped with a multi-anode PMT (MAPMT), measuring the light output of individual bars, and a single-anode PMT (SAPMT), recording the integrated response of all bars in the plane.
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The MAPMT is a 64-channel PMT produced by Hamamatsu (model R5900-00-M64 [18], as pictured in figure 9). The spectral response matches the peak emission frequency of the wavelength

shifting fibre. It is placed in a μ -metal tube acting as additional shielding against the fringe magnetic field. The PMT is aligned with respect to the fibre connector in such a way that each fibre shines on one channel. It is important to measure the dimensions of the PMT and particularly the position of the anode matrix with respect to the PMT case. Figure 10 shows the distributions of the measured dimensions (width and height) and displacements of the anode matrix for 53 MAPMTs. On average, the matrix is shifted by 0.5 mm upwards, which was taken into account in the design of the MAPMT fibre connectors.

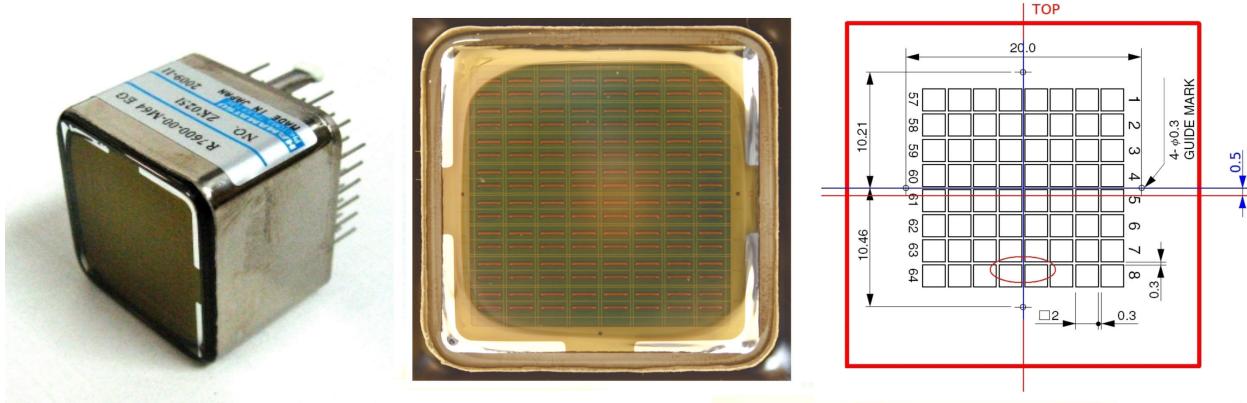


Figure 9: EMR Multi-Anode PMT: picture of the case and pins (left), anode matrix (centre) and anode matrix dimensions and offsets (right).

The SAPMT is also placed in a μ -metal casing. The EMR detector was initially assembled using second hand SAPMTs, available after the disassembly of the HARP experiment [19]. They were 10-stage, linear-focused PMTs produced by Philips (model XP2972). A special selection procedure was developed in order to select the best samples for the assembly of the detector [20]. In 2014, during the upgrade of the detector, all Philips SAPMTs were replaced by new tubes produced by Hamamatsu (model R6427 [18]).

140 2.3 Electronics Layout

In MICE the spill is defined as the short period following a target dip in the ISIS proton beam. The maximum spill rate allowed by the MICE target system is ~ 0.75 Hz. The overall principle of the MICE Data Acquisition (DAQ) system is that, during the spill, the accumulated digital data is kept in local memory buffers and the readout is performed once at the end of the spill.

145 A schematic layout of the EMR electronics is shown in figure 11. The multi-anode PMT is connected via a flex cable to a front-end board (FEB), which processes the signals and sends them to a piggy-back digitizer-buffer board (DBB) for digitization and storage. The FEB is configured by the VME configuration board (VCB), which resides in the VME crate in the control rack. Each board is able to configure up to 16 FEBs, therefore three of them are required for the full detector. The DBBs are readout by groups of six. In each group the first DBB is a master and the other five are slaves. All six boards are daisy-chained via ethernet cable and the master is connected to a VME readout board (VRB), which transfers all the data from the six DBBs to the DAQ computer. In the whole detector there are 8 groups of DBBs, i.e. 8 VRBs are installed in the control rack.

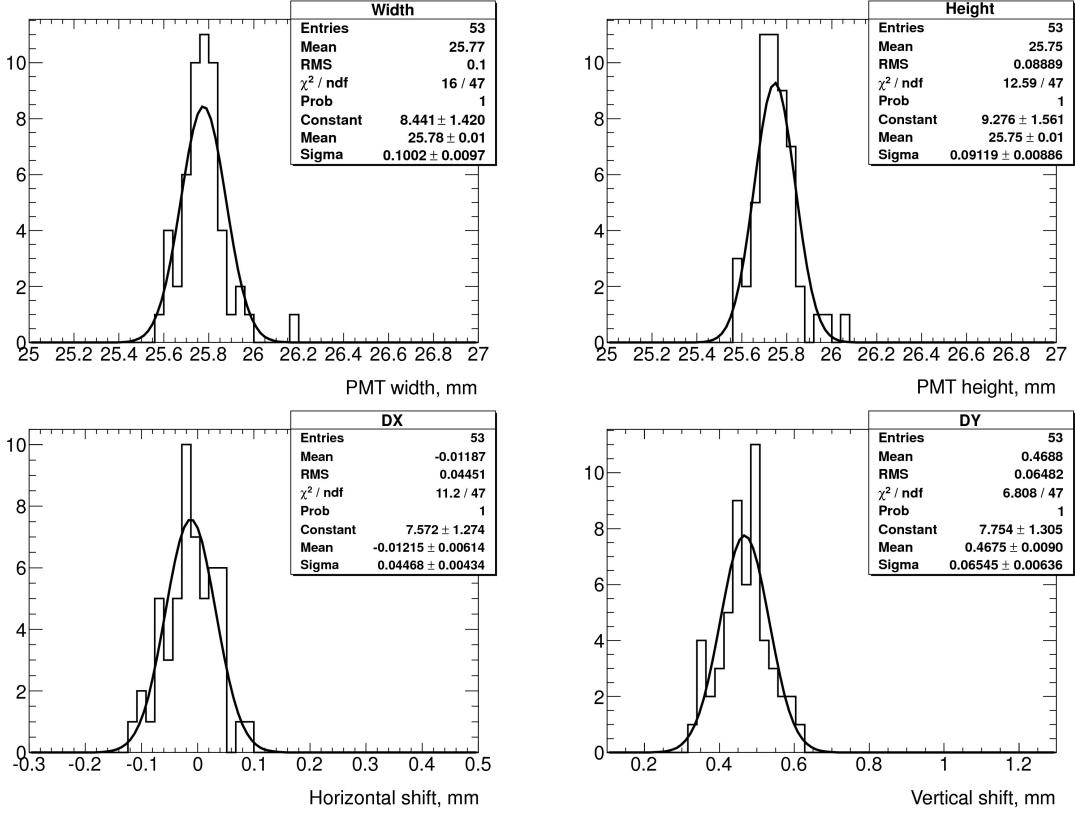


Figure 10: Distribution of Multi-Anode PMT dimensions and offsets.

2.3.1 Front-End and Digitizer-Buffer Boards

155 The multi-anode PMT is readout by a dedicated front-end board equipped with piggy-back digitizer-buffer board [21], which stores hit information during a spill. Figure 12 shows the full assembly that is mounted on each plane of the detector. It consists of a PMT and its voltage divider connected to an FEB through a flex cable. The FEB processes all 64 MAPMT signals using a a 64-channel ASIC⁴ called MAROC⁵[22].

160 The analogue signals are fed into the chip where they are processed in parallel. Each channel consists of a pre-amplifier with a variable gain, a tunable slow shaper for analogue readout, a tunable fast shaper and a discriminator for digital. The MAROC ASIC provides parallel digital outputs forwarded to two high density connectors. The width of the discriminated signal represents the time-over-threshold measurement. One multiplexed analogue output is also provided and this 165 output is digitized by an external ADC⁶. It takes ~ 10 ms to process the multiplexed signals, too slow to keep up with the MICE DAQ duty cycle (~ 1 ms spills). Only the fast time-over-threshold measurement is used and recorded.

The function of the FPGA chip⁷ is mainly to forward data from the MAROC to the DBB and to send configuration signals from the VCB to the MAROC and verify their status. The board has 170 a separate power supply for analogue and digital parts. The total power consumption of the board is about 3 W and operates at 5 V.

⁴ Application-Specific Integrated Circuit

⁵ Multi Anode ReadOut Chip

⁶ Analog Devices AD9220

⁷ Altera Cyclone II (EP2C35F484C8N)

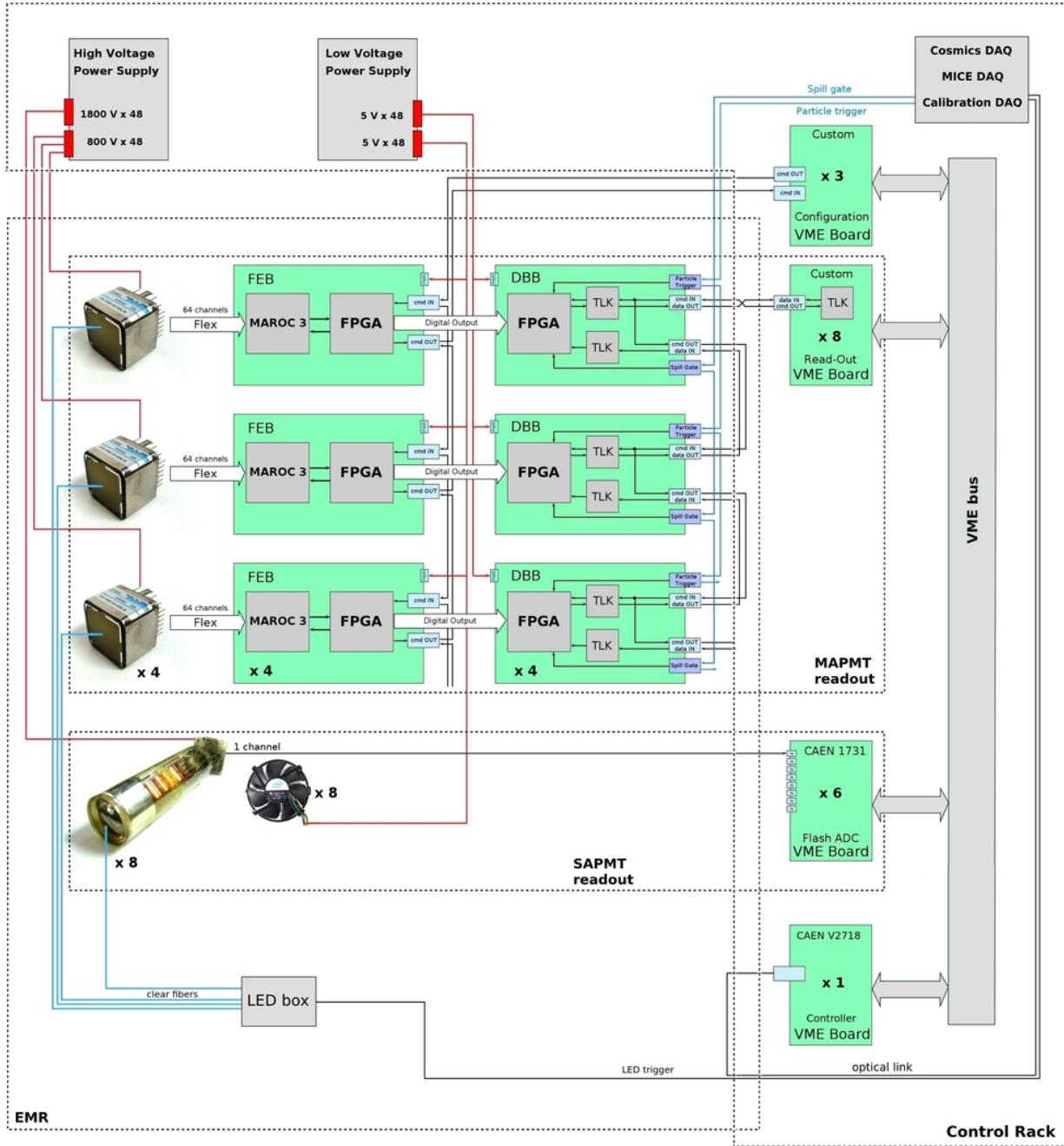


Figure 11: EMR electronics layout. **FEB:** front-end board for multi-anode PMT readout. **DBB:** digitizer-buffer board. **MAROC 3:** 64 channel readout ASIC for multi-anode PMT. **MAPMT:** multi-anode PMT. **SAPMT:** single-anode PMT.

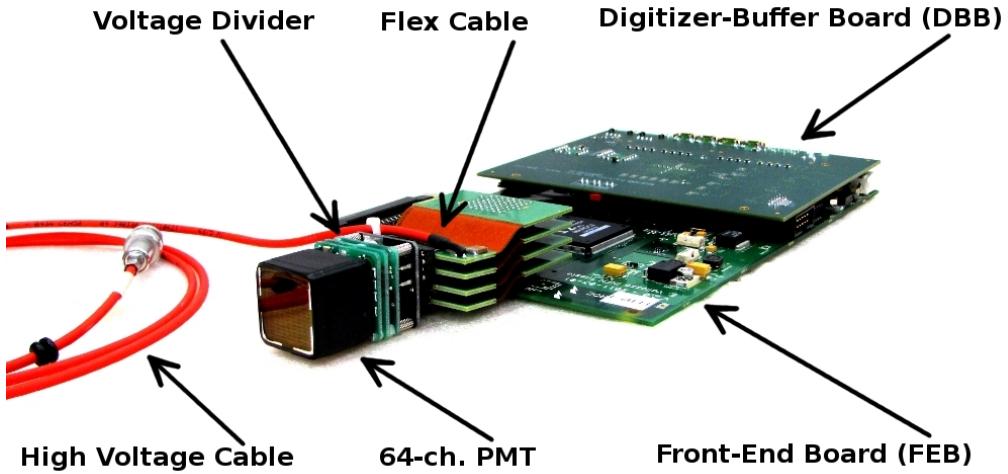


Figure 12: Front-end and Digitizer-Buffer boards assembly.

The two essential roles of the DBB are to sample 63 of the channels coming from the FEB plus an external trigger signal and to store the accumulated digital data during the spill. It also transmits this data upon request from the acquisition system. The digitization starts when the board receives the "Spill Gate" signal from an external LEMO connector. The number of clock ticks from the beginning of the spill to the leading edge and trailing edge of every discriminated signal coming from the FEB is recorded. The difference between two subsequent measurements represents the time-over-threshold of the original signal. The clock sampling rate is 400 MHz (2.5 ns resolution). The external trigger signal is fed into one specific input channels and is treated as any other signal. This signal does not serve as a trigger for the DBB itself, since the board records continuously and all signals arriving within the spill gate are digitized and recorded. The timing of the trigger signal is important to identify the hits that belong to a given particle and to match them with other detectors. The board also calculates the width of each spill, counts the number of spills, the number of triggers in each spill and the number of hits in each channel.

The architecture of the DBB is organized around a single FPGA⁸ that performs the sampling, data buffering and data-flow control functions of the board. The internal memory of the FPGA, configured as FIFO, is used to store the event data. Two gigabit transceivers⁹ are interfaced to the FPGA to provide the physical transmission channels and form an upstream command link and a downstream data link. Six DBB's are grouped together and daisy-chained with upstream and downstream links via Ethernet cables. The first DBB in each group is directly connected to the VRB via four coaxial cables.

2.3.2 VME Configuration Board

The VCB is a single FPGA¹⁰ board designed to configure the MAROC chips on the FEBs. The communication between the two boards is accomplished by LVDS¹¹ signals driven and received by LVDS drivers/receivers connected to a corresponding FPGAs. The MAROC chip is configured by TTL¹² signals composed of 830 bits coding the configuration parameters. The VCB supports

⁸ Altera Stratix II (EP2S30F484C3N)

⁹ TLK1501

¹⁰ Altera Cyclone II (EP2C50F484C8N)

¹¹ Low-Voltage Differential Signaling, communication protocol.

¹² Transistor-Transistor Logic

reading out from the FEB digitized measurement of the MAROC analogue output, but this is not implemented in the current design. The board communicates with the DAQ computer through the VME bus via the VME controller.

200 **2.3.3 VME Read-Out Board**

One VRB performs the readout of a group of six DBBs. It is a single FPGA¹³ board with a gigabit transceiver¹⁴, which drives the communication with the DBBs and four high-speed 16M-bit static RAMs¹⁵, providing a local memory buffer. During the readout cycle, the data transfer between the DBBs and the DAQ computer is executed in two steps. After a request from the DAQ computer, 205 the VRB starts transferring data from the 6 DBBs. The gigabit transceiver is used for this and the received data is temporarily stored locally. The four static RAMs, organized as 16 bits data words, are grouped in two pairs, providing the record of the DBB data, originally structured in 32 bits data words. Once the first part of the transfer is completed and all the data accumulated by the 6 DBBs during the spill is available in the local memory buffer of the VRB, the DAQ computer sends 210 a second request which triggers the transfer of this data over the VME bus.

2.3.4 Flash ADC Board

A waveform digitizer V1731, made by CAEN [23] is used to read out signals from the single-anode PMTs. The digitizer has a sampling frequency of 500 MHz (2 ns timing resolution). The pulse shape of the input signal is digitized by an 8-bit ADC and continuously written in a circular memory 215 buffer. When a trigger is received the FPGA writes a certain number samples into the buffer, which then is available for readout via the VME bus.

2.4 Mechanics

The total weight of the sensitive volume of the detector is almost 1 tonne. During construction and installation, it was required to be rotated and transported from Geneva to the UK. A reinforced 220 support frame, represented in figure 13, was design to withstand the weight of the sensitive detector and the stress coming from the transportation and installation. In its final position, the EMR is installed such that planes are located perpendicular to a beam direction.

Figure 14 shows the location of the sensitive volume with respect to the support frame. The frame is covered with panels so that the entire detector is light-tight. A 5 cm-thick iron plate is used 225 as magnetic shielding (total weight of ~ 755 kg). The opening in the shielding panel, which matches the size of the sensitive volume, is closed with a thin rubber end cap. The back panel is closed with a metal end cap.

3 Construction

All the construction work was done at the University of Geneva. As exposure to ultra-violet (UV) 230 light or high temperature can damage the polystyrene molecules, activities related to fibres and scintillators were performed in a UV clean room, i.e. lights and windows were covered with UV-protective films, while air conditioning kept the temperature around 25 °C.

¹³Altera Cyclone II (EP2C50F484C8N)

¹⁴TLK1501

¹⁵IS61WV102416BLL-10TLI - SRAM, 16Mbit, 10ns, 48TSOP

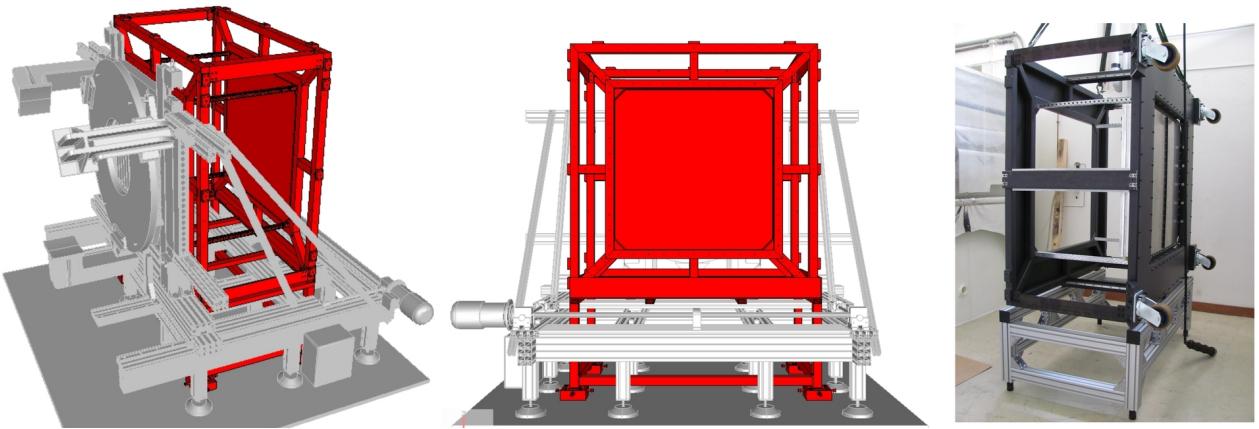


Figure 13: EMR support frame. When installed in the MICE experimental hall, the EMR is integrated into the support structure of the other downstream particle identification detectors.

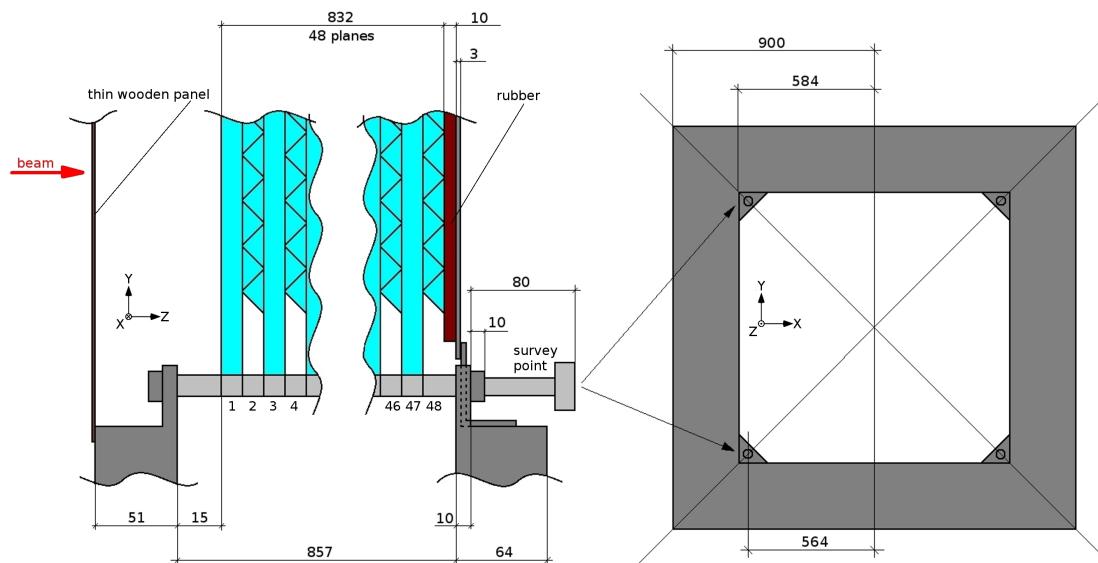


Figure 14: EMR dimensions [mm].

The first step in the construction was to glue the wavelength shifting fibres into the bars. Transparent epoxy¹⁶ was used to glue the WLS fibre in order to increase the light collection efficiency.
235 Although 2832 bars were required for building the full detector, 3150 bars were glued and assembled with fibre connectors in order to provide enough spares. Both faces of the bar's fibre connectors were polished with a custom polishing machine. Four different grades of sand paper are used to achieve a mirror like quality of the polished surfaces. The last step is performed using a $1\text{ }\mu\text{m}$ grade diamond-based polishing paper.

240 Fiber bundles made of 60 clear fibres (see figure 15) were manufactured. In the bundle, each fibre has an individual length, providing a maximum bending radius when connected. A fibre connector (see figure 8, bottom right) is glued at one end of each fibre. At the other end all fibres are glued either in multi-anode or single-anode PMT connector (see figure 5). Once glued, both fibres and connectors are polished on a bench, similar to the one used to polish all bar connectors. In total 96
245 fibre bundles were produced (48 per type of PMTs).



Figure 15: Clear fibre bundle construction: fibres cut to the right lengths (left), an MAPMT connector (centre) and its fibre connectors (right).

3.1 Quality Tests

Numerous quality test were implemented, in order to assure the best possible performance of the different components of the detector.

A dedicated bar quality test bench was constructed in order to test the light transmission of each
250 bar, including the transmission of the WLS fibre and the quality of the two connectors. The test bench consisted of an LED¹⁷ system, a holder for 4 scintillator bars and a digital camera placed in a light-tight box. The LED system included a blue LED source, a light mixing box and diffusers to provides an homogeneous light signal in the four bars. The camera takes a photo of the four connectors at the opposite side of the bars. One of the bars is considered to be the reference and
255 so that the other measurements are normalized to it. This takes into account the effect of any LED instability and allows to compare different measurements.

An automated program was used to analyse the photos (figure 16, left) and calculate the luminosity of each bar. The right plot in figure 16 shows the distribution of the measured relative residuals of the light output with respect to the reference bar. The relative residual is defined as the
260 difference between the measured value and the average value normalised by the average. Only bars with a relative residual intensity above -0.15 were accepted for plane assembly. A fraction of 9.7% of the 3150 bars did not pass that requirement and were rejected.

A similar test was used to examine each EMR plane after the assembly [24]. An LED tube attached to a single-anode PMT connector was used to send light through the fibres (WLS and

¹⁶Prochima E30 water effect resin

¹⁷Light Emitting Diode

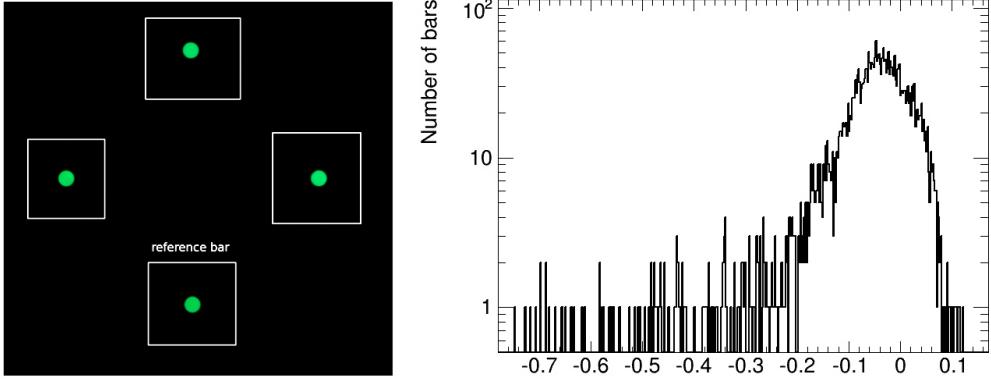


Figure 16: Bar light transmission test: single measurement of four bars (left) and the distribution of the relative residual luminosity (right).

265 clear) to the multi-anode PMT connector, where a picture of the PMT mask was taken by a camera. An automated program was used to analyse the photos (figure 17, left) and calculate the relative residuals of the light intensity of the individual channels as shown for a single plane in the right plot of figure 17. This test verified the light transmission of the fibre bundles, but also the quality of the interconnections between the WLS fibres and clear fibres. A plane was accepted only if the relative
270 residual intensities of all 60 channels were above -0.4.

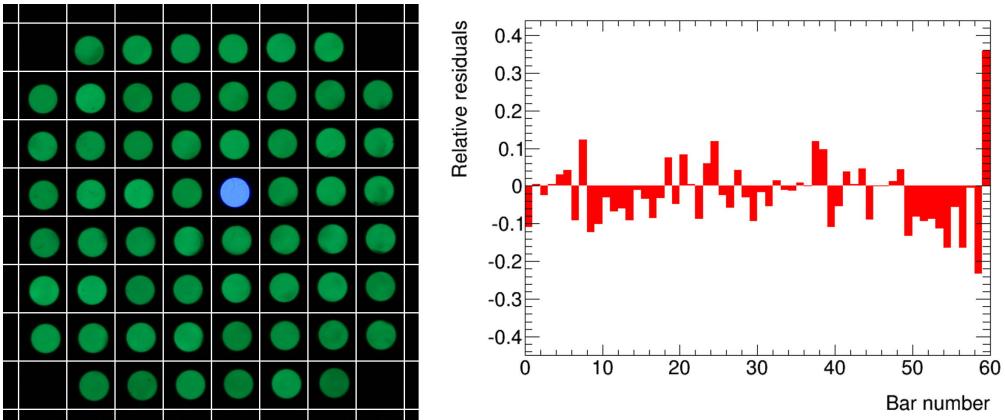


Figure 17: Example of a single plane quality test: picture of the PMT fibre mask (left) and relative residual luminosity of the 60 fibre outputs (right). The 60th channel is the test channel.

A separate test bench was set up in order to verify the functionality of the three major components of the EMR electronics: the multi-anode PMTs, the front-end boards and the digitizer-buffer boards. It reproduced the full electronics chain used to readout the detector with the only difference that the light was generated by an LED source, powered by a variable amplitude pulser. The LED was attached to the MAPMT injecting light in all channels at the same time. The final measurement that is provided by the system is a time-over-threshold of the PMT signal. During the tests this measurement is used as a figure of merit to characterize the electronics chain (PMT, FEB and DBB).
275 The top of figure 18 shows an example of a fully functional electronics chain and the bottom an example of a faulty board. Boards exhibiting the former behaviour were accepted for installation in the detector.
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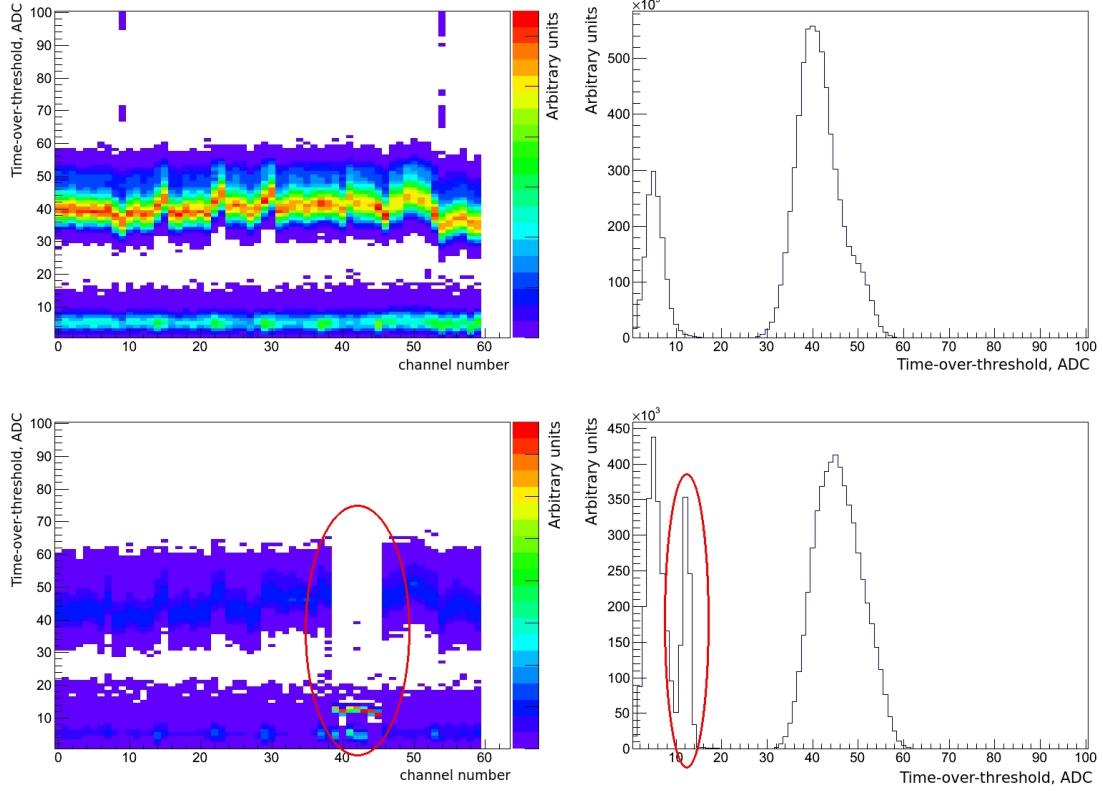


Figure 18: MAPMT readout quality tests of a functional board (top) and a faulty board (bottom). The left plots show the time-over-threshold distribution as a function of the channel number and the right-hand plots represent the integrated distribution of all channels in a given board.

3.2 Examining the performance with the LED calibration system

After the assembly was completed, the detector was fully powered and tested during a few days of LED and cosmics data collection. As described above, the detector is equipped with a built-in LED system for calibration. Light is transported from a LED driver through 96 clear fibres to each SAPMT and to one specific channel of each MAPMT (test channel).

The LED driver was tuned with a variety of voltages ranging from 11.0 V to 22.0 V by steps of 0.5V. For each setting, 10000 pulses were recorded. The mean time-over-threshold in the test channel of an MAPMT is represented as a function of the LED driver voltage in Figure 19. The green area represents the voltage region for which the recorded ToT is consistent with the signature of a minimum ionizing particle.

The collected data was used to investigate the dependence between the ToT measurement and the original total charge of the MAPMT signal. This can be done, assuming that the total charge of the signal in the test channel of the MAPMT is proportional to the total charge Q , recorded by the SAPMT when both receive light from the same LED pulse. An exponential behaviour of the form

$$Q = \exp [a \times ToT + b] \quad (1)$$

is expected, with a and b being two unknown parameters. The parameter a gives the slope of the exponential in log scale and depends on the EMR characteristics such as the scintillation time constant, the FEB shaping function or the threshold level. As a result, we expect this parameter to be constant for each plane with small variations. The parameter b , on the other hand, depends

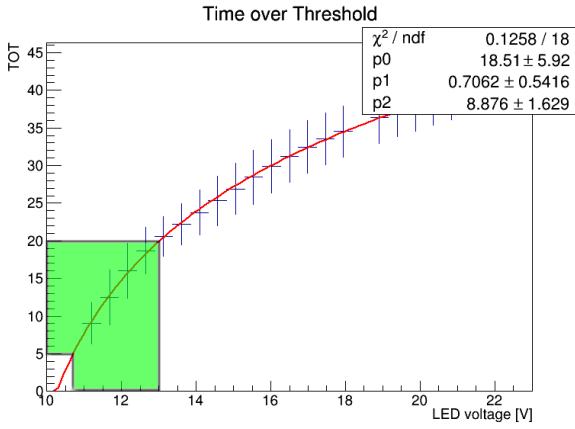


Figure 19: Mean time-over-threshold (ToT) in the test channel as a function of the LED driver voltage. The fit shows a logarithmic relation of the form $\text{ToT} = p_0 \ln [p_1 V + p_2]$.

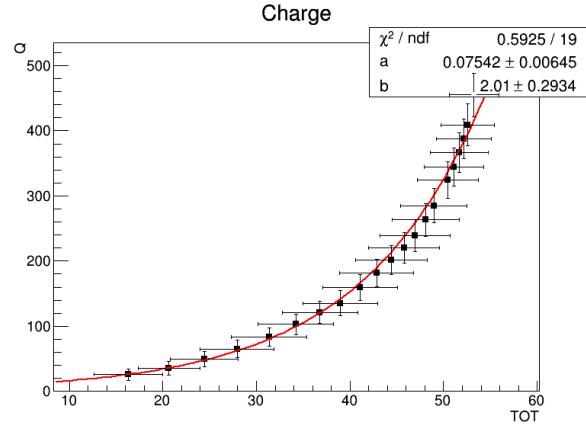


Figure 20: Plane charge as a function of time-over-threshold for different settings. The error bars represent the distributions RMS. The fit shows a relation of the form $Q = \exp(a\text{ToT}+b)$.

on the two PMTs gain and can vary significantly from one plane to another. These two parameters
300 were obtained experimentally by fitting the relation Q vs. ToT for each individual plane of the detector. Figure 20 shows the exponential relation between time-over-threshold and charge in the one of the planes of the EMR.

3.3 Examining the performance with cosmic rays

Cosmic rays present an ideal source of particles that can be used to characterize, debug and tune
305 the detector. Cosmic rays that reach the detector are typically multi-GeV muons that traverse the EMR without stopping. An externally generated 3 ms signal was used in order to reproduce the timing structure of the "Spill" gate signal, used by the MICE DAQ system. A coincidence between the SAPMT signals from two planes and the Spill gate signal was used as a trigger.

The EMR planes were perpendicular to the ground at the time of this test. Data was taken for
310 60 hours and yielded $\sim 2.23 \times 10^5$ triggers. The raw measurements of the EMR comprise the hit time and time-over-threshold, ToT, for each bar and the integrated plane charge. The two planes used as trigger did not record a plane charge. The amount of hits recorded in each bar was of order $\sim 10^3$. The test revealed only 5 dead channels ($\sim 0.2\%$ of the detector). A typical cosmic event is shown in Figure 21.

315 3.3.1 Cosmic muon signature

Cosmic muons are minimum ionizing particles and hence deposit on average the same amount of energy per unit length. The muon typically hits two triangular bars in a plane, by design. The additional hits come either from crosstalk or noise (e.g. third hit in plane 26 in figure 21, top-left). All hits from cosmic muons have approximatively the same time offset with respect to the trigger.
320 To separate the true hits from the noise, a cut on the time difference between a bar hit and the trigger was applied. A thorough study of the crosstalk was conducted and is presented in section 3.4.

Figure 22 shows the time and ToT structure of the hits recorded in the MAPMT for the whole sample of cosmic data. The hits come prior to the trigger in the readout chain due to the delay in the logic box. Time walk affects the timing so that the lower amplitude signals come later on average.
325 The distinctive spike present at ~ 15 ADC counts in the ToT distribution is a feature of cosmic

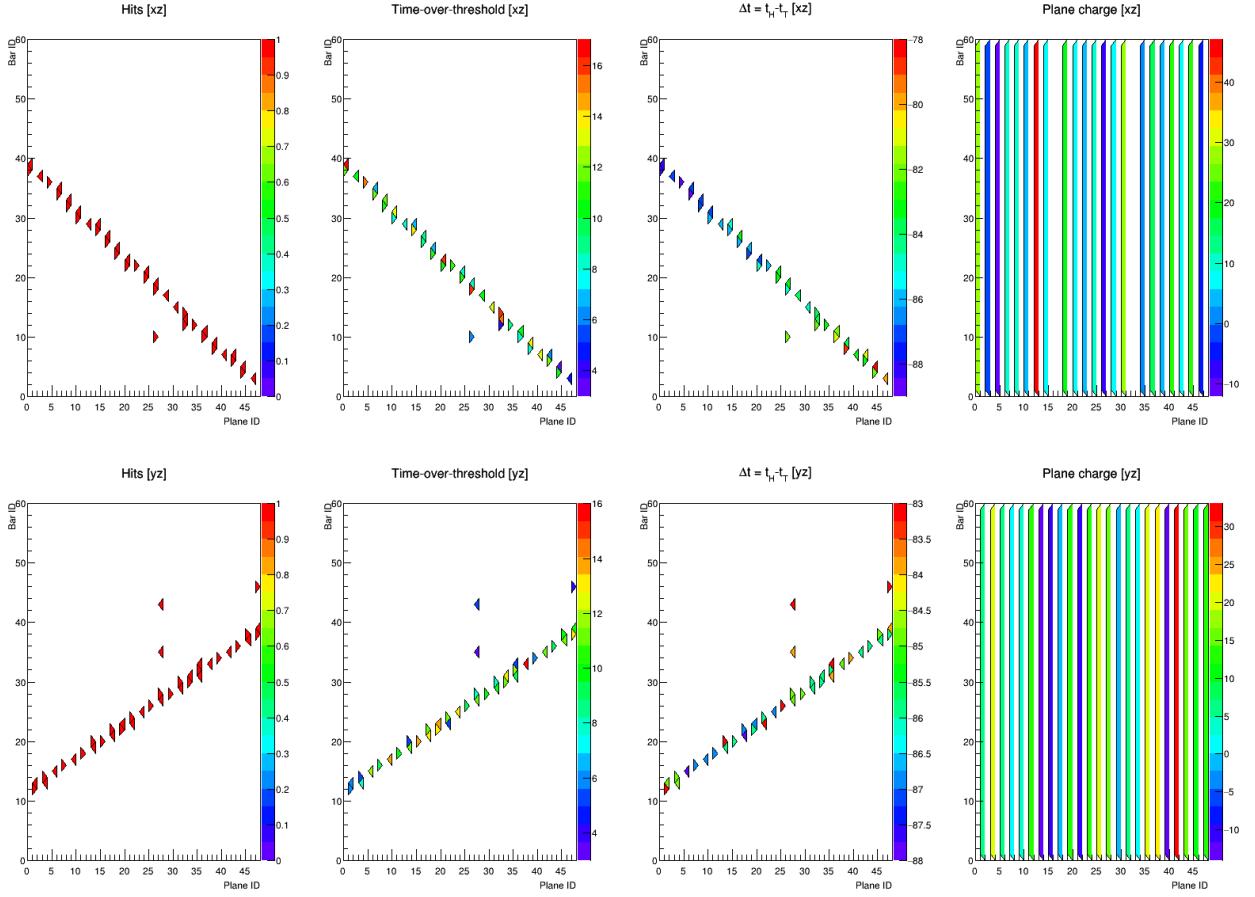


Figure 21: Cosmic muon event in the EMR in the xz (top) and yz (bottom) projections. From left to right: hits per bar, ToT, hit time with respect to the trigger and plane charge.

data acquired with the detector planes perpendicular to the ground and the non-linear connection between charge and ToT.

The SAPMTs were used to measure total charge in planes. The digitizers store waveforms of signals associated to triggers within a certain acquisition window. These waveforms are integrated in a signal window off-line taking into account the pedestal positions in order to compute the total plane charge, as shown for the whole cosmic data sample in Figure 23.

3.4 LED-based crosstalk analysis

The EMR is susceptible to two types of crosstalk: optical crosstalk, i.e. a single fibre of a bundle shining on more than one channel of the MAPMT mask, and anode crosstalk, i.e. a photo-electron leaking from a dynode to an adjacent accelerating structure. An analysis was developed in [26, 27] to evaluate the significance of this phenomenon.

Cosmic or beam data are poorly suited for this analysis. A real particle often hits two bars or more within each plane which makes it impossible to disentangle real signals from crosstalk in neighbouring channels. An LED calibration system is a more reliable tool to drive the analysis. The test channel, connected to the LED light source, has four directly adjacent channels: top (N), bottom (S), left (W) and right(E). This method ensures that hits in the adjacent channels are caused by crosstalk only.

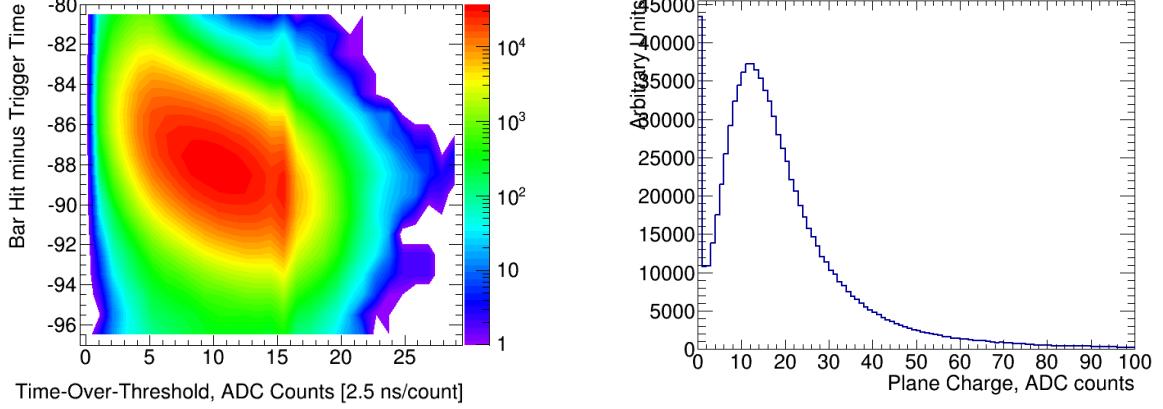


Figure 22: Energy and time structure of the hits recorded in the MAPMT for cosmic muons (MIP signals).

Figure 23: Distribution of the charge recorded in the SAPMT for cosmic muons (MIP signals).

The first parameter that characterizes the crosstalk is the charge ratio, R_Q^i , between the signal amplitude in an adjacent channel i and the primary amplitude in the test channel. As explained already, the charge is not measured directly but is related to the ToT through equation 1. The ratio subsequently reads

$$R_Q^i = \frac{Q_i}{Q_0} = \frac{\exp[aToT_i + b]}{\exp[aToT_0 + b]} = \exp[a(ToT_i - ToT_0)]. \quad (2)$$

The ratio is measured for the highest achievable LED voltage setting as the resolution evolves as $1/\sqrt{Q}$. The ratio measured in the 192 readout channels (directly adjacent N,S,W,E channels of each plane) is represented in Figure 24. The fraction of the original signal that typically leaks in adjacent channels is $4.49 \pm 0.11\%$.

The second parameter used to characterize the crosstalk is the rate. The measured quantity is the ratio R_N^i of hits in a surrounding channel i to the total amount of pulses generated in the test channel. This quantity is measured in the 192 readout channels for a voltage setting in the green area of Figure 19, corresponding to MIP-like signals, and represented in Figure 25. The average rate fraction is $0.20 \pm 0.01\%$, well within design requirements.

The measurement of the crosstalk rate in the adjacent channels also provides a measurement of misalignment of the MAPMT mask with respect to the fibre bundle. If a mask is shifted, light is more likely to leak and create signals in the channel towards which it is offset. The centre of the mask with respect to the centre of fibre bundle is computed through

$$(x_C, y_C) = \left(\frac{\sum_i x_i w_i}{\sum_i w_i}, \frac{\sum_i y_i w_i}{\sum_i w_i} \right), \quad (3)$$

with (x_i, y_i) the coordinates of the surrounding channels and w_i the amount of hits recorded in them. The resolution is function of $1/\sqrt{N}$, N the amount of signals recorded, hence a high voltage is chosen for this analysis. The results for the 48 planes are presented in Figure 26. There is a noticeable cluster around $(-0.3, 0.3)$ but nothing that could impair the detector.

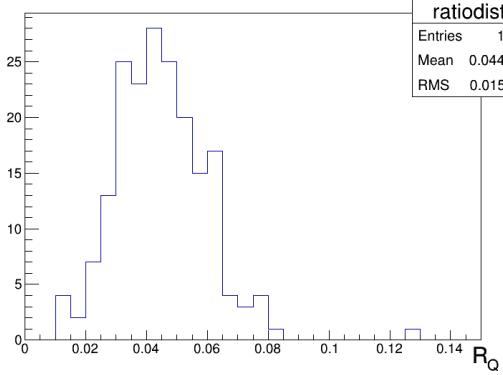


Figure 24: Fraction of the original charge that can leak in adjacent channels.

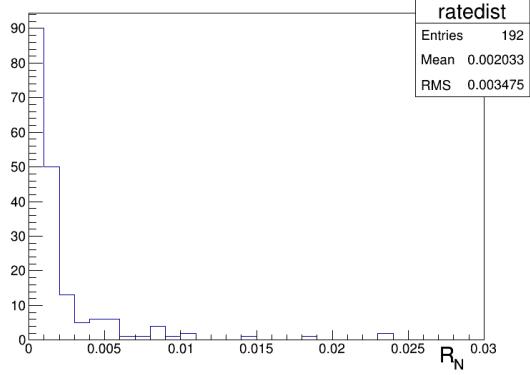


Figure 25: Fraction of the time a signal produces crosstalk for a typical MIP energy loss.

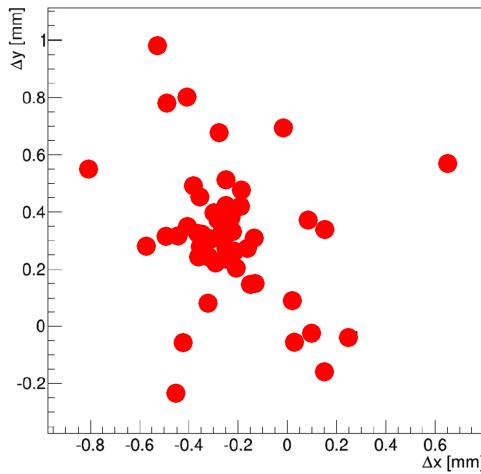


Figure 26: Misalignment of the MAPMT mask with respect to the fibre bundle for the 48 planes.

3.5 Cosmic-based channel mismatch analysis

365 The design of the EMR, involving the connection of external clear fibres to internal WLS fibres [25], leaves room for human error in matching the two correctly. A dedicated analysis was designed in order to verify the consistency of this connection across the 2832 bars in the detector.

370 This analysis [26, 27] uses the distance between each bar hit and its particle track as a tool to estimate the likelihood of mismatch. A mismatched channel is not reconstructed in the right location and is, on average, significantly less consistent with the other measurements in a reconstructed particle track. Cosmic muons were particularly suited for this procedure as they traverse the whole detector in straight lines, without stopping and provide full coverage. When the data sample used in this analysis was recorded, the EMR was positioned up right with planes vertically oriented. Two cuts are applied to the data sample in order to rid the muon tracks of artificial hits caused by 375 crosstalk and noise. Crosstalk signals were rejected by placing a lower limit on the ToT measurement ($ToT > 5$). Restricting the delay between the trigger time and the hit time to a small interval was used to rid of most of the noise ($-100 < \Delta t < -80$ ADC counts).

To reconstruct tracks and calculate the distance of each hit from its particle trail, the hits were split into two projections qz , $q = x, y$. The plane ID of the channel hit provides the z coordinate

and the bar ID provides either the x or y coordinates, depending on the plane orientation. The (q_i, z_i) coordinates were those of the barycentre of the triangular section or the bar corresponding to the hit. For a linear fit $q = a_q z + b_q$, the absolute distance between a hit (q_i, z_i) and the track within a plane reads $\Delta q_i = |q_i - (a_q z_i + b_q)|$. For intuitiveness, distances are expressed in bar units (b.u.) in the following developments. A b.u. corresponds to the height of the triangular section or equivalently to the half width of its base.

The critical secondary variables, measured for each channel are the ratios of mismatch, R_i . Given an integer i , the ratio R_i corresponds to the fraction of the sample for which the bar is within $i \pm 2/3$ b.u. off-track. For a distance distribution $f(\Delta)$, the ratio is defined as

$$R_i = \frac{\int_{i-\sigma}^{i+\sigma} f(\Delta) d\Delta}{\int_0^\sigma f(\Delta) d\Delta + \int_{i-\sigma}^{i+\sigma} f(\Delta) d\Delta}. \quad (4)$$

with $\sigma = 2/3$ b.u., an arbitrary overlapping uncertainty on the point.

For instance, the ratio R_1 represents the probability of a bar of being mismatched by exactly 1 b.u., i.e. to be swapped with an adjacent bar. It is shown in [27] that R_i is theoretically estimated to take values summarized in table 1 for different scenarios. The $X - Y$ asymmetry of the ratio R_i is due to the different angular distribution of muons seen by the vertical and the horizontal bars.

| | Matched | | Mismatched | |
|----------------|------------|------------|--------------|--------------|
| | xz proj. | yz proj. | xz proj. | yz proj. |
| R_1 | 25.3 % | 32.2 % | 62.6 % | 66.1 % |
| $R_{i \geq 2}$ | ~ 0 % | ~ 0 % | ~ 100 % | ~ 100 % |

Table 1: Mismatch ratios, R_i , for matched and mismatched bars in the two projections.

The mismatch ratio for adjacent bars was measured and is represented for each channel in fig. 27. The ratio distribution is represented next to it in log scale. The bulk of the distribution is centred around 28.88 %, consistent with the weighted average of the theoretical predictions for the two projections. Bars 47 and 48 of plane 44 record a ratio of 62.5 ± 3.5 % and 57.2 ± 3.2 %, respectively, significantly superior to the bulk and in agreement with the prediction. Their proximity to each other corroborates the hypothesis of a channel swap. The mismatch is fixed at the level of the channel map in the reconstruction.

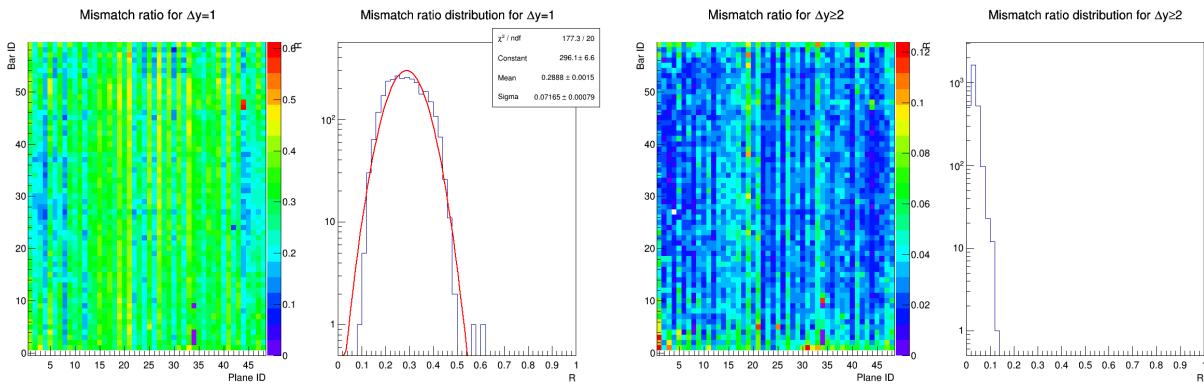


Figure 27: Mismatch ratio for adjacent bars.

Figure 28: Mismatch ratio for distant bars.

The same analysis has been conducted for potential mismatches of two bars or more, $R_{i \geq 2}$. Figure 28 represents the value of that ratio for each channel. The results strongly reject any mismatch at this level.

3.6 PMT Calibration

405 A thorough charge calibration was performed shortly after completion of the detector. Cosmic data was used and the charge on the MAPMT side, Q_M^i was reconstructed by using equation 1. Provided these measurements, a calibration constant is produced for each MAPMT and SAPMT channel through

$$\epsilon_M^i = \frac{\overline{Q_M^i}}{\frac{1}{N} \sum_{j=1}^N Q_M^j}, \quad \epsilon_S^i = \frac{\overline{Q_S^i}}{\frac{1}{N} \sum_{j=1}^N Q_S^j}, \quad (5)$$

410 with \overline{Q} the average charges measured in the channel and N the total number of channels under calibration. The indices M and S stand for MAPMT and SAPMT, respectively. Provided calibration, each charge measured is corrected by dividing it by its corresponding calibration constant.

The measurements obtained for the 5664 channels of the EMR are represented in figure 29. The figure compiles the mean charges recorded in the MAPMT and SAPMT for each channel and each plane. These values are used to compile the calibration constants.

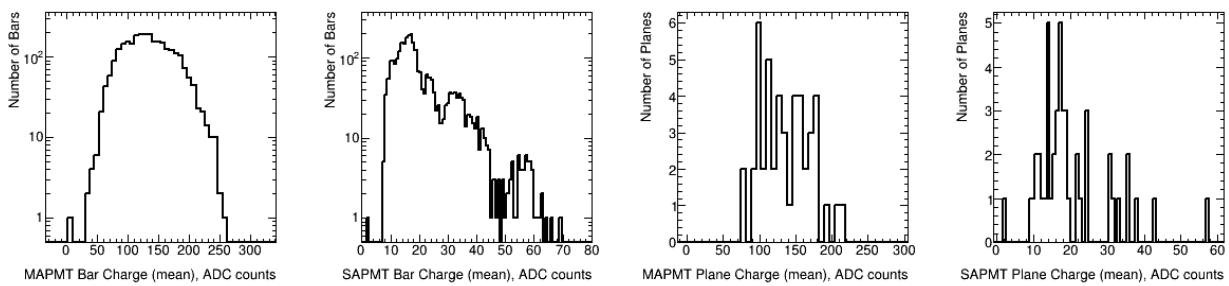


Figure 29: Distributions of the first round of calibration. From left to right: mean MAPMT bar charge, mean SAPMT bar charge, mean MAPMT plane charge and mean SAPMT plane charge.

415 4 Transportation and installation at Rutherford Lab

The total weight of the EMR detector is 2.5 tonnes. Therefore a special care was taken to insure safety and shock-free transportation of the detector. The detector was attached to special shock absorbers designed to withstand its weight and allow for shock absorption in all three directions. The shock absorbers were then attached to a pallet by which the detector was handled. It was placed in a
420 truck and delivered from the University of Geneva to the Rutherford Appleton Laboratory (Didcot, Oxfordshire, UK) in September 2013.

Once delivered, the EMR detector was installed in the MICE hall and positioned vertically at the end of the existing MICE beamline. It was later exposed to a beam which parameters were varied in order to achieve different beam compositions and momenta. This data was used to verify the
425 designed functionality of the detector, i.e. the ability to distinguish different particle types (muons, electrons and pions) and to measure their ranges [28].

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